

Precise Tradeoffs in [and asymptotics of] Adversarial Training for Linear Regression

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STAT 972 Final Presentation

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Precise Tradeoffs in Adversarial Training for Linear Regression

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Modern Neural Networks are very good tools for prediction.



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Modern Neural Networks are very good tools for prediction.



Modern Neural Networks are not robust to adversarial attacks.



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- Data: $(\mathbf{x}_i, y_i) \sim \mathbb{P}(\mathbb{R}^d, \mathbb{R})$
- Model: $f_{\theta}(\cdot) : \mathbb{R}^d \to \mathbb{R}$
- Loss Function: $\ell(\theta, \mathbf{x}, y) = (y f_{\theta}(\mathbf{x}))^2$

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Traditional Supervised learning

Population Loss:

$$SR(\theta) = \mathbb{E}_{\mathbf{x},y}[\ell(\theta, \mathbf{x}, y)]$$

Empirical Risk Minimization:

$$\widehat{\boldsymbol{\theta}}_{ERM} = \arg\min_{\boldsymbol{\theta}} \frac{1}{n} \sum_{i=1}^{n} \ell(\boldsymbol{\theta}, \mathbf{x}_i, y_i)$$



L_p , $p \ge 1$: Simplest Possible Geometry



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Robust supervised learning

Adversarial Loss:

$${\sf AR}(oldsymbol{ heta}) = \mathbb{E}_{{\sf x},y}\left[\max_{||oldsymbol{\delta}||_2 \leq arepsilon} \ell(oldsymbol{ heta},{\sf x}+oldsymbol{\delta},y)
ight]$$

Adverasrial Training:

$$\widehat{\boldsymbol{\theta}^{\varepsilon}} = \arg\min_{\boldsymbol{\theta}} \frac{1}{n} \sum_{i=1}^{n} \max_{||\boldsymbol{\delta}_i||_2 \leq \varepsilon} \ell(\boldsymbol{\theta}, \mathbf{x}_i + \boldsymbol{\delta}_i, y_i)$$





• $AR(\widehat{\theta}_{ERM})$ is large and $AR(\widehat{\theta}^{\varepsilon})$ is much smaller.

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Observations



- $AR(\hat{\theta}_{ERM})$ is large and $AR(\hat{\theta}^{\varepsilon})$ is much smaller.
- $SR(\widehat{\theta}^{\varepsilon})$ is larger than $SR(\widehat{\theta}_{ERM})$.

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Observations



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Observations



- $AR(\hat{\theta}_{ERM})$ is large and $AR(\hat{\theta}^{\varepsilon})$ is much smaller.
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Questions:

- Is there a fundamental tradeoff between SR and AR?
- How can we algorithmically achieve this tradeoff?

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Linear Regression: Fundamental Tradeoffs

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$$y_i = \langle \mathbf{x}_i, \boldsymbol{\theta}_0
angle + w_i$$
 where $\mathbf{x}_i \sim \mathcal{N}\left(\mathbf{0}, \mathbf{I}_p\right)$ $w_i \sim \mathcal{N}\left(0, \sigma_0^2\right)$

for $1 \leq i \leq n$.

• We also focus on training linear models of the form $f_{\theta}(\mathbf{x}) = \langle \mathbf{x}, \theta \rangle$



$$m{y}_i = \langle \mathbf{x}_i, m{ heta}_0
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We also focus on training linear models of the form f_θ(x) = (x, θ)
 We can write:

$$\mathsf{SR}(\widehat{\boldsymbol{ heta}}) := \mathbb{E}\left[(y - \langle \boldsymbol{x}, \widehat{\boldsymbol{ heta}} \rangle)^2\right]$$

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We also focus on training linear models of the form f_θ(x) = (x, θ)
 We can write:

$$\mathsf{SR}(\widehat{\boldsymbol{\theta}}) := \mathbb{E}\left[(\boldsymbol{y} - \langle \boldsymbol{x}, \widehat{\boldsymbol{\theta}} \rangle)^2 \right] = \sigma_0^2 + \left\| \widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \right\|_{\ell_2}^2,$$

