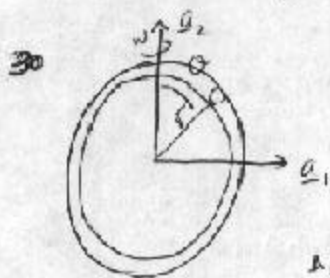


HW #7 Solutions.



$$\underline{\omega} = \omega \underline{a}_2 + \dot{\theta} \underline{a}_3$$

$$\underline{r} = r \sin \theta \underline{a}_1 + r \cos \theta \underline{a}_2$$

$$\underline{v} = \frac{d}{dt} \underline{r} = \underline{\omega} \times \underline{r} = -\dot{\theta} r \cos \theta \underline{a}_1 + \dot{\theta} r \sin \theta \underline{a}_2 - \omega r \sin \theta \underline{a}_3$$

$$T = \frac{1}{2} m (\underline{v} \cdot \underline{v})$$

$$= \frac{1}{2} m [(\dot{\theta} r \cos \theta)^2 + (\dot{\theta} r \sin \theta)^2 + (\omega r \sin \theta)^2]$$

$$= \frac{1}{2} (\dot{\theta}^2 r^2 + \omega^2 r^2 \sin^2 \theta) m$$

$$V = m g r \cos \theta$$

$$L = T - V = \frac{1}{2} m (\dot{\theta}^2 r^2 + \omega^2 r^2 \sin^2 \theta) - m g r \cos \theta$$

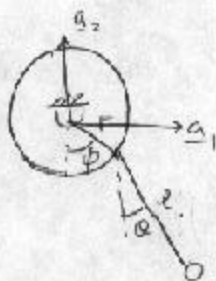
$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0$$

$$\frac{d}{dt} (m \dot{\theta} r^2) - (m \omega^2 r^2 \sin \theta \cos \theta + m g r \sin \theta) = 0$$

$$m \ddot{\theta} r^2 - m \omega^2 r^2 \sin \theta \cos \theta - m g r \sin \theta = 0$$

$$\boxed{\ddot{\theta} - \omega^2 \sin \theta \cos \theta - \frac{g}{r} \sin \theta = 0}$$

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$$\underline{r}^m = (r \sin \phi + l \sin \theta) \underline{a}_1 + (r \cos \phi + l \cos \theta) \underline{a}_2$$

$$\underline{v}^m = (\dot{\phi} r \cos \phi + \dot{\theta} l \cos \theta) \underline{a}_1 - (\dot{\phi} r \sin \phi + \dot{\theta} l \sin \theta) \underline{a}_2$$

$$T = \frac{1}{2} m \underline{v} \cdot \underline{v}^m$$

$$= \frac{1}{2} m \left[(\dot{\phi} r \cos \phi + \dot{\theta} l \cos \theta)^2 + (\dot{\phi} r \sin \phi + \dot{\theta} l \sin \theta)^2 \right]$$

$$= \frac{1}{2} m (\dot{\phi}^2 r^2 + \dot{\theta}^2 l^2 + 2 r l \dot{\phi} \dot{\theta} \cos(\phi - \theta))$$

$$V = -mg(r \cos \phi + l \cos \theta)$$

$$L = T - V$$

$$= \frac{1}{2} m (\dot{\phi}^2 r^2 + \dot{\theta}^2 l^2 + 2 r l \dot{\phi} \dot{\theta} \cos(\phi - \theta)) + mg(r \cos \phi + l \cos \theta)$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\phi}} \right) - \frac{\partial L}{\partial \phi} = 0$$

$$m r \ddot{\phi} + m r l \ddot{\theta} \cos(\phi - \theta) - m r l \dot{\theta} \sin(\phi - \theta) (\dot{\phi} - \dot{\theta}) + m r l \dot{\phi} \dot{\theta} \sin(\phi - \theta) + mg r \sin \phi = 0$$

$$r \ddot{\phi} + l \ddot{\theta} \cos(\phi - \theta) + l \dot{\theta}^2 \sin(\phi - \theta) + g \sin \phi = 0$$

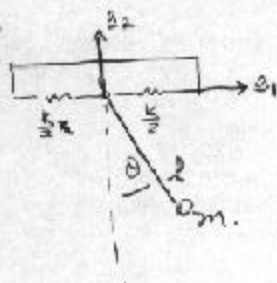
$$\boxed{\ddot{\phi} + \frac{l}{r} \ddot{\theta} \cos(\phi - \theta) + \frac{l}{r} \dot{\theta}^2 \sin(\phi - \theta) + g \sin \phi = 0}$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0$$

$$m r l \ddot{\theta} + m r l \dot{\phi} \cos(\phi - \theta) - m r l \dot{\phi} \sin(\phi - \theta) (\dot{\phi} - \dot{\theta}) + m r l \dot{\phi} \dot{\theta} \sin(\phi - \theta) + mg l \sin \theta = 0$$

$$\boxed{\ddot{\theta} + \frac{r}{l} \dot{\phi} \cos(\phi - \theta) - \frac{r}{l} \dot{\phi}^2 \sin(\phi - \theta) + \frac{g}{r} \sin \theta = 0}$$

31.



$${}^A P^M = (x + l \sin \theta) \mathbf{e}_1 + (-l \cos \theta) \mathbf{e}_2$$

$$\underline{V}^M = \frac{d}{dt} {}^A P^M = (\dot{x} + \dot{\theta} l \cos \theta) \mathbf{e}_1 + \dot{\theta} l \sin \theta \mathbf{e}_2$$

$$\begin{aligned} T &= \frac{1}{2} m \underline{V}^M \cdot \underline{V}^M \\ &= \frac{1}{2} m (\dot{x} + \dot{\theta} l \cos \theta)^2 + (\dot{\theta} l \sin \theta)^2 \\ &= \frac{1}{2} m (\dot{x}^2 + 2\dot{x}\dot{\theta} l \cos \theta + \dot{\theta}^2 l^2) \end{aligned}$$

$$V = -mgl \cos \theta + \frac{1}{2} k x^2$$

$$L = T - V = \frac{1}{2} m (\dot{x}^2 + 2\dot{x}\dot{\theta} l \cos \theta + \dot{\theta}^2 l^2) + mgl \cos \theta - \frac{1}{2} k x^2$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) - \frac{\partial L}{\partial x} = 0$$

$$\frac{d}{dt} \left(\frac{1}{2} m (2\dot{x} + 2\dot{\theta} l \cos \theta) \right) + kx = 0$$

$$m\ddot{x} + m\dot{\theta} l \cos \theta - m\dot{\theta}^2 l \sin \theta + kx = 0$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0$$

$$\frac{d}{dt} \left(\frac{1}{2} m (2\dot{x} l \cos \theta + 2\dot{\theta} l^2) \right) - \frac{1}{2} m (-2\dot{x}\dot{\theta} l \sin \theta) + mgl \sin \theta = 0$$

$$m\dot{x} l \cos \theta + m\dot{\theta} l^2 \sin \theta + m\dot{x}\dot{\theta} l \sin \theta + mgl \sin \theta = 0$$

$$\dot{\theta} l + \dot{x} l \cos \theta + gl \sin \theta = 0$$

$$\ddot{\theta} l + \ddot{x} l \cos \theta + g \sin \theta = 0$$

$$\begin{aligned} m \left[\begin{aligned} \ddot{x} + \dot{\theta} l \cos \theta - \dot{\theta}^2 l \sin \theta + \frac{k}{m} x &= 0 \\ \ddot{\theta} l + \ddot{x} l \cos \theta + g \sin \theta &= 0 \end{aligned} \right. \end{aligned}$$