# ESE 531: Digital Signal Processing

Lec 10: February 18, 2020

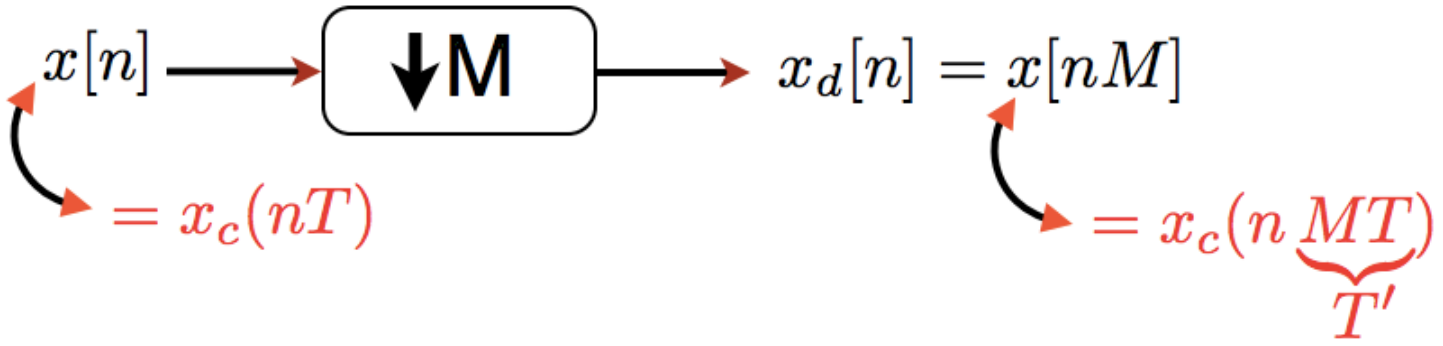
Non-Integer and Multi-rate Sampling

# Lecture Outline

- Review: Downsampling/Upsampling
- Interpolation
- Non-integer Resampling
- Multi-Rate Processing
  - Interchanging Operations

# Downsampling

- Definition: Reducing the sampling rate by an integer number



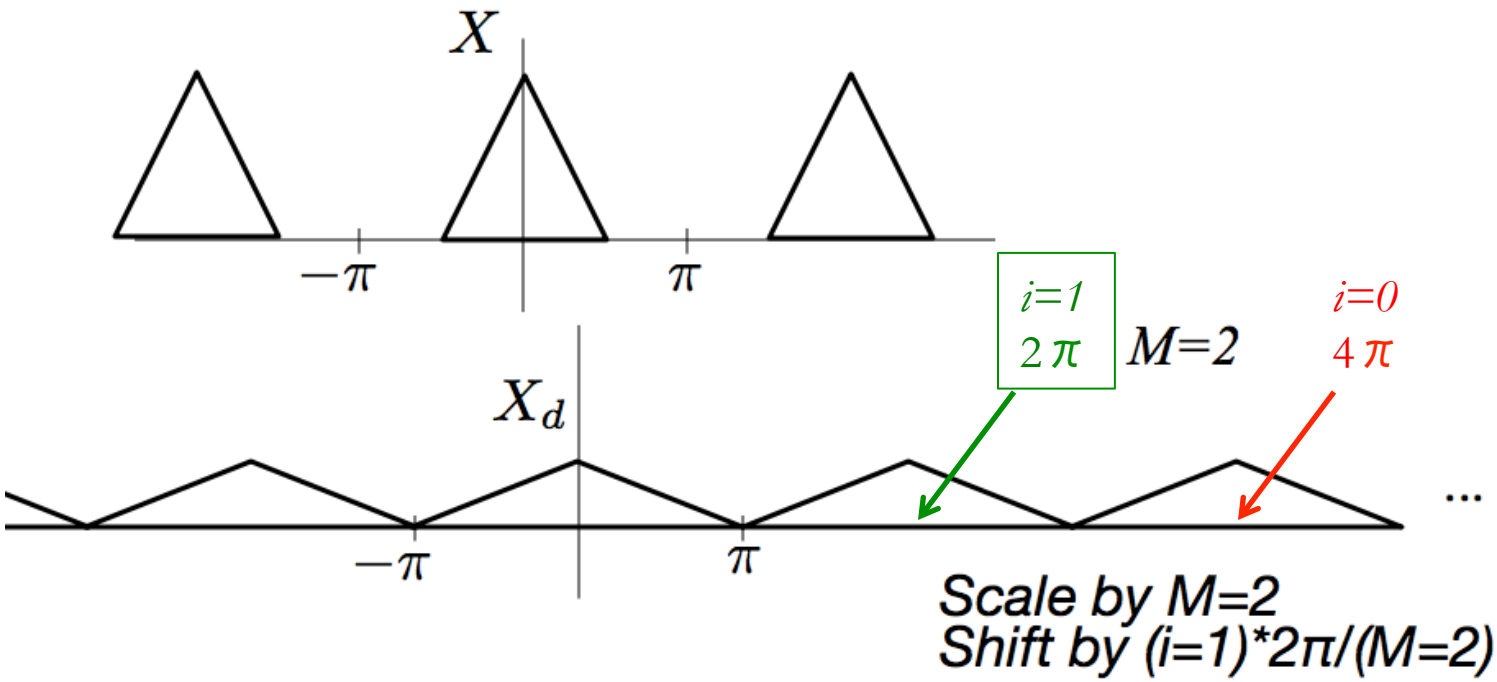

$$X_d(e^{j\omega}) = \frac{1}{M}\sum_{i=0}^{M-1} X(e^{j(\frac{\omega}{M} - \frac{2\pi}{M}i)})$$

stretch by M

replicate

# Example

$$X_d(e^{j\omega}) = \frac{1}{M}\sum_{i=0}^{M-1} X\left(e^{j(\frac{w}{M} - \frac{2\pi}{M}i)}\right)$$



