

ESE 531: Digital Signal Processing

Lec 11: February 16th, 2017
Data Converters, Noise Shaping



Lecture Outline

- ❑ Multi-Rate Filter Banks (con't)
- ❑ Data Converters
 - Anti-aliasing
 - ADC
 - Quantization
 - Practical DAC
- ❑ Noise Shaping

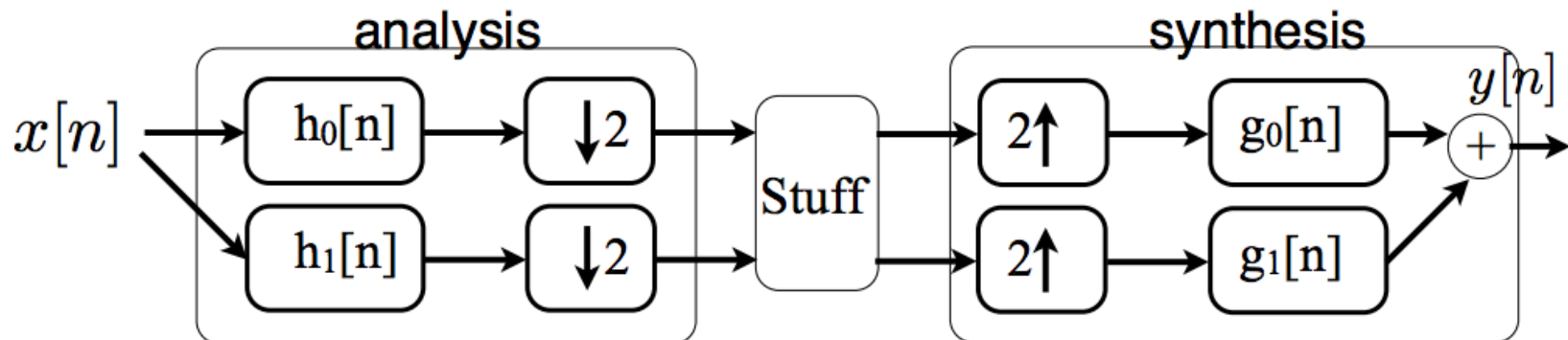


Multi-Rate Filter Banks

- ❑ Use filter banks to operate on a signal differently in different frequency bands
 - To save computation, reduce the rate after filtering

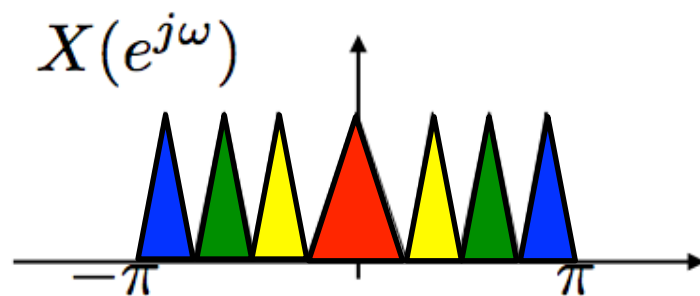
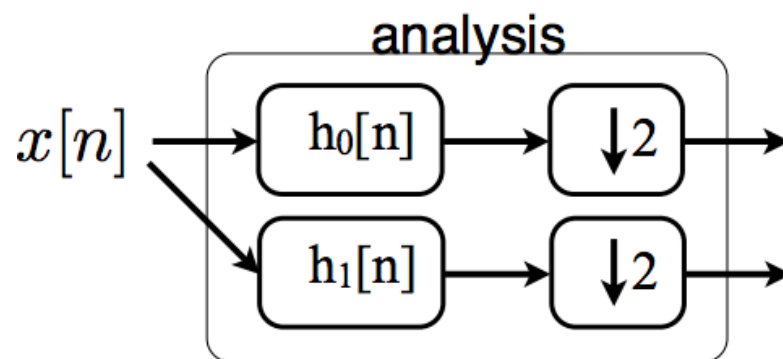
Multi-Rate Filter Banks

- ❑ Use filter banks to operate on a signal differently in different frequency bands
 - To save computation, reduce the rate after filtering
- ❑ $h_0[n]$ is low-pass, $h_1[n]$ is high-pass
 - Often $h_1[n] = e^{j\pi n} h_0[n] \leftarrow$ shift freq resp by π



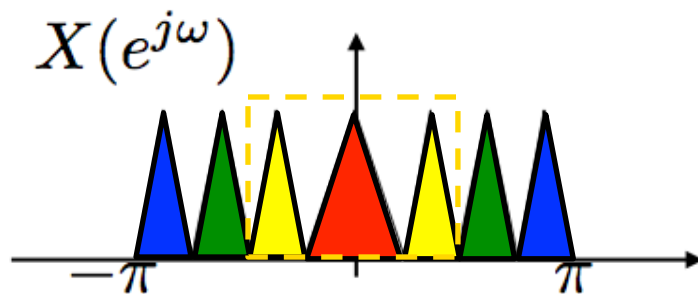
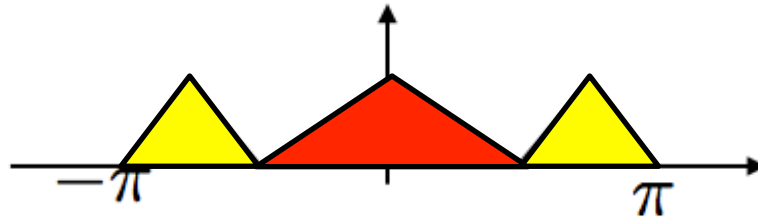
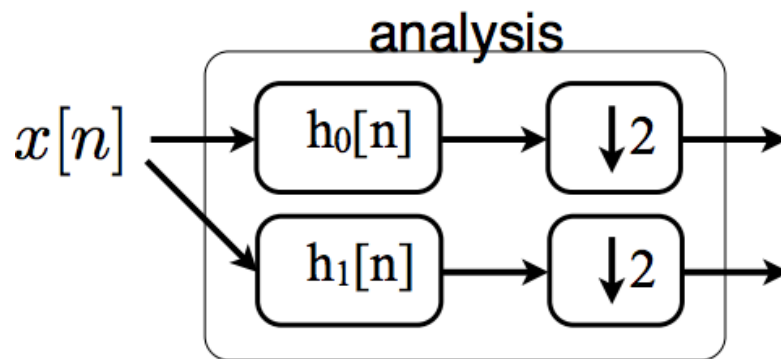
Multi-Rate Filter Banks

- Assume h_0 , h_1 are ideal low/high pass



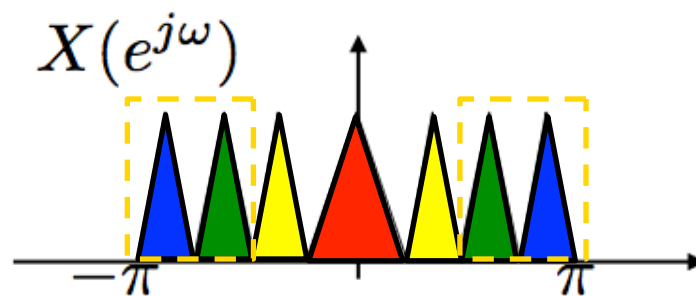
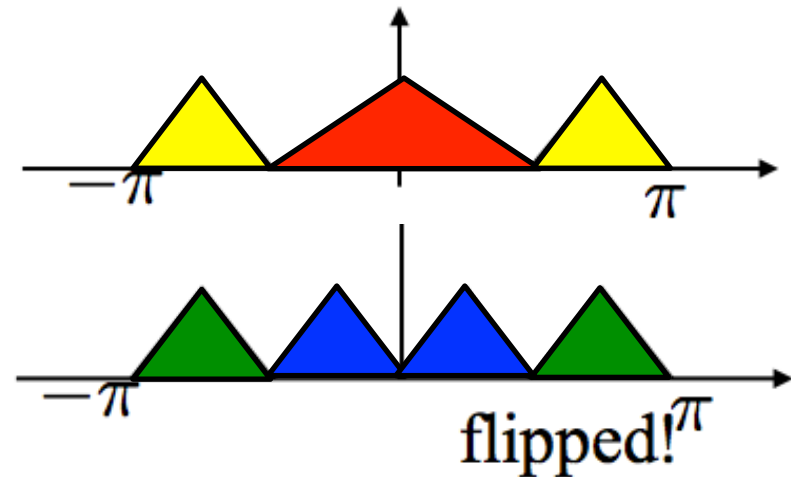
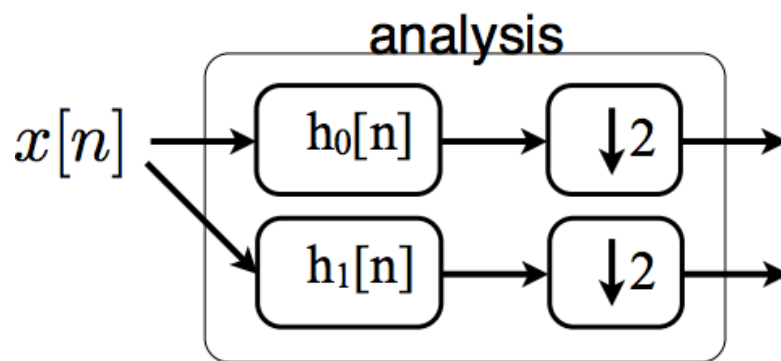
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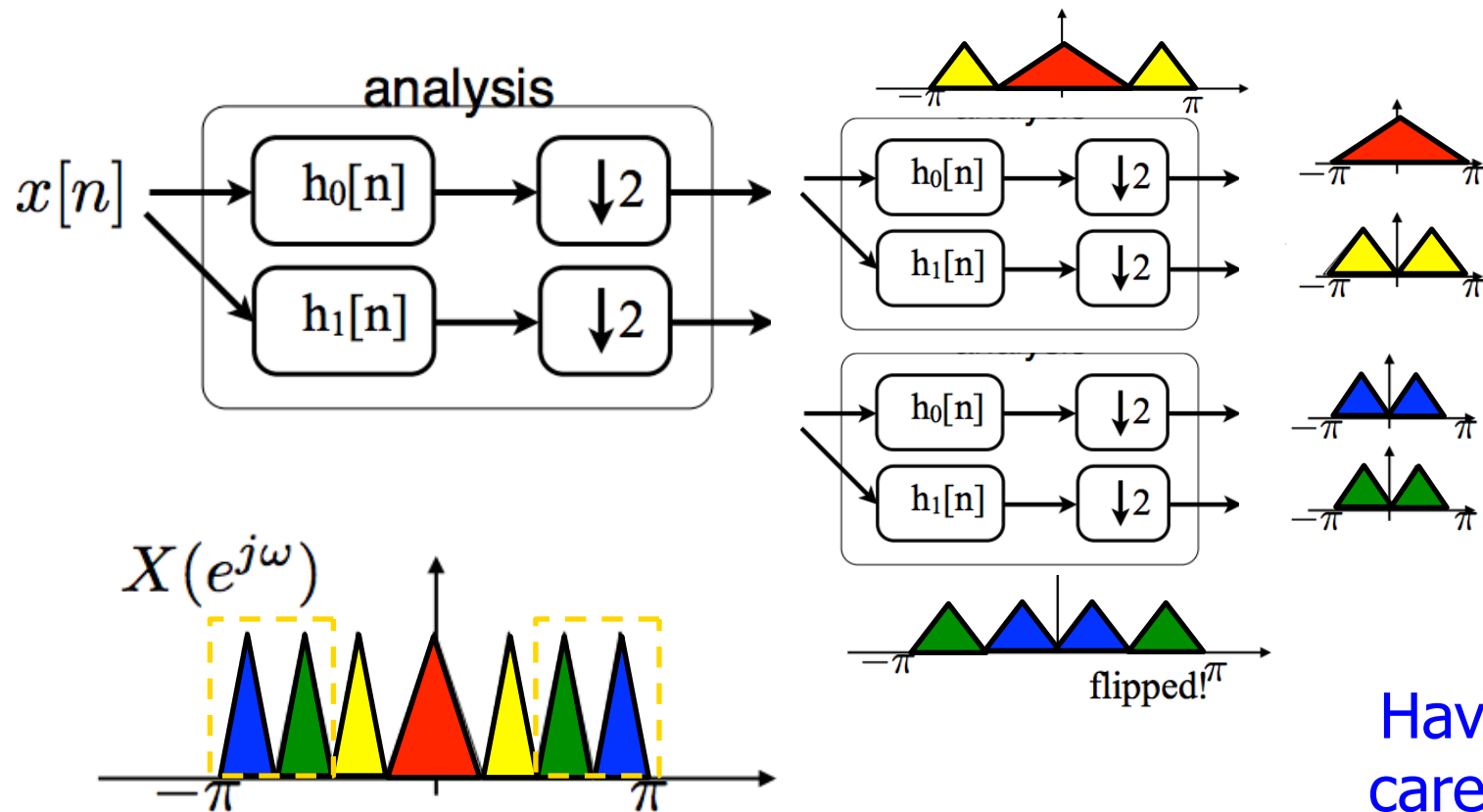
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Multi-Rate Filter Banks

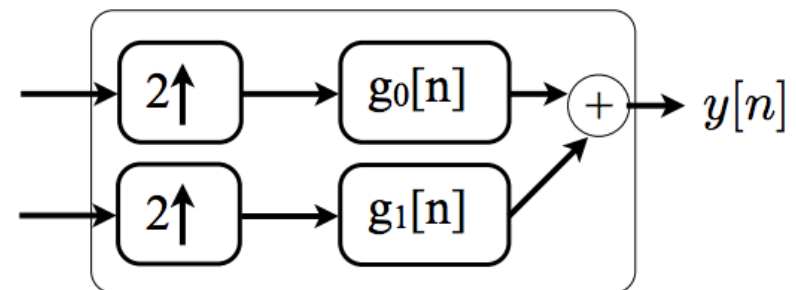
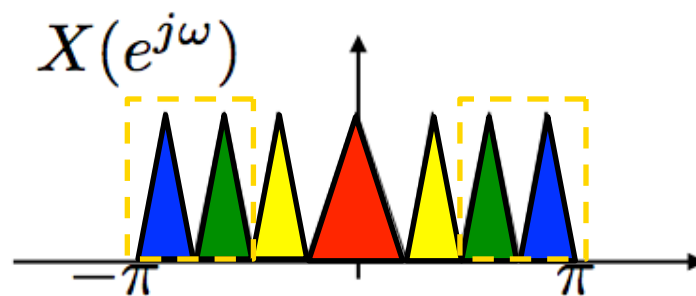
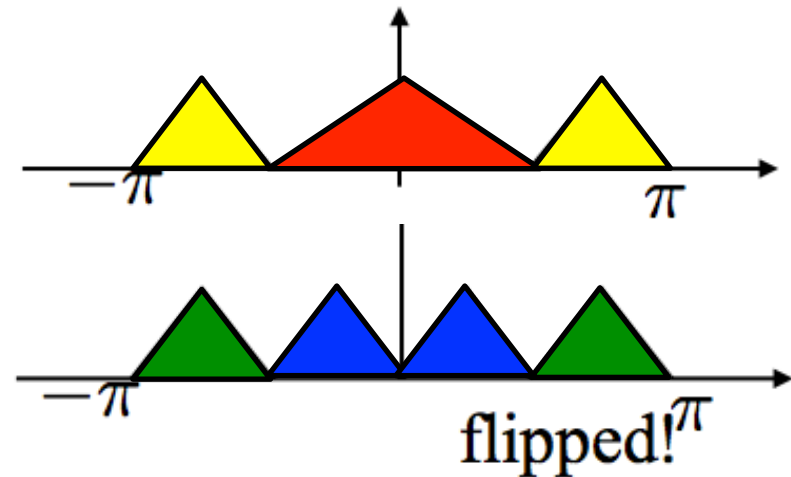
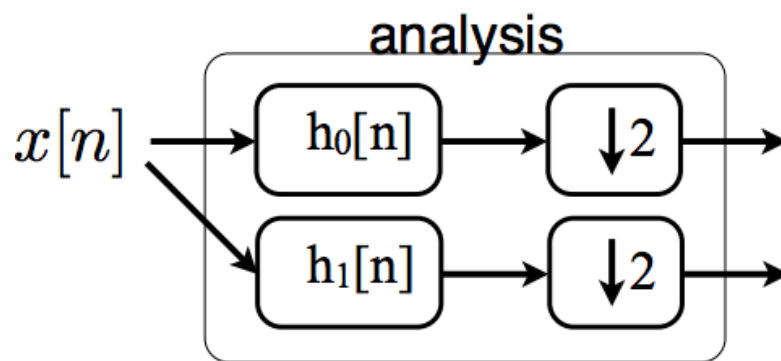
- Assume h_0 , h_1 are ideal low/high pass



Have to be
careful with
order!

