

ESE 531: Digital Signal Processing

Lec 19: April 6, 2017
Discrete Fourier Transform

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Today

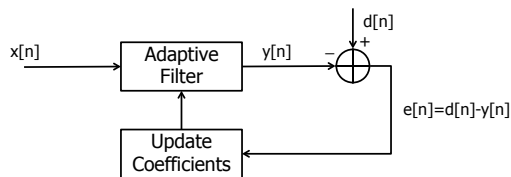
- Adaptive filtering
 - Blind equalization
- Discrete Fourier Series
- Discrete Fourier Transform (DFT)
- DFT Properties

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Adaptive Filters

- An adaptive filter is an adjustable filter that processes in time
 - It adapts...

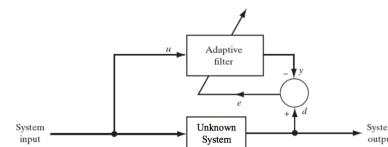


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Adaptive Filter Applications

- System Identification

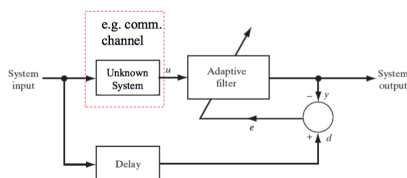


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Adaptive Filter Applications

- Identification of inverse system

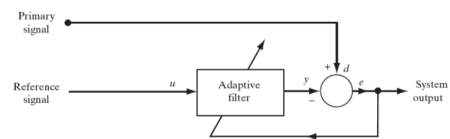


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Adaptive Filter Applications

- Adaptive Interference Cancellation

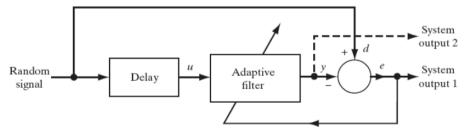


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Adaptive Filter Applications

Adaptive Prediction



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Stochastic Gradient Approach

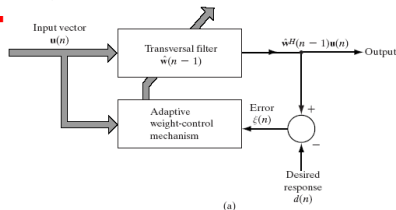
- Most commonly used type of Adaptive Filters
- Define cost function as mean-squared error
 - Difference between filter output and desired response
- Based on the method of steepest descent
 - Move towards the minimum on the error surface to get to minimum
 - Requires the gradient of the error surface to be known

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Least-Mean-Square (LMS) Algorithm

□ The LMS Algorithm consists of two basic processes

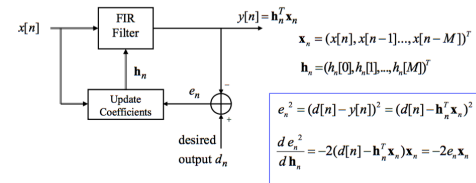
- Filtering process
 - Calculate the output of FIR filter by convolving input and taps
 - Calculate estimation error by comparing the output to desired signal



(a)

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Adaptive FIR Filter: LMS



Coefficient Update: Move in direction *opposite* to sign of gradient,
proportional to magnitude of gradient

$$\mathbf{h}_{n+1} = \mathbf{h}_n + 2\mu e_n \mathbf{x}_n$$

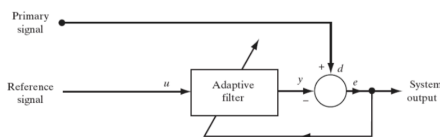
Stochastic Gradient Algorithm

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Adaptive Filter Applications

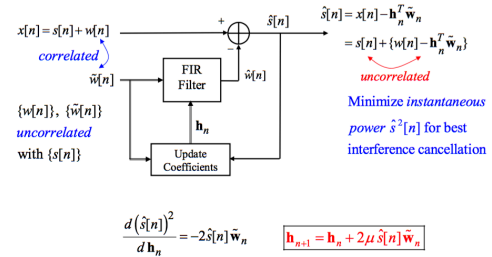
Adaptive Interference Cancellation



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Adaptive Interference Cancellation



$$\frac{d(\hat{s}[n])^2}{d\mathbf{h}_n} = -2\hat{s}[n]\tilde{\mathbf{w}}_n \quad \mathbf{h}_{n+1} = \mathbf{h}_n + 2\mu \hat{s}[n]\tilde{\mathbf{w}}_n$$

