

# ESE 531: Digital Signal Processing

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Lec 16: March 23, 2017  
Design of FIR/IIR Filters



# Midterm

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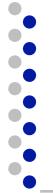
- Midterm
  - Mean: 74.5
  - Standard Dev: 13.7



# Linear Filter Design

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- ❑ Used to be an art
  - Now, lots of tools to design optimal filters
- ❑ For DSP there are two common classes
  - Infinite impulse response IIR
  - Finite impulse response FIR
- ❑ Both classes use finite order of parameters for design
- ❑ Today we will focus on FIR designs
  - And we will end early today, because I have to leave early....

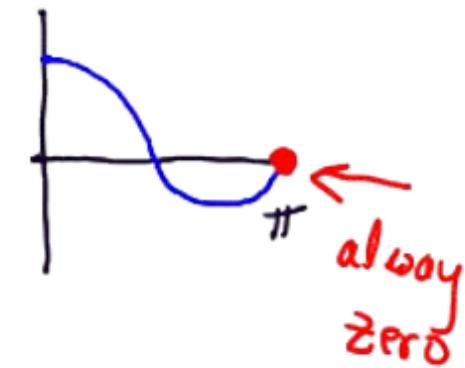
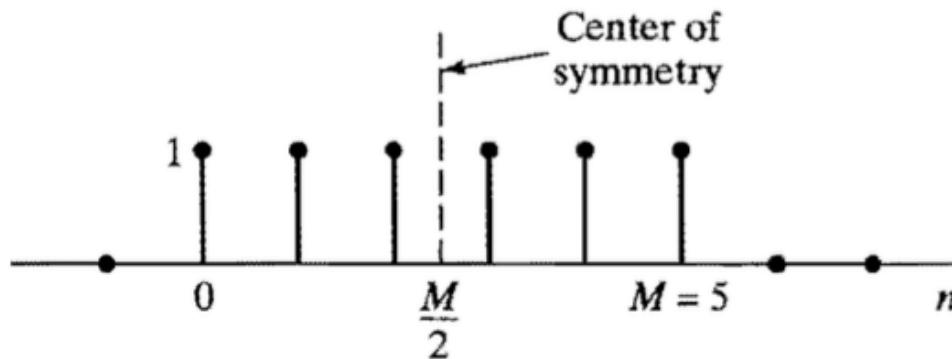
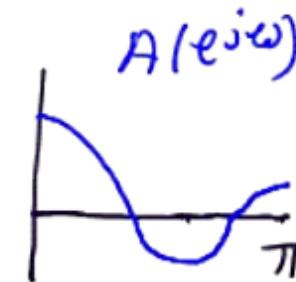
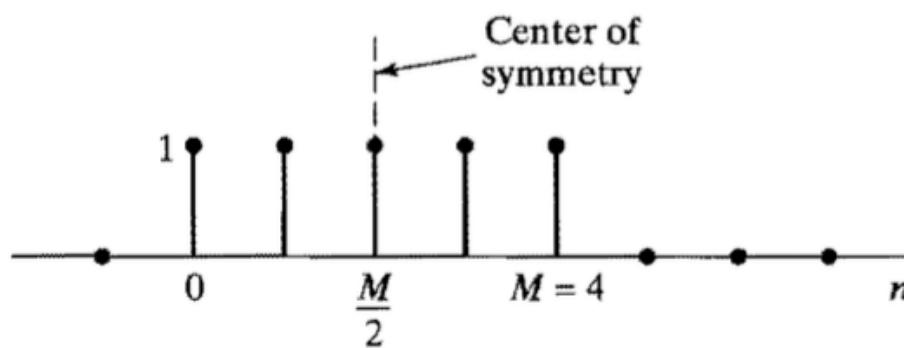


# What is a Linear Filter?

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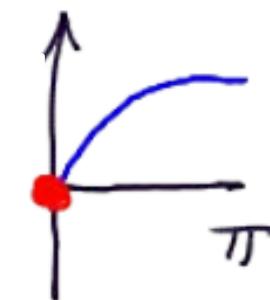
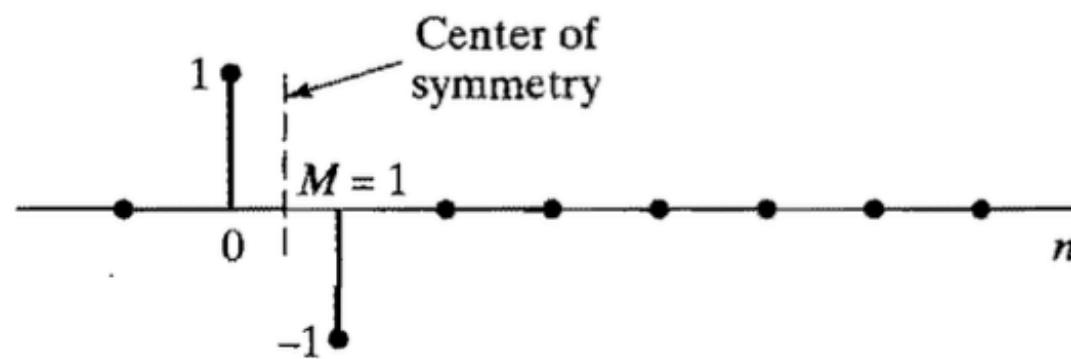
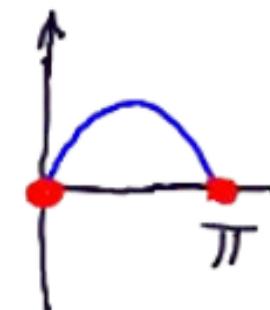
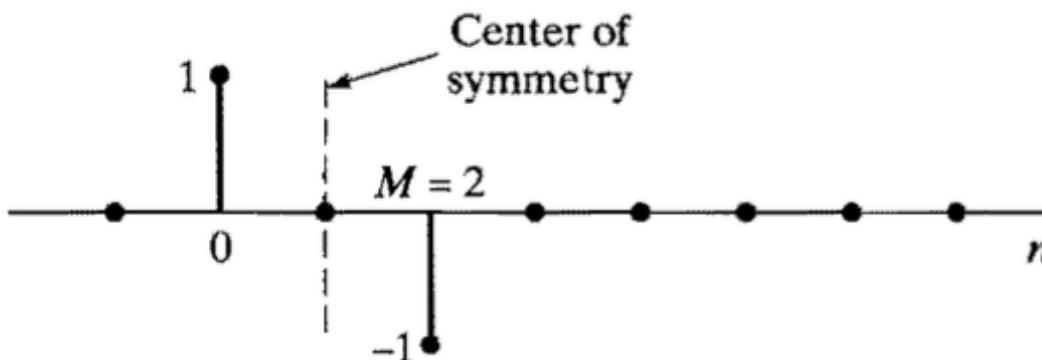
- Attenuates certain frequencies
  - Passes certain frequencies
  - Affects both phase and magnitude
- 
- IIR
    - Mostly non-linear phase response
    - Could be linear over a range of frequencies
  - FIR
    - Much easier to control the phase
    - Both non-linear and linear phase

