

pubs.acs.org/NanoLett

Enhanced Piezoelectricity and Stretchability in Energy Harvesting 1 **Devices Fabricated from Buckled PZT Ribbons**

Yi Qi,[†] Jihoon Kim,[†] Thanh D. Nguyen,[†] Bozhena Lisko,[†] Prashant K. Purohit,^{*,†} and Michael C. McAlpine^{*,†} 3

[†]Department of Mechanical and Aerospace Engineering, Princeton University, Princeton, New Jersey 08544, United States 4

- [‡]Department of Mechanical Engineering and Applied Mechanics, University of Pennsylvania, Philadelphia, Pennsylvania 19104, United States 6
- Supporting Information 7

2

ABSTRACT: The development of a method for integrating 8 highly efficient energy conversion materials onto soft, bio-9 compatible substrates could yield breakthroughs in implan-10 table or wearable energy harvesting systems. Of particular 11 interest are devices which can conform to irregular, curved 12 surfaces, and operate in vital environments that may involve 13 both flexing and stretching modes. Previous studies have 14 15 shown significant advances in the integration of highly 16 efficient piezoelectric nanocrystals on flexible and bendable substrates. Yet, such inorganic nanomaterials are mechani-17



cally incompatible with the extreme elasticity of elastomeric substrates. Here, we present a novel strategy for overcoming these 18 limitations, by generating wavy piezoelectric ribbons on silicone rubber. Our results show that the amplitudes in the waves 19 2.0 accommodate order-of-magnitude increases in maximum tensile strain without fracture. Further, local probing of the buckled ribbons reveals an enhancement in the piezoelectric effect of up to 70%, thus representing the highest reported piezoelectric 21 response on a stretchable medium. These results allow for the integration of energy conversion devices which operate in stretching 22 mode via reversible stretching and release deformations in the wavy/buckled ribbons. 23

KEYWORDS: Hybrid mechanics, flexoelectric effect, stretchable energy harvesting, piezoribbons 24

iomechanical energy represents a feasible source of contin-25 Duous power for wearable or implantable devices.¹⁻⁷ Since 26 such applications operate via strain-driven modes, they require 27 the associated energy converting devices to be both flexible and 28 stretchable. Recent research has accelerated in the implementa-29 tion of highly efficient nanoscale piezoelectric energy harvesters 30 on unconventional substrates and in unusual form factors for bendable energy harvesting.^{2,3,5,6,8} Yet, stretchability remains a 31 32 more difficult prospect, as the strains involved can exceed the 33 fracture limits of the most efficient piezoelectric crystals. Poly-34 meric polyvinylidine fluoride (PVDF) nanofibers are naturally 35 flexible and stretchable, accommodating a maximal strain of 2% 36 or higher.9 However, this advantage is offset by the relatively 37 weak electromechanical coupling, with a piezoelectric coefficient 38 of -25 pC/N.10 On the other hand, most highly efficient 39 piezoelectric inorganic ceramic materials are mechanically brittle. 40 For example, lead zirconate titanate (PZT, $Pb[Zr_{0.52}Ti_{0.48}]O_3$) 41 has a piezoelectric coefficient ~ 10 times higher than that for 42 PVDF¹¹ but an elastic modulus of 50–100 GPa⁷ and a maximum 43 tensile strain of 0.2% before fracture.¹² Nanoribbons of PZT, 5,13,14 zinc oxide (ZnO), or barium titanate 44 45 $(BaTiO_3)^{15,16}$ printed onto stretchable elastomeric or flexible 46 plastic substrates are thus susceptible to cracking, slipping, or 47 delamination during operation.^{17,18} Thus, despite their higher 48 fundamental performances, these drawbacks naturally limit the 49

power generating capabilities of such hybrid devices, by requiring large forces to compress the materials and rendering the devices susceptible to mechanical failure.

Here we present a new approach for the generation of hybrid energy harvesting materials, which can simultaneously display high piezoelectric performance while retaining mechanical integrity under both stretching and flexing operating modes. Inspired by recent work in rendering electronic materials stretchable,^{19–21} our approach takes advantage of the nanoscale thicknesses of piezoelectric ribbons to rationally form wavy ribbon geometries on soft substrates, such as poly(dimethyl-siloxane) (PDMS).^{19,22,23} By utilizing prestrains in PDMS to buckle the ribbons, these structures can accommodate significantly higher compressive and tensile poststrains via changes in the wave amplitudes rather than destructive strains in the materials. Most importantly, localized probing of the buckled regions reveals enhanced piezoelectric response, allowing for the generation of stretchable energy harvesting devices.