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Stability of LMS

- The LMS algorithm is convergent in the mean square if and only if the step-size parameter satisfy

$$0 < \mu < \frac{2}{\lambda_{\max}}$$

- Here $\lambda_{\max}$ is the largest eigenvalue of the correlation matrix of the input data

- More practical test for stability is

$$0 < \mu < \frac{2}{\text{input signal power}}$$

- Larger values for step size
 - Increases adaptation rate (faster adaptation)
 - Increases residual mean-squared error

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Discrete Fourier Series



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Reminder: Eigenvalue (DTFT)

- $x[n] = e^{j\omega n}$

$$\begin{aligned} y[n] &= \sum_{k=-\infty}^{\infty} x[n-k]h[k] \\ &= \sum_{k=-\infty}^{\infty} e^{j\omega(n-k)}h[k] \\ &= e^{j\omega n} \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k} \\ &= H(e^{j\omega})e^{j\omega n} \end{aligned}$$

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k}$$

- Describes the change in amplitude and phase of signal at frequency ω
- Frequency response
- Complex value
 - Re and Im
 - Mag and Phase

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Discrete Fourier Series

- Definition:

- Consider N-periodic signal:

$$\tilde{x}[n + N] = \tilde{x}[n] \quad \forall n$$

- Frequency-domain also periodic in N:

$$\tilde{X}[k + N] = \tilde{X}[k] \quad \forall k$$

- “~” indicates periodic signal/spectrum

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Discrete Fourier Series

- Define:

$$W_N \triangleq e^{-j2\pi/N}$$

- DFS:

$$\begin{aligned} \tilde{x}[n] &= \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}[k] W_N^{-kn} \\ \tilde{X}[k] &= \sum_{n=0}^{N-1} \tilde{x}[n] W_N^{kn} \end{aligned}$$

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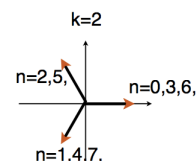
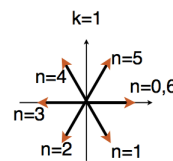
Discrete Fourier Series

$$W_N \triangleq e^{-j2\pi/N}$$

- Properties of W_N :

- $W_N^0 = W_N^N = W_N^{2N} = \dots = 1$
- $W_N^{k+r} = W_N^k W_N^r$ and $W_N^{k+N} = W_N^k$

- Example: W_N^{kn} ($N=6$)



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Discrete Fourier Transform

- By convention, work with one period:

$$x[n] \triangleq \begin{cases} \tilde{x}[n] & 0 \leq n \leq N-1 \\ 0 & \text{otherwise} \end{cases}$$

$$X[k] \triangleq \begin{cases} \tilde{X}[k] & 0 \leq k \leq N-1 \\ 0 & \text{otherwise} \end{cases}$$

Same, but different!

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Discrete Fourier Transform

- The DFT

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] W_N^{-kn} \quad \text{Inverse DFT, synthesis}$$

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn} \quad \text{DFT, analysis}$$

- It is understood that,

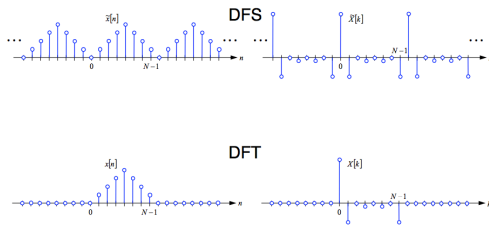
$$x[n] = 0 \quad \text{outside } 0 \leq n \leq N-1$$