# FIR GLP: Type I and II





# FIR GLP: Type III and IV



# FIR Design by Windowing

- Given desired frequency response,  $H_d(e^{j\omega})$ , find an impulse response

$$h_d[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_d(e^{j\omega}) e^{j\omega n} d\omega$$

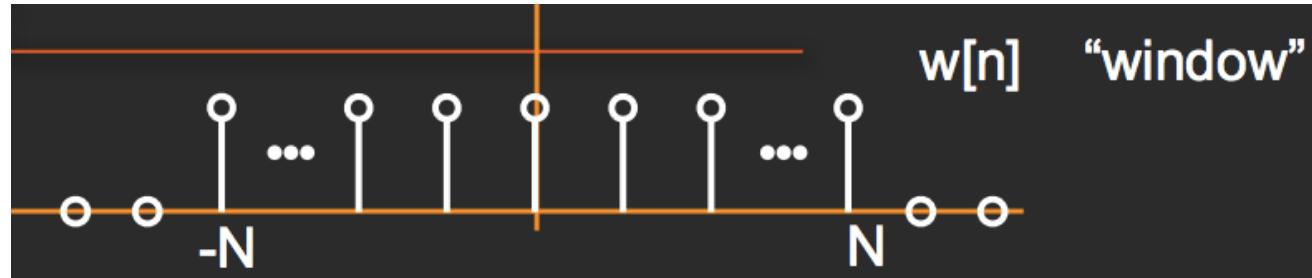
ideal

- Obtain the  $M^{\text{th}}$  order causal FIR filter by truncating/windowing it

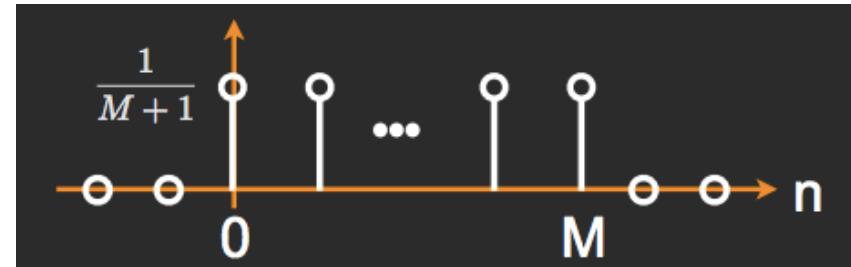
$$h[n] = \begin{cases} h_d[n]w[n] & 0 \leq n \leq M \\ 0 & \text{otherwise} \end{cases}$$



## Example: Moving Average



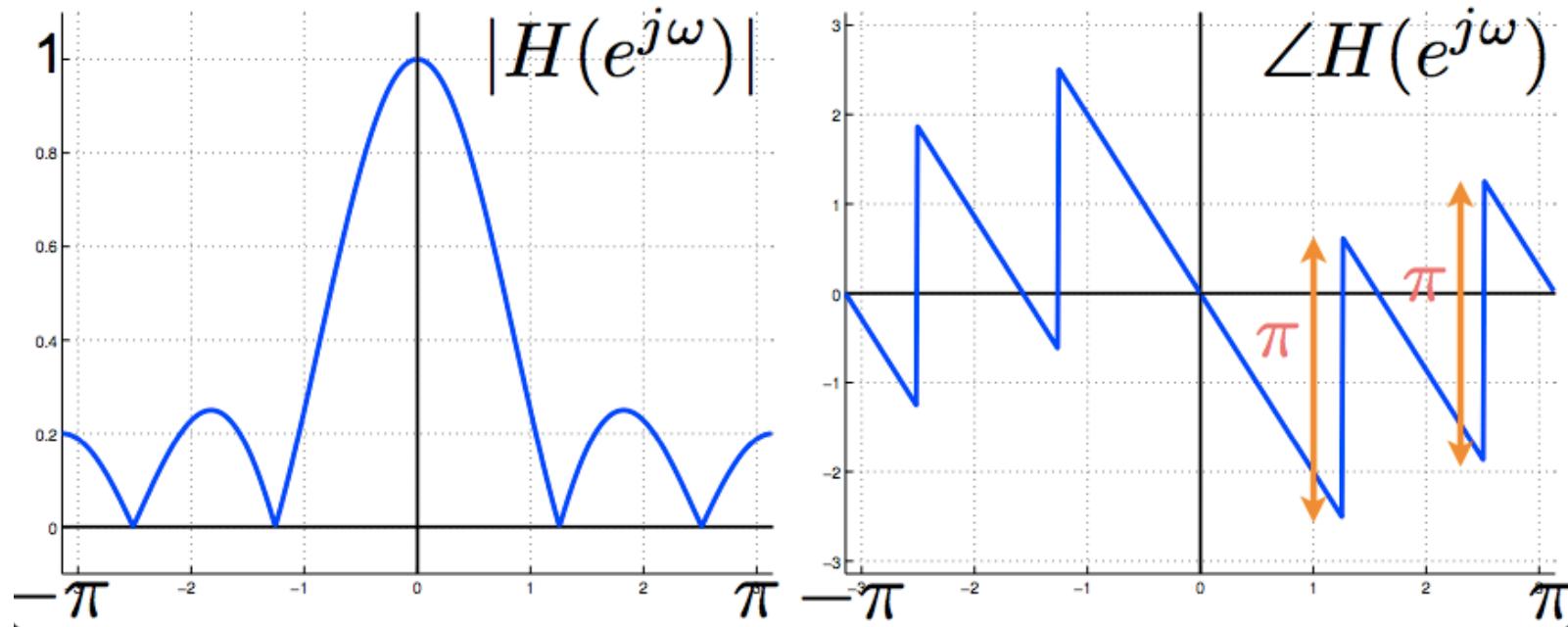
$$w[n] \Leftrightarrow W(e^{j\omega}) = \frac{\sin((N+1/2)\omega)}{\sin(\omega/2)}$$



$$\frac{1}{M+1} w[n - M/2] \Leftrightarrow W(e^{j\omega}) = \frac{e^{-j\omega M/2}}{M+1} \frac{\sin((M/2 + 1/2)\omega)}{\sin(\omega/2)}$$



