

ESE 531: Digital Signal Processing

Lec 19: April 6, 2017
Discrete Fourier Transform

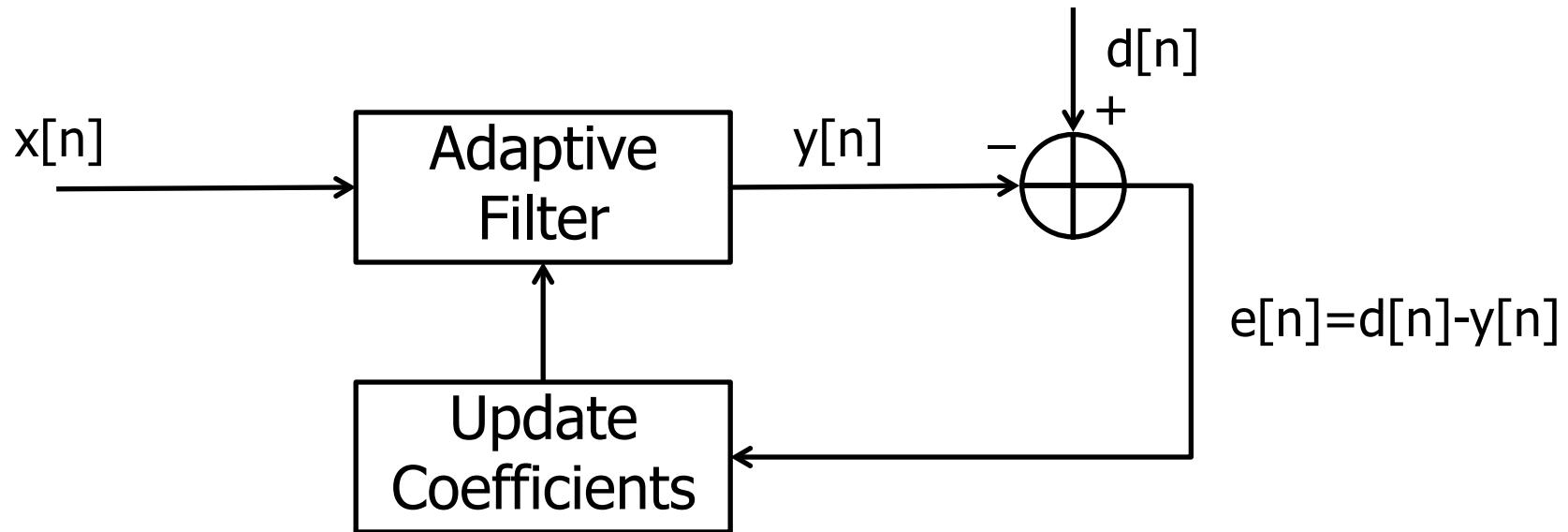


Today

- ❑ Adaptive filtering
 - Blind equalization
- ❑ Discrete Fourier Series
- ❑ Discrete Fourier Transform (DFT)
- ❑ DFT Properties

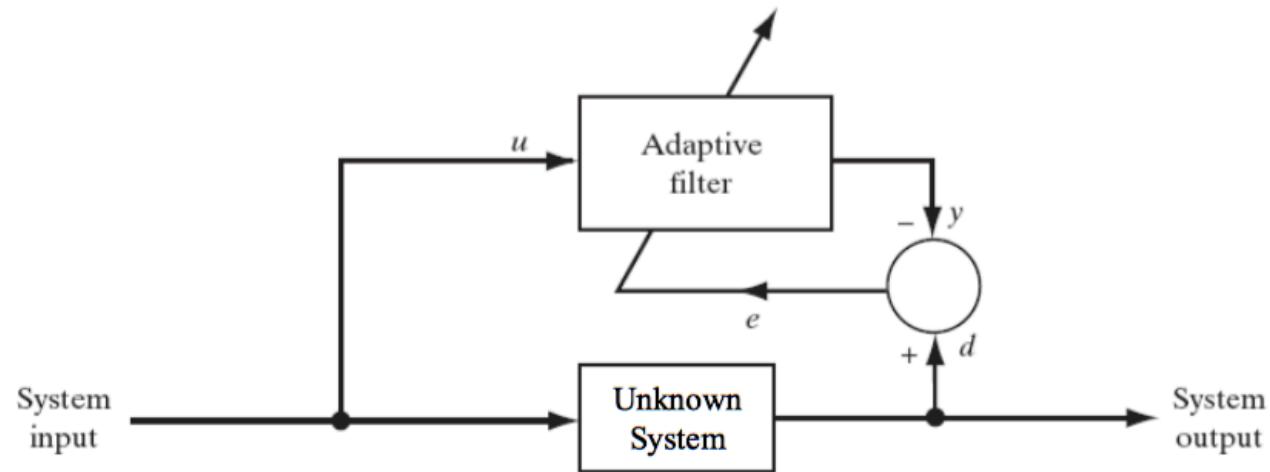
Adaptive Filters

- ❑ An adaptive filter is an adjustable filter that processes in time
 - It adapts...



