Announcements

• HW 5 due **Wednesday, November 16**

• Quiz 10 is due **Thursday, November 17 at 8pm**
Lecture 20: Bayesian Networks

CIS 4190/5190
Fall 2022
Class So Far

• **Supervised Learning**
  • Linear/logistic regression, MLE, decision trees, ensembles, neural networks
  • Application to computer vision, NLP

• **Unsupervised Learning**
  • PCA, K-Means, neural networks
  • Application to NLP

• **Today:** Bayesian networks
  • Very different viewpoint, but concepts are pervasive in ML research
  • Probability as a unifying framework for machine learning
Design Decisions

• **Model family**
  • Flexible architectures
  • **Implicit functions (inference)**
  • Very different from what we’ve seen so far!

• **Optimization algorithm**
  • Typically straightforward
Models So Far

\[ f_\beta(x) \]

\[ x \xrightarrow{f_\beta(x)} y \]

\[ \beta \]
Bayesian Network Inference

\[ x \quad \beta \quad \text{“Inference Algorithm”} \quad y \]
Logic & AI

• Efficient algorithm for logical reasoning was a major focus of early research on artificial intelligence

• **Logical inference problem**
  • Given a set of “facts”, is a given statement true or false?
  • “Facts” can be formalized as a set of logical formulas

• **Example:**
  • **Facts**: All men are mortal. Socrates is a man.
  • **Question**: Is Socrates mortal?
  • **Answer**: Yes!
Logic & AI

• Pure logic is very limited compared to human reasoning

• Example (McDermott 1987):
  • Facts: There is an empty can of soda
  • Question: Did someone drink soda?
  • Answer: Probably!

• Issues
  • Consider the facts “only people drink soda”, “soda cans start out full”
  • These facts often have many exceptions that can typically be ignored
Probabilistic Inference

- **Solution:** Probabilistic inference
  - **Input:** Facts that hold with some probability, desired query
  - **Output:** Probability of query holding

- Use simplified facts but account for the fact that they may be wrong
Probabilistic Inference

• Probabilistic models
  • Probability distribution designed to describe how portion of the world works

\[ P(X_1 = x_1, \ldots, X_n = x_n) \]

• Encode world as set of random variables and their relationships

• Always simplifications (e.g., may not account for every variable, or all dependences between variables)

• Example: “Drinking can of soda” and “can being empty/full”
Probabilistic Inference

• **Probabilistic inference**: Compute distribution of unobserved variables
  • **Example**: Explanation (i.e., observe empty soda can, infer someone drank it)
  • **Example**: Prediction (i.e., observe soda can purchase, infer they will drink it)

• **Problem**: Probabilistic inference is computationally challenging!
  • We won’t address the question of where the facts come from (huge literature on inducing knowledge graphs that aims to solve this problem)
Bayesian Networks

- **Bayesian networks** (Pearl 1985) are a graph-based data structure for representing probability distributions

- Expose structure in the form of dependences between variables that can make probabilistic inference more tractable

- As with neural networks, you can design the model family!
  - Widely used in computer vision and NLP prior to success of deep learning
  - Incorporated into modern neural network architectures (e.g., VAEs)
Bayesian Networks

• **Logic**: Inference is checking if a fact can be deduced from given facts

• **Bayesian network**: Inference is evaluating the probability of a fact given the probabilities of other facts
Random Variables

• A random variable represents a quantity we are uncertain about.

• Random variable takes values in a domain.
  • We will focus on random variables with finite domains.

• Examples:
  • $R =$ Is it raining? ($R \in \{\text{true, false}\}$, which we may write as $\{+r, -r\}$)
  • $T =$ Is it hot or cold? ($T \in \{\text{hot, cold}\}$)
  • $D =$ How long will it take to drive to work? ($D \in [0, \infty)$)
Probability Distributions

• **Probability distribution:** For random variable $X$, $P(X = x) \in [0,1]$ is probability $X$ has value $x$

• **Recall:** Probabilities satisfy $P(X = x) \geq 0$ and $\sum_x P(X = x) = 1$

• **Notation:** When unambiguous, we drop the random variable

\[
\begin{align*}
P(\text{hot}) &= P(T = \text{hot}), \\
P(\text{cold}) &= P(T = \text{cold}), \\
P(\text{rain}) &= P(W = \text{rain}),
\end{align*}
\]
Probability Distributions

• For finite domains, the distribution can be represented as a table

• Examples:

<table>
<thead>
<tr>
<th>$T$</th>
<th>$P(T)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>hot</td>
<td>0.5</td>
</tr>
<tr>
<td>cold</td>
<td>0.5</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>$W$</th>
<th>$P(W)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>sun</td>
<td>0.6</td>
</tr>
<tr>
<td>rain</td>
<td>0.1</td>
</tr>
<tr>
<td>fog</td>
<td>0.3</td>
</tr>
<tr>
<td>meteor</td>
<td>0.0</td>
</tr>
</tbody>
</table>
Joint Distributions

• Given random variables $X_1, \ldots, X_n$, they have a **joint distribution**

\[ P(X_1 = x_1, \ldots, X_n = x_n) \]

• As before, satisfy
  - $P(X_1 = x_1, \ldots, X_n = x_n) \geq 0$
  - $\sum_{(x_1, \ldots, x_n)} P(X_1 = x_1, \ldots, X_n = x_n) = 1$
Joint Distributions

• For finite domains, the distribution can be represented as a table

• Example:

<table>
<thead>
<tr>
<th>$T$</th>
<th>$R$</th>
<th>$P(T,R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>hot</td>
<td>no rain</td>
<td>0.4</td>
</tr>
<tr>
<td>hot</td>
<td>rain</td>
<td>0.1</td>
</tr>
<tr>
<td>cold</td>
<td>no rain</td>
<td>0.2</td>
</tr>
<tr>
<td>cold</td>
<td>rain</td>
<td>0.3</td>
</tr>
</tbody>
</table>
Designing a Probabilistic Model

• Naïve idea
  • Write down the full joint distribution $P(x_1, ..., x_n)$
  • Perform inference using this distribution

• Problem: For $n$ random variables with domain size $|D| = d$, the table representing the joint distribution has $d^n$ entries!
  • Learning and inference are both intractable!

