## CIS 500 - Software Foundations

Final Exam (and WPE-I exam)
Answer key
November 13, 2002

## Inductive definitions

1. (20 points) Suppose we define a set of expressions called widgets as follows. (We'll use the metavariables $\mathrm{X}, \mathrm{Y}, \mathrm{A}, \mathrm{B}$, and C to range over widgets.)

$$
\begin{aligned}
\mathrm{X}::= & X \otimes X \\
& X \square X \\
& \star
\end{aligned}
$$

We can express the syntax of widgets equivalently in OCaml, as follows:

```
type widget = Cross of widget * widget
    | Box of widget * widget
    | Star
```

The following OCaml function computes a relation on widgets, written $X \multimap Y$ in mathematical notation and 1olli widX widY in ascii. (Note: don't waste time figuring out what the $\circ$ relation "means": it was invented just for the exam and is not intended to correspond to anything computationally natural.)

```
let rec lolli widX widY =
    widX = widY ||
    match (widX, widY) with
            (Cross(widA, widB), Cross(widC, widD)) ->
                (lol1i widA widC) || (lolli widB widD)
        | (Box(widA, Star), Star) }
            lolli widA Star
        | (Box(widA, Cross(widB, widC)), _) ->
                1olli (Cross(widA, widY)) (Box(widC, widB))
            | (_, Box(widB, widC)) -
                (lolli widB Star) && (lolli widC widX)
        | (_,_) ->
            fa1se
```

Recall that the OCaml operator \&\& is "boolean and" and || is "or."
Give a set of inference rules for the $\rightarrow$ relation corresponding to the given OCaml implementation-i.e., such that $X \multimap Y$ iff evaluating 1o11i widX widY in OCaml yields true (where widX is an OCaml value of type widget representing the mathematical widget $X$ and similarly widY represents $Y$ ). One of the required rules is given as an example; you write the rest.

$$
\frac{A \multimap \star}{A \square \star \multimap \star}
$$

Answer:

$$
\begin{gathered}
A \multimap A \\
A \multimap C \\
\hline A \otimes B \multimap C \otimes D \\
B \multimap D \\
\hline A \otimes B \multimap C \otimes D \\
A \otimes Y \multimap C \square B \\
\hline A \square(B \otimes C) \multimap Y \\
B \multimap \star \quad C \multimap X \\
\hline X \multimap B \square C
\end{gathered}
$$

Grading scheme:

- 0 points for omitted rule
- 4 points for each rule with the following deductions:
- -2 for each upside-down rule
- -2 for wild card or blank where meta variable should be
- -1 for incorrect variable other than wild card
- No deductions were made for the following
- full credit (8/8) for folding to "or" rules together into 1 rule with an "or" separating the premises
- attempting a rule for the last case in the OCaml match
- No deduction for minor, but clear, notational deviations, including a different arrow character or a blank, or ordered pair notation instead of lollipop arrow
- no deduction for omitting parens from 4th rule in key (a surprisingly rare error!)


## Untyped lambda-calculus

2. Recall that the Church encoding of the natural numbers in untyped lambda-calculus represents a number $n$ as a function that applies a given "successor operation" $n$ times to a given "starting value."
Church numerals:
```
0 = \lambdas. \lambdaz. z
1 = \lambdas. \lambdaz. (s z)
2 = \lambdas. \lambdaz. s (s z)
3 = \lambdas. \lambdaz. s (s (s z))
```

In this problem, we explore a different encoding of natural numbers based on their binary representation. Example encodings in this new system are:

Binary numerals:

```
0 = \lambdaone. \lambdazero. \lambdat. zero t
1 = \lambdaone. \lambdazero. \lambdat. one t
2 = \lambdaone. \lambdazero. \lambdat. one (zero t)
3 = \lambdaone. \lambdazero. \lambdat. one (one t)
4 = \lambdaone. \lambdazero. \lambdat. one (zero (zero t))
5 = \lambdaone. \lambdazero. \lambdat. one (zero (one t))
```

As in the standard Church encoding, numbers are represented as functions that can be used to "count." However, rather then applying a single given function $n$ times to a starting value, the binary encoding is supplied with two functions plus a starting value. It applies its one argument to the starting value if the lowest-order bit of the binary representation of $n$ is 1 ; otherwise (if the lowest order bit is 0 ) it applies its zero argument. To the result, it applies one if the next lowest bit in the binary representation of $n$ is 1 , otherwise zero; and so on up to the highest-order bit.

Note that, leading zeros are considered insignificant in this encoding-i.e., both

```
fn one. fn zero. fn t. zero (one t)
```

and
fn one. fn zero. fn $t$. one $t$
are valid encodings of the number 1. (This implies that the function passed for the zero argument should "have no effect" if it is the last one to be applied.)
(a) (7 points) Write a function that multiplies a number in the binary encoding by 2. (Hint: in base 2, a multiplication by 2 is just a one-bit shift.)
Answer: $\lambda \mathrm{n}$. $\lambda$ one. $\lambda$ zero. $\lambda \mathrm{t}$. n one zero (zero t)

## Grading scheme:

- 2 points for correct args./shape of the function
- 3 points for using the term (zero t) in roughly the correct way
- 2 points for having everything else right
(b) (7 points) Recall that we can encode Boolean values in the untyped lambda calculus as follows:

```
tru = \lambdat. \lambdaf. t
fls = \lambdat. \lambdaf. f
```

Write a function that returns tru when given the binary encoding of 0 and fl s if given the encoding of any non-zero number.
Answer: $\lambda \mathrm{n}$. $\mathrm{n}(\lambda \mathrm{x} . \mathrm{fls})(\lambda \mathrm{y} . \mathrm{y})$ tru
Grading scheme:

- 2 points for correct args./shape of the function
- 1 point for replacing 'one' by something like " $\lambda x$. f7s"
- 1 point for replacing 'zero' by something like " $\lambda x$. $x$ "
- 1 point for replacing ' $t$ ' by something like "tru"
- 2 points for everything else right extra points for being close


## Simply typed lambda-calculus

The definition of the simply typed lambda-calculus is reproduced on pages 15 to 17 .
3. (4 points)

For each of the following types, write a closed lambda-term that has that type and that contains at least one application. For example, for the type ( $\mathrm{Nat} \rightarrow \mathrm{Nat}$ ) $\rightarrow \mathrm{Nat}$, the following is a correct answer:

```
\lambdaf:Nat->Nat. f 1
```

On the other hand,

```
\lambdaf:Nat->Nat. 1
```

is not an acceptable answer (even though it has the correct type) because it does not contain an application.
(a) $($ (Nat $\rightarrow$ Unit $) \rightarrow \mathrm{Nat}) \rightarrow \mathrm{Nat}$

Answer: $\lambda \mathrm{f}:($ Nat $\rightarrow$ Unit) $\rightarrow$ Nat. $f(\lambda x: N a t . u n i t)$
(b) (Unit $\rightarrow$ Nat) $\rightarrow($ (Unit $\rightarrow$ Nat) $\rightarrow$ Nat) $\rightarrow$ Nat Answer: $\lambda f$ :Unit $\rightarrow$ Nat. $\lambda g:($ Unit $\rightarrow$ Nat) $\rightarrow$ Nat. $g f$

Grading scheme: Two points for each part.

