

Ranking of nodes in graphs

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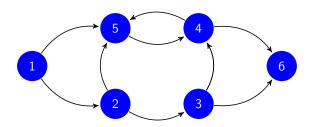
Ranking of nodes in graphs: Random walk



Ranking of nodes in graphs: Random walk

Ranking of nodes in graphs: Markov chain

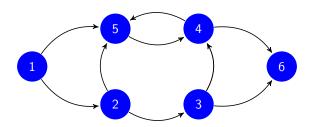




- ► Graph \Rightarrow A set of J nodes j = 1, ..., J \Rightarrow Connected by a set of edges E defined as ordered pairs (i, j)
- ▶ In figure \Rightarrow nodes are j = 1, 2, 3, 4, 5, \Rightarrow edges $E = \{(1, 2), (1, 5), (2, 3), (2, 5), (3, 4), ...$ $(3, 6), (4, 5), (4, 6), (5, 4)\}$
- ▶ Websites and links ⇒ "The" web.
- ▶ People and friendship ⇒ Social network

How well connected nodes are?



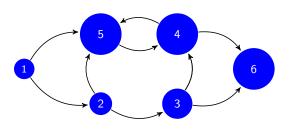


- Q: Which node is the most connected? A: Define most connected
- ► Can define "most connected" in different ways
- ▶ Node rankings to measure website quality, social influence
- ▶ There are two important connectivity indicators
 - ⇒ How many nodes point to a link (outgoing links irrelevant)
 - ⇒ How Important are the links that point to a node

Connectivity ranking



- ▶ Insight ⇒ There is information in the structure of the network
- ► Knowledge is distributed through the network
 - ⇒ The network (not the nodes) knows the rankings
- ▶ Idea exploited by Google's PageRank[©] to rank webpages
- ... by social scientists to study trust & reputation in social networks
- ▶ ... by ISI to rank scientific papers, transactions & magazines ...



- No one points to 1
- Only 1 points to 2
- Only 2 points to 3, but 2 more important than 1
- ▶ 4 as high as 5 with less links
- Links to 5 have lower rank
- ► Same for 6

Preliminary definitions



- ▶ Graph $\mathcal{G} = (V, E) \Rightarrow$ sets of vertices $V = \{1, 2, ..., J\}$ and edges E
- ▶ Edges (elements of E) are ordered pairs (i,j)
- ightharpoonup We say there is a connection from i to j
- ightharpoonup Outgoing neighborhood of i is the set of nodes j to which i points

$$n(i) := \{j : (i,j) \in E\}$$

▶ Incoming neighborhood, $n^{-1}(i)$ is the set of nodes that point to i:

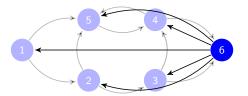
$$n^{-1}(i) := \{j : (j, i) \in E\}$$

- Connected graph
 - ⇒ There is a path from any node to any other node

Definition of rank



- ▶ Agent A chooses node i, e.g., web page, at random for initial visit
- ▶ Next visit randomly chosen between links in the neighborhood n(i)
 - ⇒ All neighbors chosen with equal probability
- ▶ If reach a dead end because node *i* has no neighbors
 - ⇒ Chose next visit at random equiprobably among all nodes
- ▶ Redefine graph G = (V, E) adding edges from dead ends to all nodes
- Restrict attention to connected (modified) graphs



▶ Rank of node *i* is the average number of visits of *A* to *i*

Equiprobable random walk



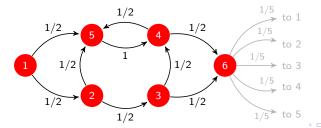
- \blacktriangleright Formally, let A_n be the node visited at time n
- ▶ Define transition probability P_{ij} from node i into node j

$$P_{ij} := \mathsf{P}\left[A_{n+1} = j \mid A_n = i\right]$$

► Next visit equiprobable among neighbors

$$P_{ij} = \frac{1}{\#[n(i)]} = \frac{1}{N_i}, \quad \text{for all } j \in n(i)$$

▶ Defined number of neighbors $N_i = \#[n(i)]$



- ► Still have a graph
- ▶ But also a MC
- ► Red (not blue) circles

Formal definition of rank



- ▶ Consider variable $\mathbb{I}\{A_m = i\}$ to indicate visit to state i at time m.
- \triangleright Rank r_i of i-th node defined as time average of number of visits, i.e.,

$$r_i := \lim_{n \to \infty} \frac{1}{n} \sum_{m=1}^n \mathbb{I} \left\{ A_m = i \right\}$$