• Is there structure we can exploit to improve tractability?
  • Yes, conditional independence!
Independence

• Two random variables are independent (denoted $X \perp Y$) if

$$\forall x, y . P(x, y) = P(x)P(y)$$

• Here, $P(x) = \sum_y P(x, y)$ is the marginal distribution

• That is, the joint distribution factors into two simpler distributions
Independence

• Example (not independent):

<table>
<thead>
<tr>
<th>$T$</th>
<th>$R$</th>
<th>$P(T, R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>hot</td>
<td>no rain</td>
<td>0.4</td>
</tr>
<tr>
<td>hot</td>
<td>rain</td>
<td>0.1</td>
</tr>
<tr>
<td>cold</td>
<td>no rain</td>
<td>0.2</td>
</tr>
<tr>
<td>cold</td>
<td>rain</td>
<td>0.3</td>
</tr>
</tbody>
</table>
Independence

- Example (independent):

<table>
<thead>
<tr>
<th>$T$</th>
<th>$R$</th>
<th>$P(T, R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>hot</td>
<td>no rain</td>
<td>0.3</td>
</tr>
<tr>
<td>hot</td>
<td>rain</td>
<td>0.2</td>
</tr>
<tr>
<td>cold</td>
<td>no rain</td>
<td>0.3</td>
</tr>
<tr>
<td>cold</td>
<td>rain</td>
<td>0.2</td>
</tr>
</tbody>
</table>

\[
P(T) \times P(R) =
\]

<table>
<thead>
<tr>
<th>$T$</th>
<th>$P(T)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>hot</td>
<td>0.5</td>
</tr>
<tr>
<td>cold</td>
<td>0.5</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>$R$</th>
<th>$P(R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>0.6</td>
</tr>
<tr>
<td>rain</td>
<td>0.4</td>
</tr>
</tbody>
</table>
Independence

• **Example:** Coin flips

\[
\begin{array}{|c|c|}
\hline
X_1 & P(X_1) \\
\hline
\text{heads} & 0.5 \\
\text{tails} & 0.5 \\
\hline
\end{array}
\times \cdots \times
\begin{array}{|c|c|}
\hline
X_n & P(X_n) \\
\hline
\text{heads} & 0.5 \\
\text{tails} & 0.5 \\
\hline
\end{array}
\]

\[
\begin{array}{|c|c|c|c|}
\hline
X_1 & \cdots & X_n & P(X_1, \ldots, X_n) \\
\hline
\text{heads} & \cdots & \text{heads} & 2^{-n} \\
\cdots & \cdots & \cdots & 2^{-n} \\
\hline
\end{array}
\]

\[2^n \text{ rows}\]

Independence can lead to much more compact representations!
Conditional Probabilities

• Conditional probability:

\[ P(x \mid y) = \frac{P(x, y)}{P(y)} \]

• Product rule: \( P(x, y) = P(x \mid y)P(y) \)

• Chain rule: \( P(x_1, \ldots, x_n) = P(x_1)P(x_2 \mid x_1) \cdots P(x_n \mid x_1, \ldots, x_{n-1}) \)
Conditional Probabilities

• Conditional probability:

\[ P(x \mid y) = \frac{P(x, y)}{P(y)} \]

• Product rule: \( P(x, y) = P(x \mid y)P(y) \)

• Chain rule: \( P(x_1, \ldots, x_n) = \prod_{i=1}^{n} P(x_i \mid x_1, \ldots, x_{i-1}) \)

• Note: Independence is equivalently \( \forall x, y \ . \ P(y \mid x) = P(y) \)
Conditional Independence

• Independence **conditioned** on other random variables

• **Example:** \( P(\text{rain, traffic, umbrella}) \)
  - “Having traffic” and “needing an umbrella” are not independent!
  - But if we know there is rain, traffic does not depend on umbrella:

\[
P(+\text{traffic}|+\text{rain, +umbrella}) = P(+\text{traffic}|+\text{rain})
\]

• Similarly for not having rain:

\[
P(+\text{traffic}|-\text{rain, +umbrella}) = P(+\text{traffic}|-\text{rain})
\]
Conditional Independence

• Traffic is *conditionally independent* of umbrella given rain

\[ P(\text{traffic}|\text{rain}, \text{umbrella}) = P(\text{traffic}|\text{rain}) \]

• The following statements are equivalent to the one above:
  • \( P(\text{umbrella}|\text{rain}, \text{traffic}) = P(\text{umbrella}|\text{rain}) \)
  • \( P(\text{traffic}, \text{umbrella}|\text{rain}) = P(\text{traffic}|\text{rain})P(\text{umbrella}|\text{rain}) \)

