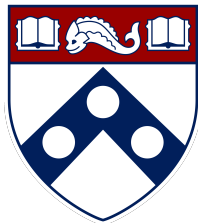


Demystifying *Disagreement-on-the-Line* in High Dimensions

(Joint work with Donghwan Lee, Xinmeng Huang, Edgar Dobriban, and Hamed Hassani)

Behrad Moniri
University of Pennsylvania

April 21, 2023





Introduction

Accuracy of ML models can degrade under distribution shifts.











[Koh et al., 2021]



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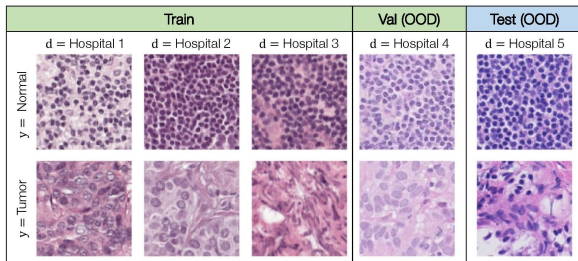
		Train			Val (OOD)	Test (OOD)
		d = Hospital 1	d = Hospital 2	d = Hospital 3	d = Hospital 4	d = Hospital 5
y = Normal						
y = Tumor						



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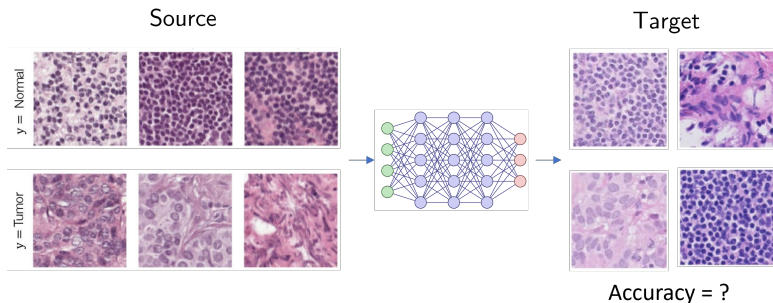


Dataset	Metric	In-dist setting	In-dist	Out-of-dist	Gap
iWILD/CAM2020-WILDS	Macro F1	Train-to-train	47.0 (1.4)	31.0 (1.3)	16.0
CAMELYON17-WILDS	Average acc	Train-to-train	93.2 (5.2)	70.3 (6.4)	22.9
RxRx1-WILDS	Average acc	Mixed-to-test	39.8 (0.2)	29.9 (0.4)	9.9
OGB-MolPCBA	Average AP	Random split	34.4 (0.9)	27.2 (0.3)	7.2
GLOBALWHEAT-WILDS	Average domain acc	Mixed-to-test	63.3 (1.7)	49.6 (1.9)	13.7
CIVILCOMMENTS-WILDS	Worst-group acc	Average	92.2 (0.1)	56.0 (3.6)	36.2
FMoW-WILDS	Worst-region acc	Mixed-to-test	48.6 (0.9)	32.3 (1.3)	16.3
POVERTYMAP-WILDS	Worst-U/R Pearson R	Mixed-to-test	0.60 (0.06)	0.45 (0.06)	0.15
AMAZON-WILDS	10th percentile acc	Average	71.9 (0.1)	53.8 (0.8)	18.1
PY150-WILDS	Method/class acc	Train-to-train	75.4 (0.4)	67.9 (0.1)	7.5



Estimate OOD Performance

Can we estimate OOD performance?

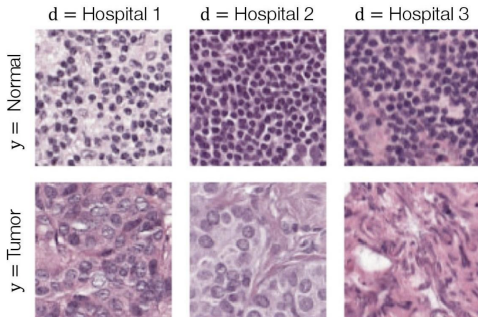




Why unlabeled data?

Often, we don't have access to labeled data from target.

- It is expensive to label new data.





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Often, we don't have access to labeled data from target.

- Rapidly changing environment. No time to label data.