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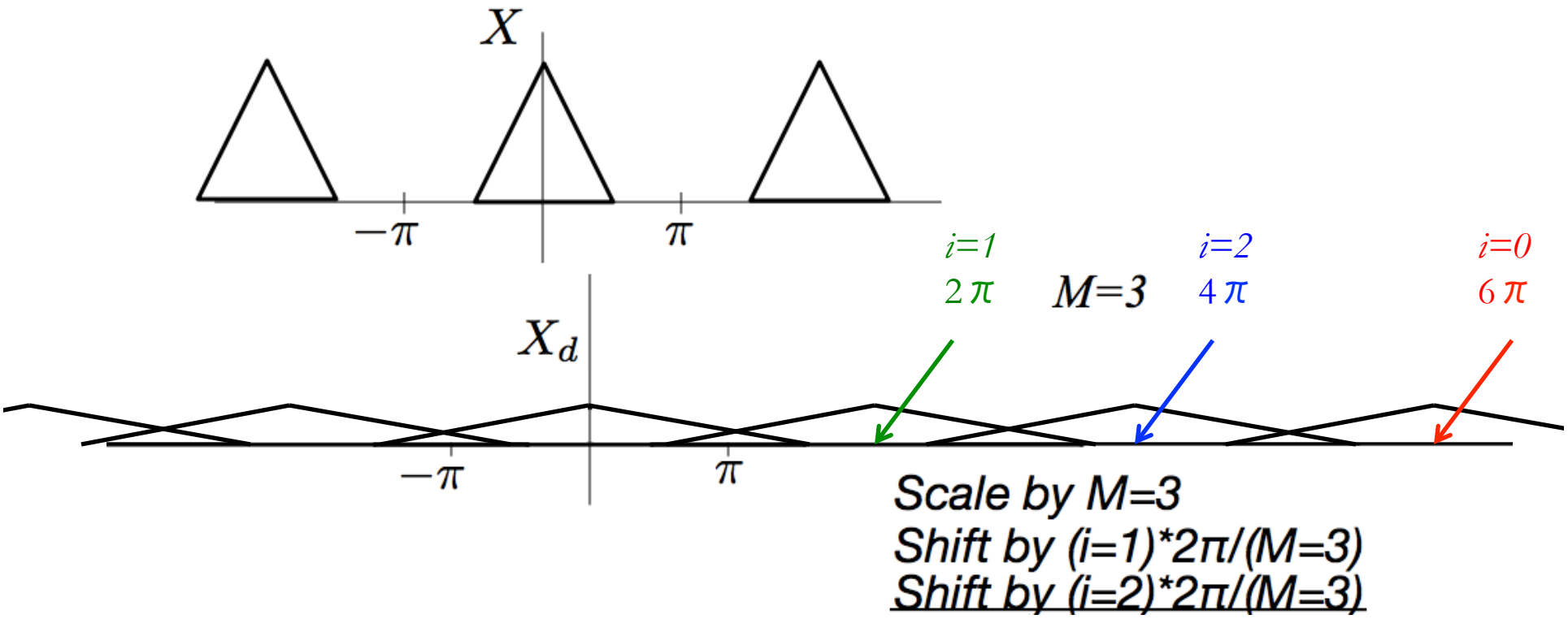
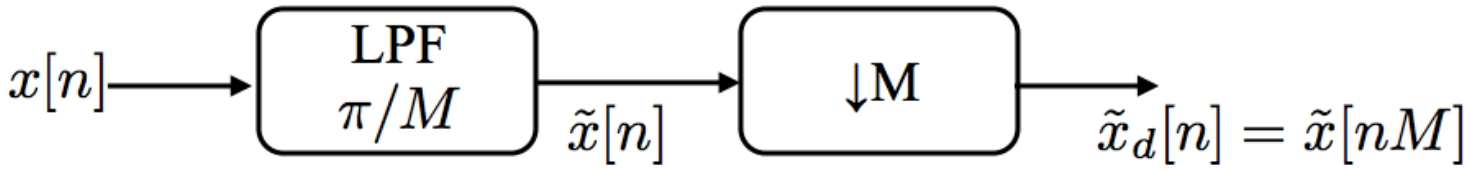
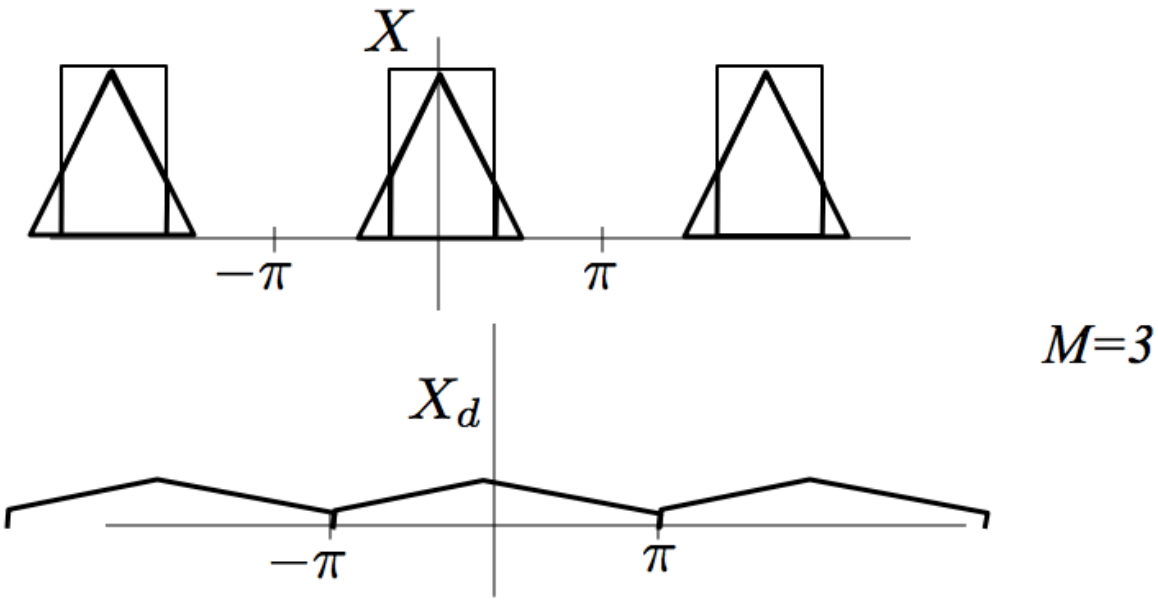


