

ESE 531: Digital Signal Processing

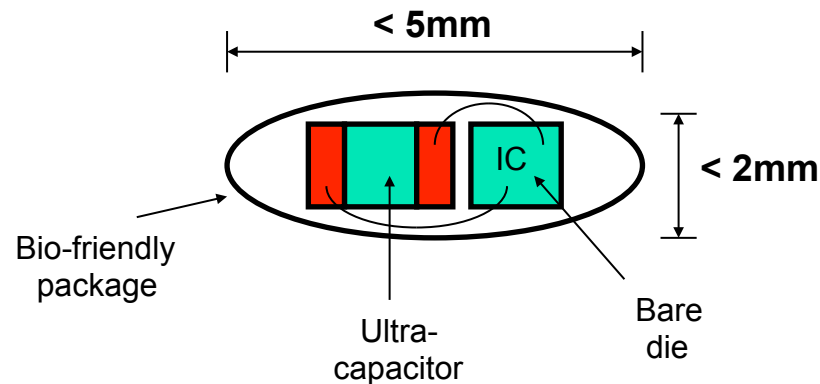
Lec 1: January 12, 2017
Introduction and Overview



Where I come from

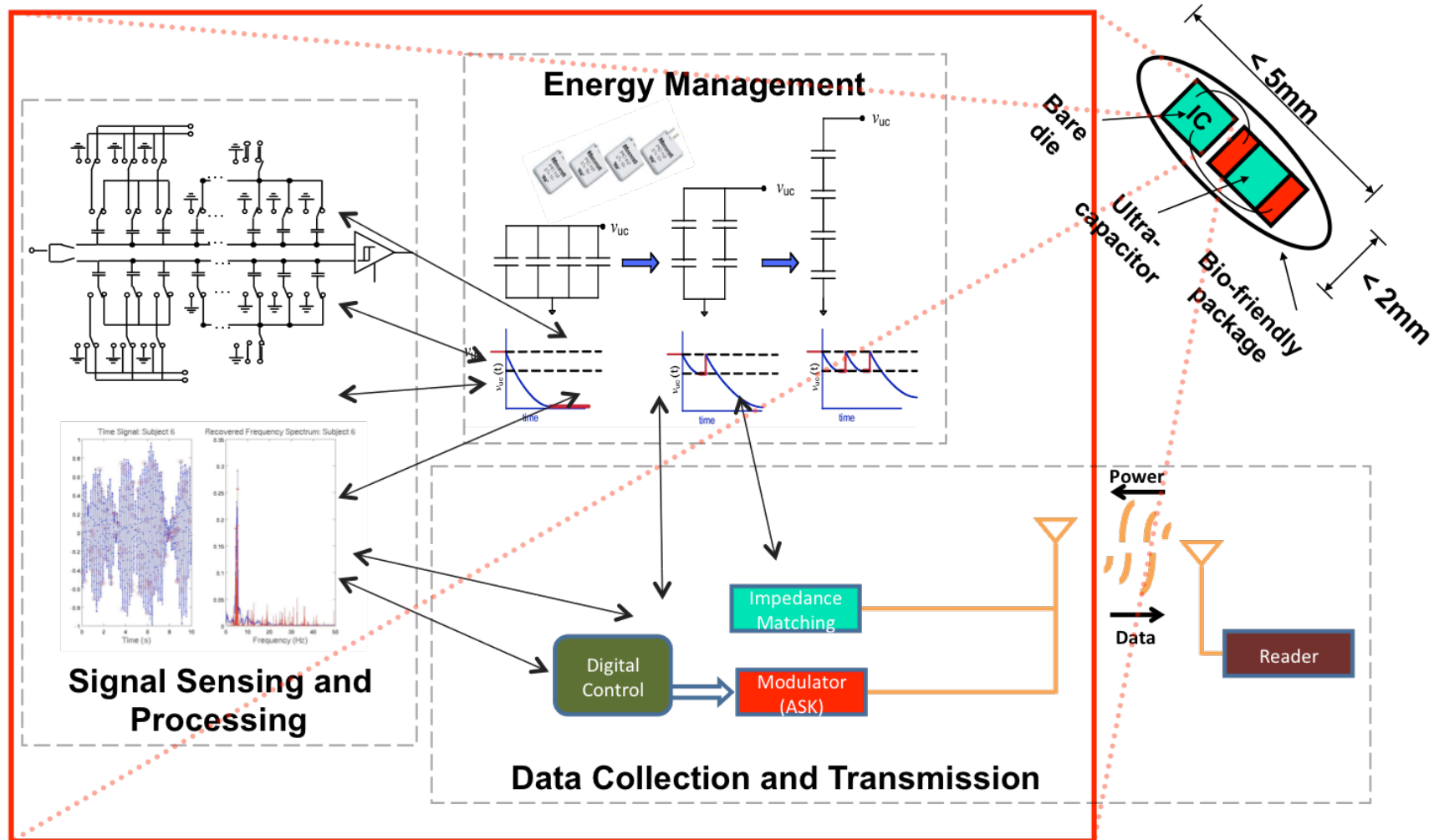
- ❑ Analog VLSI Circuit Design
- ❑ Convex Optimization
 - System Hierarchical Optimization
- ❑ Biomedical Electronics
- ❑ Biometric Data Acquisition
 - Compressive Sampling
- ❑ ADC Design
 - SAR, Pipeline, Delta-Sigma
- ❑ Low Energy Circuits
 - Adiabatic Charging

Minimally Invasive Implant to Combat Healthcare Noncompliance



- ❑ Model for implants: reconfigurable RFID tags that continuously record specific biometric
 - During the read operation, energy storage element is recharged
- ❑ Size of package small enough to allow injection
- ❑ Actigraphy expected to be clinically useful
 - Platform allows for any sensor that gathers information on a slow time scale

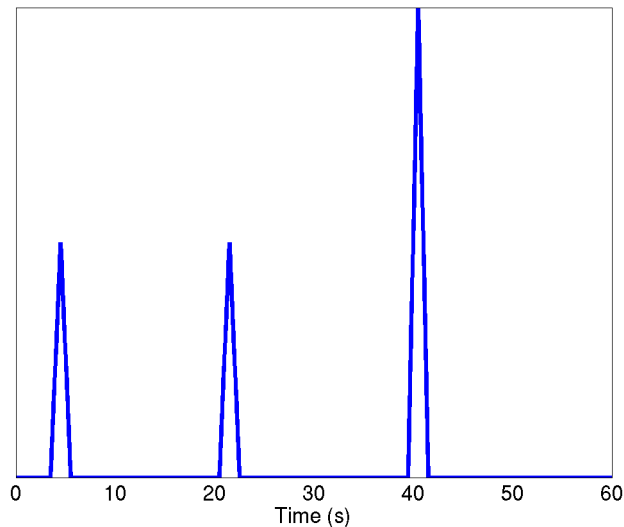
MicroImplant: An Electronic Platform for Minimally Invasive Sensory Monitors



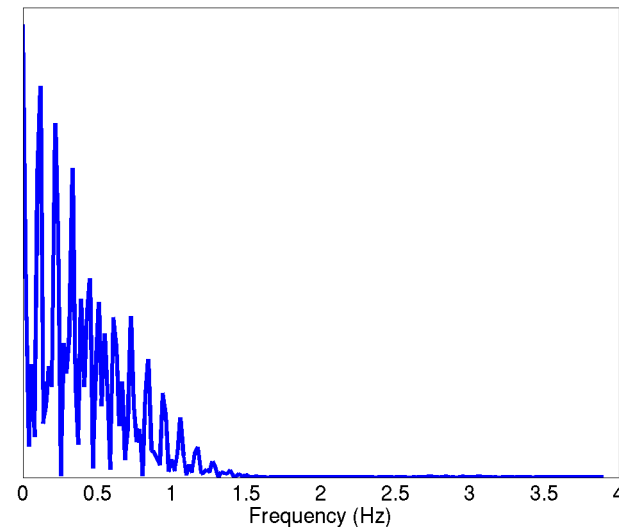
Compressive Sampling

- ❑ Sample at lower than the Nyquist rate and still accurately recover the signal, and in some cases exactly recover

