

CIS 500

Software Foundations

Fall 2004

29 September

- Upcoming CIS Colloquia related to programming languages
- Tuesdays, 3:00-4:30, Levine 101
- ◆ Oct 19 - Andy Gordon, MSR Cambridge
 - ◆ Nov 16 - Greg Morrisett, Harvard University
 - ◆ Nov 23 - Jeannette Wing, CMU

Announcements

- ◆ Encoding recursion
- ◆ Providing properties by induction
- ◆ Variable substitution and alpha-equivalence
- ◆ Program equivalence

Tod^ay

Recursion in the Lambda Calculus

$$Y_f = (\lambda x. f(x))(\lambda x. f(x))$$

Suppose f is some λ -abstraction, and consider the following term:

Iterated Application

$$\begin{array}{c}
 \dots \\
 \leftarrow \\
 (((\overline{(\lambda x. f (x))})) f) f \\
 \leftarrow \\
 (((\overline{(\lambda x. f (x))})) (\lambda x. f (x))) f \\
 \leftarrow \\
 (\overline{((\lambda x. f (x)) (\lambda x. f (x)))}) f \\
 \leftarrow \\
 ((\lambda x. f (x)) (\lambda x. f (x))) f \\
 = \\
 Y^f
 \end{array}$$

Now the “pattern of divergence” becomes more interesting:

$$Y^f = (\lambda x. f (x)) (\lambda x. f (x))$$

Suppose f is some λ -abstraction, and consider the following term:

Iterated Application

Y⁴ is still not very useful, since (like omega), all it does is diverge.
Is there any way we could "slow it down"?

$$\begin{array}{c}
 \dots \\
 \leftarrow \\
 \text{omega} \\
 \leftarrow \\
 \overline{\text{posonpil\ } \text{tru}} \\
 \leftarrow^* \\
 \text{fst } (\text{pair posonpil\ } \text{fis}) \text{ tru} \\
 \leftarrow \\
 \overline{(\lambda p.\ \text{fst } (\text{pair } p \text{ fis}) \text{ tru}) \text{ posonpil\ } \text{tru}}
 \end{array}$$

Note that `posonpil` is a value — it it will only diverge when we actually apply it to an argument. This means that we can safely pass it as an argument to other functions, return it as a result from functions, etc.

$$\text{posonpil} = \lambda y.\ \text{omega}$$

Delayed Divergence

$$\begin{aligned}
 & \text{omegav} \vee \\
 & = \\
 & \Delta (\lambda x. (\lambda y. x x y) (\lambda y. x x y)) \wedge \\
 & \quad \leftarrow \\
 & \frac{\Delta (\lambda x. (\lambda y. x x y) (\lambda y. x x y)) \wedge}{\Delta (\lambda x. (\lambda y. x x y) (\lambda y. x x y)) \wedge} \\
 & \quad \leftarrow \\
 & \frac{\Delta (\lambda y. (\lambda x. (\lambda y. x x y) (\lambda x. (\lambda y. x x y)) y) \wedge}{\Delta (\lambda y. (\lambda x. (\lambda y. x x y) (\lambda y. x x y)) y) \wedge} \\
 & = \\
 & \text{omegav} \vee
 \end{aligned}$$

it diverges:

Note that **omegav** is a normal form. However, if we apply it to any argument Δ ,

$$\text{omegav} = \lambda y. (\lambda x. (\lambda y. x x y) (\lambda x. (\lambda y. x x y)) y)$$

tightly intertwined:

Here is a variant of **omegav** in which the delay and divergence are a bit more

A delayed variant of omegav

omegaV.

This term combines the "added f " from Y^f with the "delayed divergence" of

$$Z^f = \forall y. (\forall x. f(\forall y. x \ x \ y)) (\forall x. f(\forall y. x \ x \ y)) \ y$$

Suppose f is a function. Define

Another delayed variant

Now we are getting somewhere.