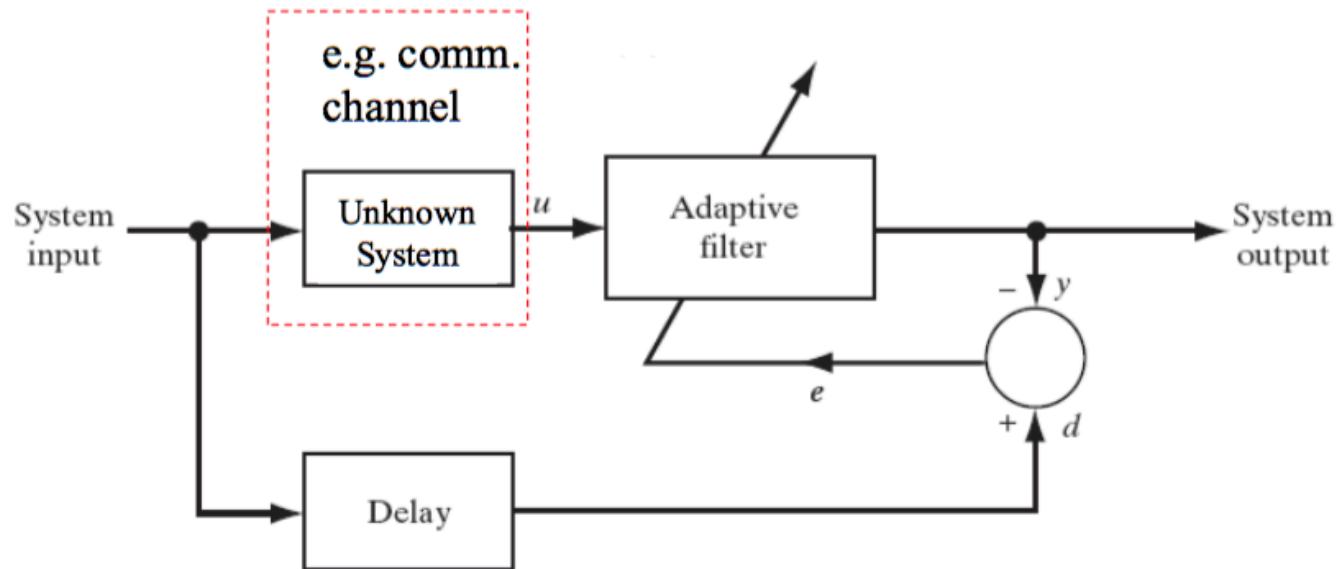
Adaptive Filter Applications

□ System Identification



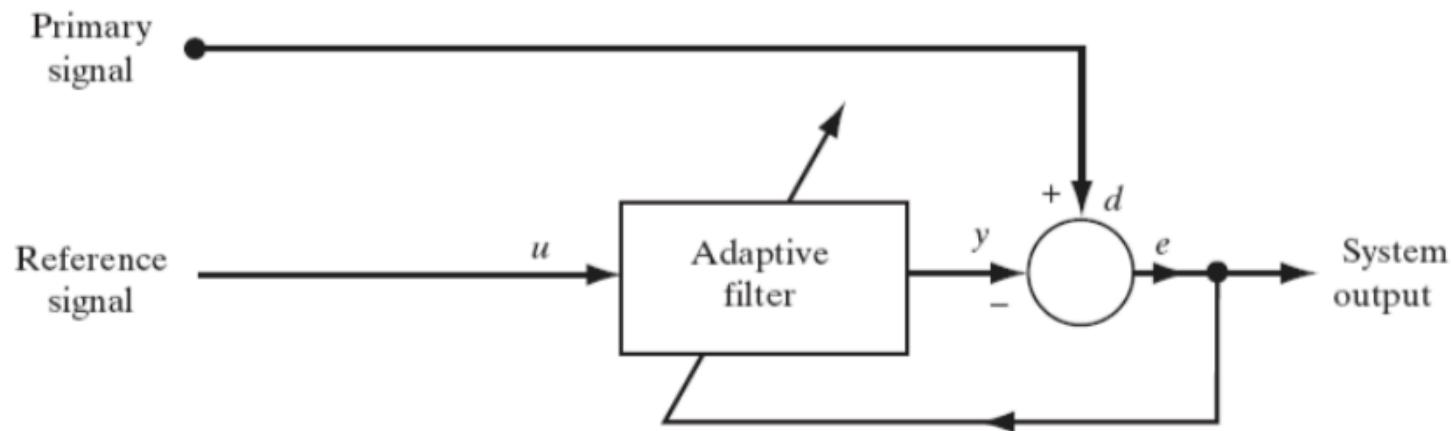
Adaptive Filter Applications

□ Identification of inverse system



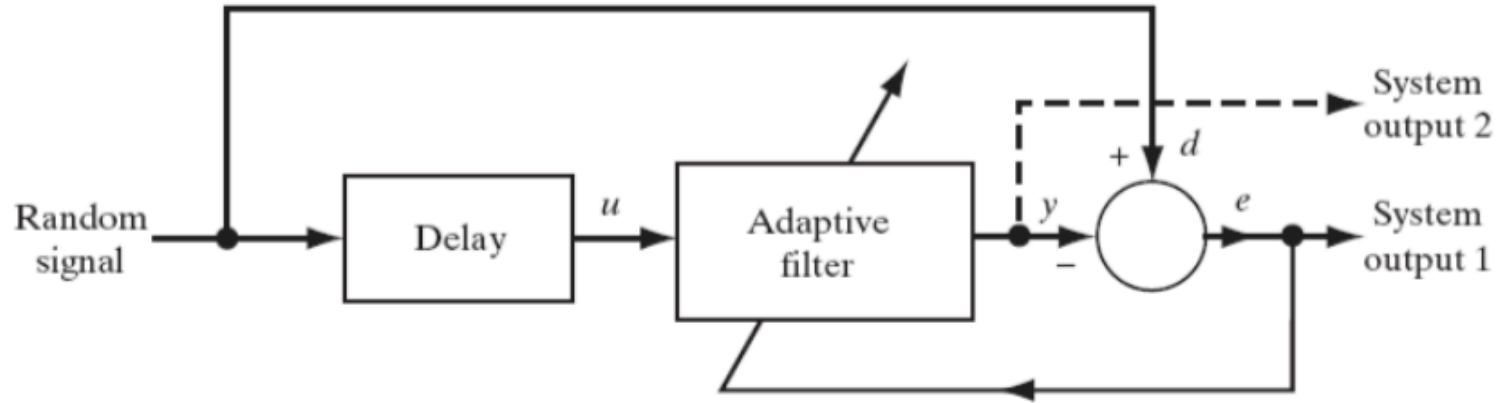
Adaptive Filter Applications

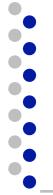
□ Adaptive Interference Cancellation



Adaptive Filter Applications

❑ Adaptive Prediction



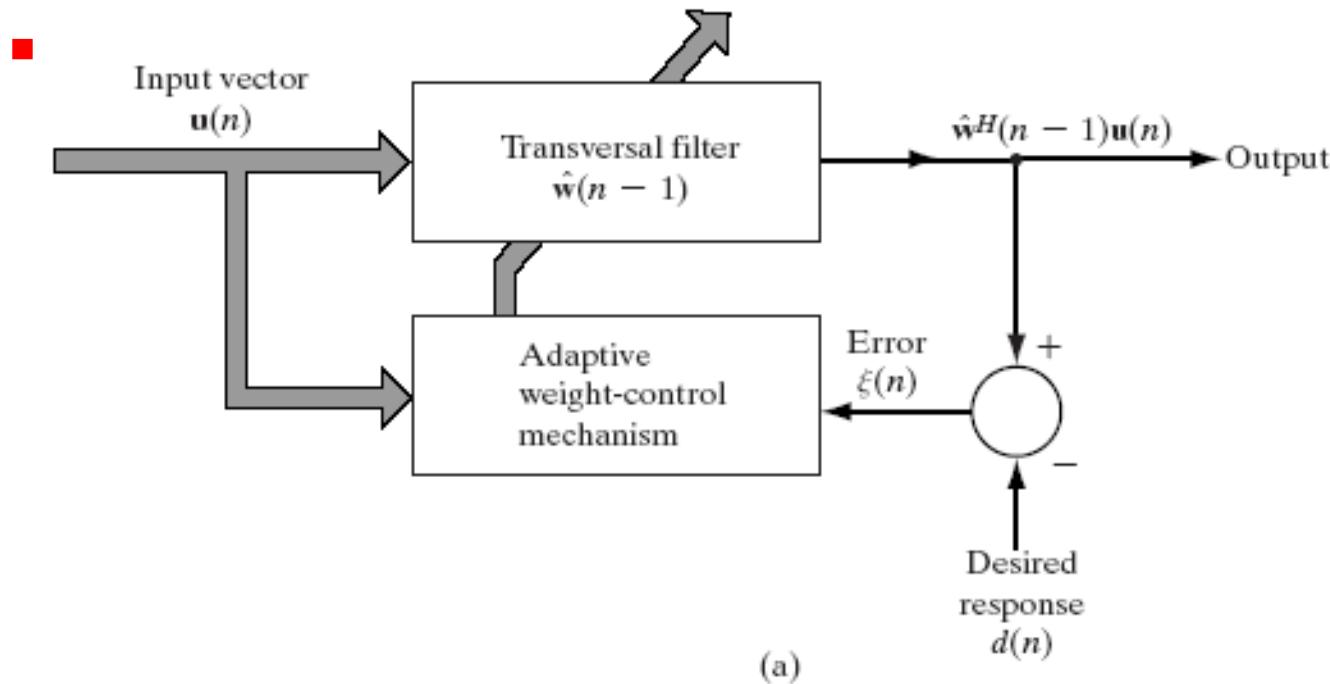


Stochastic Gradient Approach

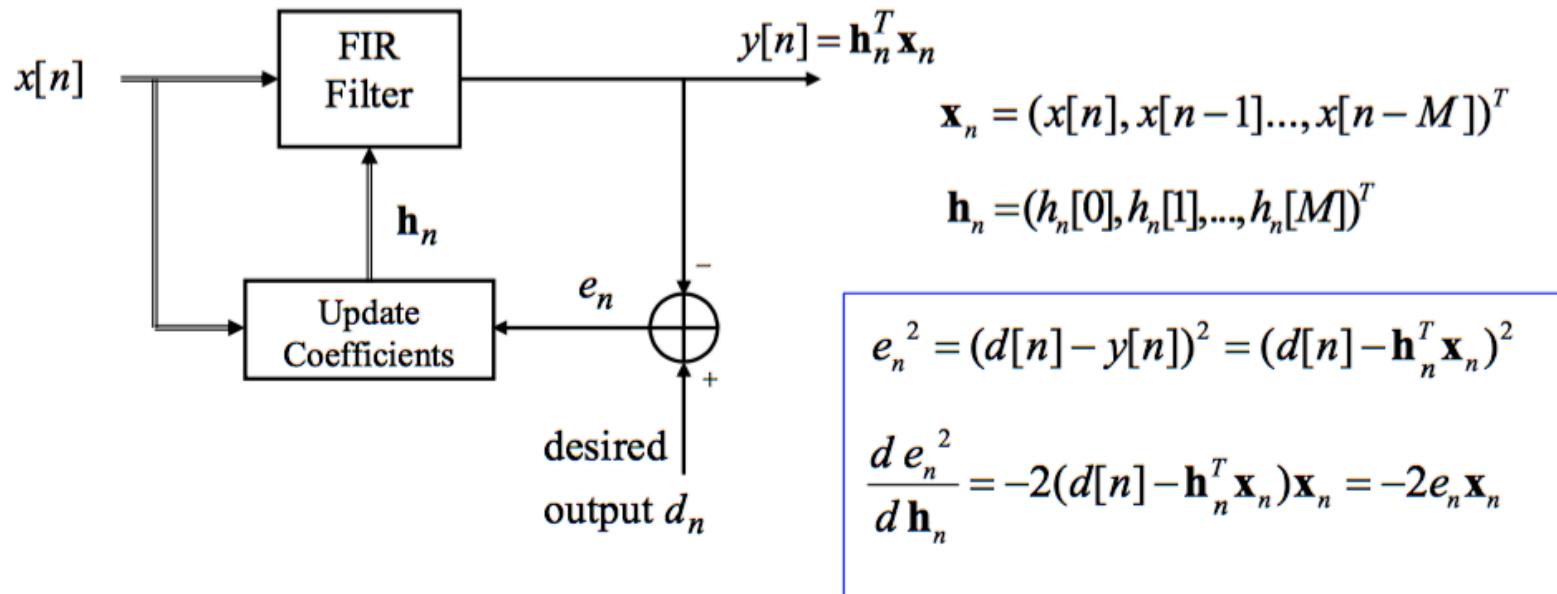
- Most commonly used type of Adaptive Filters
- Define cost function as mean-squared error
 - Difference between filter output and desired response
- Based on the method of steepest descent
 - Move towards the minimum on the error surface to get to minimum
 - Requires the gradient of the error surface to be known