Figure 1a illustrates our approach.⁵ PZT ribbons $(5-10 \,\mu \text{m})$ wide and 250-500 nm thick) were patterned on a magnesium oxide (MgO) host substrate as described previously^{5,13} and subsequently released from the mother substrate using

Received: December 17, 2010 **Revised:** January 21, 2011

50

- 66 67
- 68 F1 69

70 71

108

109

110

111



Figure 1. Formation of wavy/buckled piezoelectric PZT ribbons. (a) From top to bottom: PZT ribbons were patterned on an MgO substrate and undercut etched to release them from the mother substrate; a slab of prestrained PDMS was laminated against the ribbons and peeled off quickly; retrieved PZT ribbons were transferred onto PDMS and formed wavy/buckled structures upon strain relaxation. (b) SEM image of PZT ribbons transfer printed to PDMS with zero prestrain. (c) PZT ribbons spontaneously buckled under prestrained conditions.

phosphoric acid (85% concentration, 75 °C, ~50 s). A slab of 72 PDMS (\sim 2 mm thick) was then elastically stretched and brought 73 into conformal contact with the ribbons. Peeling off the PDMS 74 allowed for complete transfer of the PZT ribbons to the 75 elastomer via adhesive van der Waals forces in the surface-76 dominated ribbons. Finally, releasing the prestrain in the PDMS 77 78 led to a compressive force in the PZT ribbons as the PDMS relaxed to zero strain, leading to periodic de-adhesion and 79 buckling. The resulting wavy geometry is a result of the transfer 80 of mechanical compressive energy into bending energy. 81 Figure 1b shows a scanning electron microscopy (SEM) image 82 of PZT ribbons transferred using unstrained PDMS, while 83 Figure 1c shows PZT ribbons with a wavy/buckle structure 84 induced by the prestrained PDMS. 85

The resulting geometry of the wavy/buckled ribbons is 86 determined by several factors, including (1) the interaction 87 between the PDMS and the ribbons, (2) the flexural rigidity of 88 the PZT ribbons, and (3) the amount of prestrain in the 89 compliant PDMS. For example, as seen from previous theoretical 90 and experimental studies on ribbons, ^{19,22,24,25} a combination of 91 small prestrain in PDMS and strong adhesion may not lead to 92 buckling, since the ribbons remain in contact with the substrate. 93 94 In contrast, PZT ribbons buckle due to the large prestrain and moderate to weak PZT/PDMS adhesion. The result is that 95 originally flat ribbons of length L₀ will adopt a sinusoidal buckling 96 profile characterized by wavelength L and amplitude A, such that 97 L_0 becomes the contour length of the buckle. Supposing the 98 relatively thick PDMS is completely relaxed, $(L_0 - L)/L$ is then 99 simply the prestrain from PDMS. 100

In order to estimate the wavelength and amplitude of the buckled regions, we consider the total energy in the system as the sum of the energy from the uniaxial strain in the ribbon and the energy due to bending,²⁶ adding an adhesion energy term between PZT ribbons and PDMS. Using an analytical method (see Supporting Information), the wave/buckle length and amplitude in periodic structures can be calculated by minimizing the total energy, resulting in

$$L = \frac{\pi h}{\left[\frac{\varepsilon_{\rm pre}}{1 + \varepsilon_{\rm pre}} - \sqrt{\left(\frac{\varepsilon_{\rm pre}}{1 + \varepsilon_{\rm pre}}\right)^2 - \frac{6w_{\rm ad}}{Eh}}\right]^{0.5}} \qquad (1)$$
$$A = \frac{2L_0}{\pi} \sqrt{\frac{\varepsilon_{\rm pre}}{1 + \varepsilon_{\rm pre}} - \frac{\pi^2 h^2}{3L_0^2}} \qquad (2)$$

Here, *h* is the thickness of PZT ribbons, w_{ad} is the adhesion energy per unit area between the PZT and PDMS, *E* is the Young's modulus of PZT, and ε_{pre} is the prestrain of PDMS.

In practice, variations in the ribbon thickness, the adhesive 112 force, and the strain restoration could cause the ribbons to form 113 aperiodic structures containing buckles with long intervening flat 114 regions. For example, Figure 2a shows buckled PZT ribbons 115 F2 under high (8%, top image) and low (2%, bottom image) 116 prestrain conditions. These results support the idea that larger 117 prestrains lead to more periodic structures, with smaller pre-118 strains yielding isolated buckles. Panels b and c of Figure 2 show 119 experimental wavelength L and amplitude A data points, respec-120 tively, overlaid on curves calculated using the preceding equa-121 tions for ribbon thicknesses of 250 and 500 nm. Notably, the 122 experimental data agree well with the calculations using para-123 meters E = 71 GPa and $W_{ad} = 0.12$ N/m, particularly when the 124 prestrain is large. When $\varepsilon_{\rm pre} \leq 0.02$, the measured wavelength 125 and amplitude are larger than the calculated value, due to the 126 existence of long flat, unbuckled regions, indicating that at low 127 prestrains the hybrid adhered state is lower in energy. Future 128 work will allow us to control the geometry of the buckling more 129 rigorously by, for example, chemical patterning of the PDMS 130 stamp to define adhesion areas.²⁷ 131

В

Nano Letters



Figure 2. Engineering wavy ribbon geometry via prestrain. (a) Top: SEM image of wavy/buckled ribbons formed with large PDMS prestrain (8%). Bottom: SEM image of wavy/buckled ribbons formed with small PDMS prestrain (2%). (b, c) Experimental data and calculated fitting lines (from eqs 1 and 2) describing the buckle wavelength (b) and amplitude (c) as a function of various prestrains (black, 250 nm thick ribbons; red, 500 nm thick). A total of 10 data sets were used for the statistical analysis.

