ESE 531: Digital Signal Processing

Lec 8: February 7th, 2017

Sampling and Reconstruction

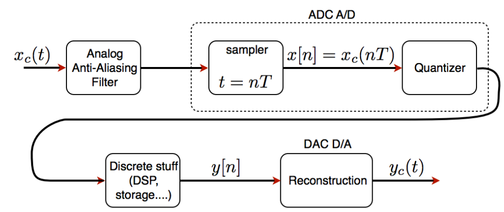
Lecture Outline

- Review
  - Ideal sampling
  - Frequency response of sampled signal
  - Reconstruction
  - Anti-aliasing filtering
- DT processing of CT signals
- CT processing of DT signals (why??)

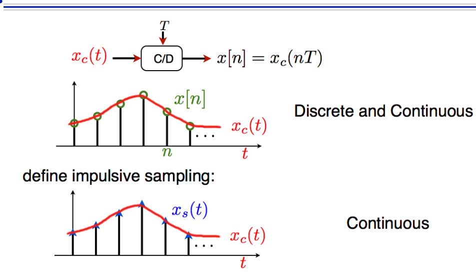
Last Time…

Sampling, Frequency Response of Sampled Signal, Reconstruction, Anti-aliasing filtering

DSP System



Ideal Sampling Model



$$x_s(t) = \cdots + x_c(0)\delta(t) + x_c(T)\delta(t-T) + \cdots$$

$$x_s(t) = x_c \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

Frequency Domain Analysis

- How is x[n] related to $x_s(t)$ in frequency domain?

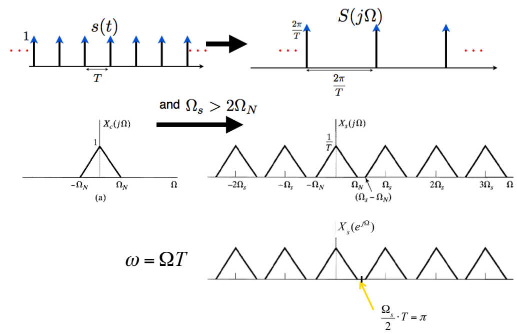
$$x[n] = x_c(nT) \qquad x_s(t) = x_c \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

$x_s(t)$:C.T $\qquad X_s(j\Omega) = \sum_n x_c(nT) e^{-j\Omega nT}$

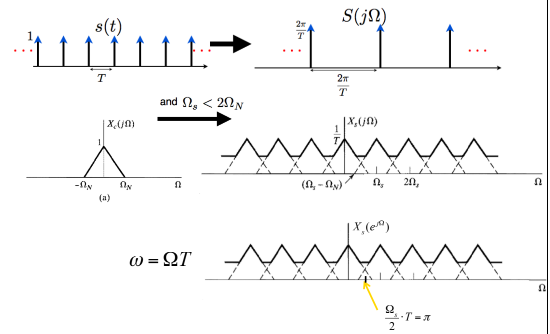
$x[n]$:D.T $\qquad X(e^{j\omega}) = \sum_n x[n] e^{-j\omega n} \qquad \omega = \Omega T$

$$X(e^{j\omega}) = X_s(j\Omega)|_{\Omega=\omega/T} \qquad X_s(j\Omega) = X(e^{j\omega})|_{\omega=\Omega T}$$

Frequency Domain Analysis



Frequency Domain Analysis

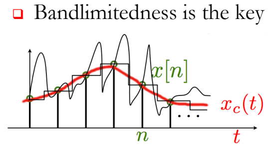


Reconstruction of Bandlimited Signals

- Nyquist Sampling Theorem: Suppose $x_c(t)$ is bandlimited. I.e.