Least-Mean-Square (LMS) Algorithm

- ❑ The LMS Algorithm consists of two basic processes
 - Filtering process
 - Calculate the output of FIR filter by convolving input and taps
 - Calculate estimation error by comparing the output to desired signal
 -



Adaptive FIR Filter: LMS



Coefficient Update: Move in direction *opposite* to sign of gradient,

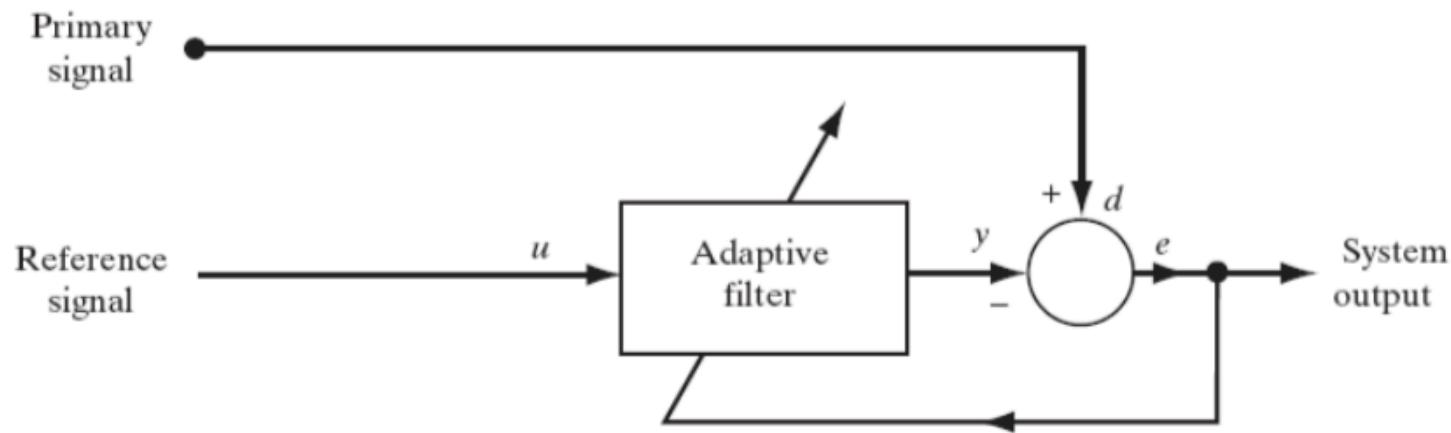
proportional to magnitude of gradient

$$\mathbf{h}_{n+1} = \mathbf{h}_n + 2\mu e_n \mathbf{x}_n$$

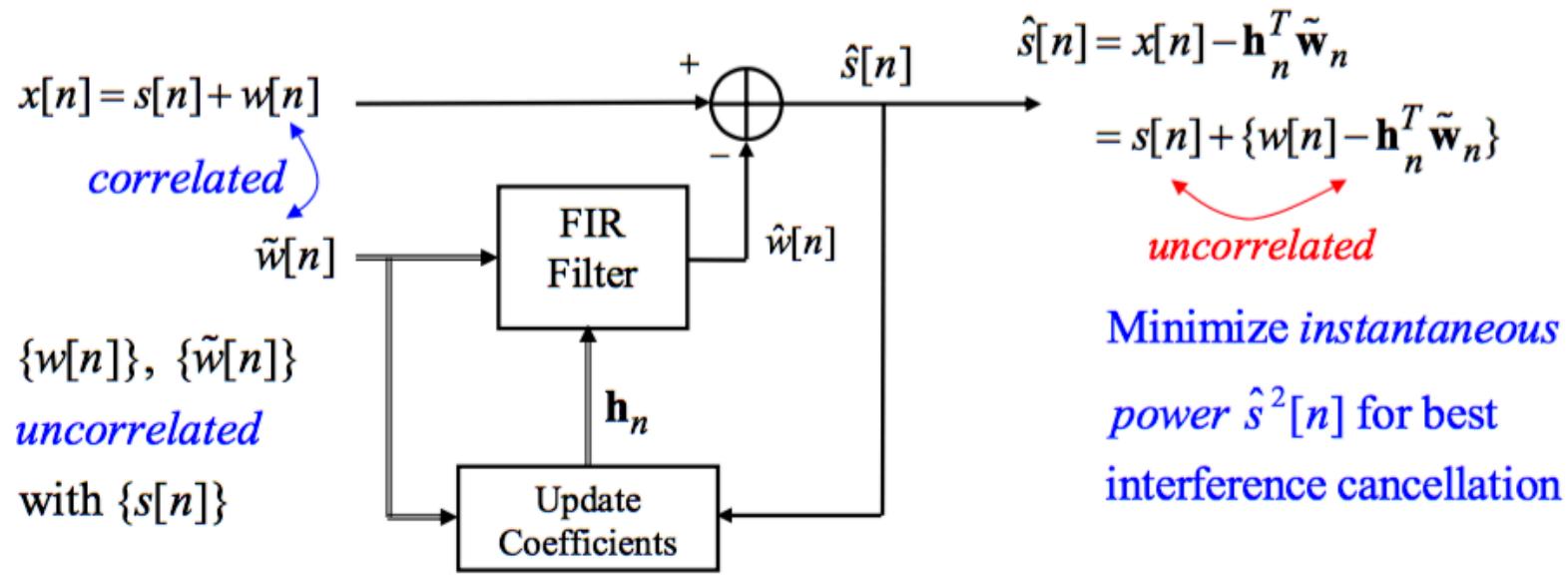
Stochastic Gradient Algorithm

Adaptive Filter Applications

□ Adaptive Interference Cancellation



Adaptive Interference Cancellation



$$\frac{d(\hat{s}[n])^2}{d \mathbf{h}_n} = -2\hat{s}[n] \tilde{\mathbf{w}}_n$$

$$\mathbf{h}_{n+1} = \mathbf{h}_n + 2\mu \hat{s}[n] \tilde{\mathbf{w}}_n$$



Stability of LMS

- ❑ The LMS algorithm is convergent in the mean square if and only if the step-size parameter satisfy

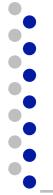
$$0 < \mu < \frac{2}{\lambda_{\max}}$$

- ❑ Here λ_{\max} is the largest eigenvalue of the correlation matrix of the input data
- ❑ More practical test for stability is

$$0 < \mu < \frac{2}{\text{input signal power}}$$

- ❑ Larger values for step size
 - Increases adaptation rate (faster adaptation)
 - Increases residual mean-squared error

Discrete Fourier Series



Reminder: Eigenvalue (DTFT)

□ $x[n] = e^{j\omega n}$

$$y[n] = \sum_{k=-\infty}^{\infty} x[n-k]h[k]$$

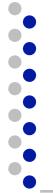
$$= \sum_{k=-\infty}^{\infty} e^{j\omega(n-k)} h[k]$$

$$= e^{j\omega n} \sum_{k=-\infty}^{\infty} h[k] e^{-j\omega k}$$

$$= H(e^{j\omega}) e^{j\omega n}$$

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h[k] e^{-j\omega k}$$

- Describes the change in amplitude and phase of signal at frequency ω
- Frequency response
- Complex value
 - Re and Im
 - Mag and Phase



Discrete Fourier Series

- Definition:

