

**CIS 500**

Software Foundations

Fall 2002

**25 September**

# The Pure Lambda Calculus

# Syntax

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$t ::=$

$x$

$\lambda x. t$

$t t$

terms:

variable

abstraction

application

# Values

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$v ::=$

$\lambda x. t$

values:

abstraction value

# Operational Semantics

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Computation rule:

$$(\lambda x. t_{12}) v_2 \longrightarrow [x \mapsto v_2]t_{12} \quad (\text{E-APPABS})$$

$[x \mapsto v_2]t_{12}$  is “the term that results from substituting occurrences of  $x$  in  $t_{12}$  with  $v_2$ .”

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Congruence rules:

$$\frac{t_1 \longrightarrow t'_1}{t_1 t_2 \longrightarrow t'_1 t_2} \quad (\text{E-APP1})$$

$$\frac{t_2 \longrightarrow t'_2}{v_1 t_2 \longrightarrow v_1 t'_2} \quad (\text{E-APP2})$$

# Terminology

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A term of the form  $(\lambda x.t) v$  — that is, a  $\lambda$ -abstraction applied to a **value** — is called a **redex** (from “reducible expression”).

## Alternative evaluation strategies

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The evaluation strategy we have chosen — called **call by value** — reflects standard conventions found in most mainstream languages.

Some other common ones:

- ◆ Full beta-reduction
- ◆ Normal order (leftmost/outermost)
- ◆ Call by name (cf. Haskell)



# Programming in the Lambda-Calculus

## Multiple arguments

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On Monday, we wrote a function `double` that returns a function as an argument.

$$\text{double} = \lambda f. \lambda y. f (f y)$$

This idiom — a  $\lambda$ -abstraction that does nothing but immediately yield another abstraction — is very common in the  $\lambda$ -calculus.

In general,  $\lambda x. \lambda y. t$  is a function that, given a value  $v$  for  $x$ , yields a function that, given a value  $u$  for  $y$ , yields  $t$  with  $v$  in place of  $x$  and  $u$  in place of  $y$ .

That is,  $\lambda x. \lambda y. t$  is a two-argument function.

## Aside: Currying

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The transformation from a function taking a pair of arguments (in a language like OCaml that provides pairs) to a one-argument function returning another one-argument function is called **currying**.

It is considered good style in OCaml to define functions in curried style whenever possible.

## Syntactic conventions

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Since  $\lambda$ -calculus provides only one-argument functions, all multi-argument functions must be written in curried style.

The following conventions make the linear forms of terms easier to read and write:

- ◆ Application associates to the left
- ◆ Bodies of  $\lambda$ - abstractions extend as far to the right as possible

## The “Church Booleans”

`tru` =  $\lambda t. \lambda f. t$

`fls` =  $\lambda t. \lambda f. f$

`tru v w`  
=  $(\lambda t. \lambda f. t)$  `v w` by definition  
→  $(\lambda f. v)$  `w` reducing the underlined redex  
→ `v` reducing the underlined redex

`fls v w`  
=  $(\lambda t. \lambda f. f)$  `v w` by definition  
→  $(\lambda f. f)$  `w` reducing the underlined redex  
→ `w` reducing the underlined redex

## Functions on Booleans

---

`not = λb. b fls tru`

That is, `not` is a function that, given a boolean value `v`, returns `fls` if `v` is `tru` and `tru` if `v` is `fls`.

## Functions on Booleans

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`and = λb. λc. b c fls`

That is, `and` is a function that, given two boolean values `v` and `w`, returns `w` if `v` is `tru` and `fls` if `v` is `fls`

Thus `and v w` yields `tru` if both `v` and `w` are `tru` and `fls` if either `v` or `w` is `fls`.

# Pairs

---

```
pair =  $\lambda f. \lambda s. \lambda b. b f s$   
fst  =  $\lambda p. p \text{ tru}$   
snd  =  $\lambda p. p \text{ fls}$ 
```

That is, `pair v w` is a function that, when applied to a boolean value `b`, applies `b` to `v` and `w`.

By the definition of booleans, this application yields `v` if `b` is `tru` and `w` if `b` is `fls`, so the first and second projection functions `fst` and `snd` can be implemented simply by supplying the appropriate boolean.



