

Simple Unification-based Type Inference for GADTs

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Abstract

Generalized algebraic data types (GADTs), sometimes known as “guarded recursive data types” or “first-class phantom types”, are a simple but powerful generalization of the data types of Haskell and ML. Recent works have given compelling examples of the utility of GADTs, although type inference is known to be difficult. Our contribution is to show how to exploit programmer-supplied type annotations to make the type inference task almost embarrassingly easy. Our main technical innovation is *wobbly types*, which express in a declarative way the uncertainty caused by the incremental nature of typical type-inference algorithms.

Categories and Subject Descriptors D.3.3 [PROGRAMMING LANGUAGES]: Language Constructs and Features—abstract data types, polymorphism

General Terms Languages, Theory

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1. Introduction

Generalized algebraic data types (GADTs) are a simple but potent generalization of the recursive data types that play a central role in ML and Haskell. In recent years they have appeared in the programming language literature with a variety of names (guarded recursive data types [25], first-class phantom types [5], equality-qualified types [18], and so on), although they have a much longer history in the dependent types community. Any feature with so many names must be useful—and indeed these papers and others give many compelling examples.

It is time to turn GADTs from a specialized hobby into a mainstream programming technique, by incorporating them as a conservative extension of Haskell (a similar design would work for ML). The main challenge is integrating GADTs with *type inference*, a dominant feature of Haskell and ML.

Rather than seeking a super-sophisticated inference algorithm, an increasingly popular approach is to guide type inference using programmer-supplied type annotations. With this in mind, our central focus is this: *we seek a declarative type system for a language that includes both GADTs and programmer-supplied type annotations, which has the property that type inference is straightforward*. Our goal is a type system that is *predictable* enough to be used by

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ordinary programmers; and *simple* enough to be implemented without heroic efforts. We make the following specific contributions:

- We specify a programming language that supports GADTs and programmer-supplied type annotations (Section 4). The key innovation in the type system is the notion of a *wobbly type* (Section 3), which models the places where an inference algorithm would “guess”. The idea is that type refinements induced by GADTs never refine wobbly types, and hence type inference is insensitive to the order in which the algorithm traverses the abstract syntax tree.
- Like any system making heavy use of type annotations, we offer support for lexically scoped type variables that can be bound by both polymorphic type signatures and signatures on patterns (Section 4.5 and 5.5). There is no rocket science here, but we think our design is particularly simple and easy to specify, certainly compared to our earlier efforts.
- We explore a number of extensions to the basic system, including improved type checking rules for patterns and case expression scrutinees, and nested patterns (Section 5).
- We prove that our type system is sound, and that it is a conservative extension of a standard Hindley-Milner type system (Section 6). Moreover our language can express all programs that an explicitly-typed language could express.
- We sketch a type inference algorithm for our type system that is a modest variant of the standard algorithm for Hindley-Milner type inference. We prove that this algorithm is sound and complete (Section 6.3).

Space restrictions prohibit a complete presentation of these contributions. The details of the algorithm and related technical material are given in a companion technical report [23]¹.

We have implemented type inference for GADTs, using wobbly types, in the Glasgow Haskell Compiler (GHC). GHC’s type checker is already very large; not only does it support Haskell’s type classes, but also numerous extensions, such as functional dependencies, implicit parameters, arbitrary-rank types, and more besides. An extension that required all this to be re-engineered would be a non-starter, and it is here that the simplicity of our GADT inference algorithm pays off. In particular, we have successfully extended GHC to support *both* GADTs and impredicative polymorphism (described in a companion paper in this volume [22]), without undesirable interactions with each other, or with existing features.

Our implementation has already received heavy use. The released implementation in GHC uses a more complicated scheme than that described here, originally given in an earlier version of this paper (see Section 7). We are in the midst of re-engineering the implementation to match what we describe in this revised, simpler version.

¹ www.cis.upenn.edu/~dimitriv/dimitriv-inference.html

2. Background

By way of background, we use a standard example to remind the reader of the usefulness of GADTs. Here is a declaration of a `Term` data type for a simply-typed language:

```
data Term a where
  Lit  :: Int -> Term Int
  Inc  :: Term Int -> Term Int
  IsZ  :: Term Int -> Term Bool
  If   :: Term Bool -> Term a -> Term a -> Term a
  Pair :: Term a -> Term b -> Term (a,b)
  Fst  :: Term (a,b) -> Term a
  Snd  :: Term (a,b) -> Term b
```

`Term` has a type parameter `a` that indicates the type of the term it represents, and the declaration enumerates the constructors, giving each an explicit type signature. We note that the type parameter `a` is a “dummy” parameter used only to indicate the kind of `Term`, and does not scope over the types of the constructors. All type variables in the types of constructors are implicitly universally quantified. We adopt this convention for the examples appearing in the rest of this paper. Equivalently one could write

```
data Term :: * -> * where ...
```

The type signatures of the constructors only allow one to construct well-typed terms; for example, the term `(Inc (IsZ (Lit 0)))` is rejected as ill-typed, because `(IsZ (Lit 0))` has type `Term Bool` and that is incompatible with the argument type of `Inc`.

An evaluator for terms is stunningly direct:

```
eval :: Term a -> a
eval (Lit i)    = i
eval (Inc t)   = eval t + 1
eval (IsZ t)   = eval t == 0
eval (If b t e) = if eval b then eval t else eval e
eval (Pair a b) = (eval a, eval b)
eval (Fst t)   = fst (eval t)
eval (Snd t)   = snd (eval t)
```

It is worth studying this definition. Note that the right hand side of the first equation patently has type `Int`, not `a`. But, if the argument to `eval` is a `Lit`, then the type parameter `a` must be `Int` (because the `Lit` constructor only produces terms of type `Term Int`), and so the right hand side has type `a` also. Similarly, the right hand side of the third equation has type `Bool`, but in a context in which `a` must be `Bool`. And so on.

The key ideas of the semantics for GADTs are these:

- A generalized data type is declared by enumerating its constructors, giving an explicit type signature for each. In conventional data types in Haskell or ML, the result type of a data constructor must be the type constructor applied to all of the type parameters of the data constructor. In a generalized data type, the result type must still be an application of the type constructor, but the argument types are arbitrary. For example `Lit` mentions no type variables, `Pair` has a result type with structure `(a,b)`, and `Fst` mentions some, but not all, of its universally-quantified type variables.
- The data constructors are functions with ordinary polymorphic types. There is nothing special about how they are used to construct terms, apart from their unusual types.
- All the excitement lies in pattern matching. Matching against a constructor may induce a *type refinement* in the case alternative. For example, in the `Lit` branch of `eval`, we can refine `a` to `Int`.
- The dynamic semantics is unchanged. Pattern-matching is done on data constructors only and there is no run-time type passing.

The `eval` function is a somewhat specialized example, but earlier papers have given many other applications of GADTs, including

generic programming, modeling programming languages, maintaining invariants in data structures (e.g. red-black trees), expressing constraints in domain-specific embedded languages (e.g. security constraints), and modeling objects [8, 25, 5, 18, 16, 17]. The interested reader should consult these works; meanwhile, for this paper we simply take it for granted that GADTs are useful.

3. The key idea

Our goal is to combine the flexibility of Hindley-Milner type inference with the expressiveness of GADTs, by using the programmer’s annotations to guide type inference. Furthermore, we seek a system that gives as much freedom as possible to the inference algorithm. For example, we would like to retro-fit GADT inference to existing compilers, as well as use it in new ones.

The difficulty with type inference for GADTs is well illustrated by the `eval` example of Section 2. In the absence of the type signature for `eval`, a type inference engine would have to anti-refine the `Int` result type for the first two equations, and the `Bool` result type of the third (etc.), to guess that the overall result should be of type `a`. Such a system would certainly lack principal types. Furthermore, polymorphic recursion is required: for example, the recursive call to `eval` in the second equation is at type `Int`, not `a`. All of these problems go away when the programmer supplies the type of `eval`.

Furthermore, the complete type of a function that uses GADTs is required, because, even if the return type is clear, type inference may still be challenging. Here is another variant:

```
f x y = case x of
  Lit i -> i + y
  other -> 0
```

There are at least two types one could attribute to `f`, namely `Term a -> Int -> Int` and `Term a -> a -> Int`. The latter works because type refinement induced by the pattern match on `x` refines the type of `y`. Alas, neither is more general than the other. Again, a programmer-supplied type signature would solve the problem.

Thus motivated, our main idea is the following:

Type refinement applies only to user-specified types.

In the case of `f`, since there are no type annotations, no type refinement will take place: `x` must have type `Term Int` and `y` will get type `Int`. However, if the programmer adds a type annotation, the situation is quite different:

```
f :: Term a -> a -> Int
f x y = case x of
  Lit i -> i + y
  other -> 0
```

Now it is “obvious” that `x` has type `Term a` and `y` has type `a`. Because the scrutinee of the `case` has the user-specified type `Term a`, the `case` expression does type refinement, and in the branch the type system knows that `a = Int`. Because the type of `y` is also user-specified, this type refinement is applied when `y` occurs in the right hand side.

To summarise, our general approach is this:

- Instead of “user-specified type”, we use the briefer term *rigid type* to describe a type that is completely specified, in some direct fashion, by a programmer-supplied type annotation.
- A *wobbly type* is one that is not rigid. There is no such thing as a partly-rigid type; if a type is not rigid, it is wobbly².
- A variable is assigned a rigid type if it is clear, *at its binding site*, precisely what its type should be.

²In an earlier version of this paper, types were allowed to have both rigid and wobbly components (Section 7).