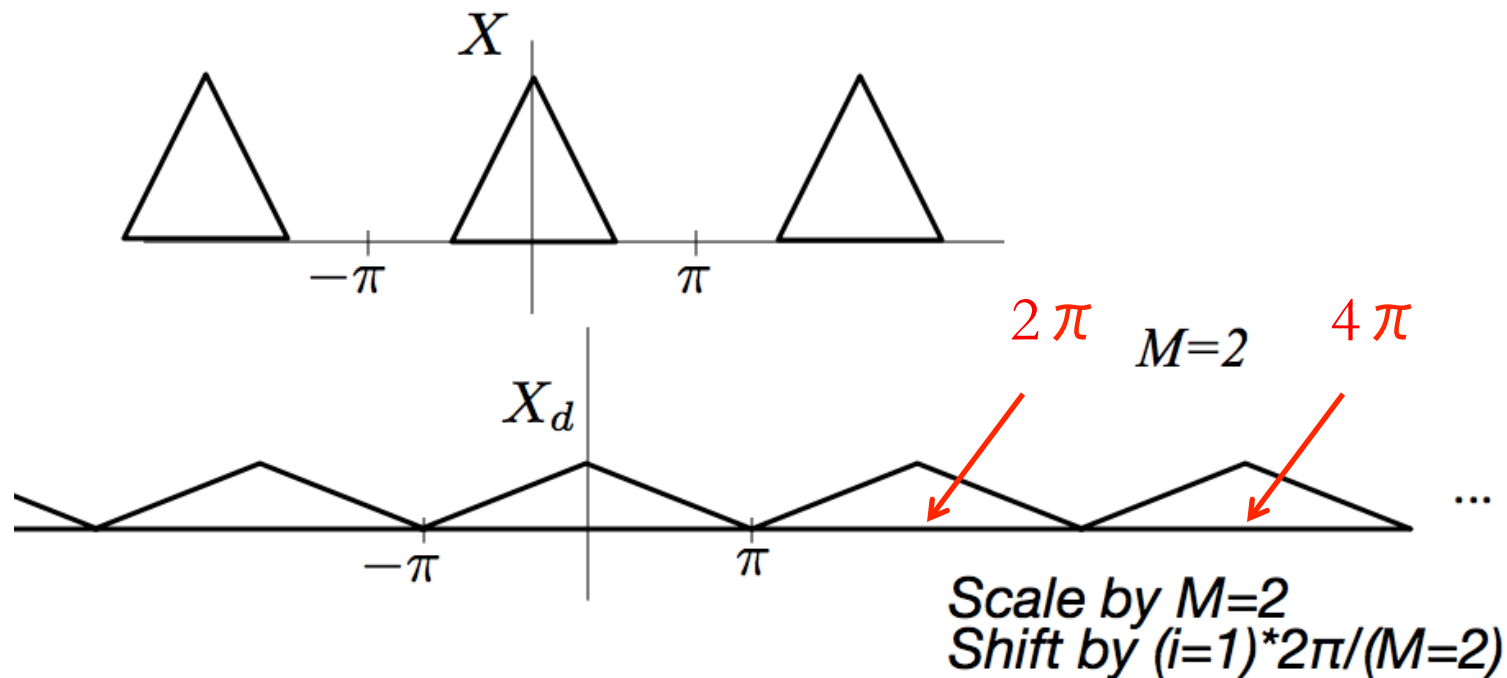
Multi-Rate Filter Banks

- Assume h_0 , h_1 are ideal low/high pass



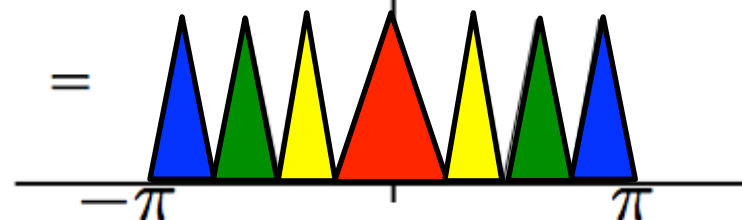
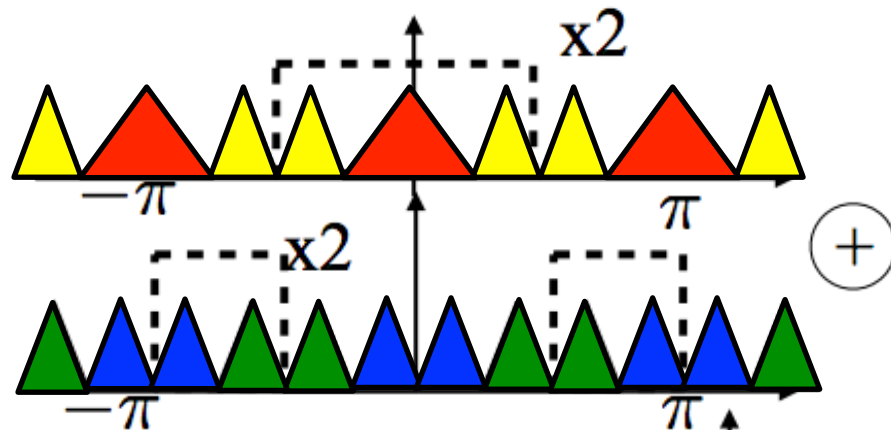
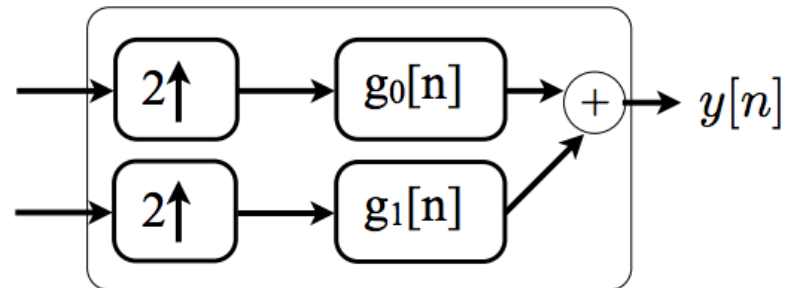
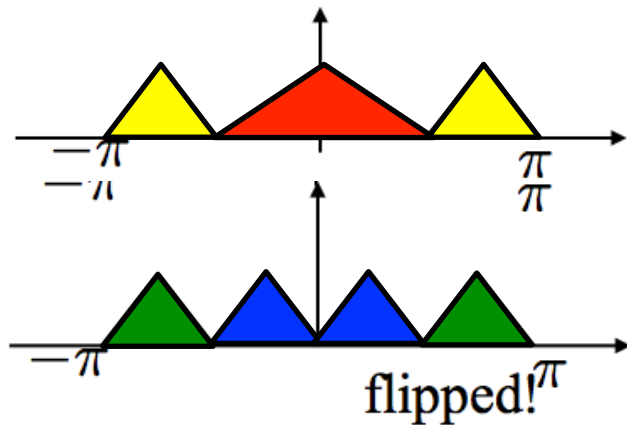
Downsampling Reminder: Example

$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X \left(e^{j \left(\frac{\omega}{M} - \frac{2\pi}{M} i \right)} \right)$$



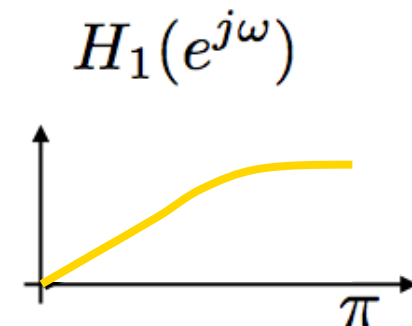
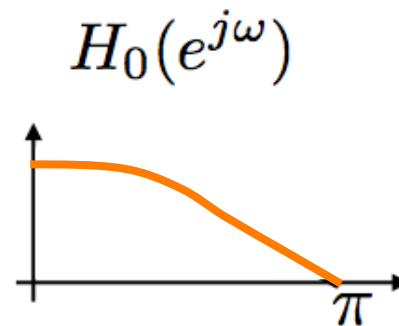
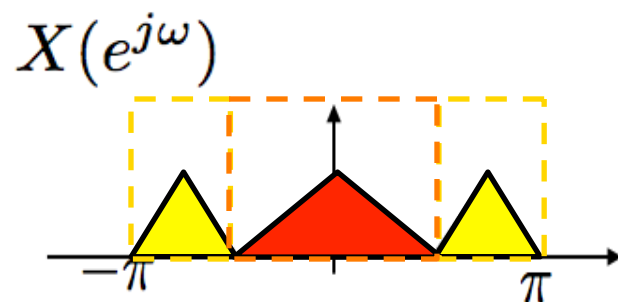
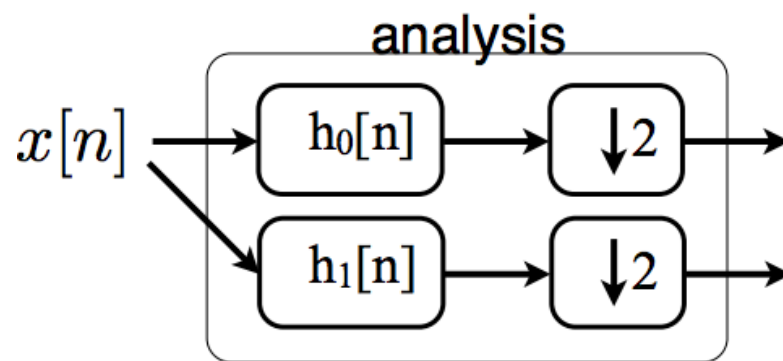
Multi-Rate Filter Banks

- Assume h_0, h_1 are ideal low/high pass



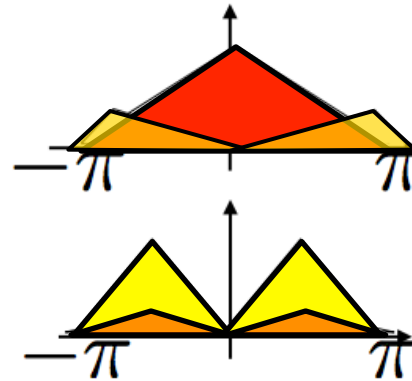
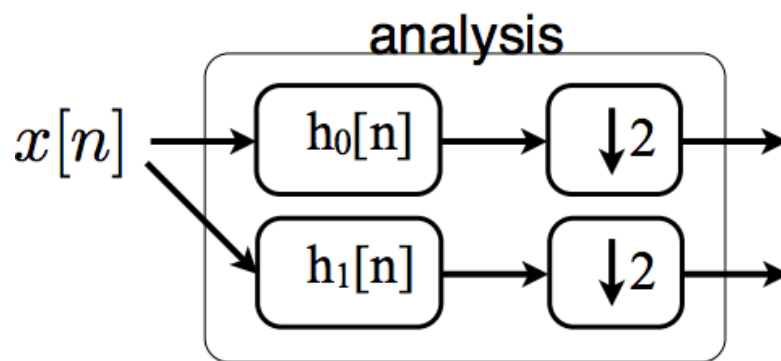
Multi-Rate Filter Banks

- h_0, h_1 are NOT ideal low/high pass

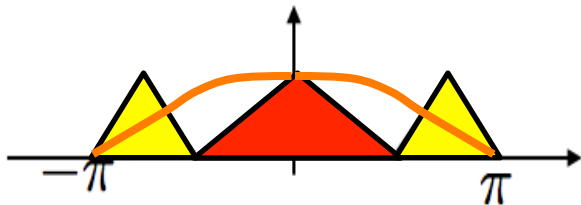


Non Ideal Filters

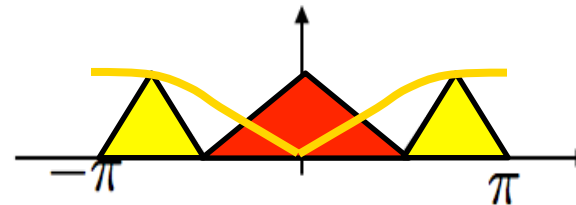
- h_0, h_1 are NOT ideal low/high pass



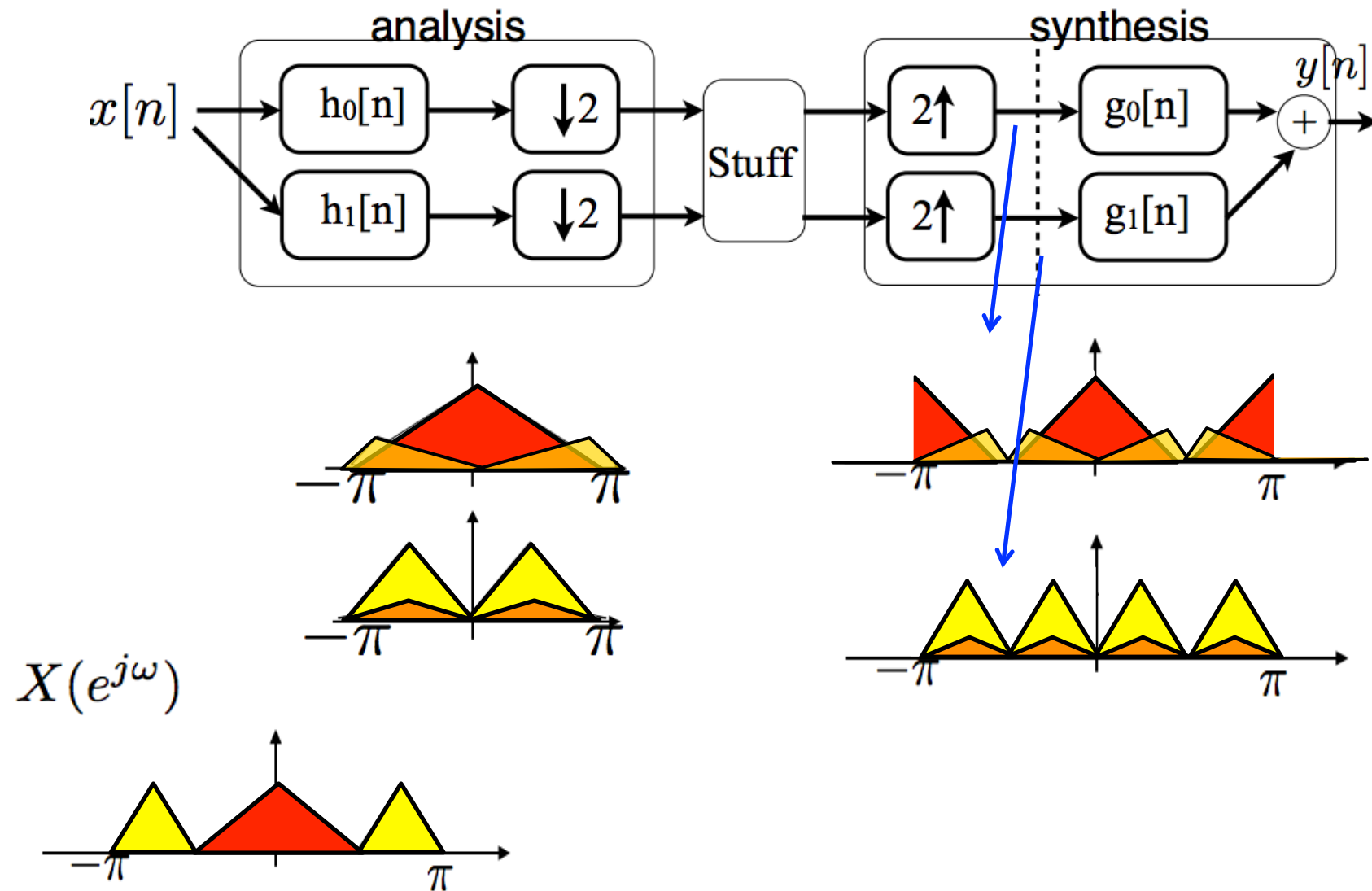
$X(e^{j\omega})$



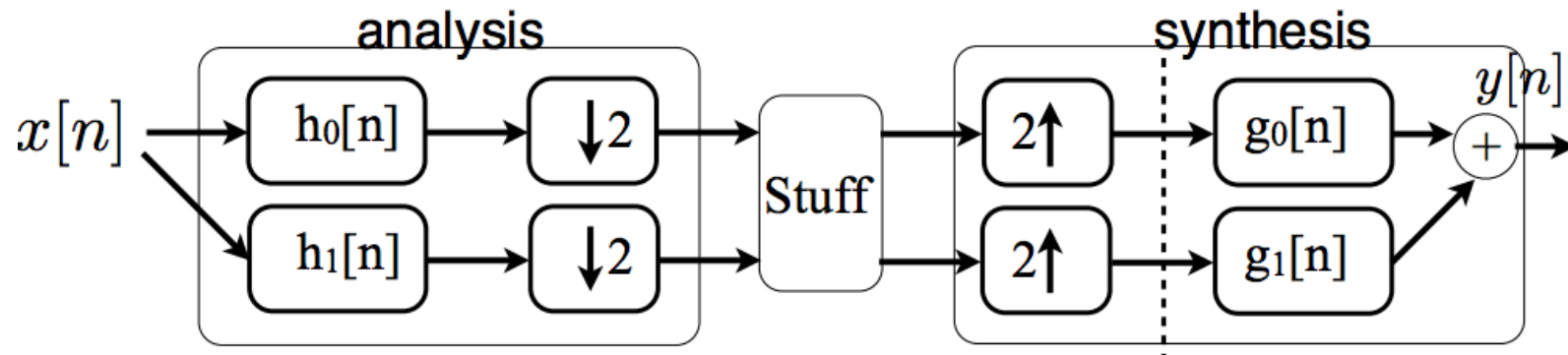
$X(e^{j\omega})$



Non Ideal Filters



Perfect Reconstruction non-Ideal Filters

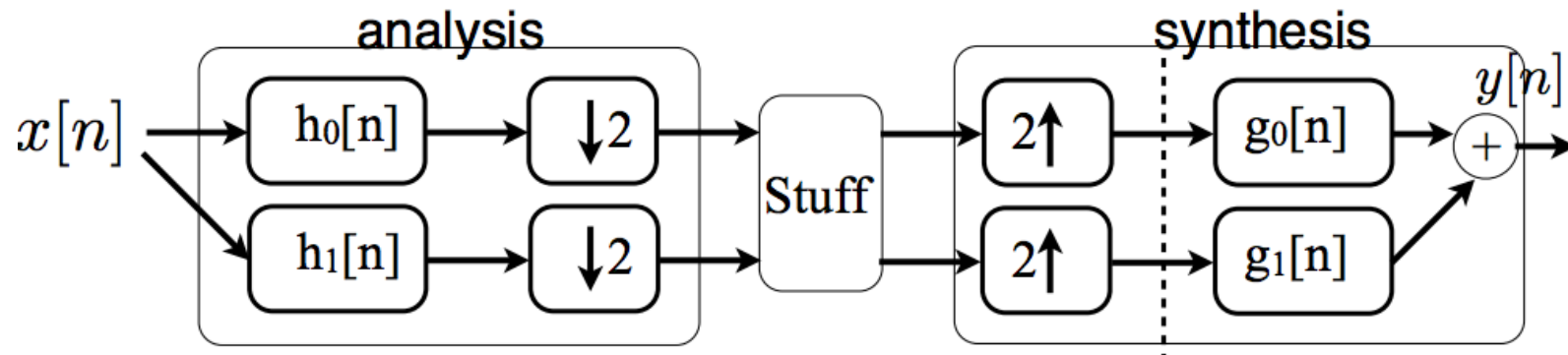


$$\begin{aligned}
 Y(e^{j\omega}) &= \frac{1}{2} [G_0(e^{j\omega})H_0(e^{j\omega}) + G_1(e^{j\omega})H_1(e^{j\omega})] X(e^{j\omega}) \\
 &\quad + \frac{1}{2} [G_0(e^{j\omega})H_0(e^{j(\omega-\pi)}) + G_1(e^{j\omega})H_1(e^{j(\omega-\pi)})] X(e^{j(\omega-\pi)})
 \end{aligned}$$

↑
↑

need to cancel!
aliasing

Quadrature Mirror Filters



Quadrature mirror filters

$$\begin{aligned}
 H_1(e^{j\omega}) &= H_0(e^{j(\omega-\pi)}) \\
 G_0(e^{j\omega}) &= 2H_0(e^{j\omega}) \\
 G_1(e^{j\omega}) &= -2H_1(e^{j\omega})
 \end{aligned}$$

Perfect Reconstruction non-Ideal Filters

$$Y(e^{j\omega}) = \frac{1}{2} [G_0(e^{j\omega})H_0(e^{j\omega}) + G_1(e^{j\omega})H_1(e^{j\omega})] X(e^{j\omega}) \\ + \frac{1}{2} [G_0(e^{j\omega})H_0(e^{j(\omega-\pi)}) + G_1(e^{j\omega})H_1(e^{j(\omega-\pi)})] X(e^{j(\omega-\pi)})$$

↑
need to cancel!

