

CIS 500
Software Foundations
Fall 2006

October 25

A Little More on References

Recap

Last time, we discussed how to formalize languages with mutable state...

Syntax

We added to λ_{\rightarrow} (with `Unit`) syntactic forms for creating, dereferencing, and assigning reference cells, plus a new type constructor `Ref`.

`t ::=`

`unit`

`x`

`$\lambda x:T.t$`

`t t`

`ref t`

`!t`

`t:=t`

`/`

terms

unit constant

variable

abstraction

application

reference creation

dereference

assignment

store location

Evaluation

Evaluation becomes a four-place relation: $t \mid \mu \longrightarrow t' \mid \mu'$

$$\frac{l \notin \text{dom}(\mu)}{\text{ref } v_1 \mid \mu \longrightarrow l \mid (\mu, l \mapsto v_1)} \quad (\text{E-REFV})$$

$$\frac{\mu(l) = v}{!l \mid \mu \longrightarrow v \mid \mu} \quad (\text{E-DEREFLOC})$$

$$l := v_2 \mid \mu \longrightarrow \text{unit} \mid [l \mapsto v_2]\mu \quad (\text{E-ASSIGN})$$

(Plus several congruence rules.)

Typing

Typing becomes a three-place relation: $\Gamma \mid \Sigma \vdash t : T$

$$\frac{\Sigma(l) = T_1}{\Gamma \mid \Sigma \vdash l : \text{Ref } T_1} \quad (\text{T-LOC})$$

$$\frac{\Gamma \mid \Sigma \vdash t_1 : T_1}{\Gamma \mid \Sigma \vdash \text{ref } t_1 : \text{Ref } T_1} \quad (\text{T-REF})$$

$$\frac{\Gamma \mid \Sigma \vdash t_1 : \text{Ref } T_{11}}{\Gamma \mid \Sigma \vdash !t_1 : T_{11}} \quad (\text{T-DEREF})$$

$$\frac{\Gamma \mid \Sigma \vdash t_1 : \text{Ref } T_{11} \quad \Gamma \mid \Sigma \vdash t_2 : T_{11}}{\Gamma \mid \Sigma \vdash t_1 := t_2 : \text{Unit}} \quad (\text{T-ASSIGN})$$

Preservation

Theorem: If

$$\Gamma \mid \Sigma \vdash t : T$$

$$\Gamma \mid \Sigma \vdash \mu$$

$$t \mid \mu \longrightarrow t' \mid \mu'$$

then, for **some** $\Sigma' \supseteq \Sigma$,

$$\Gamma \mid \Sigma' \vdash t' : T$$

$$\Gamma \mid \Sigma' \vdash \mu'.$$

Progress

Theorem: Suppose t is a closed, well-typed term (that is, $\emptyset \mid \Sigma \vdash t : T$ for some T and Σ). Then either t is a value or else, for any store μ such that $\emptyset \mid \Sigma \vdash \mu$, there is some term t' and store μ' with $t \mid \mu \longrightarrow t' \mid \mu'$.

Nontermination via references

There are well-typed terms in this system that are not strongly normalizing. For example:

```
t1 = λr:Ref (Unit→Unit).  
      (r := (λx:Unit. (!r)x);  
       (!r) unit);  
t2 = ref (λx:Unit. x);
```

Applying `t1` to `t2` yields a (well-typed) divergent term.

Recursion via references

Indeed, we can define arbitrary recursive functions using references.

1. Allocate a `ref` cell and initialize it with a dummy function of the appropriate type:

```
factref = ref (λn:Nat.0)
```

2. Define the body of the function we are interested in, using the contents of the reference cell for making recursive calls:

```
factbody =  
  λn:Nat.  
    if iszero n then 1 else times n (!!factref)(pred n))
```

3. “Backpatch” by storing the real body into the reference cell:

```
factref := factbody
```

4. Extract the contents of the reference cell and use it as desired:

```
fact = !factref  
fact 5
```

Exceptions

Motivation

Most programming languages provide some mechanism for interrupting the normal flow of control in a program to signal some exceptional condition.

Note that it is always *possible* to program without exceptions — instead of raising an exception, we return `None`; instead of returning result `x` normally, we return `Some(x)`. But now we need to wrap every function application in a `case` to find out whether it returned a result or an exception.

It is much more convenient to build this mechanism into the language.