- ▶ Define vector of ranks $\mathbf{r} := [r_1, r_2, \dots, r_J]^T$
- ▶ Rank r_i can be approximated by average r_{ni} at time n

$$r_{ni} := \frac{1}{n} \sum_{m=1}^{n} \mathbb{I} \left\{ A_m = i \right\}$$

- ▶ Since $\lim_{n\to\infty} r_{ni} = r_i$, it holds $r_{ni} \approx r_i$ for n sufficiently large
- ▶ Define vector of approximate ranks $\mathbf{r}_n := [r_{n1}, r_{n2}, \dots, r_{nJ}]^T$
- ▶ If modified graph is connected, rank independent of initial visit



```
Output: Vector \mathbf{r}(i) with ranking of node i
Input: Vector N(i) containing number of neighbors of i
Input : Matrix N(i, k) containing indices i of neighbors of i
m=1; \mathbf{r}=zeros(J,1); % Initialize time and ranks
A_0 = \text{random('unid', J)}; % Draw first visit uniformly at random
while m < n do
     jump = random('unid', N_{A_{m-1}}); % Neighbor uniformly at random
     A_m = N(A_{m-1}, jump); % Jump to selected neighbor
    \mathbf{r}(A_m) = \mathbf{r}(A_m) + 1; % Update ranking for A_m
m = m + 1:
end
```

 $\mathbf{r} = \mathbf{r}/n$; % Normalize by number of iterations n

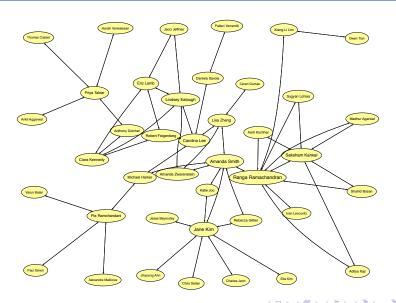
Example: Social graph



- Asked students taking ESE303 about homework collaboration
- Created (crude) graph of the social network of students in this class
- Used ranking algorithm to understand connectedness
- ► E.g., If I want to know how well students are coping with the class it is best to ask people with higher connectivity ranking
- ▶ 2009 data

Ranked class graph





Convergence metrics



- \triangleright Recall **r** is vector of ranks and **r**_n of rank iterates
- ▶ By definition $\lim_{n\to\infty} \mathbf{r}_n = \mathbf{r}$. How fast \mathbf{r}_n converges to \mathbf{r} (\mathbf{r} given)?
- ▶ Can measure by distance between **r** and $\mathbf{r}_n \Rightarrow$

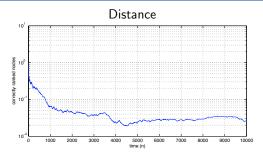
$$\zeta_n := \|\mathbf{r} - \mathbf{r}_n\|_2 = \left(\sum_{i=1}^J (r_{ni} - r_i)^2\right)^{1/2}$$

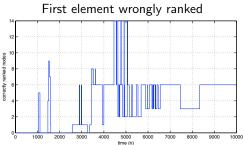
- ▶ If interest is only on largest ranked nodes, e.g., a web search
- ▶ Denote $r^{(i)}$ as the index of the *i*-th highest ranked node
- ▶ Similarly, $r_n^{(i)}$ is the index of the *i*-th highest ranked node at time n
- First element wrongly ranked at time *n*

$$\xi_n := \min_i r^{(i)} \neq r_n^{(i)}$$

Evaluation of convergence metrics





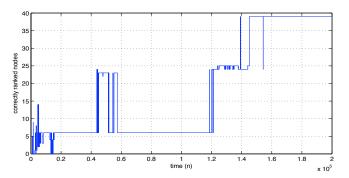


- ▶ Distance gets close to 10⁻² in approx. 5 × 10³ iterations
- ▶ Bad: Two largest ranks in 3 × 10³ iterations
- ► Awful: Six best ranks in 8 × 10³ iterations
- Convergence appears (very) slow

When does this algorithm converge?