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$$m{y}_i = \langle m{x}_i, m{ heta}_0
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We also focus on training linear models of the form f_θ(x) = (x, θ)
 We can write:

$$\begin{split} \mathsf{SR}(\widehat{\boldsymbol{\theta}}) &:= \mathbb{E}\left[(y - \langle \boldsymbol{x}, \widehat{\boldsymbol{\theta}} \rangle)^2 \right] = \sigma_0^2 + \left\| \widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \right\|_{\ell_2}^2, \\ \mathsf{AR}(\widehat{\boldsymbol{\theta}}) &:= \mathbb{E}\left[\max_{\|\boldsymbol{\delta}\|_{\ell_2} \leq \varepsilon} (y - \langle \boldsymbol{x} + \boldsymbol{\delta}, \widehat{\boldsymbol{\theta}} \rangle)^2 \right] \end{split}$$

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$$m{y}_i = \langle m{x}_i, m{ heta}_0
angle + w_i$$
 where $m{x}_i \sim \mathcal{N}\left(m{0}, m{I}_
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for $1 \leq i \leq n$.

We also focus on training linear models of the form f_θ(x) = (x, θ)
 We can write:

$$\begin{aligned} \mathsf{SR}(\widehat{\boldsymbol{\theta}}) &:= \mathbb{E}\left[(\boldsymbol{y} - \langle \boldsymbol{x}, \widehat{\boldsymbol{\theta}} \rangle)^2 \right] = \sigma_0^2 + \left\| \widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \right\|_{\ell_2}^2, \\ \mathsf{AR}(\widehat{\boldsymbol{\theta}}) &:= \mathbb{E}\left[\max_{\|\boldsymbol{\delta}\|_{\ell_2} \leq \varepsilon} (\boldsymbol{y} - \langle \boldsymbol{x} + \boldsymbol{\delta}, \widehat{\boldsymbol{\theta}} \rangle)^2 \right] \\ &= \left(\sigma_0^2 + \left\| \widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \right\|_{\ell_2}^2 + \varepsilon^2 \| \widehat{\boldsymbol{\theta}} \|_{\ell_2}^2 \right) \\ &+ 2\sqrt{\frac{2}{\pi}} \varepsilon \| \widehat{\boldsymbol{\theta}} \|_{\ell_2} \left(\sigma_0^2 + \left\| \widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \right\|_{\ell_2}^2 \right)^{1/2}. \end{aligned}$$

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Pareto-optimal points are the intersection points of the region with the supporting lines:

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The solution θ^{λ} is given by

$$oldsymbol{ heta}^{\lambda} = \left(1+\gamma_0^{\lambda}
ight)^{-1}oldsymbol{ heta}_0,$$

with γ_0^{λ} the fixed point of the following two equations:

$$\begin{split} \gamma_{0}^{\lambda} &= \frac{\varepsilon_{\text{test}}^{2} + \sqrt{\frac{2}{\pi}}\varepsilon_{\text{test}} A^{\lambda}}{1 + \lambda + \sqrt{\frac{2}{\pi}}\frac{\varepsilon_{\text{test}}}{A^{\lambda}}} \\ A^{\lambda} &= \frac{1}{\|\boldsymbol{\theta}_{0}\|_{\ell_{2}}} \left(\left(1 + \gamma_{0}^{\lambda}\right)^{2} \sigma_{0}^{2} + \left(\gamma_{0}^{\lambda}\right)^{2} \|\boldsymbol{\theta}_{0}\|_{\ell_{2}}^{2} \right)^{1/2} \end{split}$$



Linear Regression: Algorithmic Tradeoffs

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• Consider a class of estimators $\left\{\widehat{\theta^{\varepsilon}} : \varepsilon \ge 0\right\}$ constructed via the following saddle point problem:

$$\widehat{\boldsymbol{\theta}^{\varepsilon}} \in \arg\min_{\boldsymbol{\theta} \in \mathbb{R}^{\rho}} \max_{\|\boldsymbol{\delta}_i\| \leq \varepsilon} \frac{1}{n} \sum_{i=1}^n \left(y_i - \langle \boldsymbol{x}_i + \boldsymbol{\delta}_i, \boldsymbol{\theta} \rangle \right)^2$$

Can one of these (adversarially trained) estimators achieve the optimal tradeoff?