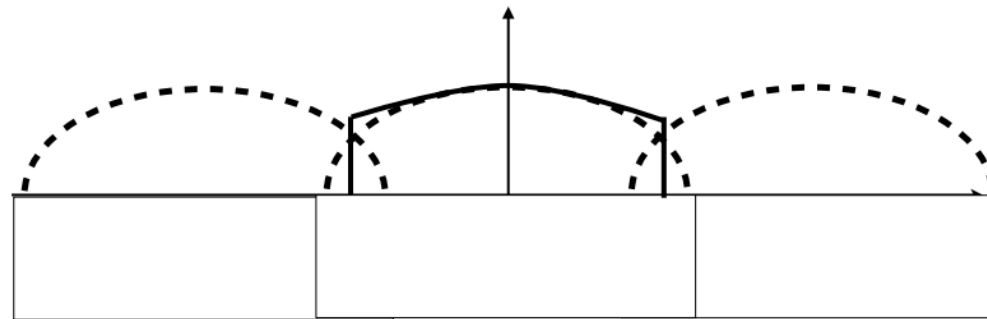
↑
aliasing

$$\begin{aligned} H_1(e^{j\omega}) &= H_0(e^{j(\omega-\pi)}) \\ G_0(e^{j\omega}) &= 2H_0(e^{j\omega}) \\ G_1(e^{j\omega}) &= -2H_1(e^{j\omega}) \end{aligned}$$

ADC

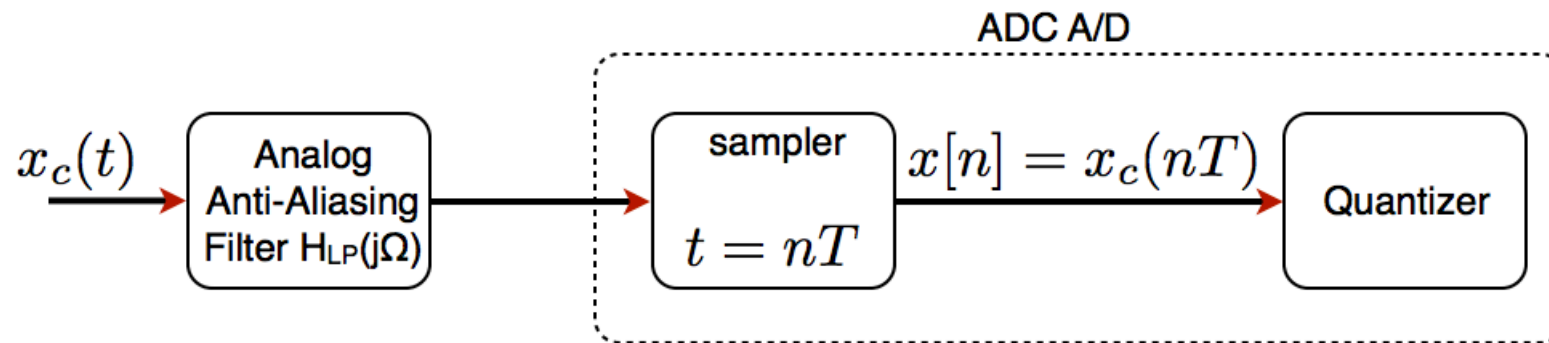
Aliasing

- If $\Omega_N > \Omega_s/2$, $x_r(t)$ an aliased version of $x_c(t)$

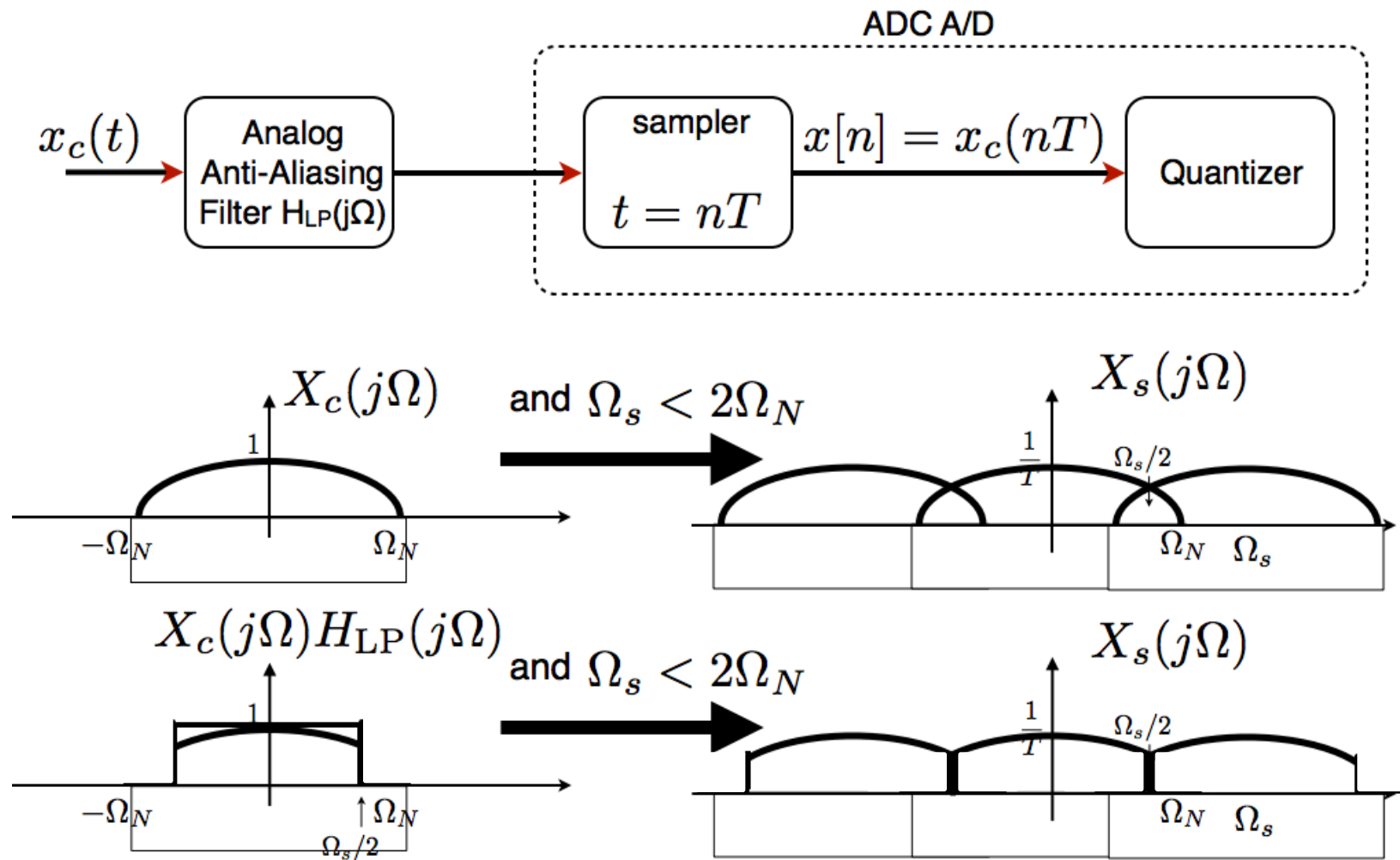


$$X_r(j\Omega) = \begin{cases} TX_s(j\Omega) & \text{if } |\Omega| \leq \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