Since Z^f and Λ are both values, the next computation step will be the reduction of $f Z^f$ — that is, before we “dereference,” f gets to do some computation.

$$\begin{aligned}
 & \Lambda \quad f \quad Z^f \\
 & = \\
 & \Lambda \quad (\lambda \quad ((\lambda \quad x \quad x \cdot \lambda y \cdot f x) \quad (\lambda y \cdot x \quad x \quad y)) \quad (\lambda y \cdot f x \cdot (\lambda y \cdot x \quad x \quad y))) \\
 & \qquad \qquad \qquad \longleftarrow \\
 & \Lambda \quad \overline{(\lambda x \cdot f (\lambda y \cdot x \quad x \quad y)) \quad (\lambda x \cdot f (\lambda y \cdot x \quad x \quad y))} \\
 & \qquad \qquad \qquad \longleftarrow \\
 & \Lambda \quad (\lambda y \cdot (\lambda x \cdot f (\lambda y \cdot x \quad x \quad y)) \quad (\lambda x \cdot f (\lambda y \cdot x \quad x \quad y))) \\
 & \qquad \qquad \qquad = \\
 & \Lambda \quad Z^f
 \end{aligned}$$

If we now apply Z^f to an argument Λ , something interesting happens:

N.b.: for brevity, this example uses “real” numbers and booleans, infix syntax etc. It can easily be translated into the pure Lambda-calculus (using Church numerals, etc.).

call in the last time, it calls the function `fct`, which is passed as a parameter. It looks just like ordinary factorial function, except that, in place of a recursive

```
else u * (fct (pred u))  
if u=0 then 1  
     .  
f = fct.
```

Let

Recursion

$$\begin{array}{c}
 \dots \\
 3 * (\text{f } Z^f 2) \\
 \leftarrow * \\
 3 * (Z^f 2) \\
 \leftarrow \\
 3 * (Z^f (\text{pred } 3)) \\
 \leftarrow * \\
 \text{if } 3=0 \text{ then 1 else } 3 * (Z^f (\text{pred } 3)) \\
 \leftarrow \quad \leftarrow \\
 (\text{fact. } \text{an. } \dots) \ Z^f 3 \\
 = \\
 \text{f } Z^f 3 \\
 \leftarrow * \\
 Z^f 3
 \end{array}$$

factorial function:

We can use Z to “tie the knot” in the definition of f and obtain a real recursive

$$\vdash Z \leftarrow f Z$$

to f .

then we can obtain the behavior of Z^f for any f we like, simply by applying Z

$$Z = \forall f. \forall y. (\forall x. f(\forall y. x x y)) (\forall x. f(\forall y. x x y)) y$$

i.e.,

$$Z = \forall f. Z^f$$

If we define

A Generic Z

```
fact = Z ( fact.  
          if n=0 then 1  
          else n * (fact(pred n)) )  
       an.
```

For example:

$Z f v \xleftarrow{*} f(Z f) v$, which **fix** does not (quite) share.
 Z is hopefully slightly easier to understand, since it has the property that

$$\begin{aligned} fix &= \lambda f. (\lambda x. f(\lambda y. x x y)) (\lambda x. f(\lambda y. x x y)) \\ Z &= \lambda f. \lambda y. (\lambda x. f(\lambda y. x x y)) (\lambda x. f(\lambda y. x x y)) y \end{aligned}$$

The term **Z** here is essentially the same as the **fix** discussed the book.

Technical note:

Proofs about the Lambda Calculus

Like before, we have mentioned two ways to prove properties are true of the untyped lambda calculus.

Two induction principles

Recall the induction principle for the small-step evaluation relation.
We can show a property P is true for all derivations of $t \rightarrow t'$, when

- ♦ P holds for all derivations that use the rule E-APPAs.
- ♦ P holds for all derivations that end with a use of E-APP1 assuming that P holds for all subderivations.
- ♦ P holds for all derivations that end with a use of E-APP2 assuming that P holds for all subderivations.