• Consider a class of estimators $\left\{\widehat{\theta^{\varepsilon}} : \varepsilon \ge 0\right\}$ constructed via the following saddle point problem:

$$\widehat{\boldsymbol{\theta}^{\varepsilon}} \in \arg\min_{\boldsymbol{\theta} \in \mathbb{R}^p} \max_{\|\boldsymbol{\delta}_i\| \leq \varepsilon} \frac{1}{n} \sum_{i=1}^n \left(y_i - \langle \boldsymbol{x}_i + \boldsymbol{\delta}_i, \boldsymbol{\theta} \rangle \right)^2$$

- Can one of these (adversarially trained) estimators achieve the optimal tradeoff?
- ► The answer is in the limit.

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- Assume that $n \to \infty$, $d \to \infty$ and $n/d \to \delta$.
- Can we find an asymptotic expression for $AR(\widehat{\theta^{\varepsilon}})$ and $SR(\widehat{\theta^{\varepsilon}})$?

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- Assume that $n \to \infty$, $d \to \infty$ and $n/d \to \delta$.
- Can we find an asymptotic expression for $AR(\widehat{\theta}^{\varepsilon})$ and $SR(\widehat{\theta}^{\varepsilon})$?
- Note that these expression can both be written in terms of only $\|\widehat{\theta} \theta_0\|_{\ell_2}^2$ and $\|\widehat{\theta}\|_{\ell_2}^2$.

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- Assume that $n \to \infty$, $d \to \infty$ and $n/d \to \delta$.
- Can we find an asymptotic expression for $AR(\widehat{\theta^{\varepsilon}})$ and $SR(\widehat{\theta^{\varepsilon}})$?
- Note that these expression can both be written in terms of only $\|\widehat{\theta} \theta_0\|_{\ell_2}^2$ and $\|\widehat{\theta}\|_{\ell_2}^2$.
- ► To do this, we will use Convex Gaussian Minmax Theorem (CGMT).

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Standard linear regression has widely been studied in the proportional limit:

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- Standard linear regression has widely been studied in the proportional limit:
 - The underparameterized regime:

[1] Antonia M. Tulino and Sergio Verdu. Random matrix theory and wireless communications. Foundations and Trends in Communications and Information Theory, 2004.

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General case:

[2] Edgar Dobriban and Stefan Wager. High-dimensional asymptotics of prediction: ridge regression and classification. Annals of Statistics, 2018.

[3] Trevor Hastie, Andrea Montanari, Saharon Rosset, Ryan J. Tibshirani. Surprises in High-Dimensional Ridgeless Least Squares Interpolation, Annals of Statistics, 2022.

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They all use the Marchenko-Pastur limit. Here, we cannot use that because there is no closed form for the estimator.

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Theorem (Convex Gaussian Min-Max Theorem (CGMT) – informal) For **X** with i.i.d standard normal entries and $\psi(\cdot, \cdot)$ a convex-concave function, define

$$\Phi(\mathbf{X}) := \min_{\mathbf{z}} \max_{\mathbf{u}} \mathbf{u}^{T} \mathbf{X} \mathbf{z} + \psi(\mathbf{z}, \mathbf{u}) \quad (PO)$$

$$\phi(\mathbf{g},\mathbf{h}) := \min_{\mathbf{z}} \max_{\mathbf{u}} \|\mathbf{z}\| \mathbf{g}^{\mathsf{T}} \mathbf{u} + \|\mathbf{u}\| \mathbf{h}^{\mathsf{T}} \mathbf{z} + \psi(\mathbf{z},\mathbf{u}) \quad (AO)$$

We have $\Phi(\mathbf{X}) \approx \phi(\mathbf{g}, \mathbf{h})$, in which \mathbf{g}, \mathbf{h} are standard Gaussian random vectors. Also the norms of the solutions for both optimization problems are equal.