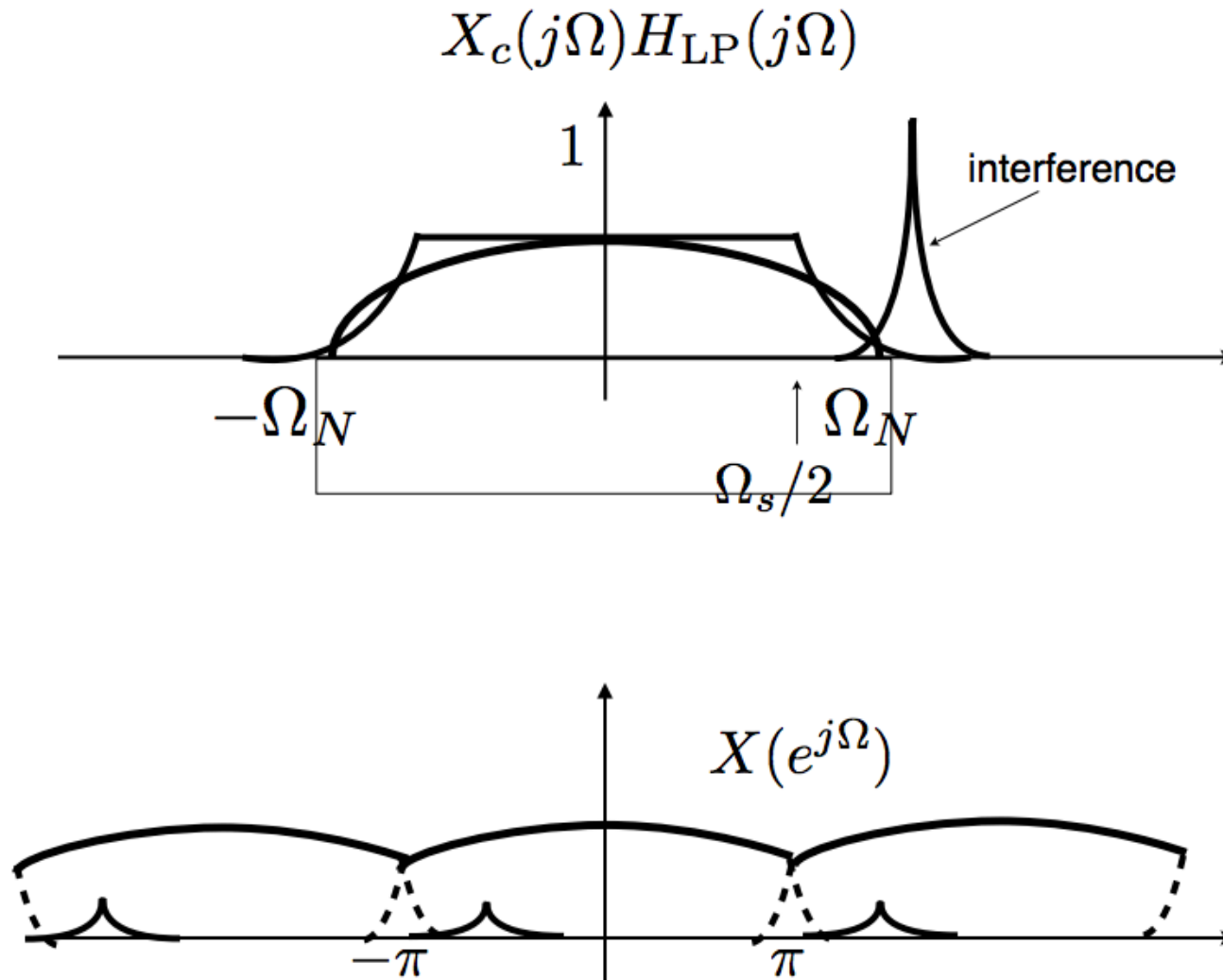
Anti-Aliasing Filter with ADC



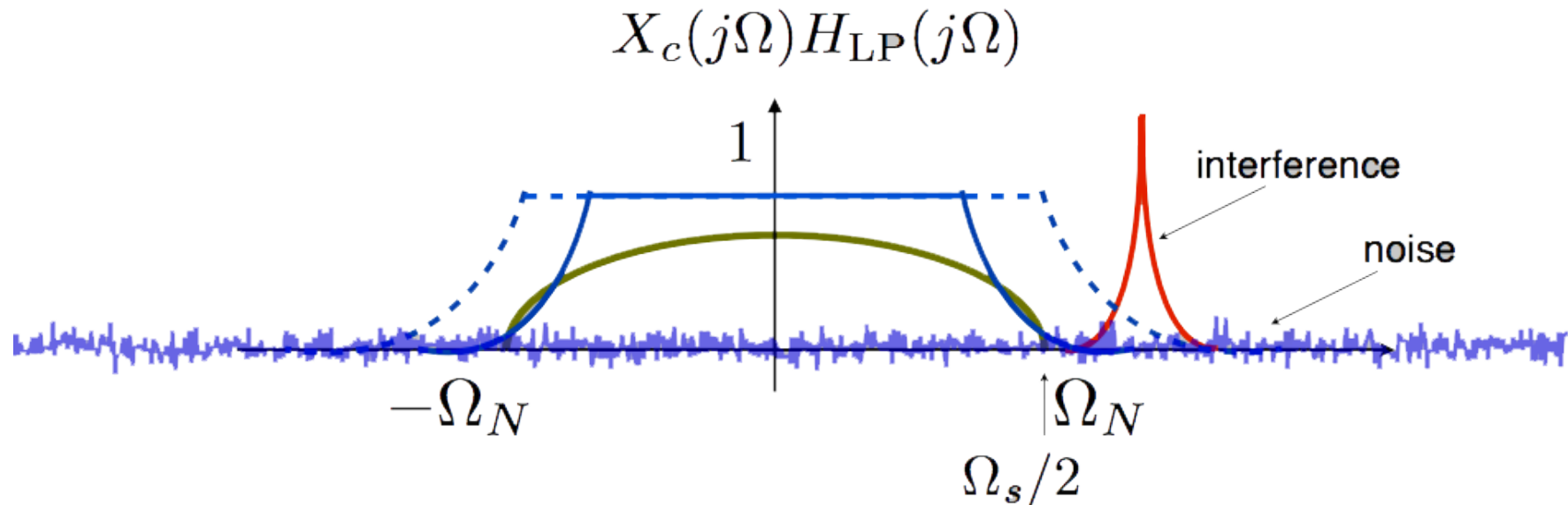
Anti-Aliasing Filter with ADC



Non-Ideal Anti-Aliasing Filter

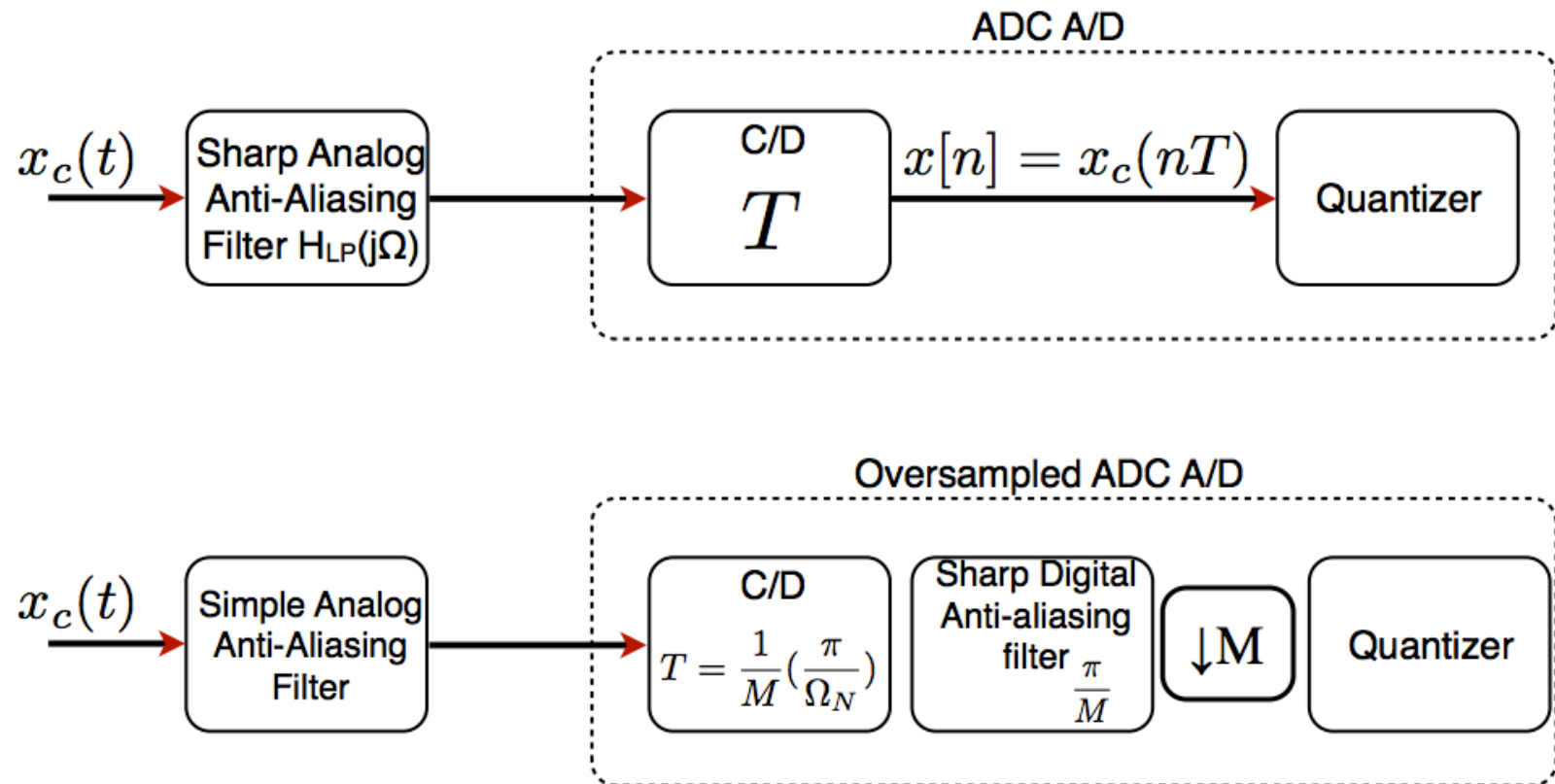


Non-Ideal Anti-Aliasing Filter

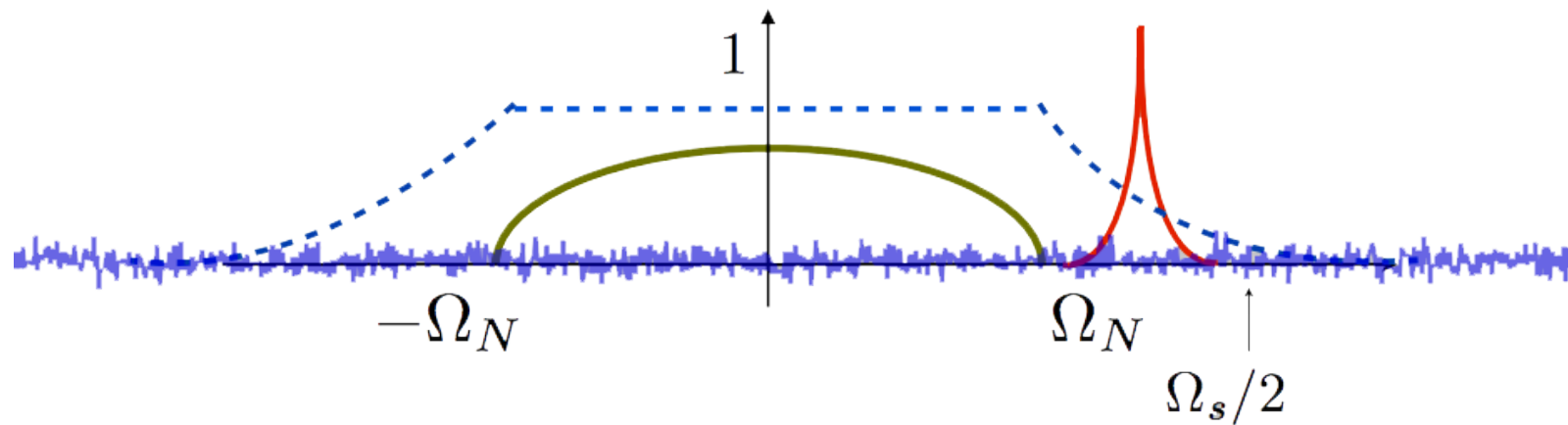


- ❑ Problem: Hard to implement sharp analog filter
- ❑ Solution: Crop part of the signal and suffer from noise and interference

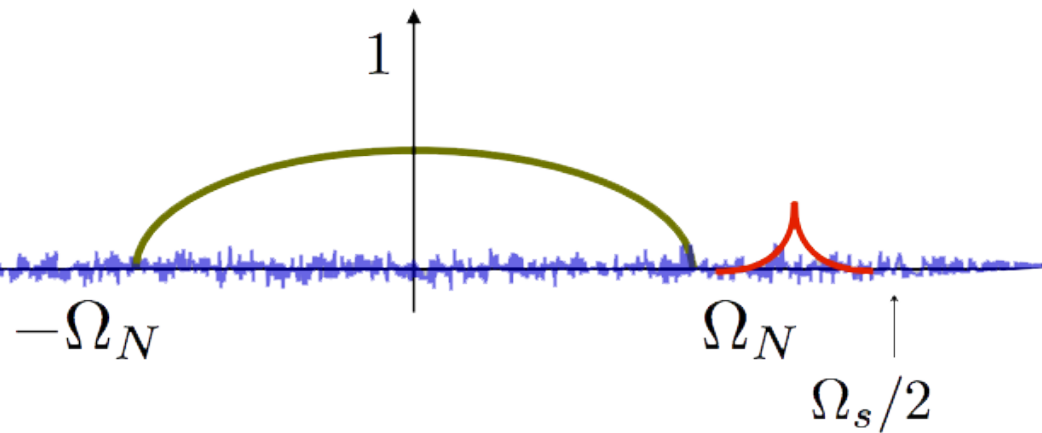
Oversampled ADC



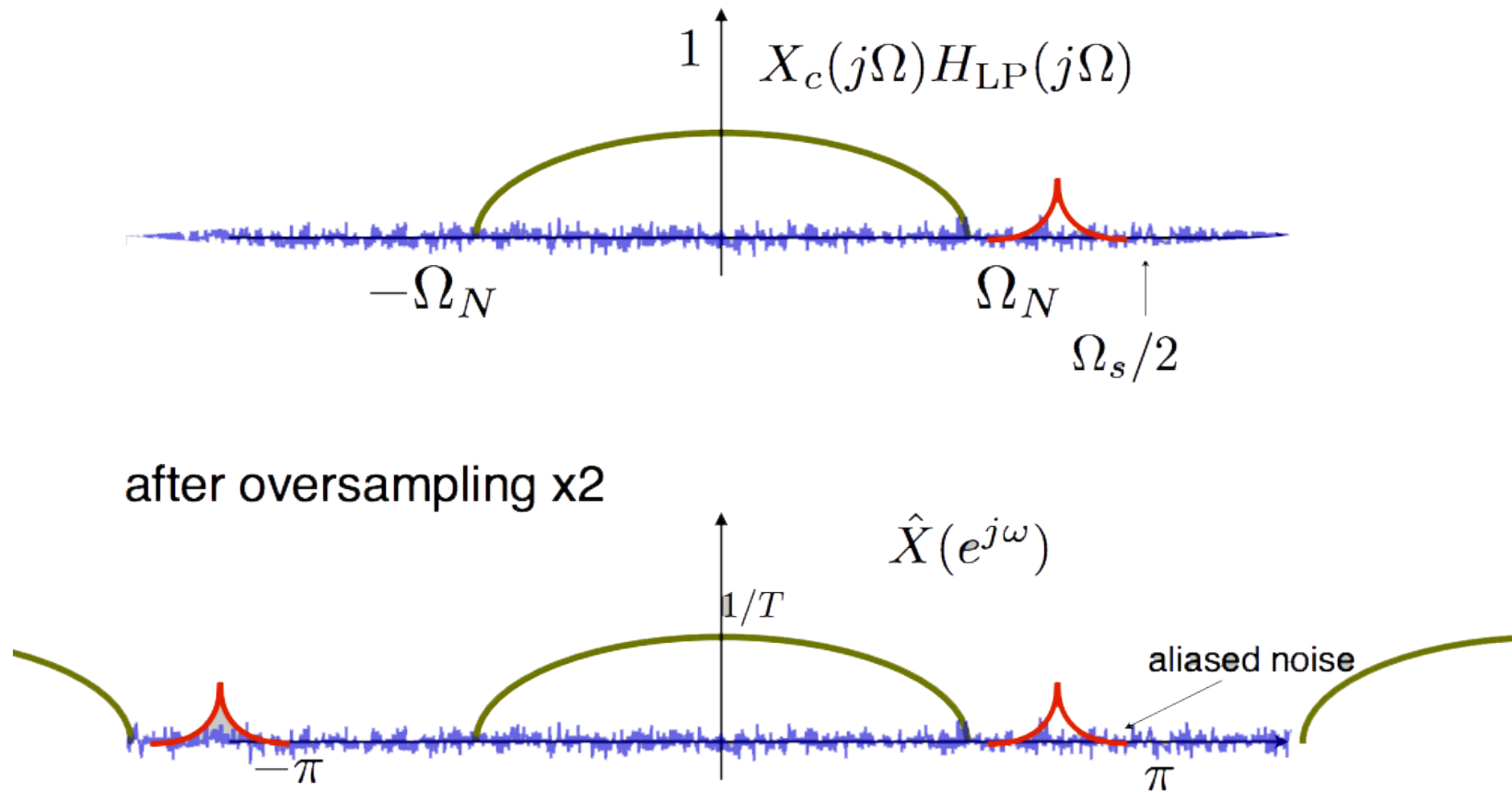
Oversampled ADC



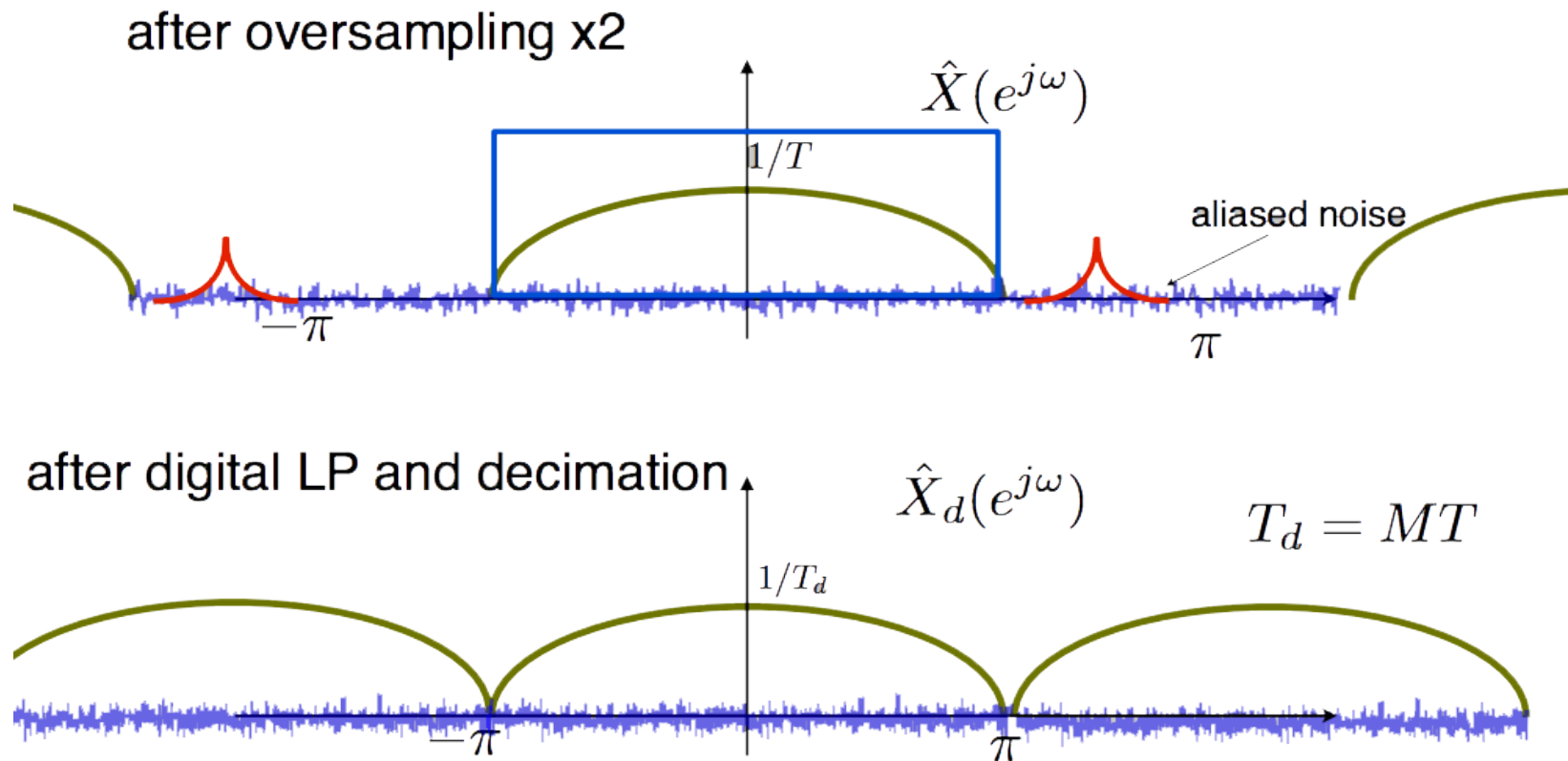
$$X_c(j\Omega)H_{LP}(j\Omega)$$



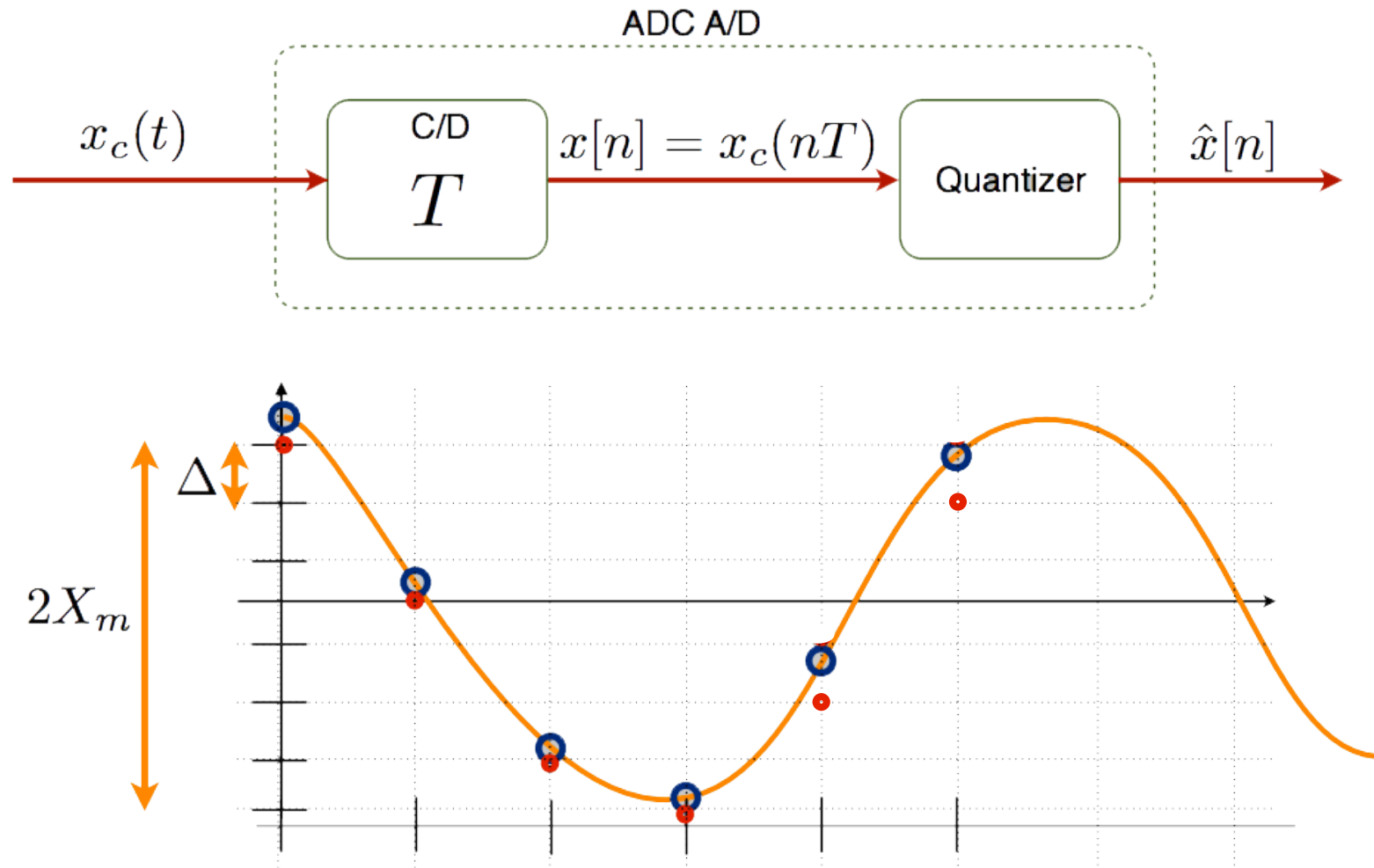
Oversampled ADC



Oversampled ADC



Sampling and Quantization

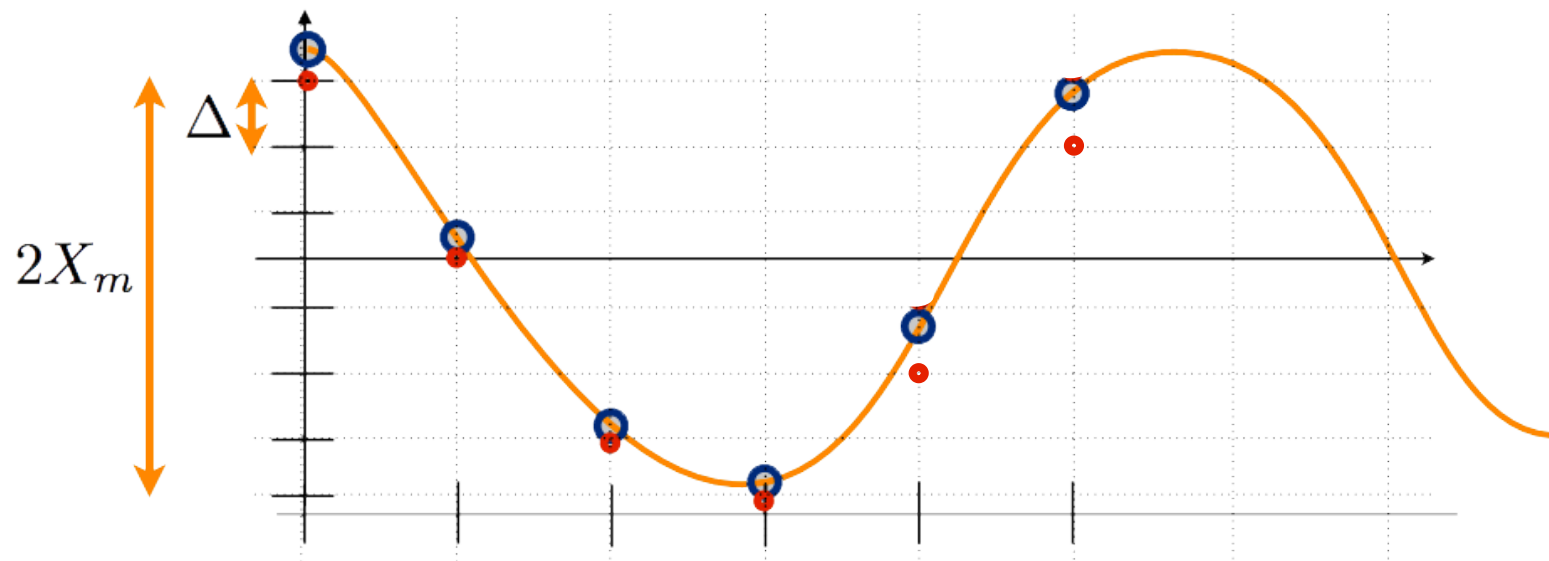


Sampling and Quantization

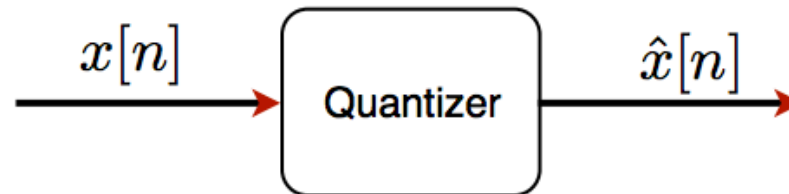
for 2's complement with $B+1$ bits $-1 \leq \hat{x}_B[n] < 1$