## Example

$\text{fst } (\text{pair } v \ w)$   
 $= \text{fst } ((\lambda f. \lambda s. \lambda b. \underline{b \ f \ s}) \ v \ w)$  by definition  
 $\longrightarrow \text{fst } ((\lambda s. \lambda b. \underline{b \ v \ s}) \ w)$  reducing the underlined redex  
 $\longrightarrow \text{fst } (\lambda b. \underline{b \ v \ w})$  reducing the underlined redex  
 $= \underline{(\lambda p. p \ \text{tru})} \ (\lambda b. \underline{b \ v \ w})$  by definition  
 $\longrightarrow \underline{(\lambda b. \underline{b \ v \ w})} \ \text{tru}$  reducing the underlined redex  
 $\longrightarrow \text{tru } v \ w$  reducing the underlined redex  
 $\longrightarrow^* v$  as before.

## Church numerals

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Idea: represent the number  $n$  by a function that “repeats some action  $n$  times.”

$$c_0 = \lambda s. \lambda z. z$$

$$c_1 = \lambda s. \lambda z. s z$$

$$c_2 = \lambda s. \lambda z. s (s z)$$

$$c_3 = \lambda s. \lambda z. s (s (s z))$$

That is, each number  $n$  is represented by a term  $c_n$  that takes two arguments,  $s$  and  $z$  (for “successor” and “zero”), and applies  $s$ ,  $n$  times, to  $z$ .

# Functions on Church Numerals

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Multiplication:

$$\text{times} = \lambda m. \lambda n. m (\text{plus } n) c_0$$



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Zero test:

# Functions on Church Numerals

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```
scc = λn. λs. λz. s (n s z)
```

Addition:

```
plus = λm. λn. λs. λz. m s (n s z)
```

Multiplication:

```
times = λm. λn. m (plus n) c0
```

Zero test:

```
iszro = λm. m (λx. fls) tru
```

# Functions on Church Numerals

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Successor:

$$\text{scc} = \lambda n. \lambda s. \lambda z. s (n s z)$$

Addition:

$$\text{plus} = \lambda m. \lambda n. \lambda s. \lambda z. m s (n s z)$$

Multiplication:

$$\text{times} = \lambda m. \lambda n. m (\text{plus } n) c_0$$

Zero test:

$$\text{iszro} = \lambda m. m (\lambda x. \text{fls}) \text{tru}$$

What about predecessor?

# Predecessor

---