[Thrampoulidis, Oymak, and Hassibi; 2016 & 2018]



Finding the asymptotic expressions for $AR(\widehat{\theta^{\varepsilon}})$ and $SR(\widehat{\theta^{\varepsilon}})$:

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Finding the asymptotic expressions for $AR(\widehat{\theta^{\varepsilon}})$ and $SR(\widehat{\theta^{\varepsilon}})$:

Step 1: Adversarial loss has a closed form:

$$egin{aligned} \widehat{oldsymbol{ heta}}^{\widehat{oldsymbol{arepsilon}}} \in & rg\min_{oldsymbol{ heta}\in\mathbb{R}^d}\max_{\|oldsymbol{\delta}_i\|\leq arepsilon}rac{1}{2n}\sum_{i=1}^nig(y_i-\langleoldsymbol{x}_i+oldsymbol{\delta}_i,oldsymbol{ heta}
ight)^2 \ &= rg\min_{oldsymbol{ heta}\in\mathbb{R}^d}rac{1}{2n}\sum_{i=1}^nig(|y_i-\langleoldsymbol{x}_i,oldsymbol{ heta}
angle|+arepsilon\|oldsymbol{ heta}|_{\ell_2}ig)^2 \end{aligned}$$

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• Step 2: Write in the form of a Primary Optimization. $\min_{\boldsymbol{\theta} \in \mathbb{R}^d} \frac{1}{2n} \sum_{i=1}^n (|y_i - \langle \boldsymbol{x}_i, \boldsymbol{\theta} \rangle| + \varepsilon \|\boldsymbol{\theta}\|_{\ell_2})^2$

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► **Step 2**: Write in the form of a Primary Optimization.

$$\min_{\boldsymbol{\theta} \in \mathbb{R}^{d}} \frac{1}{2n} \sum_{i=1}^{n} (|y_{i} - \langle \mathbf{x}_{i}, \boldsymbol{\theta} \rangle| + \varepsilon \|\boldsymbol{\theta}\|_{\ell_{2}})^{2}$$

$$= \min_{\boldsymbol{\theta} \in \mathbb{R}^{d}} \frac{1}{2n} \sum_{i=1}^{n} (|w_{i} - \langle \mathbf{x}_{i}, \boldsymbol{\theta} - \boldsymbol{\theta}_{0} \rangle| + \varepsilon \|\boldsymbol{\theta}\|_{\ell_{2}})^{2}$$

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$$= \min_{\boldsymbol{z} \in \mathbb{R}^{d}, \boldsymbol{v} \in \mathbb{R}^{n}} \frac{1}{2n} \sum_{i=1}^{n} (|\boldsymbol{v}_{i}| + \varepsilon \|\boldsymbol{z} + \boldsymbol{\theta}_{0}\|_{\ell_{2}})^{2}$$
s.t. $\boldsymbol{v} = \boldsymbol{w} - \boldsymbol{X}\boldsymbol{z}$

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► Step 2: Write in the form of a Primary Optimization.

$$\min_{\boldsymbol{\theta} \in \mathbb{R}^{d}} \frac{1}{2n} \sum_{i=1}^{n} (|\mathbf{y}_{i} - \langle \mathbf{x}_{i}, \boldsymbol{\theta} \rangle| + \varepsilon ||\boldsymbol{\theta}||_{\ell_{2}})^{2}$$