$$\Delta = \frac{2X_m}{2^{B+1}} = \frac{X_m}{2^B}$$

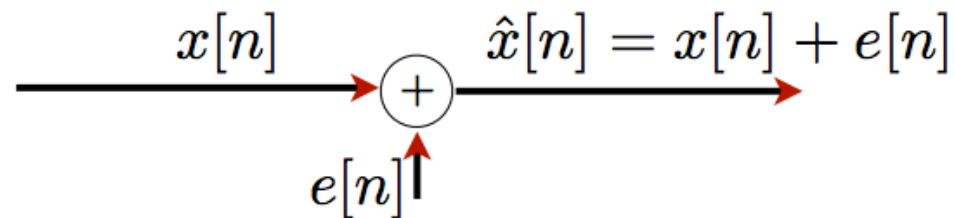
$$\hat{x}[n] = X_m \hat{x}_B[n]$$



Quantization Error



- Model quantization error as noise



- In that case:

$$-\Delta/2 \leq e[n] < \Delta/2$$

$$(-X_m - \Delta/2) < x[n] \leq (X_m - \Delta/2)$$

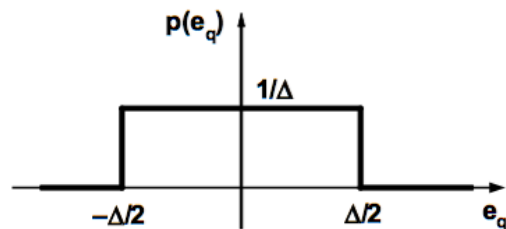


Effect of Quantization Error on Signal

- ❑ Quantization error is a deterministic function of the signal
 - Consequently, the effect of quantization strongly depends on the signal itself
- ❑ Unless, we consider fairly trivial signals, a deterministic analysis is usually impractical
 - More common to look at errors from a statistical perspective
 - "Quantization noise"
- ❑ Two aspects
 - How much noise power (variance) does quantization add to our samples?
 - How is this noise distributed in frequency?

Quantization Error Statistics

- ❑ Crude assumption: $e_q(x)$ has uniform probability density
- ❑ This approximation holds reasonably well in practice when
 - Signal spans large number of quantization steps
 - Signal is "sufficiently active"
 - Quantizer does not overload



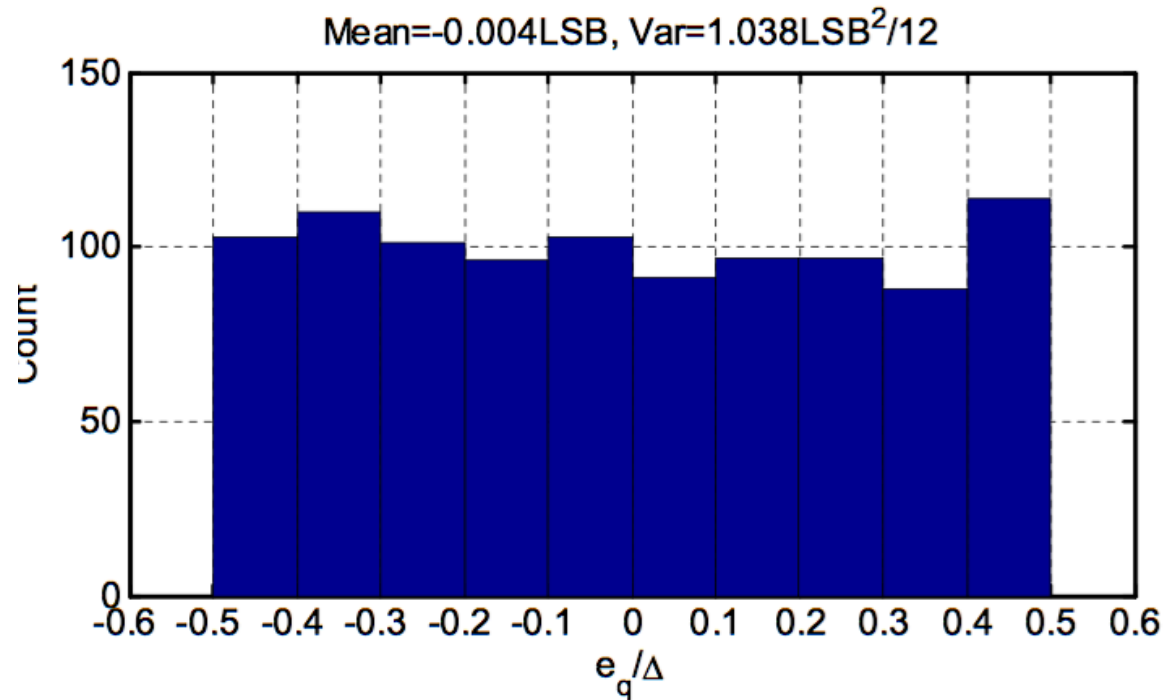
Mean

$$\bar{e} = \int_{-\Delta/2}^{+\Delta/2} \frac{e}{\Delta} de = 0$$

Variance

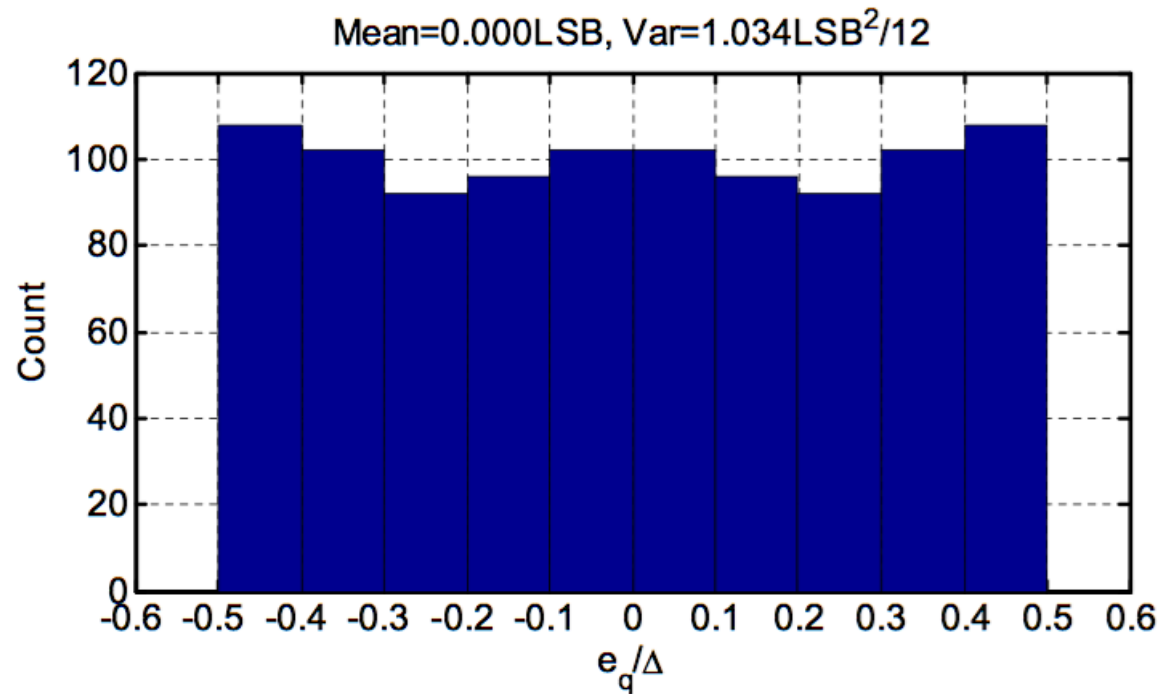
$$\overline{e^2} = \int_{-\Delta/2}^{+\Delta/2} \frac{e^2}{\Delta} de = \frac{\Delta^2}{12}$$

Reality Check



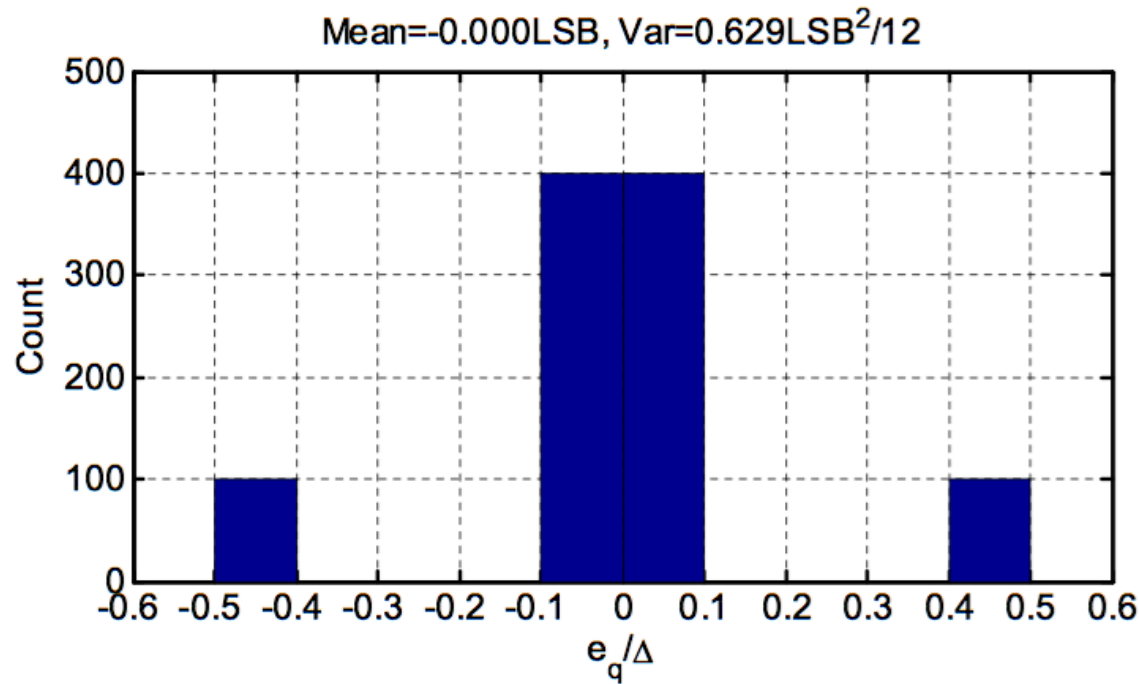
- Shown below is a histogram of e_q in an 8-bit quantizer
 - Input sequence consists of 1000 samples with Gaussian distribution, $4\sigma = \text{FSR}$

Reality Check



- Same as before, but now using a sinusoidal input signal with $f_{\text{sig}}/f_s = 101/1000$

Reality Check



- ❑ Same as before, but now using a sinusoidal input signal with $f_{\text{sig}}/f_s = 100/1000$
- ❑ What went wrong?



Analysis

$$v_{\text{sig}}(n) = \cos\left(2\pi \cdot \frac{f_{\text{sig}}}{f_s} \cdot n\right)$$

- Signal repeats every m samples, where m is the smallest integer that satisfies

$$m \cdot \frac{f_{\text{sig}}}{f_s} = \text{integer}$$

$$m \cdot \frac{101}{1000} = \text{integer} \Rightarrow m=1000$$

$$m \cdot \frac{100}{1000} = \text{integer} \Rightarrow m=10$$

- This means that in the last case $e_q(n)$ consists at best of 10 different values, even though we took 1000 samples

Noise Model for Quantization Error

□ Assumptions:

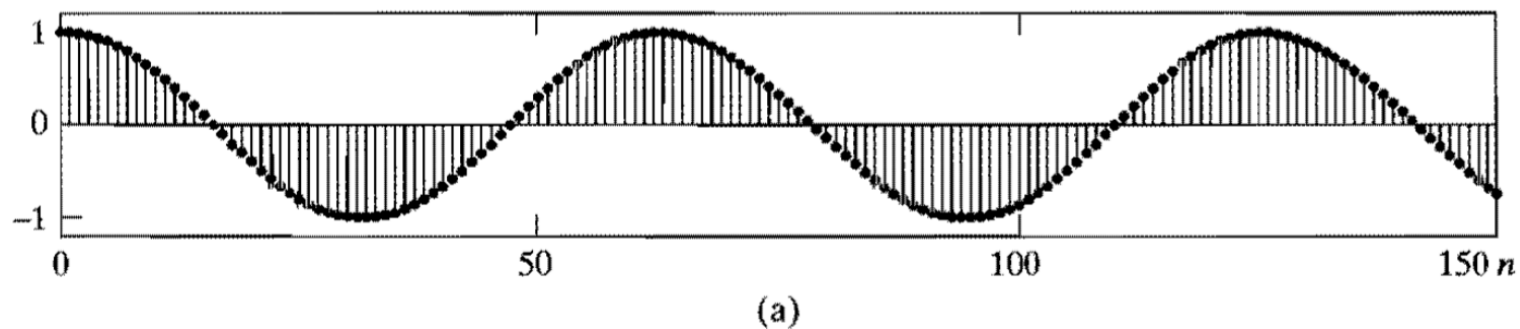
- Model $e[n]$ as a sample sequence of a stationary random process
- $e[n]$ is not correlated with $x[n]$
- $e[n]$ not correlated with $e[m]$ where $m \neq n$ (white noise)
- $e[n] \sim U[-\Delta/2, \Delta/2]$ (uniform pdf)

□ Result:

- Variance is: $\sigma_e^2 = \frac{\Delta^2}{12}$, or $\sigma_e^2 = \frac{2^{-2B} X_m^2}{12}$ since $\Delta = 2^{-B} X_m$
- Assumptions work well for signals that change rapidly, are not clipped, and for small Δ

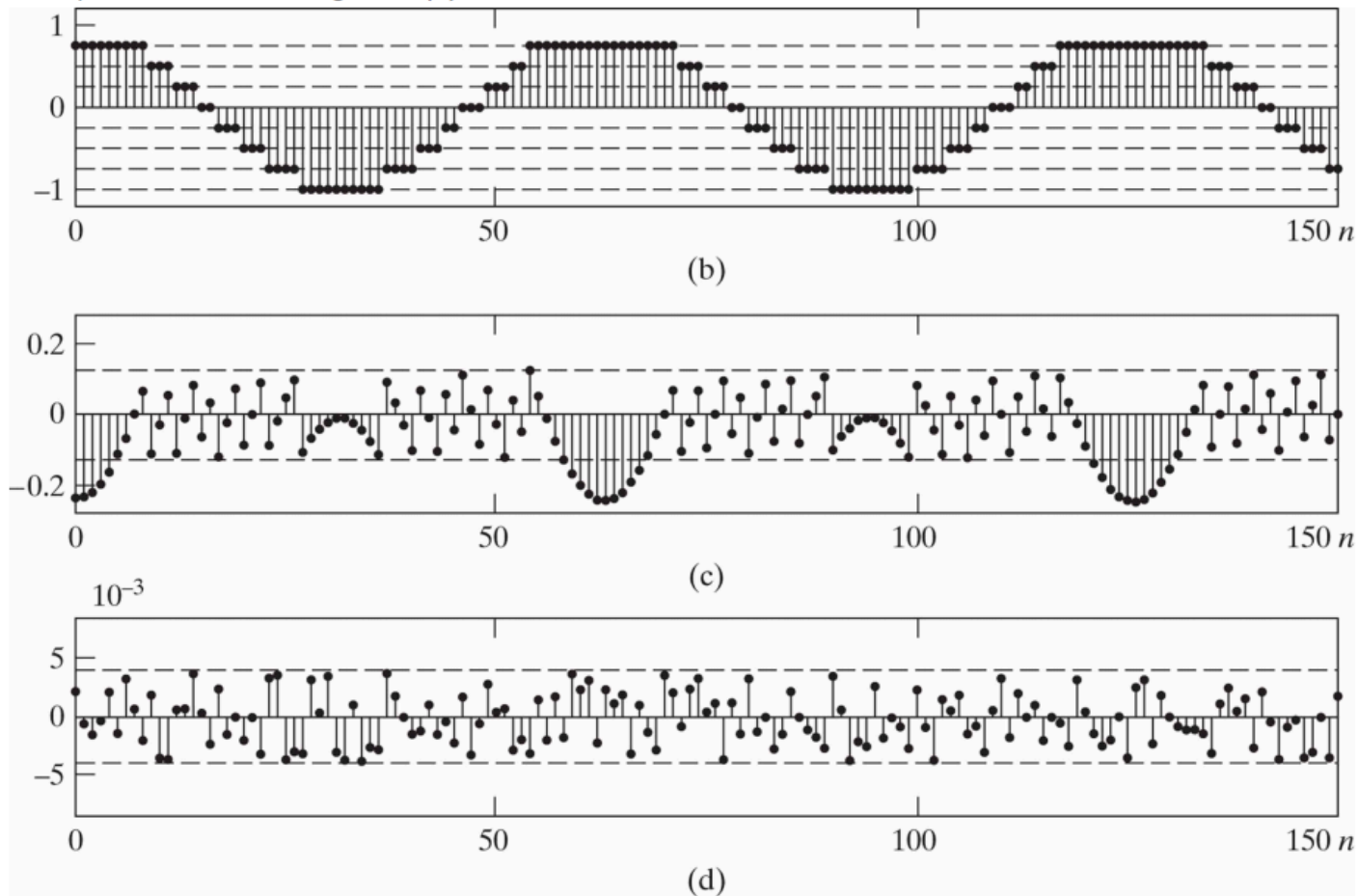
Quantization Noise

- **Figure 4.57** Example of quantization noise. (a) Unquantized samples of the signal $x[n] = 0.99\cos(n/10)$.