Varieties of non-local control

There are *many* ways of adding “non-local control flow”

- ▶ `exit(1)`
- ▶ `goto`
- ▶ `setjmp/longjmp`
- ▶ `raise/try` (or `catch/throw`) in many variations
- ▶ `callcc` / continuations
- ▶ more esoteric variants (cf. many Scheme papers)

Let's begin with the simplest of these.

An “abort” primitive in λ_{\rightarrow}

First step: raising exceptions (but not catching them).

$t ::= \dots$ *terms*
 error *run-time error*

Evaluation

$\text{error } t_2 \longrightarrow \text{error}$ (E-APPERR1)

$v_1 \text{ error} \longrightarrow \text{error}$ (E-APPERR2)

- ▶ What if we had booleans and numbers in the language?

Typing

Typing

$\Gamma \vdash \text{error} : T$

(T-ERROR)

Typing errors

Note that the typing rule for `error` allows us to give it *any* type `T`.

$$\Gamma \vdash \text{error} : T \quad (\text{T-ERROR})$$

This means that both

```
if x>0 then 5 else error
```

and

```
if x>0 then true else error
```

will typecheck.

Aside: Syntax-directedness

Note that this rule

$$\Gamma \vdash \text{error} : T \quad (\text{T-ERROR})$$

has a problem from the point of view of implementation: it is not *syntax directed*.

This will cause the Uniqueness of Types theorem to fail.

For purposes of defining the language and proving its type safety, this is not a problem — Uniqueness of Types is not critical.

Let's think a little, though, about how the rule might be fixed...

An alternative

Can't we just decorate the `error` keyword with its intended type, as we have done to fix related problems with other constructs?

$$\Gamma \vdash (\text{error as } T) : T \quad (\text{T-ERROR})$$

An alternative

Can't we just decorate the `error` keyword with its intended type, as we have done to fix related problems with other constructs?

$$\Gamma \vdash (\text{error as } T) : T \quad (\text{T-ERROR})$$

No, this doesn't work!

E.g. (assuming our language also has numbers and booleans):

```
      succ (if (error as Bool) then 5 else 7)
→ succ (error as Bool)
```

Exercise: Come up with a similar example using just functions and `error`.

Another alternative

In a system with universal polymorphism (like OCaml), the variability of typing for `error` can be dealt with by assigning it a variable type!

$$\Gamma \vdash \text{error} : 'a \quad (\text{T-ERROR})$$

In effect, we are replacing the *uniqueness of typing* property by a weaker (but still very useful) property called *most general typing*.

I.e., although a term may have many types, we always have a compact way of *representing* the set of all of its possible types.

Yet another alternative

Alternatively, in a system with subtyping (which we'll discuss in the next lecture) and a minimal `Bot` type, we *can* give `error` a unique type:

$$\Gamma \vdash \text{error} : \text{Bot} \quad (\text{T-ERROR})$$

(Of course, what we've really done is just pushed the complexity of the old `error` rule onto the `Bot` type! We'll return to this point later.)

For now...

Let's stick with the original rule

$$\Gamma \vdash \text{error} : T \quad (\text{T-ERROR})$$

and live with the resulting nondeterminism of the typing relation.

Type safety

The *preservation* theorem requires no changes when we add `error`: if a term of type `T` reduces to `error`, that's fine, since `error` has every type `T`.

Type safety

The *preservation* theorem requires no changes when we add `error`: if a term of type `T` reduces to `error`, that's fine, since `error` has every type `T`.

Progress, though, requires a little more care.

Progress

First, note that we do *not* want to extend the set of values to include `error`, since this would make our new rule for propagating errors through applications.

$$v_1 \text{ error} \longrightarrow \text{error} \quad (\text{E-APPERR2})$$

overlap with our existing computation rule for applications:

$$(\lambda x:T_{11}.t_{12}) v_2 \longrightarrow [x \mapsto v_2]t_{12} \quad (\text{E-APPABS})$$

e.g., the term

$$(\lambda x:\text{Nat}.0) \text{ error}$$

could evaluate to either `0` (which would be wrong) or `error` (which is what we intend).

Progress

Instead, we keep `error` as a non-value normal form, and refine the statement of progress to explicitly mention the possibility that terms may evaluate to `error` instead of to a value.