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$$= \min_{\boldsymbol{z} \in \mathbb{R}^{d}, \mathbf{v} \in \mathbb{R}^{n}} \frac{1}{2n} \sum_{i=1}^{n} (|\mathbf{v}_{i}| + \varepsilon ||\mathbf{z} + \boldsymbol{\theta}_{0}||_{\ell_{2}})^{2} \quad \text{s.t. } \mathbf{v} = \mathbf{w} - \mathbf{X}\mathbf{z}$$

$$= \min_{\boldsymbol{z} \in \mathbb{R}^{d}, \mathbf{v} \in \mathbb{R}^{n}} \frac{1}{2n} (||\mathbf{v}||_{\ell_{2}}^{2} + n\varepsilon^{2}||\mathbf{z} + \boldsymbol{\theta}_{0}||_{\ell_{2}}^{2} + 2\varepsilon ||\mathbf{z} + \boldsymbol{\theta}_{0}||_{\ell_{2}}||\mathbf{v}||_{\ell_{1}})$$

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► Step 2: Write in the form of a Primary Optimization.

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$$= \min_{\boldsymbol{z} \in \mathbb{R}^{d}, \mathbf{v} \in \mathbb{R}^{n}} \max_{\mathbf{u} \in \mathbb{R}^{n}} \frac{1}{2n} (||\mathbf{v}||_{\ell_{2}}^{2} + n\varepsilon^{2}||\mathbf{z} + \boldsymbol{\theta}_{0}||_{\ell_{2}}^{2} + 2\varepsilon ||\mathbf{z} + \boldsymbol{\theta}_{0}||_{\ell_{2}}||\mathbf{v}||_{\ell_{1}})$$

$$+ \frac{1}{2n} \mathbf{u}^{\top} (\mathbf{v} - \mathbf{w} + \mathbf{X}\mathbf{z})$$

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CGMT PO and AO forms:

$$\Phi(\mathbf{X}) := \min_{\mathbf{z}} \max_{\mathbf{u}} \mathbf{u}^{T} \mathbf{X} \mathbf{z} + \psi(\mathbf{z}, \mathbf{u}) \quad (PO)$$
$$\phi(\mathbf{g}, \mathbf{h}) := \min_{\mathbf{z}} \max_{\mathbf{u}} \|\mathbf{z}\| \mathbf{g}^{T} \mathbf{u} + \|\mathbf{u}\| \mathbf{h}^{T} \mathbf{z} + \psi(\mathbf{z}, \mathbf{u}) \quad (AO)$$

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Primary Optimization:

$$\min_{\boldsymbol{z} \in \mathbb{R}^{d}, \boldsymbol{\mathsf{v}} \in \mathbb{R}^{n}} \max_{\boldsymbol{\mathsf{u}} \in \mathbb{R}^{n}} \quad \frac{1}{2n} \left(||\boldsymbol{\mathsf{v}}||_{\ell_{2}}^{2} + n\varepsilon^{2} ||\boldsymbol{z} + \boldsymbol{\theta}_{0}||_{\ell_{2}}^{2} + 2\varepsilon ||\boldsymbol{z} + \boldsymbol{\theta}_{0}||_{\ell_{2}} ||\boldsymbol{\mathsf{v}}||_{\ell_{1}} \right) \\ + \frac{1}{2n} \boldsymbol{\mathsf{u}}^{\top} (\boldsymbol{\mathsf{v}} - \boldsymbol{\mathsf{w}} + \boldsymbol{\mathsf{X}} \boldsymbol{z})$$

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Primary Optimization:

$$\min_{\mathbf{z} \in \mathbb{R}^{d}, \mathbf{v} \in \mathbb{R}^{n}} \max_{\mathbf{u} \in \mathbb{R}^{n}} \quad \frac{1}{2n} \left(||\mathbf{v}||_{\ell_{2}}^{2} + n\varepsilon^{2} ||\mathbf{z} + \theta_{0}||_{\ell_{2}}^{2} + 2\varepsilon ||\mathbf{z} + \theta_{0}||_{\ell_{2}} ||\mathbf{v}||_{\ell_{1}} \right)$$
$$+ \frac{1}{2n} \mathbf{u}^{\top} (\mathbf{v} - \mathbf{w} + \mathbf{X}\mathbf{z})$$