Challenge

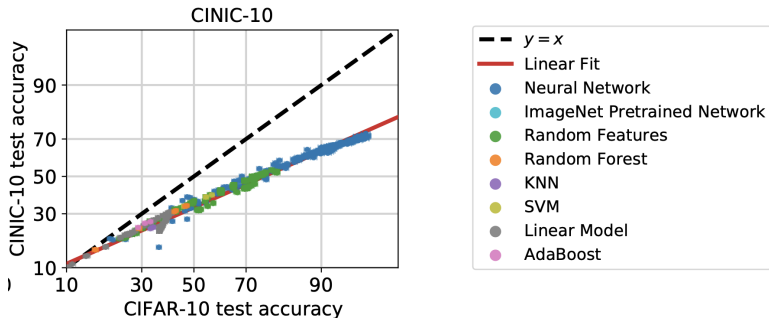
Challenge:

Estimate out-of-distribution performance
of a model only with unlabeled data.



Accuracy-on-the-line

- A linear trend between OOD and ID test error has been observed recently.



[Recht et al., 2019, Hendrycks et al., 2021, Koh et al., 2021, Taori et al., 2020, Miller et al., 2021]



Disagreement

- Disagreement = $\mathbb{E}[\mathbf{1}\{f_1(x) \neq f_2(x)\}]$



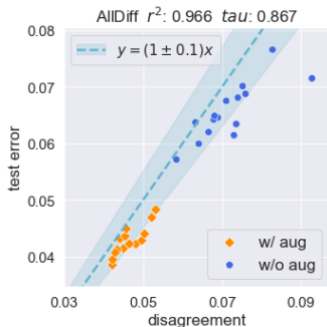
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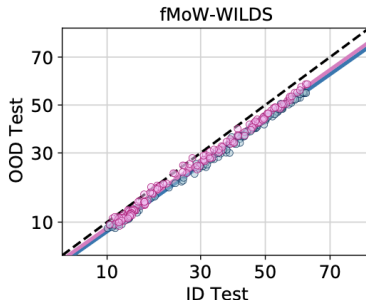
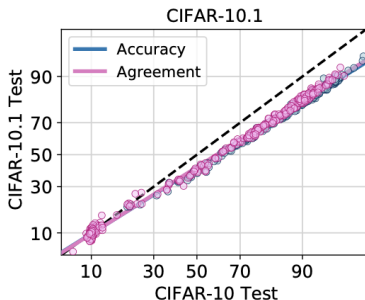


[Hacohen et al., 2020, Chen et al., 2021, Jiang et al., 2021, Nakkiran and Bansal, 2020, Baek et al., 2022, Atanov et al., 2022, Pliushch et al., 2022]



Disagreement-on-the-line

- In particular, [Baek et al., 2022] found that OOD vs. ID agreement forms a line, and it closely matches that of the accuracy.





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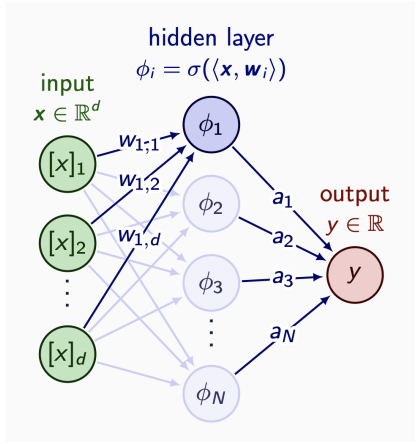
Theoretical Model



Two-Layer Neural Network

$$f_{\text{NN}}(x) = a^T \sigma(Wx)$$

- **Input data:** $x \in \mathbb{R}^d$.
- **Trainable parameters:** $W \in \mathbb{R}^{N \times d}, a \in \mathbb{R}^N$.
- **Nonlinearity:** $\sigma : \mathbb{R} \rightarrow \mathbb{R}$.





