

ESE 531: Digital Signal Processing

Lec 4: January 24, 2017
Discrete Time Fourier Transform



Lecture Outline

- Difference Equations
- Eigenfunctions
- Discrete Time Fourier Transform
 - Definition
 - Properties
- Frequency Response of LTI Systems

LTI Systems

Difference Equations



LTI Systems

A system $\mathcal{H}$ is **linear time-invariant (LTI)** if it is both linear and time-invariant

- LTI system can be completely characterized by its impulse response

$$\delta \rightarrow \boxed{\mathcal{H}} \rightarrow h$$

- Then the output for an arbitrary input is a sum of weighted, delay impulse responses

$$x \rightarrow \boxed{h} \rightarrow y \quad y[n] = \sum_{m=-\infty}^{\infty} h[n-m]x[m]$$
$$y[n] = x[n] * h[n]$$

Difference Equations

- Accumulator example

$$y[n] = \sum_{k=-\infty}^n x[k]$$
$$y[n] = x[n] + \sum_{k=-\infty}^{n-1} x[k]$$
$$y[n] = x[n] + y[n-1]$$
$$y[n] - y[n-1] = x[n]$$

Difference Equations

- Accumulator example

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$$y[n] - y[n-1] = x[n]$$

$$\sum_{k=0}^N a_k y[n-k] = \sum_{m=0}^M b_m y[n-m]$$

Difference Equations

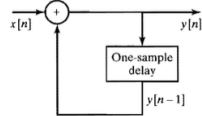
- Accumulator example

$$y[n] = \sum_{k=-\infty}^n x[k]$$

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$$y[n] - y[n-1] = x[n]$$



$$\sum_{k=0}^N a_k y[n-k] = \sum_{m=0}^M b_m y[n-m]$$

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Example: Difference Equation

- Moving Average System

$$y[n] = \frac{1}{M_1 + M_2 + 1} \sum_{k=-M_1}^{M_2} x[n-k]$$

- Let $M_1=0$ (i.e. system is causal)

$$y[n] = \frac{1}{M_2 + 1} \sum_{k=0}^{M_2} x[n-k]$$

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Eigenfunctions



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Eigenfunction

- $x[n] = e^{j\omega n}$

$$y[n] = \sum_{k=-\infty}^{\infty} x[n-k]h[k]$$

$$= \sum_{k=-\infty}^{\infty} e^{j\omega(n-k)}h[k]$$

$$= e^{j\omega n} \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k}$$

$$= H(e^{j\omega})e^{j\omega n}$$

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Eigenvalue (frequency response)

- $x[n] = e^{j\omega n}$

$$y[n] = \sum_{k=-\infty}^{\infty} x[n-k]h[k]$$

$$= \sum_{k=-\infty}^{\infty} e^{j\omega(n-k)}h[k]$$

$$= e^{j\omega n} \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k}$$

$$= H(e^{j\omega})e^{j\omega n}$$

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k}$$

- Describes the change in amplitude and phase of signal at frequency ω
- Frequency response
- Complex value
 - Re and Im
 - Mag and Phase

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CT vs DT Frequency Response

- $H(e^{j(\omega+2\pi)n})?$

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CT vs DT Frequency Response

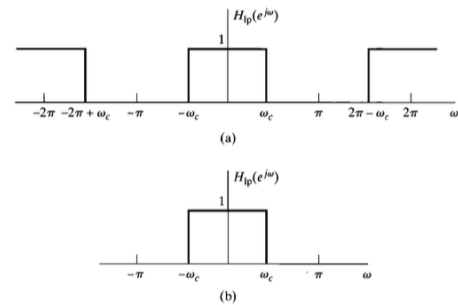
□ $H(e^{j(\omega+2\pi)n})$?

$$\begin{aligned} H(e^{j(\omega+2\pi)n}) &= \sum_{k=-\infty}^{\infty} h[k] e^{-j(\omega+2\pi)kn} \\ &= \sum_{k=-\infty}^{\infty} h[k] e^{-j\omega kn} e^{-j2\pi kn} \\ &= \sum_{k=-\infty}^{\infty} h[k] e^{-j\omega kn} \\ &= H(e^{j\omega n}) \end{aligned}$$

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Periodicity of Low Pass Freq Response

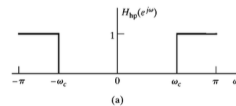


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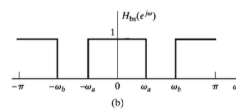
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Other Filters

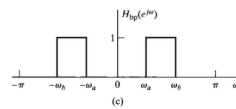
High-pass



Band-stop



Band-pass



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Discrete-Time Fourier Transform (DTFT)