Sparse signal in time

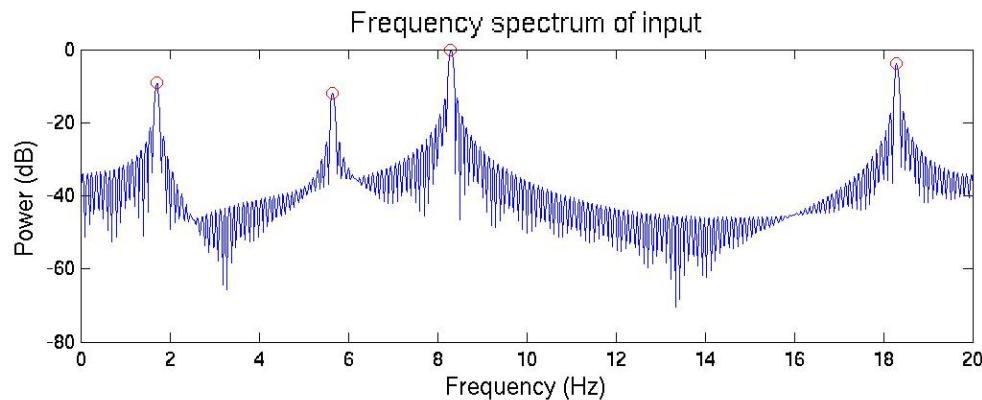
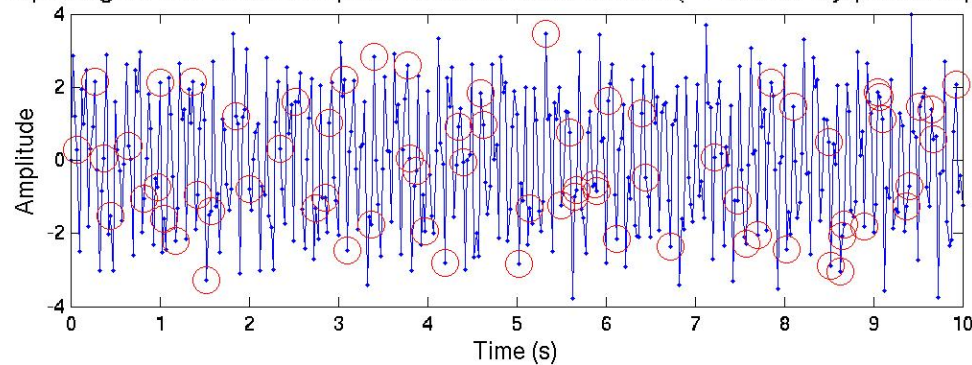


Frequency spectrum



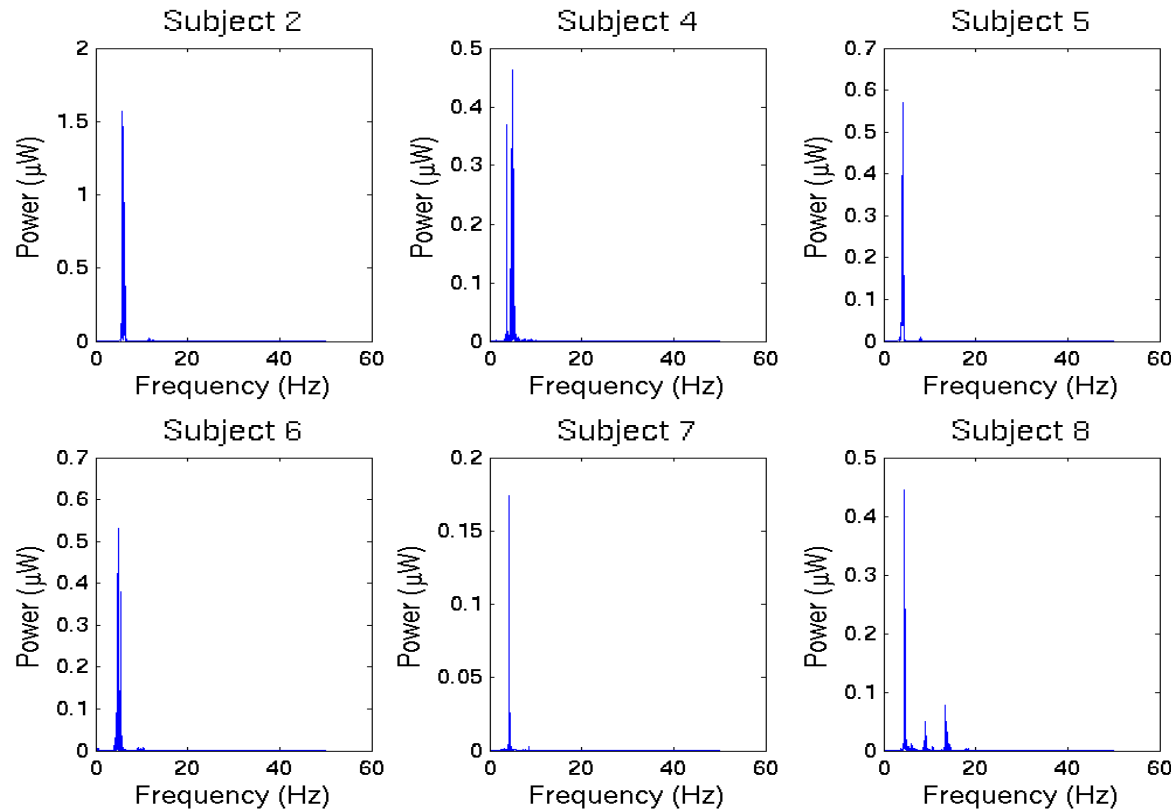
Example: Sum of Sinusoids

Input signal with undersampled measurements circled ($\sim 17.5\%$ of Nyquist samples)



- Sense signal randomly M times
 - $M > C \cdot \mu^2(\Phi, \Psi) \cdot S \cdot \log N$
- Recover with linear program