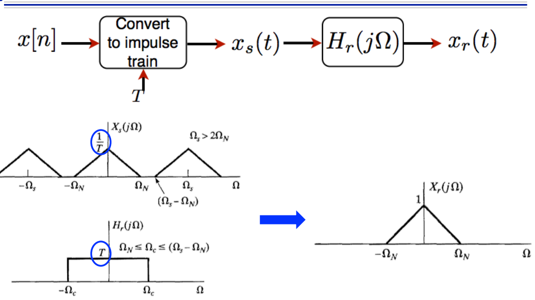
$$X_c(j\Omega) = 0 \quad \forall \quad |\Omega| \geq \Omega_N$$

- If $\Omega_s \geq 2\Omega_N$, then $x_c(t)$ can be uniquely determined from its samples $x[n]=x_c(nT)$
- Bandlimitedness is the key to uniqueness



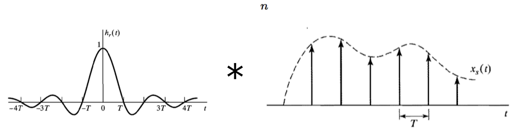
Mulitiple signals go through the samples, but only one is bandlimited within our sampling band

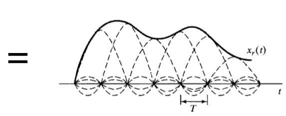
Reconstruction in Frequency Domain



Reconstruction in Time Domain

$$x_r(t) = x_s(t) * h_r(t) = \left(\sum_n x[n]\delta(t-nT)\right) * h_r(t)$$
$$= \sum_n x[n]h_r(t-nT)$$

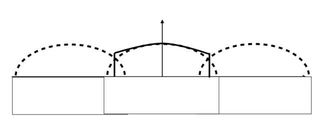




The sum of "sincs" gives $x_r(t)$ → unique signal that is bandlimited by sampling bandwidth

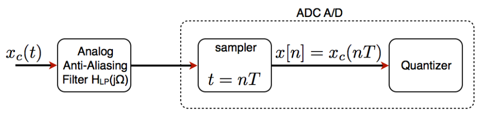
Aliasing

- If $\Omega_N > \Omega_s/2$, $x_r(t)$ an aliased version of $x_c(t)$

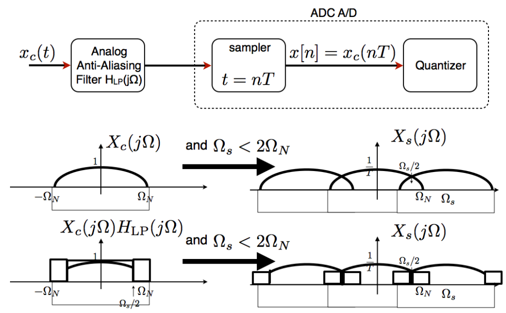


$$X_r(j\Omega) = \begin{cases} TX_s(j\Omega) & \text{if} \quad |\Omega| \leq \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

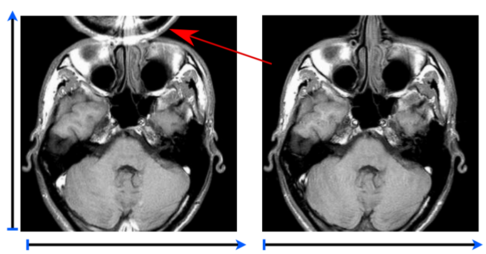
Anti-Aliasing Filter



Anti-Aliasing Filter



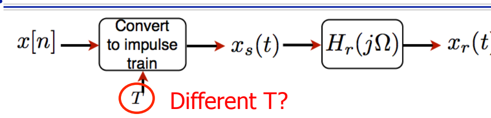
MRI aliasing example

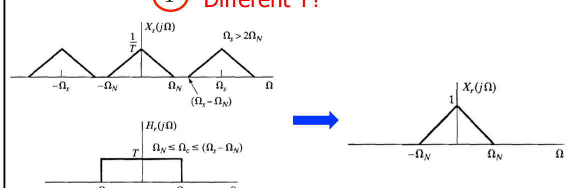


MRI anti-aliasing example

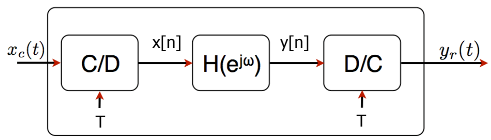
MRI anti-aliasing example

Reconstruction in Frequency Domain



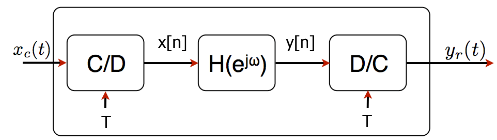


Discrete-Time Processing of Continuous Time



$$X(e^{j\omega}) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c\left[j\left(\frac{\omega}{T}-\frac{2\pi k}{T}\right)\right]$$