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DTFT Definition

$$\begin{aligned} X(e^{j\omega}) &= \sum_{k=-\infty}^{\infty} x[k] e^{-j\omega k} \\ x[n] &= \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega \end{aligned}$$

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DTFT Definition

$$\begin{aligned} X(e^{j\omega}) &= \sum_{k=-\infty}^{\infty} x[k] e^{-j\omega k} \\ x[n] &= \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega \end{aligned}$$

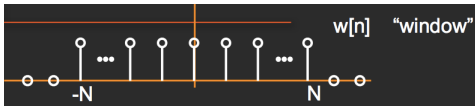
Alternate

$$\begin{aligned} X(f) &= \sum_{k=-\infty}^{\infty} x[k] e^{-j2\pi f k} \\ x[n] &= \int_{-0.5}^{0.5} X(f) e^{j2\pi f n} df \end{aligned}$$

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Example: Window DTFT



$$W(e^{j\omega}) = \sum_{k=-\infty}^{\infty} w[k]e^{-j\omega k}$$

$$= \sum_{k=-N}^N e^{-j\omega k}$$

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Example: Window DTFT

$$W(e^{j\omega}) = \sum_{k=-N}^N e^{-j\omega k}$$

$$= e^{j\omega N} + e^{j\omega(N-1)} + \dots + e^{j\omega 0} + \dots + e^{-j\omega(N-1)} + e^{-j\omega N}$$

$$= e^{-j\omega N} (1 + e^{j\omega} + \dots + e^{j\omega N} + \dots + e^{j\omega(2N-1)} + e^{j\omega 2N})$$

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Example: Window DTFT

$$W(e^{j\omega}) = \sum_{k=-N}^N e^{-j\omega k}$$

$$= e^{j\omega N} + e^{j\omega(N-1)} + \dots + e^{j\omega 0} + \dots + e^{-j\omega(N-1)} + e^{-j\omega N}$$

$$= e^{-j\omega N} (1 + e^{j\omega} + \dots + e^{j\omega N} + \dots + e^{j\omega(2N-1)} + e^{j\omega 2N})$$

Useful sum: $1 + p + p^2 + \dots + p^M = \frac{1 - p^{M+1}}{1 - p}$

$$= e^{-j\omega N} (1 + e^{j\omega} + \dots + e^{j\omega N} + \dots + e^{j\omega(2N-1)} + e^{j\omega 2N})$$

$$= e^{-j\omega N} \frac{1 - e^{j\omega(2N+1)}}{1 - e^{j\omega}}$$

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Example: Window DTFT

$$W(e^{j\omega}) = e^{-j\omega N} \frac{1 - e^{j\omega(2N+1)}}{1 - e^{j\omega}}$$

$$= \frac{e^{-j\omega N} - e^{j\omega(N+1)}}{1 - e^{j\omega}}$$

$$= \frac{e^{-j\omega N} - e^{j\omega(N+1)}}{1 - e^{j\omega}} \times \frac{e^{-j\omega/2}}{e^{-j\omega/2}}$$

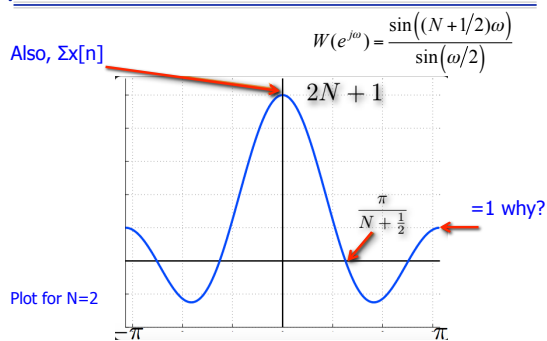
$$= \frac{e^{-j\omega(N+1/2)} - e^{j\omega(N+1/2)}}{e^{-j\omega/2} - e^{j\omega/2}} = \frac{\sin((N+1/2)\omega)}{\sin(\omega/2)}$$

Periodic sinc

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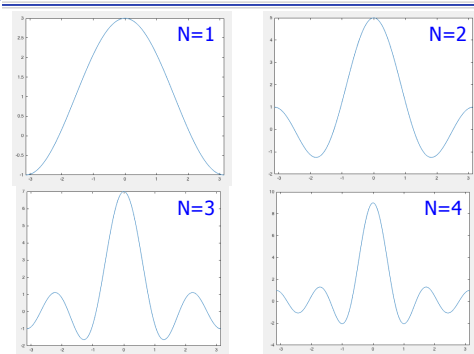
Example: Window DTFT