Hence, the Auxiliary Optimization is:

$$\min_{\boldsymbol{z}\in\mathbb{R}^{n},\boldsymbol{v}\in\mathbb{R}^{n}}\max_{\boldsymbol{u}\in\mathbb{R}^{n}} \frac{1}{2n}\left(\|\boldsymbol{z}\|_{\ell_{2}}\boldsymbol{g}^{T}\boldsymbol{u}+\|\boldsymbol{u}\|_{\ell_{2}}\boldsymbol{h}^{T}\boldsymbol{z}-\boldsymbol{u}^{T}\boldsymbol{\omega}+\boldsymbol{u}^{T}\boldsymbol{v}\right)$$
$$+\frac{1}{2n}\left(\|\boldsymbol{v}\|_{\ell_{2}}^{2}+n\varepsilon^{2}\|\boldsymbol{z}+\boldsymbol{\theta}_{0}\|_{\ell_{2}}^{2}+2\varepsilon\|\boldsymbol{z}+\boldsymbol{\theta}_{0}\|_{\ell_{2}}\|\boldsymbol{v}\|_{\ell_{1}}\right).$$



$$\min_{\mathbf{z}\in\mathbb{R}^{d},\mathbf{v}\in\mathbb{R}^{n}} \max_{\mathbf{u}\in\mathbb{R}^{n}} \quad \frac{1}{2n} \left(\|\mathbf{z}\|_{\ell_{2}} \mathbf{g}^{\mathsf{T}} \mathbf{u} + \|\mathbf{u}\|_{\ell_{2}} \mathbf{h}^{\mathsf{T}} \mathbf{z} - \mathbf{u}^{\mathsf{T}} \boldsymbol{\omega} + \mathbf{u}^{\mathsf{T}} \mathbf{v} \right) \\ + \frac{1}{2n} \left(||\mathbf{v}||_{\ell_{2}}^{2} + n\varepsilon^{2} ||\mathbf{z} + \theta_{0}||_{\ell_{2}}^{2} + 2\varepsilon ||\mathbf{z} + \theta_{0}||_{\ell_{2}} ||\mathbf{v}||_{\ell_{1}} \right).$$

Scalarization: Starting with the maximization over **u**, let $\mathbf{u} = \beta \tilde{\mathbf{u}}$.

$$\max_{\mathbf{u}\in\mathbb{R}^n} \quad \frac{1}{2n} \left(\|\boldsymbol{z}\|_{\ell_2} \boldsymbol{g}^T \boldsymbol{u} + \|\boldsymbol{u}\|_{\ell_2} \boldsymbol{h}^T \boldsymbol{z} - \boldsymbol{u}^T \boldsymbol{\omega} + \boldsymbol{u}^T \boldsymbol{v} \right)$$
$$= \max_{\beta} \quad \frac{1}{2n} \left(\beta \boldsymbol{h}^T \boldsymbol{z} + \|\|\boldsymbol{z}\|_{\ell_2} \boldsymbol{g} - \boldsymbol{w} + \boldsymbol{v}\|_{\ell_2} \right).$$

Repeat for the other variables z and v.

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Eventually, the AO is reduced to

$$\max_{0 \leq \beta \leq K_{\beta}} \sup_{\gamma, \tau_h \geq 0} \min_{0 \leq \alpha \leq K_{\alpha}} \min_{\tau_g \geq 0} D(\alpha, \beta, \gamma, \tau_h, \tau_g),$$