Induction principle

Theorem: If $t \rightarrow t'$, then $\text{FV}(t) \subseteq \text{FV}(t')$.

$$\text{FV}(t_1 \cdot t_2) = \text{FV}(t_1) \cup \text{FV}(t_2)$$

$$\text{FV}(\lambda x. t_1) = \text{FV}(t_1) / \{x\}$$

$$\{x\} = \text{FV}(x)$$

We can formally define the set of free variables in a λ -term as follows:

Example

We want to prove, for all derivations of $t \rightarrow t'$, that $\text{FV}(t) \subseteq \text{FV}(t')$.

We have three cases.

Induction on derivation

$$\begin{aligned}
 & (\textcolor{blue}{t}, \textcolor{blue}{FV}(t)) = \\
 & \subseteq \textcolor{blue}{FV}(\textcolor{blue}{x} \leftrightarrow \textcolor{blue}{v}[\textcolor{blue}{u}]) \\
 & (\textcolor{blue}{u}, \textcolor{blue}{FV}(u)) / \{x\} \cap \textcolor{blue}{FV}(v) = \\
 & \textcolor{blue}{FV}(t) = \textcolor{blue}{FV}((\forall x \cdot u \cdot v))
 \end{aligned}$$

is $(\forall x \cdot u \cdot v)$ which steps to $\textcolor{blue}{[x \leftrightarrow v]u}$.

♦ The derivation of $t \leftarrow t'$ could just be a use of E-APPLabs. In this case, t

We have three cases.

We want to prove, for all derivations of $t \leftarrow t'$, that $\textcolor{blue}{FV}(t) \subseteq \textcolor{blue}{FV}(t')$.

Induction on derivation

$$\begin{aligned}
 & (\text{FV}(t') = \\
 & = \text{FV}(t'_1 \ t_2) \\
 & \subseteq \text{FV}(t'_1) \cup \text{FV}(t_2) \\
 & = \text{FV}(t_1) \cup \text{FV}(t_2) \\
 & \text{FV}(t) = \text{FV}(t_1 \ t_2)
 \end{aligned}$$

By induction $\text{FV}(t_1) \subseteq \text{FV}(t'_1)$.

derivation of $t_1 \rightarrow t'_1$ and we use it to show that $t_1 \ t_2 \rightarrow t'_1 \ t_2$.

- ♦ The derivation could end with a use of E-APP1. In other words, we have a

- ◆ The derivation could end with a use of E-APP2. Here, we have a derivation of $t_2 \rightarrow t'_2$ and we use it to show that $t_1 \quad t_2 \rightarrow t'_1 \quad t'_2$. This case is analogous to the previous case.

$$\begin{aligned}
 & (\text{FV}(t')) = \\
 & = \text{FV}(t'_1 \quad t'_2) \\
 & \subseteq \text{FV}(t'_1) \cup \text{FV}(t'_2) \\
 & = \text{FV}(t_1) \cup \text{FV}(t_2) \\
 & \text{FV}(t) = \text{FV}(t_1 \quad t_2)
 \end{aligned}$$

- ◆ The derivation could end with a use of E-APP1. In other words, we have a derivation of $t_1 \rightarrow t'_1$ and we use it to show that $t_1 \quad t_2 \rightarrow t'_1 \quad t'_2$. By induction $\text{FV}(t_1) \subseteq \text{FV}(t'_1)$.

More about bound variables

Our definition of evaluation was based on the substitution of values for free variables within terms.

E-Apps

$(\lambda x.t_1) v_2 \rightarrow [x \rightarrow v_2] t_1$

But what is substitution, really? How do we define it?

Substitution

What is wrong with this definition?

$$[x \leftarrow s[t_1 t_2]] = ([x \leftarrow s[t_1]] [x \leftarrow s[t_2]])$$

$$[x \leftarrow s(\forall y.t_1)] = \forall y. ([x \leftarrow s[t_1]]$$

$$\text{if } x \neq y \quad [x \leftarrow s[y = y]]$$

$$[x \leftarrow s[x = s]]$$

Consider the following definition of substitution:

Formalizing Substitution

This is not what we want.

$$[x \leftarrow y] (\lambda x. x) = \lambda x. y$$

It substitutes for free and bound variables!