Quantization Noise

Figure 4.57 (continued) (b) Quantized samples of the cosine waveform in part (a) with a 3-bit quantizer. (c) Quantization error sequence for 3-bit quantization of the signal in (a). (d) Quantization error sequence for 8-bit quantization of the signal in (a).



Signal-to-Quantization-Noise Ratio

- For uniform $B+1$ bits quantizer

$$\begin{aligned} SNR_Q &= 10 \log_{10} \left(\frac{\sigma_x^2}{\sigma_e^2} \right) \\ &= 10 \log_{10} \left(\frac{12 \cdot 2^{2B} \sigma_x^2}{X_m^2} \right) \end{aligned}$$

$$SNR_Q = 6.02B + 10.8 - 20 \log_{10} \left(\frac{X_m}{\sigma_x} \right) \begin{matrix} \text{Quantizer range} \\ \text{rms of amp} \end{matrix}$$



Signal-to-Quantization-Noise Ratio

$$\text{SNR}_Q = 6.02B + 10.8 - 20 \log_{10} \left(\frac{X_m}{\sigma_x} \right) \frac{\text{Quantizer range}}{\text{rms of amp}}$$

- ❑ Improvement of 6dB with every bit
- ❑ The range of the quantization must be adapted to the rms amplitude of the signal
 - Tradeoff between clipping and noise!
 - Often use pre-amp
 - Sometimes use analog auto gain controller (AGC)

Signal-to-Quantization-Noise Ratio

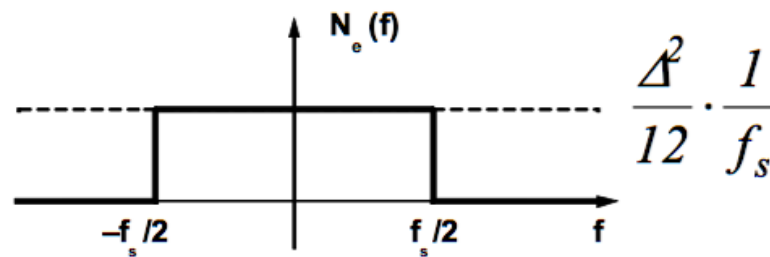
- Assuming full-scale sinusoidal input, we have

$$\text{SQNR} = \frac{P_{\text{sig}}}{P_{\text{qnoise}}} = \frac{\frac{1}{2} \left(\frac{2^B \Delta}{2} \right)^2}{\frac{\Delta^2}{12}} = 1.5 \times 2^{2B} = 6.02B + 1.76 \text{ dB}$$

B (Number of Bits)	SQNR
8	50dB
12	74dB
16	98dB
20	122dB

Quantization Noise Spectrum

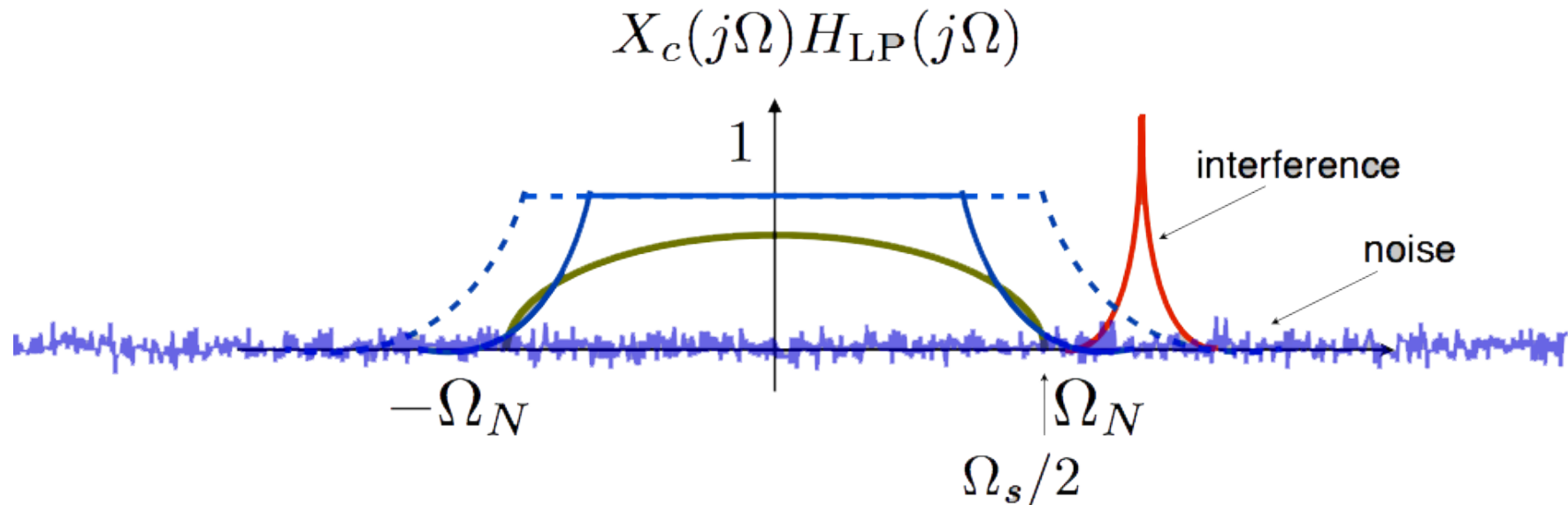
- If the quantization error is "sufficiently random", it also follows that the noise power is uniformly distributed in frequency



References

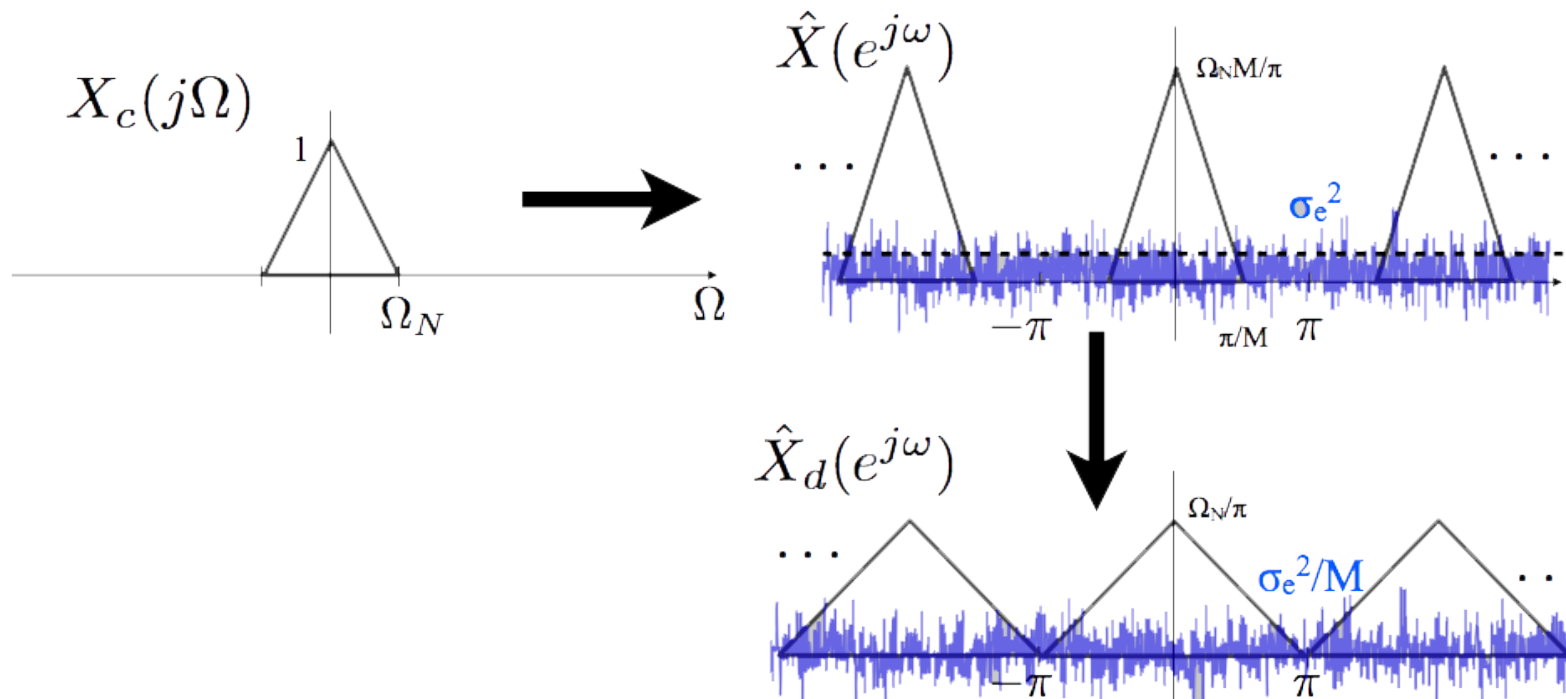
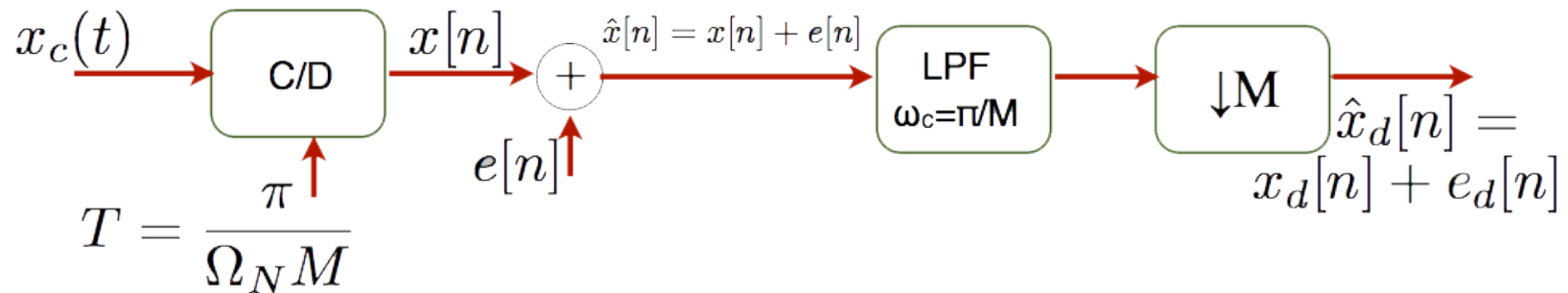
- W. R. Bennett, "Spectra of quantized signals," Bell Syst. Tech. J., pp. 446-72, July 1988.
- B. Widrow, "A study of rough amplitude quantization by means of Nyquist sampling theory," IRE Trans. Circuit Theory, vol. CT-3, pp. 266-76, 1956.

Non-Ideal Anti-Aliasing Filter



- ❑ Problem: Hard to implement sharp analog filter
- ❑ Solution: Crop part of the signal and suffer from noise and interference

Quantization Noise with Oversampling



Quantization Noise with Oversampling

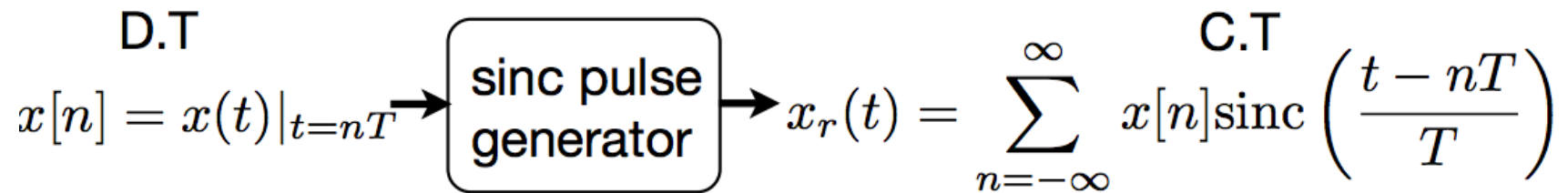
- ❑ Energy of $x_d[n]$ equals energy of $x[n]$
 - No filtering of signal!
- ❑ Noise variance is reduced by factor of M

$$\text{SNR}_Q = 6.02B + 10.8 - 20 \log_{10} \left(\frac{X_m}{\sigma_x} \right) + 10 \log_{10} M$$

- ❑ For doubling of M we get 3dB improvement, which is the same as 1/2 a bit of accuracy
 - With oversampling of 16 with 8bit ADC we get the same quantization noise as 10bit ADC!

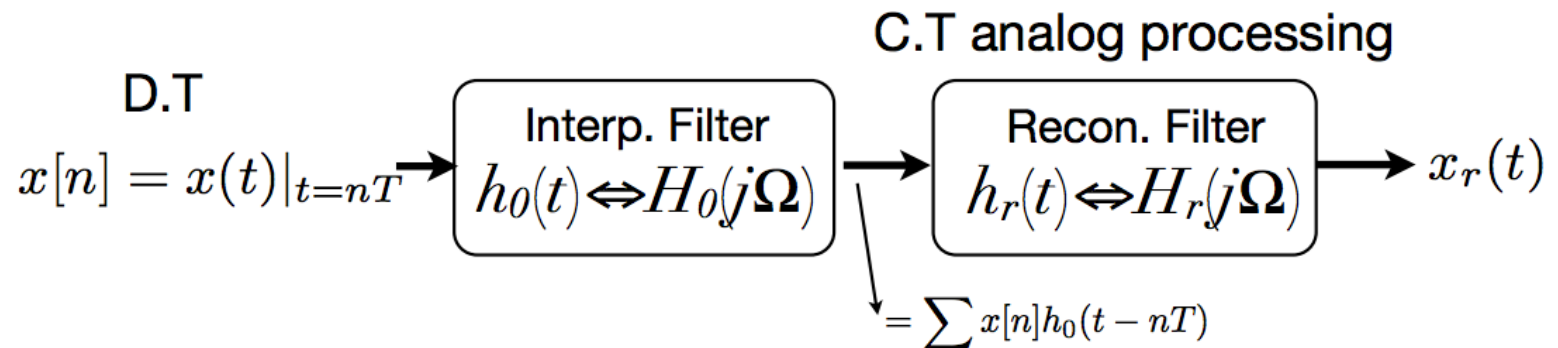
Practical DAC

Practical DAC

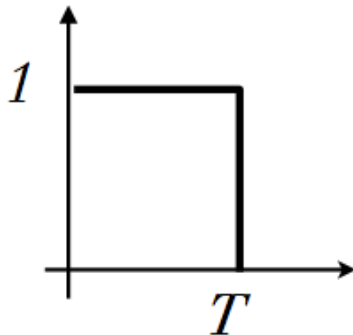


- ❑ Scaled train of sinc pulses
- ❑ Difficult to generate sinc \rightarrow Too long!