- Consider N-periodic signal:

$$\tilde{x}[n + N] = \tilde{x}[n] \quad \forall n$$

- Frequency-domain also periodic in N:

$$\tilde{X}[k + N] = \tilde{X}[k] \quad \forall k$$

- “~” indicates periodic signal/spectrum



Discrete Fourier Series

- Define:

$$W_N \triangleq e^{-j2\pi/N}$$

- DFS:

$$\tilde{x}[n] = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}[k] W_N^{-kn}$$

$$\tilde{X}[k] = \sum_{n=0}^{N-1} \tilde{x}[n] W_N^{kn}$$

Discrete Fourier Series



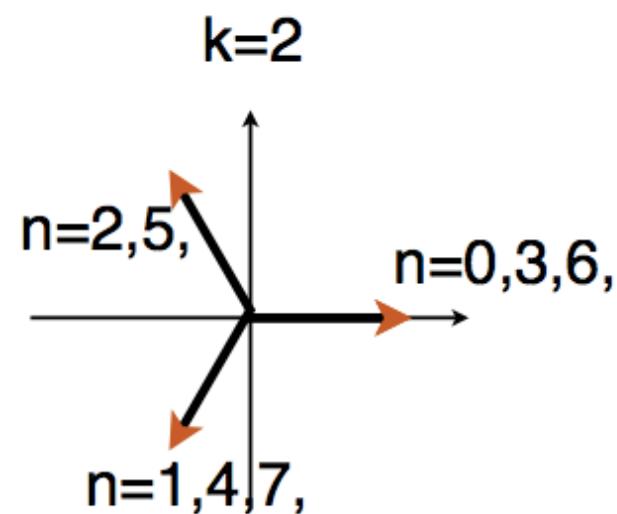
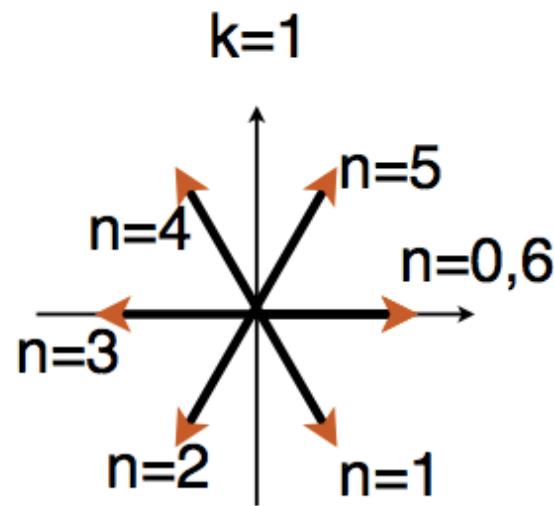
Discrete Fourier Series

$$W_N \triangleq e^{-j2\pi/N}$$

□ Properties of WN:

- $W_N^0 = W_N^N = W_N^{2N} = \dots = 1$
- $W_N^{k+r} = W_N^k W_N^r$ and, $W_N^{k+N} = W_N^k$

□ Example: W_N^{kn} ($N=6$)





Discrete Fourier Transform

- By convention, work with one period:

$$x[n] \triangleq \begin{cases} \tilde{x}[n] & 0 \leq n \leq N - 1 \\ 0 & \text{otherwise} \end{cases}$$

$$X[k] \triangleq \begin{cases} \tilde{X}[k] & 0 \leq k \leq N - 1 \\ 0 & \text{otherwise} \end{cases}$$

Same, but different!



Discrete Fourier Transform

- The DFT

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] W_N^{-kn} \quad \text{Inverse DFT, synthesis}$$

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn} \quad \text{DFT, analysis}$$

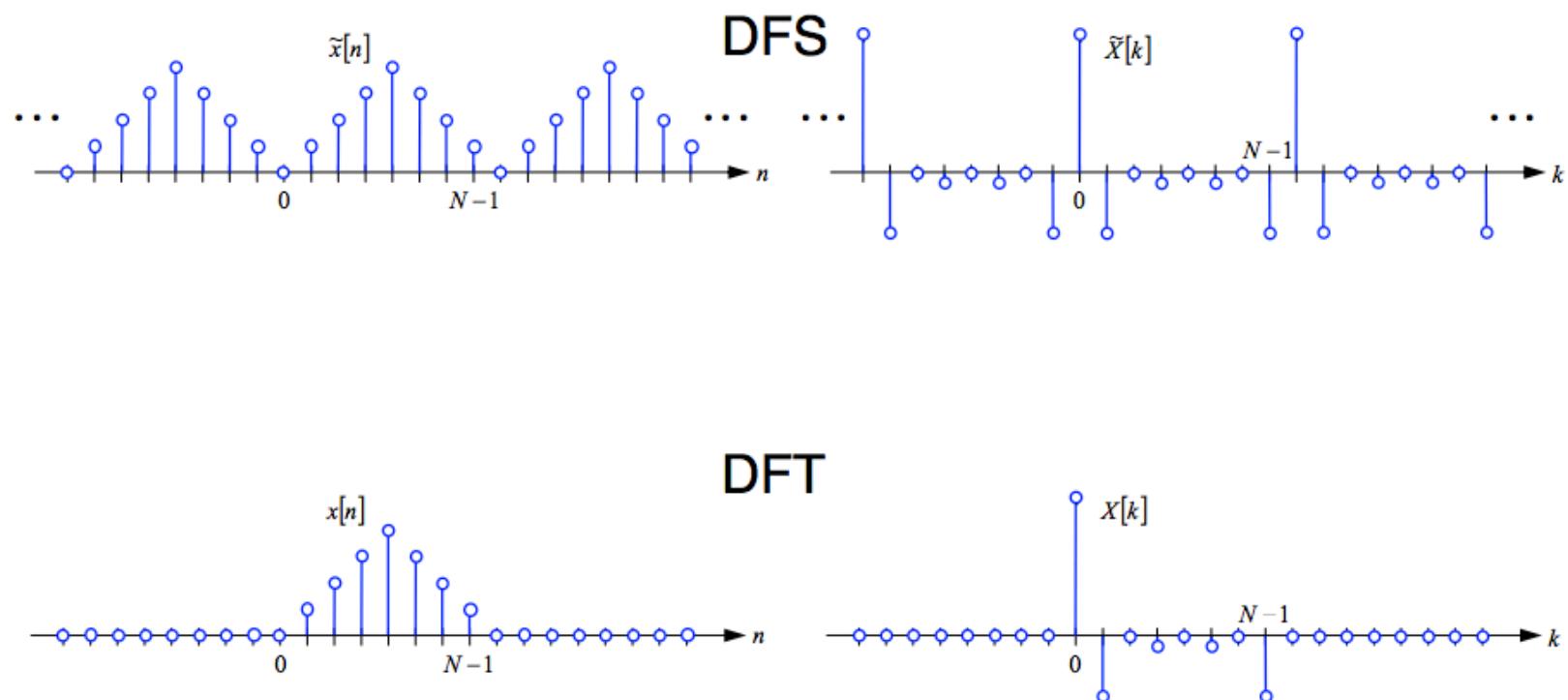
- It is understood that,

$$x[n] = 0 \quad \text{outside } 0 \leq n \leq N - 1$$

$$X[k] = 0 \quad \text{outside } 0 \leq k \leq N - 1$$



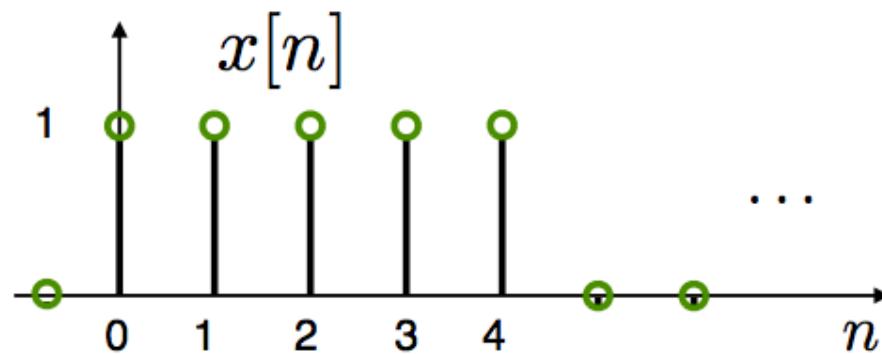
DFS vs. DFT





Example

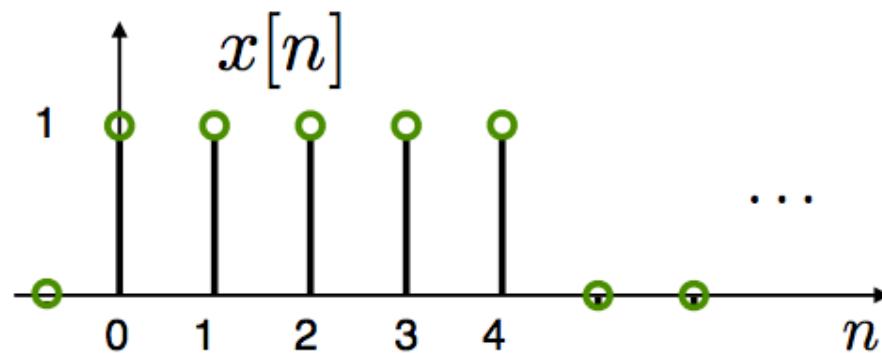
$$W_N \triangleq e^{-j2\pi/N}$$





Example

$$W_N \triangleq e^{-j2\pi/N}$$



- Take N=5

$$\begin{aligned} X[k] &= \begin{cases} \sum_{n=0}^4 W_5^{nk} & k = 0, 1, 2, 3, 4 \\ 0 & \text{otherwise} \end{cases} \\ &= 5\delta[k] \end{aligned}$$