What is wrong with this definition?

$$[x \leftarrow s[t_1 t_2]] = ([x \leftarrow s[t_1]] [x \leftarrow s[t_2]])$$

$$[x \leftarrow s](\lambda y. t_1) = \lambda y. ([x \leftarrow s] t_1)$$

$$\text{if } x \neq y \quad [x \leftarrow s] y = y$$

$$[x \leftarrow s] x = s$$

Consider the following definition of substitution:

Formalizing Substitution

What is wrong with this definition?

$$[x \leftarrow s[t_1 t_2]] = ([x \leftarrow s[t_1]] [x \leftarrow s[t_2]])$$

$$[x \leftarrow s(\forall x. t_1)] = \forall x. t_1$$

$$[x \leftarrow s(\forall y. t_1)] = \forall y. ([x \leftarrow s[t_1]]$$

$$[x \leftarrow s[y = y] = y \quad \text{if } x \neq y$$

$$s = x[s \leftarrow x]$$

Substitution, take two

This is also not what we want.

$$[x \hookrightarrow y (\forall x. x) = \forall x. x]$$

It suffers from **variable capture**!

What is wrong with this definition?

$$[x \hookrightarrow s (t_1 t_2) = ([x \hookrightarrow s t_1] (x \hookrightarrow s t_2))$$

$$[x \hookrightarrow s (\forall x. t_1) = \forall x. t_1]$$

$$[x \hookrightarrow s (\forall y. t_1) = \forall y. ([x \hookrightarrow s t_1]) \quad \text{if } x \neq y$$

$$[x \hookrightarrow s y = y \quad \text{if } x \neq y]$$

$$s = x [s \hookrightarrow x]$$

Substitution, take two

What is wrong with this definition?

$$[x \leftarrow s](t_1 t_2) = ([x \leftarrow s]t_1)([x \leftarrow s]t_2)$$

$$[x \leftarrow s](\lambda x. t_1) = \lambda x. [t_1]$$

$$[x \leftarrow s](\lambda y. t_1) = \lambda y. ([x \leftarrow s]t_1)$$

$$[x \leftarrow s]y = y \quad \text{if } x \text{ is not } y$$

$$s = x[s \leftarrow x]$$

Substitution, take three

But we want an answer for every substitution.

$[x \rightarrow y](\lambda y.x)$ is undefined.

Now substitution is a **partial function**!

What is wrong with this definition?

$$[x \rightarrow s](t_1 t_2) = ([x \rightarrow s]t_1)([x \rightarrow s]t_2)$$

$$[x \rightarrow s](\lambda x.t_1) = \lambda x. [x \rightarrow s]t_1$$

$$[x \rightarrow s](\lambda y.t_1) = \lambda y. ([x \rightarrow s]t_1) \quad \text{if } x \neq y, y \notin \text{FV}(s)$$

$$[x \rightarrow s]y = y \quad \text{if } x \text{ is not } y$$

$$[x \rightarrow s]x = s$$

Substitution, take three

Bound variable names shouldn't matter

It's annoying that the names of bound variables are causing trouble with our definition of substitution.

Intuition tells us that there shouldn't be a difference between the functions Ax.x and Ay.y . Both of these functions will do the same thing.

Because they differ only in the names of their bound variables, we'd like to think that these **are** the same function.

We call such terms **alpha-equivalent**.

Alpha-equivalence Classes

In fact, we can create equivalence classes of terms that differ only in the names of bound variables.

When working with the Lambda calculus, it is convenient to think about these equivalence classes, instead of raw terms.

For example, when we write $\lambda x.x$ we mean not just this term, but the class of terms that includes $\lambda y.y$ and $\lambda z.z$.

Unfortunately, we have to be more clever when implementing the Lambda calculus in ML... (cf. TAPL chapters 6 and 7)

the latter is $\lambda w.z$ so that is what we use for the former.

♦ $[x \leftarrow y](\lambda x.z)$ must give the same result as $[x \leftarrow y](\lambda w.z)$. We know

the latter is $\lambda z.y$, so that is what we will use for the former.