136

138

139

F3 137

A key question is whether PZT ribbons formed using prestretched elastomers are capable of sustaining larger tensile strains due to their wavy/buckled geometry. To test this stretchability, hybrid structures containing flat ribbons and wavy/buckled PZT ribbons were sequentially mounted on a tensile stage and observed by SEM in situ during deformation. Figure 3 shows the results. For PDMS containing flat PZT ribbons, fracture initiated almost immediately with a low applied tensile strain (<1%) and propagated



Figure 3. Application of tensile and compressive poststrains. (a, b) SEM images showing the stretching of flat ribbons (a) and wavy/ buckled ribbons (b) on PDMS under progressive tensile strains. Scale bars: 20 μ m. (c) Plots of the change in wavelength and amplitude of buckled ribbons as a function of applied compressive or tensile post-strains. The red line is a linear fit of the experimental wavelength data, while the blue line is calculated from eq 2.

quickly into brittle fracture (Figure 3a), consistent with PZT's bulk failure strain of $\sim 0.2\%$.¹² By contrast, similar experiments on wavy/ buckled PZT ribbons formed using an 8% prestrain do not show any stress cracks with applied tensile poststrains (up to >8%) and even under compressive strains (-1%) (Figure 3b). This stretch and release process was repeated for several cycles without observing any crack formation. This stretchability is enabled by the ability of the wavy/buckled PZT ribbons to vary their wavelength and amplitude to accommodate an applied poststrain.

Figure 3c shows the length and amplitude of the buckles with a range of applied poststrains. The initial wavelength and amplitude were 150 and 18 μ m, respectively. With increased poststrain, the wavelength increases linearly with poststrain as shown by the red data fit line, until the applied poststrain reaches the prestrain value, at which point ribbon slippage occurs. With compressive strains, slippage commences at a relatively smaller

149

150

151

152

153

154

155

140

dx.doi.org/10.1021/nl104412b |Nano Lett. XXXX, XXX, 000-000

 \mathbf{F}_{4}



Figure 4. Local probing of piezoelectric response in buckled ribbons. (a) Schematic illustration of the PFM measurement performed on a ribbon buckle. (b) Representative piezoelectric displacement in buckled and flat regions of wavy PZT ribbons, as functions of the applied ac tip bias, before and after poling. (c) Average piezoelectric coefficients d_{33} retrieved from the PFM line slopes, before and after poling, and at various locations. Five sets of measurements from different buckles were used for the statistical analysis. (d) Calculated profile of a buckled ribbon and the corresponding strain gradient as determined from eq 4.

strain due to the large modulus of PZT and the increased bending 156 157 energy. Similarly, the amplitude decreases with increased poststrain in order to maintain a constant ribbon contour length with 158 changing wavelength. This amplitude can be calculated from eq 2 159 by substituting $\varepsilon_{\rm pre}$ with $\varepsilon_{\rm pre}-\varepsilon_{\rm post}$ as shown by the blue line in 160 Figure 3c. In other words, imposing a poststrain $\varepsilon_{\text{post}}$ on ribbons 161 formed with a prestrain $\varepsilon_{\rm pre}$ yields equivalent geometries to 162 ribbons released from a $\varepsilon_{\rm pre} - \varepsilon_{\rm post}$ prestrain, as shown by the 163 strong agreement between the data points and calculations. 164

Interestingly, in both the static and stretched states, fractures 165 were not observed in the wavy/buckled ribbons even with the 166 originally destructive tensile poststrain (up to 8%). This can be 167 explained by the small residual strain present after ribbons relax 168 into the wavy geometry. Following the preceding mechanical 169 170 analysis, the uniaxial strain at the midplane of the ribbon is determined to be $\varepsilon_{\rm mid} = -4.5 \times 10^{-5}$, which is 3 orders of 171 172 magnitude smaller than the prestrain and remains a constant along the extent of the buckles. The maximum surface strain in 173 PZT ribbons occurs at the peak and trough locations where the 174 curvature is largest, $\varepsilon_{\text{max}} = kh/2$, where *k* is the curvature. Thus, 175 for a ribbon thickness of 500 nm, and a prestrain of 8%, the 176 calculated value of maximum surface strain is 6.3×10^{-3} , which 177 178 is 1 order of magnitude smaller than the prestrain.

Previous studies on PZT thin films have suggested that inplane tensile or compressive strains, either applied during measurement²⁸ or residual from the annealing procedure,²⁹ can significantly affect the piezoelectric response due to perovskite domain reorientation.^{30–32} For example, a 45 MPa compressive stress in PZT films can lead to a 37% increase in piezoelectric displacement.²⁹ Another factor that may enhance the piezoelectric response is strain gradient induced polarization, or the "flexoelectric" effect, ³³ which is particularly prominent in thin films due to the larger strain gradients.^{34–36} Finally, it has been shown that the substrate clamping effect can reduce the piezoelectric response of thick PZT films by up to 62% relative to bulk values of the piezoelectric charge constant, d_{33} .³⁷ 191