- ► Can confidently claim convergence not until 10⁵ iterations
- ► True for particular case. Slow convergence inherent to algorithm
- ► Example has 40 nodes, want to use in network with 10⁹ nodes



▶ Use fact that this process is a MC to obtain faster algorithm

Ranking of nodes in graphs: Markov chain



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Limit probabilities



- ▶ Recall definition of rank $\Rightarrow r_i := \lim_{t \to \infty} \frac{1}{t} \sum_{u=1}^{t} \mathbb{I}\{A(u) = i\}$
- ▶ Rank is time average of number of state visits in a MC
 ⇒ Can be equally obtained from limiting probabilities
- ▶ Recall transition probabilities $\Rightarrow P_{ij} = \frac{1}{N_i}$, for all $j \in n(i)$
- ▶ Stationary distribution $\boldsymbol{\pi} = [\pi_1, \pi_1, \dots, \pi_J]^T$ solution of

$$\pi_i = \sum_{j \in n^{-1}(i)} P_{ji} \pi_j = \sum_{j \in n^{-1}(i)} \frac{\pi_j}{N_j} \quad \text{for all } i$$

- ▶ Plus normalization equation $\sum_{i=1}^{J} \pi_i = 1$
- As per ergodicity $\Rightarrow \mathbf{r} = \boldsymbol{\pi}$

Matrix notation, eigenvalue problem



► As always, can define matrix **P** with elements P_{ij}

$$\pi_i = \sum_{j \in n^{-1}(i)} P_{ji} \pi_j = \sum_{j=1}^J P_{ji} \pi_j \qquad \text{for all } i$$

Right hand side is just definition of a matrix product leading to

$$\pi = \mathbf{P}^T \pi, \qquad \pi^T \mathbf{1} = 1$$

- Also added normalization equation
- Can solve as system of linear equations or eigenvalue problem on P^T
- ► Non-iterative method ⇒ Convergence not an issue
- ▶ But requires matrix **P** available at a central location
- ► Computationally costly (matrix **P** with 10⁹ rows and columns)
 - All methods are costly to compute exact solution
 - ► This one is costly to find even approximate solution

What are limit probabilities?



Let $p_i(n)$ denote probability of agent A visiting node i at time t

$$p_i(n) := P[A_n = i]$$

▶ Probabilities at time n + 1 and n can be related

$$P[A_{n+1} = i] = \sum_{j \in n^{-1}(i)} P[A_n = i \mid A_n = j] P[A_n = j]$$

Which is, of course, probability propagation in a MC

$$p_i(n+1) = \sum_{j \in n^{-1}(i)} P_{ji} p_j(n)$$

▶ By definition limit probabilities are (let $\mathbf{p}(n) = [p_1(n), \dots, p_J(n)]^T$)

$$\lim_{n\to\infty}\mathbf{p}(n)=\boldsymbol{\pi}=\mathbf{r}$$

Compute ranks from limit of probability propagation

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Probability propagation



► Can also write probability propagation in matrix form

$$p_i(n+1) = \sum_{j \in n^{-1}(i)} P_{ji} p_j(n) = \sum_{j=1}^J P_{ji} p_j(n)$$
 for all i

Right hand side is just definition of a matrix product leading to

$$\mathbf{p}(n+1) = \mathbf{P}^T \mathbf{p}(n)$$

Can approximate rank by probability distribution

$$\Rightarrow$$
 r = $\lim_{n\to\infty}$ **p**(n) \approx **p**(n) for n sufficiently large



▶ Algorithm is just a recursive matrix product

Interpretation of probability propagation



- ▶ Why does the random walk converges so slow?
- ▶ What does it take to obtain a time average r_{ni} close to r_i ?
- ▶ Need to register a large number of agent visits to every state
- ▶ Back of hand: 40 nodes, some 100 visits to each \Rightarrow 4 × 10³ iters.
- ▶ Idea: Unleash a large number of agents *K*

$$r_i = \lim_{n \to \infty} \frac{1}{n} \sum_{m=1}^{n} \frac{1}{K} \sum_{k=1}^{K} \mathbb{I} \{ A_{km} = i \}$$

- Visits are now spread over time and space
 - \Rightarrow Converges "K times faster" (depends agents' initial distribution)
 - ⇒ But haven't changed computational cost

Interpretation of prob. propagation (continued)



▶ What happens if we unleash infinite number of agents *K*?