“5-point DFT”



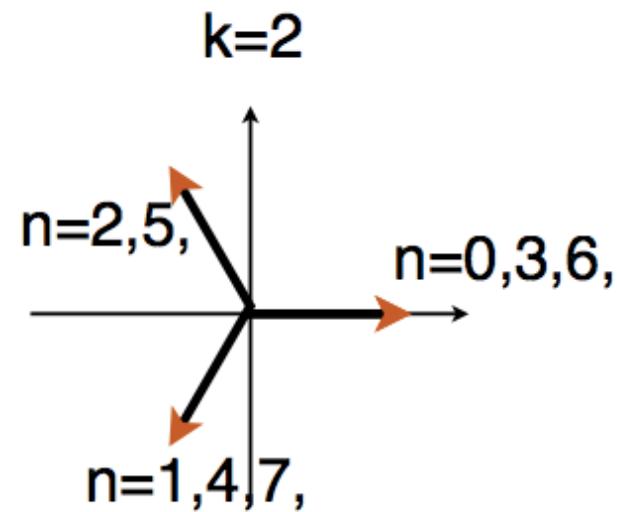
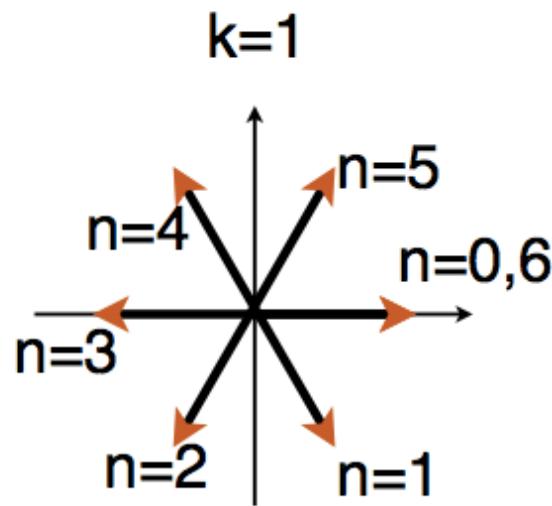
Discrete Fourier Series

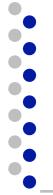
$$W_N \triangleq e^{-j2\pi/N}$$

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- $W_N^0 = W_N^N = W_N^{2N} = \dots = 1$
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□ Example: W_N^{kn} ($N=6$)




$$W_N \triangleq e^{-j2\pi/N}$$

Example

- Q: What if we take $N=10$?
- A: $X[k] = \tilde{X}[k]$ where $\tilde{x}[n]$ is a period-10 seq.

$$W_N \triangleq e^{-j2\pi/N}$$

Example

- Q: What if we take $N=10$?
- A: $X[k] = \tilde{x}[k]$ where $\tilde{x}[n]$ is a period-10 seq.



$$X[k] = \begin{cases} \sum_{n=0}^4 W_{10}^{nk} & k = 0, 1, 2, \dots, 9 \\ 0 & \text{otherwise} \end{cases}$$

“10-point DFT”



Example

- Now, sum from n=0 to 9

$$X[k] = \sum_{n=0}^9 W_{10}^{nk}$$



Example

- Now, sum from $n=0$ to 9

$$\begin{aligned} X[k] &= \sum_{n=0}^9 W_{10}^{nk} \\ &= \sum_{n=0}^4 W_{10}^{nk} \\ &= e^{-j\frac{4\pi}{10}k} \frac{\sin(\frac{\pi}{2}k)}{\sin(\frac{\pi}{10}k)} \end{aligned}$$



DFT vs. DTFT

- For finite sequences of length N:

- The N-point DFT of $x[n]$ is:

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn} = \sum_{n=0}^{N-1} x[n] e^{-j(2\pi/N)nk} \quad 0 \leq k \leq N - 1$$

- The DTFT of $x[n]$ is:

$$X(e^{j\omega}) = \sum_{n=0}^{N-1} x[n] e^{-j\omega n} \quad -\infty < \omega < \infty$$



DFT vs. DTFT

- The DFT are samples of the DTFT at N equally spaced frequencies

$$X[k] = X(e^{j\omega})|_{\omega=k\frac{2\pi}{N}} \quad 0 \leq k \leq N - 1$$



DFT vs DTFT

- Back to example

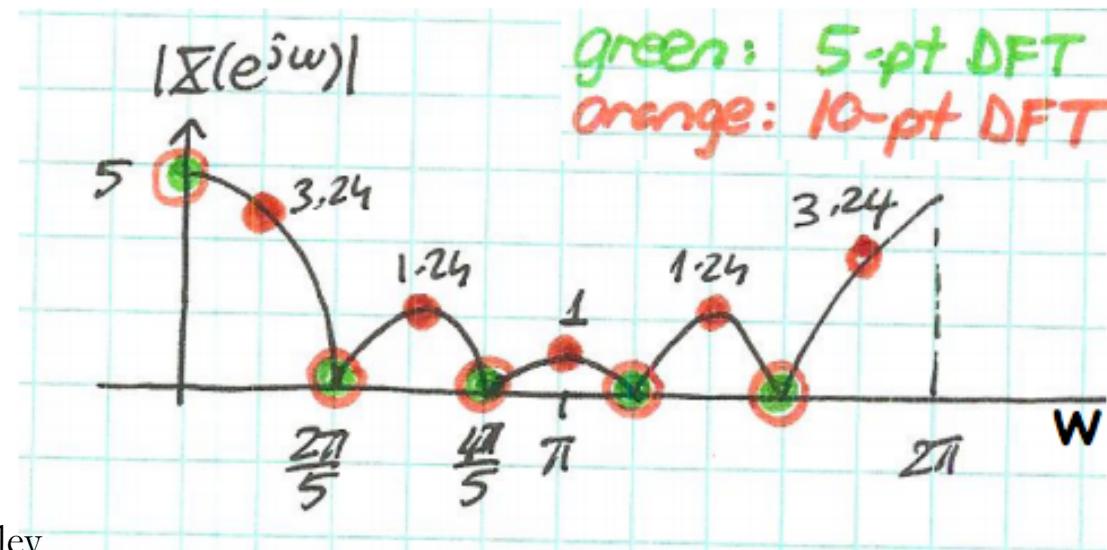
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“10-point DFT”

DFT vs DTFT

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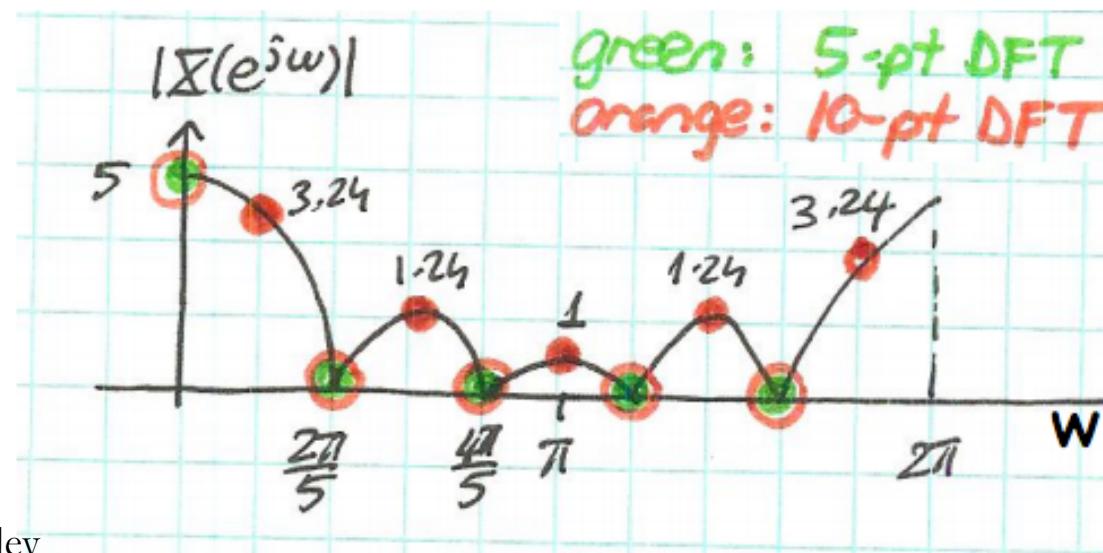