$$X[k] = 0 \quad \text{outside } 0 \leq k \leq N-1$$

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DFS vs. DFT

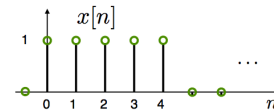


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Example

$$W_N \triangleq e^{-j2\pi/N}$$

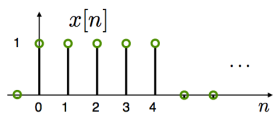


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Example

$$W_N \triangleq e^{-j2\pi/N}$$



Take $N=5$

$$X[k] = \begin{cases} \sum_{n=0}^4 W_5^{nk} & k = 0, 1, 2, 3, 4 \\ 0 & \text{otherwise} \end{cases}$$

$$= 5\delta[k] \quad \text{"5-point DFT"}$$

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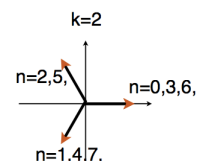
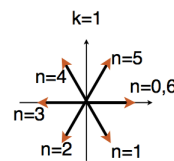
Discrete Fourier Series

$$W_N \triangleq e^{-j2\pi/N}$$

- Properties of W_N :

- $W_N^0 = W_N^N = W_N^{2N} = \dots = 1$
- $W_N^{k+r} = W_N^k W_N^r$ and $W_N^{k+N} = W_N^k$

- Example: W_N^{kn} ($N=6$)



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Example

$$W_N \triangleq e^{-j2\pi/N}$$

- Q: What if we take $N=10$?
- A: $X[k] = \tilde{X}[k]$ where $\tilde{x}[n]$ is a period-10 seq.

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Example

$$W_N \triangleq e^{-j2\pi/N}$$

- Q: What if we take $N=10$?
- A: $X[k] = \tilde{X}[k]$ where $\tilde{x}[n]$ is a period-10 seq.



$$X[k] = \begin{cases} \sum_{n=0}^4 W_{10}^{nk} & k = 0, 1, 2, \dots, 9 \\ 0 & \text{otherwise} \end{cases}$$

"10-point DFT"

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Example

- Now, sum from $n=0$ to 9

$$X[k] = \sum_{n=0}^9 W_{10}^{nk}$$

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Example

- Now, sum from $n=0$ to 9

$$\begin{aligned} X[k] &= \sum_{n=0}^9 W_{10}^{nk} \\ &= \sum_{n=0}^4 W_{10}^{nk} \\ &= e^{-j\frac{4\pi}{10}k} \frac{\sin(\frac{\pi}{2}k)}{\sin(\frac{\pi}{10}k)} \end{aligned}$$

"10-point DFT"

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DFT vs. DTFT

- For finite sequences of length N :

- The N -point DFT of $x[n]$ is:

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn} = \sum_{n=0}^{N-1} x[n] e^{-j(2\pi/N)nk} \quad 0 \leq k \leq N-1$$

- The DTFT of $x[n]$ is:

$$X(e^{j\omega}) = \sum_{n=0}^{N-1} x[n] e^{-j\omega n} \quad -\infty < \omega < \infty$$

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DFT vs. DTFT

- The DFT are samples of the DTFT at N equally spaced frequencies

$$X[k] = X(e^{j\omega})|_{\omega=k\frac{2\pi}{N}} \quad 0 \leq k \leq N-1$$

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DFT vs DTFT

- Back to example

$$\begin{aligned} X[k] &= \sum_{n=0}^4 W_{10}^{nk} \\ &= e^{-j\frac{4\pi}{10}k} \frac{\sin(\frac{\pi}{2}k)}{\sin(\frac{\pi}{10}k)} \end{aligned}$$

"10-point DFT"

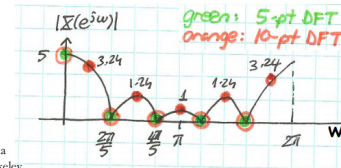
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DFT vs DTFT

- Back to example

$$\begin{aligned} X[k] &= \sum_{n=0}^4 W_{10}^{nk} \\ &= e^{-j\frac{4\pi}{10}k} \frac{\sin(\frac{\pi}{2}k)}{\sin(\frac{\pi}{10}k)} \end{aligned}$$



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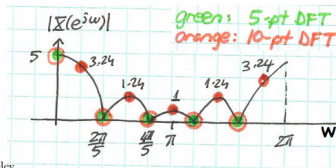
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DFT vs DTFT