## Subtyping

4. (20 points) In this question, you will be asked to fill in a proof of the preservation theorem for the simply typed lambda calculus with records and subtyping. The theorem is identical to the one in Chapter 15 of TAPL, but for the sake of variety we'll do proof by induction on evaluation derivations (in TAPL it went by induction on typing derivations).
The following two lemmas will be used in the proof. (Note that the first four cases of the first lemma list inversion properties of the typing relation, while the last case concerns the subtype relation.)
LEmMA [INVERSION]:
(a) If $\Gamma \vdash\left\{\mathrm{k}_{i}=\mathrm{s}_{i}{ }^{i \in 1 . . m}\right\}: T$, then there are types $\mathrm{T}_{1}$ to $\mathrm{T}_{m}$ such that $\Gamma \vdash \mathrm{s}_{i}: \mathrm{T}_{i}$ for each $i$ and such that $\left\{\mathrm{k}_{i}: \mathrm{T}_{i}{ }^{i \in 1 . m}\right\}<$ : T .
(b) If $\Gamma \vdash \mathrm{t} .1: T$, then $\Gamma \vdash \mathrm{t}:\{1: T\}$.
(c) If $\Gamma \vdash \mathrm{t}_{1} \mathrm{t}_{2}: \mathrm{T}$ then $\Gamma \vdash \mathrm{t}_{1}: \mathrm{T}^{\prime} \rightarrow \mathrm{T}$ and $\Gamma \vdash \mathrm{t}_{2}: \mathrm{T}^{\prime}$.
(d) If $\Gamma \vdash \lambda x: S_{1} . s_{2}: T_{1} \rightarrow T_{2}$, then $T_{1}<: S_{1}$ and $\Gamma, x: S_{1} \vdash \mathrm{~s}_{2}: \mathrm{T}_{2}$.
(e) If $\mathrm{S}<$ : $\left\{\mathrm{T}_{j}: \mathrm{T}_{j}{ }^{i \in 1 . . m}\right\}$, then $\mathrm{S}=\left\{\mathrm{k}_{i}: \mathrm{S}_{i}{ }^{i \in 1 . . n}\right\}$, where $\left\{\mathrm{T}_{j}{ }^{i \in 1 . . m}\right\} \subseteq\left\{\mathrm{k}_{i}^{i \in 1 . . n}\right\}$ and $\mathrm{S}_{i}<: \mathrm{T}_{j}$ for each common label $\mathrm{k}_{i}=1_{j}$.

Lemma [SUBSTITUTION]: If $\Gamma, \mathrm{x}: \mathrm{S} \vdash \mathrm{t}: \mathrm{T}$ and $\Gamma \vdash \mathrm{s}: \mathrm{S}$, then $\Gamma \vdash[\mathrm{x} \mapsto \mathrm{s}] \mathrm{t}: \mathrm{T}$.
For each case in the proof on the next page, write down the skeleton of the argument. A skeleton contains the same sequence of steps as the full argument, but omits all details. The rules for writing skeletons are as follows:

- Steps of the form "By part (x) of the inversion lemma, we obtain..." in the full argument become "inversion(x)" in the skeleton.
- Steps of the form "By the substitution lemma, we obtain..." become "substitution."
- Steps of the form "By the induction hypothesis, we obtain..." become "IH."
- Steps of the form "By typing rule T-XXX, we obtain..." become "T-XXX."
- If the full argument doesn't use any of the lemmas or the induction hypothesis, then its skeleton is "Direct."

For example, if the full argument is
Case E-APP1: $\quad \mathrm{t}=\mathrm{t}_{1} \mathrm{t}_{2} \quad \mathrm{t}^{\prime}=\mathrm{t}_{1}^{\prime} \mathrm{t}_{2} \quad \mathrm{t}_{1} \longrightarrow \mathrm{t}_{1}^{\prime}$
By part (c) of the inversion lemma, we obtain $\Gamma \vdash \mathrm{t}_{1}: \mathrm{T}^{\prime} \rightarrow \mathrm{T}$ and $\Gamma \vdash \mathrm{t}_{2}: \mathrm{T}^{\prime}$. By the induction hypothesis, we obtain $\Gamma \vdash \mathrm{t}_{1}^{\prime}: \mathrm{T}^{\prime} \rightarrow \mathrm{T}$. The required result $\left(\Gamma \vdash \mathrm{t}_{1}^{\prime} \mathrm{t}_{2}: \mathrm{T}\right.$ ) now follows by T-App.
the skeleton is written:
Case E-APP1: $\quad \mathrm{t}=\mathrm{t}_{1} \mathrm{t}_{2} \quad \mathrm{t}^{\prime}=\mathrm{t}_{1}^{\prime} \mathrm{t}_{2} \quad \mathrm{t}_{1} \longrightarrow \mathrm{t}_{1}^{\prime}$
Inversion(c), IH, T-APp.

Theorem [Preservation]: If $\mathrm{t} \longrightarrow \mathrm{t}^{\prime}$ and $\Gamma \vdash \mathrm{t}: \mathrm{T}$, then $\Gamma \vdash \mathrm{t}^{\prime}: \mathrm{T}$.
Proof: By induction on evaluation derivations, with a case analysis on the final rule used.
Case E-Appı: $\quad \mathrm{t}=\mathrm{t}_{1} \mathrm{t}_{2} \quad \mathrm{t}^{\prime}=\mathrm{t}_{1}^{\prime} \mathrm{t}_{2} \quad \mathrm{t}_{1} \longrightarrow \mathrm{t}_{1}^{\prime}$
Inversion(c), IH, T-APP.
Case E-App2: $\quad \mathrm{t}=\mathrm{v}_{1} \mathrm{t}_{2} \quad \mathrm{t}^{\prime}=\mathrm{v}_{1} \mathrm{t}_{2}^{\prime} \quad \mathrm{t}_{2} \longrightarrow \mathrm{t}_{2}^{\prime}$
Answer: Inversion(c), IH, T-APP.
Case E-AppABs: $\quad \mathrm{t}=\left(\lambda \mathrm{x}: \mathrm{T}_{11} . \mathrm{t}_{12}\right) \mathrm{v}_{2} \quad \mathrm{t}^{\prime}=\left[\mathrm{x} \mapsto \mathrm{v}_{2}\right] \mathrm{t}_{12}$
Answer: Inversion(c), inversion(d), T-SuB, substitution.