<p>—Source language syntax—</p> <p>Atoms $c ::= x \mid C$</p> <p>Terms $t, u ::= c \mid \lambda x.t \mid t\bar{u}$</p> <ul style="list-style-type: none"> let $x = u$ in t let $x::sig = u$ in t case t of $p \rightarrow t$ <p>Patterns $p ::= x \mid C\bar{p} \mid p::tau$</p> <p>Type annotations $sig ::= forall \bar{a}.tau$</p> <p>$\tau ::= tau \rightarrow tau \mid a \mid T\bar{\tau}$</p> <p>Polytypes $\sigma ::= \forall \bar{a}.\tau$</p> <p>Monotypes $\tau, v ::= \tau \rightarrow \tau \mid a \mid T\bar{\tau}$</p>
<p>—Meta language syntax—</p> <p>Environments $\Gamma, \Delta ::= \cdot \mid \Gamma, c :^m \sigma \mid \Gamma, a \hookrightarrow \tau$</p> <p>Modifiers $m, n ::= w \mid r$</p> <p>Refinements $\theta, \psi ::= [\bar{a} \mapsto \bar{\tau}]$</p> <p>Triples $K, L ::= (\bar{a}, \Delta, \theta)$</p>

$$\begin{array}{lll} \text{—Annotation translation—} \\ \llbracket a \rrbracket_{\Gamma} & = \Gamma(a) \\ \llbracket tau_1 \rightarrow tau_2 \rrbracket_{\Gamma} & = \llbracket tau_1 \rrbracket_{\Gamma} \rightarrow \llbracket tau_2 \rrbracket_{\Gamma} \\ \llbracket T\bar{tau} \rrbracket_{\Gamma} & = T \llbracket tau \rrbracket_{\Gamma} \\ \llbracket forall \bar{a}.tau \rrbracket_{\Gamma} & = \forall \bar{a}. \llbracket tau \rrbracket_{\Gamma, a \hookrightarrow \bar{a}} \quad \bar{a} \text{ fresh} \end{array}$$

$$\begin{array}{lll} \text{—Refinement application—} \\ \theta^r(\sigma) = \theta(\sigma) & \theta(\cdot) = \cdot \\ \theta^w(\sigma) = \sigma & \left| \begin{array}{ll} \theta(\Gamma, c :^m \sigma) = \theta(\Gamma), c :^m \theta^m(\sigma) \\ \theta(\Gamma, a \hookrightarrow \tau) = \theta(\Gamma), a \hookrightarrow \theta(\tau) \end{array} \right. \end{array}$$

Figure 1: Syntax of source language and types

- A `case` expression performs type refinement in each of its alternatives only if its scrutinee has a rigid type.
- The type of a variable occurrence is refined by the current type refinement only if the variable has a rigid type.

But exactly when is a type “completely specified by a type annotation”? After all, no type annotation decorates the binding for x in the definition of f above, nor is the `case` expression adorned with a result type, and yet we argued above that both should be rigid. Would it make any difference if we had written `case (id x) of ...`, where `id` is the identity function?

To answer these questions, we need a precise and predictable description of what it means for a type to be rigid, which is what our type system provides.

4. The type system

The syntax of a language with GADTs is shown in Figure 1, and is entirely conventional. We use $\bar{\cdot}$ to represent a sequence of elements. For example, \bar{p} abbreviates the sequence of patterns $p_1 \dots p_n$. We assume that data types are declared by simply enumerating the constructors and their types (as in Section 2), and those typings are used to pre-populate the type environment Γ . The `let` binding form is recursive. Pattern matching is performed only by `case` expressions, but we will occasionally take the liberty of writing $\lambda p.t$ instead of $\lambda x.\text{case } x \text{ of } p \rightarrow t$.

The language of types is also entirely conventional, stratified into *polytypes* σ and quantifier-free *monotypes* τ . We abbreviate polytypes that bind no type variables ($\forall \cdot$) as τ . We use a different syntactic domain for programmer-supplied type annotations, `sig` and `tau`. Such annotations appear in the syntax of the source language in two places: a `let` definition may be annotated with a polytype, or a pattern may be annotated with a monotype. Haskell also allows an expression to be annotated with a

$\boxed{\Gamma \vdash t :^m \tau}$ $\frac{c :^n \forall \bar{a}.\tau \in \Gamma}{\Gamma \vdash c :^m [\bar{a} \mapsto \bar{v}] \tau} \text{ ATM}$ $\frac{\Gamma \vdash t :^w \tau_1 \rightarrow \tau_2 \quad \Gamma \vdash u :^w \tau_1}{\Gamma \vdash t u :^m \tau_2} \text{ APP}$ $\frac{\Gamma, x :^m \tau_1 \vdash t :^m \tau_2}{\Gamma \vdash \lambda x.t :^m \tau_1 \rightarrow \tau_2} \text{ ABS}$ $\frac{\bar{a} = \text{ftv}(\tau_1) - \text{ftv}(\Gamma) \quad \Gamma, x :^w \forall \bar{a}.\tau_1 \vdash t :^m \tau_2}{\Gamma \vdash (\text{let } x = u \text{ in } t) :^m \tau_2} \text{ LET-W}$ $\frac{\Gamma, x :^r \forall \bar{a}.\tau_1, \bar{a} \hookrightarrow \bar{a} \vdash u :^r \tau_1 \quad \Gamma, x :^r \forall \bar{a}.\tau_1 \vdash t :^m \tau_2}{\Gamma \vdash (\text{let } x :: \text{forall } \bar{a}.tau = u \text{ in } t) :^m \tau_2} \text{ LET-R}$ $\frac{\Gamma \vdash u : \tau_p \mid ^{m_p} \quad \Gamma \vdash p \rightarrow t :^{(m_p, m_t)} \tau_p \rightarrow \tau_t}{\Gamma \vdash (\text{case } u \text{ of } p \rightarrow t) :^{m_t} \tau_t} \text{ CASE}$
$\boxed{\Gamma \vdash t : \tau \mid^m}$ $\frac{v :^m \tau \in \Gamma}{\Gamma \vdash v : \tau \mid^m} \text{ SCR-VAR}$ $\frac{\Gamma \vdash t :^w \tau}{\Gamma \vdash t : \tau \mid^w} \text{ SCR-OTHER}$
$\boxed{\Gamma \vdash p \rightarrow t :^{(m_p, m_t)} \tau_p \rightarrow \tau_t}$ $\frac{\begin{array}{c} C :^r \forall \bar{a}.\bar{\tau}_1 \rightarrow T\bar{\tau}_2 \in \Gamma \quad \bar{a} \# \text{ftv}(\Gamma, \bar{\tau}_p, \tau_t) \\ \bar{a}_c = \bar{a} \cap \text{ftv}(\bar{\tau}_2) \quad \theta = [\bar{a}_c \mapsto \bar{v}] \quad \theta(\bar{\tau}_2) = \bar{\tau}_p \end{array}}{\Gamma, x :^w \theta(\tau_1) \vdash t :^m \tau_t} \text{ PCON-W}$ $\frac{\begin{array}{c} C :^r \forall \bar{a}.\bar{\tau}_1 \rightarrow T\bar{\tau}_2 \in \Gamma \quad \bar{a} \# \text{ftv}(\Gamma, \bar{\tau}_p, \tau_t) \\ \theta \in \text{fmgu}(\bar{\tau}_p \doteq \bar{\tau}_2) \quad \theta(\Gamma, x :^r \tau_1) \vdash t :^m \theta^m(\tau_t) \end{array}}{\Gamma \vdash C \bar{x} \rightarrow t :^{(r, m)} T\bar{\tau}_p \rightarrow \tau_t} \text{ PCON-R}$

Figure 2: Typing rules and case alternatives

type, thus $(e :: sig)$. We interpret this form as syntactic sugar for $(\text{let } x :: sig = e \text{ in } x)$. We often use the term *type signature* for a programmer-supplied type annotation.

The type environment Γ is more unusual. Each variable (or constructor) binding $c :^m \sigma$ is annotated with a modifier, m , which indicates whether the type is rigid (r) or wobbly (w). Types of constructors are always closed and rigid. Furthermore the type environment maps *lexically scoped type variables*, a , to rigid types, as we discuss in Section 4.5. This last binding form allows us to translate a (possibly open) type annotation `sig` to an internal type σ , which we write as $\llbracket sig \rrbracket_{\Gamma} = \sigma$. We write $\Gamma(a) = \tau$ whenever $a \hookrightarrow \tau \in \Gamma$.

A *type refinement*, θ , is simply a substitution mapping type variables to monotypes. (One can also represent the type refinement as a set of constraints, an alternative that we discuss in Section 4.3.) The operation $\theta(\Gamma)$ applies the type refinement θ to the context Γ , and is also defined in Figure 1. The key thing to note is that only the rigid bindings in Γ are affected. We write $\text{dom}(\theta)$ for the finite

set of type variables for which θ is not the identity. Concretely, we represent a substitution by listing the non-identity mappings $[\overline{a} \mapsto \overline{\tau}]$, and use ϵ for the identity-everywhere substitution.

We use $\text{ftv}(\tau)$ to denote the free type variables of the type τ . Abusing the notation we write $\text{ftv}(\overline{\tau})$ to denote the union of the sets of free variables of every τ in $\overline{\tau}$. Additionally, we write $\text{ftv}(\Gamma)$ for the free type variables appearing in the environment Γ , either in the types that lexical variables bind, or in the types that term variables bind. We write $\text{dom}(\Gamma)$ to refer to the collection of all lexical and term variables bound in Γ .

4.1 Typing rules: overview

The typing rules for the language are syntax-directed and are given in Figure 2. The main judgement has the form $\Gamma \vdash t :^m \tau$. The unusual feature is the modifier m , which indicates whether the type τ is rigid. In algorithmic terms, $\Gamma \vdash t :^r \tau$ checks that t has type τ *when we know τ completely in advance*, whereas $\Gamma \vdash t :^w \tau$ checks that t has type τ without that assumption— τ may be partially or entirely unknown.

