



### Motivation

Most programming languages provide some mechanism for interrupting the normal flow of control in a program to signal some exceptional condition.

Note that it is always possible to program without exceptions instead of raising an exception, we return None; instead of returning result x normally, we return  $\exists(x)$ . But now we need to wrap every function application in a case to find out whether it returned a result or an exception.

 $\longrightarrow$  much more convenient to build this mechanism into the language.

### Varieties of non-local control

There are many ways of adding "non-local control flow"

- ♦ exit(1)
- ♦ goto
- setjmp/longjmp
- \* raise/try (or catch/throw) in many variations
- callcc / continuations
- more esoteric variants (cf. many Scheme papers)

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Let's begin with the simplest of these.





# Aside: Syntax-directedness

Note that this rule

```
\Gamma \vdash \text{error} : T (T-ERROR)
```

has a problem from the point of view of implementation: it is not syntax-directed!

This will cause the Uniqueness of Types theorem to fail.

For purposes of defining the language and proving its type safety, this is not a problem — Uniqueness of Types is not critical.

Let's think a little, though, about how the rule might be fixed...

### An alternative

Can't we just decorate the error keyword with its intended type, as we have done to fix related problems with other constructs?

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No, this doesn't work!

E.g. (assuming our language also has numbers and booleans):

succ (if (error as Bool) then 5 else 7)  $\rightarrow$  succ (error as Bool)

Exercise: Come up with a similar example using just functions and error.

#### Another alternative

In a system with universal polymorphism (like OCaml), the variability of typing for error can be dealt with by assigning it a variable type!

```
\Gamma \vdash error : 'a
```

In effect, we are replacing the uniqueness of typing property by a weaker (but still useful) property called most general typing.

I.e., although a term may have many types, we always have a compact way of representing the set of all of its possible types.

(T-ERROR)

#### Yet another alternative

Alternatively, in a system with subtyping (which we'll discuss in the next lecture) and a minimal Bot type, we can give error a unique type:

 $\Gamma \vdash \text{error} : Bot$ 

(T-ERROR)

(Of course, what we've really done is just pushed the complexity of the old error rule onto the Bot type! We'll return to this point later.)



# Type safety

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Progress, though, requires a litte more care.

### Progress

First, note that we do not want to extend the set of values to include error, since this would make our new rule for propagating errors through applications.

 $v_1 \text{ error} \longrightarrow \text{error}$ 

overlap with our existing computation rule for applications:

$$(\lambda x:T_{11}.t_{12}) v_2 \longrightarrow [x \mapsto v_2]t_{12}$$
 (E-APPABS)

e.g., the term

 $(\lambda x: Nat.0)$  error

could evaluate to either 0 (which would be wrong) or error (which is what we intend).

(E-AppErr2)

### Progress

Instead, we keep error as a non-value normal form, and refine the statement of progress to explicitly mention the possibility that terms may evaluate to error instead of to a value.

THEOREM [PROGRESS]: Suppose t is a closed, well-typed normal form. Then either t is a value or t = error.