# Example




*M=3*

# Upsampling

- Definition: Increasing the sampling rate by an integer number

$$x[n] = x_c(nT)$$

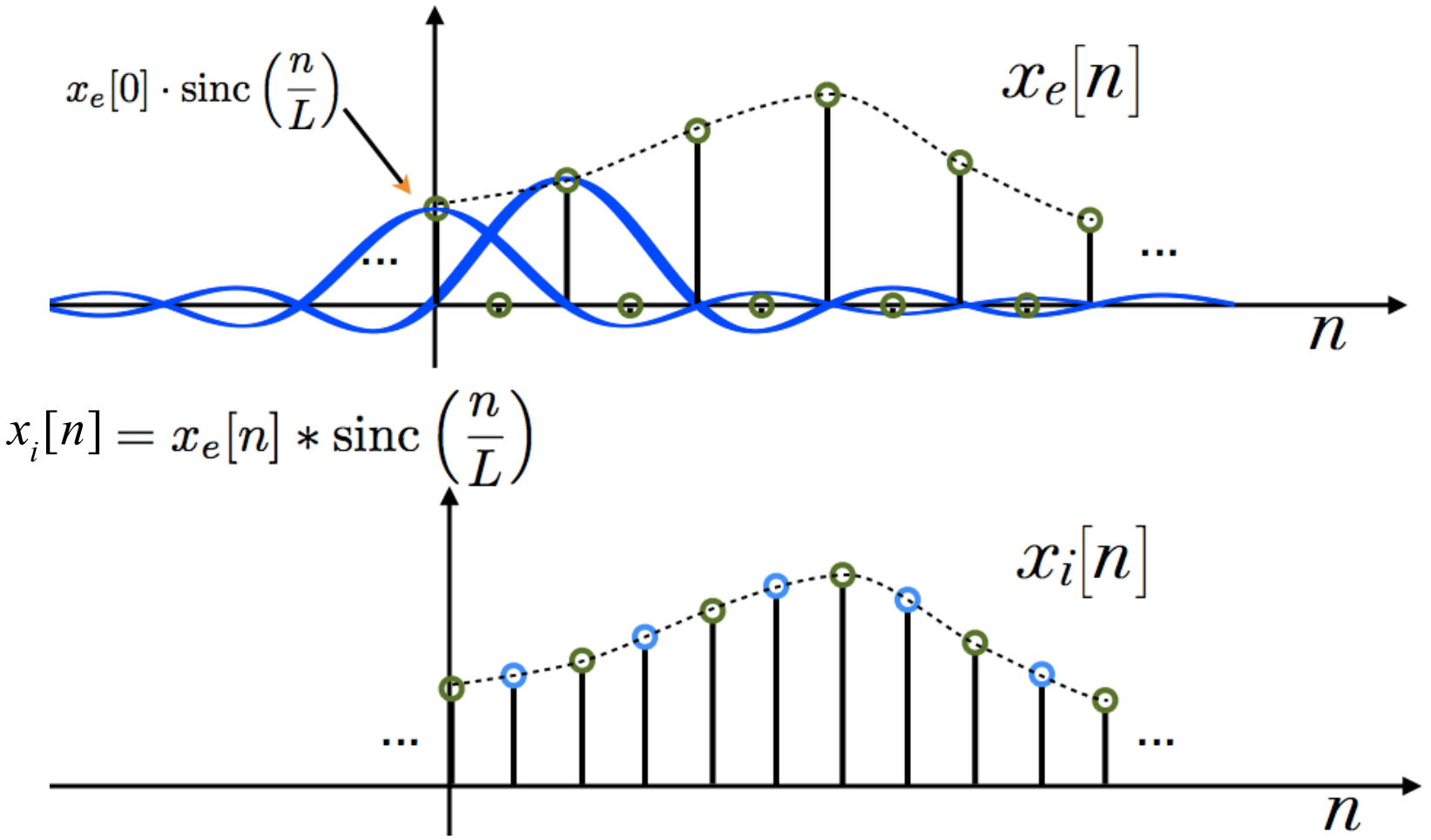
$$x_i[n] = x_c(nT') \quad \text{where } T' = \frac{T}{L} \qquad L \text{ integer}$$

Obtain $x_i[n]$ from $x[n]$ in two steps:

(1) Generate: $x_e[n] = \begin{cases} x[n/L] & n = 0, \ \pm L, \ \pm 2L, \cdots \\ 0 & \text{otherwise} \end{cases}$

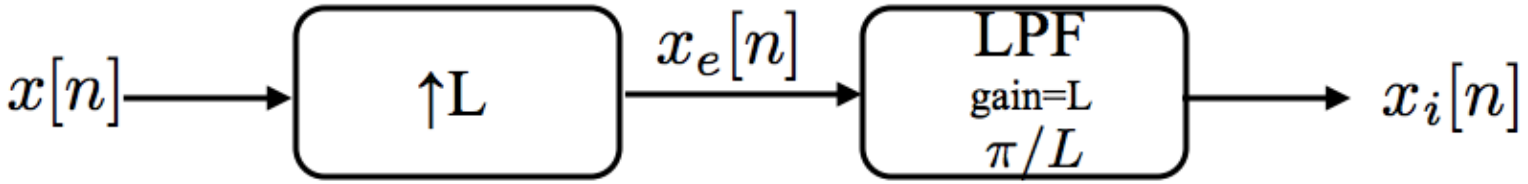
# Upsampling

(2) Obtain $x_i[n]$ from $x_e[n]$ by bandlimited interpolation:

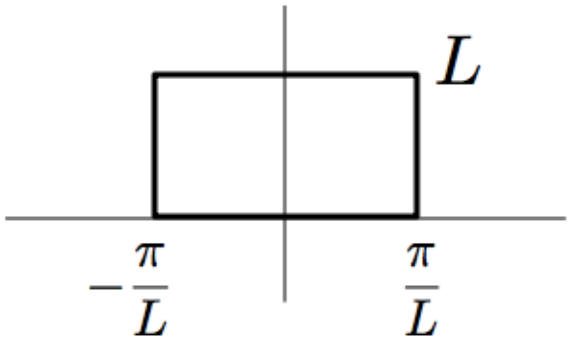


# Frequency Domain Interpretation

$$x_i[n] = x_e[n] * \text{sinc}(n/L)$$




$\text{sinc}(n/L)$ DTFT $\Rightarrow$



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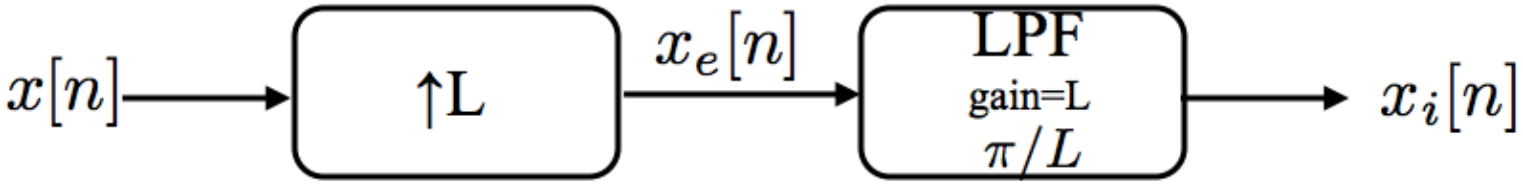