• Traffic and umbrella are *conditionally independent* given rain
Conditional Independence

- $X$ is **conditionally independent** of $Y$ given $Z_1, \ldots, Z_n$ if

  $\forall x, y, z_1, \ldots, z_n \cdot P(x, y|z_1, \ldots, z_n) = P(x|z_1, \ldots, z_n)P(y|z_1, \ldots, z_n)$

- Equivalently:

  $\forall x, y, z_1, \ldots, z_n \cdot P(x|z_1, \ldots, z_n, y) = P(x|z_1, \ldots, z_n)$

- Denoted $X \perp Y \mid Z_1, \ldots, Z_n$
Designing a Probabilistic Model

• **Idea:** Restrict to joint distributions with given independence relations
  - Posit set of conditional independence relationships $X_i \perp X_j \mid \{X_k\}$
  - Only learn joint distributions $P(x_1, \ldots, x_n)$ that satisfy these relationships
  - **Intuition:** Conditional independences define “local” distributions that are chained together to form “global” distribution

• This is the approach taken by **Bayesian networks**
  - **Note on terminology:** Special kind of **graphical model**

• Rarely have exact independence, but useful modeling assumption
Bayesian Networks

• Represent conditional independences via a directed acyclic graph

• **Nodes/vertices:** Variables \( \{(X_k, D_k)\} \) (and their domains)

• **Arcs/edges:** Encode parameter structure
  • **Parameters:** Distribution of each \( X_i \) given its parents
Example: Coin Flips

<table>
<thead>
<tr>
<th>$X_1$</th>
<th>$P(X_1)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>heads</td>
<td>0.5</td>
</tr>
<tr>
<td>tails</td>
<td>0.5</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>$X_n$</th>
<th>$P(X_n)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>heads</td>
<td>0.5</td>
</tr>
<tr>
<td>tails</td>
<td>0.5</td>
</tr>
</tbody>
</table>

no interactions $\rightarrow$ all random variables are independent
Example: Weather

Rain

Traffic
Parameters

• Conditional probabilities of node given parents:

\[ \theta_{i,x_1,...,x_{k_i},x} = P(X_i = x \mid X_{i_1} = x_1, ..., X_{i_k} = x_{k_i}) \]

• Here, \( x_i \in D_i \) is in the domain of \( X_i \)
Example: Weather

<table>
<thead>
<tr>
<th>R</th>
<th>$P(R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>0.6</td>
</tr>
<tr>
<td>rain</td>
<td>0.4</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>R</th>
<th>$T$</th>
<th>$P(T \mid R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>no traffic</td>
<td>0.75</td>
</tr>
<tr>
<td>no rain</td>
<td>traffic</td>
<td>0.25</td>
</tr>
<tr>
<td>rain</td>
<td>no traffic</td>
<td>0.25</td>
</tr>
<tr>
<td>rain</td>
<td>traffic</td>
<td>0.75</td>
</tr>
</tbody>
</table>
Example: Weather

<table>
<thead>
<tr>
<th>$R$</th>
<th>$P(R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>0.6</td>
</tr>
<tr>
<td>rain</td>
<td>0.4</td>
</tr>
</tbody>
</table>

$P(R,T) = P(T \mid R)P(R)$
Example: Weather

<table>
<thead>
<tr>
<th>$R$</th>
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</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
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</tr>
<tr>
<td>rain</td>
<td>0.4</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>$R$</th>
<th>$T$</th>
<th>$P(T \mid R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>no traffic</td>
<td>0.75</td>
</tr>
<tr>
<td>no rain</td>
<td>traffic</td>
<td>0.25</td>
</tr>
<tr>
<td>rain</td>
<td>no traffic</td>
<td>0.25</td>
</tr>
<tr>
<td>rain</td>
<td>traffic</td>
<td>0.75</td>
</tr>
</tbody>
</table>

$P(R, T) = P(T \mid R)P(R)$
Example: Weather

<table>
<thead>
<tr>
<th>$R$</th>
<th>$P(R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>0.6</td>
</tr>
<tr>
<td>rain</td>
<td>0.4</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>$R$</th>
<th>$T$</th>
<th>$P(T \mid R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>no traffic</td>
<td>0.75</td>
</tr>
<tr>
<td>no rain</td>
<td>traffic</td>
<td>0.25</td>
</tr>
<tr>
<td>rain</td>
<td>no traffic</td>
<td>0.25</td>
</tr>
<tr>
<td>rain</td>
<td>traffic</td>
<td>0.75</td>
</tr>
</tbody>
</table>

$P(R,T) = P(T \mid R)P(R)$
Example: Weather

\[
P(R, T) = P(T | R) P(R)
\]

| \( R \) | \( T \) | \( P(T | R) \) |
|--------|--------|-------------|
| no rain | no traffic | 0.75        |
| no rain | traffic    | 0.25        |
| rain    | no traffic | 0.25        |
| rain    | traffic    | 0.75        |

<table>
<thead>
<tr>
<th>( R )</th>
<th>( T )</th>
<th>( P(R, T) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>no traffic</td>
<td>0.45</td>
</tr>
<tr>
<td>no rain</td>
<td>traffic</td>
<td>0.15</td>
</tr>
<tr>
<td>rain</td>
<td>no traffic</td>
<td>0.1</td>
</tr>
</tbody>
</table>