DFT vs DTFT

- Back to example

$$\begin{aligned} X[k] &= \sum_{n=0}^4 W_{10}^{nk} \\ &= e^{-j\frac{4\pi}{10}k} \frac{\sin(\frac{\pi}{2}k)}{\sin(\frac{\pi}{10}k)} \end{aligned}$$

Use `fftshift`
to center
around dc





DFT and Inverse DFT

- ❑ Use the DFT to compute the inverse DFT. How?

$$N \cdot x^*[n] = N (\mathcal{DFT}^{-1}\{X[k]\})^*$$



DFT and Inverse DFT

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DFT and Inverse DFT

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DFT and Inverse DFT

□ So

$$\mathcal{DFT}\{X^*[k]\} = N \left(\mathcal{DFT}^{-1}\{X[k]\} \right)^*$$



DFT and Inverse DFT

□ So

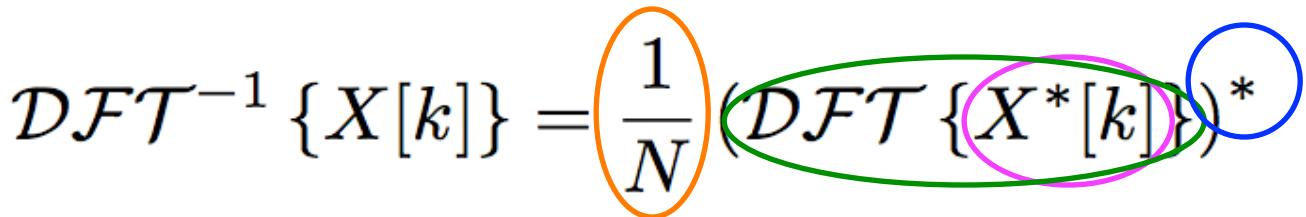
$$\mathcal{DFT}\{X^*[k]\} = N \left(\mathcal{DFT}^{-1}\{X[k]\} \right)^*$$

$$\mathcal{DFT}^{-1}\{X[k]\} = \frac{1}{N} (\mathcal{DFT}\{X^*[k]\})^*$$

DFT and Inverse DFT

□ So

$$\mathcal{DFT}\{X^*[k]\} = N \left(\mathcal{DFT}^{-1}\{X[k]\} \right)^*$$

$$\mathcal{DFT}^{-1}\{X[k]\} = \frac{1}{N} \left(\mathcal{DFT}\{X^*[k]\} \right)^*$$


□ Implement IDFT by:

- Take complex conjugate
- Take DFT
- Multiply by 1/N
- Take complex conjugate



DFT as Matrix Operator

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn}$$

DFT:

$$\begin{pmatrix} X[0] \\ \vdots \\ X[k] \\ \vdots \\ X[N-1] \end{pmatrix} = \begin{pmatrix} W_N^{00} & \dots & W_N^{0n} & \dots & W_N^{0(N-1)} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ W_N^{k0} & \dots & W_N^{kn} & \dots & W_N^{k(N-1)} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ W_N^{(N-1)0} & \dots & W_N^{(N-1)n} & \dots & W_N^{(N-1)(N-1)} \end{pmatrix} \begin{pmatrix} x[0] \\ \vdots \\ x[n] \\ \vdots \\ x[N-1] \end{pmatrix}$$



DFT as Matrix Operator

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn}$$

DFT:

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IDFT:

$$\begin{pmatrix} x[0] \\ \vdots \\ x[n] \\ \vdots \\ x[N-1] \end{pmatrix} = \frac{1}{N} \begin{pmatrix} W_N^{-00} & \cdots & W_N^{-0k} & \cdots & W_N^{-0(N-1)} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ W_N^{-n0} & \cdots & W_N^{-nk} & \cdots & W_N^{-n(N-1)} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ W_N^{-(N-1)0} & \cdots & W_N^{-(N-1)k} & \cdots & W_N^{-(N-1)(N-1)} \end{pmatrix} \begin{pmatrix} X[0] \\ \vdots \\ X[k] \\ \vdots \\ X[N-1] \end{pmatrix}$$



DFT as Matrix Operator

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn}$$

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DFT as Matrix Operator

- Can write compactly as

$$\begin{aligned}\mathbf{X} &= \mathbf{W}_N \mathbf{x} \\ \mathbf{x} &= \frac{1}{N} \mathbf{W}_N^* \mathbf{X}\end{aligned}$$



Properties of the DFT

- ❑ Properties of DFT inherited from DFS
- ❑ Linearity

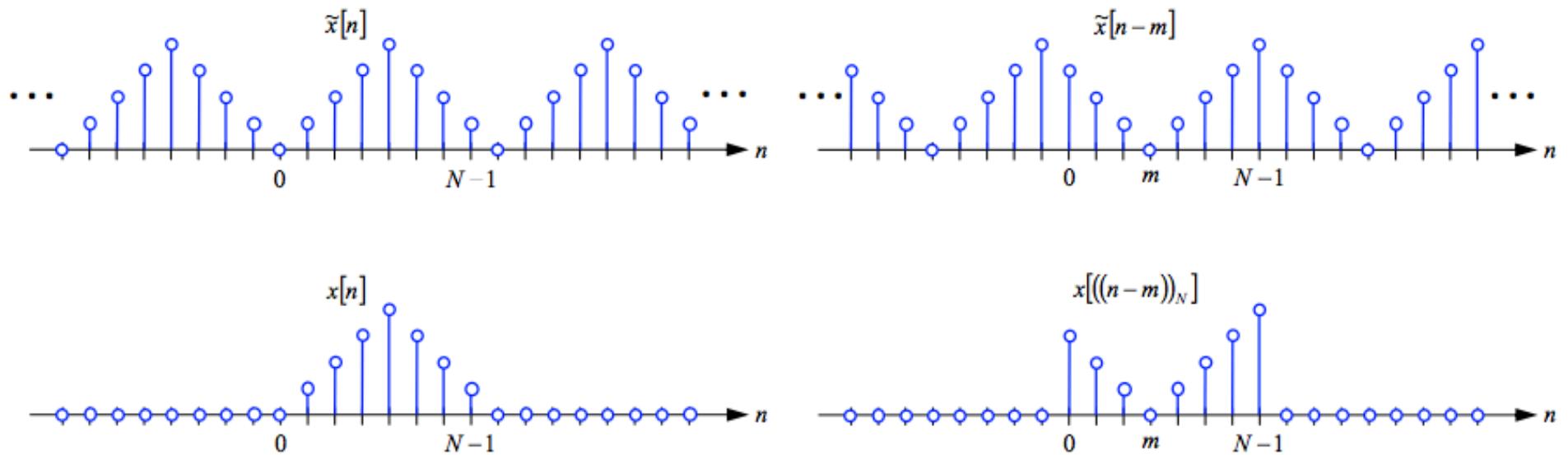
$$\alpha_1 x_1[n] + \alpha_2 x_2[n] \leftrightarrow \alpha_1 X_1[k] + \alpha_2 X_2[k]$$

- ❑ Circular Time Shift

$$x[((n - m))_N] \leftrightarrow X[k]e^{-j(2\pi/N)km} = X[k]W_N^{km}$$



Circular Shift





Properties of DFT

- ❑ Circular frequency shift

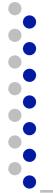
$$x[n]e^{j(2\pi/N)nl} = x[n]W_N^{-nl} \leftrightarrow X[((k-l))_N]$$