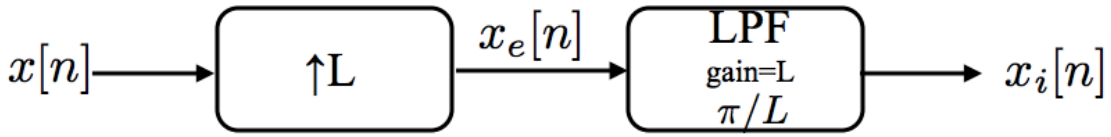

$$X_e(e^{j\omega}) = \sum_{n=-\infty}^{\infty} \underbrace{x_e[n]}\, e^{-j\omega n}$$

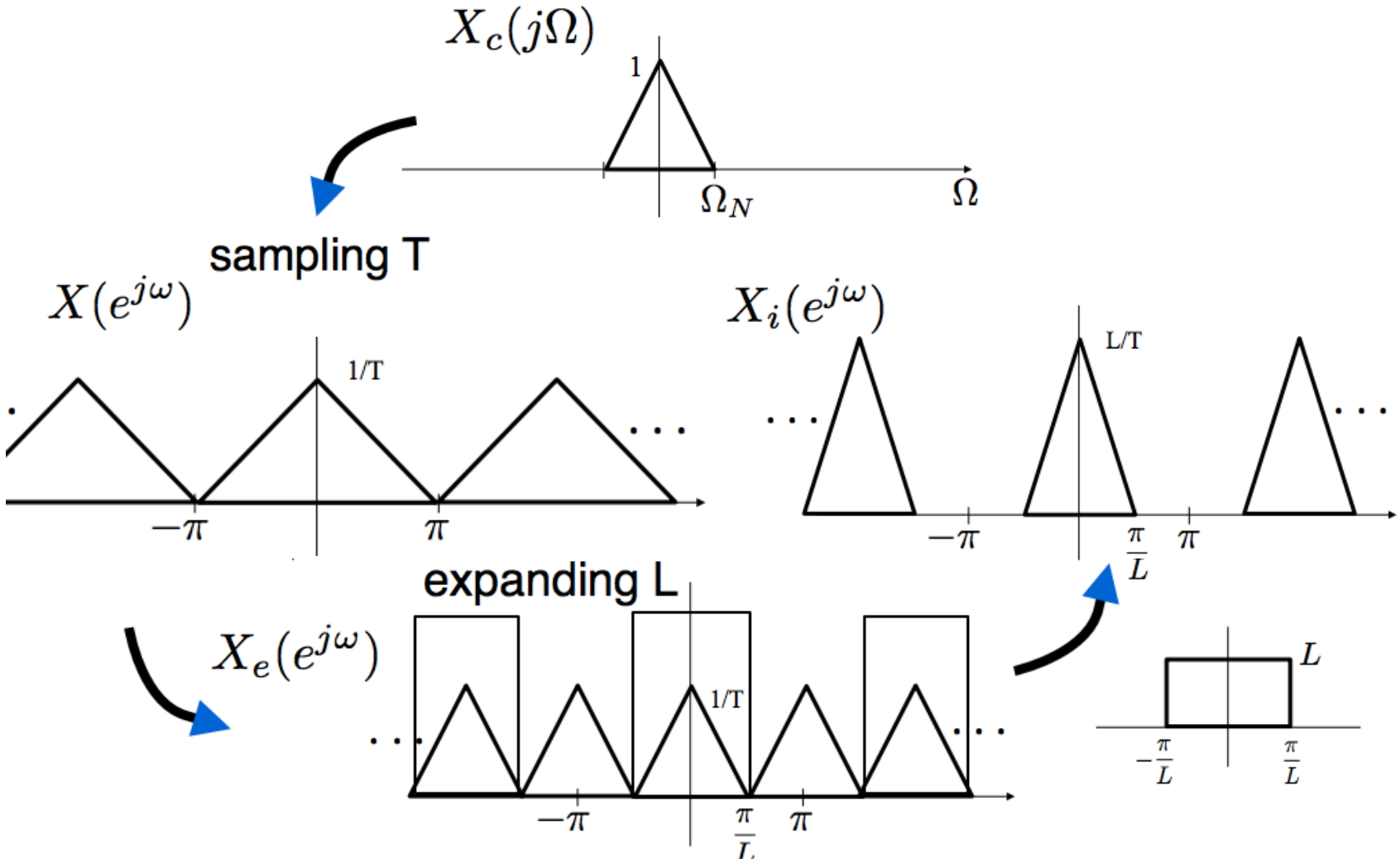
≠ 0 only for n=mL (integer m)

$$= \sum_{m=-\infty}^{\infty} \underbrace{x_e[mL]}_{=x[m]}\, e^{-j\omega mL} = X(e^{j\omega L})$$

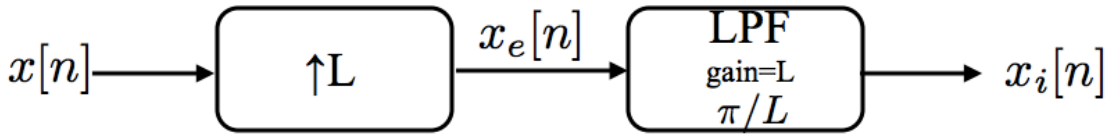
Compress DTFT by a factor of L!

# Example


$x[n]$
↑L
$x_e[n]$
LPF
gain=L
$\pi/L$
$x_i[n]$


$X_c(j\Omega)$
1
$\Omega_N$
$\Omega$
sampling T
$X(e^{j\omega})$
1/T
$-\pi$
$\pi$
$X_i(e^{j\omega})$
L/T
$-\pi$
$\frac{\pi}{L}$
$\pi$
expanding L
$X_e(e^{j\omega})$
1/T
$-\pi$
$\frac{\pi}{L}$
$\pi$
$L$
$-\frac{\pi}{L}$
$\frac{\pi}{L}$