# Example: Moving Average



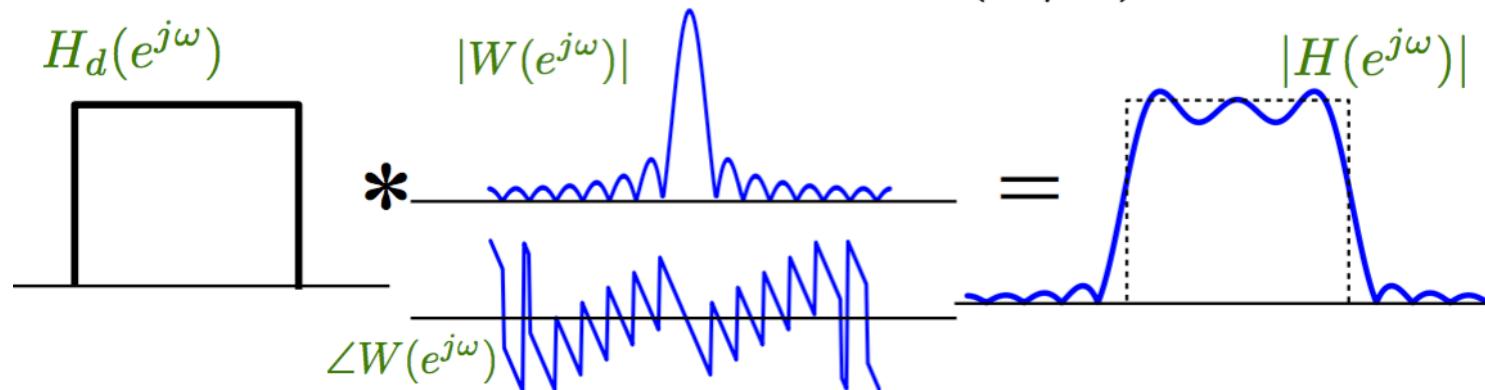
# FIR Design by Windowing

- We already saw this before,

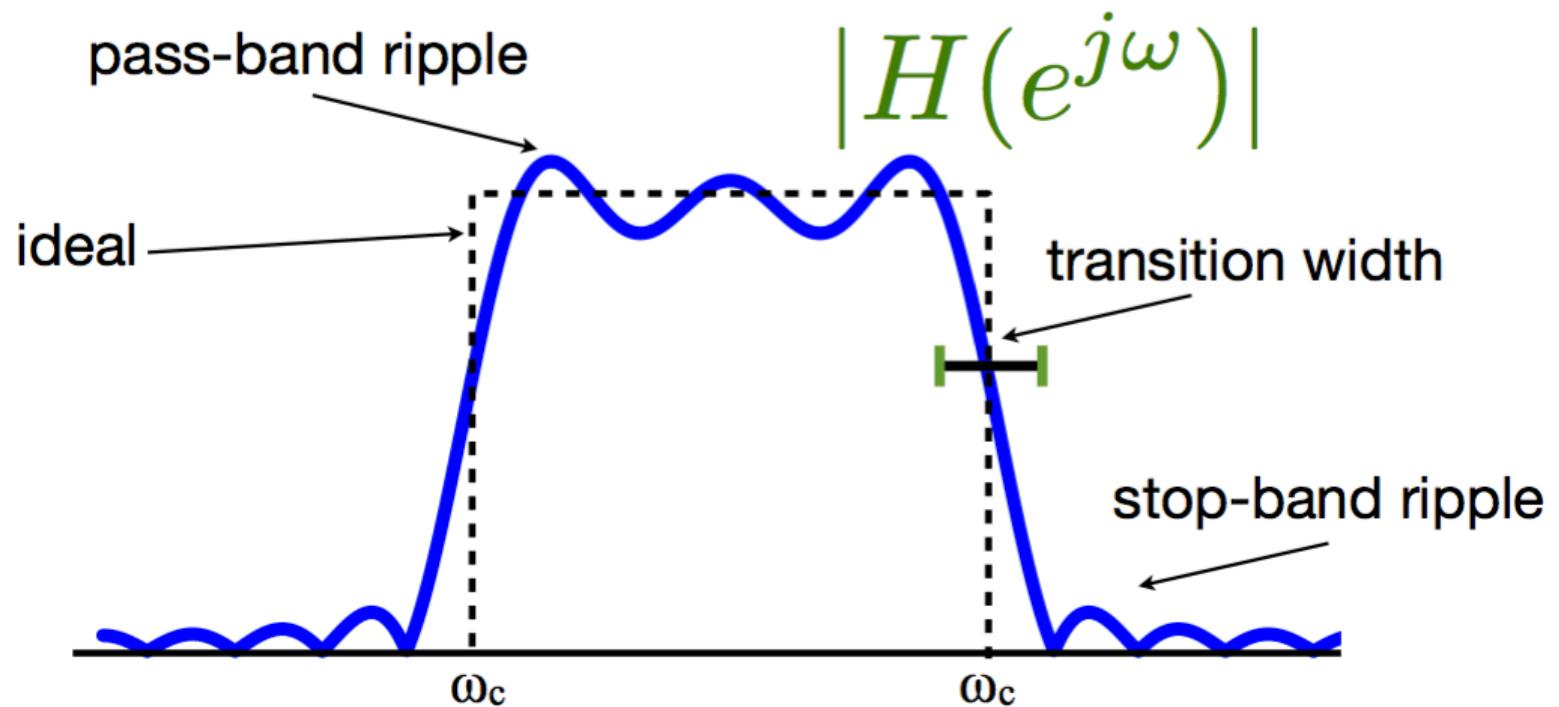
$$H(e^{j\omega}) = H_d(e^{j\omega}) * W(e^{j\omega})$$

- For Boxcar (rectangular) window

$$W(e^{j\omega}) = e^{-j\omega \frac{M}{2}} \frac{\sin(w(M+1)/2)}{\sin(w/2)}$$

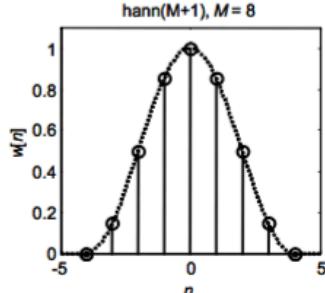
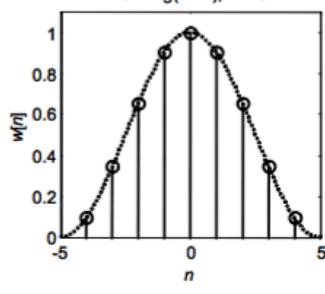
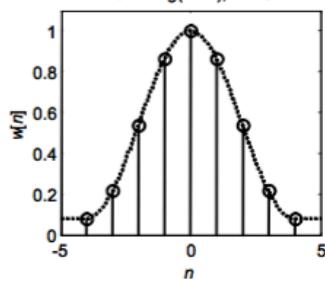