$$r_i = \lim_{n \to \infty} \frac{1}{n} \sum_{m=1}^{n} \lim_{K \to \infty} \frac{1}{K} \sum_{k=1}^{K} \mathbb{I} \left\{ A_{km} = i \right\}$$

Using law of large numbers and expected value of indicator function

$$r_i = \lim_{n \to \infty} \frac{1}{n} \sum_{m=1}^n \mathbb{E}\left[\mathbb{I}\left\{A_m = i\right\}\right] = \lim_{n \to \infty} \frac{1}{n} \sum_{m=1}^n P\left[A_m = i\right]$$

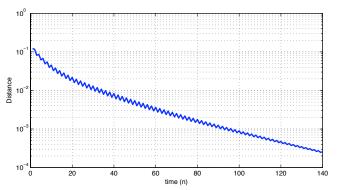
▶ Graph walk is a MC, then $\lim_{m\to\infty} P[A_m = i] = \lim_{m\to\infty} p_i(m)$ exists, and

$$r_i = \lim_{n \to \infty} \frac{1}{n} \sum_{m=1}^n p_i(m) = \lim_{n \to \infty} p_i(n)$$

- ▶ Probability propagation ≈ Unleashing infinite number of agents
- ► Interpretation true for any MC



- ▶ Initialize with uniform probability distribution \Rightarrow **p**(0) = (1/J)**1**
- ▶ Distance between $\mathbf{p}(n)$ and \mathbf{r}

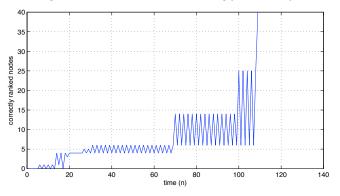


- ► Distance is 10⁻² in approximately 30 iterations, 10⁻⁴ in 140 iterations
- ► Convergence is two orders of magnitude faster than random walk

Number of nodes correctly ranked



▶ Rank of highest ranked node that is wrongly ranked by time *n*



- ▶ Not bad: All nodes correctly ranked in 120 iterations
- ► Good: Ten best ranks in 80 iterations
- ▶ Great: Four best ranks in 20 iterations

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Distributed algorithm to compute ranks



- \triangleright Nodes want to compute their rank r_i
 - ⇒ Can communicate with neighbors only (incoming + outgoing)
 - ⇒ Access to neighborhood information only
- ► Recall probability update

$$p_i(n+1) = \sum_{j \in n^{-1}(i)} P_{ji} p_j(n) = \sum_{j \in n^{-1}(i)} \frac{1}{N_j} p_j(n)$$

- Uses local information only
- ▶ Algorithm. Nodes keep local rank estimates $p_i(n)$
- ▶ Receive rank (probability) estimates $p_j(n)$ from neighbors $j \in n^{-1}(i)$
- ▶ Update local rank estimate $p_i(n+1) = \sum_{j \in n^{-1}(i)} p_j(n)/N_j$
- ▶ Communicate rank estimate $p_i(n+1)$ to outgoing neighbors $j \in n(i)$
- ▶ Need only know number of neighbors of my neighbors

Distributed implementation of random walk



- ► Can communicate with neighbors only (incoming + outgoing)
- ▶ But cannot access neighborhood information
- Pass agent around
- ▶ Local rank estimates $r_i(n)$ and counter with number of visits V_i
- Algorithm run by node i at time n

```
if Agent received from neighbor then V_i = V_i + 1
Choose random neighbor Send agent to chosen neighbor end n = n + 1; r_i(n) = V_i/n;
```

▶ Speed up convergence by generating many agents to pass around

Comparison of different algoithms



- ► Random walk implementation
 - \Rightarrow Most secure & robust. No information shared with other nodes
 - ⇒ Implementation can be distributed
 - ⇒ Convergence exceedingly slow
- System of linear equations
 - ⇒ Least security and robustness. Graph in central server
 - ⇒ Distributed implementation not clear
 - ⇒ Non-iterative method, convergence not a problem
 - ⇒ But computationally costly to obtain approximate solutions
- Probability propagation, matrix powers
 - ⇒ Somewhat secure/robust. Info. shared with neighbors only
 - ⇒ Implementation can be distributed
 - \Rightarrow Convergence rate acceptable (orders of magnitude faster than RW)