Problem Setting



- **Data generation:**

$$x_i \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \Sigma_s), \quad y_i = f^*(x_i) + \varepsilon_i, \quad \varepsilon_i \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma_\varepsilon^2).$$

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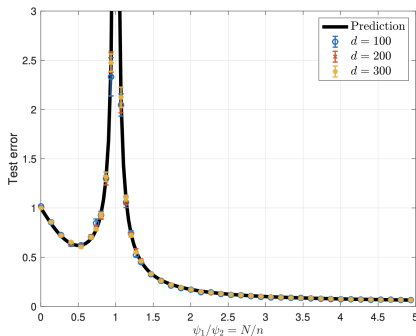
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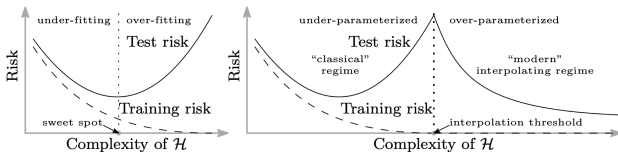
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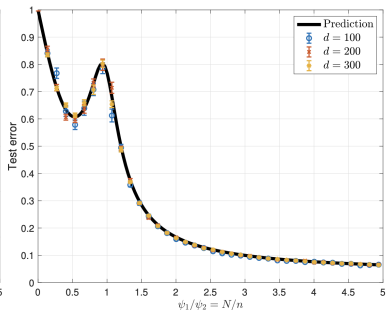
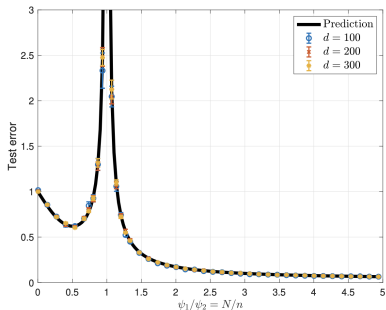
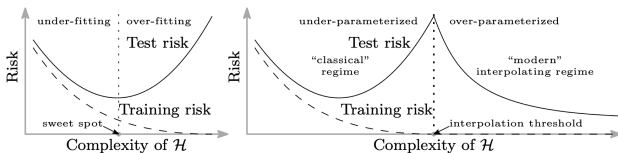




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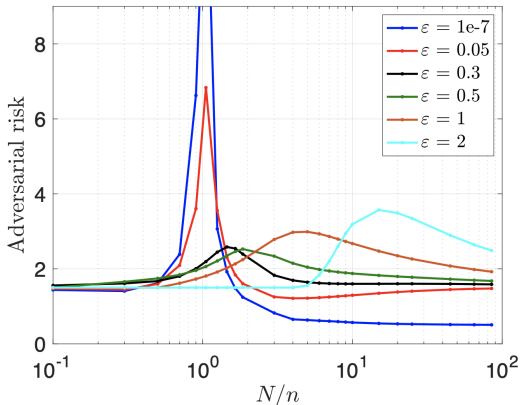


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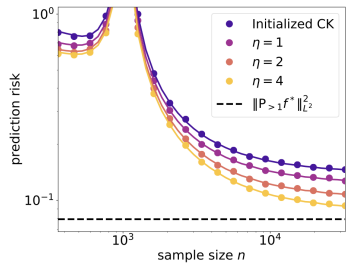
- Feature Learning. [Ba et al., 2022]



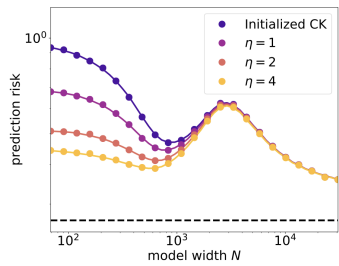
Why random features model?

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(a) One step (risk vs. sample size).



(b) One step (risk vs. width).

Analysis of Disagreement



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- We train two models with different “randomness” and then see how much they disagree on new data points.



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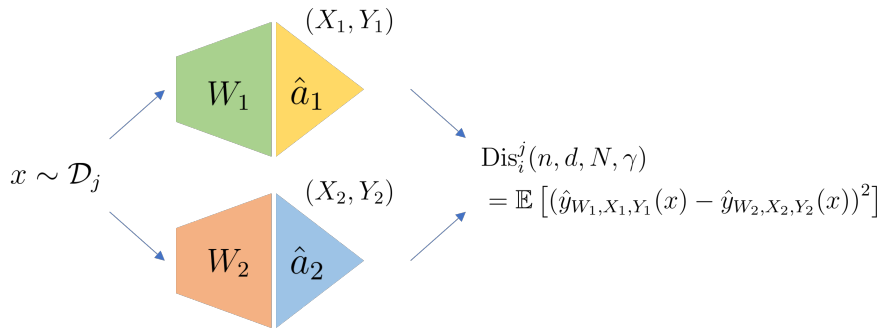


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- What do these translate to in random features models?