# FIR Design by Windowing

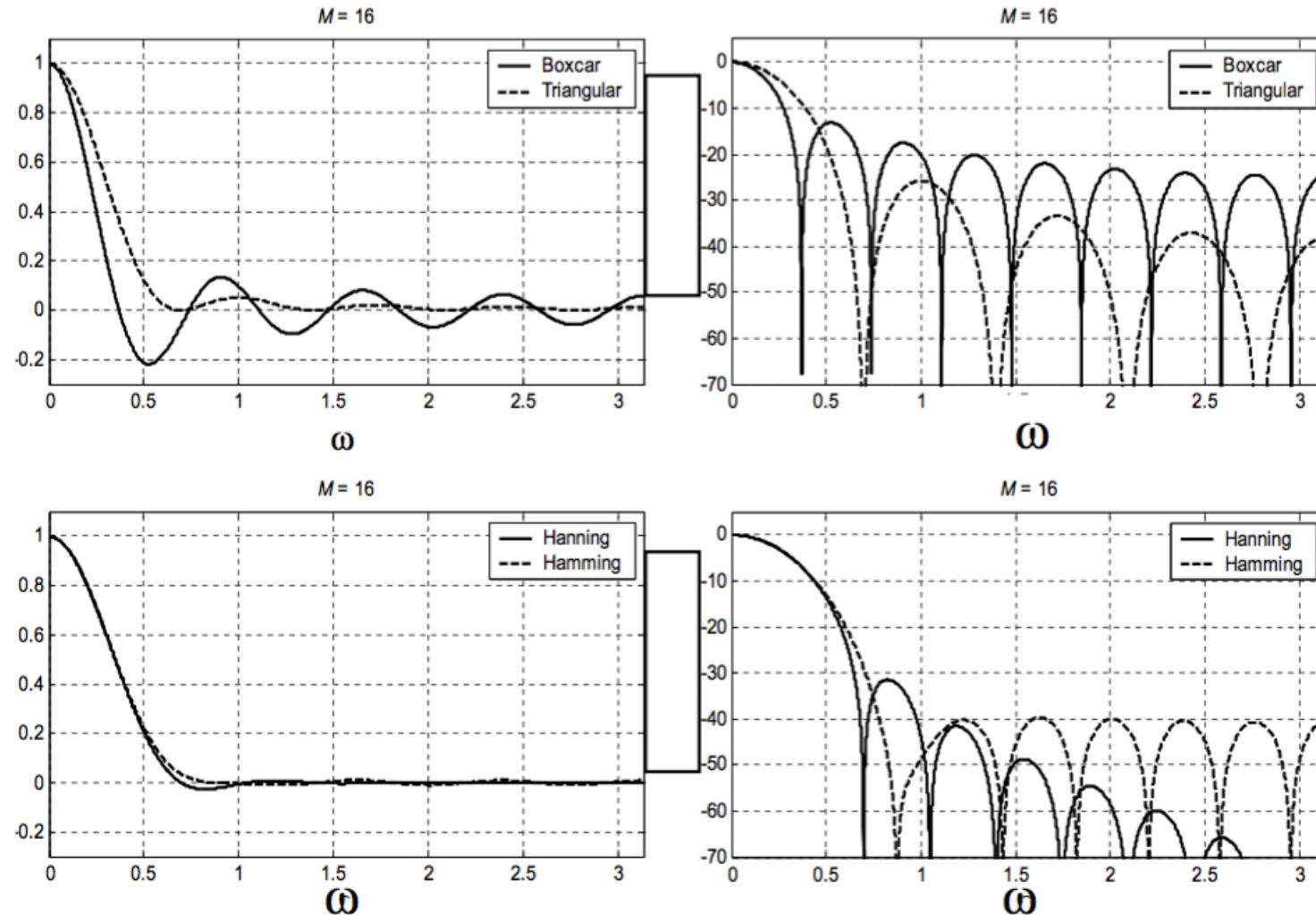


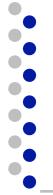


# Tapered Windows

Name(s)	Definition	MATLAB Command	Graph ( $M = 8$ )
Hann	$w[n] = \begin{cases} \frac{1}{2} \left[ 1 + \cos\left(\frac{\pi n}{M/2}\right) \right] &  n  \leq M/2 \\ 0 &  n  > M/2 \end{cases}$	<code>hann(M+1)</code>	
Hanning	$w[n] = \begin{cases} \frac{1}{2} \left[ 1 + \cos\left(\frac{\pi n}{M/2+1}\right) \right] &  n  \leq M/2 \\ 0 &  n  > M/2 \end{cases}$	<code>hanning(M+1)</code>	
Hamming	$w[n] = \begin{cases} 0.54 + 0.46 \cos\left(\frac{\pi n}{M/2}\right) &  n  \leq M/2 \\ 0 &  n  > M/2 \end{cases}$	<code>hamming(M+1)</code>	

# Tradeoff – Ripple vs. Transition Width





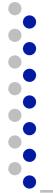
# FIR Filter Design

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- Choose a desired frequency response  $H_d(e^{j\omega})$ 
  - non causal (zero-delay), and infinite imp. response
  - If derived from C.T, choose T and use:

$$H_d(e^{j\omega}) = H_c(j \frac{\Omega}{T})$$

- Window:
  - Length  $M+1 \Leftrightarrow$  affects transition width
  - Type of window  $\Leftrightarrow$  transition-width/ ripple



# FIR Filter Design

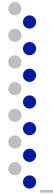
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- Choose a desired frequency response  $H_d(e^{j\omega})$ 
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- Window:
  - Length  $M+1 \Leftrightarrow$  affects transition width
  - Type of window  $\Leftrightarrow$  transition-width/ ripple
  - Modulate to shift impulse response
    - Force causality

$$H_d(e^{j\omega})e^{-j\omega \frac{M}{2}}$$



# FIR Filter Design

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- ❑ Determine truncated impulse response  $h_1[n]$

$$h_1[n] = \begin{cases} \frac{1}{2\pi} \int_{-\pi}^{\pi} H_d(e^{j\omega}) e^{-j\omega \frac{M}{2}} e^{j\omega n} & 0 \leq n \leq M \\ 0 & \text{otherwise} \end{cases}$$

- ❑ Apply window

$$h_w[n] = w[n]h_1[n]$$

- ❑ Check:

- Compute  $H_w(e^{j\omega})$ , if does not meet specs increase  $M$  or change window

## Example: FIR Low-Pass Filter Design

$$H_d(e^{j\omega}) = \begin{cases} 1 & |\omega| \leq \omega_c \\ 0 & \text{otherwise} \end{cases}$$

Choose M  $\Rightarrow$  Window length and set

$$H_1(e^{j\omega}) = H_d(e^{j\omega})e^{-j\omega \frac{M}{2}}$$

$$h_1[n] = \begin{cases} \frac{\sin(\omega_c(n-M/2))}{\pi(n-M/2)} & 0 \leq n \leq M \\ 0 & \text{otherwise} \end{cases}$$

$\frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c}{\pi}(n - M/2)\right)$

# Example: FIR Low-Pass Filter Design

- The result is a windowed sinc function

$$h_w[n] = w[n]h_1[n]$$

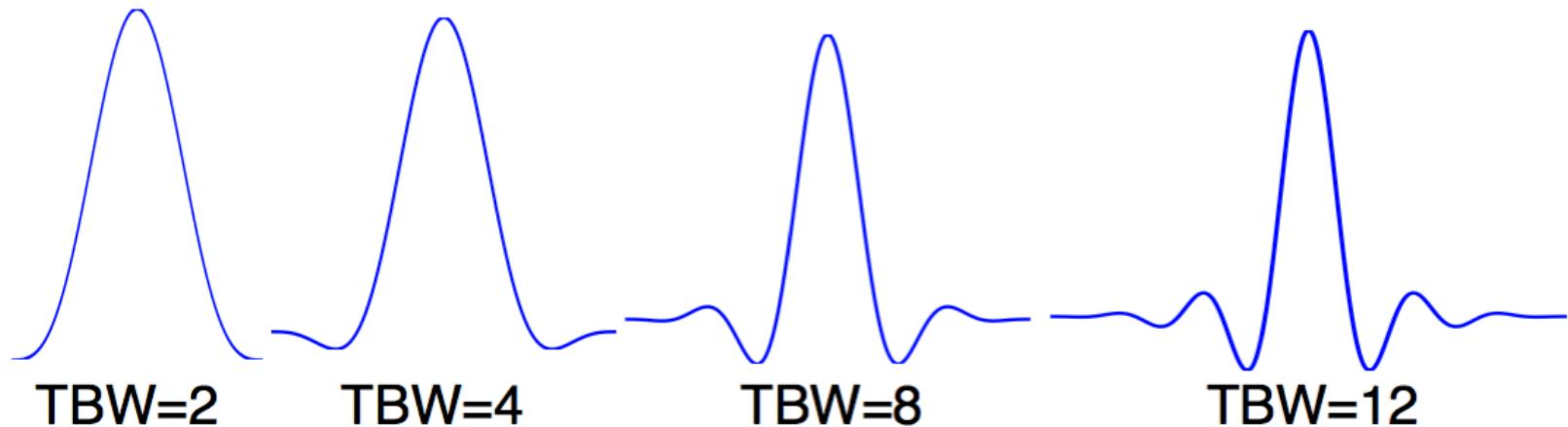
$$\frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c}{\pi}(n - M/2)\right)$$