- Back to example

$$\begin{aligned} X[k] &= \sum_{n=0}^4 W_{10}^{nk} \\ &= e^{-j\frac{4\pi}{10}k} \frac{\sin(\frac{\pi}{2}k)}{\sin(\frac{\pi}{10}k)} \end{aligned}$$

Use `fftshift`
to center
around dc



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DFT and Inverse DFT

- Use the DFT to compute the inverse DFT. How?

$$N \cdot x^*[n] = N (\mathcal{DFT}^{-1} \{X[k]\})^*$$

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DFT and Inverse DFT

- Use the DFT to compute the inverse DFT. How?

$$\begin{aligned} N \cdot x^*[n] &= N (\mathcal{DFT}^{-1} \{X[k]\})^* \\ &= N \left(\frac{1}{N} \sum_{k=0}^{N-1} X[k] W_N^{-kn} \right)^* \end{aligned}$$

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DFT and Inverse DFT

- Use the DFT to compute the inverse DFT. How?

$$\begin{aligned} N \cdot x^*[n] &= N (\mathcal{DFT}^{-1} \{X[k]\})^* \\ &= N \left(\frac{1}{N} \sum_{k=0}^{N-1} X[k] W_N^{-kn} \right)^* \\ &= \sum_{k=0}^{N-1} X^*[k] W_N^{kn} \end{aligned}$$

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DFT and Inverse DFT

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DFT and Inverse DFT

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DFT and Inverse DFT

- So

$$\mathcal{DFT} \{X^*[k]\} = N (\mathcal{DFT}^{-1} \{X[k]\})^*$$

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DFT and Inverse DFT

- So

$$\mathcal{DFT} \{X^*[k]\} = N (\mathcal{DFT}^{-1} \{X[k]\})^*$$

$$\mathcal{DFT}^{-1} \{X[k]\} = \frac{1}{N} (\mathcal{DFT} \{X^*[k]\})^*$$

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DFT and Inverse DFT

- So

$$\mathcal{DFT} \{X^*[k]\} = N (\mathcal{DFT}^{-1} \{X[k]\})^*$$

$$\mathcal{DFT}^{-1} \{X[k]\} = \frac{1}{N} (\mathcal{DFT} \{X^*[k]\})^*$$

- Implement IDFT by:

- Take complex conjugate
- Take DFT
- Multiply by 1/N
- Take complex conjugate

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DFT as Matrix Operator

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn}$$

DFT:

$$\begin{pmatrix} X[0] \\ \vdots \\ X[k] \\ \vdots \\ X[N-1] \end{pmatrix} = \begin{pmatrix} W_N^{00} & \cdots & W_N^{0n} & \cdots & W_N^{0(N-1)} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ W_N^{k0} & \cdots & W_N^{kn} & \cdots & W_N^{k(N-1)} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ W_N^{(N-1)0} & \cdots & W_N^{(N-1)n} & \cdots & W_N^{(N-1)(N-1)} \end{pmatrix} \begin{pmatrix} x[0] \\ \vdots \\ x[n] \\ \vdots \\ x[N-1] \end{pmatrix}$$

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DFT as Matrix Operator

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn}$$

DFT:

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IDFT:

$$\begin{pmatrix} x[0] \\ x[1] \\ \vdots \\ x[n] \\ \vdots \\ x[N-1] \end{pmatrix} = \frac{1}{N} \begin{pmatrix} W_N^{-00} & \dots & W_N^{-0k} & \dots & W_N^{-0(N-1)} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ W_N^{-(N-1)0} & \dots & W_N^{-(N-1)k} & \dots & W_N^{-(N-1)(N-1)} \end{pmatrix} \begin{pmatrix} X[0] \\ X[1] \\ \vdots \\ X[k] \\ \vdots \\ X[N-1] \end{pmatrix}$$

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DFT as Matrix Operator

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DFT:

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IDFT:

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N^2 complex multiples

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DFT as Matrix Operator

Can write compactly as

$$\mathbf{X} = \mathbf{W}_N \mathbf{x}$$

$$\mathbf{x} = \frac{1}{N} \mathbf{W}_N^* \mathbf{X}$$

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Properties of the DFT

- Properties of DFT inherited from DFS
- Linearity

$$\alpha_1 x_1[n] + \alpha_2 x_2[n] \leftrightarrow \alpha_1 X_1[k] + \alpha_2 X_2[k]$$

