- (a) Find  $[\mathbf{T}]_{\mathfrak{RR}}$ .
- (b) Find the coordinate transformation  $S_{\alpha,\alpha_{j}}$ .
- (c) Use the answers to (a) and (b) to compute  $[\mathbf{T}]_{\mathfrak{Y}}$  by means of a similarity transformation.
- 2.35 Multiplication by an invertible matrix can be interpreted either as a linear transformation or as a change of coordinates. Let  $\mathfrak{X} = \{\mathbf{x_1}, \mathbf{x_2}\}$  be a basis for a two-dimensional space  $\mathfrak{V}$  and  $\mathbf{x}$  a vector in  $\mathfrak{V}$ . Then  $[\mathbf{x_1}]_{\mathfrak{K}} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $[\mathbf{x_2}]_{\mathfrak{K}} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . Let

$$[\mathbf{x}]_{\mathfrak{N}} = \begin{pmatrix} 2\\1 \end{pmatrix}, \qquad \mathbf{A} = \begin{pmatrix} 1 & -1\\1 & 0 \end{pmatrix}$$

- (a) Alias interpretation: assume  $\mathbf{A}[\mathbf{x}]_{\mathfrak{N}} = [\mathbf{x}]_{\mathfrak{Y}}$ , where  $\mathfrak{Y} = \{\mathbf{y}_1, \mathbf{y}_2\}$  is a second basis for  $\mathcal{V}$ . Find  $[\mathbf{y}_1]_{\mathfrak{N}}$  and  $[\mathbf{y}_2]_{\mathfrak{N}}$ . Sketch  $[\mathbf{x}_1]_{\mathfrak{N}}$ ,  $[\mathbf{x}_2]_{\mathfrak{N}}, [\mathbf{x}]_{\mathfrak{N}}, [\mathbf{y}_1]_{\mathfrak{N}}$ , and  $[\mathbf{y}_2]_{\mathfrak{N}}$  as arrows in a plane. What is the relationship between  $[\mathbf{x}]_{\mathfrak{N}}$  and the basis  $\{[\mathbf{y}_1]_{\mathfrak{N}}, [\mathbf{y}_2]_{\mathfrak{N}}\}$ ; that is, what is meant by the notation  $[\mathbf{x}]_{\mathfrak{Y}}$ ?
- (b) Alibi interpretation: assume  $\mathbf{A}[\mathbf{x}]_{\mathfrak{X}} = [\mathbf{T}\mathbf{x}]_{\mathfrak{X}}$ . Sketch  $[\mathbf{x}_1]_{\mathfrak{X}}$ ,  $[\mathbf{x}_2]_{\mathfrak{X}}$ ,  $[\mathbf{x}]_{\mathfrak{X}}$ , and  $[\mathbf{T}\mathbf{x}]_{\mathfrak{X}}$  as arrows in a plane. What is the relationship between  $[\mathbf{T}\mathbf{x}]_{\mathfrak{X}}$  and the basis  $\{[\mathbf{x}_1]_{\mathfrak{X}}, [\mathbf{x}_2]_{\mathfrak{X}}\}$ ; that is, what is meant by the notation  $[\mathbf{T}\mathbf{x}]_{\mathfrak{X}}$ ?

## 2.7 References

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