```
zz = pair c0 c0
```

```
ss = λp. pair (snd p) (scc (snd p))
```

# Predecessor

---

```
zz = pair c0 c0
```

```
ss = λp. pair (snd p) (scc (snd p))
```

```
prd = λm. fst (m ss zz)
```

## Normal forms

---

A **normal form** is a term that cannot take an evaluation step.

A **stuck** term is a normal form that is not a value.

Are there any stuck terms in the pure  $\lambda$ -calculus?

Prove it.

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Are there any stuck terms in the pure  $\lambda$ -calculus?

Prove it.

Does every term evaluate to a normal form?

Prove it.

# Divergence

---

$\text{omega} = (\lambda x. x x) (\lambda x. x x)$

Note that `omega` evaluates in one step to itself!

So evaluation of `omega` never reaches a normal form: it **diverges**.



# Divergence

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Note that `omega` evaluates in one step to itself!

So evaluation of `omega` never reaches a normal form: it **diverges**.

Being able to write a divergent computation does not seem very useful in itself. However, there are variants of `omega` that are **very** useful...

## Iterated Application

---

Suppose  $f$  is some  $\lambda$ -abstraction, and consider the following term:

$$Y_f = (\lambda x. f (x x)) (\lambda x. f (x x))$$

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Now the “pattern of divergence” becomes more interesting:

$$\begin{aligned} Y_f &= \\ & \underline{(\lambda x. f (x x)) (\lambda x. f (x x))} \\ & \longrightarrow \\ & f \left( \underline{(\lambda x. f (x x)) (\lambda x. f (x x))} \right) \\ & \longrightarrow \\ & f \left( f \left( \underline{(\lambda x. f (x x)) (\lambda x. f (x x))} \right) \right) \\ & \longrightarrow \\ & f \left( f \left( f \left( \underline{(\lambda x. f (x x)) (\lambda x. f (x x))} \right) \right) \right) \\ & \longrightarrow \\ & \dots \end{aligned}$$

$Y_f$  is still not very useful, since (like  $\omega$ ), all it does is diverge.

Is there any way we could “slow it down”?

## Delaying Divergence

`poisonpill = λy. omega`

Note that `poisonpill` is a value — it will only diverge when we actually apply it to an argument. This means that we can safely pass it as an argument to other functions, return it as a result from functions, etc.

`(λp. fst (pair p fls) tru) poisonpill`  
→  
`fst (pair poisonpill fls) tru`  
→\*  
`poisonpill tru`  
→  
`omega`  
→  
...

## A delayed variant of omega

Here is a variant of `omega` in which the delay and divergence are a bit more tightly intertwined:

$$\text{omegav} = \lambda y. (\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) y$$

Note that `omegav` is a normal form. However, if we apply it to any argument `v`, it diverges:

$$\begin{aligned} & \text{omegav } v \\ & = \\ & \underline{(\lambda y. (\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) y) v} \\ & \longrightarrow \\ & \underline{(\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) v} \\ & \longrightarrow \\ & (\lambda y. (\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) y) v \\ & = \\ & \text{omegav } v \end{aligned}$$

## Another delayed variant

---

Suppose  $f$  is a function. Define

$$Z_f = \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y$$

This term combines the “added  $f$ ” from  $Y_f$  with the “delayed divergence” of  $\text{omegav}$ .

If we now apply  $Z_f$  to an argument  $v$ , something interesting happens:

$$\begin{aligned} & Z_f \ v \\ & = \\ & \underline{(\lambda y. (\lambda x. f (\lambda y. x \ x \ y)) (\lambda x. f (\lambda y. x \ x \ y)) \ y) \ v} \\ & \longrightarrow \\ & \underline{(\lambda x. f (\lambda y. x \ x \ y)) (\lambda x. f (\lambda y. x \ x \ y)) \ v} \\ & \longrightarrow \\ & f (\lambda y. (\lambda x. f (\lambda y. x \ x \ y)) (\lambda x. f (\lambda y. x \ x \ y)) \ y) \ v \\ & = \\ & f \ Z_f \ v \end{aligned}$$

Since  $Z_f$  and  $v$  are both values, the next computation step will be the reduction of  $f \ Z_f$  — that is, before we “diverge,”  $f$  gets to do some computation.

Now we are getting somewhere.



# Recursion

---

Let

```
f = λfct.  
    λn.  
    if n=0 then 1  
    else n * (fct (pred n))
```

`f` looks just the ordinary factorial function, except that, in place of a recursive call in the last time, it calls the function `fct`, which is passed as a parameter.

N.b.: for brevity, this example uses “real” numbers and booleans, infix syntax, etc...

We can use `Z` to “tie the knot” in the definition of `f` and obtain a real recursive factorial function:

$$\begin{aligned}
 & Z_f \ 3 \\
 & \longrightarrow^* \\
 & f \ Z_f \ 3 \\
 & = \\
 & (\lambda f \text{ct. } \lambda n. \dots) \ Z_f \ 3 \\
 & \longrightarrow \longrightarrow \\
 & \text{if } 3=0 \text{ then } 1 \text{ else } 3 * (Z_f \ (\text{pred } 3)) \\
 & \longrightarrow^* \\
 & 3 * (Z_f \ (\text{pred } 3)) \\
 & \longrightarrow \\
 & 3 * (Z_f \ 2) \\
 & \longrightarrow^* \\
 & 3 * (f \ Z_f \ 2) \\
 & \dots
 \end{aligned}$$

## A Generic Z

---

If we define

$$Z = \lambda f. Z_f$$

i.e.,

$$Z = \lambda f. \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y$$

then we can obtain the behavior of  $Z_f$  for any  $f$  we like, simply by applying  $Z$  to  $f$ .

$$Z f \longrightarrow Z_f$$

N.b.:

The term  $Z$  here is essentially the same as the `fix` discussed in the book.

$$Z = \lambda f. \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y$$
$$\text{fix} = \lambda f. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y))$$

$Z$  is hopefully slightly easier to understand, since it has the property that  $Z f v \rightarrow^* f (Z f) v$ , which `fix` does not (quite) share.