An intriguing question is whether the piezoelectric response is 192 altered in buckled PZT ribbons relative to their flat counterparts. 193 Piezoelectric force microscopy (PFM)³⁸ allows for the local 194 probing of the piezoelectric effect at various points along the 195 ribbons, including at wavy and flat regions. Figure 4a shows the 196 PFM experimental setup. Buckled PZT ribbons containing a Pt 197 underlayer were generated with wavelengths of 80 μ m and 198 heights of 11 μ m, and the PFM tip was brought into contact 199 with the top of the ribbons. Next, an ac modulating voltage was 200 applied between the tip and Pt underlayer, and the piezoelectric 201 response amplitude was measured at the tip. Figure 4b shows the 202 typical piezoelectric response amplitude as a function of applied 203 ac voltage, as the modulating voltage was swept from 1 to 10 V. 204 PFM measurements were performed at flat and buckled regions 205 of the ribbons and were taken before and after poling at 100 kV/ 206 cm for 30 min. The piezoelectric coefficient, d_{33} , was determined 207 from the slopes of the measured lines as described previously.^{5,39} 208 Figure 4c shows statistical d_{33} values taken from flat and buckled 209 positions along the ribbons, before and after poling (10 V, 30 210 min). The data show that d_{33} values in the flat regions before and 211 after poling are ca. 40 and 75 pm/V, respectively, while those in 212 the buckled regions are ca. 80 and 130 pm/V, respectively. 213 Significantly, this value of 130 pm/V is a 70% increase over the 214 response at the flat region and thus represents the highest 215



Figure 5. Energy conversion from stretching wavy/buckled PZT ribbons. (a) Schematic illustration of the experimental setup. (b) Top: photograph of the hybrid chip mounted on a stretching stage, with silver paint contacts separated by 0.5 mm. Bottom: optical micrograph of wavy ribbons bridging silver-paint contacts. (c, d) Short-circuit current measured from devices consisting of 5 (c) and 10 (d) ribbons under periodic stretch (8% strain) and release.

216 reported piezoelectric charge constant value on a flexible 217 medium.⁵

To understand this piezoelectric enhancement, we calculated the uniaxial strain and strain gradient along the length of the wavy ribbons. The midplane uniaxial strain is given by

$$\varepsilon_{\rm mid} = \frac{\pi^2 A^2}{4L_0^2} - \frac{\varepsilon_{\rm pre}}{1 + \varepsilon_{\rm pre}} \tag{3}$$

221 which yields a midplane stress of 8.5 MPa. This uniaxial strain is independent of the position, such that the midplane strain $\varepsilon_{
m mid}$ 222 223 and stress ($\sigma_{mid} = E\varepsilon_{mid}$) are the same everywhere in the ribbons and are functions of prestrain only (since A and L_0 are functions 224 of prestrain only). Given the small magnitude of the uniaxial 225 midplane strain, and the fact that it is a constant along the 226 227 ribbons, we conclude that this strain does not account for the observed location-dependent enhancement. By contrast, in the 228 buckled PZT ribbons, the strain gradient k is calculated as 229

$$k = -\frac{2\pi^2 A}{L_0^2} \cos\left(\frac{2\pi x}{L_0}\right) \tag{4}$$

which is a function of the location *x*. The strain gradient reaches 230 positive and negative maxima at the peak and trough locations 231 and is zero in flat ribbon regions. The maximum strain gradient 232 can be as high as 3.0 \times 10^4 m $^{-1}$, which is several orders of 233 magnitude larger than those achieved by four-point bend tests.³⁴ 234 It can thus be concluded that this large, location-dependent strain 235 gradient accounts for the piezoelectric enhancement. Further, 236 237 the lack of substrate clamping in the elevated buckles is also 238 expected to contribute to the increased piezoresponse.³⁷

In order to demonstrate a proof-of-principle test of wavy
 piezoelectric ribbons in stretchable systems, the ribbons were
 integrated into energy conversion devices. PDMS samples

containing wavy/buckled ribbons were contacted by two spots 242 of silver paint at the ribbon ends, connected to a current meter, 243 poled at 10 kV/cm for 5 h, and mounted on a tensile stage for 244 reversible stretching and releasing (strain $\sim 0-8\%$). Figure 5a 245 E5 schematically illustrates this experiment setup, while Figure 5b 246 shows the stretching stage and the ribbons under test, respec-247 tively. Peaks in the current signal were recorded at the moments 248 of stretching and releasing, as indicated in panels c and d of 249 Figure 5, which are from samples consisting of 5 wavy ribbons 250 (effective cross-sectional area, $A_{\rm cross} \approx 12.5 \times 10^{-6} \,\rm mm^2$) and 10 wavy ribbons ($A_{\rm cross} \approx 25 \times 10^{-6} \,\rm mm^2$), respectively. On the 251 252 basis of the current peaks, the current density is calculated to be *j* 253 = $I/A_{\rm cross} \approx 2.5 \,\mu {\rm A/mm^2}$, which compares favorably to the peak 254 current density measured in vertical PZT nanowire-based 255 devices.8 The energy harvesting here is explained by overall 256 changes in the midplane strain upon stretching and releasing, as 257 described by eq 3. 258