$$
\begin{array}{ll}
\text { Case E-RCD: } & \mathrm{t}=\left\{7_{i}=\mathrm{V}_{i} i \in 1 . . j-1\right. \\
& \mathrm{t}_{j}=\mathrm{t}_{j}, 1_{k}=\mathrm{t}_{k}=\left\{\mathrm{1}_{i}=\mathrm{V}_{i}{ }^{i \in 1 . . j-j+1+. . n},\right. \\
& \left.\mathrm{1}_{j}=\mathrm{t}_{j}^{\prime}, 1_{k}=\mathrm{t}_{k}{ }^{k \in j+1 . n}\right\} \\
& \mathrm{t}_{j} \rightarrow \mathrm{t}_{j}^{\prime}
\end{array}
$$

Answer: Inversion(a), IH, T-RCD, T-SuB.
Case E-PROJ: $\quad \mathrm{t}=\mathrm{t}_{1} .1 \quad \mathrm{t}^{\prime}=\mathrm{t}_{1}^{\prime} .1 \quad \mathrm{t}_{1} \rightarrow \mathrm{t}_{1}^{\prime}$
Answer: Inversion(b), IH, T-PROJ.
Case E-ProjRcD: $\quad \mathrm{t}=\left\{\mathrm{1}_{i}=\mathrm{V}_{i}{ }^{i \in 1 . n}\right\} . \mathrm{1}_{j} \quad \mathrm{t}^{\prime}=\mathrm{v}_{j}$
Answer: Inversion(b), inversion(a), inversion(e), T-SUB.
Grading scheme: 4 points per case. -2 for missing or extra IH. -1 for missing rule. -1 for extraneous rule. Exceptions: instead of counting off 2 points for a wrong but similar rule (i.e. the right rule is missing and the wrong rule extraneous) only deducted 1 point. Also, only 1 point deducted for rules in transposed order.
5. (3 points) Suppose we changed part (a) of the inversion lemma in problem 4 to match the one given in chapter 15 of TAPL:

If $\Gamma \vdash\left\{\mathrm{k}_{a}=\mathrm{S}_{a}{ }^{a \in 1 . . m}\right\}:\left\{7_{i}: \mathrm{T}_{i}{ }^{i \in 1 . . n}\right\}$, then $\left\{1_{i}{ }^{i \in 1 . n}\right\} \subseteq\left\{\mathrm{k}_{a}{ }^{a \in 1 . . m}\right\}$ and $\Gamma \vdash \mathrm{S}_{a}: \mathrm{T}_{i}$ for each common label $\mathrm{k}_{a}=1_{i}$.

Which step would fail in the above proof of preservation? Briefly explain why.
Answer: The E-RcD case would fail, for several reasons: First of all, the new case (a) of the inversion lemma would not apply at all, because the assumption on $t$ is just that it has some type $T$, not that $T$ has the form of a record type. Even assuming that we could apply the new inversion lemma, we would not get much further since, in order to apply the IH and reconstruct the original type for $t^{\prime}$, we need to have typing derivations for all fields of the record; but this variant of the rule doesn't provide typing derivations for fields that do not appear in $\left\{7_{i}: T_{i} \in 1 . . n\right\}$.

The other cases all still work (including in particular E-PROJRCD).
Grading scheme: 1 point for mentioning E-RCD; 0 points if E-RCD not mentioned. -1 for mentioning cases besides E-RCD. One additional point for an incomplete but not wrong explanation. Full credit for explaining any of the difficulties listed in the sample answer above. (Strictly speaking, only the first difficulty is correct: the new inversion lemma simply cannot be applied. But we still gave full credit to answers that focused on the other difficulties.)
6. (3 points) Another natural-looking variant of part (a) of the inversion lemma is this:

$$
\text { If } \Gamma \vdash\left\{\mathrm{k}_{i}=\mathrm{s}_{i} \in 1 . . n\right\}: \mathrm{T} \text {, then } \mathrm{T}=\left\{\mathrm{k}_{i}: \mathrm{T}_{i}{ }^{i \in 1 . . n}\right\} \text { and } \Gamma \vdash \mathrm{s}_{i}: \mathrm{T}_{i} \text { for each } i \in \text { 1..n. }
$$

Sadly, however, this variant is false.
Briefly explain why.
Answer: Because it claims that any type for a record expression will have the same fields as the record (in the same order); but the subsumption rule allows us to "forget" fields in the type that the expression actually mentions and to permute the order and raise the types of the remaining fields.

Grading scheme: This question was a bit hard to answer because the clear-cut part (the fact that the lemma is problematic because of being false) was already given. Full credit was awarded for any answer that suggested that the possibility of subsumption was not taken into account, or that gave a correct counter-example. 2 points for "sort of correct" but garbled answers. 1 point for very brief or garbled answers that mention the word "subtyping." No points for explaining that the proof of preservation doesn't go through (it does go through, if we assume the lemma is true).

## Subtyping

7. Suppose we add new types A, B, C, D, and E to the simply typed lambda-calculus with subtyping, along with the following subtyping rules:

$$
\begin{aligned}
& \mathrm{A}<: \mathrm{B} \\
& \mathrm{~B}<: \mathrm{C} \\
& \mathrm{D}<: \mathrm{E} \\
& \mathrm{~A}<: \mathrm{E}
\end{aligned}
$$

(a) (6 points) For each type $S$ from the left-hand column and type $T$ from the right-hand column such that $S<$ : $T$, draw a line connecting $S$ to $T$.

## Choices for S:

## Choices for $T$ :

$$
\begin{array}{ll}
S_{1}=\{x: D\} \rightarrow\{y: A\} & T_{1}=E \\
S_{2}=\{y: B\} & T_{2}=\{x: D\} \\
S_{3}=\{x: A, y: A\} & T_{3}=\{x: E\} \\
S_{4}=D & T_{4}=\{ \} \\
S_{5}=\{x: B\} & T_{5}=\{y: E\}
\end{array}
$$

Answer:

- $S_{1}$ not a subtype of any $T_{i}$
- $S_{2}<: T_{4}$
- $S_{3}<: T_{4}, T_{5}$
- $S_{4}<: T_{1}$
- $S_{5}<: T_{4}$

Grading scheme: One point off for each missing line; one point off for each incorrect line.
(b) (6 points) Recall the definitions of joins and meets in the subtype relation:

- A type J is called a join of a pair of types $S$ and $T$ if $S<: J, T<$ : J, and, for all types $U$, if $\mathrm{S}<$ : U and $\mathrm{T}<: \mathrm{U}$, then $\mathrm{J}<: \mathrm{U}$.
- A type $M$ is a meet of $S$ and $T$ if $M<: S, M<$ : $T$, and, for all types $L$, if $L<$ : $S$ and $L<$ : $T$, then L <: M.