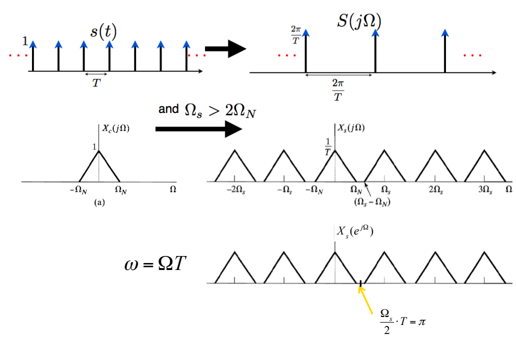
Discrete-Time Processing of Continuous Time



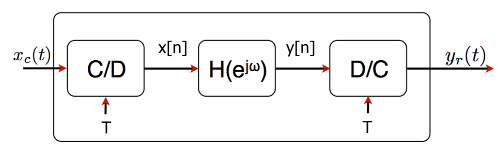
$$X_s(j\Omega) = \frac{1}{2\pi}X_c(j\Omega) * S(j\Omega) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s)) \qquad \Omega_s = \frac{2\pi}{T}$$

$$X(e^{j\omega}) = X_s(j\Omega)|_{\Omega=\omega/T} \qquad X(e^{j\omega}) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c\left[j\left(\frac{\omega}{T}-\frac{2\pi k}{T}\right)\right]$$

Frequency Domain Analysis



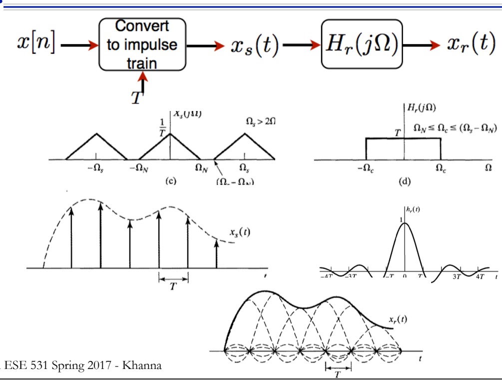
Discrete-Time Processing of Continuous Time



$$X(e^{j\omega}) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c\left[j\left(\frac{\omega}{T}-\frac{2\pi k}{T}\right)\right]$$

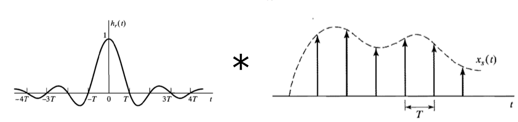
$$y_r(t) = \sum_{n=-\infty}^{\infty} y[n]\frac{\sin[\pi(t-nT)/T]}{\pi(t-nT)/T}$$

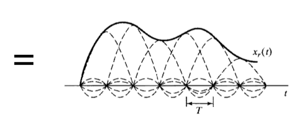
Reconstruction in Frequency Domain



Reconstruction in Time Domain

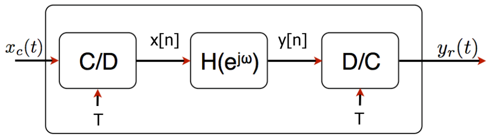
$$x_r(t) = x_s(t) * h_r(t) = \left(\sum_n x[n]\delta(t-nT)\right) * h_r(t) = \sum_n x[n]h_r(t-nT)$$





The sum of "sincs" gives $x_r(t)$ → unique signal that is bandlimited by sampling bandwidth

Discrete-Time Processing of Continuous Time

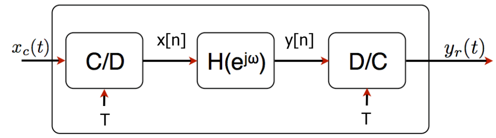


$$X(e^{j\omega}) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c\left[j\left(\frac{\omega}{T} - \frac{2\pi k}{T}\right)\right]$$