The modifier m propagates information about type rigidity. For example, in rule LET-R we see that a *type-annotated let* binding causes the right hand side u to be type-checked in a rigid context $(\dots \vdash u :^r \tau)$. (The notation $\overline{a} \# \text{ftv}(\Gamma)$ means that the type variables \overline{a} do not appear in Γ .) Furthermore, when typechecking u , the environment Γ is extended with a rigid binding for x , giving its specified, polymorphic type, thereby permitting polymorphic recursion, which is very often necessary in GADT programs (e.g. eval in Section 2).

Then, in rule ABS we see that to type check an abstraction $\lambda x. t$ we extend the environment Γ with a binding for x that is rigid if the context is rigid, and vice versa. For example, consider the term

```
let f::(forall a.Term a→a→a) = λx.λy.u in t
```

The body u of the abstraction will be type checked in an environment that has rigid bindings for both x and y (as well as f).

The APP rule always typechecks both function and argument in a wobbly context: even if the result type is entirely known, the function and argument types are not. One might wonder whether the function might provide a rigid context for its argument, or vice versa, but APP does not attempt such sophistication (but see Section 5.1).

Rule ATM does not use the modifier n of the variable (or constructor) type in the environment. It merely checks that the type of the variable (or constructor) in the environment can be instantiated to the type given by the judgement.

The really interesting rule is, of course, that for case, which we discuss next. For the moment we restrict ourselves to flat patterns, of form $C \overline{x}$, leaving nested patterns for Section 5.4.

4.2 Pattern matching

A case expression only performs type refinement if the scrutinee has a rigid type. The auxiliary judgement $\Gamma \vdash t : \tau \upharpoonright^m$, defined in Figure 2, determines whether the scrutinee is rigid. Rather than pushing the modifier inwards as the main judgement does, it *infers* the modifier. The judgement has just one interesting case, the one for variables. Rule SCR-VAR returns the modifier found for the variable in Γ ; otherwise the judgement conservatively returns a wobbly modifier w (SCR-OTHER)³. We will extend this judgement later, in Section 5.1.

Rule CASE first uses this new judgement to typecheck the scrutinee u and then typechecks each alternative, passing in both the

³To be truly syntax-directed, SCR-OTHER would need a side condition to exclude the variable case.

rigidity of the scrutinee, m_p , and the rigidity of the result type, m_t .

The case-alternative rules are also given in Figure 2. There are two cases to consider. Rule PCON-W is used when the scrutinee has a wobbly type. In that case, we use ordinary Hindley-Milner type checking. We look up the constructor C in the type environment, α -rename its quantified type variables to avoid ones that are in use, and then find a substitution θ that makes the result type of the constructor $T \overline{\tau}_2$ match the type of the pattern $T \overline{\tau}_p$. Finally, we extend Γ with wobbly bindings for the variables \overline{x} (obtained by instantiating the constructor’s type), and type check the right hand side of the alternative, t .

One subtle point is that the constructor may bind *existential* type variables. For example, suppose $\text{MkT} :: \forall a.b \rightarrow (a \rightarrow b) \rightarrow T b$. Then the type variable a is existentially bound by a pattern for MkT , because a does not appear in the result type $T b$. Clearly, we must not substitute for a ; for example, this term is ill-typed, if $x : \text{MkT} \text{ Bool}$:

```
case x of MkT r s -> r+t
```

We must form the substitution $[b \mapsto \text{Bool}]$ to make the result type of the constructor match that of x , but a is simply a fresh skolem constant. That is why PCON-W first computes \overline{a}_c , the subset of C ’s quantified variables that appear in its result type, and permits only these variables in the domain of θ .

Rule PCON-W gives a wobbly type to *all* the bound variables \overline{x} , which is safe but pessimistic; for example above, r could have a rigid type. We return to this question in Section 5.3.

4.3 Type refinement

Now we consider rule PCON-R, which is used when the scrutinee of the case has a rigid type. In that case we compute a type refinement with the judgement $\theta \in \text{fm.gr}(\overline{\tau}_p \doteq \overline{\tau}_2)$. We return to the details of this judgement in Section 4.4—for now let us only assume that the returned θ is a substitution that *unifies* the type of the pattern, $T \overline{\tau}_p$, and the result type of the constructor, $T \overline{\tau}_2$.

Unlike rule PCON-W, θ can contain in its domain type variables mentioned in the type of the pattern, $T \overline{\tau}_p$, as well as type variables mentioned in the return type of the constructor, $T \overline{\tau}_2$. Now we apply the type refinement to the environment, and to the result type, before type-checking the right hand side of the branch. When applying the refinement to the environment, we only refine rigid bindings (see Figure 1), and similarly we only refine the result type τ_t if it is rigid (hence $\theta^m(\tau_t)$). We do not need to apply the refinement to the term: if the term contains open type annotations, the scoped type variables of these annotations must be bound in the environment, in which we do apply the refinement.

If unification fails to compute a type refinement, then the case alternative cannot possibly match, and the type system rejects the program. Another possible design choice is to accept statically-inaccessible alternatives without even type-checking the right hand side (since it can never be reached). However, we think that we are more likely to help programmers by rejecting such programs than by silently accepting them.

The appearance of unification is slightly unusual for a declarative type system, although not without precedent [9]. The best way to think about it is that a successful pattern match implies the truth of an equality constraint of form $T \overline{\tau}_p \doteq T \overline{\tau}_2$, and the case alternative should be checked under that constraint. We express this idea by solving the constraint to get its most general unifier, and applying the unifier to the entire judgement (modulo the rigid/wobbly distinctions).

Most other authors choose to deal with the constraint sets explicitly, using a judgement of form $C, \Gamma \vdash t : \tau$, where C is a set of constraints, and type equality is taken modulo these constraints

[25, 5, 19, 15]. That approach is more general, but it is less convenient in our context, because by the time that type equality is invoked, the provenance of the types (and in particular whether or not they are rigid) has been lost. For example, we do not want this judgement to hold:

$$a \doteq \text{Int}, \text{xs} :^w [a] \vdash (3 : \text{xs}) : [\text{Int}]$$

It should not hold because `xs` has a wobbly type. But the type equality arises from instantiating the call to `cons (:)`, and by that time the fact that its second argument had a wobbly type has been lost. A solution would be to embody wobbliness in the types themselves, as an earlier version of this paper did, but the approach we give here is significantly simpler.

4.4 Fresh “most general” unifiers

What unifiers should be used in rule PCON-R for refinement? First, will *any* unifier θ do? No: we must not make up any substitution beyond those justified by the constraints. For example, consider the program

```
f :: forall a. (a,b) -> Int
f = \x. case x of (p,q) -> p+1
```

It would obviously be wrong to substitute `Int` for `a` in the case alternative! Nor, just as in rule PCON-W, can we refine the types of existential variables.⁴

Hence, choosing θ to be a most general unifier (mgu), guaranteed not to introduce any spurious equalities, seems reasonable to ensure sound type inference. Alas, sometimes two types can have more than one mgu and the choice among these mgu s can determine whether the program typechecks. Consider the following example:

```
data Eq a b where Refl :: Eq c c

f :: forall a b. Eq a b -> (a->Int) -> b -> Int
f x y z = (\w. case x of Refl -> y w) z
```

First, note that `w` enters the environment with the *wobbly* type `b` (rules APP and ABS). Now, when checking the pattern, we are faced with the problem of computing a θ such that $\theta(\text{Eq } c \ c) = \theta(\text{Eq } a \ b)$. There are three most general unifiers, $[b \mapsto a, c \mapsto a]$, $[a \mapsto b, c \mapsto b]$, or $[a \mapsto c, b \mapsto c]$. Because `w`'s type is wobbly, it will not be refined by the pattern match, but `y`'s (rigid) type will be. Hence, the body of the `case` will typecheck *only* if we choose the second of the three substitutions. (If the case alternative was `y z` instead of `y w`, it would typecheck with any mgu , because `z`'s binding is rigid.) So if the rules specify θ is *some* mgu , there certainly is an mgu that makes the program typecheck—but it is hard to see how an *algorithm* could know which of the three mgu s to choose.

Since type inference is hard for this case, the thing to do is to reject this program. But how can we do so? Our solution is to use a modified form of mgu , called fmgu : whenever we have to unify two variables from the context type, we do not unify them directly; instead, we make up a fresh variable and map both variables to the new one. In our example, the substitution $[a \mapsto d, b \mapsto d, c \mapsto d]$ (where `d` is a fresh type variable) is a fmgu of `Eq c c` and `Eq a b`. The device of choosing a fresh type variable ensures that a wobbly binding (such as `w`'s) will *never* be compatible with the refined type, rather than being compatible under some unifiers but not others. A fmgu is technically not a most general unifier, because the latter never involves variables that do not appear in the argument types, but its definition is very similar to that of mgu :

⁴There is also a dual question: must θ be a unifier at all? The answer here is more nuanced: “no” for soundness, but “yes” for completeness: see Section 6.4.

DEFINITION 4.1 (fmgu). An idempotent substitution θ is a fresh most general unifier of τ_1 and τ_2 , written $\theta \in \text{fmgu}(\tau_1 \doteq \tau_2)$, iff

- (i) θ is a unifier of τ_1 and τ_2 , that is, $\theta(\tau_1) = \theta(\tau_2)$.
- (ii) For any idempotent unifier ϕ of τ_1 and τ_2 there exists a substitution ψ such that $\phi(a) = \psi(\theta(a))$ for all $a \in \text{ftv}(\tau_1, \tau_2)$.
- (iii) For every $a, b \in \text{ftv}(\tau_1)$, with $a \neq b$, $\theta(a) \neq b$. For every $a, b \in \text{ftv}(\tau_2)$, with $a \neq b$, $\theta(a) \neq b$.
- (iv) $\text{dom}(\theta) \subseteq \text{ftv}(\tau_1, \tau_2)$ and all type variables in $\text{range}(\theta)$ are either in $\text{ftv}(\tau_1, \tau_2)$ or are fresh (disjoint from variables introduced by the typing judgment that uses θ).