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Periodic Sinc



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Properties of the DTFT

Linearity:

$$ax_1[n] + bx_2[n] \leftrightarrow aX_1(e^{j\omega}) + bX_2(e^{j\omega})$$

Periodicity:

$$X(e^{j(\omega+2\pi)}) = X(e^{j\omega})$$

Conjugate Symmetry:

$$X^*(e^{j\omega}) = X(e^{-j\omega}) \quad \text{If } x[n] \text{ real}$$

$$\text{Re}\{X(e^{-j\omega})\} = \text{Re}\{X(e^{j\omega})\}$$

$$\text{Im}\{X(e^{-j\omega})\} = -\text{Im}\{X(e^{j\omega})\}$$

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Properties of the DTFT

Time Reversal:

$$x[n] \leftrightarrow X(e^{j\omega}) \quad \text{If } x[n] \text{ real}$$

$$x[-n] \leftrightarrow X(e^{-j\omega}) \quad x[-n] \leftrightarrow X^*(e^{-j\omega})$$

Time/Freq Shifting:

$$x[n] \leftrightarrow X(e^{j\omega})$$

$$x[n - n_d] \leftrightarrow e^{-j\omega n_d} X(e^{j\omega})$$

$$e^{j\omega_0 n} x[n] \leftrightarrow X(e^{j(\omega - \omega_0)})$$

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Properties of the DTFT

Differentiation in Frequency:

$$x[n] \leftrightarrow X(e^{j\omega})$$

$$nx[n] \leftrightarrow j \frac{dX(e^{j\omega})}{d\omega}$$

Convolution in Time:

$$y[n] = x[n] * h[n]$$

$$Y(e^{j\omega}) = X(e^{j\omega})H(e^{j\omega})$$

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Example: Windowed $\cos(\pi n)$

What is DTFT of:



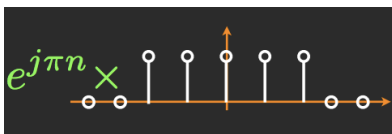
$$X(e^{j\omega}) = \sum_{k=-\infty}^{\infty} x[k]e^{-j\omega k}$$

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Example: Windowed $\cos(\pi n)$

What is DTFT of:



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Properties of the DTFT

Time Reversal:

$$x[n] \leftrightarrow X(e^{j\omega}) \quad \text{If } x[n] \text{ real}$$

$$x[-n] \leftrightarrow X(e^{-j\omega}) \quad x[-n] \leftrightarrow X^*(e^{-j\omega})$$

Time/Freq Shifting:

$$x[n] \leftrightarrow X(e^{j\omega})$$

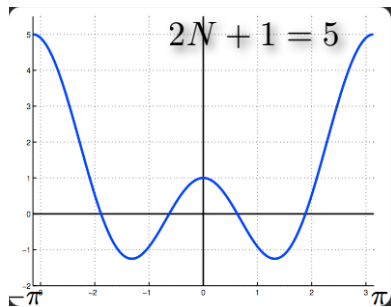
$$x[n - n_d] \leftrightarrow e^{-j\omega n_d} X(e^{j\omega})$$

$$e^{j\omega_0 n} x[n] \leftrightarrow X(e^{j(\omega - \omega_0)})$$

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Example: Windowed $\cos(\pi n)$



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Frequency Response of LTI Systems



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LTI Systems

A system $\mathcal{H}$ is **linear time-invariant (LTI)** if it is both linear and time-invariant

- LTI system can be characterized by its impulse response $H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k}$
- Then the output for an arbitrary input is a sum of weighted, delay impulse responses

$$x \rightarrow \boxed{h} \rightarrow y \quad y[n] = \sum_{m=-\infty}^{\infty} h[n-m]x[m]$$

$$y[n] = x[n] * h[n]$$

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LTI System Frequency Response

- Fourier Transform of impulse response

$$x[n] = e^{j\omega n} \rightarrow \boxed{\text{LTI System}} \rightarrow y[n] = H(e^{j\omega})e^{j\omega n}$$

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k}$$

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Example: Moving Average

- Moving Average Filter

- Causal: $M_1=0, M_2=M$

$$y[n] = \frac{x[n-M] + \dots + x[n]}{M+1}$$

Impulse response



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Example: Moving Average

- Moving Average Filter

- Causal: $M_1=0, M_2=M$

$$y[n] = \frac{x[n-M] + \dots + x[n]}{M+1}$$

Impulse response



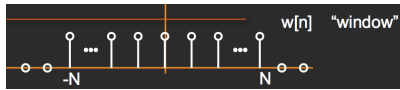
Scaled & Time Shifted window



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Example: Moving Average



$$w[n] \leftrightarrow W(e^{j\omega}) = \frac{\sin((N+1/2)\omega)}{\sin(\omega/2)}$$