Sum of scaled shifted sincs

$$y_r(t) = \sum_{n=-\infty}^{\infty} y[n]\frac{\sin[\pi(t-nT)/T]}{\pi(t-nT)/T}$$

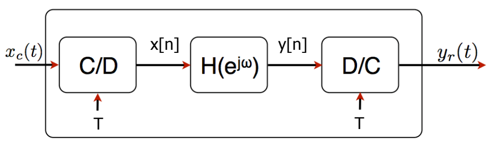
Discrete-Time Processing of Continuous Time



$$X(e^{j\omega}) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c\left[j\left(\frac{\omega}{T} - \frac{2\pi k}{T}\right)\right] \qquad y_r(t) = \sum_{n=-\infty}^{\infty} y[n]\frac{\sin[\pi(t-nT)/T]}{\pi(t-nT)/T}$$

- If h[n] is LTI, $H(e^{j\omega})$ exists
  - Is the whole system from $x_c(t) \rightarrow y_c(t)$ LTI?

Discrete-Time Processing of Continuous Time



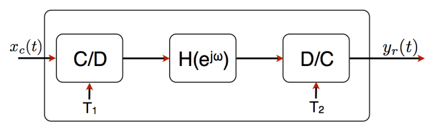
$$X(e^{j\omega}) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c\left[j\left(\frac{\omega}{T} - \frac{2\pi k}{T}\right)\right] \qquad y_r(t) = \sum_{n=-\infty}^{\infty} y[n]\frac{\sin[\pi(t-nT)/T]}{\pi(t-nT)/T}$$

- If $x_c(t)$ is bandlimited by $\Omega_s/T = \pi/T$, then,

$$\frac{Y_r(j\Omega)}{X_c(j\Omega)} = H_{eff}(j\Omega) = \begin{cases} H(e^{j\omega})\big|_{\omega=\Omega T} & |\Omega| < \Omega_s/T \\ 0 & else \end{cases}$$

Example

- Consider the following system



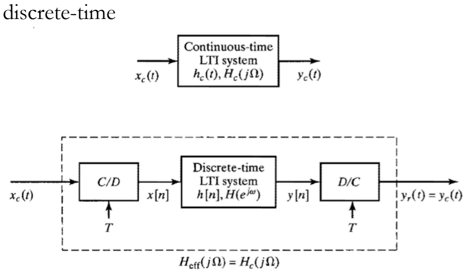
- Where

$$H(e^{j\omega}) = \begin{cases} 1 & |\omega| < \omega_c \\ 0 & \omega_c < |\omega| \le \pi \end{cases}$$

- What is the effective frequency response of the system? What happens to a signal bandlimited by Ω_N?

Impulse Invariance

- Want to implement continuous-time system in discrete-time



Impulse Invariance

- With $H_c(j\Omega)$ bandlimited, choose

$$H(e^{j\omega}) = H_c(j\omega/T), \qquad |\omega| < \pi$$

- With the further requirement that T be chosen such that

$$H_c(j\Omega) = 0, \qquad |\Omega| \ge \pi/T$$

Impulse Invariance

- With $H_c(j\Omega)$ bandlimited, choose

$$H(e^{j\omega}) = H_c(j\omega / T), \qquad |\omega| < \pi$$

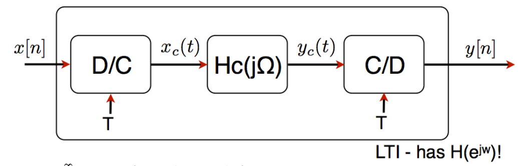
- With the further requirement that T be chosen such that

$$H_c(j\Omega) = 0, \qquad |\Omega| \geq \pi / T$$

$$\boxed{h[n] = T h_c(nT)}$$

Continuous-Time Processing of Discrete-Time

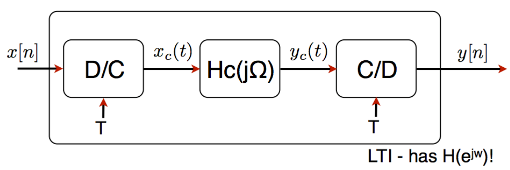
- Useful to interpret DT systems with no simple interpretation in discrete time



$$x_c(t) = \sum_{n=-\infty}^{\infty} x[n] \frac{\sin[\pi(t - nT)/T]}{\pi(t - nT)/T}$$