Give the join and meet of each pair of types, where they exist (otherwise write "undefined.")
i. $\{x: E, y: C\}$ and $\{x: B, y: B\}$

$$
\text { join }=\{x: \text { Top }, y: C\} \quad \text { meet }=\{x: A, y: B\}
$$

ii. $\{x: B\}$ and $\{y: B\}$

$$
\text { join }=\{ \} \quad \text { meet }=\{x: B, y: B\}
$$

iii. $\{x: A\}$ and $\{x: D\}$

$$
\text { join }=\{x: E\} \quad \text { meet }=\text { undefined }
$$

Grading scheme: 1 point for each exactly correct answer. No partial credit.
(c) (3 points) How does the join of $\{x: A\}$ and $\{x: D\}$ change if we add the rule $D<$ : $B$ to the subtyping judgment?
Answer: It ceases to exist: in the enriched system, the common upper bounds of $\{x: A\}$ and $\{x: D\}$ are $\{x: B\},\{x: C\}$, and $\{x: E\}$; but none of these is a subtype of all the others.

Grading scheme:

- full credit for "becomes undefined"
- no points for giving a join
- 1 point for saying something like "there are 2 possible joins"
- 1/2 points deducted for saying "undefined" plus something incorrect
- full credit for "unchanged" on papers where 7Biii was (incorrectly) marked as undefined
- 1 point for \{\} with a semi-reasonable explanation


## Imperative object encodings

This problem involves an encoding of simple objects in the simply typed lambda-calculus with subtyping, records, references, and fixed points. This calculus is defined for your reference on pages 15 to 21 .
8. (20 points) Consider the five following class definitions, in the style of TAPL Chapter 18:

```
R = {};
O = {m:Unit->Unit, n:Unit->Unit, o:Unit->Unit};
classA = \lambdar:R. \lambdaself: Unit->0. \lambda_:Unit.
    {m = \lambda_:Unit. (self unit).n unit,
    n = \lambda_:Unit. (self unit).m unit,
    o = \lambda_:Unit. unit };
classB = \lambdar:R. \lambdaself: Unit->0. \lambda_:Unit.
    let super = classA r self unit in
    {m = \lambda_:Unit. unit,
    n = super.n,
    o = super.o };
classC = \lambdar:R. \lambdaself: Unit->0. \lambda_:Unit.
    let super = classA r self unit in
    {m = super.m,
        n = \lambda_:Unit. super.n unit,
        o = super.o };
classD = \lambdar:R. \lambdaself: Unit->0. \lambda_:Unit.
        1et super = classA r self unit in
        {m = super.m,
        n = \lambda_:Unit. super.o unit,
        o = super.o };
classE = \lambdar:R. \lambdaself: Unit->0. \lambda_:Unit.
        1et super = classA r self unit in
        {m = (self unit).m,
        n = super.n,
        o = super.o };
```

Each of these classes produces objects with the same type, 0 , which offers three methods. Their state representations are all the trivial record type, $R$. The methods $m, n$, and $o$ all take Unit arguments and return Unit results-that is, the only interesting thing about them is whether they diverge or converge. The class classA is the "root class" from which the other four are derived.

Given these definitions, does evaluation of the following expressions converge (yielding unit) or diverge? For each one, circle the word "converges" or "diverges," as appropriate. Answers boxed below.

| ( (fix (classA \{\})) unit).n unit | converges | diverges |
| :---: | :---: | :---: |
| ( (fix (classA \{\})) unit).ounit | converges | diverges |
| ((fix (classB \{\})) unit).n unit | converges | diverges |
| ((fix (classB \{\}) ) unit).ounit | converges | diverges |
| ((fix (classC \{\})) unit).n unit | converges | diverges |
| ((fix (classC \{\})) unit).ounit | Converges | diverges |
| ((fix (classD \{\}) ) unit).n unit | converges | diverges |
| ( (fix (classD \{\}) ) unit).ounit | converges | diverges |
| ((fix (classE \{\})) unit).n unit | converges | diverges |
| ((fix (classE \{\})) unit).ounit | converges | diverges |

## Featherweight Java

The definition of Featherweight Java is reproduced on pages 22 to 24.
9. (a) (16 points)

Chapter 3 of TAPL introduced an alternative big-step style for presenting evaluation relations, in which each rule shows how to evaluate a term of a particular form "all the way" to a final value, rather than just showing how to make it take a single step. For example, in the lambda-calculus with booleans, the usual small step evaluation rules for if...

$$
\begin{gathered}
\text { if true then } t_{2} \text { else } t_{3} \rightarrow t_{2} \\
\text { if false then } t_{2} \text { else } t_{3} \rightarrow t_{3} \\
t_{1} \rightarrow t_{1}^{\prime} \\
\text { if } t_{1} \text { then } t_{2} \text { else } t_{3} \rightarrow \text { if } t_{1}^{\prime} \text { then } t_{2} \text { else } t_{3}
\end{gathered}
$$

correspond to the following big-step rules:

$$
\begin{gathered}
\frac{t_{1} \Downarrow \text { true }}{\text { if } t_{1} \text { then } t_{2} \text { else } t_{3} \Downarrow v_{2}} \\
\frac{t_{1} \Downarrow \text { false } \quad t_{3} \Downarrow v_{3}}{\text { if } t_{1} \text { then } t_{2} \text { else } t_{3} \Downarrow v_{3}}
\end{gathered}
$$

Write down a big step evaluation relation for Featherweight Java. (You'll need four inference rules.)
Answer:

$$
\begin{gathered}
\frac{\mathrm{t}_{0} \Downarrow \text { new } C(\overline{\mathrm{v}}) \quad \mathrm{C}<: \mathrm{D}}{(\mathrm{D}) \mathrm{t}_{0} \Downarrow \text { new } \mathrm{C}(\overline{\mathrm{v}})} \\
\frac{\mathrm{t}_{0} \Downarrow \text { new } \mathrm{C}(\overline{\mathrm{v}}) \quad \text { fields }(\mathrm{C})=\overline{\mathrm{C}} \overline{\mathrm{f}}}{\mathrm{t}_{0} \cdot \mathrm{f}_{i} \longrightarrow \mathrm{v}_{i}} \\
\frac{\mathrm{t}_{0} \Downarrow \operatorname{new} \mathrm{C}(\overline{\mathrm{v}}) \quad \operatorname{mbody}(\mathrm{m}, \mathrm{C})=(\overline{\mathrm{x}}, \mathrm{~s}) \quad \overline{\mathrm{t}} \Downarrow \overline{\mathrm{u}} \quad[\overline{\mathrm{x}} \mapsto \overline{\mathrm{u}}, \text { this } \mapsto \text { new } C(\overline{\mathrm{v}})] \mathrm{s} \Downarrow v}{\mathrm{t}_{0} \cdot \mathrm{~m}(\overline{\mathrm{t}}) \longrightarrow \mathrm{v}} \\
\frac{\overline{\mathrm{t}} \Downarrow \overline{\mathrm{v}}}{\text { new } \mathrm{C}(\overline{\mathrm{t}}) \Downarrow \text { new } \mathrm{C}(\overline{\mathrm{v}})}
\end{gathered}
$$

Grading scheme:

- 4 points per rule.
- For all rules:
- -2 points for using a value instead of a term on the LHS.
- -4 points for a loop in the operational semantics.
- +/- points for being very close or very wrong.
- Individual rules: Cast:
- -1 for no subtyping constraint.
- -2 for no class mentioned in the new expression.
- -1 for evaluating to wrong type.
- Prj.:
- -2 for no class mentioned in the record evaluation.
- -1 for no constraint that project field exists
- -3 for not projecting from the record
- Meth:
- -2 for no substitution at all
- -3 for substitution in the conclusion
(b) (5 points) State the preservation theorem for the big-step variant of FJ.