In summary, nanothick ribbons of the piezoelectric ceramic 259 PZT have been rendered stretchable via printing onto pre-260 strained elastomeric substrates and releasing the strain to form 261 buckled ribbons with engineered wavelengths and amplitudes. 262 The wavy shapes of the ribbons can accommodate order-of-263 magnitude larger poststrains relative to their flat counterparts 264 and thus are suitable for implementation in devices with challen-265 ging form factors. Further, the buckled ribbons display enhanced 266 piezoelectric performance, thereby representing a promising 267 hybrid materials platform for wearable or even implantable 268 energy harvesting devices (using encapsulated PDMS).²⁷ Yet, a 269 number of key challenges remain. In particular, future work will 270 help us understand in more detail: (1) the relative contributions 271 of substrate clamping and the flexoelectric effect enabled by the 272 strain gradient to the enhanced piezoelectric response, (2) the 273 ability to print buckled PZT ribbons over large areas, as has been 274

Nano Letters

accomplished with flat ribbons, and (3) a better understanding of
the hard inorganic/soft polymeric interface and its longevity
under mechanoelectrical cycling.

278 ASSOCIATED CONTENT

Supporting Information. Detailed analytical method for
 deriving the buckle wavelengths and amplitudes. This material is
 available free of charge via the Internet at http://pubs.acs.org.

282 **AUTHOR INFORMATION**

283 Corresponding Author

²⁸⁴ *E-mail: mcm@princeton.edu and purohit@seas.upenn.edu.

285 **ACKNOWLEDGMENT**

We acknowledge the use of the PRISM Imaging and Analysis 286 Center, which is supported by the NSF MRSEC Program via the 2.87 Princeton Center for Complex Materials (No. DMR-0819860). 288 P.K.P. acknowledges support of this work by the National 289 Science Foundation CAREER Award (No. CMMI-0953548). 290 M.C.M. acknowledges support of this work by the Defense 291 Advanced Research Projects Agency (No. N66001-10-1-2012) 292 and the National Science Foundation (No. NSF CMMI-293 1036055). 294

REFERENCES

- (1) Service, R. F. Science 2010, 328, 304-305.
- (2) Xu, S.; Qin, Y.; Xu, C.; Wei, Y.; Yang, R.; Wang, Z. L. Nat. Nanotechnol. 2010, 5, 366–373.
- (3) Yang, R.; Qin, Y.; Dai, L.; Wang, Z. L. Nat. Nanotechnol. 2009, 4, 34–39.
- (4) Yang, R.; Qin, Y.; Li, C.; Zhu, G.; Wang, Z. L. Nano Lett. 2009, 9, 1201–1205.
- 303 (5) Qi, Y.; Jafferis, N. T.; Lyons, K.; Lee, C. M.; Ahmad, H.;
 304 McAlpine, M. C. Nano Lett. 2010, 10, 524–528.
 - (6) Qi, Y.; McAlpine, M. C. Energy Environ. Sci. 2010, 3, 1275–1285.
 - (7) Starner, T. IBM Syst. J. 1996, 35, 618–629.
 - (8) Xu, S.; Hansen, B. J.; Wang, Z. L. Nat. Commun. 2010, 1, 93.
 - (9) Chang, C.; Tran, V. H.; Wang, J.; Fuh, Y.-K.; Lin, L. Nano Lett. 2010, 10, 726–731.
 - (10) Furukawa, T.; Seo, N. Jpn. J. Appl. Phys. 1990, 29, 675-680.

(11) Kim, H.; Tadesse, Y.; Priya, S. *Energy Harvesting Technologies*; Springer: New York, 2008.

- (12) Guillon, O.; Thiebaud, F.; Perreux, D. Int. J. Fract. 2002,
 117, 235–246.
- (13) Nguyen, T. D.; Nagarah, J. M.; Qi, Y.; Nonnenmann, S. S.;
 Morozov, A. V.; Li, S.; Arnold, C. B.; McAlpine, M. C. *Nano Lett.* 2010,
 10, 4595–4599.

(14) Martin, C. R.; Aksay, I. A. J. Phys. Chem. B 2003, 107, 4261–
 4268.

- (15) Park, K.-I.; Xu, S.; Liu, Y.; Hwang, G.-T.; Kang, S.-J. L.; Wang,
 Z. L.; Lee, K. J. Nano Lett. 2010, 10, 4939–4943.
- (16) Spanier, J. E.; Kolpak, A. M.; Urban, J. J.; Grinberg, I.; Lian,
 O. Y.; Yun, W. S.; Rappe, A. M.; Park, H. *Nano Lett.* 2006, *6*, 735–739.

O. Y.; Yun, W. S.; Rappe, A. M.; Park, H. Nano Lett. 2006, 6, 735–739.
 (17) Park, S. I.; Ahn, J. H.; Feng, X.; Wang, S. D.; Huang, Y. G.;

(17) Park, S. I.; Ahn, J. H.; Feng, X.; Wang, S. D.; Huang, Y. G.;
 Rogers, J. A. Adv. Funct. Mater. 2008, 18, 2673–2684.

- (18) Cho, J.-H.; Datta, D.; Park, S.-Y.; Shenoy, V. B.; Gracias, D. H.
 Nano Lett. 2010, 10, 5098–5102.
- (19) Khang, D.-Y.; Jiang, H.; Huang, Y.; Rogers, J. A. Science 2006,
 311, 208–212.