- Circular Time Shift

$$x[((n-m))_N] \leftrightarrow X[k] e^{-j(2\pi/N)km} = X[k] W_N^{km}$$

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Circular Shift

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Properties of DFT

- Circular frequency shift

$$x[n] e^{j(2\pi/N)nl} = x[n] W_N^{-nl} \leftrightarrow X[((k-l))_N]$$

- Complex Conjugation

$$x^*[n] \leftrightarrow X^*[((-k))_N]$$

- Conjugate Symmetry for Real Signals

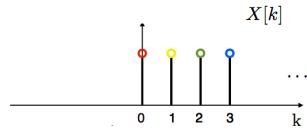
$$x[n] = x^*[n] \leftrightarrow X[k] = X^*[((-k))_N]$$

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Example: Conjugate Symmetry

4-point DFT
-Symmetry

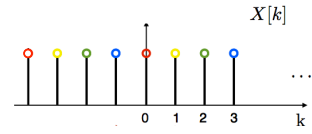


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4-point DFT
-Symmetry

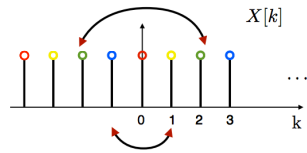


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Example: Conjugate Symmetry

4-point DFT
-Symmetry

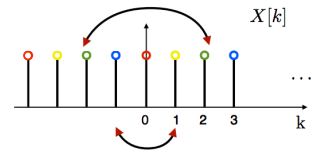


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Example: Conjugate Symmetry

4-point DFT
-Symmetry

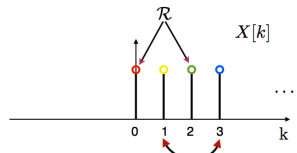


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Adapted from M. Lustig, EECS Berkeley $x[n] = x^*[n] \leftrightarrow X[k] = X^*[(N-k)]_N$

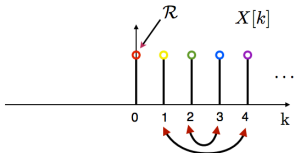
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Example

4-point DFT
-Symmetry



5-point DFT
-Symmetry



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Properties of the DFS/DFT

Discrete Fourier Series			Discrete Fourier Transform		
Property	N-periodic sequence	N-periodic DFS	Property	N-point sequence	N-point DFT
	$\tilde{x}[p]$	$\tilde{X}[k]$		$x[p]$	$X[k]$
Linearity	$a\tilde{x}_1[n] + b\tilde{x}_2[n]$	$a\tilde{X}_1[k] + b\tilde{X}_2[k]$	Linearity	$a x_1[n] + b x_2[n]$	$a X_1[k] + b X_2[k]$
Duality	$\tilde{X}[p]$	$N \tilde{x}[-k]$	Duality	$X[p]$	$N x[-k]$
Time Shift	$\tilde{x}[n-m]$	$e^{-j2\pi km/N} \tilde{X}[k]$	Circular Time Shift	$x[(n-m)]_N$	$e^{-j2\pi km/N} X[k]$
Frequency Shift	$e^{j2\pi kn/N} \tilde{x}[n]$	$\tilde{X}[k-l]$	Circular Frequency Shift	$e^{j2\pi kn/N} x[n]$	$X[k-l]$
Periodic Convolution	$\sum_{m=0}^{N-1} \tilde{x}_1[m] \tilde{x}_2[n-m]$	$\tilde{X}_1[k] \tilde{X}_2[k]$	Circular Convolution	$\sum_{m=0}^{N-1} x_1[m] x_2[(n-m)]_N$	$X_1[k] X_2[k]$
Multiplication	$\tilde{x}_1[n] \tilde{x}_2[n]$	$\frac{1}{N} \sum_{l=0}^{N-1} \tilde{X}_1[l] \tilde{X}_2[k-l]$	Multiplication	$x_1[n] x_2[n]$	$\frac{1}{N} \sum_{l=0}^{N-1} X_1[l] X_2[k-l]$
Complex Conjugation	$\tilde{x}^*[n]$	$\tilde{X}^*[-k]$	Complex Conjugation	$x^*[n]$	$X^*[-k]$