THEOREM [PROGRESS]: *Suppose t is a closed, well-typed normal form. Then either t is a value or $t = \text{error}$.*

Catching exceptions

$t ::= \dots$

$\text{try } t \text{ with } t$

Evaluation

terms

trap errors

$\text{try } v_1 \text{ with } t_2 \longrightarrow v_1$ (E-TRYV)

$\text{try error with } t_2 \longrightarrow t_2$ (E-TRYERROR)

$$\frac{t_1 \longrightarrow t'_1}{\text{try } t_1 \text{ with } t_2 \longrightarrow \text{try } t'_1 \text{ with } t_2}$$
 (E-TRY)

Typing

$$\frac{\Gamma \vdash t_1 : T \quad \Gamma \vdash t_2 : T}{\Gamma \vdash \text{try } t_1 \text{ with } t_2 : T}$$
 (T-TRY)

Exceptions carrying values

`t ::= ...`
`raise t`

terms
raise exception

Evaluation

$(\text{raise } v_{11}) t_2 \longrightarrow \text{raise } v_{11}$ (E-APPRAISE1)

$v_1 (\text{raise } v_{21}) \longrightarrow \text{raise } v_{21}$ (E-APPRAISE2)

$$\frac{t_1 \longrightarrow t'_1}{\text{raise } t_1 \longrightarrow \text{raise } t'_1} \quad (\text{E-RAISE})$$

$\text{raise } (\text{raise } v_{11}) \longrightarrow \text{raise } v_{11}$ (E-RAISERAISE)

$\text{try } v_1 \text{ with } t_2 \longrightarrow v_1$ (E-TRYV)

$\text{try } \text{raise } v_{11} \text{ with } t_2 \longrightarrow t_2 v_{11}$ (E-TRYRAISE)

$$\frac{t_1 \longrightarrow t'_1}{\text{try } t_1 \text{ with } t_2 \longrightarrow \text{try } t'_1 \text{ with } t_2} \quad (\text{E-TRY})$$

Typing

To typecheck `raise` expressions, we need to choose a type — let's call it T_{exn} — for the values that are carried along with exceptions.

$$\frac{\Gamma \vdash t_1 : T_{\text{exn}}}{\Gamma \vdash \text{raise } t_1 : T} \quad (\text{T-EXN})$$

$$\frac{\Gamma \vdash t_1 : T \quad \Gamma \vdash t_2 : T_{\text{exn}} \rightarrow T}{\Gamma \vdash \text{try } t_1 \text{ with } t_2 : T} \quad (\text{T-TRY})$$

What is T_{exn} ?

To complete the story, we need to decide what type to use as T_{exn} . There are several possibilities.

1. Numeric error codes: $T_{\text{exn}} = \text{Nat}$ (as in C)

What is T_{exn} ?

To complete the story, we need to decide what type to use as T_{exn} . There are several possibilities.

1. Numeric error codes: $T_{\text{exn}} = \text{Nat}$ (as in C)
2. Error messages: $T_{\text{exn}} = \text{String}$

What is T_{exn} ?

To complete the story, we need to decide what type to use as T_{exn} . There are several possibilities.

1. Numeric error codes: $T_{\text{exn}} = \text{Nat}$ (as in C)
2. Error messages: $T_{\text{exn}} = \text{String}$
3. A predefined variant type:

```
 $T_{\text{exn}}$  = <divideByZero:    Unit,  
          overflow:      Unit,  
          fileNotFound:  String,  
          fileNotReadable: String,  
          ... >
```

What is T_{exn} ?

To complete the story, we need to decide what type to use as T_{exn} . There are several possibilities.

1. Numeric error codes: $T_{\text{exn}} = \text{Nat}$ (as in C)
2. Error messages: $T_{\text{exn}} = \text{String}$
3. A predefined variant type:

```
 $T_{\text{exn}}$  = <divideByZero:    Unit,  
          overflow:      Unit,  
          fileNotFound:  String,  
          fileNotReadable: String,  
          ... >
```

4. An *extensible* variant type (as in OCaml)

What is T_{exn} ?

To complete the story, we need to decide what type to use as T_{exn} . There are several possibilities.

1. Numeric error codes: $T_{\text{exn}} = \text{Nat}$ (as in C)
2. Error messages: $T_{\text{exn}} = \text{String}$
3. A predefined variant type:

```
 $T_{\text{exn}}$  = <divideByZero:  Unit,  
           overflow:    Unit,  
           fileNotFound: String,  
           fileNotReadable: String,  
           ... >
```

4. An *extensible* variant type (as in OCaml)
5. A *class* of “throwable objects” (as in Java)