\( P(R) \) and \( P(T | R) \) are the probabilities for rain and traffic, respectively.
Example: Weather

\[
P(R, T) = P(T | R)P(R)
\]
Example: Weather

<table>
<thead>
<tr>
<th>$R$</th>
<th>$P(R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>0.6</td>
</tr>
<tr>
<td>rain</td>
<td>0.4</td>
</tr>
</tbody>
</table>

| $R$       | $T$        | $P(T | R)$ |
|-----------|------------|-----------|
| no rain   | no traffic | 0.75      |
| no rain   | traffic    | 0.25      |
| rain      | no traffic | 0.25      |
| rain      | traffic    | 0.75      |

$$P(R,T) = P(T | R) P(R)$$
Summary

• **Bayesian network**
  • Nodes represent random variables
  • Edges encode conditional independences
  • For each node, parameters at that node encode probability distribution of node conditioned on its parents

• **Edge directions**
  • Determines parameters
  • Often encode intuitive notion of causality (can be formalized)
Summary

• Any joint distribution satisfying the conditional independencies can be expressed as product of \( P(X_i = x_i \mid \text{parents}(X_i) = (x_{i_1}, \ldots, x_{i_k})) \)

• We can compute the corresponding joint distribution using chain rule:

\[
P(x_1, \ldots, x_n) = \prod_{i=1}^{n} P(X_i = x_i \mid (X_1, \ldots, X_{i-1}) = (x_1, \ldots, x_{i-1})) \\
= \prod_{i=1}^{n} P(X_i = x_i \mid \text{parents}(X_i) = (x_{i_1}, \ldots, x_{i_k}))
\]

• First equality holds for any distribution by chain rule
• Second equality holds by assumption (assumes topological order)
Example: More Complex Traffic Model

• Variables:
  • Low pressure ($L$)
  • Rain ($R$)
  • Traffic ($T$)
  • Roof damage ($D$)
  • Ballgame ($B$)
  • Mood ($M$)
Example

\[ P(L, B, R, T, D, M) = \]
\[ P(L) \]
\[ P(B) \]
\[ P(R | L) \]
\[ P(T | R, B) \]
\[ P(D | R, T) \]
\[ P(M | B, D) \]
Example: Insurance
Queries on Bayesian Networks

• Which variables are conditionally independent?
  • For any values of the parameters
  • Called d-separation

• What is the most likely assignment, i.e., \( \max_{x_1, \ldots, x_n} P(x_1, \ldots, x_n) \)?
  • Called maximum a posteriori (MAP) inference

• What is the conditional distribution \( P(X_i \mid X_{i_1} = x_{i_1}, \ldots, X_{i_k} = x_{i_k}) \)?
  • For any \( X_i \) and any \( X_{i_1} = x_{i_1}, \ldots, X_{i_k} = x_{i_k} \)
  • Called marginal inference
Queries on Bayesian Networks

• Which variables are conditionally independent?
  • For any values of the parameters
  • Called d-separation

• What is the most likely assignment, i.e., \( \max_{x_1, \ldots, x_n} P(x_1, \ldots, x_n) \)?
  • Called maximum a posteriori (MAP) inference

• What is the conditional distribution \( P(X_i \mid X_{i_1} = x_{i_1}, \ldots, X_{i_k} = x_{i_k}) \)?
  • For any \( X_i \) and any \( X_{i_1} = x_{i_1}, \ldots, X_{i_k} = x_{i_k} \)
  • Called marginal inference
D-Separation Strategy

• **Step 1:** Look at three special cases
  • Causal chain
  • Common cause
  • Common effect

• **Step 2:** Piece them together
Causal Chain

• \( X \rightarrow Y \rightarrow Z \)

• Is \( X \perp Z? \) **Not necessarily**
  - E.g., Rain = Pressure and Traffic = Rain

• Is \( X \perp Z \mid Y? \) **Yes**
  - \( P(z \mid x, y) = \frac{P(x,y,z)}{P(x,y)} = \frac{P(x)P(y|x)P(z|y)}{P(x)P(y|x)} = P(z \mid y) \)
Common Cause

• $X \leftarrow Y \rightarrow Z$

• Is $X \perp Z$? Not necessarily
  • E.g., Traffic $=$ Rain and Damage $=$ Rain

• Is $X \perp Z \mid Y$? Yes
  • $P(z \mid x, y) = \frac{P(x, z, y)}{P(x, y)}$
    $= \frac{P(x)P(x \mid y)P(z \mid y)}{P(x)P(x \mid y)} = P(z \mid y)$
Common Effect

• $X \rightarrow Y \leftarrow Z$

• Is $X \perp Z$? Yes
  - Proof left as exercise

• Is $X \perp Z \mid Y$? Not necessarily
  - E.g., for $Y = X \oplus Z$ (XOR), then if $Y = \text{False}$, then $X = \neg Z$
  - Example: Medical diagnosis

• Observation “activates” path
General Case

• **Query:** For a general Bayesian network, is $X \perp Y \mid Z_1, \ldots, Z_k$?