- ❑ Complex Conjugation

$$x^*[n] \leftrightarrow X^*((-k))_N$$

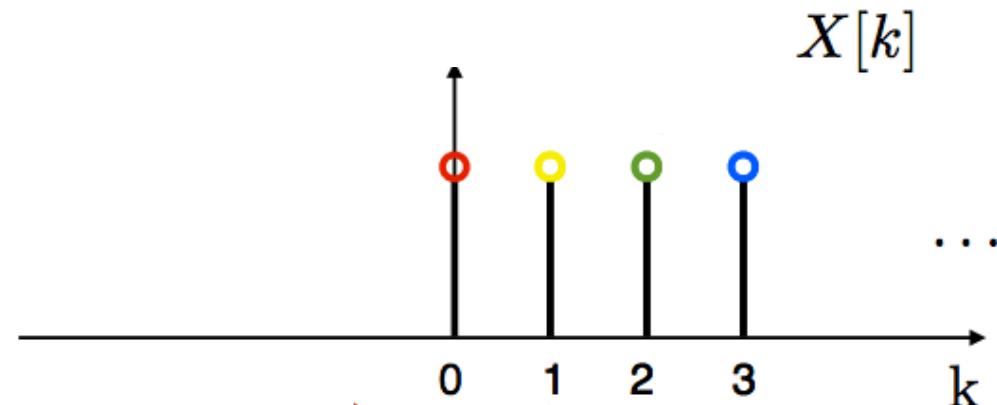
- ❑ Conjugate Symmetry for Real Signals

$$x[n] = x^*[n] \leftrightarrow X[k] = X^*((-k))_N$$



Example: Conjugate Symmetry

4-point DFT
-Symmetry

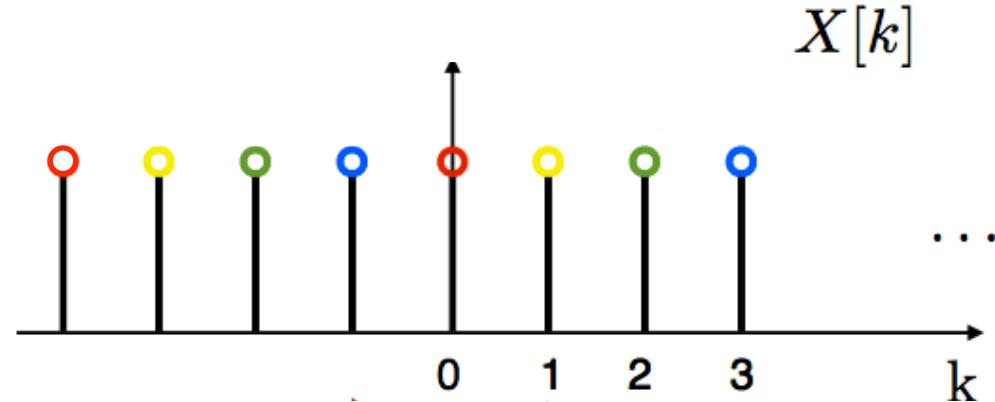




Example: Conjugate Symmetry

4-point DFT

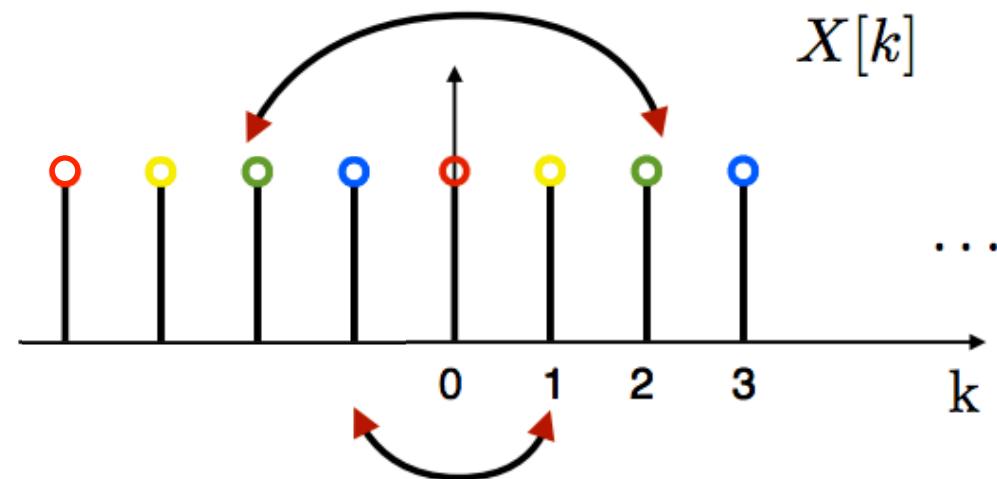
-Symmetry



Example: Conjugate Symmetry

4-point DFT

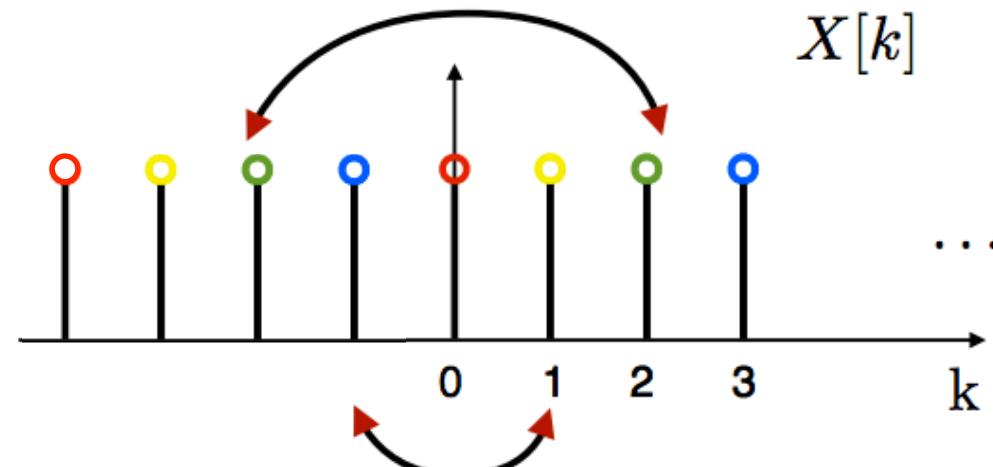
-Symmetry



Example: Conjugate Symmetry

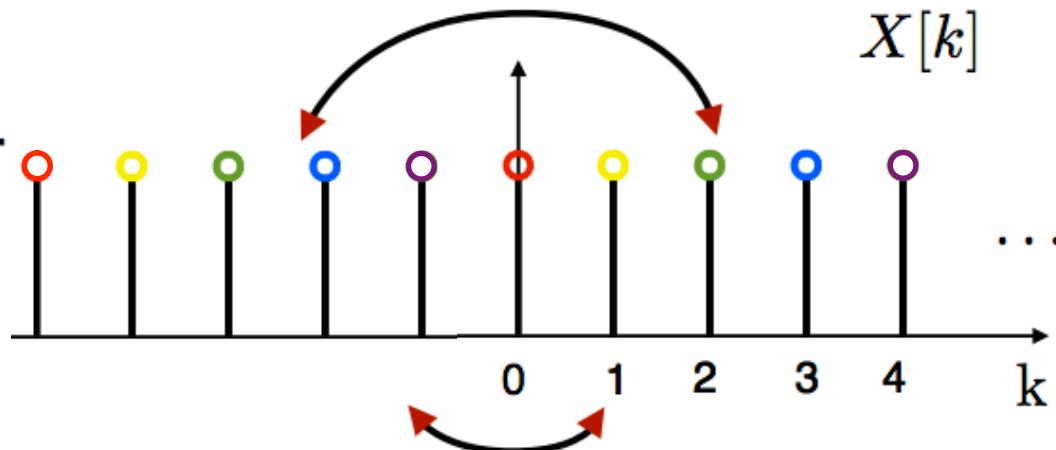
4-point DFT

-Symmetry



5-point DFT

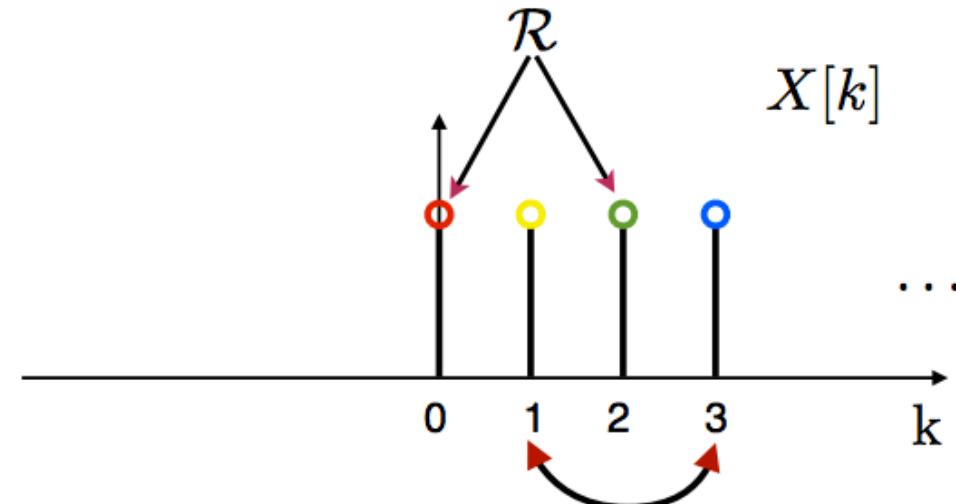
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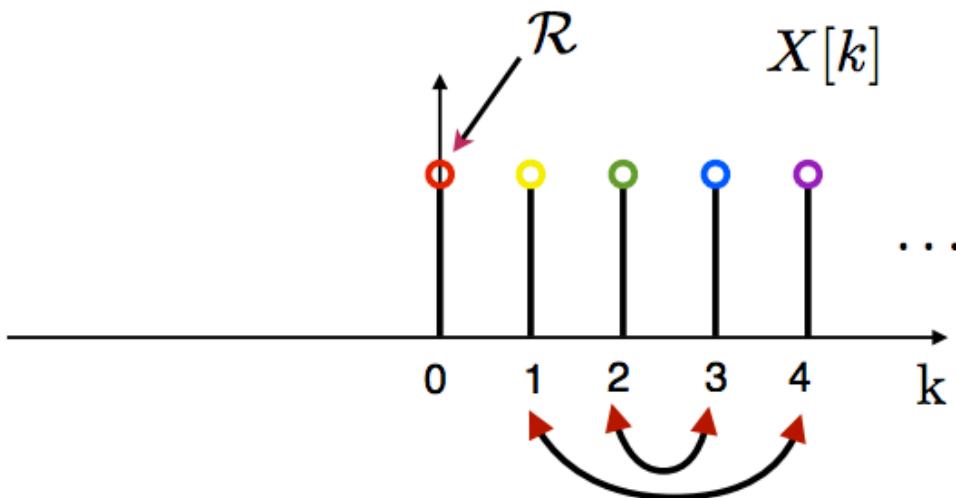