Conditions (i) and (ii) resemble the corresponding properties of most general unifiers.⁵ Condition (iii) is the distinctive feature of fmgu : it guarantees that no two variables from the context type or the constructor type are directly equated to each other; instead, this can only happen through a third fresh variable. Finally condition (iv) ensures that θ does not include any extra spurious equalities for variables that appear free elsewhere in the typing derivation. To simplify the exposition, we state this freshness condition informally here and only make it precise in the companion technical report [23].

It is not hard to come up with a procedure to calculate such fresh most general unifiers. Figure 3 gives one implementation, fmgu , with the property that if $\text{fmgu}(\tau_1 \doteq \tau_2) = \theta$ then $\theta \in \text{fmgu}(\tau_1 \doteq \tau_2)$. The fmgu procedure in turn calls the auxiliary procedure fmgu^* , and then restricts the domain of the unifier it returns to ensure that it is contained in $\text{ftv}(\tau_1, \tau_2)$ —the restriction is written $|_{\text{ftv}(\tau_1, \tau_2)}$ in Figure 3. In a call of the form $\text{fmgu}^*(\mathcal{E}, \mathcal{B})$ the set \mathcal{E} represents type equalities that must be satisfied, of the form $\tau_1 \doteq \tau_2$. The set \mathcal{B} is used to determine which variables must not be unified to each other: If $\text{fmgu}^*(\mathcal{E}, \mathcal{B}) = \theta$ then no two variables from \mathcal{B} are directly equated through θ and no two variables from $\text{ftv}(\mathcal{E}) - \mathcal{B}$ (which were not introduced as fresh by the algorithm) are directly equated through θ . A subtle point in this algorithm is that the set \mathcal{B} also adds “directionality” to the unifier, namely that variables from \mathcal{B} are preferred in the domain of the returned substitution. The fmgu procedure is initialized with $\mathcal{B} = \text{ftv}(\tau_2)$, hence preferring variables of τ_2 in the domain of the returned substitution, for reasons that we describe in Section 4.6.

4.5 Lexically scoped type variables

Any polymorphic language that exploits user type annotations, as we do here, must support lexically scoped type variables, so that a type signature can mention type variables that are bound “further out”. This feature is curiously absent from Haskell 98, and its absence is often awkward. For example:

```
prefix :: forall a. a -> [[a]] -> [[a]]
prefix x yss = let xcons :: [a] -> [a]
                xcons ys = x : ys
                in map xcons yss
```

This program is rejected by Haskell, because the type signature for `xcons` is implicitly quantified to mean $\forall a. [a] \rightarrow [a]$. What we want here is an *open* type signature for `xcons` that mentions a type variable bound by the definition of `prefix`.

⁵If θ is an mgu of τ_1 and τ_2 , then for any other unifier of τ_1 and τ_2 , ϕ , there exists a substitution ψ such that $\phi(a) = \psi(\theta(a))$ for all a . The difference here is that condition (ii) requires equality only for a in the free type variables of τ_1 and τ_2 . This allows “fresh” type variables to appear in the domains of ϕ , θ and ψ . Moreover we work with the lattice of idempotent substitutions, as it is technically more tractable, but condition (ii) could be recast in terms of arbitrary unifiers.

$$\text{fmgu}(\tau_1 \doteq \tau_2) = \theta \quad \text{fmgu}(\tau_1 \doteq \tau_2) = \text{fmgu}^*(\{\tau_1 \doteq \tau_2\}, \text{ftv}(\tau_2))|_{\text{ftv}(\tau_1, \tau_2)}$$

$$\text{fmgu}^*(\mathcal{E}, \mathcal{B}) = \theta \quad \mathcal{E} = \cdot \mid (\tau_1 \doteq \tau_2) \cup \mathcal{E}$$

$$\begin{aligned}
1. \text{ fmgu}^*(\emptyset, \mathcal{B}) &= \epsilon \\
2. \text{ fmgu}^*(a \doteq a \cup \mathcal{E}, \mathcal{B}) &= \text{fmgu}^*(\mathcal{E}, \mathcal{B}) \\
3. \text{ fmgu}^*(a \doteq b \cup \mathcal{E}, \mathcal{B}) &= \text{fmgu}^*([a \mapsto b]\mathcal{E}, \mathcal{B}) \cdot [a \mapsto b] \quad a \in \mathcal{B}, b \notin \mathcal{B} \\
4. \text{ fmgu}^*(b \doteq a \cup \mathcal{E}, \mathcal{B}) &= \text{fmgu}^*([a \mapsto b]\mathcal{E}, \mathcal{B}) \cdot [a \mapsto b] \quad a \in \mathcal{B}, b \notin \mathcal{B} \\
5. \text{ fmgu}^*(a \doteq b \cup \mathcal{E}, \mathcal{B}) &= \text{fmgu}^*([a \mapsto c, b \mapsto c]\mathcal{E}, \mathcal{B}) \cdot [a \mapsto c, b \mapsto c] \\
&\quad \text{where } (a, b \notin \mathcal{B} \vee a, b \in \mathcal{B}) \text{ and } c \text{ fresh} \\
6. \text{ fmgu}^*(a \doteq \tau \cup \mathcal{E}, \mathcal{B}) &= \text{fmgu}^*([a \mapsto \tau]\mathcal{E}, \mathcal{B}) \cdot [a \mapsto \tau] \quad \text{where } a \notin \text{ftv}(\tau) \text{ and } \tau \neq b \\
7. \text{ fmgu}^*(\tau \doteq a \cup \mathcal{E}, \mathcal{B}) &= \text{fmgu}^*([a \mapsto \tau]\mathcal{E}, \mathcal{B}) \cdot [a \mapsto \tau] \quad \text{where } a \notin \text{ftv}(\tau) \text{ and } \tau \neq b \\
8. \text{ fmgu}^*((T \bar{\tau}_1 \doteq T \bar{\tau}_2) \cup \mathcal{E}, \mathcal{B}) &= \text{fmgu}^*(\bar{\tau}_1 \doteq \bar{\tau}_2 \cup \mathcal{E}, \mathcal{B}) \\
9. \text{ fmgu}^*((\tau_1 \rightarrow \tau_2 \doteq \tau_3 \rightarrow \tau_4) \cup \mathcal{E}, \mathcal{B}) &= \text{fmgu}^*(\{\tau_1 \doteq \tau_3, \tau_2 \doteq \tau_4\} \cup \mathcal{E}, \mathcal{B})
\end{aligned}$$

Figure 3: An implementation of fmgu

In our small language, we therefore allow the programmer to annotate a `let` definition with a polymorphic type, `forall a. tau`. The type variables that are lexically in scope are those bound by the environment Γ (see the syntax in Figure 1); in a full-blown system, the environment would also record their kinds. Rule LET-R first uses the bindings of scoped type variables in the environment Γ to translate the typing annotation to an internal type, with the judgement $\llbracket \text{forall } a. \text{tau} \rrbracket_\Gamma = \forall a. \tau$. It also requires that $\overline{a} \# \text{ftv}(\Gamma)$, and extends the environment with the new bindings $a \rightsquigarrow a$, to bring a in scope. The right-hand side is checked under this extended environment.

The idea that the quantified type variables of a type signature should scope over the right hand side of its definition is not new: it is used in Mondrian [12] and Chameleon [20]. It seems a little peculiar, and we resisted it for a long time, but it is extremely direct and convenient, and we now regard it as the Right Thing.

The job is not done, though. We still need a way to name *existentially-bound* type variables. For example, consider this (slightly contrived) example:

```
data T where MkT :: [a] -> (a->Int) -> T
f :: T -> Int
  = \x. case x of
    MkT ys g -> let y::=? = head ys
                  in g y
```

What type can we attribute to y in the inner `let` binding? We need a name for the existential type variable that is bound by the pattern $(\text{MkT } ys \ g)$. Pattern annotations provide such functionality. For example:

```
f :: T -> Int
  = \x. case x of
    MkT (ys :: [a]) g -> let y :: a = head ys
                              in g y
```

The pattern $(ys :: [a])$ brings the type variable a into scope so that it can be used in the `let` binding for y . In general, a type-annotated pattern $(p :: \text{tau})$ brings into scope the type variables of tau that are not yet bound in the environment. These variables then scope over tau , p , all patterns to the right of the binding site, and the right hand side of the case alternative. The typing rules of Figure 2 only deal with simple flat patterns; we formalize type-annotated patterns when we discuss nested patterns in Section 5.4.

Lexically-scoped type variables are always bound to type *variables*, and hence enter Γ with a binding of form $(a \rightsquigarrow a)$ (see LET-R). However, in a type-refining case alternative, we apply the refinement to the type environment, *including the bindings for scoped*

type variables, so now a type variable may be bound to an arbitrary type. For that reason, bindings in Γ take the form $(a \rightsquigarrow \tau)$.

In a real programming language, such as Haskell, quantification is often implicit. For example, the “`forall a`” quantification in a `let` binding might be determined by calculating the type variables that are mentioned in the type, but are not already in scope. (Indeed, we adopt this convention for many of the types we write in this paper.) However, for our formal material we assume that quantification is explicit.

4.6 Type inference

It is very straightforward to perform type inference for our system. One algorithm that we have worked out in detail is based on the standard approach for Hindley-Milner systems [4, 13]. The inference engine maintains an ever-growing substitution mapping meta type variables to monotypes. Whenever the inference engine needs to guess a type (for example in rule ABS) it allocates a fresh meta type variable; whenever it must equate two types (such as rule APP) it unifies the types and extends the substitution.