- High Pass Design:
  - Design low pass
  - Transform to  $h_w[n](-1)^n$
- General bandpass
  - Transform to  $2h_w[n]\cos(\omega_0 n)$

# Characterization of Filter Shape

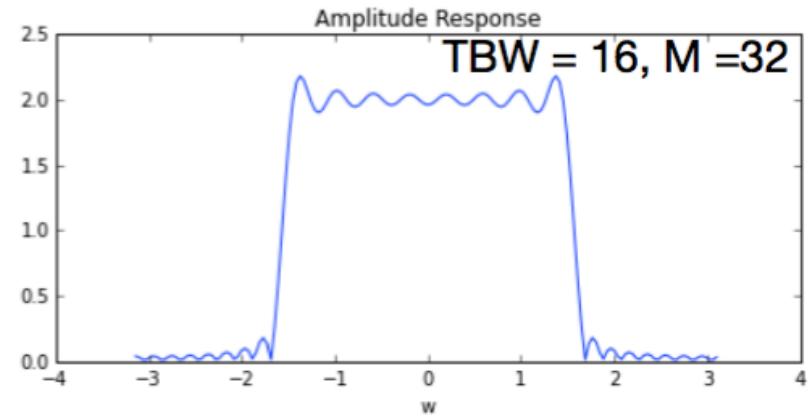
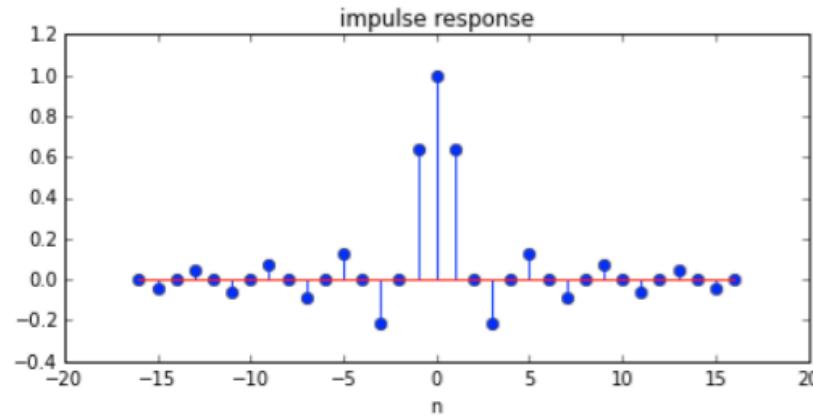
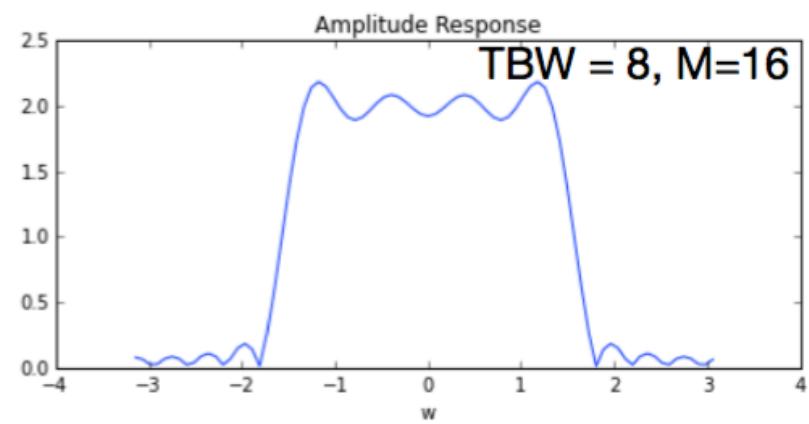
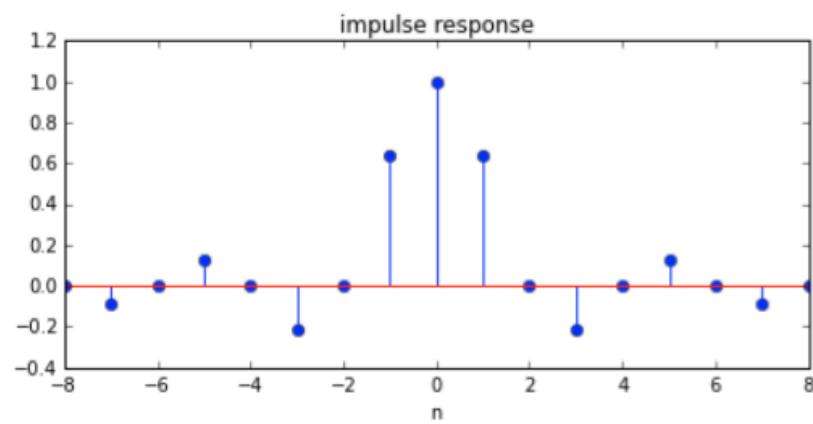
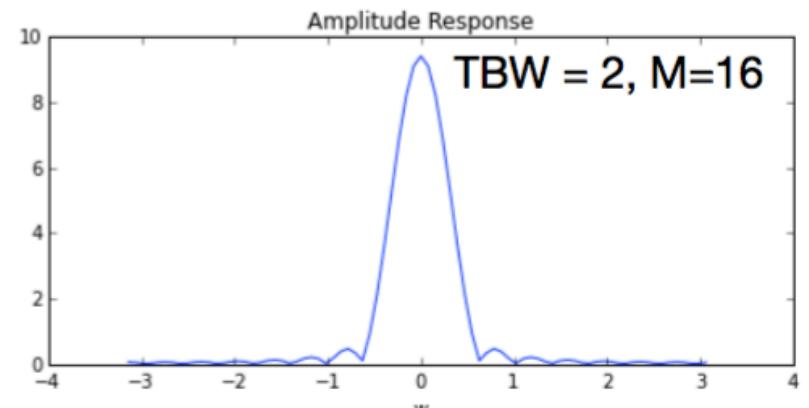
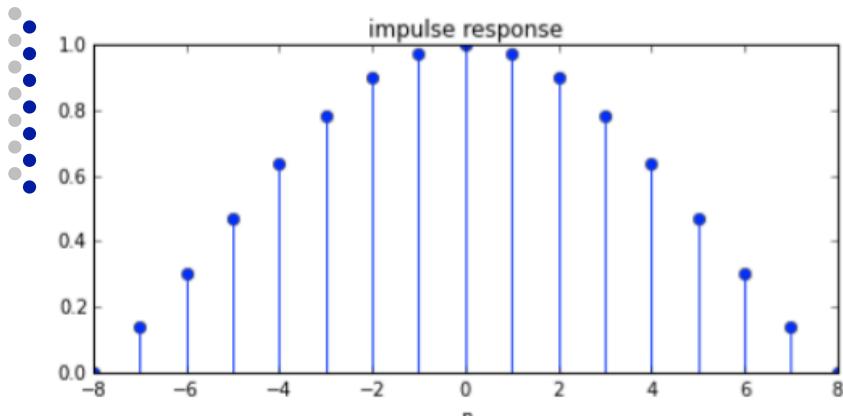
Time-Bandwidth Product, a unitless measure

$$T(BW) = (M+1)\omega/2\pi \quad \Rightarrow \text{also, total } \# \text{ of zero crossings}$$