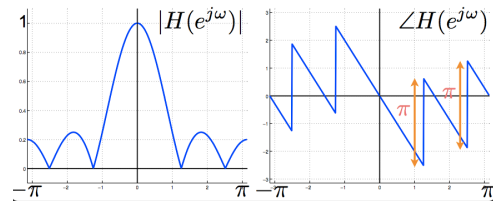


$$\frac{1}{M+1} w[n - M/2] \leftrightarrow W(e^{j\omega}) = \frac{e^{-j\omega M/2}}{M+1} \frac{\sin((M/2+1/2)\omega)}{\sin(\omega/2)}$$

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Example: Moving Average



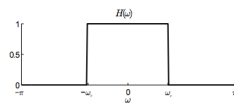
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Example: Ideal Low-Pass Filter

- The frequency response $H(\omega)$ of the ideal low-pass filter passes low frequencies (near $\omega = 0$) but blocks high frequencies (near $\omega = \pm\pi$)

$$H(\omega) = \begin{cases} 1 & -\omega_c \leq \omega \leq \omega_c \\ 0 & \text{otherwise} \end{cases}$$



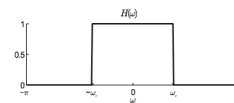
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Example: Ideal Low-Pass Filter

- The frequency response $H(\omega)$ of the ideal low-pass filter passes low frequencies (near $\omega = 0$) but blocks high frequencies (near $\omega = \pm\pi$)

$$H(\omega) = \begin{cases} 1 & -\omega_c \leq \omega \leq \omega_c \\ 0 & \text{otherwise} \end{cases}$$



- Compute the impulse response $h[n]$ given this $H(\omega)$
- Apply the inverse DTFT

$$h[n] = \int_{-\pi}^{\pi} H(\omega) e^{j\omega n} \frac{d\omega}{2\pi} = \int_{-\omega_c}^{\omega_c} e^{j\omega n} \frac{d\omega}{2\pi} = \frac{e^{j\omega_c n} - e^{-j\omega_c n}}{2\pi j n} = \frac{\omega_c \sin(\omega_c n)}{\pi \omega_c n}$$

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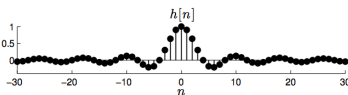
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Example: Ideal Low-Pass Filter

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$$H(\omega) = \begin{cases} 1 & -\omega_c \leq |\omega| \leq \omega_c \\ 0 & \text{otherwise} \end{cases}$$

$$h[n] = 2\omega_c \frac{\sin(\omega_c n)}{\omega_c n}$$



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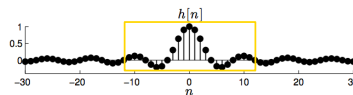
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Example: Ideal Low-Pass Filter

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$$H(\omega) = \begin{cases} 1 & -\omega_c \leq |\omega| \leq \omega_c \\ 0 & \text{otherwise} \end{cases}$$

$$h[n] = 2\omega_c \frac{\sin(\omega_c n)}{\omega_c n}$$



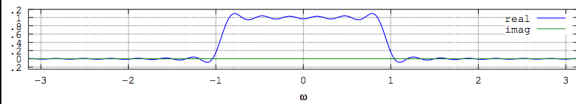
Truncation
and shift

$$h_{LP}[n] = w_N[n - N] \cdot h[n - N]$$

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Example: Practical LP Filter



- Pass band smeared and rippled
 - Smearing determined by width of main lobe
 - Rippling determined by size of main lobes

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Big Ideas

- Difference Equations
 - Help see implementation... more next time with z-transform
- Discrete Time Fourier Transform
 - Represent signals as a sum of scaled and phase shifted complex sinusoids (eigenfunctions) $X(e^{j\omega}) = \sum_{k=-\infty}^{\infty} x[k]e^{-j\omega k}$
 - Continuous in frequency over 2π
- Frequency Response of LTI Systems $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})e^{j\omega n} d\omega$
 - Frequency response of impulse response
 - Describes scaling and phase shifting of a pure frequency

$$x[n] = e^{j\omega n} \rightarrow \boxed{\text{LTI System}} \rightarrow y[n] = H(e^{j\omega})e^{j\omega n}$$

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Admin

- HW 1 out now
 - Due 1/27 at midnight
 - Submit in Canvas
- Updated office hours
 - See Piazza and course website for info

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