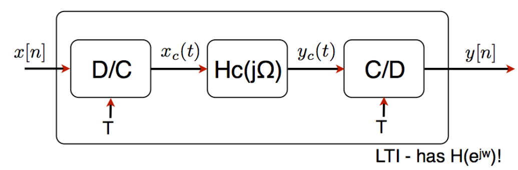
$$y_c(t) = \sum_{n=-\infty}^{\infty} y[n] \frac{\sin[\pi(t - nT)/T]}{\pi(t - nT)/T}$$

Continuous-Time Processing of Discrete-Time



$$X_c(j\Omega) = \begin{cases} TX(e^{j\Omega T}) & |\Omega| < \pi / T \\ 0 & else \end{cases}$$

Continuous-Time Processing of Discrete-Time

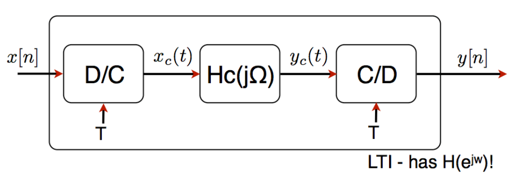


$$X_c(j\Omega) = \begin{cases} TX(e^{j\Omega T}) & |\Omega| < \pi / T \\ 0 & else \end{cases}$$

$$Y_c(j\Omega) = H_c(j\Omega) X_c(j\Omega)$$

Also bandlimited

Continuous-Time Processing of Discrete-Time

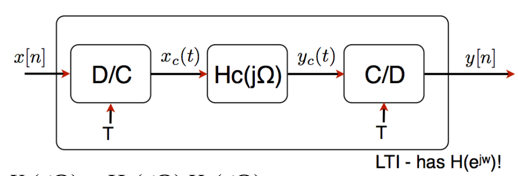


$$Y_c(j\Omega) = H_c(j\Omega) X_c(j\Omega)$$

Also bandlimited

$$Y(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} Y_c\left[j(\Omega - k\Omega_s)\right]\Bigg|_{\Omega=\omega/T} = \frac{1}{T} Y_c(j\Omega)\Bigg|_{\Omega=\omega/T}$$

Continuous-Time Processing of Discrete-Time



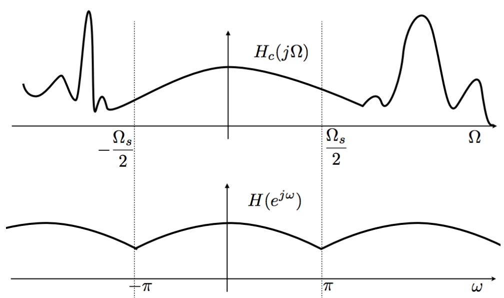
$$Y_c(j\Omega) = H_c(j\Omega) X_c(j\Omega)$$

$$Y(e^{j\omega}) = \frac{1}{T} Y_c(j\Omega)\Bigg|_{\Omega=\omega/T}$$

$$Y(e^{j\omega}) = \frac{1}{T} H_c(j\Omega)\Big|_{\Omega=\omega/T} X_c(j\Omega)\Big|_{\Omega=\omega/T}$$

$$= \frac{1}{T} H_c(j\Omega)\Big|_{\Omega=\omega/T} (TX(e^{j\omega})) = H(e^{j\omega}) X(e^{j\omega}) \qquad |\omega| < \pi$$

Example



Example: Non-integer Delay

- What is the time domain operation when Δ is non-integer? I.e $\Delta = 1/2$

$$H(e^{j\omega}) = e^{-j\omega\Delta}$$

Reminder: Properties of the DTFT

- Time Reversal:

$$x[n] \leftrightarrow X(e^{j\omega})$$
$$x[-n] \leftrightarrow X(e^{-j\omega})$$

If x[n] real

$$x[-n] \leftrightarrow X^*(e^{-j\omega})$$

- Time/Freq Shifting:

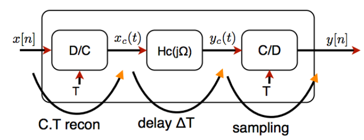
$$x[n] \leftrightarrow X(e^{j\omega})$$
$$x[n-n_d] \leftrightarrow e^{-j\omega n_d} X(e^{j\omega})$$
$$e^{j\omega_0 n} x[n] \leftrightarrow X(e^{j(\omega-\omega_0)})$$