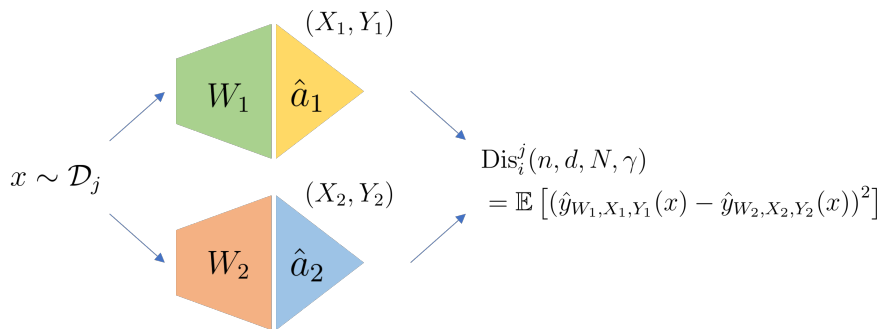


Types of Disagreement





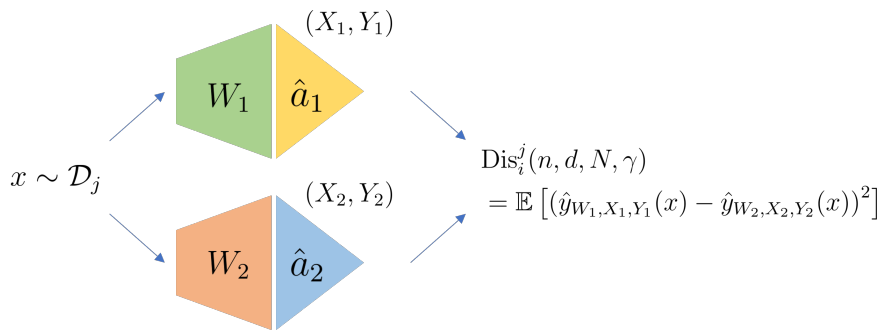
Types of Disagreement



- Independent ($i = \text{I}$): $(X_1, Y_1) \perp\!\!\!\perp (X_2, Y_2)$ and $W_1 \perp\!\!\!\perp W_2$.



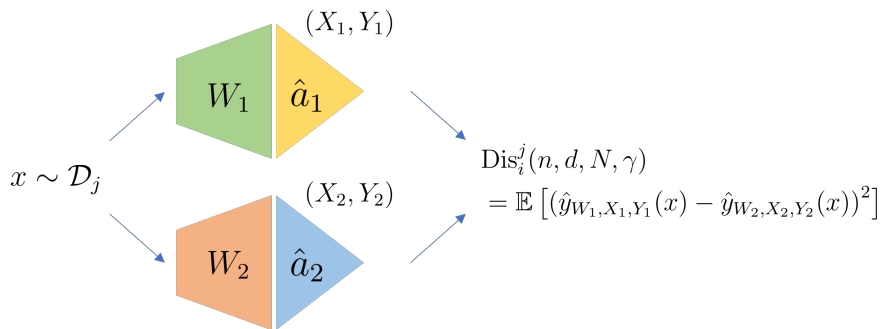
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- Shared-Weight ($i = SW$): $(X_1, Y_1) \perp\!\!\!\perp (X_2, Y_2)$ and $W_1 = W_2$.



Main Result

Theorem



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In the proportional regime ($n, d, N \rightarrow \infty$ with $d/n \rightarrow \phi$ and $d/N \rightarrow \psi$), we derive exact asymptotic formulae for disagreements. For $j \in \{s, t\}$, we derive

$$\text{Dis}_I^j(n, d, N, \gamma) \rightarrow \delta_I^j(\phi, \psi, \gamma)$$

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Proof technique: justify that the activation function can be linearized (Gaussian equivalence), then write disagreement as the expected trace of product of multiple random matrices and use tools from random matrix theory to analyze its limit.



Main Result

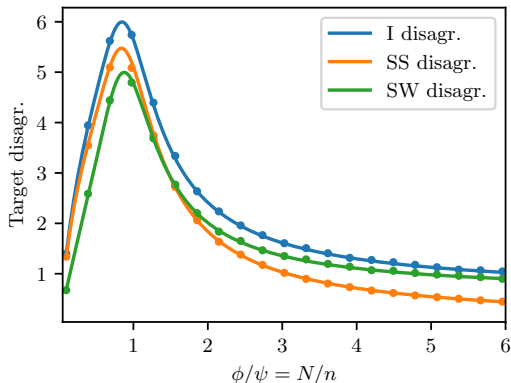


Figure: Asymptotics vs. simulations. We set $\gamma = 0.01$, $\sigma_\epsilon^2 = 0.25$, $\phi = 0.5$, $d = 512$, $n = 1024$, and specific Σ_s and Σ_t .