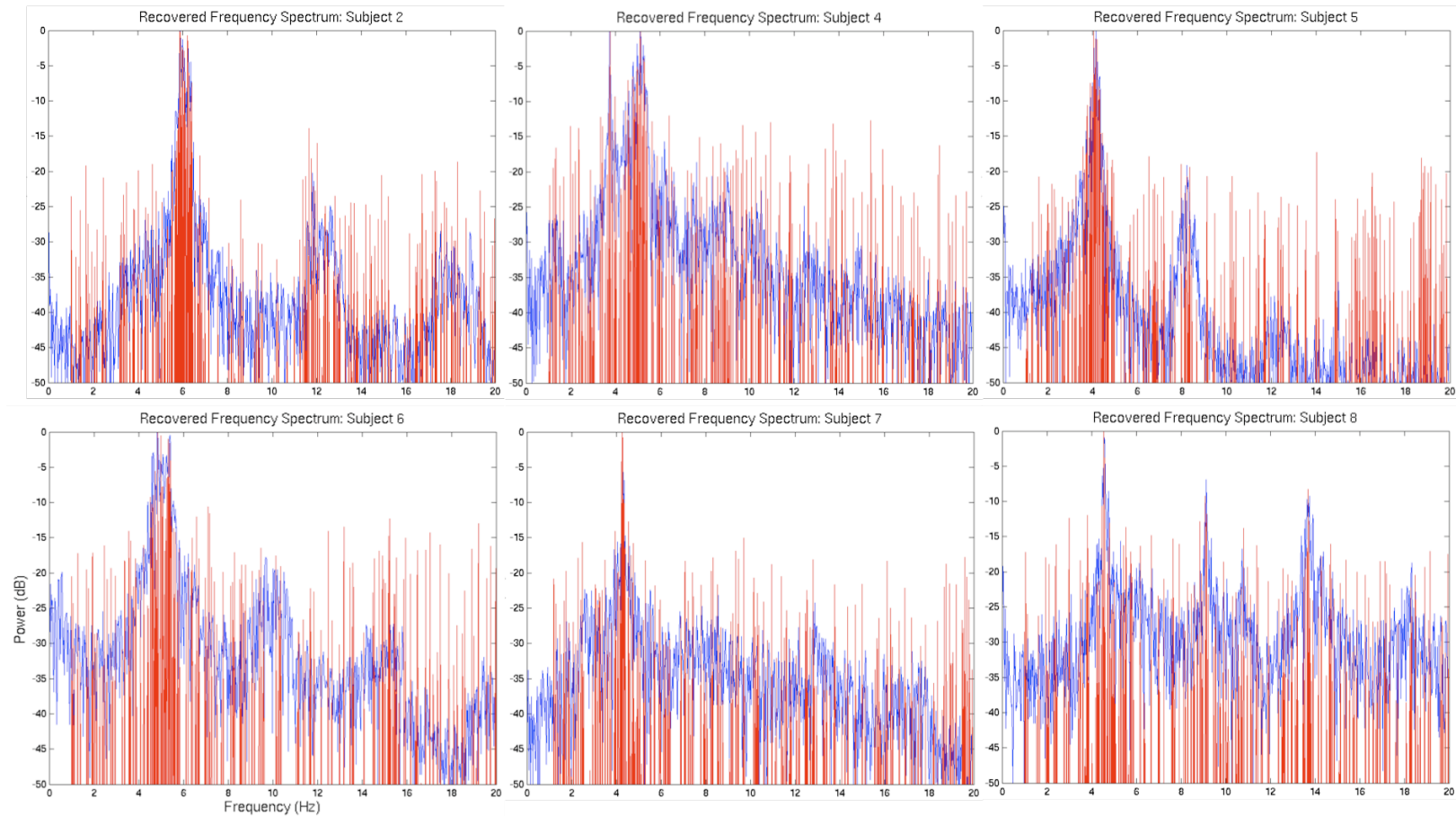
Biometric Example: Parkinson's Tremors



6 Subjects of real tremor data

- collected using low intensity velocity-transducing laser recording aimed at reflective tape attached to the subjects' finger recording the finger velocity
- All show Parkinson's tremor in the 4-6 Hz range.
- Subject 8 shows activity at two higher frequencies
- Subject 4 appears to have two tremors very close to each other in frequency

Biometric Example: Parkinson's Tremors



■ **C=10.5, T=30**

■ 20% Nyquist required samples



Lecture Outline

- ❑ Course Topics Overview
- ❑ Learning Objectives
- ❑ Course Structure
- ❑ Course Policies
- ❑ Course Content
- ❑ Industry Trends
- ❑ Design Example



Course Topics Overview

- ❑ Discrete-Time (DT) Signals
- ❑ Time-Domain Analysis of DT Systems
- ❑ Discrete Fourier Transform (DFT)
- ❑ Fast Fourier Transform (FFT)
- ❑ Discrete-Time Fourier Transform (DTFT)
- ❑ z-Transform
- ❑ Sampling of Continuous Time Signals
- ❑ Data Converters and Modulation
- ❑ Upsampling/Downsampling
- ❑ Discrete-Time Filter Design



Learning Objectives

- ❑ Learn the fundamentals of digital signal processing
- ❑ Provide an understanding of discrete-time signals and systems and digital filters
- ❑ Enable you to apply DSP concepts to a wide range of fields
- ❑ Gain the ability to read the technical literature on DSP
- ❑ Apply the techniques learned in a final project encompassing many different application types



Learning Objectives

□ In other words...

□ Math, Math, Math*

*With MATLAB application for intuition



Course Structure

- ❑ TR Lecture, 4:30-6:00pm in Towne 303
 - Start 5 minutes after, end 5 minutes early (~75-80min)
- ❑ Website (<http://www.seas.upenn.edu/~ese531/>)
 - Course calendar is used for all handouts (lectures slides, assignments, and readings)
 - Canvas used for assignment submission and grades
 - Piazza used for announcements and discussions



Course Structure

- ❑ Course Staff (complete info on course website)
- ❑ Instructor: Tania Khanna
 - Office hours – Wednesday 2-4:30 pm or by appointment
 - Email: taniak@seas.upenn.edu
 - Best way to reach me
- ❑ TA: Shlesh Tiwari
 - Office hours – TBD



Course Structure

❑ Lectures

- Statistically speaking, you will do better if you come to lecture
- Better if interactive, **everyone** engaged
 - Asking and answering questions
 - Actively thinking about material

❑ Textbook

- A. V. Oppenheim and R. W. Schafer (with J. R. Buck), Discrete-Time Signal Processing. 3rd. Edition, Prentice-Hall, 2010
- Class will follow text structure... mostly



Course Structure - Assignments/Exams

- ❑ Homework – 1-2 week(s) long (8 total) [25%]
 - Due Thursdays at start of class (1:30pm)
 - Combination of book problems and matlab problems
 - MATLAB problems not optional
- ❑ Project – two+ weeks long (2 total) [30%]
 - Combination of different DSP applications
- ❑ Midterm exam [20%]
- ❑ Final exam [25%]



Course Policies

See web page for full details

- ❑ Turn homework in Canvas before lecture starts
 - Anything handwritten/drawn must be clearly legible
 - Submit CAD generated figures, graphs, results when specified
 - NO LATE HOMEWORKS!
- ❑ Individual work (except project)
 - CAD drawings, simulations, analysis, writeups
 - May discuss strategies, but acknowledge help



Course Content

- ❑ Introduction
- ❑ Discrete Time Signals & Systems
- ❑ Discrete Time Fourier Transform
- ❑ Z-Transform
- ❑ Inverse Z-Transform
- ❑ Sampling of Continuous Time Signals
- ❑ Frequency Domain of Discrete Time Series
- ❑ Downsampling/Upsampling
- ❑ Data Converters, Sigma Delta Modulation
- ❑ Frequency Response of LTI Systems
- ❑ Signal Flow Representation
- ❑ Basic Structures for IIR and FIR Systems
- ❑ Design of IIR and FIR Filters
- ❑ Butterworth, Chebyshev, and Elliptic Filters
- ❑ Filter Banks
- ❑ Adaptive Filters
- ❑ Computation of the Discrete Fourier Transform
- ❑ Fast Fourier Transform

Course Content

ESE531 Spring 2017 Working Schedule

Wk	Lect.	Date	Lecture	Slides	Due	Reading
1	1	1/12	Th Intro/Overview			review course webpage completely
2	2	1/17	T Discrete Time Signals & Systems, Part 1			2.1-2.2
	3	1/19	Th Discrete Time Signals & Systems, Part 2			2.3-2.5
3	4	1/24	T Discrete Time Fourier Transform			2.5-2.7
	5	1/26	Th Z-Transform		HW 1	3.0-3.1
4	6	1/31	T Inverse Z-Transform			3.3
	7	2/2	Th Z-Transform Properties		HW 2	3.4
5	8	2/7	T Sampling of Continuous Time Signals			4.0-4.1
	9	2/9	Th Frequency Domain of Discrete Time Series		HW 3	4.2-4.3
6	10	2/14	T Downsampling/Upsampling			4.6
	11	2/16	Th Data Converters, Sigma Delta Modulation		HW 4	4.8-4.9
7	12	2/21	T Frequency Response of LTI Systems			5.0-5.2
	13	2/23	Th Signal Flow Representation			6.0-6.2
8	14	2/28	T Basic Structures for IIR Systems			6.3
	15	3/2	Th Basic Structures for FIR Systems, Parameter Quantization Effects		HW 5	6.5, 6.8
9		3/7	T SPRING BREAK -- no class			
		3/9	Th SPRING BREAK -- no class			
		3/14	T Midterm Exam, in class			
10	16	3/16	Th Design of IIR Filters, Part 1			7.0-7.2
	17	3/21	T Design of IIR Filters, Part 2			7.0-7.2
11	18	3/23	Th Butterworth, Chebyshev, and Elliptic Filters		HW 6	7.3
	19	3/28	T Design of FIR Filters			7.5
12	20	3/30	Th Filter Banks		HW 7	TBD
	21	4/4	T Adaptive Filters			TBD
13	22	4/6	Th Discrete Fourier Transform		HW 8	8.0-8.2
	23	4/11	T Computation of the DFT, Part 1			9.0-9.1
14	24	4/13	Th Computation of the DFT, Part 2			9.0-9.1
	25	4/18	T Fast Fourier Transform			9.2-9.3
15	26	4/20	Th DSP Applications			TBD
16	27	4/25	T Review		Project	
17		TBD	FINAL EXAM: TBD in TBD			

This working calendar is on the web: <http://www.eecs.upenn.edu/~ese531/spring2017/syllabus.html>. Please, recheck the page on the web as details may be adjusted as the term progresses. Lectures notes, reading, and handouts will be filled as we reach them.

[ESE531 Home Page](#)

What is DSP



DSP is Everywhere

❑ Sound applications

- Compression, enhancement, special effects, synthesis, recognition, echo cancellation,...
- Cell Phones, MP3 Players, Movies, Dictation, Text-to-speech,...