Modifying the type inference algorithm for Hindley-Milner systems to support GADTs is simple. Bindings in the type environment Γ carry a boolean rigid/wobbly flag, as does the result type. The implementation of pattern-matching can be read directly from rules PCON-R and PCON-W.

There is one subtlety, which lies in the implementation of fmgu. Consider the possible type derivations for

$$x :^r (a, b) \vdash (\text{case } x \text{ of } (p, q) \rightarrow p) :^w a$$

The pair constructor has type $\forall cd. c \rightarrow d \rightarrow (c, d)$, the unification problem in PCON-R is to compute a fmgu for $(a, b) \doteq (c, d)$. There are several fmgu's of this constraint, and not all of them are useful. For example, the substitution $[a \mapsto c, b \mapsto d]$ will not type this program because the type of p will be c which does not match the result type a . Alternatively, the fmgu $[c \mapsto a, b \mapsto d]$ succeeds. The key idea is that, given a choice, *the unifier should eliminate the freshly-bound type variables*, in this case c and d .

Our inference engine therefore uses a “biased” fmgu algorithm, based on Figure 3, that preferentially eliminates freshly-bound type variables. To achieve this we simply require that the procedure fmgu^* of Figure 3 is called with an initial \mathcal{B} that contains the required freshly-introduced type variables. In rule PCON-R, these variables are the free type variables of $\bar{\tau}_2$, therefore the implementation makes a call to $\text{fmgu}(\bar{\tau}_p \doteq \bar{\tau}_2)$, which results in passing the $\text{ftv}(\bar{\tau}_2)$ as \mathcal{B} .

We have proven that if a program type checks with any fmgu then it typechecks with the biased implementation. Therefore we have complete type inference without searching for an appropriate fmgu (see Section 6.3). Additionally, the biased implementation has the property that $\text{fmgu}(\text{T } \bar{\tau} \doteq \text{T } \bar{b}) = [\bar{b} \mapsto \bar{\tau}]$, when the lengths of $\bar{\tau}$ and \bar{b} are the same. This property ensures that our system conservatively extends Haskell (Section 6.6).

5. Variations on the theme

The type system we have described embodies a number of somewhat *ad hoc* design choices, which aim to balance expressiveness with predictability and ease of type inference. In this section we explore the design space a bit further, explaining several variations on the basic design that we have found useful in practice.

5.1 Smart application

The rules we have presented will type many programs, but there are still some unexpected failures. Here is an example⁶ (c.f. [3]):

```

data Equal a b where
  Eq :: Equal a a
data Rep a where
  RI :: Rep Int
  RP :: Rep a -> Rep b -> Rep (a,b)

test :: Rep a -> Rep b -> Maybe (Equal a b)
test RI RI = Just Eq
test (RP s1 t1) (RP s2 t2)
  = case (test s1 s2) of
    Nothing -> Nothing
    Just Eq -> case (test t1 t2) of
      Nothing -> Nothing
      Just Eq -> Eq
  
```

A non-bottom value Eq of type Equal a b is a witness that the types a and b are the same; that is why the constructor has type $\forall a. \text{Equal a a}$. Consider the outer `case` expression in `test`. The programmer reasons that since the types of s_1 and s_2 are rigid, *then so is the type of* $(\text{test } s_1 s_2)$, and hence the `case` should perform type refinement; and indeed, `test` will only pass the type checker if both its `case` expressions perform type refinement.

The difficulty is that the scrutinee-typing rules of Figure 2 conservatively assume that an application has a wobbly type, so neither `case` expression will perform type refinement. We could solve the problem by adding type annotations, but that is clumsy:

```

test :: Rep a -> Rep b -> Maybe (Equal a b)
test RI RI = Just Eq
test (RP (s1::Rep a1) (t1::Rep b1))
  (RP (s2::Rep a2) (t2::Rep b2))
  = let r1 :: Maybe (Equal a1 a2) = test a1 a2
    r2 :: Maybe (Equal b1 b2) = test b1 b2
    in case r1 of
      Nothing -> Nothing
      Just Eq -> case r2 of
        Nothing -> Nothing
        Just Eq -> Eq
  
```

(However, note the importance of pattern-binding the type variables a_1, a_2 etc., so that they can be used to attribute a type to s_1, t_1 etc.) To avoid this clumsiness, we need a way to encode the programmer's intuition that if `test`'s argument types are rigid, then so is its result type. More precisely, if all of the type variables in `test`'s *result* appear in an *argument* type that is rigid, then the result type should be rigid. Here is the rule, which extends the scr-

⁶We take the liberty of using pattern matching on the left-hand side and separate type signatures, but they are just syntactic sugar.

tinee typing rules of Figure 2:

$$\frac{\begin{array}{c} C :^r \forall \bar{a}. \bar{\tau} \rightarrow T \bar{\tau}_r \in \Gamma \quad \Gamma \vdash u_i : [\bar{a} \mapsto \bar{v}] \tau_i \mid^{m_i} \\ \bar{a}_r = \{a \in \bar{a} \mid \exists i. a \in \text{ftv}(\tau_i) \wedge m_i = r\} \\ m = \begin{cases} r & \text{if } \text{ftv}(\tau_r) \subseteq \bar{a}_r \\ w & \text{otherwise} \end{cases} \end{array}}{\Gamma \vdash c \bar{u} : [\bar{a} \mapsto \bar{v}] \tau_r \mid^m} \text{SCR-APP}$$

The rule gives special treatment to applications $c \bar{u}$ of an atom c to zero or more arguments \bar{u} , where c has a rigid type in Γ . In that case, SCR-APP recursively uses the scrutinee typing judgement to infer the rigidity m_i of each argument u_i . Then it computes the subset \bar{a}_r of v 's quantified type variables that appear in at least one rigid argument. We can deduce (rigidly) how these variables should be instantiated. Hence, if all the type variables free in the result type of c are in \bar{a}_r then the result type of the call is also known rigidly.

One could easily imagine adding further scrutinee-typing rules. Notably, if the language supported type annotations on terms, $(t :: \text{sig})$, then one would definitely also want to add a scrutinee-typing rule to exploit such annotations:

$$\frac{\llbracket t \rrbracket_\Gamma = \tau \quad \Gamma \vdash t :^r \tau}{\Gamma \vdash (t :: t \rrbracket) : \tau \mid^r} \text{SCR-SIG}$$

Now, in any place where a `case` expression has a wobbly scrutinee, the programmer can make it rigid by adding an annotation, thus: $(\text{case } (t :: t \rrbracket) \text{ of } \dots)$. Beyond that, we believe that there is little to be gained by adding further rules to the scrutinee-typing rules.

5.2 Smart let

Consider these two terms, where $(f x)$ is determined to be rigid by SCR-APP:

$$\frac{\begin{array}{c} \text{case } f x \text{ of} \\ \quad \text{MkT } a b \rightarrow \dots \end{array}}{\text{let } s = f x \quad \text{in case } s \text{ of} \quad \text{MkT } a b \rightarrow \dots} \text{LET-W}$$

With the rules so far, the left-hand `case` would do refinement, but the right hand `case` would not, because s would get a wobbly type. This is easily fixed by re-using the scrutinee judgement for the right hand side of a `let`:

$$\frac{\begin{array}{c} \Gamma, x :^w \tau \vdash u : \tau \mid^n \\ \bar{a} = \text{ftv}(\tau) - \text{ftv}(\Gamma) \quad \Gamma, x :^n \forall \bar{a}. \tau \vdash t :^m \tau \end{array}}{\Gamma \vdash (\text{let } x = u \text{ in } t) :^m \tau} \text{LET-W}$$

This change means that introducing a `let` does not gratuitously lose rigidity information. An interesting property is that if LET-W infers a rigid type for x , then x is monomorphic and \bar{a} is empty:

THEOREM 5.1. If $\Gamma \vdash u : \tau \mid^r$ then $\text{ftv}(\tau) \subseteq \text{ftv}(\Gamma)$.

Why is this true? Because the only way u could get a rigid type is by extracting it from Γ .

5.3 Smart patterns

Consider rule PCON-W in Figure 2, used when the scrutinee has a wobbly type. It gives a wobbly type to *all* the variables \bar{x} bound by the pattern. However, if some of the fields of the constructor have purely existential types, then these types are definitely rigid, and it is over-conservative to say they are wobbly.

This observation motivates the following variant of PCON-W

$$\frac{\begin{array}{c} C :^r \forall \bar{a}. \bar{\tau}_1 \rightarrow T \bar{\tau}_2 \in \Gamma \quad \bar{a} \# \text{ftv}(\Gamma, \bar{\tau}_p, \tau_t) \\ \bar{a}_c = \bar{a} \cap \text{ftv}(\bar{\tau}_2) \quad \theta = [\bar{a}_c \mapsto \bar{v}] \quad \theta(\bar{\tau}_2) = \bar{\tau}_p \\ m_i = \begin{cases} r & \text{if } \text{ftv}(\tau_{1i}) \# \bar{a}_c \\ w & \text{otherwise} \end{cases} \\ \Gamma, x :^{m_i} \theta(\tau_{1i}) \vdash t :^m \tau_t \end{array}}{\Gamma \vdash C \bar{x} :^{(w,m)} T \bar{\tau}_p \rightarrow \tau_t} \text{PCON-W}$$