Theorem (Exact linear relation)



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In the overparameterized regime $\phi > \psi$ and for $i \in \{\text{I}, \text{SS}\}$,

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where the slopes and the intercepts are independent of ψ .



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The slope a is same as the slope for OOD vs. ID risk derived in [Tripuraneni et al., 2021] for the risk.



Linear Relation

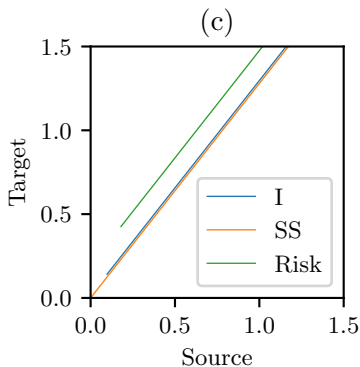


Figure: I and SS disagreement in the overparameterized and ridgeless setting have a linear relationship.

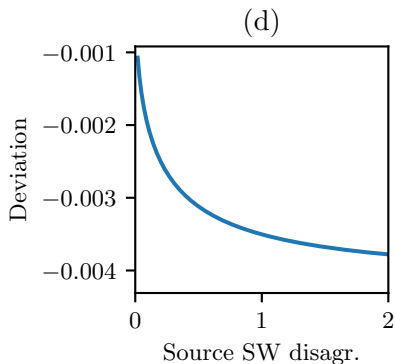


Figure: SW disagreement deviates from a line, even in the overparameterized and ridgeless setting.

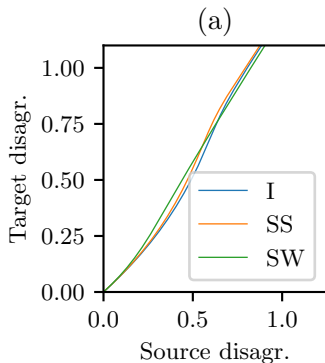


Figure: Disagreement-on-the-line *does not hold* in the underparametrized regime.



Theorem (Approximate linear relation)

When $\gamma \neq 0$, in the overparameterized regime, deviation from the line, for I and SS disagreement, is bounded by

$$|\delta_I^t(\phi, \psi, \gamma) - a\delta_I^s(\phi, \psi, \gamma) - b_I| \leq \frac{C(\gamma + \sqrt{\psi\gamma} + \psi\gamma + \gamma\sqrt{\psi\gamma})}{(1 - \psi/\phi + \sqrt{\psi\gamma})^2},$$

$$|\delta_{SS}^t(\phi, \psi, \gamma) - a\delta_{SS}^s(\phi, \psi, \gamma) - b_{SS}| \leq \frac{C(\sqrt{\psi\gamma} + \psi\gamma + \gamma\sqrt{\psi\gamma})}{(1 - \psi/\phi + \sqrt{\psi\gamma})^2},$$

where $C > 0$ depends on $\phi, \mu, \sigma_\varepsilon^2$, and σ .



Approximate Linear Relation

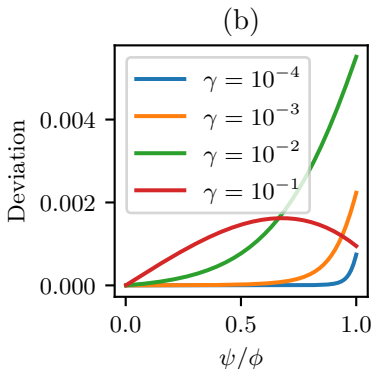


Figure: Deviation from the line, $\text{Dis}_{\text{SS}}^t(\phi, \psi, \gamma) - a\text{Dis}_{\text{SS}}^s(\phi, \psi, \gamma)$, as a function of ψ for non-zero γ .



Summary

Table: Existence of disagreement-on-the-line in the overparameterized regime for different regularization and types of disagreement.