♦ $[x \leftarrow y](\lambda y.x)$ must give the same result as $[x \leftarrow y](\lambda z.x)$. We know

Examples:

$$[x \leftarrow s](t_1 t_2) = ([x \leftarrow s]t_1)([x \leftarrow s]t_2)$$

$$[x \leftarrow s](\lambda y.t_1) = \lambda y. ([x \leftarrow s]t_1) \quad \text{if } x \neq y, y \notin \text{FV}(s)$$

$$[x \leftarrow y]y = y \quad \text{if } x \neq y$$

$$[x \leftarrow s]x = s$$

terms:

Now consider substitution as an operation over alpha-equivalence classes of

Substitution, for alpha-equivalence classes

Equivalence of Lambda Terms

- ♦ Syntactic equivalence - Are the terms the same "letter by letter"? Note that useful.
- ♦ Alpha-equivalence - Are the terms equivalent up to renaming of bound variables?
- ♦ Beta/eta-equivalence - Can we use specific program transformations to convert one term into another?
- ♦ Behavioral equivalence - If both terms are placed in the same context, will they produce the same result?

Program Equivalence

Why is program equivalence important?

- ◆ Used to catch cheaters in low-level programming classes.
- ◆ Used to prove the correctness of embeddings. (Why should we believe that Church encodings represent natural numbers?)
- ◆ Used to prove the correctness of compiler optimizations.
- ◆ Used to show that updates to a program do not break it.

Why is program equivalence important?

$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

Other lambda-terms represent common operations on numbers:

$$c_3 = \lambda s. \lambda z. s (s (s z))$$

$$c_2 = \lambda s. \lambda z. s (s z)$$

$$c_1 = \lambda s. \lambda z. s z$$

$$c_0 = \lambda s. \lambda z. z$$

represent natural numbers.

We have seen how certain terms in the lambda-calculus can be used to

Representing Numbers

corresponds to ordinary successor on numbers?

In particular, on what basis can we argue that scc on church numerals

In what sense can we say this representation is “correct”?

$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

Other lambda-terms represent common operations on numbers:

$$c_3 = \lambda s. \lambda z. s (s (s z))$$

$$c_2 = \lambda s. \lambda z. s (s z)$$

$$c_1 = \lambda s. \lambda z. s z$$

$$c_0 = \lambda s. \lambda z. z$$

represent natural numbers.

We have seen how certain terms in the lambda-calculus can be used to

Representing Numbers

One possibility:

For each n , the term $\text{scc } c_n$ evaluates to c_{n+1} .

The naive approach

$$\begin{aligned} & \text{scc } c_2 = (\lambda n. \lambda s. \lambda z. s (n s z)) (\lambda s. \lambda z. s (s z)) \\ & \qquad\qquad\qquad \longleftarrow \qquad\qquad\qquad \text{as. } \lambda z. \text{ s ((as. } \lambda z. \text{ s (z)) s (z)) \\ & \qquad\qquad\qquad \neq \qquad\qquad\qquad \text{as. } \lambda z. \text{ s (s (z s (s z))) } \\ & \qquad\qquad\qquad = \qquad\qquad\qquad c_3 \end{aligned}$$

E.g.:

Unfortunately, this is false.

For each n , the term $\text{scc } c_n$ evaluates to c_{n+1} .

One possibility:

The naive approach... doesn't work

I.e., what we really care about is that `scc c2` behaves the same as `c3` when applied to two arguments.

- ◆ `scc` takes a term that „does something n times to something else“ and returns a term that „does something $n + 1$ times to something else“
- ◆ a number n is represented as a term that „does something n times to something else“

Recall the intuition behind the church numeral representation:

A better approach

$((\lambda \Lambda) \Lambda) \Lambda \leftarrow$
 $\lambda ((z \Lambda) \Lambda) \Lambda . z \lambda \leftarrow$
 $\lambda \Lambda ((z s) s) s . z \lambda . s \lambda = \lambda \Lambda$