• **Algorithm**
  • Look for paths from $X$ to $Y$
  • Segment $A \rightarrow B \rightarrow C$ only “active” (from previous three cases, see next slide)

• If there are no paths from $X$ to $Y$ such that all segments are active, then $X \perp Y \mid Z_1, \ldots, Z_k$
  • Otherwise, conditional independence is not guaranteed
General Case

• Causal chain
  • \( A \to B \to C \)
  • Active iff \( B \notin \{Z_i\} \)

• Common cause
  • \( A \leftarrow B \to C \)
  • Active iff \( B \notin \{Z_i\} \)

• Common effect
  • \( A \to B \leftarrow C \)
  • Active iff \( B \in \{Z_i\} \) (or descendant \( \in \{Z_i\} \))
Example

• **Query:** Is $L \perp M$?
  • No, $L \rightarrow R \rightarrow D \rightarrow M$

• **Query:** Is $L \perp B$?
  • Yes!
  • $L \rightarrow R \rightarrow T \leftarrow B$
  • $L \rightarrow R \rightarrow D \leftarrow T \leftarrow B$
  • $L \rightarrow R \rightarrow D \rightarrow M \leftarrow B$

• **Note:** If we observe $T$, $D$, or $M$, breaks independence
  • None of $L \perp B \mid T$, $L \perp B \mid D$, and $L \perp B \mid M$ hold
Queries on Bayesian Networks

• Which variables are conditionally independent?
  • For any values of the parameters
  • Called d-separation

• What is the most likely assignment, i.e., $\max_{x_1, \ldots, x_n} P(x_1, \ldots, x_n)$?
  • Called maximum a posteriori (MAP) inference

• What is the conditional distribution $P(X_i \mid X_{i_1} = x_{i_1}, \ldots, X_{i_k} = x_{i_k})$?
  • For any $X_i$ and any $X_{i_1} = x_{i_1}, \ldots, X_{i_k} = x_{i_k}$
  • Called marginal inference
Marginal Inference

• **Input:**
  - Evidentiary variables: $E_1 = e_1, \ldots, E_k = e_k$ (features)
  - Query variable: $Q$ (label)
  - Hidden variables: $H_1, \ldots, H_m$ (all remaining, “latent” variables)

• **Goal:** For each $q$, compute

$$P(Q = q \mid E_1 = e_1, \ldots, E_k = e_k)$$

• **Equivalently:** Likelihood $p(y \mid x)$
Enumerative Algorithm

• **Step 1:** Construct table for joint distribution $P(q, h_1, \ldots, h_m, e_1, \ldots, e_k)$

• **Step 2:** Select rows consistent with evidence
  
  - i.e., $P(q, h_1, \ldots, h_m, e_1, \ldots, e_k)$ for some $h_1, \ldots, h_m$

• **Step 3:** Sum out hidden variables and normalize:

  $$P(Q = q \mid e_1, \ldots, e_k) = \frac{1}{Z} \sum_{h_1,\ldots,h_h} P(q, h_1, \ldots, h_m, e_1, \ldots, e_k)$$

  • Normalizing constant $Z = \sum_{q,h_1,\ldots,h_h} P(q, h_1, \ldots, h_m, e_1, \ldots, e_k)$
**Step 1: Construct Joint Distribution**

### Rain

<table>
<thead>
<tr>
<th>R</th>
<th>P(R)</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>0.6</td>
</tr>
<tr>
<td>rain</td>
<td>0.4</td>
</tr>
</tbody>
</table>

### Traffic

| R   | T                | P(T | R) |
|-----|------------------|-------|
| no rain | no traffic   | 0.75  |
| no rain | traffic       | 0.25  |
| rain     | no traffic   | 0.25  |
| rain     | traffic      | 0.75  |

\[
P(R, T) = P(T | R)P(R)
\]

**Query: \( P(R | \text{traffic}) \)**
Step 2: Select Rows

<table>
<thead>
<tr>
<th>$R$</th>
<th>$T$</th>
<th>$P(R, T)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>no traffic</td>
<td>0.45</td>
</tr>
<tr>
<td>no rain</td>
<td>traffic</td>
<td>0.15</td>
</tr>
<tr>
<td>rain</td>
<td>no traffic</td>
<td>0.1</td>
</tr>
<tr>
<td>rain</td>
<td>traffic</td>
<td>0.3</td>
</tr>
</tbody>
</table>

Query: $P(R \mid \text{traffic})$
Step 2: Select Rows

<table>
<thead>
<tr>
<th>$R$</th>
<th>$T$</th>
<th>$P(R, T)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>no traffic</td>
<td>0.45</td>
</tr>
<tr>
<td>no rain</td>
<td>traffic</td>
<td>0.15</td>
</tr>
<tr>
<td>rain</td>
<td>no traffic</td>
<td>0.1</td>
</tr>
<tr>
<td>rain</td>
<td>traffic</td>
<td>0.3</td>
</tr>
</tbody>
</table>

Query: $P(R \mid \text{traffic})$
Step 3: Sum and Normalize

<table>
<thead>
<tr>
<th></th>
<th></th>
<th>( P(R, T) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>no rain</td>
<td>no traffic</td>
<td>0.45</td>
</tr>
<tr>
<td>no rain</td>
<td>traffic</td>
<td>0.15</td>
</tr>
<tr>
<td>rain</td>
<td>no traffic</td>
<td>0.1</td>
</tr>
<tr>
<td>rain</td>
<td>traffic</td>
<td>0.3</td>
</tr>
</tbody>
</table>

\[
P(\text{rain} \mid \text{traffic}) = \frac{0.15}{0.3+0.15} = \frac{1}{3}
\]

\[
P(\text{no rain} \mid \text{traffic}) = \frac{0.3}{0.3+0.15} = \frac{2}{3}
\]

Query: \( P(R \mid \text{traffic}) \)
Enumerative Algorithm

• Constructing the joint distribution is very computationally expensive!