Practical DAC



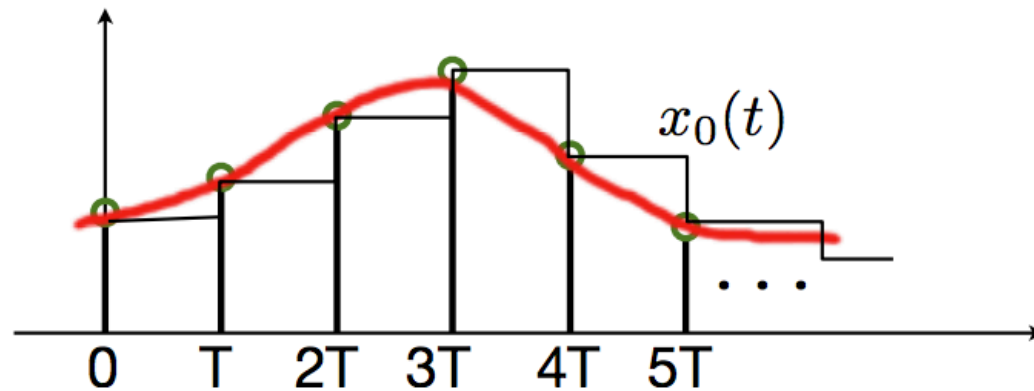
- $h_0(t)$ is finite length pulse \rightarrow easy to implement
- For example: zero-order hold



$$H_0(j\Omega) = T e^{-j\Omega \frac{T}{2}} \text{sinc}\left(\frac{\Omega}{\Omega_s}\right)$$

Practical DAC

Zero-Order-Hold interpolation



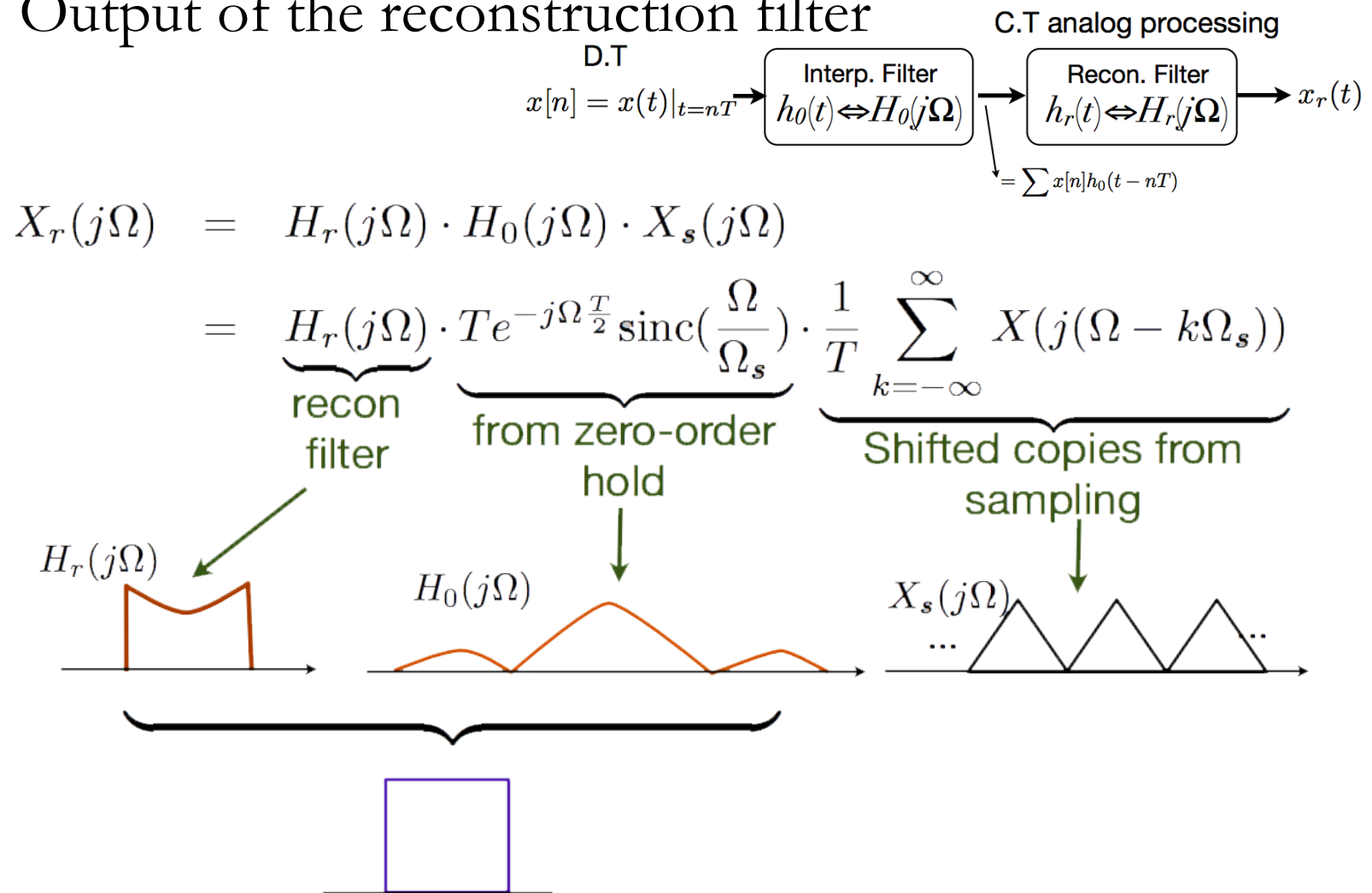
$$x_0(t) = \sum_{n=-\infty}^{\infty} x[n]h_0(t - nT) = h_0(t) * x_s(t)$$

Taking a FT:

$$\begin{aligned} X(j\Omega) &= H_0(j\Omega)X_s(j\Omega) \\ &= H_0(j\Omega)\frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(\Omega - k\Omega_s)) \end{aligned}$$

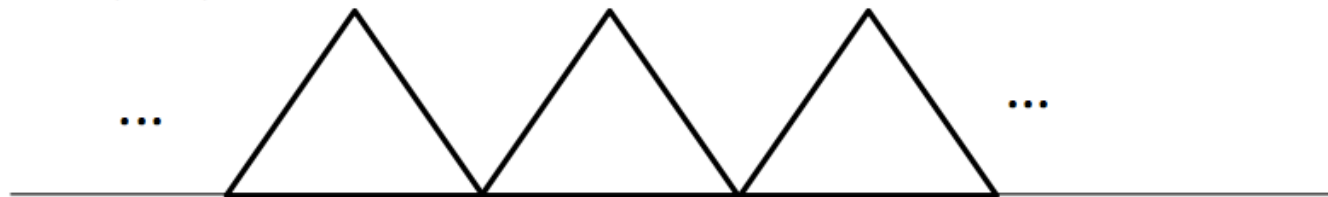
Practical DAC

□ Output of the reconstruction filter



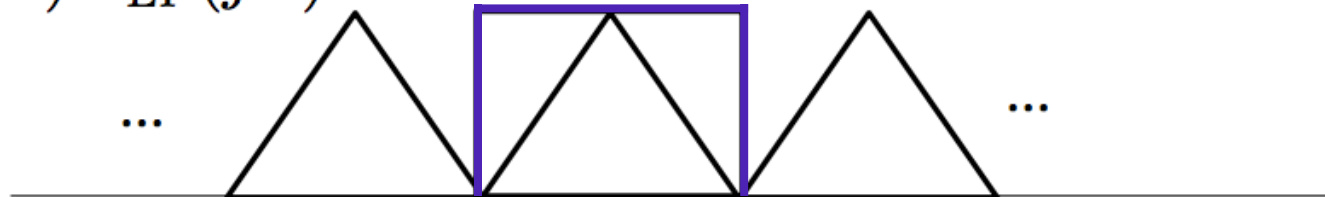
Practical DAC

$$X_s(j\Omega)$$



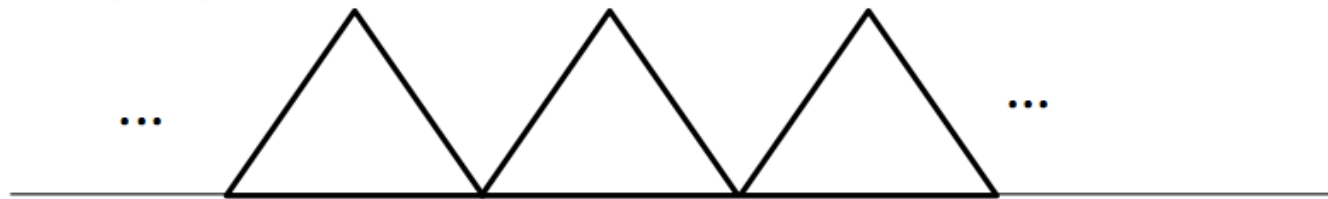
Ideally:

$$X_s(j\Omega)H_{LP}(j\Omega)$$

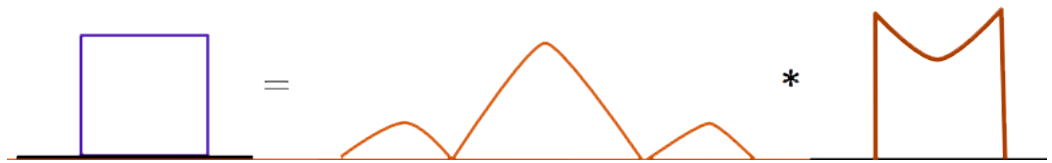


Practical DAC

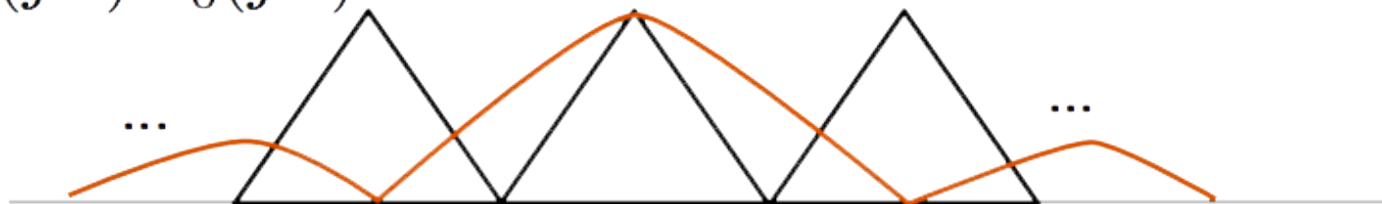
$$X_s(j\Omega)$$



Practically:

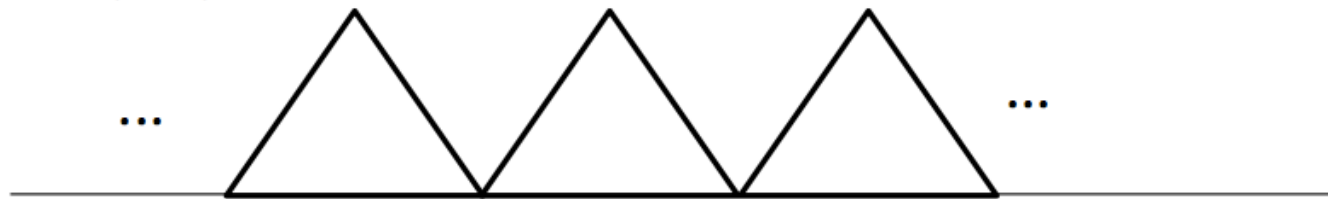


$$X_s(j\Omega)H_0(j\Omega)$$



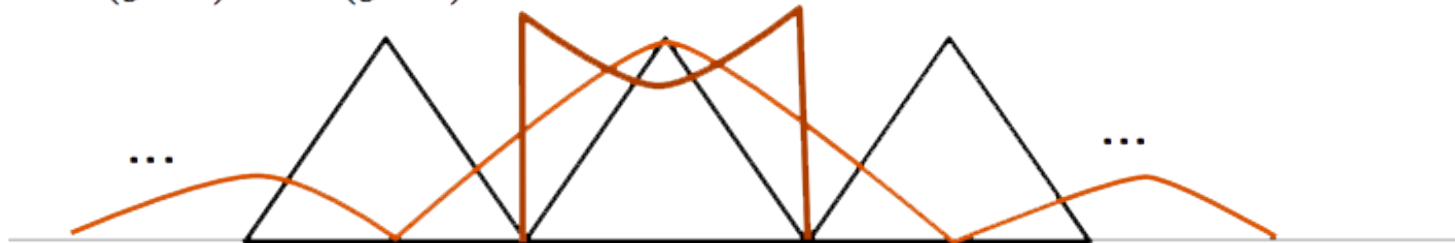
Practical DAC

$$X_s(j\Omega)$$

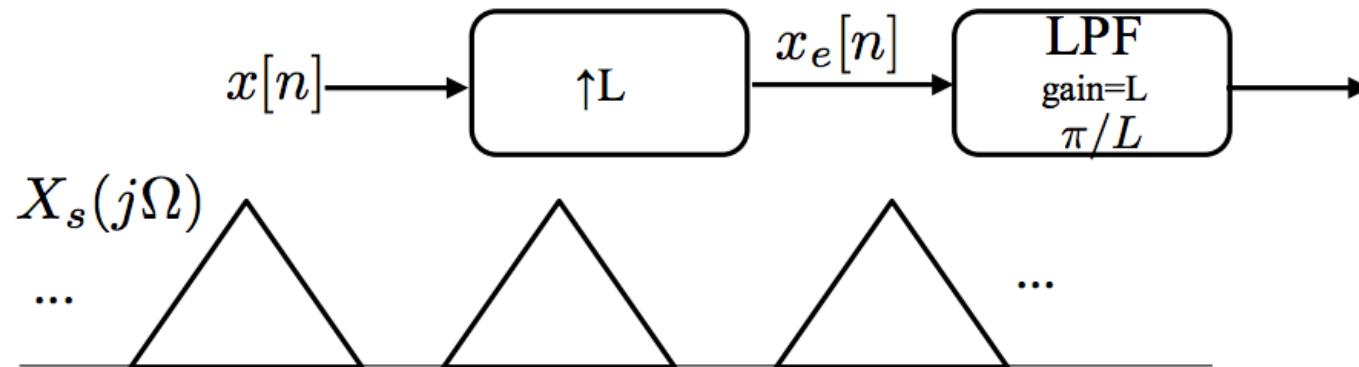


Practically:

$$X_s(j\Omega)H_0(j\Omega)H_r(j\Omega)$$

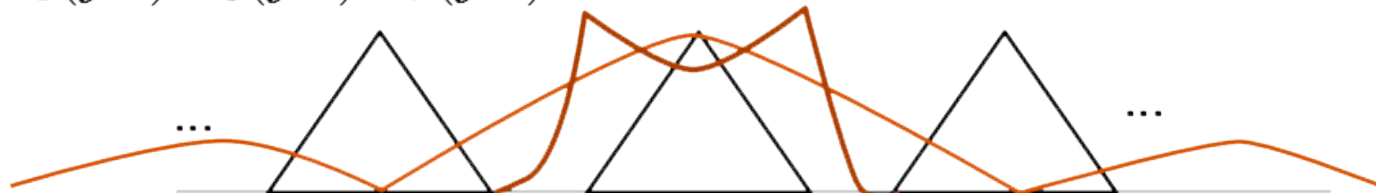


Practical DAC with Upsampling



Practically:

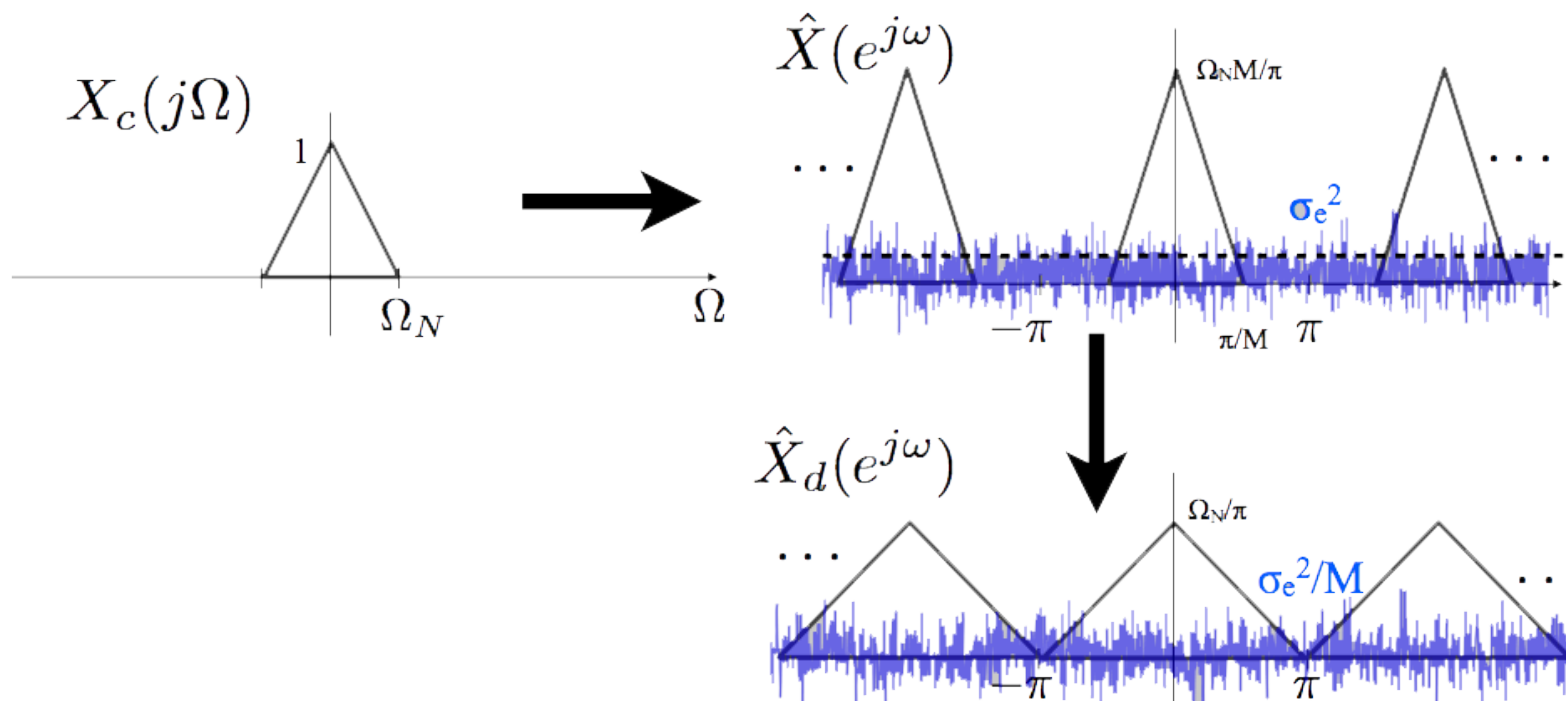
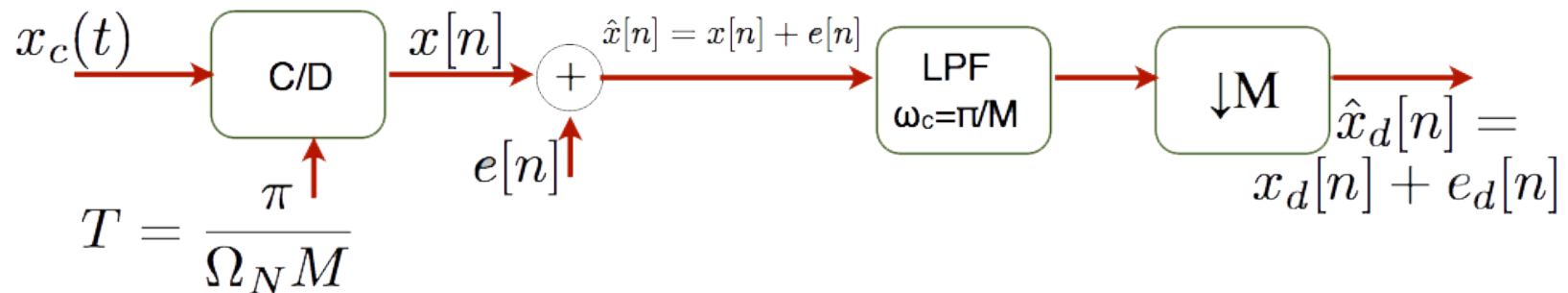
$$X_s(j\Omega)H_0(j\Omega)H_r(j\Omega)$$