Example: Non-integer Delay

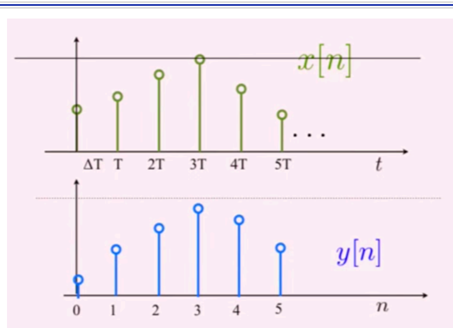
- What is the time domain operation when Δ is non-integer? I.e $\Delta = 1/2$

$$H(e^{j\omega}) = e^{-j\omega\Delta}$$

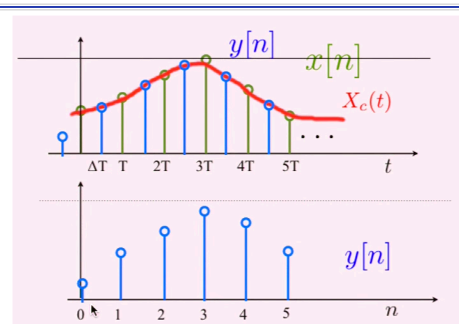
Let: $H_c(j\Omega) = e^{-j\Omega\Delta T}$ delay of ΔT in time



Example: Non-integer Delay

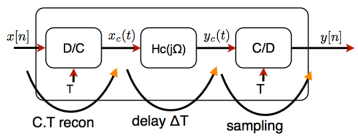


Example: Non-integer Delay



Example: Non-integer Delay

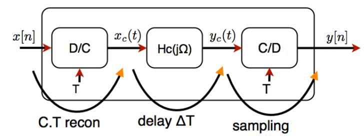
- The block diagram is for interpretation/analysis only



$$y_c(t) = x_c(t - T\Delta)$$

Example: Non-integer Delay

- The block diagram is for interpretation/analysis only



$$y_c(t) = x_c(t - T\Delta)$$

$$\begin{aligned} y[n] &= y_c(nT) = x_c(nt - T\Delta) \\ &= \sum_k x[k]\,\text{sinc}\left(\frac{t - kT - T\Delta}{T}\right)\Bigg|_{t=nT} \\ &= \sum_k x[k]\,\text{sinc}\left(n - k - \Delta\right) \end{aligned}$$

Example: Non-integer Delay

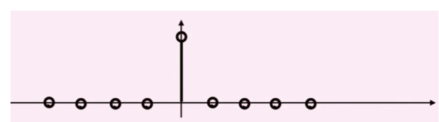
- My delay system has an impulse response of a sinc with a continuous time delay

$$h[n] = \text{sinc}(n - \Delta)$$

Example: Non-integer Delay

- My delay system has an impulse response of a sinc with a continuous time delay

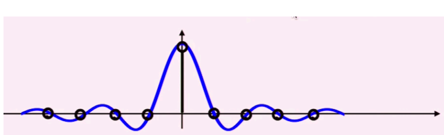
$$h[n] = \text{sinc}(n - \Delta)$$



Example: Non-integer Delay

- My delay system has an impulse response of a sinc with a continuous time delay

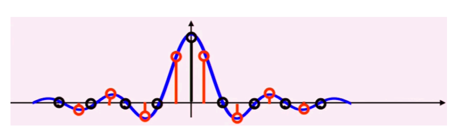
$$h[n] = \text{sinc}(n - \Delta)$$



Example: Non-integer Delay

- My delay system has an impulse response of a sinc with a continuous time delay

$$h[n] = \text{sinc}(n - \Delta)$$



Big Ideas

- Sampling and reconstruction
  - Rely on bandlimitedness for unique reconstruction
- CT processing of DT
  - Effectively LTI if no aliasing
- DT processing of CT
  - Always LTI
  - Useful for interpretation

- Changing the sampling rates next time
  - Upsampling, downsampling

Admin

- HW 2 due Friday
- Ahead of schedule
  - Watch course calendar online for changes