❑ Communication

- Modulation, coding, detection, equalization, echo cancellation,...
- Cell Phones, dial-up modem, DSL modem, Satellite Receiver,...

❑ Automotive

- ABS, GPS, Active Noise Cancellation, Cruise Control, Parking,...



DSP is Everywhere (con't)

- ❑ Medical
 - Magnetic Resonance, Tomography, Electrocardiogram, Biometric Monitoring...
- ❑ Military
 - Radar, Sonar, Space photographs, remote sensing,...
- ❑ Image and Video Applications
 - DVD, JPEG, Movie special effects, video conferencing...
- ❑ Mechanical
 - Motor control, process control, oil and mineral prospecting,...



Signal Processing

- ❑ Humans are the most advanced signal processors
 - speech and pattern recognition, speech synthesis,...
- ❑ We encounter many types of signals in various applications
 - Electrical signals: voltage, current, magnetic and electric fields,...
 - Mechanical signals: velocity, force, displacement,...
 - Acoustic signals: sound, vibration,...
 - Other signals: pressure, temperature,...
- ❑ Most real-world signals are analog
 - They are continuous in time and amplitude
 - Convert to voltage or currents using sensors and transducers



Signal Processing (con't)

- ❑ Analog circuits process these signals using
 - Resistors, Capacitors, Inductors, Amplifiers,...
- ❑ Analog signal processing examples
 - Audio processing in FM radios
 - Video processing in traditional TV sets

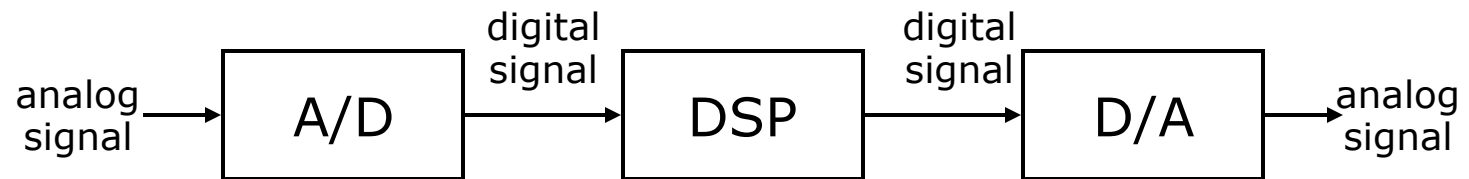


Limitations of Analog Signal Processing

- ❑ Accuracy limitations due to
 - Component tolerances
 - Undesired nonlinearities
- ❑ Limited repeatability due to
 - Tolerances
 - Changes in environmental conditions
 - Temperature
 - Vibration
- ❑ Sensitivity to electrical noise
- ❑ Limited dynamic range for voltage and currents
- ❑ Inflexibility to changes
- ❑ Difficulty of implementing certain operations
 - Nonlinear operations
 - Time-varying operations
- ❑ Difficulty of storing information

Digital Signal Processing

- ❑ Represent signals by a sequence of numbers
 - Sampling and quantization (or analog-to-digital conversion)
- ❑ Perform processing on these numbers with a digital processor
 - Digital signal processing
- ❑ Reconstruct analog signal from processed numbers
 - Reconstruction or digital-to-analog conversion



- Analog input → analog output
 - Eg. Digital recording music
- Analog input → digital output
 - Eg. Touch tone phone dialing, speech to text
- Digital input → analog output
 - Eg. Text to speech
- Digital input → digital output
 - Eg. Compression of a file on computer



Pros and Cons of Digital Signal Processing

❑ Pros

- Accuracy can be controlled by choosing word length
- Repeatable
- Sensitivity to electrical noise is minimal
- Dynamic range can be controlled using floating point numbers
- Flexibility can be achieved with software implementations
- Non-linear and time-varying operations are easier to implement
- Digital storage is cheap
- Digital information can be encrypted for security
- Price/performance and reduced time-to-market

❑ Cons

- Sampling causes loss of information
- A/D and D/A requires mixed-signal hardware
- Limited speed of processors
- Quantization and round-off errors

DSP Examples



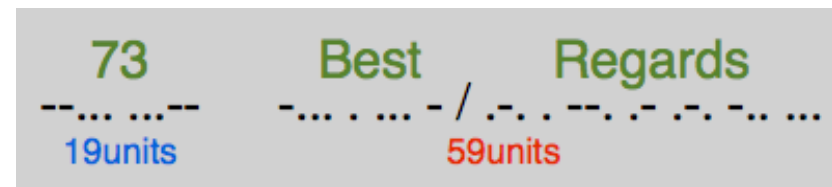
Example I: Audio Compression

- ❑ Compress audio by 10x without perceptual loss of quality.
- ❑ Sophisticated processing based on models of human perception
- ❑ 3MB files instead of 30MB
 - Entire industry changed in less than 10 years!

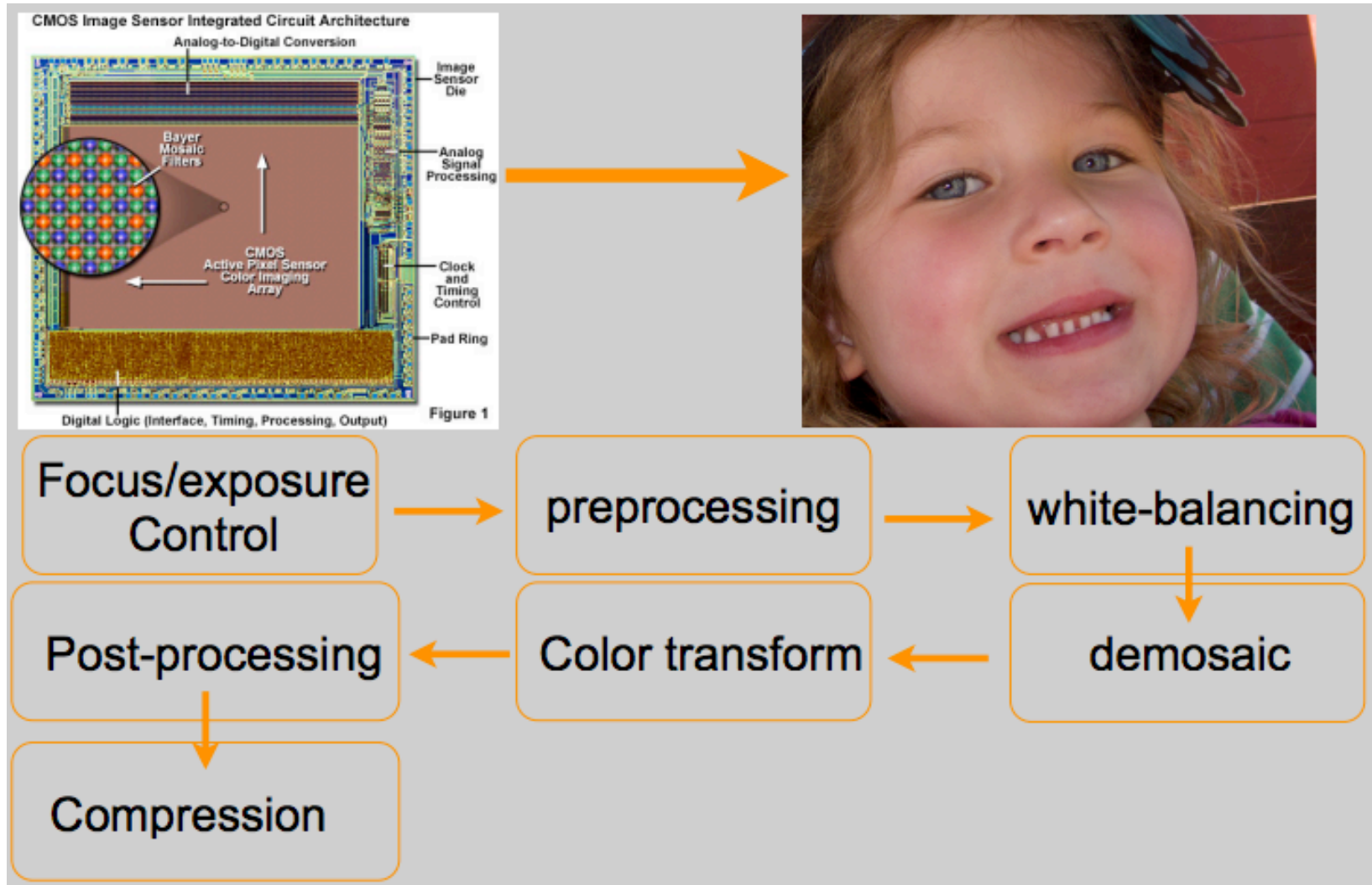
Historical Forms of Compression

- ❑ Morse code: dots (1 unit) dashes (3 units)
 - Code Length inversely proportional to frequency of character
 - E (12.7%) = . (1 unit) Q (0.1%) = --.- (10 units)