# Example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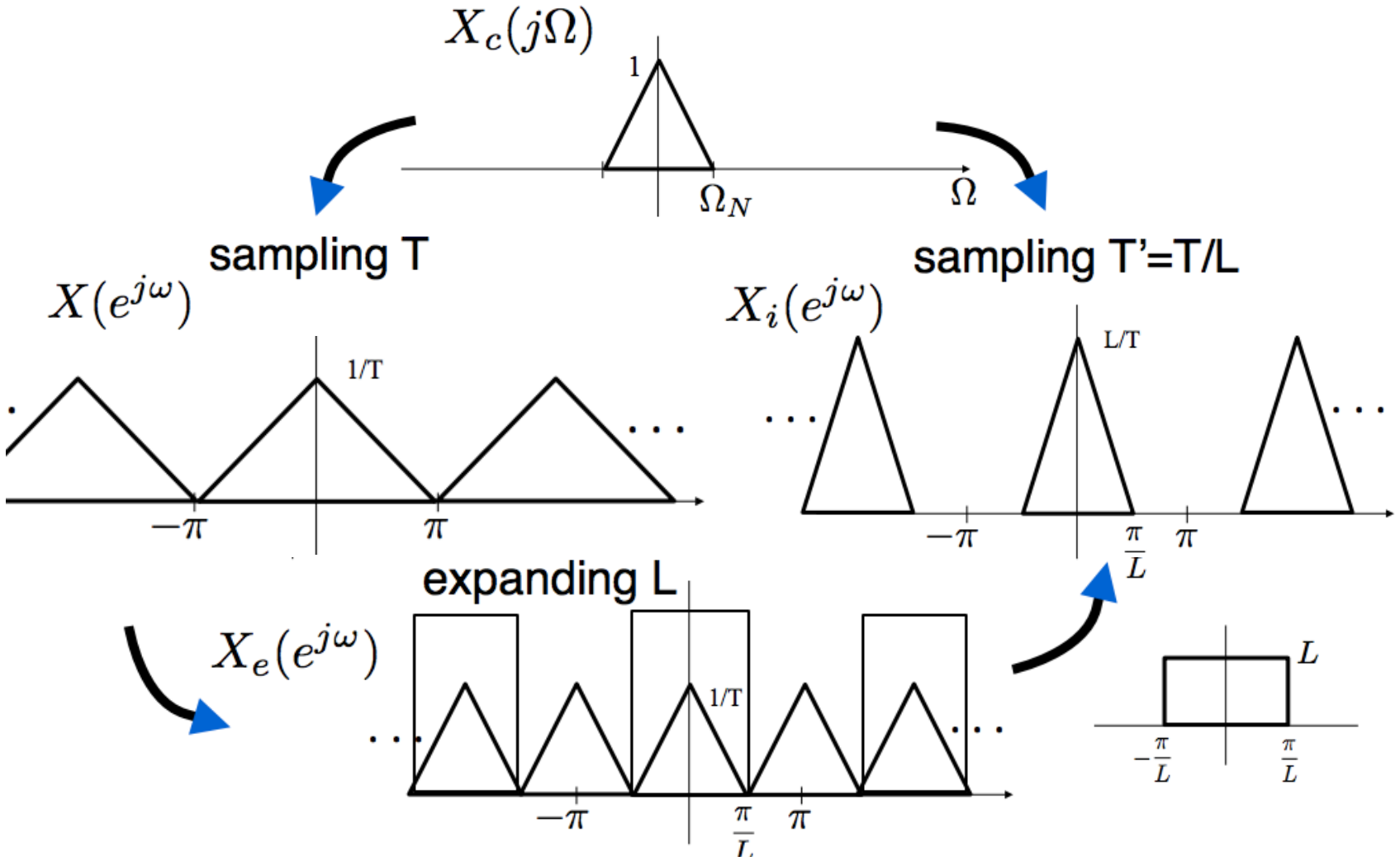
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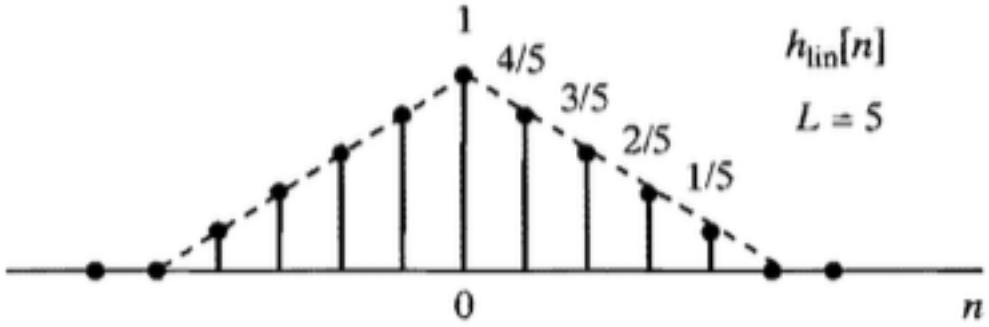
$\pi$
$L$
$-\frac{\pi}{L}$
$\frac{\pi}{L}$

# Practical Interpolation

- Interpolate with simple, practical filters
  - Linear interpolation – samples between original samples fall on a straight line connecting the samples
    - Convolve with triangle instead of sinc

$$h_{\text{lin}}[n] = \begin{cases} 1 - |n|/L, & |n| \le L, \\ 0, & \text{otherwise}, \end{cases}$$



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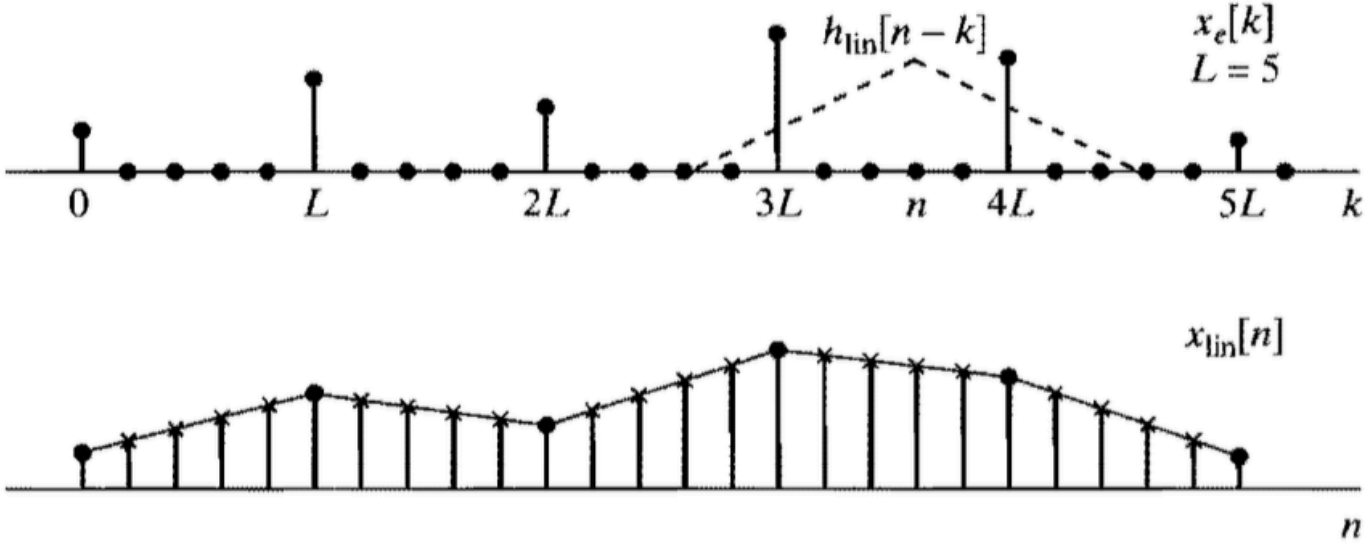

