

## CIS 419/519: Quiz 4

October 4, 2019

1. We have examples in the form of 10 boolean variables,  $\langle x_1, x_2, \dots, x_{10} \rangle$ , and know the true function  $f(X)$  is in the class of monotone conjunctions. Say we have a “teacher” who knows the true function and must teach the true function through a set of examples; the true function is  $y(X) = x_1 \wedge x_2 \wedge x_3 \wedge x_6$ . What is the minimum number of examples that is required to learn this function?
  - (a) 10
  - (b) 11
  - (c) 5
  - (d) 3

2. Let  $C$  be the finite concept class of all monotone conjunctions with up to 3 boolean variables. We are trying to learn  $f$  where  $f \in C$ . Each example in our training set is of the form  $\langle X \rangle, y$  where  $X = \langle x_1, x_2, x_3 \rangle$ ,  $x_i \in \{1, 0\}$  and  $y \in \{1, 0\}$ . Say we want to use the halving algorithm to reduce the size of consistent concepts in  $C$ ; our first data point is:

$$\langle 0, 1, 0 \rangle, 1$$

Will we make a mistake on this first example? Why?

- (a) Yes we will, because more concepts in  $C$  predict 1 than 0
  - (b) Yes we will, because more concepts in  $C$  predict 0 than 1
  - (c) No we won't, because more concepts in  $C$  predict 1 than 0
  - (d) No we won't, because more concepts in  $C$  predict 0 than 1
3. Suppose we have a weight vector  $w \in R^2$  with input vectors  $x_i \in R^2$  and  $y_i \in \{-1, 1\}$ , let us initialize our 2-dimensional weight vector to be  $w = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ . Also, suppose we only have 2 examples in our dataset:  $(x_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, y_1 = 1)$ ,  $(x_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, y_2 = -1)$ . After training a model based on the Perceptron algorithm on the above dataset over 1 epoch, which option represents the correct final state of the weight vector if the linear threshold function is  $\hat{y} = \text{sgn}\{w^T \cdot x \geq 0\}$ ?

- (a)  $w^T = [-1, -1]$
  - (b)  $w^T = [0, -1]$
  - (c)  $w^T = [0, 0]$
  - (d)  $w^T = [1, 1]$
4. In a mistake-driven algorithm, if we make a mistake on example  $x_i$  with label  $y_i$ , we can be sure that when the weights are updated we will never make a mistake on this same example if we see it again.
- (a) True
  - (b) False
5. Suppose we're using the Averaged Perceptron algorithm. The training data consists of  $m$  examples. Assume that after training for 1 epoch, we've made  $k$  mistakes on the training data. We have accumulated the following weight vectors:  $\{v_1, \dots, v_{k+1}\}$  and their respective consistency counts are  $\{c_1, \dots, c_{k+1}\}$ . Which statement is true?
- (a)  $k > m$
  - (b)  $c_1 > c_2 > \dots > c_{k+1}$  (decreasing from 1 to  $k+1$ )
  - (c)  $c_1 < c_2 < \dots < c_{k+1}$  (increasing from 1 to  $k+1$ )
  - (d) None of the above