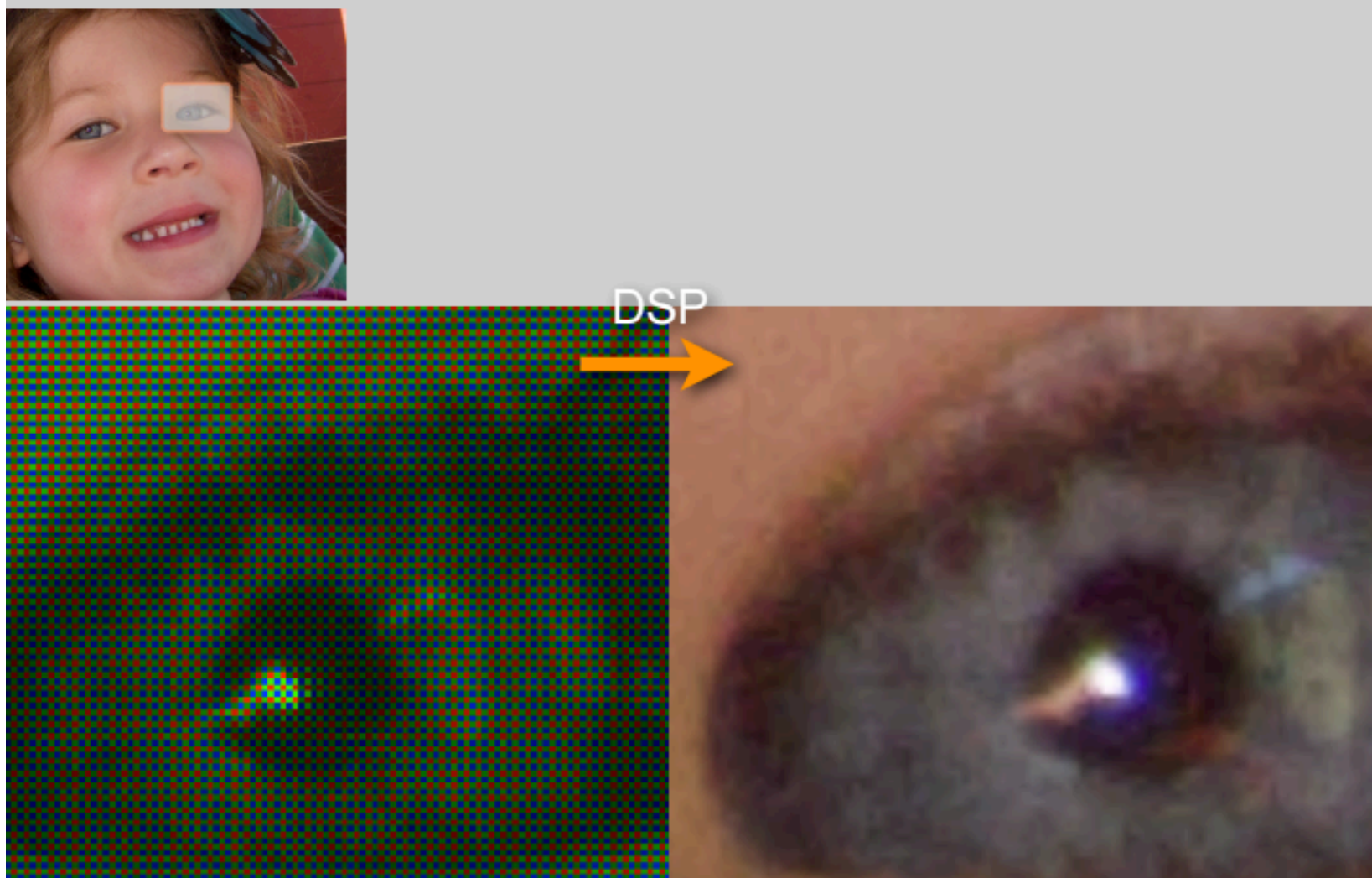
- ❑ “92 Code”
 - Used by Western-Union in 1859 to reduce BW on telegraph lines by numerical codes for frequently used phrases
 - 1 = wait a minute
 - 73 = Best Regards
 - 88 = Loves and Kisses



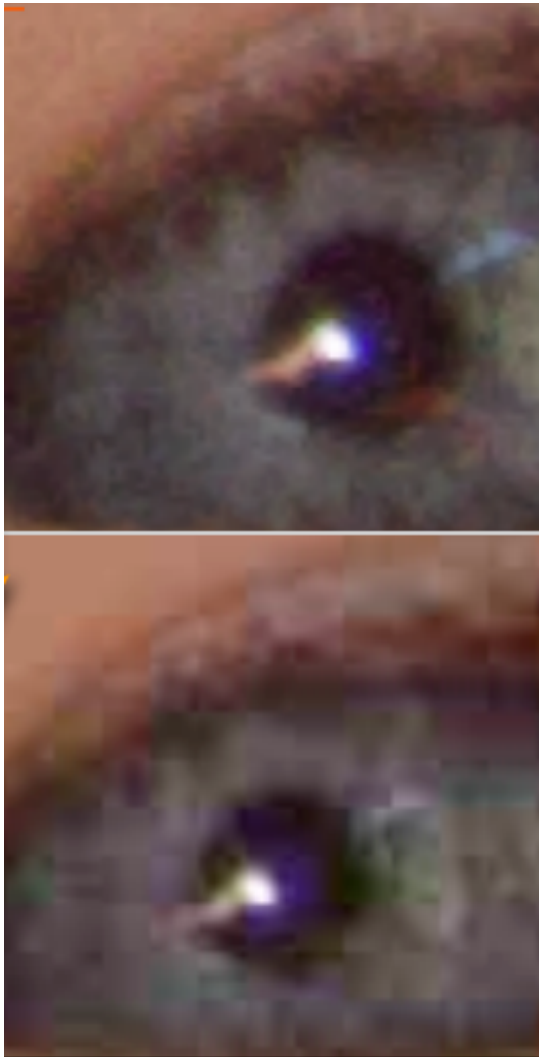
Example II: Digital Imaging Camera



Example II: Digital Imaging Camera



Example II: Digital Imaging Camera



- ❑ Compression of 40x without perceptual loss of quality.
- ❑ Example of slight overcompression: difference enables x60 compression!