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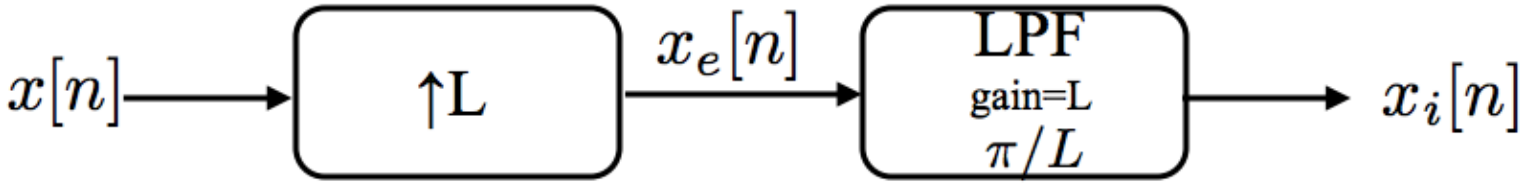


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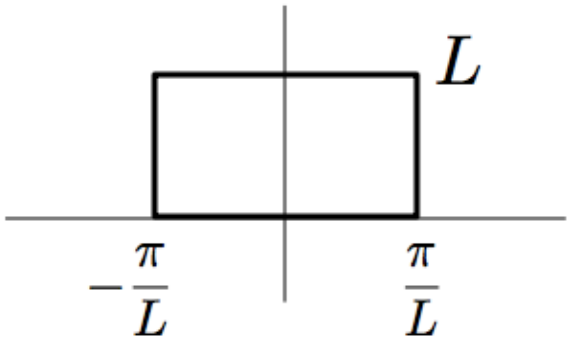
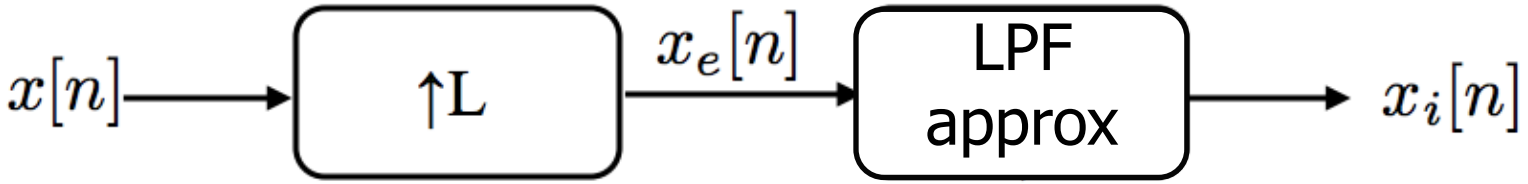


# Linear Interpolation -- Frequency Domain

$$x_i[n] = x_e[n] * h_{lin}[n]$$

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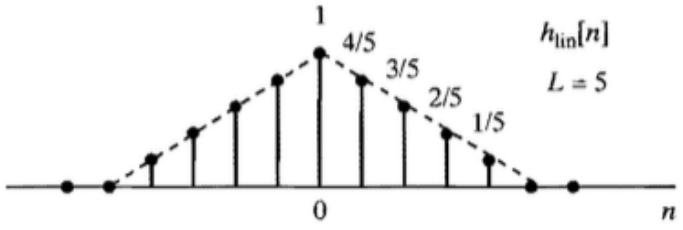

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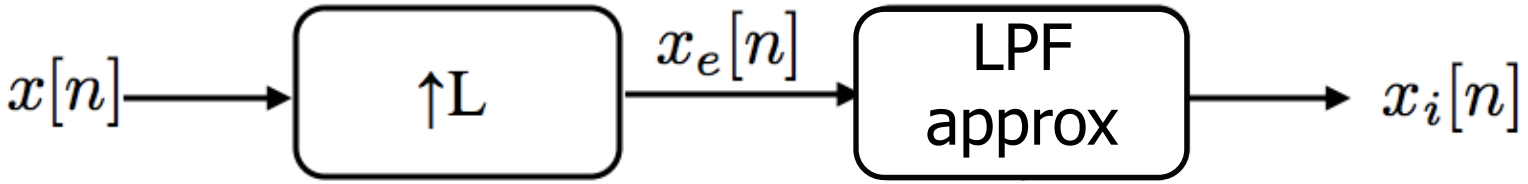


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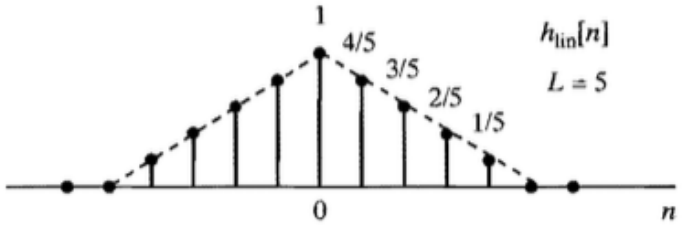
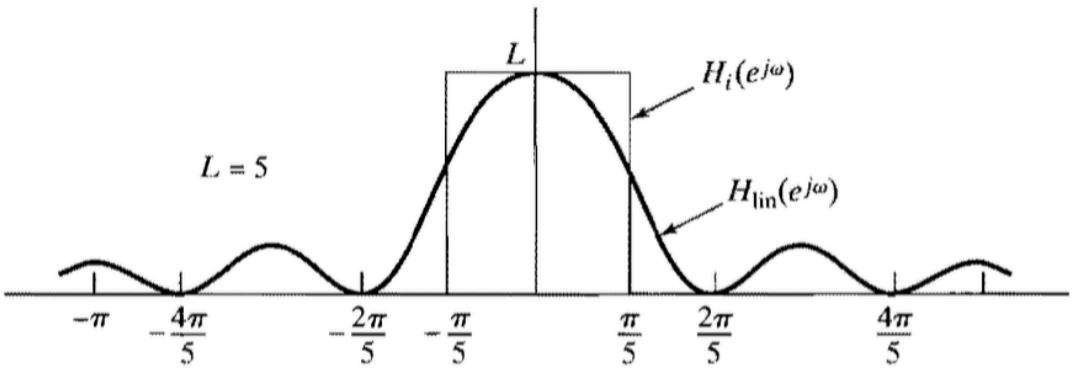