$\text{bindings}(\Delta) = \bar{\alpha}$	
$\text{bindings}(\cdot) = \emptyset$ $\text{bindings}(\Delta, a \hookrightarrow a) = \{a\} \cup \text{bindings}(\Delta)$ $\text{bindings}(\Delta, x :^m \sigma) = \text{bindings}(\Delta)$	
$\boxed{\Gamma \vdash p \rightarrow t :^{(m_p, m_t)} \tau_p \rightarrow \tau_t}$	
$\frac{\Gamma, (\emptyset, \cdot, \emptyset) \vdash p :^{m_p} \tau_p \blacktriangleright (\bar{\alpha}, \Delta, \theta) \quad \text{ftv}(\Gamma, \tau_p, \tau_t) \# \bar{\alpha} \quad \text{bindings}(\Delta) \subseteq \bar{\alpha} \quad \theta(\Gamma \cup \Delta) \vdash t :^{m_t} \theta^{m_t}(\tau_t)}{\Gamma \vdash p \rightarrow t :^{(m_p, m_t)} \tau_p \rightarrow \tau_t} \text{PAT}$	
$\boxed{\Gamma, K_1 \vdash p :^m \tau \blacktriangleright K_2}$	
$\frac{x \notin \text{dom}(\Delta)}{\Gamma, (\bar{\alpha}, \Delta, \theta) \vdash x :^m \tau \blacktriangleright (\bar{\alpha}, \Delta, x :^m \tau, \theta)} \text{PVAR}$	
$\frac{\begin{array}{l} C :^r \forall \bar{b}. \bar{\tau}_1 \rightarrow T \bar{\tau}_2 \in \Gamma \quad \bar{b} \# \bar{\alpha} \\ \bar{b}_c = \bar{b} \cap \text{ftv}(\bar{\tau}_2) \quad \psi = [\bar{b}_c \mapsto v] \quad \bar{\tau}_3 = \psi(\bar{\tau}_2) \\ m_i = \begin{cases} r & \text{ftv}(\tau_{1i}) \# \bar{b}_c \\ w & \text{otherwise} \end{cases} \\ \Gamma, (\bar{\alpha}\bar{b}, \Delta, \theta) \vdash \stackrel{\text{fold}}{p_i :^{m_i} \psi(\tau_{1i})} \blacktriangleright K \end{array}}{\Gamma, (\bar{\alpha}, \Delta, \theta) \vdash C \bar{p} :^w T \bar{\tau}_3 \blacktriangleright K} \text{PCON-W}$	
$\frac{\begin{array}{l} C :^r \forall \bar{b}. \bar{\tau}_1 \rightarrow T \bar{\tau}_2 \in \Gamma \quad \bar{b} \# \bar{\alpha} \\ \theta(\tau) = T \bar{\tau}_3 \quad \psi \in \text{fmgu}(\bar{\tau}_3 \doteq \bar{\tau}_2) \\ \Gamma, (\bar{\alpha}\bar{b}, \Delta, \psi \cdot \theta) \vdash \stackrel{\text{fold}}{p_i :^r \tau_{1i}} \blacktriangleright K \end{array}}{\Gamma, (\bar{\alpha}, \Delta, \theta) \vdash C \bar{p} :^r \tau \blacktriangleright K} \text{PCON-R}$	
$\frac{\begin{array}{l} \bar{b} = \text{ftv}(\tau) - \text{dom}(\Gamma, \Delta) \\ \bar{b} \text{ distinct } \bar{b} \# \text{bindings}(\Delta) \quad \bar{b} \# \text{dom}(\theta) \\ \llbracket \tau \rrbracket_{\Gamma, \Delta, \bar{b} \hookrightarrow \bar{b}} = \tau_s \quad \theta(\tau_s) = \theta^m(\tau) \\ \Gamma, (\bar{\alpha}, (\Delta, \bar{b} \hookrightarrow \bar{b}), \theta) \vdash p :^r \tau_s \blacktriangleright K \end{array}}{\Gamma, (\bar{\alpha}, \Delta, \theta) \vdash (p :: \tau) :^m \tau \blacktriangleright K} \text{PANN}$	
$\boxed{\Gamma, K_1 \vdash \stackrel{\text{fold}}{p_i :^{m_i} \tau_i} \blacktriangleright K_2}$	
$\frac{}{\Gamma, K \vdash \stackrel{\text{fold}}{\cdot} \blacktriangleright K} \text{F-BASE}$	
$\frac{\Gamma, K_1 \vdash p :^m \tau \blacktriangleright K_2 \quad \Gamma, K_2 \vdash \stackrel{\text{fold}}{p_i :^{m_i} \tau_i} \blacktriangleright K_3}{\Gamma, K_1 \vdash \stackrel{\text{fold}}{(p :^m \tau), p_i :^{m_i} \tau_i} \blacktriangleright K_3} \text{F-REC}$	

Figure 4: Source language pattern typing

Here we attribute a rigid type to x_i if x_i 's type does not mention any of the type variables a_c that are contaminated by appearing in the result type of the constructor; that is, x_i is rigid if its type is purely existential.

To be honest, this elaboration of PCON-W is motivated more by the fact that it is easy to describe and implement, and its symmetry with SCR-APP, rather than because we know of useful programs that would require more annotation without it.

5.4 Nested patterns

In Section 4 we treated only flat patterns, and we did not handle pattern type signatures (introduced in Section 4.5). Handling nested

patterns introduces no new technical or conceptual difficulties, but the rules look substantially more intimidating, which is why we have left them until now. The rules for nested patterns are given in Figure 4. The main new judgement typechecks a nested pattern, p :

$$\Gamma, K_1 \vdash p :^m \tau \blacktriangleright K_2$$

Here K is a triple $(\bar{\alpha}, \Delta, \theta)$, with three components (Figure 1):

- $\bar{\alpha}$ is the set of type variables bound by the pattern. We need to collect these variables so that we are sure to choose unused variables when instantiating a constructor, and so that we can ensure that none of the existential variables escape.
- Δ gives the typings of term variables bound by the pattern, and the lexically-scoped type variables brought into scope by pattern type signatures; we use Δ to extend Γ before typing the body of the case alternative.
- θ is the type refinement induced by the pattern.

This triple K is threaded through the judgement: K_1 gives the bindings from patterns to the left of p , and K_2 is the result of augmenting K_1 with the bindings from p .

With that in mind, rule PAT is easy to read (compare it with PCON-R from Figure 2): it invokes the pattern-checking judgement, starting with an empty K , checks that none of the existential type variables escape, and typechecks the body t of the case alternative after extending the type environment with Δ and applying the type refinement θ . The premise $\text{bindings}(\Delta) \subseteq \bar{\alpha}$ specifies that the scoped type variables introduced in Δ may only bind internal variables introduced by this particular pattern (bindings is defined in Figure 4⁷). The premise maintains the invariant that scoped type variables can only be introduced *close* to their quantification sites, an issue to which we return in Section 5.5.

Rule PVAR is also straightforward; the test $x \notin \text{dom}(\Delta)$ prevents a single variable from being used more than once in a single pattern match.

The constructor rules PCON-W and PCON-R are similar to those in Figure 2, with the following differences. First, the sub-patterns are checked using an auxiliary judgement \vdash^{fold} , which simply threads the K triple through a vector of patterns. Second, in PCON-R the incoming substitution θ is *composed* with the unifier, ψ , to obtain $(\psi \cdot \theta)$. In PCON-W, however, the instantiation ψ has only the fresh variables b_c in its domain, so there is no need to extend the global type refinement θ .

There is one tricky point. Consider the following example:

```

data T where C :: Rep a -> a -> T
data Rep a where RI :: Rep Int
RB :: Rep Bool
f :: T -> Bool
f (C RB True) = False
f (C RI 0) = False
f other = True

```

Should this program typecheck? The constructor C binds an existential variable a . The pattern RB induces a type refinement that refines a to $Bool$; and hence, in our system, the pattern $True$ typechecks, and the program is accepted. There is a left-to-right order implied here, and our system would reject the definition if the order of arguments to C were reversed. Furthermore, accepting the program requires that the operational order of pattern matching must also be left-to-right. In a lazy language like Haskell, termination considerations force this order anyhow, so no new compilation con-

⁷Notice that in Figure 4 there is no case for bindings of the form $a \hookrightarrow \tau$; the reason is that we never apply the refinement to the environment during checking the same pattern, therefore lexical variables only bind type variables at the point of the call to $\text{bindings}(\Delta)$ in rule PAT.

straints are added by our decision. In a strict language, however, one might argue for greater freedom for the compiler, and hence less type refinement.

This left-to-right ordering shows up in the way that the type refinement is threaded through the sub-patterns of a constructor by \vdash^{fold} . It also requires one subtlety in PCON-R. Notice that the conclusion of PCON-R does not say $C \bar{\tau}_3 : T \bar{\tau}_3$, as in PCON-W; instead, the conclusion says simply $C \bar{\tau} : \tau$, with $\theta(\tau) = T \bar{\tau}_3$ as a premise. The reason is apparent from the above example. When typechecking the pattern `True`, we must establish the judgement

$$\Gamma, (a, \cdot, [a \mapsto \text{Bool}]) \vdash \text{True} : a \blacktriangleright (a, \cdot, [a \mapsto \text{Bool}])$$

That is, we must check that the pattern `True` has type `a` (not `Bool`). Hence the need to apply the current substitution (coming from patterns to the left) before requiring the pattern type to be of the form $T \bar{\tau}_3$.

5.5 Pattern type signatures

Figure 4 also enhances the type checking of patterns to accommodate pattern type signatures, which we introduced informally in Section 4.5. First, it is worth articulating our main design choices:

- At its binding site, a scoped type variable stands for a type variable, not a type. For example, given the constructor `Lit :: Int -> Term Int`, the pattern `Lit (x::a)` is illegal because `a` must bind to `Int`. Of course, after type refinement a scoped type variable may be bound to a type, but it seems odd to allow this at its binding site.
- Furthermore, at its binding site, a scoped type variable must stand for a type variable that is not already in scope. For example, given `MkT :: forall a. a -> a -> T a`, the pattern `MkT (x::b) (y::c)` would be illegal because `x` and `y` must have the same type. Again, after type refinement two scoped type variables may indeed stand for the same type (variable).
- Lastly, at all times a scoped type variable stands for a *rigid* type, so that we may regard type annotations as rigid. For example, we reject the pattern `Just (x::a)` when the scrutinee has wobbly type `Maybe Int` because the type variable `a` would be bound to the guessed type `Int`, and any type annotation containing `a` would not be rigid.