Computational Photography

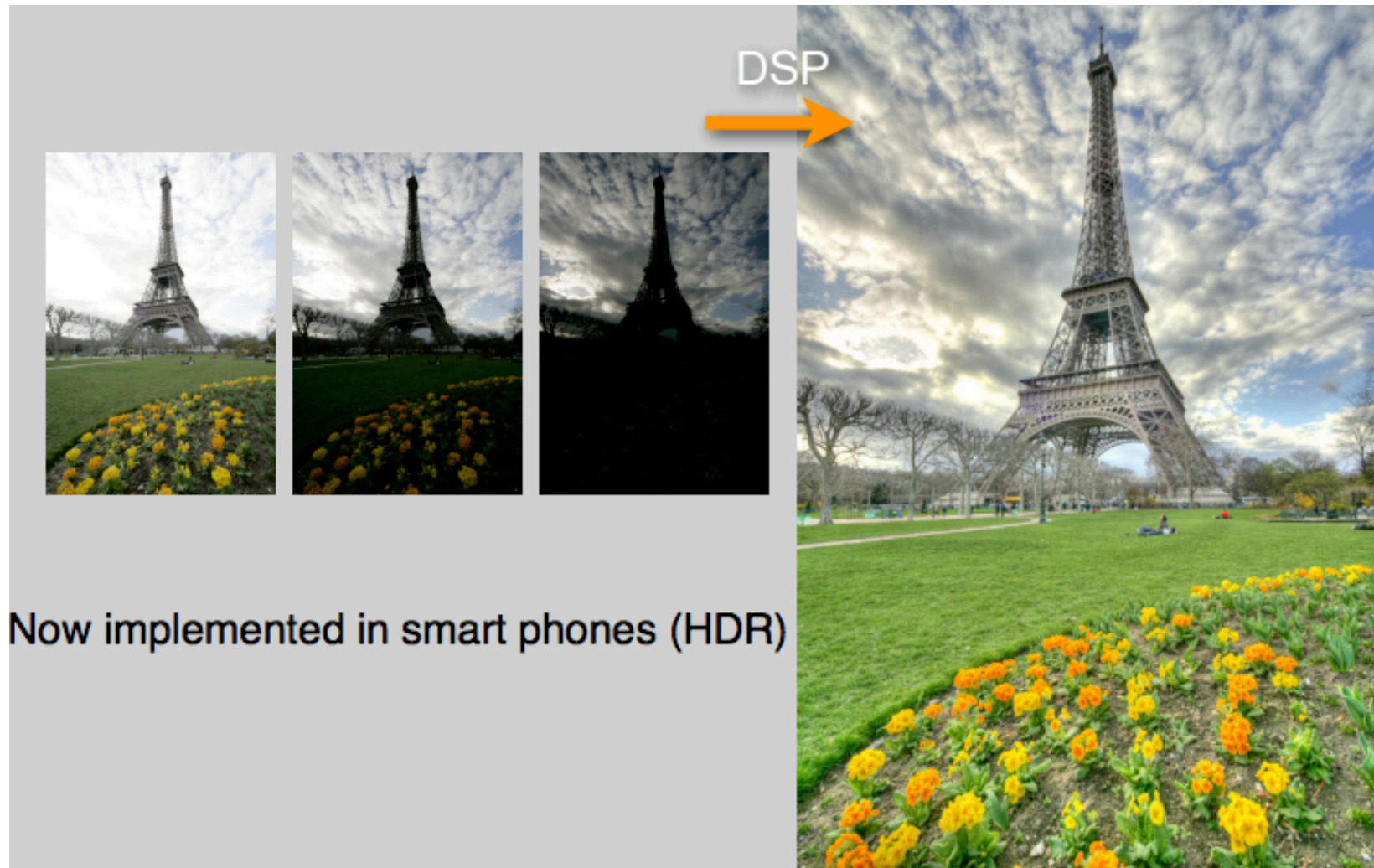


Image Processing - Saves Children

Canadian 'swirl face' pedophile jailed in Thailand

August 15, 2008

☆ Rea

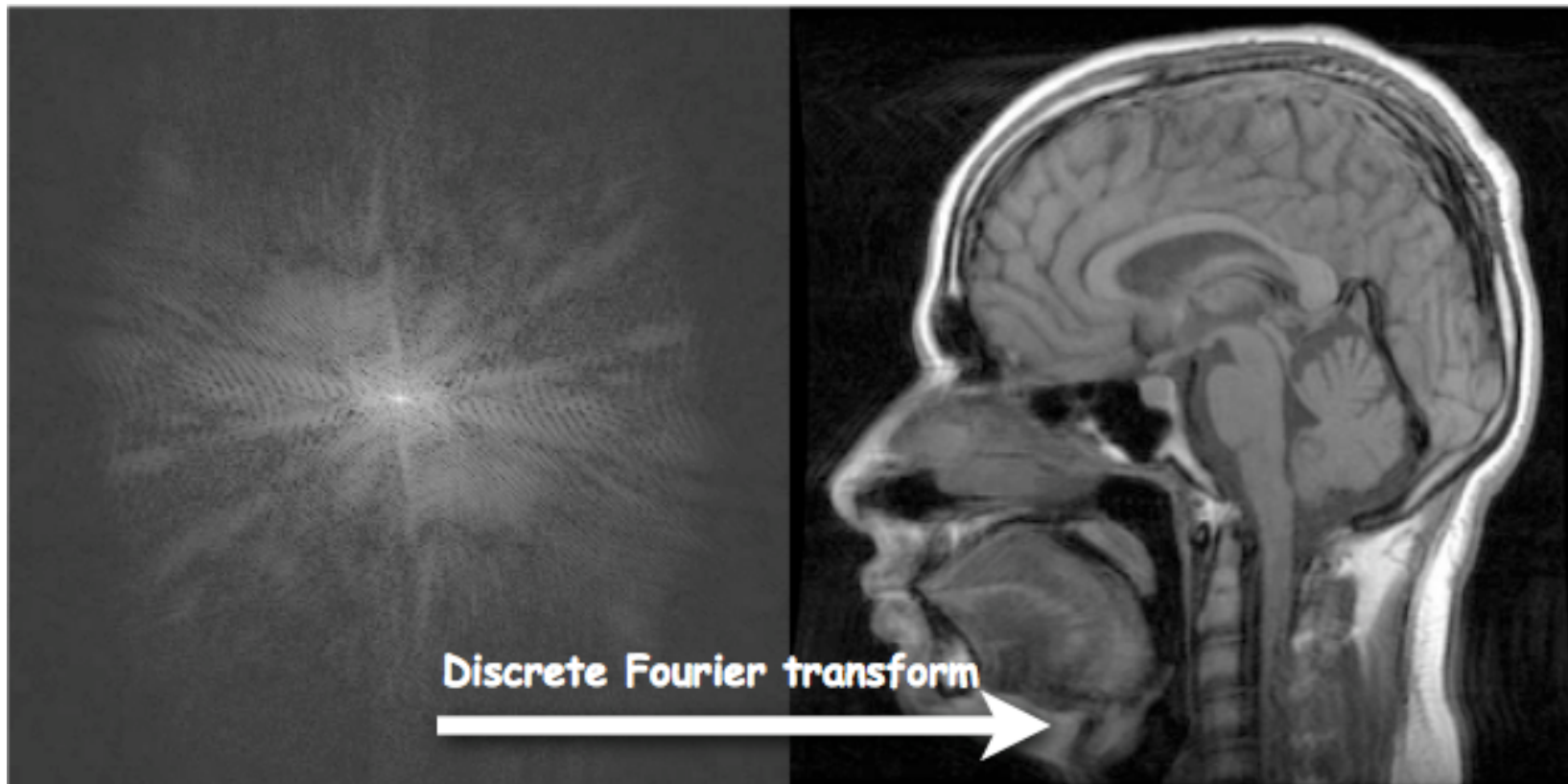


Images released by Interpol in 2007 show the 'unswirling' of the internet pictures that led to the capture of Christopher Paul Neil.

Example III: MRI

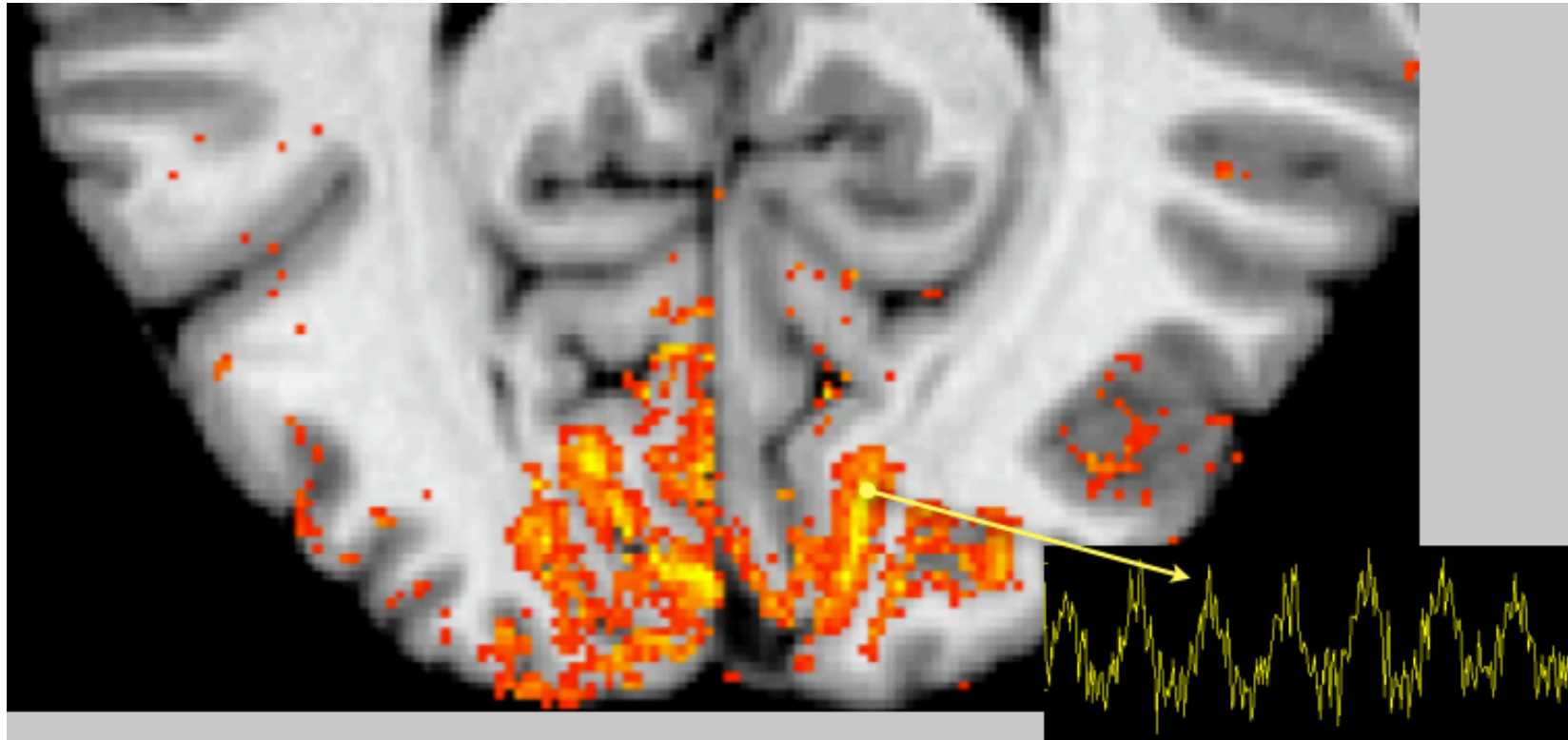
k-space (raw data)