Noise Shaping



Quantization Noise with Oversampling



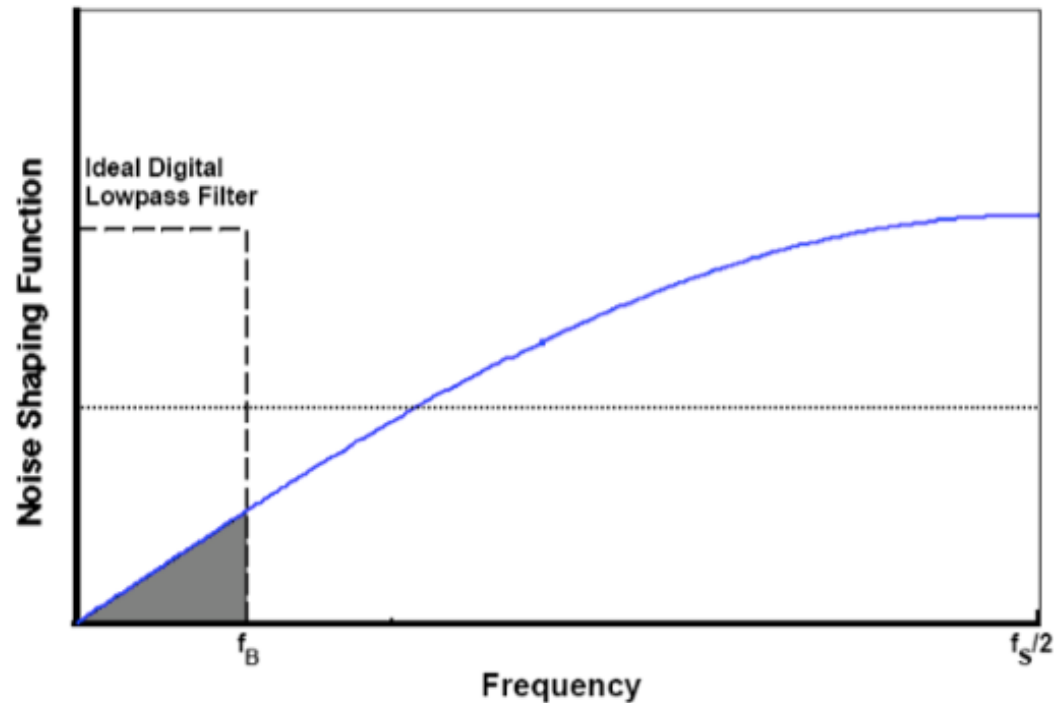
Quantization Noise with Oversampling

- ❑ Energy of $x_d[n]$ equals energy of $x[n]$
 - No filtering of signal!
- ❑ Noise variance is reduced by factor of M

$$\text{SNR}_Q = 6.02B + 10.8 - 20 \log_{10} \left(\frac{X_m}{\sigma_x} \right) + 10 \log_{10} M$$

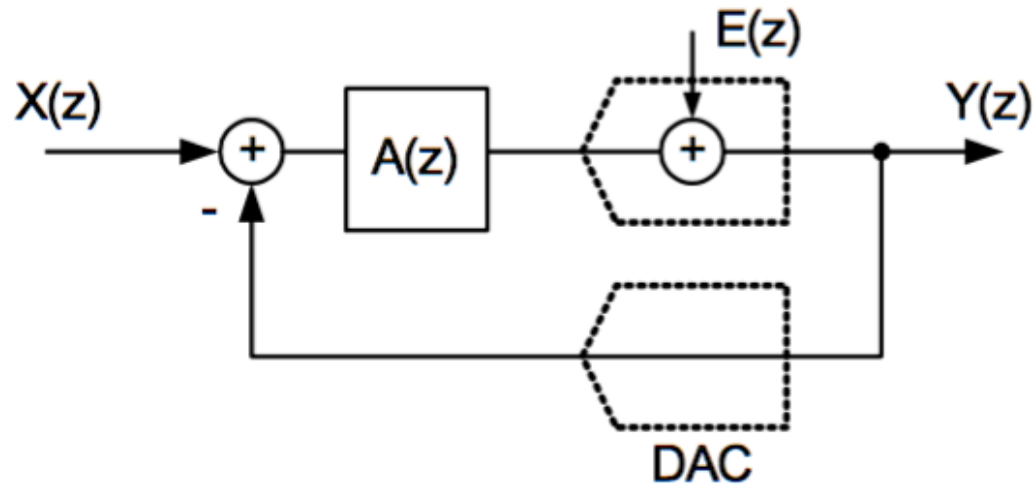
- ❑ For doubling of M we get 3dB improvement, which is the same as 1/2 a bit of accuracy
 - With oversampling of 16 with 8bit ADC we get the same quantization noise as 10bit ADC!

Noise Shaping



- ❑ Idea: "Somehow" build an ADC that has most of its quantization noise at high frequencies
- ❑ Key: Feedback

Noise Shaping Using Feedback



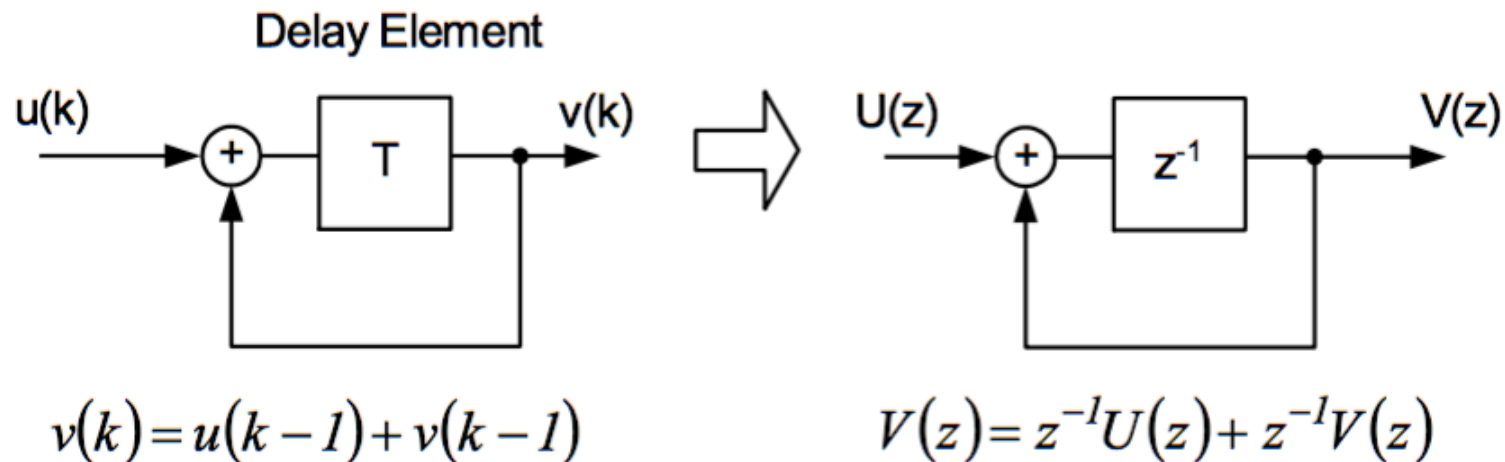
$$\begin{aligned}
 Y(z) &= E(z) + A(z)X(z) - A(z)Y(z) \\
 &= E(z) \frac{1}{1 + A(z)} + X(z) \frac{A(z)}{1 + A(z)} \\
 &= E(z) \underbrace{H_E(z)}_{\text{Noise Transfer Function}} + X(z) \underbrace{H_X(z)}_{\text{Signal Transfer Function}}
 \end{aligned}$$

Noise Shaping Using Feedback

$$Y(z) = E(z) \underbrace{\frac{1}{1 + A(z)}}_{\text{Noise Transfer Function}} + X(z) \underbrace{\frac{A(z)}{1 + A(z)}}_{\text{Signal Transfer Function}}$$

- ❑ Objective
 - Want to make STF unity in the signal frequency band
 - Want to make NTF "small" in the signal frequency band
- ❑ If the frequency band of interest is around DC ($0 \dots f_B$) we achieve this by making $|A(z)| \gg 1$ at low frequencies
 - Means that $\text{NTF} \ll 1$
 - Means that $\text{STF} \approx 1$

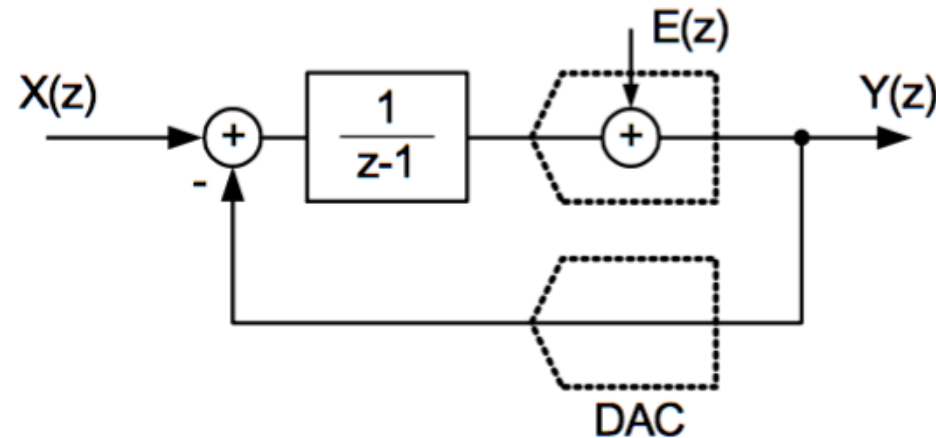
Discrete Time Integrator



$$\frac{V(z)}{U(z)} = \frac{z^{-1}}{1 - z^{-1}} = \frac{1}{z - 1} \quad z = e^{j\omega T}$$

❑ "Infinite gain" at DC ($\omega=0, z=1$)

First Order Sigma-Delta Modulator

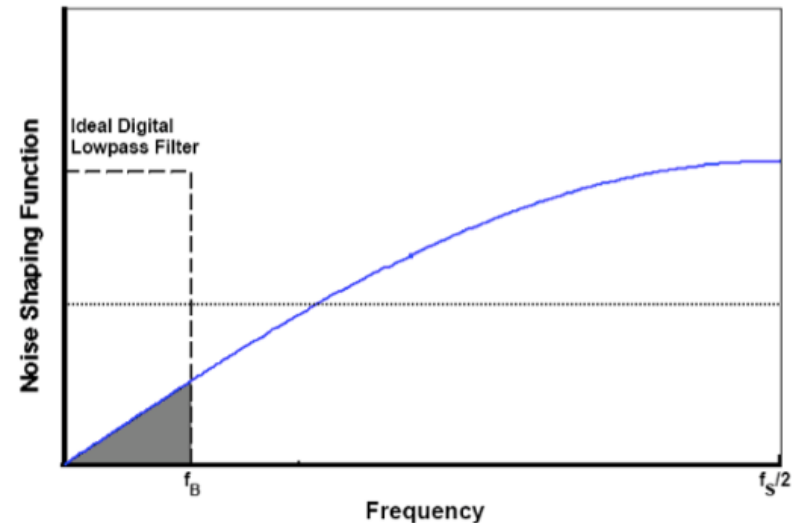


$$\begin{aligned}
 Y(z) &= E(z) \frac{1}{1 + \frac{1}{z-1}} + X(z) \frac{\frac{1}{z-1}}{1 + \frac{1}{z-1}} \\
 &= E(z)(1 - z^{-1}) + X(z)z^{-1}
 \end{aligned}$$

- ❑ Output is equal to delayed input plus filtered quantization noise

NTF Frequency Domain Analysis

$$\begin{aligned}H_e(z) &= 1 - z^{-1} \\H_e(j\omega) &= (1 - e^{-j\omega T}) = 2e^{-j\omega T/2} \left(\frac{e^{j\omega T/2} - e^{-j\omega T/2}}{2} \right) \\&= 2e^{-j\frac{\omega T}{2}} \left(j \sin\left(\frac{\omega T}{2}\right) \right) = 2 \sin\left(\frac{\omega T}{2}\right) e^{-j\frac{\omega T - \pi}{2}} \\|H_e(f)| &= 2 \left| \sin(\pi f T) \right| = 2 \left| \sin\left(\pi \frac{f}{f_s}\right) \right|\end{aligned}$$



- ❑ "First order noise Shaping"
 - Quantization noise is attenuated at low frequencies, amplified at high frequencies

In-Band Quantization Noise

- ❑ Question: If we had an ideal digital lowpass, what is the achieved SQNR as a function of oversampling ratio?
- ❑ Can integrate shaped quantization noise spectrum up to f_B and compare to full-scale signal

$$\begin{aligned} P_{qnoise} &= \int_0^{f_B} \frac{\Delta^2}{12} \cdot \frac{2}{f_s} \cdot \left[2 \sin\left(\pi \frac{f}{f_s}\right) \right]^2 df \\ &\cong \int_0^{f_B} \frac{\Delta^2}{12} \cdot \frac{2}{f_s} \cdot \left[2\pi \frac{f}{f_s} \right]^2 df \\ &\cong \frac{\Delta^2}{12} \cdot \frac{\pi^2}{3} \left[\frac{2f_B}{f_s} \right]^3 = \frac{\Delta^2}{12} \cdot \frac{\pi^2}{3} \frac{1}{M^3} \end{aligned}$$

In-Band Quantization Noise

- Assuming a full-scale sinusoidal signal, we have

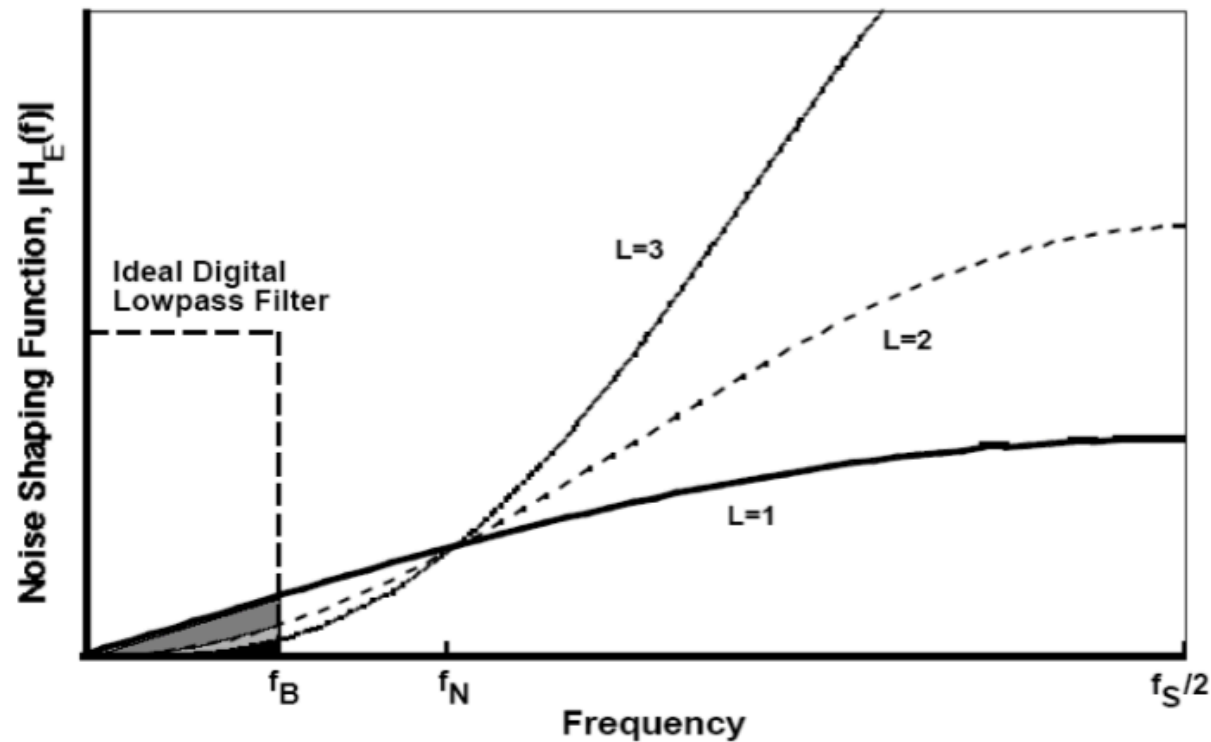
$$SQNR \cong \frac{P_{sig}}{P_{qnoise}} = \frac{\frac{1}{2} \left(\frac{(2^B - 1)\Delta}{2} \right)^2}{\frac{\Delta^2}{12} \cdot \frac{\pi^2}{3} \frac{1}{M^3}} = 1.5 \times (2^B - 1)^2 \times \underbrace{\frac{3}{\pi^2} \times M^3}_{\text{Due to noise shaping \& digital filter}}$$
$$\cong 1.76 + 6.02B - 5.2 + 30 \log(M) \quad [dB] \quad (\text{for large } B)$$

- Each 2x increase in M results in 8x SQNR improvement
 - Also added 1/2 bit resolution

Higher Order Noise Shaping

- L^{th} order noise transfer function

$$H_E(z) = (1 - z^{-1})^L$$





Big Ideas

- ❑ Multi-Rate Filter Banks (con't)
 - Operating on different frequency bands at lower sampling rates
- ❑ Data Converters
 - Oversampling to reduce interference and quantization noise → increase ENOB (effective number of bits)
 - Practical DACs use practical interpolation and reconstruction filters with oversampling
- ❑ Noise Shaping
 - Use feedback to reduce oversampling factor



Admin

- ❑ HW 4 extended to Tuesday at midnight
 - Typo in code in MATLAB problem, corrected handout
 - See Piazza for more information
- ❑ New tentative HW schedule posted