• NP hard in general, but we can do better in practice

• **Idea:** Marginalize hidden variables before the end
Factors and Operations

• **Factor:** A table encoding a distribution \( P(x_1, \ldots, x_k \mid y_1, \ldots, y_h) \)
  • In general, we denote factors by \( \phi(z_1, \ldots, z_m) \)

• **Join:** Given \( \phi(x_1, \ldots, x_k, y_1, \ldots, y_m) \) and \( \phi(x_1, \ldots, x_k, z_1, \ldots, z_n) \) output
  \[
  \phi(x_1, \ldots, x_k, y_1, \ldots, y_m, z_1, \ldots, z_n) = \phi(x_1, \ldots, x_k, y_1, \ldots, y_m)\phi(x_1, \ldots, x_k, z_1, \ldots, z_n)
  \]

• **Eliminate:** Given \( \phi(x, y_1, \ldots, y_k) \) output
  \[
  \phi(y_1, \ldots, y_k) = \sum_x \phi(x, y_1, \ldots, y_k)
  \]
Enumerative Algorithm

• **Step 0:** Initial factors are $P(X_i \mid \text{parents}(X_i))$ for each node $X_i$
  • Immediately drop rows conditioned on evidentiary variables

• **Step 1:** Join all factors

• **Step 2:** Eliminate all hidden variables

• **Output:** Remaining factor is $P(Q, e_1, ..., e_k)$, which can be normalized
Example Query

\[ P(R) \]
\[
\begin{array}{c|c}
+r & 0.1 \\
-r & 0.9 \\
\end{array}
\]

\[ P(T | R) \]
\[
\begin{array}{c|cc}
+r & +t & 0.8 \\
+r & -t & 0.2 \\
-r & +t & 0.1 \\
-r & -t & 0.9 \\
\end{array}
\]

\[ P(L | T) \]
\[
\begin{array}{c|cc}
+t & +l & 0.3 \\
+t & -l & 0.7 \\
-t & +l & 0.1 \\
-t & -l & 0.9 \\
\end{array}
\]

Query: \[ P(L) \]
Step 0: Initial Factors

\[
P(R) = \begin{array}{c|c}
+r & 0.1 \\
-r & 0.9 \\
\end{array}
\quad P(T \mid R) = \begin{array}{c|c|c}
+r & +t & 0.8 \\
+r & -t & 0.2 \\
-r & +t & 0.1 \\
-r & -t & 0.9 \\
\end{array}
\quad P(L \mid T) = \begin{array}{c|c|c}
+t & +l & 0.3 \\
+t & -l & 0.7 \\
-t & +l & 0.1 \\
-t & -l & 0.9 \\
\end{array}
\]
Step 1: Join All Factors

### $P(R)$

<table>
<thead>
<tr>
<th>$r$</th>
<th>0.1</th>
</tr>
</thead>
<tbody>
<tr>
<td>$-r$</td>
<td>0.9</td>
</tr>
</tbody>
</table>

### $P(T | R)$

<table>
<thead>
<tr>
<th>$r$</th>
<th>$t$</th>
<th>0.8</th>
</tr>
</thead>
<tbody>
<tr>
<td>$+r$</td>
<td>$+t$</td>
<td>0.2</td>
</tr>
<tr>
<td>$-r$</td>
<td>$+t$</td>
<td>0.1</td>
</tr>
<tr>
<td>$-r$</td>
<td>$-t$</td>
<td>0.9</td>
</tr>
</tbody>
</table>

### $P(R, T) = P(T | R)P(R)$

<table>
<thead>
<tr>
<th>$r$</th>
<th>$t$</th>
<th>0.08</th>
</tr>
</thead>
<tbody>
<tr>
<td>$+r$</td>
<td>$+t$</td>
<td>0.02</td>
</tr>
<tr>
<td>$+r$</td>
<td>$-t$</td>
<td>0.09</td>
</tr>
<tr>
<td>$-r$</td>
<td>$-t$</td>
<td>0.81</td>
</tr>
</tbody>
</table>

### $P(R, T, L) = P(L | T)P(R, T)$

<table>
<thead>
<tr>
<th>$r$</th>
<th>$t$</th>
<th>$l$</th>
<th>0.024</th>
</tr>
</thead>
<tbody>
<tr>
<td>$+r$</td>
<td>$+t$</td>
<td>$+l$</td>
<td>0.056</td>
</tr>
<tr>
<td>$+r$</td>
<td>$-t$</td>
<td>$+l$</td>
<td>0.002</td>
</tr>
<tr>
<td>$+r$</td>
<td>$-t$</td>
<td>$-l$</td>
<td>0.018</td>
</tr>
<tr>
<td>$-r$</td>
<td>$+t$</td>
<td>$+l$</td>
<td>0.027</td>
</tr>
<tr>
<td>$-r$</td>
<td>$+t$</td>
<td>$-l$</td>
<td>0.063</td>
</tr>
<tr>
<td>$-r$</td>
<td>$-t$</td>
<td>$+l$</td>
<td>0.081</td>
</tr>
<tr>
<td>$-r$</td>
<td>$-t$</td>
<td>$-l$</td>
<td>0.729</td>
</tr>
</tbody>
</table>
Step 2: Eliminate Hidden Variables

\[ P(R, T, L) \]