Larger TBW  $\Rightarrow$  More of the “sinc” function

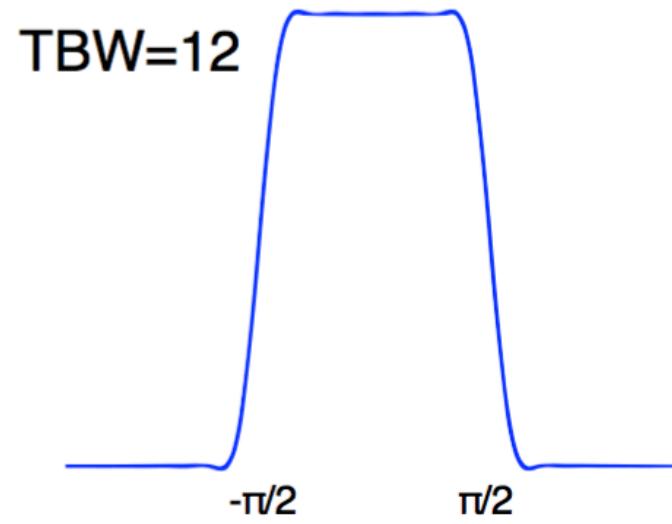
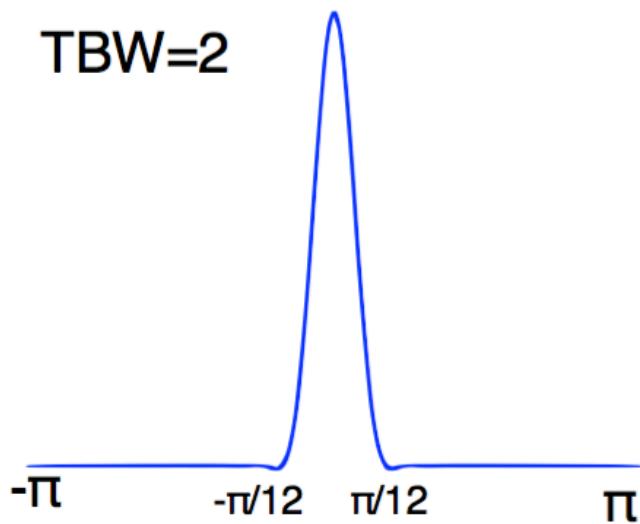
hence, frequency response looks more like a rect function





# Frequency Response Profile

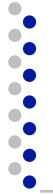
Q: What are the lengths of these filters in samples?



$$2 = (M+1) * (\pi/6) / (2\pi) \Rightarrow M=23$$

$$12 = (M+1) * (\pi) / (2\pi) \Rightarrow M=23$$

Note that transition is the same!



# Alternative Design through FFT

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- To design order M filter:
- Over-Sample/discretize the frequency response at P points where  $P \gg M$  ( $P=15M$  is good)

$$H_1(e^{j\omega_k}) = H_d(e^{j\omega_k})e^{-j\omega_k \frac{M}{2}}$$

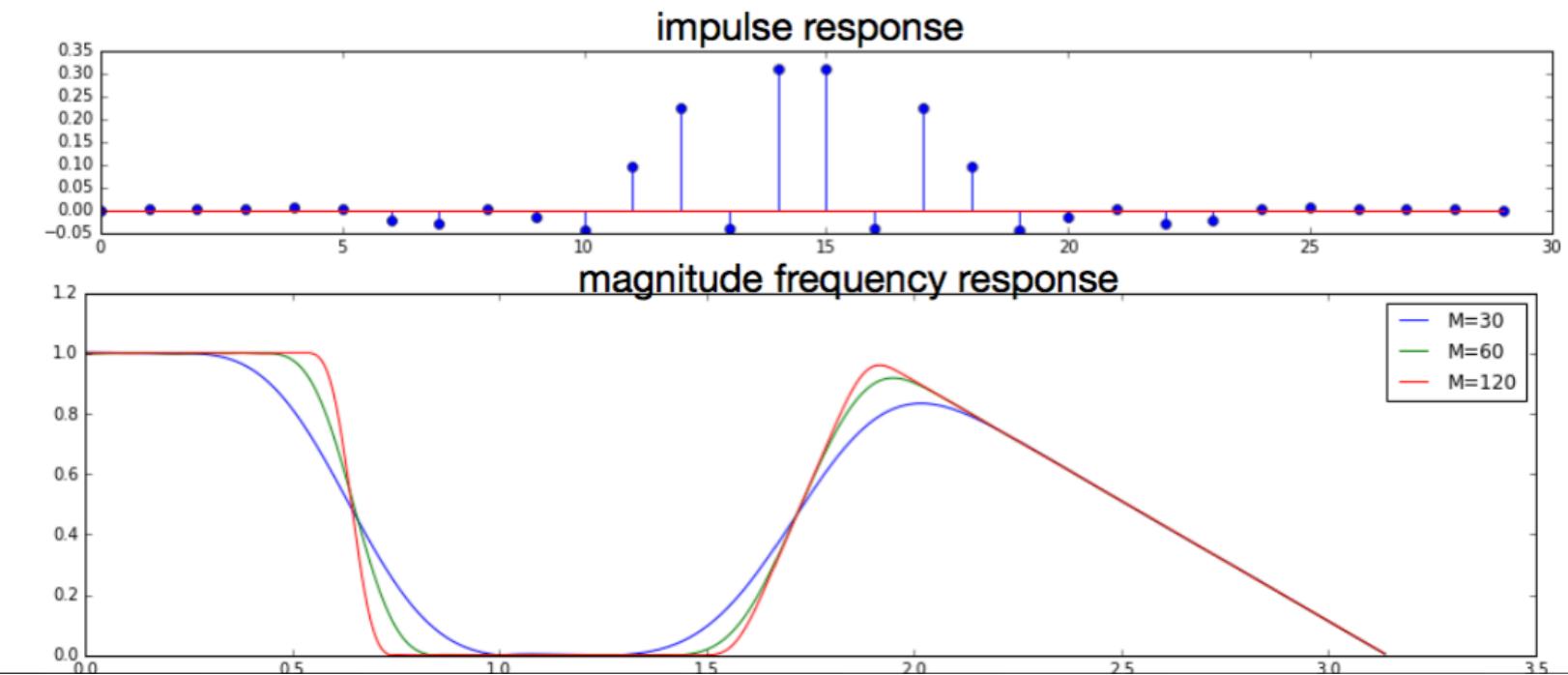
- Sampled at:  $\omega_k = k \frac{2\pi}{P}$   $|k = [0, \dots, P - 1]$
- Compute  $h_1[n] = \text{IDFT}_P(H_1[k])$
- Apply  $M+1$  length window:

$$h_w[n] = w[n]h_1[n]$$



## Example

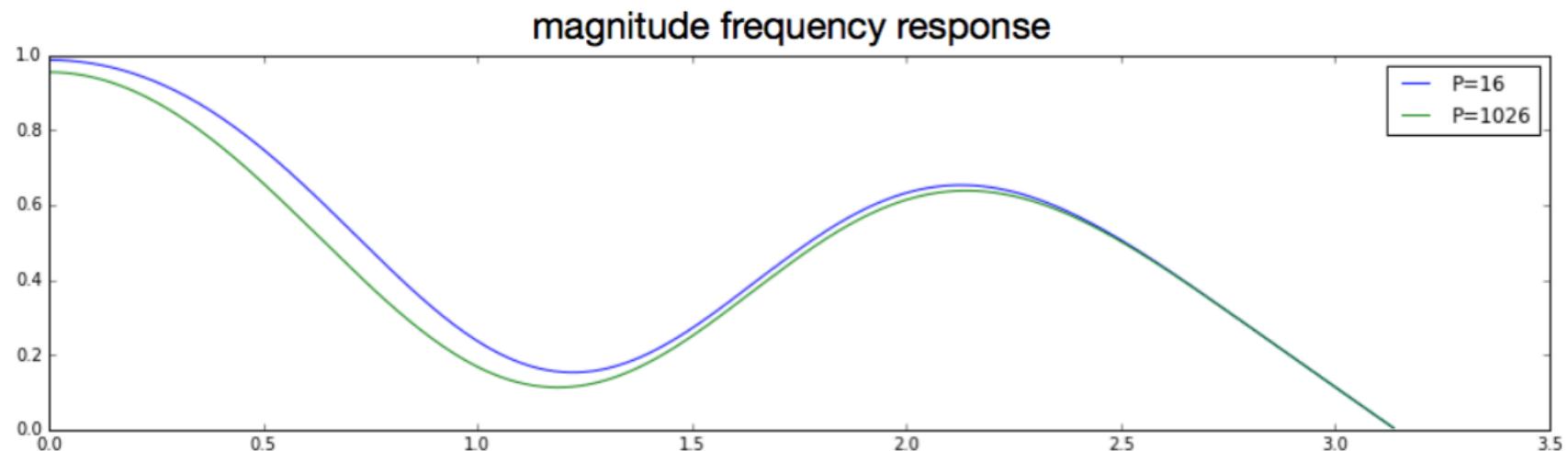
- `signal.firwin2(M+1,omega_vec/pi, amp_vec)`
- `taps1 = signal.firwin2(30, [0.0,0.2,0.21,0.5, 0.6, 1.0], [1.0, 1.0, 0.0,0.0,1.0,0.0])`

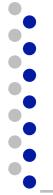




# Example

- For  $M+1=14$ 
  - $P = 16$  and  $P = 1026$



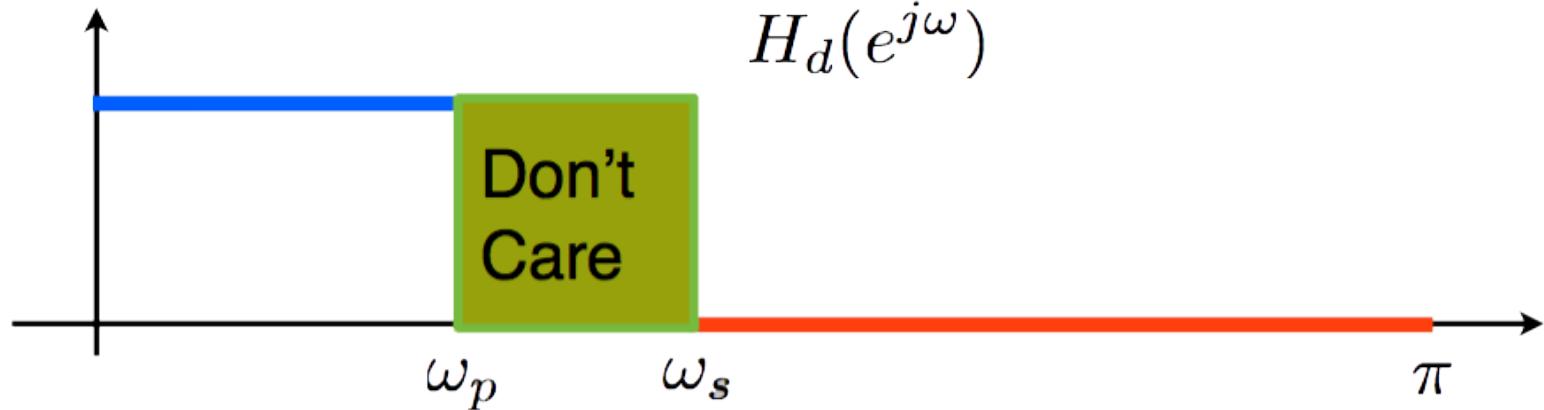


# Optimal Filter Design

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- Window method
  - Design Filters heuristically using windowed sinc functions
- Optimal design
  - Design a filter  $h[n]$  with  $H(e^{j\omega})$
  - Approximate  $H_d(e^{j\omega})$  with some optimality criteria - or satisfies specs.

# Optimality



- Least Squares:

$$\text{minimize} \quad \int_{\omega \in \text{care}} |H(e^{j\omega}) - H_d(e^{j\omega})|^2 d\omega$$

- Variation: Weighted Least Squares:

$$\text{minimize} \quad \int_{-\pi}^{\pi} W(\omega) |H(e^{j\omega}) - H_d(e^{j\omega})|^2 d\omega$$