With that in mind, let us look at rule PANN, which deals with type signatures in patterns, in the following stages:

- First we identify the lexical variables that the pattern brings into scope, \bar{b} , by removing from the free variables of the annotation those that are already bound in $\Gamma \cup \Delta$.
- Next, we “guess” distinct type variables \bar{b} to create the bindings $b \hookrightarrow \bar{b}$. We require that these variables be disjoint from the bindings of Δ to avoid binding the same type variable twice. We need not require \bar{b} to be disjoint from the bindings of Γ because rule PAT requires that the bindings of Δ (which include \bar{b}) are subset of the variables introduced by the pattern—and the latter must not appear in Γ . Additionally we require that \bar{b} have not yet been refined by θ , with the condition $\bar{b} \# \text{dom}(\theta)$, an issue which is related to type inference completeness and that we explain below.
- Using the new bindings, $\bar{b} \hookrightarrow \bar{b}$, we translate the annotation type τ_a to the internal type τ_s . Then, we check that the type τ of the pattern and the signature τ_s are identical when the current type refinement is applied. Since type signatures are always translated to rigid types, we always apply the refinement to the signature. However, we conditionally apply the refinement to τ depending on its rigidity flag.
- Finally, we check the pattern against the annotation type τ_s .

We do not allow scoped type variables to be bound after they have been refined (the condition $\bar{b} \# \text{dom}(\theta)$ above) to ensure that our algorithm is complete. The following example illustrates why.

```
data T c where MkT :: T Int
data Y where MkY :: T a -> a -> Y
f (y::Y) = case y of
  MkY MkT (z::b) -> True
```

In this example, the `f` rule refines `a` to `Int`. Algorithmically we determine what variable `b` should bind to by examining $\theta(a)$. The implementation would then fail, since `b` would have to get bound to a *type*, `Int`. However without the condition $\bar{b} \# \text{dom}(\theta)$, the specification allows `b` to map to `a` and succeeds.

By changing our first two design decisions, we could remove this restriction. If lexical variables were allowed to map to rigid types, including other in-scope type variables, we would not have to rule out the above example. However, we think that this choice leads to confusing behavior if lexical type variables can name rigid but not wobbly types. For example, we would reject the pattern `Just (x::a)` when the scrutinee has a wobbly type `Maybe Int` but accept it when the scrutinee has a rigid type.

We could then also change our third design decision, by allowing lexical type variables to name *wobbly* types, and refining them selectively just as we do term variable bindings. The type system remains tractable, but becomes noticeably more complicated, because we must now infer the rigidity of both scoped type variables (or, rather, of the types they stand for), and of type annotations.

The choice among these designs is a matter of taste. We have found the current design to be simplest to specify and reason about.

6. Properties of our system

We have proven that our system enjoys the usual desirable properties: it is sound (Section 6.1); it can express anything that an explicitly-typed language can (Section 6.2); we have a sound and complete type inference algorithm (Section 6.3); and it is a conservative extension of the standard Hindley-Milner type system (Section 6.6). Although these properties are standard, they are easily lost, as we elaborate in this section. All of the results in this section hold for the most elaborate version of the rules we have presented, including all of the extensions in Section 5.

6.1 Soundness

We prove soundness by augmenting our typing rules with a type-directed translation to the predicative fragment of System F extended with GADTs. As usual, type abstractions and applications are explicit, and every binder is annotated with its type. In addition, in support of GADTs, we annotate each `case` expression with its result type. This intermediate language is equipped with a call-by-name semantics and is type safe.

We augment each source-language typing judgement with a translation into the target language; for example the main term judgement becomes $\Gamma \vdash t :^m \tau \rightsquigarrow t'$, where t' is the translation of t . For example, here is the ATM rule, whose translation makes explicit the type application that is implicit in the source language:

$$\frac{c :^n \forall \bar{a}. \tau \in \Gamma}{\Gamma \vdash c :^m [\bar{a} \mapsto \bar{v}] \tau \rightsquigarrow c \bar{v}} \text{ATM}$$

The semantics of the source language is defined by this translation. The soundness theorem then states that if a program is well-typed in our system then its translation is well-typed in our extended System F, and hence its execution cannot “go wrong”.

THEOREM 6.1 (Type safety). *If $\vdash t :^m \tau \rightsquigarrow t'$ then $\vdash^F t' : \tau$* .

6.2 Expressiveness

Programmer-supplied annotations are expressive. Any program that can be expressed by the explicitly-typed System-F-style intermediate language can also be expressed in the source language. We show this result with a systematic translation from the intermediate language into the source language, such that any typeable intermediate-language program translates to a typeable source-language program. The translation is straightforward: type applications are merely erased, type abstractions are replaced with annotations that bring into scope the abstraction's quantified type variables, every binder is annotated with a signature, and annotations are added to every case expression.

6.3 Soundness and completeness of inference

We have a sound and complete type inference algorithm for our system, as outlined in Section 4.6. We only give a short sketch here.

The algorithm uses notation α, β for unification variables. Unifiers, that is, idempotent substitutions from unification variables to monotypes, are denoted with δ . An identity-everywhere unifier is denoted with ϵ . The algorithm also makes use of infinite sets of fresh names, which we denote with \mathcal{A} , and call *symbol supplies*. The main inference algorithm can be presented as a deterministic relation: $(\delta_0, \mathcal{A}_0) \succ \Gamma \vdash t :^w \tau \succ (\delta_1, \mathcal{A}_1)$. The judgement should be read as: “given an initial unifier δ_0 and an initial symbol supply \mathcal{A}_0 , check that t has the type τ with the modifier w under Γ , returning an extended unifier δ_1 and the rest of the symbol supply \mathcal{A}_1 ”. Everything is an input except δ_1 and \mathcal{A}_1 which are results. A precondition of the algorithm is that whenever $m = r$ then τ contains no unification variables, that is, τ is fully known. This way we enforce a clean separation between refinement and unification. For example, consider the algorithmic rule for application:

$$\frac{(\mathcal{A}_0, \delta_0) \succ \Gamma \vdash t :^w \beta \succ \tau_2 \succ (\mathcal{A}_1, \delta_1) \quad (\mathcal{A}_1, \delta_1) \succ \Gamma \vdash u :^w \beta \succ (\mathcal{A}_2, \delta_2)}{(\mathcal{A}_0 \beta, \delta_0) \succ \Gamma \vdash t u :^m \tau_2 \succ (\mathcal{A}_2, \delta_2)} \text{APP}$$

The function and the argument types contain the unification variable β and therefore should be checked with the wobbly modifier.

The algorithm is *sound*; that is, if a term is shown to be well-typed by the algorithm, there should exist a typing derivation in the specification that witnesses this fact.

THEOREM 6.2 (Type inference soundness). *Let \mathcal{A}_0 be a supply of fresh symbols. If $(\mathcal{A}_0, \epsilon) \succ \vdash t :^w \alpha \succ (\mathcal{A}_1, \delta)$ then $\vdash t :^w \delta(\alpha)$. If $(\mathcal{A}_0, \epsilon) \succ \vdash t :^r \tau \succ (\mathcal{A}_1, \delta)$ and τ does not contain unification variables, then $\vdash t :^r \tau$.*

Since unification variables live only in wobbly parts of a judgement, Theorem 6.2 relies on the following substitution property.

LEMMA 6.3 (Substitution). *If $\text{dom}(\phi)$ is disjoint from the variables appearing in the rigid parts of the judgement $\Gamma \vdash t :^m \tau$ then $\phi[\Gamma] \vdash t :^m \phi(\tau)$, where $\phi[\Gamma]$ means the application of ϕ in both rigid and wobbly parts of Γ .*

The other important property of the algorithm is *completeness*; that is for all the possible types that the type system can attribute to a term, the algorithm can infer (i.e. check against a fresh unification variable) one such that all others are instances of that type.

THEOREM 6.4 (Type inference completeness). *Let \mathcal{A}_0 be a supply of fresh symbols. If $\vdash t :^r \tau$ then $(\mathcal{A}_0, \epsilon) \succ \vdash t :^r \tau \succ (\mathcal{A}_1, \delta)$. If $\vdash t :^w \tau$, and α is a fresh unification variable then $(\mathcal{A}_0, \epsilon) \succ \vdash t :^w \alpha \succ (\mathcal{A}_1, \delta)$ and $\exists \delta_r$ such that $\delta_r \delta(\alpha) = \tau$.*

Soundness and completeness, along with determinacy of the algorithm, give us a principal types property.

THEOREM 6.5 (Principal types). *If $\vdash t :^w \tau$ then there exists a principal type τ_p such that $\vdash t :^w \tau_p$, and for every τ_1 such that $\vdash t :^w \tau_1$ it is the case that $\tau_1 = \delta(\tau_p)$ for some substitution δ .*

A principal types property for the rigid judgement is uninteresting as rigid types are always known from user type annotations.

6.4 Pre-unifiers and completeness

We remarked in Section 4.4 that in PCON-R it would be unsound to use just any unifier for θ , as θ could introduce type equalities that have no justification. But must the θ be a unifier at all? What about refinements that introduce fewer equalities than fmgu? For example, even though the `case` expression *could* do refinement, no refinement is *necessary* to typecheck this function:

```
f :: Term a -> Int
f (Lit i) = i
f other = 0
```

That motivates the following definition:

DEFINITION 6.6 (Pre-unifier). *A substitution θ is a pre-unifier of types τ_1 and τ_2 iff for every unifier ψ of τ_1 and τ_2 , there exists a substitution θ' s.t. $\psi = \theta' \cdot \theta$.*

That is, a pre-unifier is a substitution that can be extended to be any unifier. For example, the empty substitution is a pre-unifier of any two types. A most-general unifier is precisely characterized by being both (a) a unifier and (b) a pre-unifier. In our explicitly-typed internal language (Section 6.1), it is sound for rule PCON-R to use any pre-unifier, rather than a most-general unifier.