<table>
<thead>
<tr>
<th></th>
<th>+t</th>
<th>+l</th>
<th>0.024</th>
</tr>
</thead>
<tbody>
<tr>
<td>+r</td>
<td>+t</td>
<td>-l</td>
<td>0.056</td>
</tr>
<tr>
<td>+r</td>
<td>-t</td>
<td>+l</td>
<td>0.002</td>
</tr>
<tr>
<td>+r</td>
<td>-t</td>
<td>-l</td>
<td>0.018</td>
</tr>
<tr>
<td>-r</td>
<td>+t</td>
<td>+l</td>
<td>0.027</td>
</tr>
<tr>
<td>-r</td>
<td>+t</td>
<td>-l</td>
<td>0.063</td>
</tr>
<tr>
<td>-r</td>
<td>-t</td>
<td>+l</td>
<td>0.081</td>
</tr>
<tr>
<td>-r</td>
<td>-t</td>
<td>-l</td>
<td>0.729</td>
</tr>
</tbody>
</table>

\[ P(T, L) = \sum_r P(R, T, L) \]

<table>
<thead>
<tr>
<th></th>
<th>+t</th>
<th>+l</th>
<th>0.051</th>
</tr>
</thead>
<tbody>
<tr>
<td>+t</td>
<td>-l</td>
<td>0.119</td>
<td></td>
</tr>
<tr>
<td>-t</td>
<td>+l</td>
<td>0.083</td>
<td></td>
</tr>
<tr>
<td>-t</td>
<td>-l</td>
<td>0.747</td>
<td></td>
</tr>
</tbody>
</table>

\[ P(L) = \sum_t P(T, L) \]

<table>
<thead>
<tr>
<th></th>
<th>+l</th>
<th>0.134</th>
</tr>
</thead>
<tbody>
<tr>
<td>-l</td>
<td>0.886</td>
<td></td>
</tr>
</tbody>
</table>
Variable Elimination Strategy

\[ P(R) = \begin{array}{c|c}
+r & 0.1 \\
-r & 0.9 \\
\end{array} \]

\[ P(R, T) = P(T \mid R) P(R) \]

\[ P(T \mid R) = \begin{array}{c|cc}
+r & +t & 0.8 \\
+r & -t & 0.2 \\
-r & +t & 0.1 \\
-r & -t & 0.9 \\
\end{array} \]

\[ P(T) = \sum_r P(R, T) \]

\[ P(T, L) = P(L \mid T) P(T) \]

\[ P(L \mid T) = \begin{array}{c|cc}
+t & +l & 0.3 \\
+t & -l & 0.7 \\
-t & +l & 0.1 \\
-t & -l & 0.9 \\
\end{array} \]

\[ P(T) = \begin{array}{c|c}
+t & 0.17 \\
-t & 0.83 \\
\end{array} \]

\[ P(L) = \sum_t P(L, T) \]

\[ P(L) = \begin{array}{c|c}
+l & 0.134 \\
-l & 0.866 \\
\end{array} \]
Variable Elimination Strategy

- Initially, we have variables R, T, and L.
- We eliminate variable R, leaving us with T and L.
- Next, we eliminate variable T, resulting in L.
- Finally, we have the simplified expression L.
What about evidence?

- When there are evidentiary variables, select those rows first

<table>
<thead>
<tr>
<th></th>
<th>$P(R)$</th>
<th>$P(T \mid R)$</th>
<th>$P(L \mid T)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>+r</td>
<td>0.1</td>
<td>+t 0.8</td>
<td>+l 0.3</td>
</tr>
<tr>
<td>-r</td>
<td>0.9</td>
<td>-t 0.2</td>
<td>-l 0.7</td>
</tr>
</tbody>
</table>

$P(+r)$

<table>
<thead>
<tr>
<th></th>
<th>$P(+r)$</th>
<th>$P(T \mid +r)$</th>
<th>$P(L \mid T)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>+r</td>
<td>0.1</td>
<td>+t 0.8</td>
<td>+l 0.3</td>
</tr>
<tr>
<td>+r</td>
<td>-t 0.2</td>
<td>+l 0.7</td>
<td></td>
</tr>
</tbody>
</table>

Query: $P(L \mid +r)$
What about evidence?

• At the end, obtain an unnormalized distribution, which we normalize

\[
P(+r, L) = 0.026
\]

\[
P(+r, -l) = 0.074
\]

\[
P(-l, L) = 0.26
\]

\[
P(-l, -l) = 0.74
\]

Query: \( P(L \mid +r) \)
Alternative View

\[ P(\ell) = \sum_t \sum_r P(\ell | t)P(r)P(t | r) \]

join on \( r \)

join on \( t \)

eliminate \( r \)

eliminate \( t \)

Enumeration

\[ P(\ell) = \sum_t P(\ell | t) \sum_r P(r)P(t | r) \]

join on \( r \)

eliminate \( r \)

join on \( t \)

eliminate \( t \)

Variable Elimination
General Variable Elimination Strategy

• **Step 0:** Initial factors are $P(X_i \mid \text{parents}(X_i))$ for each node $X_i$
  - Immediately drop rows conditioned on evidentiary variables

• **Step 1:** For each $H_i$:
  • **Step 1a:** Join all factors containing $H_i$
  • **Step 1b:** Eliminate $H_i$

• **Output:** Join all remaining factors and normalize
Variable Elimination Order

• **Query:** \( P(X_n \mid y_1, \ldots, y_n) \)

• Eliminating \( Z \) first results in factor of size \( 2^{n+1} \)

• Eliminating \( X_1, \ldots, X_{n-1} \) first results in factors of size 2
Variable Elimination Order