DTFT ⇒



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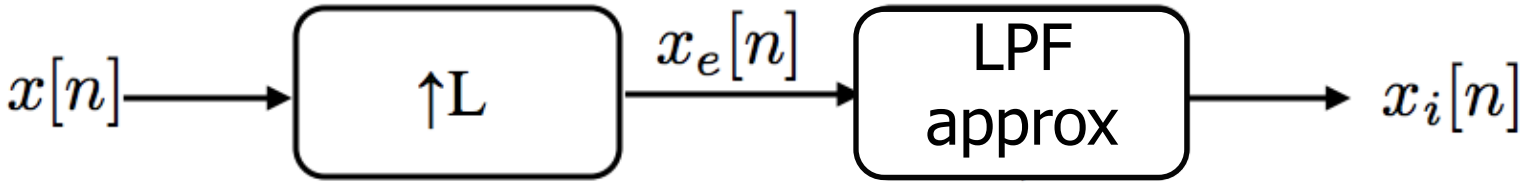


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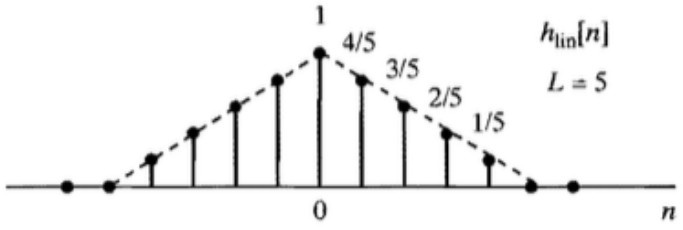


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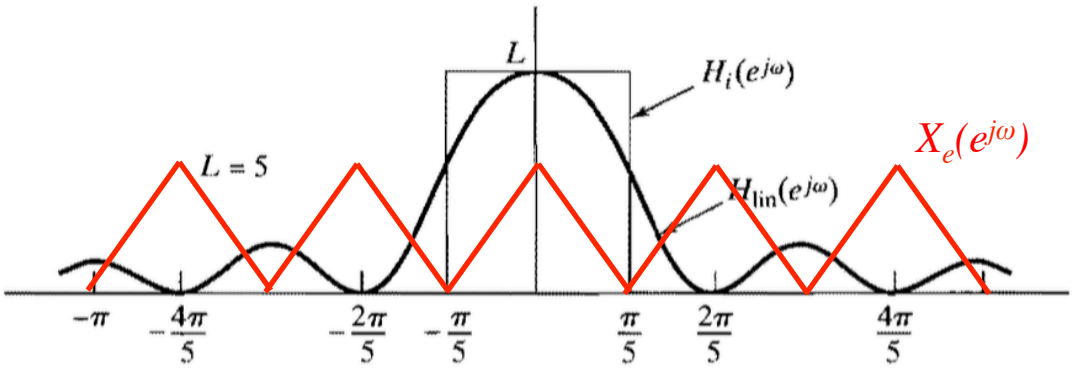

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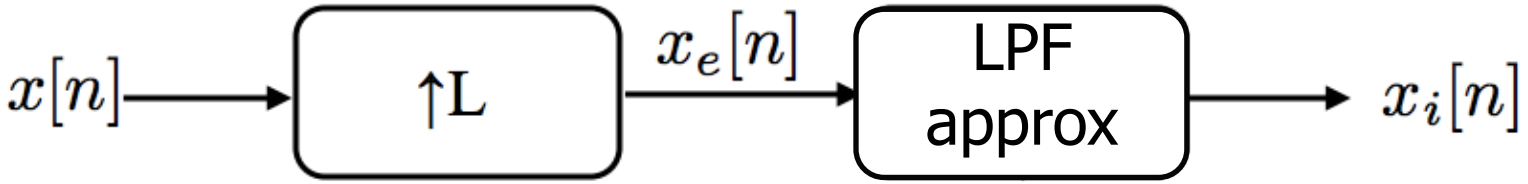


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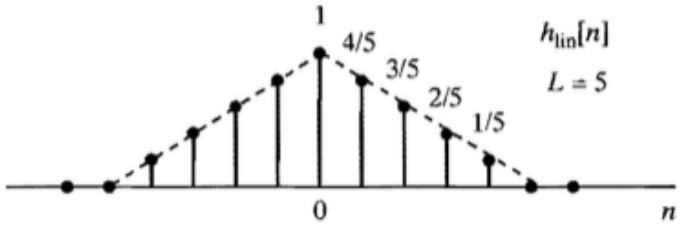


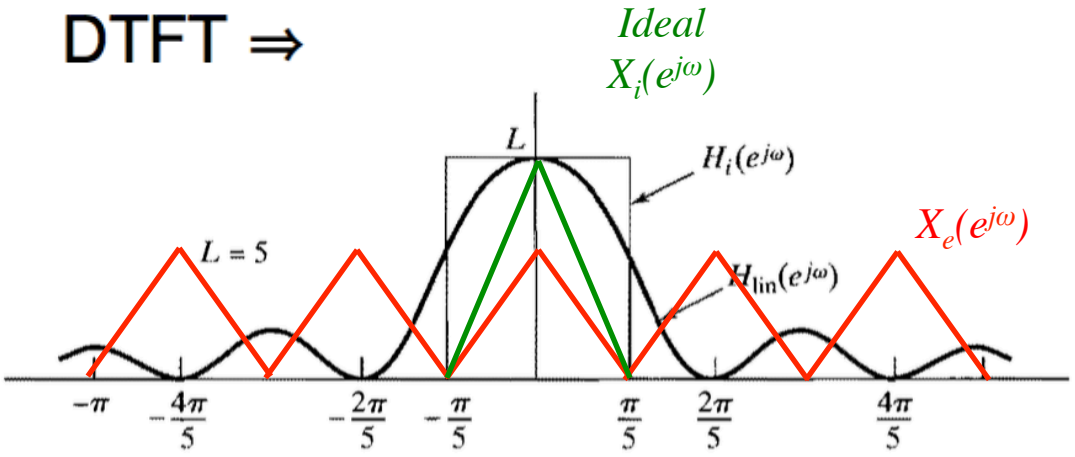

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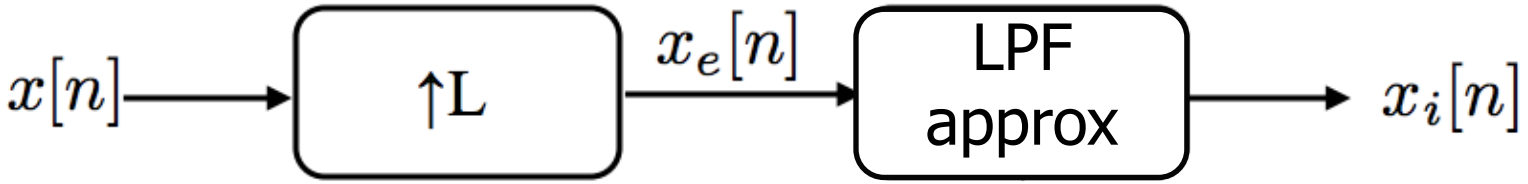