Answer: If $\Gamma \vdash t: C$ and $t \Downarrow v$, then $\Gamma \vdash v: D$ for some $D<: C$.
Grading scheme:

- No deduction for omitting $\Gamma$
- Either v or new C(v) accepted for the value
- -2 for omitting $t \Downarrow v$
- -3 for neglecting the fact that the new type can be a subtype of old type
- hand-wavy english, correct but too vague $=1 / 5$
- weird stuff that looks a tiny bit right $=1 / 5$


## For reference: Simply typed lambda calculus with records (and Nat, Bool, and Unit)

```
Syntax
    t ::=
    unit
    {1 i= til i\inl.n }
    t. }
    x
    \lambdax:T.t
    t t
        true
    false
    ift then telset
        0
    succ t
    pred t
    iszero t
    v ::=
        unit
    {7 (=\mp@subsup{V}{i}{i\inl..n}}
    \lambdax:T.t
    true
    false
    nv
T ::=
Unit
    {7 i:T Ti\inl..n}
    Boo1
    Nat
    T->T
\Gamma ::=
\varnothing
    \Gamma,x:T
nv ::=
0
    succ nv
terms
    constant unit
    record
    projection
    variable
    abstraction
    application
    constant true
    constant false
    conditional
    constant zero
    successor
    predecessor
    zero test
values
    constant unit
    record value
    abstraction value
    true value
    false value
    numeric value
types
    unit type
    type of records
    type of booleans
    type of natural numbers
    type of functions
contexts
    empty context
    term variable binding
numeric values
    zero value
    successor value
```

$$
\begin{align*}
& \left\{7_{i}=\mathrm{V}_{i}{ }^{i \in 1 . . n}\right\} .1_{j} \longrightarrow \mathrm{v}_{j} \\
& \frac{t_{1} \rightarrow t_{1}^{\prime}}{t_{1} .1 \rightarrow t_{1}^{\prime} .1} \\
& \frac{\mathrm{t}_{j} \rightarrow \mathrm{t}_{j}^{\prime}}{\left\{1_{i}=\mathrm{v}_{i}{ }^{i \in 1 . . j-1}, 1_{j}=\mathrm{t}_{j}, 1_{k}=\mathrm{t}_{k}{ }^{k \in j+1 . n}\right\}} \\
& \longrightarrow\left\{\mathrm{1}_{i}=\mathrm{V}_{i}{ }^{i \in 1 . . j-1}, \mathrm{1}_{j}=\mathrm{t}_{j}^{\prime}, \mathrm{1}_{k}=\mathrm{t}_{k}{ }^{k \in j+1 . n}\right\} \\
& \frac{t_{1} \rightarrow t_{1}^{\prime}}{t_{1} t_{2} \rightarrow t_{1}^{\prime} t_{2}} \\
& \frac{t_{2} \rightarrow t_{2}^{\prime}}{v_{1} t_{2} \longrightarrow v_{1} t_{2}^{\prime}} \\
& \left(\lambda x: T_{11} \cdot t_{12}\right) v_{2} \rightarrow\left[x \mapsto v_{2}\right] t_{12} \\
& \text { if true then } t_{2} e 1 s e t_{3} \rightarrow t_{2} \\
& \text { if false then } \mathrm{t}_{2} \mathrm{e} 1 \mathrm{se} \mathrm{t}_{3} \rightarrow \mathrm{t}_{3} \\
& \frac{t_{1} \rightarrow t_{1}^{\prime}}{\text { if } t_{1} \text { then } t_{2} \text { else } t_{3} \rightarrow \text { if } t_{1}^{\prime} \text { then } t_{2} \text { e1se } t_{3}} \\
& \frac{t_{1} \rightarrow t_{1}^{\prime}}{\text { succ } \mathrm{t}_{1} \rightarrow \operatorname{succ} \mathrm{t}_{1}^{\prime}} \\
& \text { pred } 0 \rightarrow 0 \\
& \text { pred (succ } \left.n v_{1}\right) \longrightarrow \mathrm{nv}_{1} \\
& \frac{t_{1} \rightarrow t_{1}^{\prime}}{\text { pred } t_{1} \longrightarrow \text { pred }_{1}^{\prime}} \\
& \text { iszero } 0 \rightarrow \text { true } \\
& \text { iszero (succ } n v_{1} \text { ) } \rightarrow \text { false } \\
& \frac{t_{1} \rightarrow t_{1}^{\prime}}{\text { iszero } t_{1} \rightarrow \text { iszero } t_{1}^{\prime}} \\
& \Gamma \vdash \mathrm{t}: \mathrm{T} \\
& \text { (T-UnIT) } \\
& \text { (T-RCD) } \\
& \text { (T-PROJ) } \\
& \text { (T-TruE) } \\
& \text { (T-FALSE) } \\
& \text { (T-Zero) } \tag{T-IF}
\end{align*}
$$

Typing

$$
\begin{array}{cc}
\frac{\Gamma \vdash \mathrm{t}_{1}: \mathrm{Nat}}{\Gamma \vdash \mathrm{succ} \mathrm{t}_{1}: \mathrm{Nat}} \\
\frac{\Gamma \vdash \mathrm{t}_{1}: \mathrm{Nat}}{\Gamma \vdash \mathrm{pred} \mathrm{t}_{1}: \mathrm{Nat}} \\
\frac{\Gamma \vdash \mathrm{t}_{1}: \mathrm{Nat}}{\Gamma \vdash \mathrm{iszero} \mathrm{t}_{1}: \mathrm{Boo} 1} \\
\frac{\mathrm{x}: \mathrm{T} \in \Gamma}{\Gamma \vdash \mathrm{x}: \mathrm{T}}  \tag{T-Pred}\\
\frac{\Gamma, \mathrm{x}: \mathrm{T}_{1} \vdash \mathrm{t}_{2}: \mathrm{T}_{2}}{\Gamma \vdash \lambda \mathrm{x}: \mathrm{T}_{1} \cdot \mathrm{t}_{2}: \mathrm{T}_{1} \rightarrow \mathrm{~T}_{2}} \\
\frac{\Gamma \vdash \mathrm{t}_{1}: \mathrm{T}_{11} \rightarrow \mathrm{~T}_{12}}{\Gamma \vdash \mathrm{t}_{2}: \mathrm{T}_{11}} \\
\hline \vdash \vdash \mathrm{t}_{1} \mathrm{t}_{2}: \mathrm{T}_{12} & \text { (T-ISRED) } \\
\text { (T-VAR) } \\
\text { (T-ABS) } \\
\hline
\end{array}
$$