Image



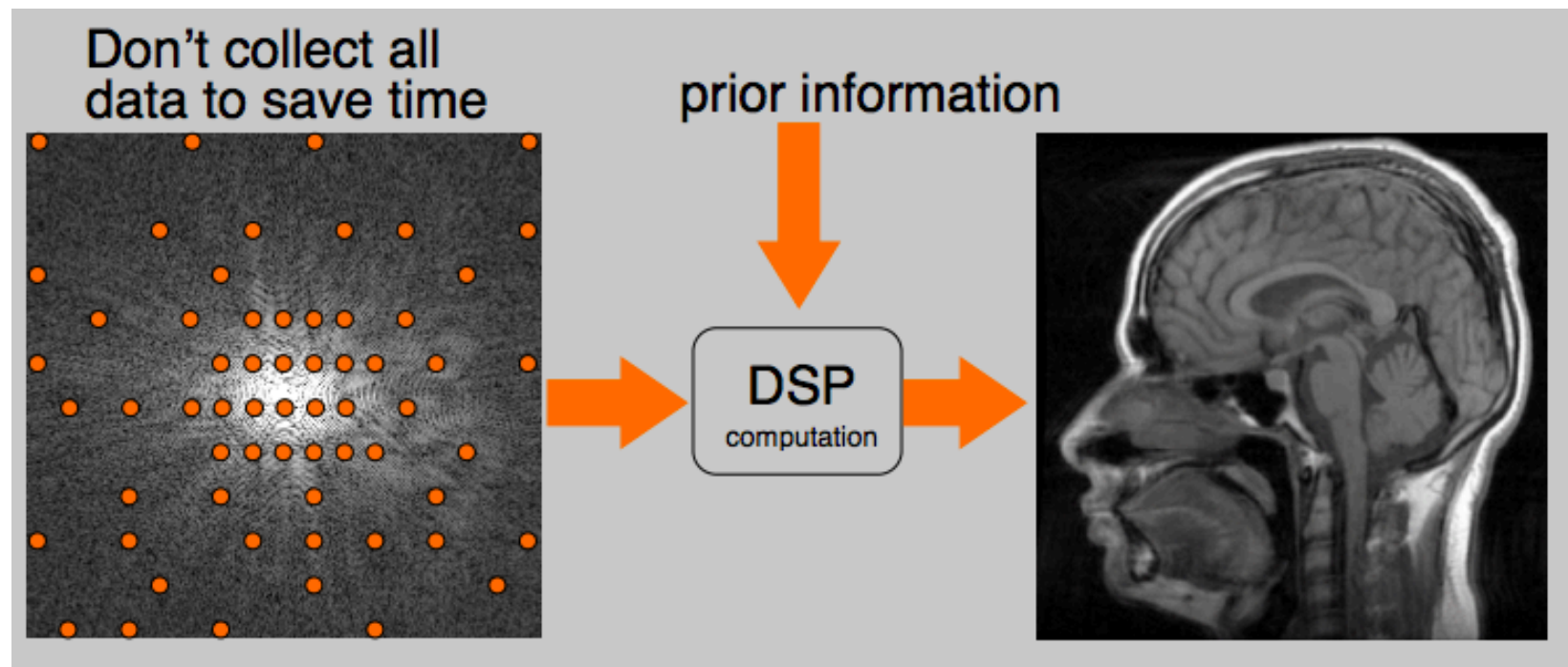
fMRI example

- Sensitivity to blood oxygenation
 - response to brain activity Convert from one signal to another



Compressive Sampling

- ❑ Compression meets sampling

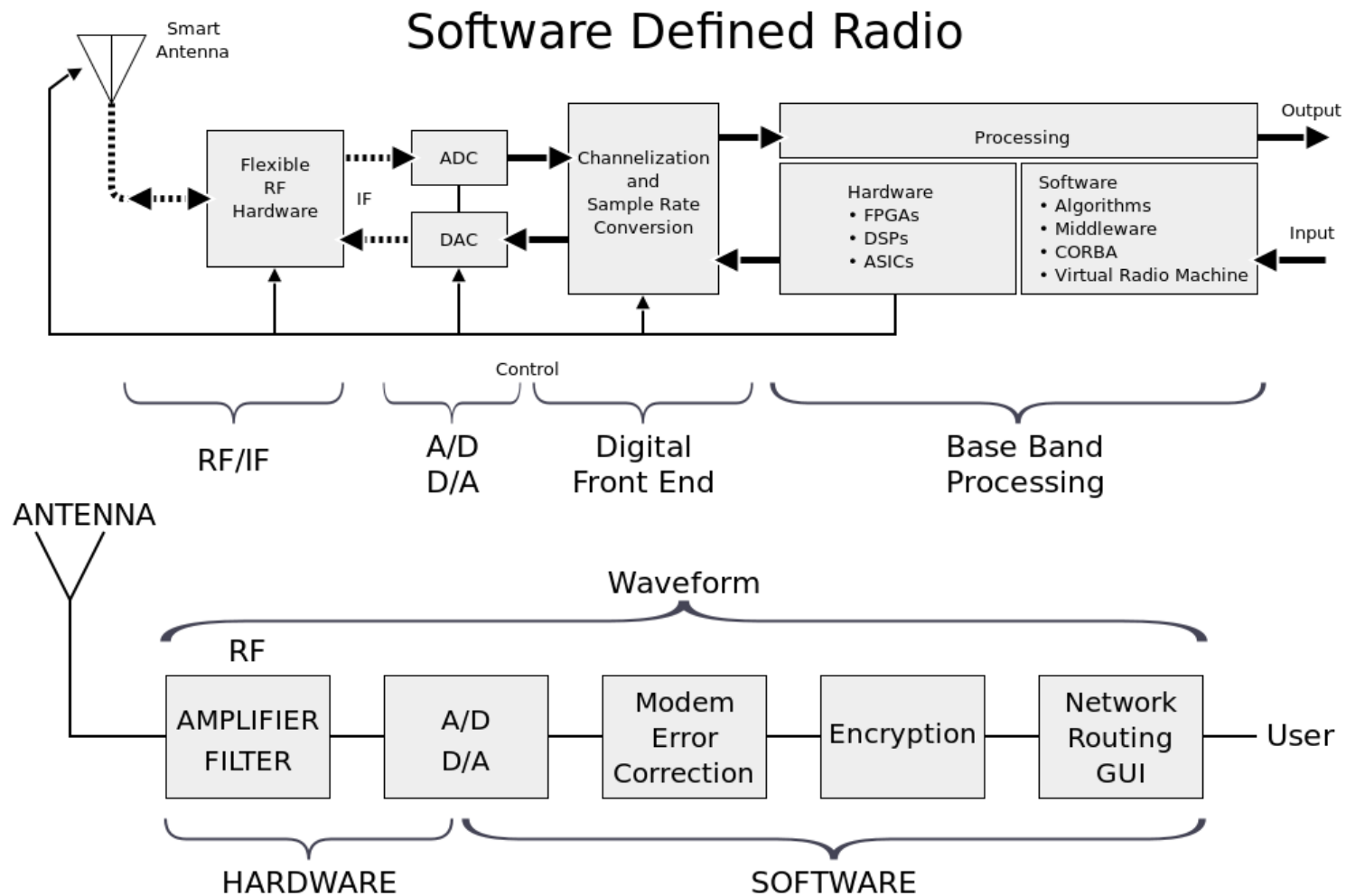




Example IV: Software Defined Radio

- ❑ Traditional radio:
 - Hardware receiver/mixers/demodulators/filtering
 - Outputs analog signals or digital bits
- ❑ Software Defined Radio:
 - Uses RF front end for baseband signal
 - High speed ADC digitizes samples
 - All processing chain done in software