• Order in which hidden variables are eliminated can greatly affect performance (e.g., exponential vs. constant)

• May not exist an efficient ordering (problem is NP hard in general)

• Computing optimal ordering is also NP hard
Learning Bayesian Networks

• **Supervised learning**
  • Features $x$ are evidentiary variables
  • Label $y$ is query variable
  • Parameters are the conditional probabilities
  • Marginal inference evaluates likelihood $p(y \mid x)$

• How to learn the parameters?
Maximum Likelihood Learning

• Minimize the NLL:

\[ \hat{\theta} = \arg \min_{\theta} \sum_{i=1}^{n} \sum_{j=1}^{d} \log P_{\theta}(X_j = x_{i,j} \mid \text{parents}(X_j) = (x_{i,k_1}, \ldots, x_{i,k_j})) \]

• Can use gradient descent to optimize
  • There is a nice formula for the gradient
Simplest Example: Naïve Bayes

• Model:

\[ P(Y, X_1 \ldots, X_n) = P(Y) \prod_{i=1}^{n} P(X_i \mid Y) \]

• If \( Y \) has domain \( D_Y \) and \( X_i \) has domain \( D_X \), then \( n \cdot |D_X| \cdot |D_Y| \) parameters
Inference in Naïve Bayes

• **Step 1:** For each $y \in D_Y$, compute joint probability distribution

\[
P(y, x_1, ..., x_n) = P(y) \prod_{i=1}^{n} P(x_i \mid y)
\]

• **Step 2:** Normalize distribution:

\[
P(y \mid x_1, ..., x_n) = \frac{P(y, x_1, ..., x_n)}{Z}
\]

• Here, $Z = \sum_{y' \in D_Y} P(y', x_1, ..., x_n)$
Naïve Bayes for Spam Detection

• Bag of words model

• Parameter sharing via “tied” distribution: For all $i, j$, constrain

$$P(X_i = x \mid Y) = P(X_j = x \mid Y)$$

• Encodes invariant structure in bag of words models
Naïve Bayes for Spam Detection

<table>
<thead>
<tr>
<th>$P(y)$</th>
<th>$P(x \mid \text{spam})$</th>
<th>$P(x \mid \text{not spam})$</th>
</tr>
</thead>
<tbody>
<tr>
<td>not spam: 0.66</td>
<td>the: 0.0156</td>
<td>the: 0.0210</td>
</tr>
<tr>
<td>spam: 0.33</td>
<td>to: 0.0153</td>
<td>to: 0.0133</td>
</tr>
<tr>
<td></td>
<td>and: 0.0115</td>
<td>and: 0.0105</td>
</tr>
<tr>
<td></td>
<td>of: 0.0095</td>
<td>of: 0.0119</td>
</tr>
<tr>
<td></td>
<td>you: 0.0093</td>
<td>2002: 0.0110</td>
</tr>
<tr>
<td></td>
<td>a: 0.0086</td>
<td>with: 0.0108</td>
</tr>
<tr>
<td></td>
<td>with: 0.0080</td>
<td>from: 0.0107</td>
</tr>
<tr>
<td></td>
<td>from: 0.0075</td>
<td>and: 0.0105</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td>a: 0.0100</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td>...</td>
</tr>
</tbody>
</table>
Maximum Likelihood Learning

- Minimize the NLL for Naïve Bayes for text:

\[
\hat{\theta} = \operatorname*{arg\,min}_{\theta} \sum_{i=1}^{n} \left\{ \log P_{\theta}(y_i) + \log \sum_{j=1}^{d} P_{\theta}(x_{i,j} \mid y_i) \right\}
\]

- Can show that parameters are counts:

\[
P_{\theta}(x \mid y) = \frac{\sum_{i=1}^{n} \sum_{j=1}^{d} 1(y_i = y \land x_{i,j} = x)}{\sum_{i=1}^{n} \sum_{j=1}^{d} 1(y_i = y)}
\]
Maximum Likelihood Learning

• Can overfit
  • If a word never occurs in the training dataset, probabilities are all undefined

• Regularization via **Laplace smoothing**
  • Assume each word occurs $k$ extra times in the dataset (increase counts by $k$)

$$P_\theta(x \mid y) = \frac{k + \sum_{i=1}^{n} \sum_{j=1}^{d} 1(y_i = y \land x_{i,j} = x)}{k \cdot d + \sum_{i=1}^{n} \sum_{j=1}^{d} 1(y_i = y)}$$

  • Can be interpreted as a prior on $\theta$ (in particular, the Dirichlet prior)
Example: Works Well

Recipients

Send me the money right away

??????,

???????? ! ???? ??????, wire the money! ???????

????? ??????

Prince ??????
Example: Works Poorly

I wanted to love XXXXX, but I couldn't.

I wanted to love XXXXX, and I did!
Reasoning Through Time

• One strength of the framework is for modeling time varying processes
  • E.g., use (partial) measurements of factors to estimate future crop yield
Hidden Markov Model

• Speech recognition, machine translation, object tracking

We want a model of sequences $y$ and observations $x$

$$p(x_1 \ldots x_n, y_1 \ldots y_n) = q(\text{STOP}|y_n) \prod_{i=1}^{n} q(y_i|y_{i-1}) e(x_i|y_i)$$

where $y_0=\text{START}$ and we call $q(y_i|y_{i-1})$ the transition distribution and $e(x_i|y_i)$ the emission (or observation) distribution.