# Optimality

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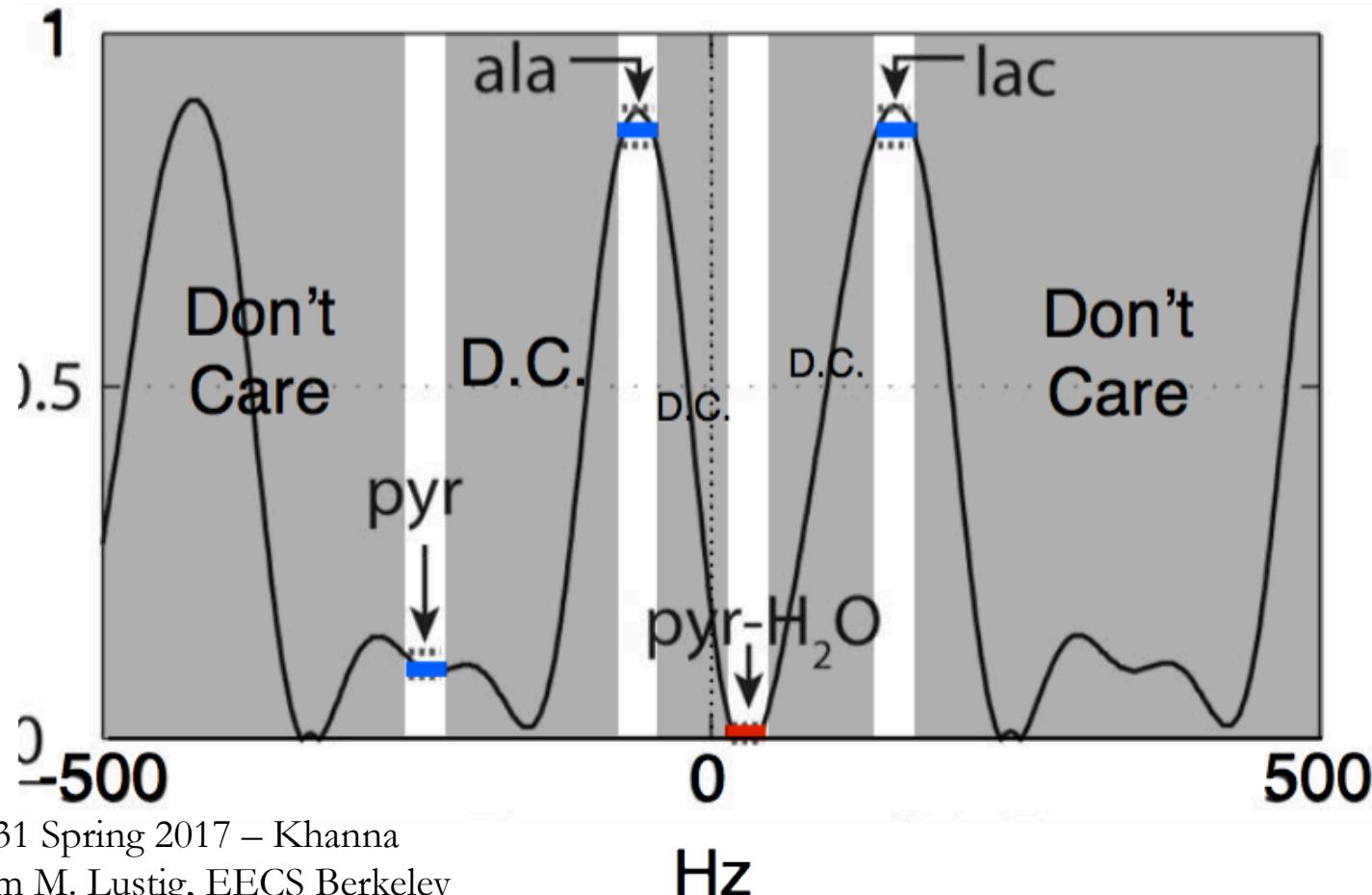
## ❑ Chebychev Design (min-max)

$$\text{minimize}_{\omega \in \text{care}} \quad \max |H(e^{j\omega}) - H_d(e^{j\omega})|$$

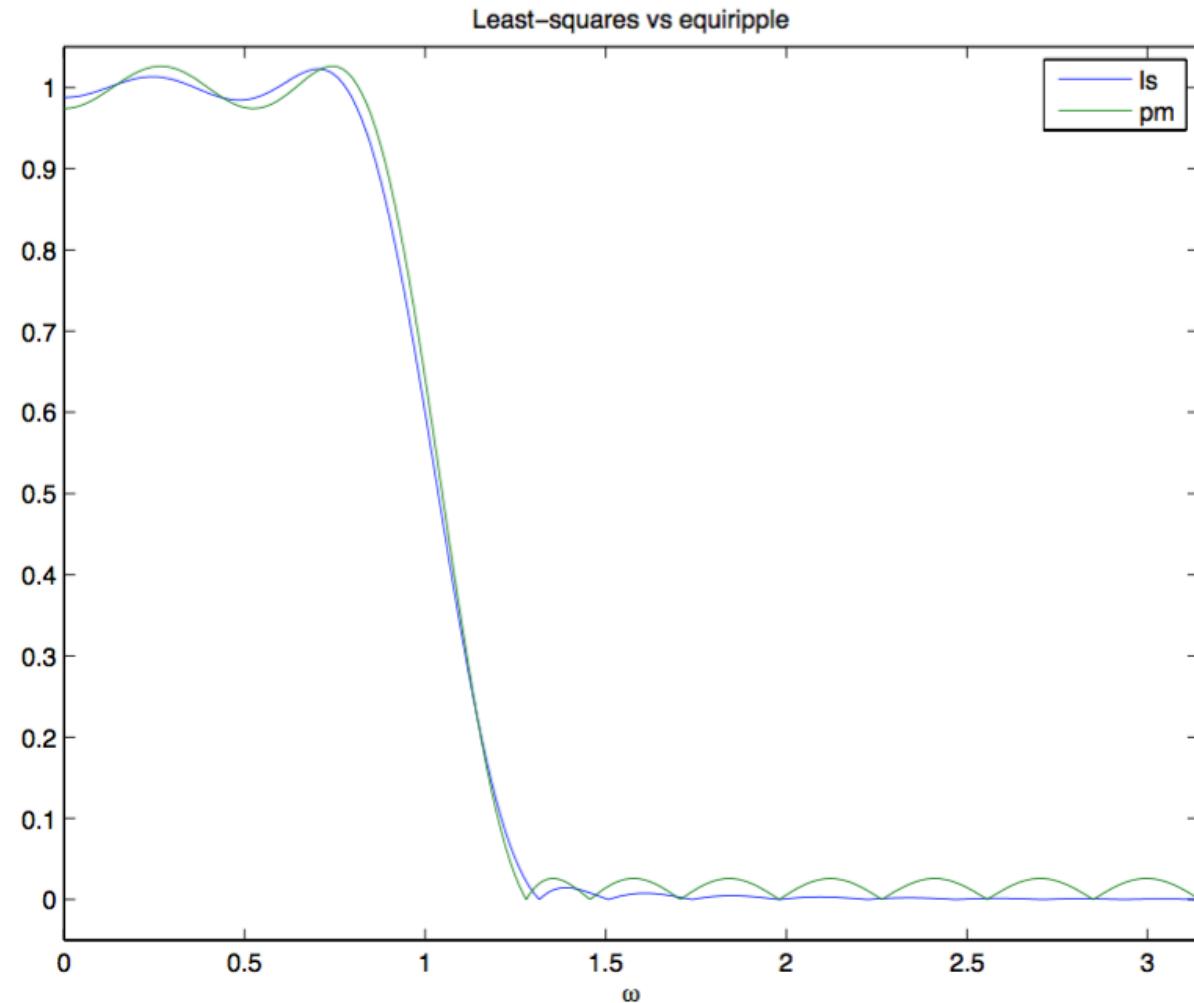
- Parks-McClellan algorithm - equi-ripple
- Also known as Remez exchange algorithms (`signal.remez`)
- Can also use convex optimization

# Example of Complex Filter

- ❑ Larson et. al, “Multiband Excitation Pulses for Hyperpolarized  $^{13}\text{C}$  Dynamic Chemical Shift Imaging” JMR 2008;194(1):121-127
- ❑ Need to design 11 taps filter with following frequency response:



# Least-Squares v.s. Min-Max





# Admin

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- ❑ HW 6
  - Out now
  - Due Tuesday 3/28
  - No MATLAB problem
  
- ❑ Pick up midterm