with

$$\begin{split} D\left(\alpha,\beta,\gamma,\tau_{h},\tau_{g}\right) &= \\ \frac{\delta\beta}{2\left(\tau_{g}+\beta\right)}\left(\alpha^{2}+\sigma^{2}\right) - \frac{\alpha}{2\tau_{h}}\left(\gamma^{2}+\beta^{2}\right) + \gamma\sqrt{\frac{\alpha^{2}\beta^{2}}{\tau_{h}^{2}}} + \mathbf{V}^{2} - \frac{\alpha\tau_{h}}{2} + \frac{\beta\tau_{g}}{2} \\ &+ \delta\mathbf{1}_{\left\{\gamma\left(\tau_{g}+\beta\right)>\sqrt{\frac{2}{\pi}}\delta\varepsilon\beta\sqrt{\alpha^{2}+\sigma^{2}}\right\}} \frac{\beta^{2}\left(\alpha^{2}+\sigma^{2}\right)}{2\tau_{g}\left(\tau_{g}+\beta\right)}\left(\operatorname{erf}\left(\frac{\tau_{*}}{\sqrt{2}}\right) - \frac{\gamma\left(\tau_{g}+\beta\right)}{\delta\varepsilon\beta\sqrt{\alpha^{2}+\sigma^{2}}}\tau_{*}\right) \end{split}$$

and τ_{\ast} is the unique solution to

$$\frac{\gamma\left(\tau_{g}+\beta\right)}{\delta\varepsilon\beta\sqrt{\alpha^{2}+\sigma^{2}}}-\frac{\beta}{\tau_{g}}\tau-\tau\cdot\mathsf{erf}\left(\frac{\tau}{\sqrt{2}}\right)-\sqrt{\frac{2}{\pi}}\mathsf{e}^{-\frac{\tau^{2}}{2}}=\mathsf{0}$$



It holds in probability that

$$\begin{split} &\lim_{n\to\infty} \frac{1}{d} \left\| \widehat{\boldsymbol{\theta}}^{\varepsilon} - \boldsymbol{\theta}_0 \right\|_{\ell_2}^2 = \alpha_*^2, \\ &\lim_{n\to\infty} \frac{1}{\sqrt{d}} \left\| \widehat{\boldsymbol{\theta}}^{\varepsilon} \right\|_{\ell_2} = \frac{\beta_* \tau_* \sqrt{\alpha_*^2 + \sigma^2}}{\varepsilon \tau_{g*}}. \end{split}$$

Hence, the following also holds in probability

$$\begin{split} \lim_{n \to \infty} \mathrm{SR}\left(\hat{\theta}^{\varepsilon}\right) &= \sigma^{2} + \alpha_{*}^{2},\\ \lim_{n \to \infty} \mathrm{AR}\left(\hat{\theta}^{\varepsilon}\right) &= \left(\sigma^{2} + \alpha_{*}^{2} + \varepsilon^{2}\left(\alpha_{*}^{2} + \sigma^{2}\right)\left(\frac{\beta_{*}\tau_{*}}{\varepsilon\tau_{g*}}\right)^{2}\right)\\ &+ 2\sqrt{\frac{2}{\pi}}\frac{\varepsilon}{\varepsilon\tau_{g*}}\frac{\beta_{*}\tau_{*}}{\varepsilon\tau_{g*}}\left(\sigma^{2} + \alpha_{*}^{2}\right). \end{split}$$





Image: A matrix

э.



Role of Overparameterization

Behrad Moniri and Samar Hadou

Adversarial Training

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Overparameterized





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Underparameterized





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Interpolation threshold depends on ε .

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What else can be done?

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Adversarial Training

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- Adversarial training of random feature models: $y = \theta^{\top} \sigma(W \mathbf{x}) + \epsilon$.
- ▶ $W \in R^{N \times d}$, $\theta \in \mathbb{R}^d$, and we have *n* samples.

•
$$\psi_1 = N/n$$
 and $\psi_2 = n/d$.

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► Idea (Gaussian Equivalence):

$$\sigma(W\mathbf{x}) = \mu_0 \mathbf{1} + \mu_1 W\mathbf{x} + \mu_2 \sigma_{\perp}(W\mathbf{x}) \quad \mathbb{E}[W\mathbf{x}\sigma_{\perp}(W\mathbf{x})^{\top}] = 0$$
$$= \mu_0 \mathbf{1} + \mu_1 W\mathbf{x} + \mathbf{u}$$

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▶ Then, use CGMT for the linear regression that pops out.





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Thank You!

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