## For reference: Subtyping

New syntactic forms

T ::= ... Top
types
maximum type

New subtyping rules
$\mathrm{S}<\mathrm{Z}$ T
$\mathrm{S}<: \mathrm{S}$
$\frac{\mathrm{S}<: \mathrm{U} \quad \mathrm{U}<: \mathrm{T}}{\mathrm{S}<: \mathrm{T}}$
S<: Top
(S-TOP)
(S-ARROW)
(S-RcDWIDTH)
(S-RCDDEPTH)
$\frac{\left\{\mathrm{k}_{j}: \mathrm{S}_{j}{ }^{j \in 1 . . n}\right\} \text { is a permutation of }\left\{\mathrm{T}_{i}: \mathrm{T}_{i}{ }^{i \in 1 . . n}\right\}}{\left\{\mathrm{k}_{j}: \mathrm{S}_{j}{ }^{j \in 1 . . n}\right\}<:\left\{\mathrm{T}_{i}: \mathrm{T}_{i}{ }^{i \in 1 . . n}\right\}}$
New typing rules
$\Gamma \vdash \mathrm{t}: \mathrm{T}$

$$
\frac{\Gamma \vdash \mathrm{t}: \mathrm{S} \quad \mathrm{~S}<: \mathrm{T}}{\Gamma \vdash \mathrm{t}: \mathrm{T}}
$$

## For reference: References, Fix, and let

New syntactic forms

| $\mathrm{t}::=$ | ... | terms |
| :---: | :---: | :---: |
|  | reft | reference creation |
|  | ! t | dereference |
|  | t : = t | assignment |
|  | 1 | store location |
|  | 1et $x=t$ in $t$ | let binding |
|  | fixt | fixed point of $t$ |
| v ::= | ... | values |
|  | $l$ | store location |
| T : $=$ |  | types |
|  | Ref T | type of reference cells |
| $\mu \quad:=$ | $\cdots$ | stores |
|  | $\varnothing$ | empty store |
|  | $\mu, l=\mathrm{v}$ | location binding |
| $\Sigma::=$ | $\ldots$ | store typings |
|  | $\varnothing$ | empty store typing |
|  | v,l:T | location typing |

New evaluation rules
terms
reference creation dereference assignment store location let binding fixed point of $t$
values store location

## types

stores
empty store
location binding
store typings empty store typing location typing
$\mathrm{t}\left|\mu \longrightarrow \mathrm{t}^{\prime}\right| \mu^{\prime}$

$$
\mathrm{t}\left|\mu \rightarrow \mathrm{t}^{\prime}\right| \mu^{\prime}
$$

$$
\begin{aligned}
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\mathrm{t}_{1} \mathrm{t}_{2}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime} \mathrm{t}_{2}\right| \mu^{\prime}} \\
& \frac{\mathrm{t}_{2}\left|\mu \rightarrow \mathrm{t}_{2}^{\prime}\right| \mu^{\prime}}{\mathrm{v}_{1} \mathrm{t}_{2}\left|\mu \longrightarrow \mathrm{v}_{1} \mathrm{t}_{2}^{\prime}\right| \mu^{\prime}} \\
& \left(\lambda \mathrm{x}: \mathrm{T}_{11} \cdot \mathrm{t}_{12}\right) \mathrm{v}_{2}\left|\mu \rightarrow\left[\mathrm{x} \mapsto \mathrm{v}_{2}\right] \mathrm{t}_{12}\right| \mu \\
& \left\{7_{i}=\mathrm{V}_{i}{ }^{i \in 1 . . n}\right\} .7_{j}\left|\mu \longrightarrow \mathrm{v}_{j}\right| \mu \\
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\mathrm{t}_{1} .1\left|\mu \rightarrow \mathrm{t}_{1}^{\prime} .1\right| \mu^{\prime}}
\end{aligned}
$$

$$
\begin{aligned}
& \longrightarrow\left\{1_{i}=\mathrm{V}_{i}{ }^{i \in 1 . . j-1}, 1_{j}=\mathrm{t}_{j}^{\prime}, 1_{k}=\mathrm{t}_{k}{ }^{k \in j+1 . n}\right\} \mid \mu^{\prime} \\
& \frac{l \notin \operatorname{dom}(\mu)}{\text { ref } \mathrm{v}_{1}|\mu \longrightarrow l|\left(\mu, l \mapsto \mathrm{v}_{1}\right)} \\
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\operatorname{ref} \mathrm{t}_{1}\left|\mu \rightarrow \operatorname{ref}^{\prime} \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}} \\
& \begin{array}{c}
\mu(l)=\mathrm{v} \\
!l|\mu \longrightarrow \mathrm{v}| \mu
\end{array}
\end{aligned}
$$

(E-APP2)
(E-APPABS)
(E-PROJRCD)
(E-PROJ)
(E-RCD)
(E-REFV)
(E-REF)
(E-DEREFLOC)