Example

4-point DFT
–Symmetry



5-point DFT
–Symmetry





Properties of the DFS/DFT

Discrete Fourier Series			Discrete Fourier Transform		
Property	N -periodic sequence	N -periodic DFS	Property	N -point sequence	N -point DFT
	$\tilde{x}[n]$ $\tilde{x}_1[n], \tilde{x}_2[n]$	$\tilde{X}[k]$ $\tilde{X}_1[k], \tilde{X}_2[k]$		$x[n]$ $x_1[n], x_2[n]$	$X[k]$ $X_1[k], X_2[k]$
Linearity	$a\tilde{x}_1[n] + b\tilde{x}_2[n]$	$a\tilde{X}_1[k] + b\tilde{X}_2[k]$	Linearity	$ax_1[n] + bx_2[n]$	$aX_1[k] + bX_2[k]$
Duality	$\tilde{X}[n]$	$N\tilde{x}[-k]$	Duality	$X[n]$	$Nx[(-k)]_N$
Time Shift	$\tilde{x}[n-m]$	$W_N^{km}\tilde{X}[k]$	Circular Time Shift	$x[((n-m))_N]$	$W_N^{km}X[k]$
Frequency Shift	$W_N^{-ln}\tilde{x}[n]$	$\tilde{X}[k-l]$	Circular Frequency Shift	$W_N^{-ln}x[n]$	$X[((k-l))_N]$
Periodic Convolution	$\sum_{m=0}^{N-1} \tilde{x}_1[m]\tilde{x}_2[n-m]$	$\tilde{X}_1[k]\tilde{X}_2[k]$	Circular Convolution	$\sum_{m=0}^{N-1} x_1[m]x_2[((n-m))_N]$	$X_1[k]X_2[k]$
Multiplication	$\tilde{x}_1[n]\tilde{x}_2[n]$	$\frac{1}{N} \sum_{l=0}^{N-1} \tilde{X}_1[l]\tilde{X}_2[k-l]$	Multiplication	$x_1[n]x_2[n]$	$\frac{1}{N} \sum_{l=0}^{N-1} X_1[l]X_2[((k-l))_N]$
Complex Conjugation	$\tilde{x}^*[n]$	$\tilde{X}^*[-k]$	Complex Conjugation	$x^*[n]$	$X^*[((-k))_N]$



Properties (Continued)

Time-Reversal and Complex Conjugation	$\tilde{x}^*[-n]$	$\tilde{X}^*[k]$	Time-Reversal and Complex Conjugation	$x^*[((-n))_N]$	$X^*[k]$
Real Part	$\text{Re}\{\tilde{x}[n]\}$	$\tilde{X}_{ep}[k] = \frac{1}{2}(\tilde{X}[k] + \tilde{X}^*[-k])$	Real Part	$\text{Re}\{x[n]\}$	$X_{ep}[k] = \frac{1}{2}(X[k] + X^*[(-k))_N])$
Imaginary Part	$j \text{Im}\{\tilde{x}[n]\}$	$\tilde{X}_{op}[k] = \frac{1}{2}(\tilde{X}[k] - \tilde{X}^*[-k])$	Imaginary Part	$j \text{Im}\{x[n]\}$	$X_{op}[k] = \frac{1}{2}(X[k] - X^*[(-k))_N])$
Even Part	$\tilde{x}_{ep}[n] = \frac{1}{2}(\tilde{x}[n] + \tilde{x}^*[-n])$	$\text{Re}\{\tilde{X}[k]\}$	Even Part	$x_{ep}[n] = \frac{1}{2}(x[n] + x^*[(-n))_N])$	$\text{Re}\{X[k]\}$
Odd Part	$\tilde{x}_{op}[n] = \frac{1}{2}(\tilde{x}[n] - \tilde{x}^*[-n])$	$j \text{Im}\{\tilde{X}[k]\}$	Odd Part	$x_{op}[n] = \frac{1}{2}(x[n] - x^*[(-n))_N])$	$j \text{Im}\{X[k]\}$
Symmetry for Real Sequence	$\tilde{x}[n] = \tilde{x}^*[n]$	$\tilde{X}[k] = \tilde{X}^*[-k]$ $\begin{cases} \text{Re}\{\tilde{X}[k]\} = \text{Re}\{\tilde{X}[-k]\} \\ \text{Im}\{\tilde{X}[k]\} = -\text{Im}\{\tilde{X}[-k]\} \end{cases}$ $\begin{cases} \tilde{X}[k] = \tilde{X}[-k] \\ \angle\tilde{X}[k] = -\angle\tilde{X}[-k] \end{cases}$	Symmetry for Real Sequence	$x[n] = x^*[n]$	$X[k] = X^*[(-k))_N]$ $\begin{cases} \text{Re}\{X[k]\} = \text{Re}\{X[(-k))_N]\} \\ \text{Im}\{X[k]\} = -\text{Im}\{X[(-k))_N]\} \end{cases}$ $\begin{cases} X[k] = X[(-k))_N] \\ \angle X[k] = -\angle X[(-k))_N] \end{cases}$
Parseval's Identity	$\sum_{n=0}^{N-1} \tilde{x}_1[n] \tilde{x}_2^*[n] = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}_1[k] \tilde{X}_2^*[k]$ $\sum_{n=0}^{N-1} \tilde{x}[n] ^2 = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}[k] ^2$	Parseval's Identity		$\sum_{n=0}^{N-1} x_1[n] x_2^*[n] = \frac{1}{N} \sum_{k=0}^{N-1} X_1[k] X_2^*[k]$ $\sum_{n=0}^{N-1} x[n] ^2 = \frac{1}{N} \sum_{k=0}^{N-1} X[k] ^2$	



Circular Convolution

- Circular Convolution:

$$x_1[n] \circledast x_2[n] \triangleq \sum_{m=0}^{N-1} x_1[m]x_2[((n-m))_N]$$

For two signals of length N

Note: Circular convolution is commutative

$$x_2[n] \circledast x_1[n] = x_1[n] \circledast x_2[n]$$



Circular Convolution

- ❑ For $x_1[n]$ and $x_2[n]$ with length N

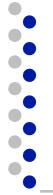
$$x_1[n] \circledast x_2[n] \leftrightarrow X_1[k] \cdot X_2[k]$$



Multiplication

- ❑ For $x_1[n]$ and $x_2[n]$ with length N

$$x_1[n] \cdot x_2[n] \leftrightarrow \frac{1}{N} X_1[k] \circledast X_2[k]$$



Linear Convolution

- Next....

- Using DFT, circular convolution is easy
- But, linear convolution is useful, not circular
- So, show how to perform linear convolution with circular convolution
- Use DFT to do linear convolution



Big Ideas

- ❑ Adaptive filtering
 - Use LMS algorithm to update filter coefficients for applications like system ID, channel equalization, and signal prediction
- ❑ Discrete Fourier Transform (DFT)
 - For finite signals assumed to be zero outside of defined length
 - N-point DFT is sampled DTFT at N points
 - Useful properties allow easier linear convolution



Admin

- ❑ HW 7 out now
 - Due tonight
- ❑ Project posted after class tonight
 - Work in groups of up to 2
 - Can work alone if you want
 - Use Piazza to find partners
 - Report your groups to me by 4/11 by email
 - taniak@seas.upenn.edu