	Dis _I and Dis _{SS}	Dis _{SW}
$\gamma \rightarrow 0$	✓ (Theorem 4.1)	✗ (Section 4.2)
$\gamma > 0$	▲ (Theorem 4.3)	

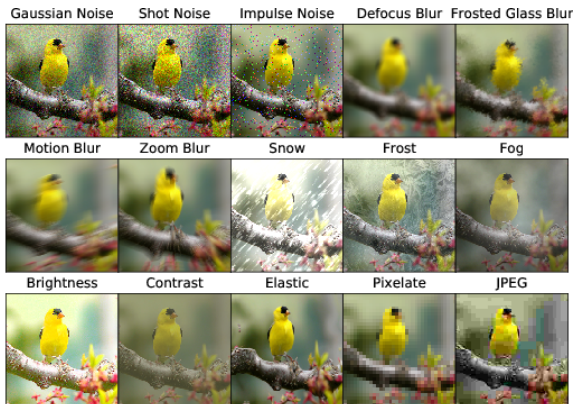
Experimental Results



- We proved everything for Gaussian input but real data is never Gaussian. Do our results still hold in more general settings?



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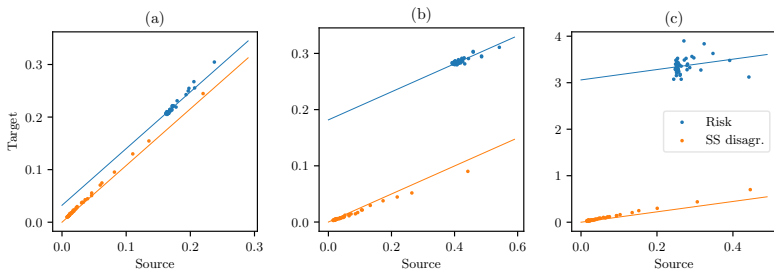


Figure: **(a)** CIFAR-10-C-Snow (severity 3) **(b)** Tiny ImageNet-C-Fog (severity 3) **(c)** Camelyon17; For more results, see Section D.3.



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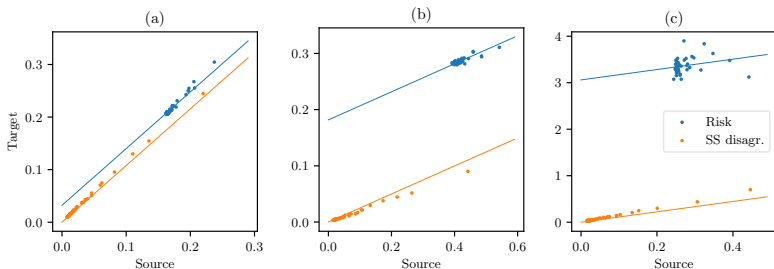


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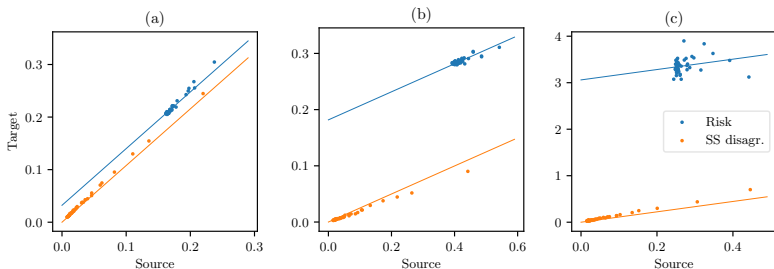


Figure: **(a)** CIFAR-10-C-Snow (severity 3) **(b)** Tiny ImageNet-C-Fog (severity 3) **(c)** Camelyon17; For more results, see Section D.3.

- Disagreement-on-the-line generalizes to non-Gaussian data (universality).
- Disagreement-on-the-line holds regardless of concept drift, i.e., the change in $\mathbb{P}(y|x)$.

Conclusion



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Conclusion

- Disagreement-on-the-line is a nuanced phenomenon that can depend on the type of *randomness shared*, *regularization*, and the level of *overparametrization*.
- Contrary to the prior observation, the line for disagreement and the line for risk can *differ* in their intercepts.
- Experiments on several real-world datasets show that our theory is relevant beyond our theoretical setting.



Open Questions

- We showed that the intercepts for disagreement and risk can be different and characterized the difference. For practical use, can this difference in intercept be corrected?



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- Formal justification of universality – [Montanari and Saeed, 2022, Goldt et al., 2022, Loureiro et al., 2021, Pesce et al., 2023]



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Thank You!