(20) Sun, Y. G.; Kumar, V.; Adesida, I.; Rogers, J. A. Adv. Mater.
 2006, 18, 2857–2862.

(21) Lacour, S. P.; Jones, J.; Wagner, S.; Li, T.; Suo, Z. Proc. IEEE **2005**, 93, 1459–1467.

(22) Bowden, N.; Brittain, S.; Evans, A. G.; Hutchinson, J. W.; Whitesides, G. M. *Nature* **1998**, 393, 146–149.

(23) Ko, H. C.; Baca, A. J.; Rogers, J. A. Nano Lett. 2006, 6, 2318–2324.

(24) Song, J.; Jiang, H.; Liu, Z. J.; Khang, D. Y.; Huang, Y.; Rogers, J. A.; Lu, C.; Koh, C. G. *Int. J. Solids Struct.* **2008**, *45*, 3107–3121.

(25) Xiao, J.; Carlson, A.; Liu, Z. J.; Huang, Y.; Rogers, J. A. J. Appl. Mech. 2010, 77, No. 011003.

- (26) Song, J.; Huang, Y.; Xiao, J.; Wang, S.; Hwang, K. C.; Ko, H. C.; Kim, D. H.; Stoykovich, M. P.; Rogers, J. A. *J. Appl. Phys.* **2009**, *105*, No. 123516.
- (27) Sun, Y.; Choi, W. M.; Jiang, H.; Huang, Y. Y.; Rogers, J. A. Nat. Nanotechnol. **2006**, *1*, 201–207.

(28) Rossetti, J.; George, A.; Cross, L. E.; Kushida, K. *Appl. Phys. Lett.* **1991**, *59*, 2524–2526.

- (29) Lee, J. W.; Lee, S. M.; Park, C. S.; Park, G. T.; Kim, H. E. J. Sol-Gel Sci. Technol. 2007, 42, 305-308.
- (30) Lu, X. M.; Zhu, J. S.; Li, X. L.; Zhang, Z. G.; Zhang, X. S.; Wu, D.; Yan, F.; Ding, Y.; Wang, Y. *Appl. Phys. Lett.* **2000**, *76*, 3103–3105.
- (31) Kumazawa, T.; Kumagai, Y.; Miura, H.; Kitano, M.; Kushida, K. *Appl. Phys. Lett.* **1998**, 72, 608–610.
- (32) Kelman, M. B.; McIntyre, P. C.; Hendrix, B. C.; Bilodeau, S. M.; Roeder, J. F. J. Appl. Phys. **2003**, 93, 9231–9236.
 - (33) Ma, W.; Cross, L. E. Appl. Phys. Lett. **2005**, 86, No. 072905.
 - (34) Ma, W. H.; Cross, L. E. Appl. Phys. Lett. 2003, 82, 3293-3295.

(35) Majdoub, M. S.; Sharma, P.; Cagin, T. Phys. Rev. B 2008, 77, No.

- 125424.
- (36) Nonnenmann, S. S.; Leaffer, O. D.; Gallo, E. M.; Coster, M. T.; Spanier, J. E. *Nano Lett.* **2010**, *10*, 542–546.

(37) Torah, R. N.; Beeby, S. P.; White, N. M. J. Phys. D: Appl. Phys. 2004, 37, 1074–1078.

(38) Bonnell, D. A.; Kalinin, S. V.; Kholkin, A. L.; Gruverman, A. *MRS Bull.* **2009**, *34*, 648–657.

(39) Kalinin, S. V.; Bonnell, D. A. *Phys. Rev. B* **2002**, 65, No. 125408.

333

334

335

336

337

338

339

340

341

342

343

344

345

346

347

348

349

350

351

352

353

354

355

356

357

358

359

360

361

362

363

364

365

366

367

LETTER

295

296

297

298

299

300

301 302

305

306 307

308

309 310

311

312

Derivation of equations for the amplitude and wavelength

Our goal in this part of the supplement is to obtain analytical expressions for the dependence of the wavelength and amplitude of the buckled regions of the PZT ribbons adhered to the PDMS substrate. Our expressions will also give us estimates of the strain-gradient and mid-plane stress/strain in the PZT ribbons. These quantities play a significant role in determining the piezoelectric response of the PZT ribbons. Our analysis follows the framework of Song *et al.* to which we add an adhesion energy term.

In our experiments PZT ribbons about 250-500nm thick adhere to pre-strained PDMS substrates that are about 2-3mm thick. For large pre-strains the PZT ribbons 'de-adhere' upon relaxation (see fig. S1). The deflection of the neutral plane of the PZT ribbon is assumed to be given by w(X) for $-\frac{L_0}{2} \le X \le \frac{L_0}{2}$, where:

$$w(X) = \frac{A}{2} \left(1 + \cos \frac{2\pi X}{L_0} \right) = \frac{A}{2} \left(1 + \cos \frac{2\pi x}{L} \right),\tag{1}$$

where A is the amplitude of the sinusoidally buckled region, L is the wavelength of the buckled sinusoid