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Properties (Continued)

Time-Reversal and Complex Conjugation	$x^*[-n]$	$\tilde{x}[k]$	Time-Reversal and Complex Conjugation	$x^*[(n-a)]_N$	$X^*[k]$
Real Part	$\text{Re}\{x[n]\}$	$\tilde{x}_r[n] = \frac{1}{2}(x[n] + x^*[-n])$	Real Part	$\text{Re}\{x[n]\}$	$X_r[k] = \frac{1}{2}(X[k] + X^*[-k])$
Imaginary Part	$\text{Im}\{x[n]\}$	$\tilde{x}_i[n] = \frac{1}{2j}(x[n] - x^*[-n])$	Imaginary Part	$\text{Im}\{x[n]\}$	$X_i[k] = \frac{1}{2j}(X[k] - X^*[-k])$
Even Part	$x_e[n] = \frac{1}{2}(x[n] + x[-n])$	$\text{Re}\{X[k]\}$	Even Part	$x_e[n] = \frac{1}{2}(x[n] + x[-n])$	$\text{Re}\{X[k]\}$
Odd Part	$x_o[n] = \frac{1}{2j}(x[n] - x[-n])$	$\text{Im}\{X[k]\}$	Odd Part	$x_o[n] = \frac{1}{2j}(x[n] - x[-n])$	$\text{Im}\{X[k]\}$
Symmetry for Real Sequence	$x[n] = x^*[n]$	$\begin{cases} \tilde{x}[k] = \tilde{x}^*[-k] \\ \text{Re}\{\tilde{x}[k]\} = \text{Re}\{\tilde{x}^*[-k]\} \\ \text{Im}\{\tilde{x}[k]\} = -\text{Im}\{\tilde{x}^*[-k]\} \end{cases}$	Symmetry for Real Sequence	$x[n] = x^*[n]$	$\begin{cases} X[k] = X^*[-k] \\ \text{Re}\{X[k]\} = \text{Re}\{X^*[-k]\} \\ \text{Im}\{X[k]\} = -\text{Im}\{X^*[-k]\} \end{cases}$
Parseval's Identity	$\sum_{n=0}^{N-1} x[n]y^*[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k]Y^*[k]$		Parseval's Identity	$\sum_{n=0}^{N-1} x[n]y^*[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k]Y^*[k]$	

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Circular Convolution

□ Circular Convolution:

$$x_1[n] \circledast x_2[n] \triangleq \sum_{m=0}^{N-1} x_1[m]x_2[((n-m))_N]$$

For two signals of length N

Note: Circular convolution is commutative

$$x_2[n] \circledast x_1[n] = x_1[n] \circledast x_2[n]$$

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Circular Convolution

□ For $x_1[n]$ and $x_2[n]$ with length N

$$x_1[n] \circledast x_2[n] \leftrightarrow X_1[k] \cdot X_2[k]$$

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Multiplication

□ For $x_1[n]$ and $x_2[n]$ with length N

$$x_1[n] \cdot x_2[n] \leftrightarrow \frac{1}{N} X_1[k] \circledast X_2[k]$$

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Linear Convolution

□ Next....

- Using DFT, circular convolution is easy
- But, linear convolution is useful, not circular
- So, show how to perform linear convolution with circular convolution
- Use DFT to do linear convolution

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Big Ideas

□ Adaptive filtering

- Use LMS algorithm to update filter coefficients for applications like system ID, channel equalization, and signal prediction

□ Discrete Fourier Transform (DFT)

- For finite signals assumed to be zero outside of defined length
- N-point DFT is sampled DTFT at N points
- Useful properties allow easier linear convolution

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Admin

- HW 7 out now
 - Due tonight

- Project posted after class tonight
 - Work in groups of up to 2
 - Can work alone if you want
 - Use Piazza to find partners
 - Report your groups to me by 4/11 by email
 - taniak@seas.upenn.edu