$((\lambda \Lambda) \Lambda) \Lambda \leftarrow$
 $(\lambda ((z \Lambda) \Lambda . z \lambda)) \Lambda \leftarrow$
 $(\lambda \Lambda ((z s) s . z \lambda . s \lambda)) \Lambda \leftarrow$
 $\lambda ((z \Lambda ((z s) s . z \lambda . s \lambda)) \Lambda . z \lambda \leftarrow$
 $\lambda \Lambda ((z s ((z s) s . z \lambda . s \lambda)) s . z \lambda . s \lambda \leftarrow$
 $\lambda \Lambda ((z s s ((z s) s . z \lambda . s \lambda)) s . z \lambda . s \lambda \leftarrow$
 $\lambda \Lambda ((z s s ((z s) s . z \lambda . s \lambda)) s . z \lambda . s \lambda = \lambda \Lambda$

We have argued that, although **scc c₂** and **c₃** do not evaluate to the same thing, they are nevertheless “behaviorally equivalent.” What, precisely, does behavioral equivalence mean?

A More General Question

Roughly, terms **s** and **t** are behaviorally equivalent
should mean:
there is no “test” that distinguishes **s** and **t** — i.e., no way to use them in
the same context and obtain different results.

Intuition

Which of these are behaviorally equivalent?

$y^t = (\forall x. f(x) \wedge f(x)) \vee (\forall x. f(x) \wedge f(x))$

$\text{placebo} = \forall x. \text{true}$

$\text{positonpill} = \forall x. \text{omega}$

$\text{omega} = (\forall x. x = x) \wedge (\forall x. x = x)$

$\text{f1s} = \forall t. \forall f. f$

$\text{true'} = \forall t. \forall f. (\forall x. x) \wedge f$

$\text{true} = \forall t. \forall f. t$

Some test cases

As a first step toward defining behavioral equivalence, we can use the notion of **normalizability** to define a simple way of testing terms.

Two terms s and t are said to be **observationally equivalent** if either both are normalizable (i.e., they reach a normal form after a finite number of evaluation steps) or both are divergent.

I.e., our primitive notion of “observing” a term’s behavior is simply running it on our abstract machine.

Observational equivalence

- ♦ Is observational equivalence a decidable property?

Aside:

on our abstract machine.

I.e., our primitive notion of "observing" a term's behavior is simply running it

evaluation steps) or both are divergent.

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Two terms s and t are said to be **observationally equivalent** if either both

normalizability to define a simple way of testing terms.

As a first step toward defining behavioral equivalence, we can use the notion of

Observational equivalence

- ♦ Does this mean the definition is ill-formed?
- ♦ Is observational equivalence a decidable property?

Aside:

As a first step toward defining behavioral equivalence, we can use the notion of **normalizability** to define a simple way of testing terms. Two terms s and t are said to be **observationally equivalent** if either both are normalizable (i.e., they reach a normal form after a finite number of evaluation steps) or both are divergent. I.e., our primitive notion of "observing" a term's behavior is simply running it on our abstract machine.

Observational equivalence

- ♦ `omega` and `true` are **not** observationally equivalent

Examples

- ♦ `true` and `fls` are observationally equivalent
- ♦ `omega` and `true` are **not** observationally equivalent

Examples

This primitive notion of observation now gives us a way of “testing” terms for behavioral equivalence

Terms s and t are said to be **behaviorally equivalent** if, for every finite sequence of values v_1, v_2, \dots, v_n , the applications

$s v_1 v_2 \dots v_n$

and

$t v_1 v_2 \dots v_n$

are observationally equivalent.

Behavioral Equivalence

$\text{placebo} = \forall x. \text{tru}$

$\text{position}[] = \forall x. \text{omega}$

$\text{f1s} = \forall t. \forall f. f$

above):

These are not behaviorally equivalent (to each other, or to any of the terms

$y^t = \forall x. f(x) ((x x) f(x))$

$\text{omega} = (\forall x. x x) (\forall x. x x)$

So are these:

$\text{tru}' = \forall t. \forall f. (\forall x. x) t$

$\text{tru} = \forall t. \forall f. t$

These terms are behaviorally equivalent:

Examples