

ESE535: Electronic Design Automation

Day 5: February 2, 2009
Architecture Synthesis
(Provisioning, Allocation)



Penn ESE535 Spring 2009 -- DeHon

Today

- Problem
- Brute-Force/Exhaustive
- Greedy
- Estimators
- Analytical Provisioning
- ILP Schedule and Provision

Penn ESE535 Spring 2009 -- DeHon

2

Previously

- General formulation for scheduled operator sharing
 - VLIW
- Fast algorithms for scheduling onto fixed resource set
 - List Scheduling

Penn ESE535 Spring 2009 -- DeHon

3

Today: Provisioning

- Given
 - An area budget
 - A graph to schedule
 - A Library of operators
- Determine:
 - Best (delay minimizing) set of operators
 - i.e. select the operator set

Penn ESE535 Spring 2009 -- DeHon

4

Exhaustive

1. Identify all area-feasible operator sets
 - E.g. preclass exercise
 2. Schedule for each
 3. Select best
- → optimal
 - Drawbacks?

Penn ESE535 Spring 2009 -- DeHon

5

Exhaustive

- How large is space of feasible operator sets?
 - As function of
 - operator types – N
 - Types: add, multiply, divide,
 - Maximum number of operators of type M

Penn ESE535 Spring 2009 -- DeHon

6

Size of Feasible Space

- Consider 10 operators
 - For simplicity all of unit area
- Total area of 100
- How many cases?

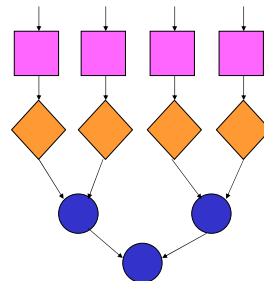
Implication

- Feasible operator space can be too large to explore exhaustively

Greedy Incremental

- Start with one of each operator
- While (there is area to hold an operator)
 - Which single operator
 - Can be added without exceeding area limit?
 - And Provides largest benefit?
 - Add one operator of that type
- How long does this run?
- Weakness?

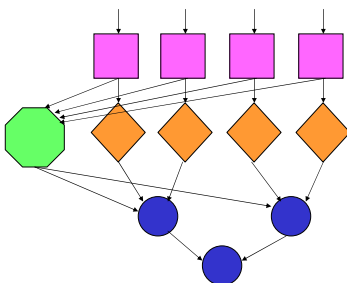
Example



Find best 5 operator solution.

original:
not quite demo.

Example



Find best 6 operator solution.

Review if this captures

Estimators

- Scheduling expensive
 - $O(|E|)$ or $O(|E| \cdot \log(|V|))$ using list-schedule
- Results not analytic
 - Cannot write an equation around them
- Saw earlier bounds sometimes useful
 - No precedence \rightarrow is resource bound
 - Often one bound dominates

Estimations

- Step 1: estimate with resource bound
 - O(|E|) vs. O(N) evaluation
- Step 2: use estimate in equations
 - $T = \max(N_1/R_1, N_2/R_2, \dots)$

Penn ESE535 Spring 2009 – DeHon

13

Constraints

- Let A_i be area of operator type i
- Let x_i be number of operators of type i

$$\sum A_i \times x_i \leq Area$$

Penn ESE535 Spring 2009 – DeHon

14

Achieve Time Target

- Want to achieve a schedule in T cycles
- Each resource bound must be less than T cycles:
 - $N_i/x_i \leq T$

Penn ESE535 Spring 2009 – DeHon

15

Algebraic Solve

- Set of equations
 - $N_i/x_i \leq T$
 - $\sum A_i x_i \leq Area$
- Assume equality
- $N_i/x_i = T \rightarrow x_i = N_i/T$

$$\frac{\sum A_i \times N_i}{T} \leq Area$$

Penn ESE535 Spring 2009 – DeHon

16

Rearranging

$$\frac{\sum A_i \times N_i}{T} \leq Area$$

$$\frac{\sum A_i \times N_i}{Area} \leq T$$

Penn ESE535 Spring 2009 – DeHon

17

Back Substitute

- $x_i = N_i/T$

$$\frac{\sum A_i \times N_i}{Area} \leq T$$

- x_i won't necessarily be integer
 - Round down definitely feasible solution
 - May have room to move a few up by 1

Penn ESE535 Spring 2009 – DeHon

18

ILP

- Integer Linear Programming
- Formulate set of linear equation constraints (inequalities)
 - $Ax_0+Bx_1+Cx_2 \leq D$
 - $x_0+x_1=1$
 - A,B,C,D – constants
 - x_i – variables to satisfy
- Can constrain variables to integers
- No polynomial time guarantee
 - But often practical
 - Solvers exist

ILP Provision and Schedule

- Possible to formulate whole operator selection and scheduling as ILP problem

Formulation

- Integer variables M_i
 - number of operators of type i
- 0-1 (binary) variables $x_{i,j}$
 - 1 if node i is scheduled into timestep j
 - 0 otherwise
- Variable assignment completely specifies schedule
- This formulation for achieving a target time T
 - j ranges 0 to $T-1$

Target $T \rightarrow \text{Min } T$

- Formulation targets T
- But do we know T ?
- Do binary search for minimum T
 - How does that impact solution time?

Constraints

1. Total area constraints
2. Not assign too many things to a timestep
3. Assign every node to some timestep
4. Maintain precedence

(1) Total Area

- Same as before

$$\sum A_i \times M_i \leq Area$$

(2) Not overload timestep

- For each timestep j
 - For each operator type k

$$\sum_{o_i \in FU_k} x_{i,j} \leq M_k$$

(3) Node is scheduled

- For each node in graph

$$\sum_j x_{i,j} = 1$$

Can narrow to sum over slack window.

(4) Precedence Holds

- For each edge from node i to node k

$$\sum_j j \times x_{i,j} - \sum_j j \times x_{k,j} \leq -1$$

Can narrow to sum over slack windows.

Round up Algorithms and Runtimes

- Exhaustive Schedule
- Exhaustive Resource Bound Estimate
- Greedy Schedule
- LP on estimates
 - Particular time bound
 - Minimize time
- ILP on estimates and exact
 - Particular time bound
 - Minimize time

Admin

- Assignment 2 out
 - Programming assignment
 - Now in two pieces
- Reading on web

Big Ideas:

- Estimators
- Dominating Effects
- Reformulate as a problem we already have a solution for
 - ILP
- Technique: Greedy
- Technique: ILP