Fig. S1: Schematic of the experiment. (a) PZT ribbons of thickness $h \approx 250 - 500$ nm are adhered to prestrained PDMS of thickness 2-3mm. (b) When the PDMS is allowed to relax the PZT ribbons 'de-adhere' in some regions to form sinusoidal buckled shapes. The red lines in the ribbon are in compression and the green lines are in tension. The neutral plane or mid-plane is the black dashed line. The deflection of the neutral plane is given by w(X) where X refers to a material point on the neutral plane. The wavelength of the sinusoidal buckled region is L in the deformed configuration. $L(1 + \epsilon_{pre}) = L_0$ where ϵ_{pre} is the pre-strain applied on the PDMS.

in the deformed or current configuration, L_0 is the wavelength in the reference configuration, x(X) = X + u(X) is the current position of a material point X and u(X) is the displacement in the X direction. Note that L and L_0 are simply related through the pre-strain which is prescribed in the experiment:

$$\epsilon_{pre} = \frac{L_0}{L} - 1. \tag{2}$$

We have assumed in writing the above expression that the PDMS is completely relaxed. This is a good assumption since the PDMS is few thousand times thicker than the PZT ribbons. Both A and L_0 (or L) are unknown and our goal is to determine how these quantities vary with the pre-strain ϵ_{pre} . We will do so by minimizing the energy with respect to A and L_0 . To calculate the energy we first need to know the uniaxial strain in the mid-plane and the bending strain which vary through the thickness of the ribbon. Note that for

a beam with large deflections and moderate rotations

$$\frac{dw}{dX} = -\frac{A\pi}{L_0} \sin \frac{2\pi X}{L_0},\tag{3}$$

$$\frac{d^2w}{dX^2} = -\frac{2A\pi^2}{L_0^2}\cos\frac{2\pi X}{L_0},$$
(4)

$$\epsilon_{mid} = \frac{du}{dX} + \frac{1}{2} \left(\frac{dw}{dX}\right)^2.$$
(5)

The mid-plane force per unit breadth is $N = Eh\epsilon_{mid}$ and we expect from equilibrium that $\frac{dN}{dX} = 0$ since there are no body forces in the X-direction. By substituting the expressions for w(X), $\frac{dw}{dX}$ etc., we can integrate $\frac{dN}{dX} = 0$ once and obtain:

$$\frac{du}{dX} = \frac{A^2 \pi^2}{4L_0^2} \cos \frac{4\pi X}{L_0} + C_1,$$
(6)

so that, after one more integration,

$$u(X) = \frac{A^2 \pi}{L_0} \sin \frac{4\pi X}{L_0} + C_1 X + C_2,$$
(7)

where C_1 and C_2 are integration constants. Now by requiring that $u(\frac{L_0}{2}) - u(-\frac{L_0}{2}) = L$ we find $C_1 = \frac{L}{L_0} - 1$. Now using the expression for $\frac{dw}{dX}$ we find that

$$\epsilon_{mid} = \frac{du}{dX} + \frac{1}{2} \left(\frac{dw}{dX}\right)^2 = \frac{\pi^2 A^2}{4L_0^2} + \frac{L}{L_0} - 1, = \frac{\pi^2 A^2}{4L_0^2} - \frac{\epsilon_{pre}}{1 + \epsilon_{pre}},\tag{8}$$

which is independent of X. This means that the mid-plane strain ϵ_{mid} and stress (which is $\sigma_{mid} = E\epsilon_{mid}$) are same everywhere in the buckled parts of the PZT ribbon and are a function of pre-strain only since A and L_0 are functions of pre-strain only. We are now ready to compute the energy of the configuration described by w(X). The energy is composed of a bending energy U^{bend} , a mid-plane energy U^{mid} , and an adhesion energy U^{adh} . In the following we compute all contributions to the energy per unit breadth of the PZT ribbons.

$$U^{bend} = \int_{-\frac{L_0}{2}}^{+\frac{L_0}{2}} \frac{1}{2} \frac{Eh^3}{12} \left(\frac{d^2w}{dX^2}\right)^2 dX = \frac{Eh^3}{12} \frac{\pi^4 A^2}{L_0^3},\tag{9}$$

$$U^{mid} = \int_{-\frac{L_0}{2}}^{+\frac{L_0}{2}} \frac{1}{2} Eh\epsilon_{mid}^2 \, dX = \frac{1}{2} EhL_0 \left(\frac{\pi^2 A^2}{4L_0^2} - \frac{\epsilon_{pre}}{1 + \epsilon_{pre}}\right)^2,\tag{10}$$

$$U^{adh} = W_{ad}L_0. (11)$$

where W_{ad} is the adhesion energy per unit area between the PZT and PDMS. Note that de-adhering of the ribbon over length L_0 causes an increase in the energy of the ribbon just as bending and compressing it does. The total energy of the ribbon is then

$$U^{tot}(A, L_0) = \frac{Eh^3}{12} \frac{\pi^4 A^2}{L_0^3} + \frac{1}{2} EhL_0 \left(\frac{\pi^2 A^2}{4L_0^2} - \frac{\epsilon_{pre}}{1 + \epsilon_{pre}}\right)^2 + W_{ad}L_0.$$
 (12)

To find A and L_0 we set

$$\frac{\partial U^{tot}}{\partial A} = 0, \qquad \frac{\partial U^{tot}}{\partial L_0} = 0.$$
 (13)



Fig. S2: Comparison of two theories for buckling of PZT ribbons with experimental data. In both the panels, the blue solid line and blue dashed line correspond to h = 500nm, while the red solid and dashed line correspond to h = 250nm. The solid lines assume that the ribbons de-adhere and buckle, while the dashed lines assume that the ribbons buckle without de-adhering. (a) plots the amplitude, and (b) plots the wavelength as functions of the pre-strain. It is clear that the theory which assumes de-adhering of the ribbons captures the trends seen in the experimental data.