$$
\begin{align*}
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{!\mathrm{t}_{1}\left|\mu \rightarrow!\mathrm{t}_{1}^{\prime}\right| \mu^{\prime}} \\
& l:=\mathrm{v}_{2} \mid \mu \rightarrow \text { unit } \mid\left[l \mapsto \mathrm{v}_{2}\right] \mu \\
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\mathrm{t}_{1}:=\mathrm{t}_{2}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}:=\mathrm{t}_{2}\right| \mu^{\prime}} \\
& \frac{\mathrm{t}_{2}\left|\mu \rightarrow \mathrm{t}_{2}^{\prime}\right| \mu^{\prime}}{\mathrm{v}_{1}:=\mathrm{t}_{2}\left|\mu \rightarrow \mathrm{v}_{1}:=\mathrm{t}_{2}^{\prime}\right| \mu^{\prime}}  \tag{E-Assign2}\\
& \text { if true then } \mathrm{t}_{2} \text { else } \mathrm{t}_{3}\left|\mu \rightarrow \mathrm{t}_{2}\right| \mu \\
& \text { (E-Deref) } \\
& \text { (E-Assign) } \\
& \text { (E-ASSIGNı) } \\
& \text { if false then } \mathrm{t}_{2} \text { else } \mathrm{t}_{3}\left|\mu \rightarrow \mathrm{t}_{3}\right| \mu  \tag{E-IFFALSE}\\
& \text { (E-IFTRUE) } \\
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\text { if } \mathrm{t}_{1} \text { then } \mathrm{t}_{2} \text { else } \mathrm{t}_{3} \mid \mu \rightarrow \text { if } \mathrm{t}_{1}^{\prime} \text { then } \mathrm{t}_{2} \text { else } \mathrm{t}_{3} \mid \mu^{\prime}}  \tag{E-IF}\\
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\operatorname{succ} \mathrm{t}_{1}\left|\mu \rightarrow \operatorname{succ} \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}  \tag{E-SUCC}\\
& \text { pred } 0|\mu \rightarrow 0| \mu \\
& \text { pred }\left(\operatorname{succ} \mathrm{nv}_{1}\right)\left|\mu \rightarrow \mathrm{nv}_{1}\right| \mu  \tag{E-PREDSUCC}\\
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\text { pred } \mathrm{t}_{1} \mid \mu \rightarrow \operatorname{pred}_{\mathrm{t}_{1}^{\prime} \mid \mu}} \\
& \text { iszero } 0 \mid \mu \rightarrow \text { true| } \mu \\
& \text { iszero (succ nv }{ }_{1} \text { ) }|\mu \rightarrow \mathrm{false}| \mu \\
& \mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime} \\
& \overline{\text { iszero } \mathrm{t}_{1} \mid \mu \rightarrow \text { iszero } \mathrm{t}_{1}^{\prime} \mid \mu^{\prime}} \\
& \text { let } \mathrm{x}=\mathrm{v}_{1} \text { in } \mathrm{t}_{2}\left|\mu \rightarrow\left[\mathrm{x} \mapsto \mathrm{v}_{1}\right] \mathrm{t}_{2}\right| \mu \\
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\text { 1et } \mathrm{x}=\mathrm{t}_{1} \text { in } \mathrm{t}_{2} \mid \mu \rightarrow \text { 1et } \mathrm{x}=\mathrm{t}_{1}^{\prime} \text { in } \mathrm{t}_{2} \mid \mu^{\prime}}  \tag{E-LeT}\\
& \text { fix }\left(\lambda x: T_{1}, t_{2}\right) \mid \mu \\
& \rightarrow\left[\mathrm{x} \mapsto\left(\mathrm{fix}\left(\lambda \mathrm{x}: \mathrm{T}_{1}, \mathrm{t}_{2}\right)\right)\right] \mathrm{t}_{2} \mid \mu \\
& \frac{\mathrm{t}_{1}\left|\mu \rightarrow \mathrm{t}_{1}^{\prime}\right| \mu^{\prime}}{\mathrm{fix}_{1}\left|\mu \rightarrow \mathrm{fixt}_{1}^{\prime}\right| \mu} \\
& \text { (E-PredZero) } \\
& \text { (E-PRED) } \\
& \text { (E-IszeroZero) } \\
& \text { (E-IszeroSucc) } \\
& \text { (E-IsZEro) } \\
& \text { (E-LETV) } \\
& \text { (E-FixBeta) } \\
& \text { (E-FiX) }
\end{align*}
$$

New subtyping rules

$$
\begin{equation*}
\frac{\mathrm{S}_{1}<: \mathrm{T}_{1} \quad \mathrm{~T}_{1}<: \mathrm{S}_{1}}{\operatorname{Ref} \mathrm{~S}_{1}<: \operatorname{Ref} \mathrm{T}_{1}} \tag{S-Ref}
\end{equation*}
$$

New typing rules

$$
\begin{align*}
& \frac{\Gamma\left|\Sigma \vdash \mathrm{t}_{1}: \mathrm{T}_{11} \rightarrow \mathrm{~T}_{12} \quad \Gamma\right| \Sigma \vdash \mathrm{t}_{2}: \mathrm{T}_{11}}{\Gamma \mid \Sigma \vdash \mathrm{t}_{1} \mathrm{t}_{2}: \mathrm{T}_{12}} \\
& \Gamma \mid \Sigma \vdash \text { unit : Unit } \\
& \frac{\Sigma(l)=\mathrm{T}_{1}}{\Gamma \mid \Sigma \vdash l: \operatorname{Ref} \mathrm{T}_{1}}  \tag{T-LOC}\\
& \frac{\Gamma \mid \Sigma \vdash \mathrm{t}_{1}: \mathrm{T}_{1}}{\Gamma \mid \Sigma \vdash \operatorname{ref} \mathrm{t}_{1}: \operatorname{Ref} \mathrm{T}_{1}}  \tag{T-REF}\\
& \frac{\Gamma \mid \Sigma \vdash \mathrm{t}_{1}: \operatorname{Ref}_{11}}{\Gamma \mid \Sigma \vdash!\mathrm{t}_{1}: \mathrm{T}_{11}} \\
& \overline{\Gamma\left|\Sigma \vdash \mathrm{t}_{1}: \operatorname{Ref} \mathrm{T}_{11} \quad \Gamma\right| \Sigma \vdash \mathrm{t}_{2}: \mathrm{T}_{11}} \\
& \Gamma \mid \Sigma \vdash \mathrm{t}_{1}:=\mathrm{t}_{2} \text { : Unit } \\
& \Gamma \vdash \mathrm{t}_{1}: \mathrm{T}_{1} \quad \Gamma, \mathrm{x}: \mathrm{T}_{1} \vdash \mathrm{t}_{2}: \mathrm{T}_{2}  \tag{T-LET}\\
& \Gamma \vdash 1 \text { et } x=t_{1} \text { in } t_{2}: T_{2} \\
& \underline{\Gamma \vdash \mathrm{t}_{1}: \mathrm{T}_{1} \rightarrow \mathrm{~T}_{1}} \\
& \overline{\Gamma \vdash \mathrm{fix}_{1}: \mathrm{T}_{1}} \\
& \text { (T-UnIT) } \\
& \text { (T-FIX) }
\end{align*}
$$

## For reference: FJ

Syntax


Subtyping

$$
\begin{gathered}
\mathrm{C}<: \mathrm{C} \\
\frac{\mathrm{C}<: \mathrm{D} \quad \mathrm{D}<: \mathrm{E}}{\mathrm{C}<: \mathrm{E}} \\
\frac{C T(\mathrm{C})=\mathrm{class} \mathrm{C} \text { extends } \mathrm{D}\{\ldots\}}{\mathrm{C}<: \mathrm{D}}
\end{gathered}
$$

Field lookup

$$
\text { fields }(\mathrm{C})=\overline{\mathrm{C}} \overline{\mathrm{f}}
$$

$$
\text { fields }(0 b j e c t)=\bullet
$$

$$
C T(\mathrm{C})=\mathrm{class} C \text { extends } D\{\overline{\mathrm{C}} \overline{\mathrm{f}} ; \mathrm{K} \overline{\mathrm{M}}\}
$$

$$
\text { fields }(\mathrm{D})=\overline{\mathrm{D}} \overline{\mathrm{~g}}
$$

$$
\text { fields }(\mathrm{C})=\overline{\mathrm{D}} \overline{\mathrm{~g}}, \overline{\mathrm{C}} \overline{\mathrm{f}}
$$