Software Defined Radio





Software Defined Radio

❑ Advantages:

- Flexibility
- Upgradable
- Sophisticated processing
- Ideal Processing chain
- not approximate like in analog hardware

❑ Already used in consumer electronics

- Cellphone baseband processors
- Wifi, GPS, etc....



Shameless Plug

- ❑ If you are interested in how Analog to digital converters, amplifiers etc...work and how to make them
- ❑ Take ESE 568!
- ❑ Good to know both sides of the system



Future of ADC design

- ❑ Today's ADCs are extremely well optimized
- ❑ For non-incremental improvements, we must explore new ideas in signal processing that tackle ADC inefficiency at the system level
 - Compressed sensing
 - Finite innovation rate sampling
 - Other ideas?



From Before: Implementing Compressive Sampling

- ❑ Devised a way to randomly sample 20% of the Nyquist required samples and still detect the tremor frequencies within 100mHz
 - Requires post processing to randomly sample!

- ❑ Implement hardware on chip to “choose” samples in real time
 - Only write to memory the “chosen” samples
 - Design random-like sequence generator
 - Only convert the “chosen” samples
 - Design low energy ADC

Discrete Time Signals



Signals

DEFINITION

Signal (n): A detectable physical quantity ... by which messages or information can be transmitted (Merriam-Webster)

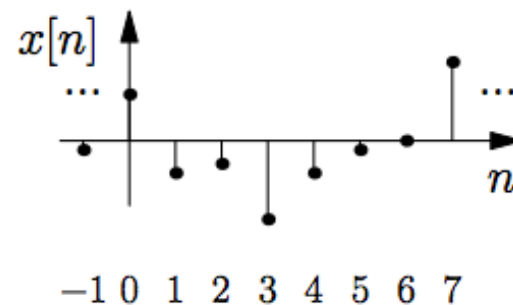
- ❑ Signals carry information
- ❑ Examples:
 - Speech signals transmit language via acoustic waves
 - Radar signals transmit the position and velocity of targets via electromagnetic waves
 - Electrophysiology signals transmit information about processes inside the body
 - Financial signals transmit information about events in the economy
- ❑ Signal processing systems manipulate the information carried by signals

Signals are Functions

DEFINITION

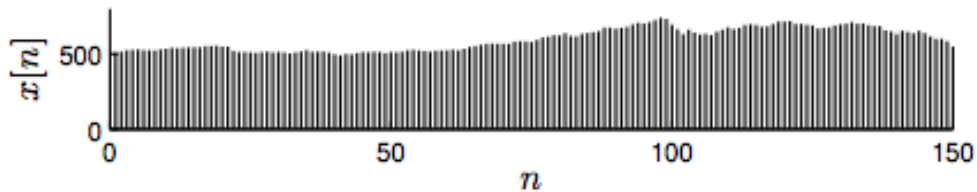
A **signal** is a function that maps an independent variable to a dependent variable.

- Signal $x[n]$: each value of n produces the value $x[n]$
- In this course, we will focus on **discrete-time** signals:
 - Independent variable is an **integer**: $n \in \mathbb{Z}$ (will refer to as time)
 - Dependent variable is a real or complex number: $x[n] \in \mathbb{R}$ or \mathbb{C}

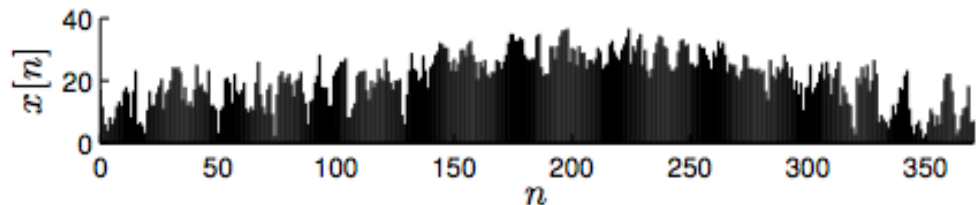


A Menagerie of Signals

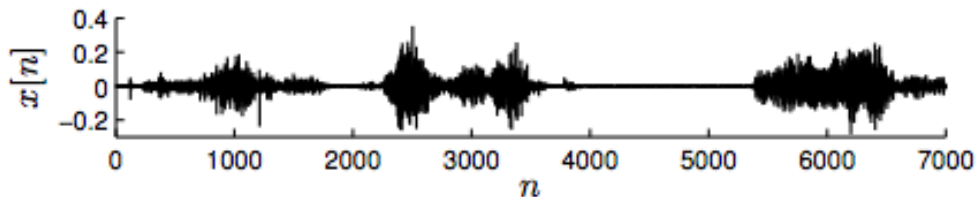
- Google Share daily share price for 5 months



- Temperature at Houston Intercontinental Airport in 2013 (Celcius)

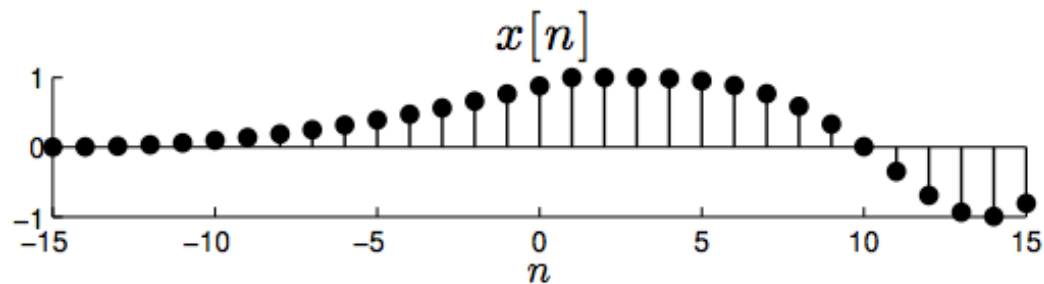


- Excerpt from Shakespeare's *Hamlet*

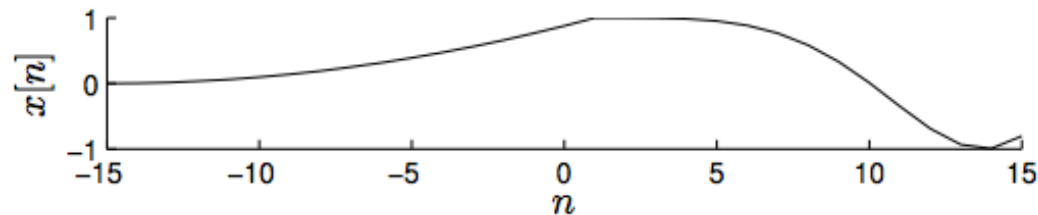


Plotting Signals Correctly

- In a discrete-time signal $x[n]$, the independent variable n is discrete (integer)
- To plot a discrete-time signal in a program like Matlab, you should use the stem or similar command and not the plot command
- Correct:



- Incorrect:





Wrap up

❑ Admin

- Find web, get text, assigned reading...
- <http://www.seas.upenn.edu/~ese531>
- <https://piazza.com/upenn/spring2017/ese531/>
- <https://canvas.upenn.edu/>

❑ Big Ideas/takeaway

- Analysis of sampled and quantized signals

❑ Remaining Questions?