Likewise, we can modify fmgu (Definition 4.1) so that it does not require the refinement to be a unifier. To our surprise, however, this flexibility in the source language precludes a complete type inference algorithm. To see why consider this program:

```
data T a where C :: T Int
g :: T a -> a -> a
g x y = let v = (case x of C -> y) in v
```

With our current specification, this program would be ill-typed: v would get `Int`, due to the refinement of y 's type inside the `case` expression, and the type `Int` does not match the return type `a` of g .

But suppose that the specification was allowed to choose the empty pre-unifier for the `case` expression (thereby performing no refinement). Then v would get the type `a`, and the definition of g would typecheck. There would be nothing unsound about doing this, but it is difficult to design a type inference algorithm that will succeed on the above program. In short, completeness of type inference becomes much harder to achieve.

This was a surprise to us. Our initial system used a pre-unifier instead of a most-general unifier in PCON-R, on the grounds that unifiers over-specify the system, and we discovered the above example only through attempting a (failed) completeness proof for our inference algorithm. The same phenomenon has been encountered by others, albeit in a very different guise [15, section 5.3.6]. Our solution is to use fresh most general unifiers in the specification as well as the implementation.

6.5 Wobbliness and completeness

Our initial intuition was that if a term typechecks in a wobbly context then, *a fortiori*, it would typecheck in a rigid context. But not so. Suppose $C :: T \text{ Int}$. Then the following holds:

$$x :^r T a, y :^w a \vdash \text{case } x \text{ of } C \rightarrow y :^w a$$

However, if we made the binding for y rigid, then the type of y would be refined to `Int`, and the judgement would not hold any more. (It can be made to hold again by making the return type rigid

as well.) This implies that there may be some programs that become untypable when (correct!) type annotations are added, which is clearly undesirable. Again this unexpected behavior is not unique to our system [15, section 5.3], and we believe that the examples that demonstrate this situation are rather contrived.

What this means is that our specification must be careful to specify *exactly* when a type is wobbly and when it is rigid. We cannot leave any freedom in the specification about which types are rigid and which are wobbly. If we did, then again inference would become much harder and, by the same token, it would be harder for the programmer to predict whether the program would typecheck.

Since our system is (with one small exception) deterministic, it already has the required precision. The exception is rule SCR-OTHER in Figure 2, which overlaps with SCR-VAR. This is easily fixed by adding to SCR-OTHER a side condition that t is not an atom c .

6.6 Relationship to Hindley-Milner

Our type system is a conservative extension of the conventional Hindley-Milner type system (augmented with existential types).

THEOREM 6.7 (Conservative extension of HM). *Say Γ contains only conventional data constructors (i.e. constructors with types of the form $\forall \bar{a}. \bar{\tau} \rightarrow T \bar{a}$). If $\Gamma \vdash t :^m \tau$ then $\Gamma \vdash^{HM} t : \tau$. Conversely, if $\Gamma \vdash^{HM} t : \tau$ then $\Gamma \vdash t :^m \tau$ for any m .*

To prove this theorem, we first use the version of PCON-R that uses a biased implementation of fmgu (Section 4.6). As mentioned in Section 4.6, any program that is typeable with the original system is typeable in the system with the biased implementation. In the latter system, it follows that, under the Hindley-Milner restrictions, the pattern judgement will return a substitution that only refines freshly-introduced type variables, because each equality generated will be of form $\tau_p = a$, where a is a fresh type variable:

LEMMA 6.8 (Shapes of refinements under HM restrictions). *If algebraic datatypes are conventional, the biased implementation is used, and $\Gamma \vdash p :^m \tau \blacktriangleright (\bar{a}, \Delta, \theta)$, then $\text{dom}(\theta) \subseteq \bar{a}$.*

For the proof of Theorem 6.7 we additionally rely on the fact that if we apply the refinement returned by the pattern typing judgement to the extra part of the environment that the pattern introduces, we get back the part of the environment that the Hindley-Milner system would introduce. The “conservativity” part is proved using the intermediate system that uses biased fmgu and the fact that this system is equivalent to the original that uses arbitrary fmgu.

7. Related work

In the dependent types community, GADTs have played a central role for over a decade, under the name *inductive families of data types* [7]. Coquand in his work on dependently typed pattern matching [6] also uses a unification based mechanism for implementing the refinement of knowledge gained through pattern matching. These ideas were incorporated in the ALF proof editor [10], and have evolved into dependently-typed programming languages such as Cayenne [1] and Epigram [11]. In the form presented here, GADTs can be regarded as a special case of dependent typing, in which the separation of types from values is maintained, with all the advantages and disadvantages that this phase separation brings.

The idea of GADTs in practical programming languages dates back to Zenger’s system of indexed types [27], but Xi *et al* were perhaps the first to suggest including GADTs in an ML-like programming language [25]. (In fact, an earlier unpublished work by Augustsson and Petersson proposed the same idea [2].) Xi’s subsequent work adopts more ideas from the dependent-type world [26, 24]. Cheney and Hinze examine numerous uses of what they

call *first class phantom types* [5, 8]. Sheard and Pasalic use a similar design they call *equality-qualified types* in the language Omega [18]. All of these works employ sets of (equality) constraints to describe the type system. We use unification instead, for reasons we discussed in Section 4.3.

Jay’s *pattern calculus* [9] also provides the same kind of type refinement via pattern matching as ours does, and it inspired our use of unification as part of the declarative type-system specification. The pattern calculus aims at a different design space than ours, choosing to lump all data type constructors into a single pool. This allows Jay to relax his rule for typing constructors. As our intended target is Haskell, where for historical and efficiency reasons constructors for different datatypes can have overlapping representations in memory, we cannot make this same design choice.

Most of this work concerns type *checking* for GADTs. Much less has been done on type *inference*. An unpublished earlier version of this paper originally proposed the idea of wobbly types, but in a more complicated form than that described here [14]. In that work, the wobbly/rigid annotations were part of the syntax of *types* whereas, in this paper, a type is either entirely rigid or entirely wobbly. For example, in the present system, $\text{case } (x, y) \text{ of } \dots$ will do no type refinement if either x or y has a wobbly type, whereas before the rigidity of either x or y would lead to type refinement of the corresponding sub-pattern. However, this fine-grain attribution of wobbliness gave rise to significant additional complexity (such as “wobbly unification”), which is not necessary here, and we believe that the gain is simply not worth the pain. Furthermore, every program in the language of the earlier draft is typeable in the current system—perhaps with the addition of a few more type annotations.

Inspired by the wobbly-type idea, Pottier and Régis-Gianis found a way to factor the complexity into three parts: a *shape-inference* phase that propagates rigid type information throughout the program (introducing type annotations), a straightforward *constraint generation* phase that turns annotated program text into a set of constraints, followed by a *constraint-solving* phase [15]. They call this process *stratified type inference*. The novelty is in shape inference; constraint generation and solving for an annotated language is well established. The shape inference algorithm they use is more aggressive about propagating rigid types than our type system—as a result their system can infer types for some programs that our system would reject. Here is an example, taken from their paper, of a program that they accept but we reject. (This program uses the `Rep` type defined in Section 5.4):

```
double :: Rep a -> [a] -> [a]
= \r xs. map (\x. case r of RI -> x+x) xs
```

In our system, `x` would be given a wobbly type, and hence the `case` on `r` does not refine its type, so the program would be rejected. To fix the problem is easy: annotate the binding of `x`. The price to be paid is that their system is more complicated than the one we present here; for example, it is non-trivial to figure out whether the annotation on `x` is required. In contrast, we think that wobbly types make it easier to determine whether type information is available for GADTs, and that the extra annotations required are barely noticeable. However, we need more experience to be sure.

Another subtle difference between our system and stratified type inference is the treatment of refinements that create equalities between type variables. In our system, fmgu ensures that arbitrary choices between variables do not determine whether a program type checks. Alternatively, Pottier and Régis-Gianis introduce a total ordering between variables. When a choice between variables must be made, they choose the smaller one. We do not find this solution satisfying as resolving ambiguity based on variable ordering means that inference is sensitive to the order in which fresh vari-

ables are chosen during skolemization. Specifying this order seems a bit much for the specification of a type system. To be fair, this issue affects a small minority of programs that use GADTs, so the difference is not that significant. In fact, since rigid type propagation is more aggressive in their system, such ambiguities arise even less frequently than in ours.

Stuckey and Sulzmann also tackle the problem of type inference for GADTs [19]. They generate constraints and then solve them, but unlike Pottier *et al.*, they do not require a shape inference phase to precisely describe necessary type annotations. Instead, their inference algorithm, which also attacks polymorphic recursion, is incomplete. To assist users whose code does not type check, they develop a set of heuristics to identify where more type annotations are required. As a result, their compiler will accept programs with fewer type annotations than our system (or stratified type inference) requires, but these programs must be developed with the assistance of their compiler.

8. Conclusions and further work

We believe that expressive languages will shift increasingly towards type systems that exploit and propagate programmer annotations. Polymorphic recursion and higher-rank types are two established examples, and GADTs is another. We need tools to describe such systems, and the wobbly types we introduce here seem to offer a nice balance of expressiveness with predictability and simplicity of type inference. Furthermore, the idea of distinguishing programmer-specified types from inferred ones may well be useful in applications beyond GADTs. The main shortcoming of our implementation in GHC is that the interaction between GADTs and type classes is not dealt with properly. We plan to address this, along the lines proposed by Sulzmann [21].

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