Method type lookup

$$
\text { mtype }(\mathrm{m}, \mathrm{C})=\overline{\mathrm{C}} \rightarrow \mathrm{C}
$$

$$
\begin{gathered}
C T(\mathrm{C})=\mathrm{class} C \text { extends } \mathrm{D}\{\overline{\mathrm{C}} \overline{\mathrm{f}} ; \mathrm{K} \overline{\mathrm{M}}\} \\
\mathrm{B} m(\overline{\mathrm{~B}} \overline{\mathrm{x})\{\text { return } \mathrm{t} ;\} \in \overline{\mathrm{M}}} \\
\operatorname{mtype}(\mathrm{m}, \mathrm{C})=\overline{\mathrm{B}} \rightarrow \mathrm{~B} \\
C T(\mathrm{C})=\mathrm{class} C \text { extends } \mathrm{D}\{\overline{\mathrm{C}} \overline{\mathrm{~F}} ; \mathrm{K} \overline{\mathrm{M}}\} \\
\mathrm{m} \text { is not defined in } \overline{\mathrm{M}} \\
\hline \operatorname{mtype}(\mathrm{~m}, \mathrm{C})=\operatorname{mtype}(\mathrm{m}, \mathrm{D})
\end{gathered}
$$

Method body lookup

$$
\begin{gathered}
C T(\mathrm{C})=\mathrm{class} C \text { extends } \mathrm{D}\{\overline{\mathrm{C}} \overline{\mathrm{~F}} ; \mathrm{K} \overline{\mathrm{M}}\} \\
\mathrm{B} m(\overline{\mathrm{~B}} \overline{\mathrm{x}})\{\text { return } \mathrm{t} ;\} \in \overline{\mathrm{M}} \\
\operatorname{mbody}(\mathrm{~m}, \mathrm{C})=(\overline{\mathrm{x}}, \mathrm{t})
\end{gathered}
$$

$C T(\mathrm{C})=\mathrm{class} C$ extends $\mathrm{D}\{\overline{\mathrm{C}} \overline{\mathrm{f}} ; \mathrm{K} \overline{\mathrm{M}}\}$ $m$ is not defined in $\bar{M}$

$$
\operatorname{mbody}(\mathrm{m}, \mathrm{C})=\operatorname{mbody}(\mathrm{m}, \mathrm{D})
$$

Valid method overriding
override $\left(\mathrm{m}, \mathrm{D}, \overline{\mathrm{C}} \rightarrow \mathrm{C}_{0}\right)$

$$
\frac{\text { mtype }(\mathrm{m}, \mathrm{D})=\overline{\mathrm{D}} \rightarrow \mathrm{D}_{0} \text { implies } \overline{\mathrm{C}}=\overline{\mathrm{D}} \text { and } \mathrm{C}_{0}=\mathrm{D}_{0}}{\text { override }\left(\mathrm{m}, \mathrm{D}, \overline{\mathrm{C}} \rightarrow \mathrm{C}_{0}\right)}
$$

Evaluation

$$
\mathrm{t} \rightarrow \mathrm{t}^{\prime}
$$

(E-ProjNew)
(E-INVKNEW)
(E-CASTNEW)
(E-FIELD)
(E-INVK-RECV)
(E-INVK-ARG)
$\mathrm{v}_{0} \cdot \mathrm{~m}\left(\overline{\mathrm{v}}, \mathrm{t}_{i}, \overline{\mathrm{t}}\right)$ $\longrightarrow \mathrm{v}_{0} . \mathrm{m}\left(\overline{\mathrm{v}}, \mathrm{t}_{i}^{\prime}, \overline{\mathrm{t}}\right)$
$\frac{\mathrm{t}_{i} \rightarrow \mathrm{t}_{i}^{\prime}}{\text { new } \mathrm{C}\left(\overline{\mathrm{v}}, \mathrm{t}_{i}, \overline{\mathrm{t}}\right)}$
$\rightarrow$ new $C\left(\bar{v}, \mathrm{t}_{i}^{\prime}, \overline{\mathrm{t}}\right)$

$$
\frac{\mathrm{t}_{0} \rightarrow \mathrm{t}_{0}^{\prime}}{(\mathrm{C}) \mathrm{t}_{0} \rightarrow(\mathrm{C}) \mathrm{t}_{0}^{\prime}}
$$

(E-CAST)

$$
\begin{equation*}
\Gamma \vdash \mathrm{t}: \mathrm{C} \tag{T-VAR}
\end{equation*}
$$

$$
\frac{\Gamma \vdash \mathrm{t}_{0}: \mathrm{D} \quad \mathrm{C}<: \mathrm{D} \quad \mathrm{C} \neq \mathrm{D}}{\Gamma \vdash(\mathrm{C}) \mathrm{t}_{0}: \mathrm{C}}
$$

$$
\frac{\begin{array}{c}
\Gamma \vdash \mathrm{t}_{0}: \mathrm{D} \quad \mathrm{C} \not: \mathrm{D} \quad \mathrm{D} \nless: \mathrm{C} \\
\text { stupid warning }
\end{array}}{\Gamma \Gamma \vdash(\mathrm{C}) \mathrm{t}_{0}: \mathrm{C}}
$$

Method typing

$$
\begin{gathered}
\overline{\mathrm{x}}: \overline{\mathrm{C}}, \text { this }: \mathrm{C} \vdash \mathrm{t}_{0}: \mathrm{E}_{0} \quad \mathrm{E}_{0}<: \mathrm{C}_{0} \\
C T(\mathrm{C})=\mathrm{class} \mathrm{C} \text { extends } \mathrm{D}\{\ldots\} \\
\quad \text { override }\left(\mathrm{m}, \mathrm{D}, \overline{\mathrm{C}} \rightarrow \mathrm{C}_{0}\right) \\
\left.\hline \mathrm{C}_{0} \mathrm{~m}(\overline{\mathrm{C}} \overline{\mathrm{x}}) \text { \{return } \mathrm{t}_{0} ;\right\} \text { OK in } \mathrm{C}
\end{gathered}
$$

Class typing

$$
\begin{gathered}
\mathrm{K}=\mathrm{C}(\overline{\mathrm{D}} \overline{\mathrm{~g}}, \overline{\mathrm{C}} \overline{\mathrm{f}}) \quad \text { \{super }(\overline{\mathrm{g}}) ; \text { this. } \overline{\mathrm{f}}=\overline{\mathrm{f}} ;\} \\
\text { fields }(\mathrm{D})=\overline{\mathrm{D}} \overline{\mathrm{~g}} \quad \overline{\mathrm{M}} \text { OK in } \mathrm{C}
\end{gathered}
$$