Note that minimizing with respect to the wavelength L in the deformed configuration is equivalent to minimizing with respect to L_0 since they are related through the given value of ϵ_{pre} . Setting the derivatives above to zero yields two equations:

$$\frac{\pi^2 h^2}{3L_0^2} + \frac{\pi^2 A^2}{4L_0^2} - \frac{\epsilon_{pre}}{1 + \epsilon_{pre}} = 0, \qquad (14)$$

$$-\frac{\pi^4 A^2 h^2}{2L_0^4} - \frac{3\pi^4 A^4}{16L_0^4} + \left(\frac{\epsilon_{pre}}{1+\epsilon_{pre}}\right)^2 + \frac{\pi^2 A^2}{2L_0^2} \frac{\epsilon_{pre}}{1+\epsilon_{pre}} + \frac{2W_{ad}}{Eh} = 0.$$
(15)

These are two simultaneous equations in the two unknowns A and L_0 , and they can be solved to give,

$$L_0 = \frac{\pi h}{\sqrt{\frac{\epsilon_{pre}}{1 + \epsilon_{pre}} - \sqrt{\frac{\epsilon_{pre}^2}{(1 + \epsilon_{pre})^2} - \frac{6W_{ad}}{Eh}}},$$
(16)

$$A = \frac{2L_0}{\pi} \sqrt{\frac{\epsilon_{pre}}{1 + \epsilon_{pre}}} - \frac{\pi^2 h^2}{3L_0^2}.$$
(17)

The wavelength in the deformed or current configuration can be computed immediately as $L = \frac{L_0}{1 + \epsilon_{pre}}$. The expression for L_0 involves a square root in the denominator. To ensure that we have real values of L_0 (or the wavelength) we require

$$\frac{\epsilon_{pre}^2}{(1+\epsilon_{pre})^2} \ge \frac{6W_{ad}}{Eh},\tag{18}$$

which boils down to $\epsilon \geq \epsilon_c$ where ϵ_c is a critical strain and is given by

$$\epsilon_c = \frac{1}{\sqrt{\frac{Eh}{6W_{ad}} - 1}}.$$
(19)

The critical strain ϵ_c increases as W_{ad} increases, which is in agreement with intuition. The expressions for L_0 and A above are similar to those for the case when the ribbons buckle into sinusoidal patterns while still being totally adhered to the substrate. The expressions for L_0 and A for the totally adhered case are:

$$L_0 = \frac{\pi h}{\sqrt{\epsilon_c}},\tag{20}$$

$$A = h\sqrt{\frac{\epsilon_{pre}}{\epsilon_a} - 1},\tag{21}$$

where $\epsilon_a = 0.52 \left[\frac{E_{sub}(1-\nu_{rib}^2)}{E_{rib}(1-\nu_{sub}^2)}\right]^{2/3}$ is a critical strain for buckling, and E_{rib} and ν_{rib} are the Young's modulus and Poisson ratio for the ribbon material and E_{sub} and ν_{sub} are the corresponding quantities for the substrate material. Fig. S2 shows the curves obtained from both these theories (buckling with de-adhering, and without de-adhering) together with the experimental data. The wavelength of the sinusoids in the fully adhered case is a constant independent of the pre-strain. This is not the case in our experiments. Furthermore, the amplitudes in the fully adhered case are much smaller than those seen in the experiments except for very small pre-strains. On the other hand, the predicted wavelength and amplitude of the sinusoidal buckles assuming de-adhering of the ribbons match the experimental data very well. This, together with the EM images in the main text, suggests that this is a case of moderate adhesion where releasing the pre-strain results in a competition between adhesion energy and bending energy in the ribbons.



Fig. S3: Mid-plane stress (a) and strain gradients (b) as functions of the pre-strain. The mid-plane stress is always compressive and the strain gradients through the thickness are large.

The strain gradient through the thickness of the ribbon (due to bending) is nothing but the curvature $\frac{d^2w}{dX^2} = -\frac{2A\pi^2}{L_0^2}\cos\frac{2\pi X}{L_0}$. The strain gradient is a function of X and it changes sign at $X = \pm \frac{L_0}{4}$. The maximum magnitude of the strain gradient is $\frac{2\pi^2 A}{L_0^2}$ and it occurs at the center and the two ends of the buckled region. Note that using the expression for A we can write the mid-plane strain, $\epsilon_{mid} = -\frac{\pi^2 h^2}{3L_0^2}$, which is always compressive. This, again, is in agreement with intuition. In fig. S3 we plot the mid-plane stress and the strain gradient as functions of pre-strain. Note that the strain-gradients are very large and could lead to the 'flexoelectric' effect in the PZT ribbons.