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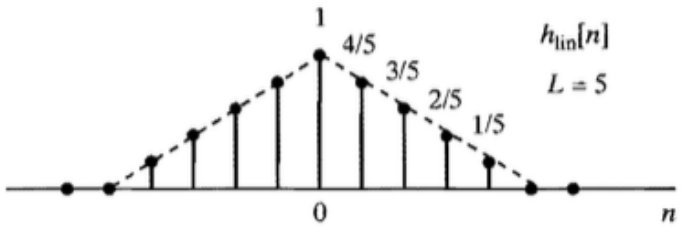
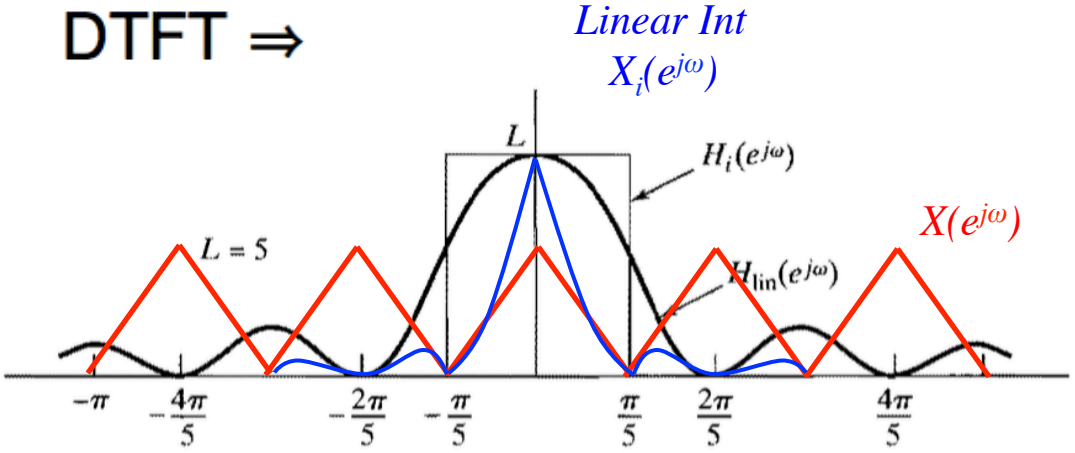



DTFT ⇒



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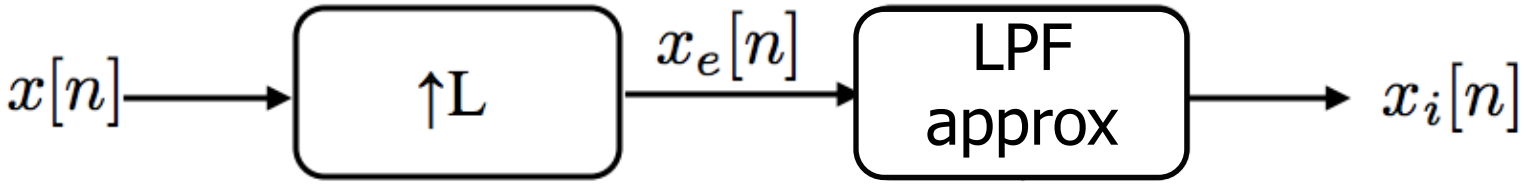


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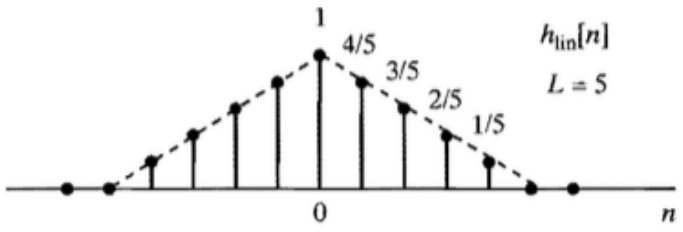
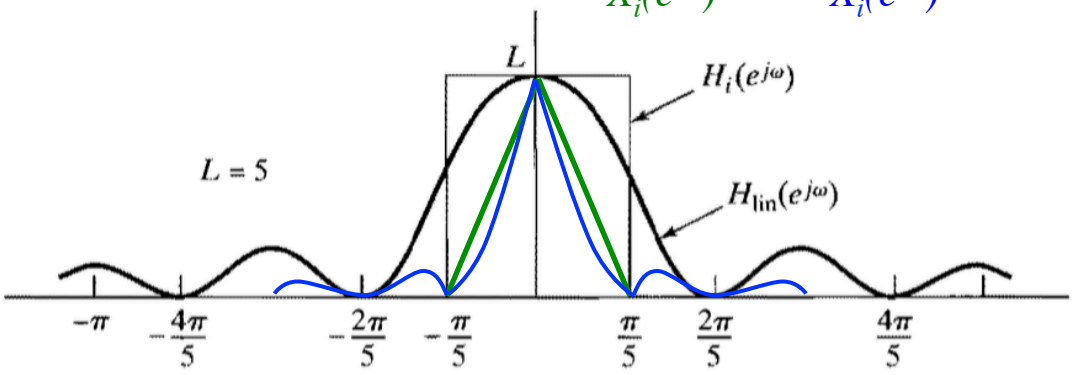


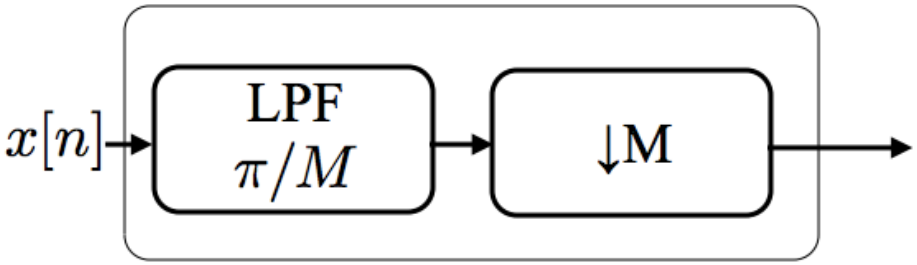

DTFT ⇒

*Ideal* $X_i(e^{j\omega})$ *Linear Int* $X_i(e^{j\omega})$

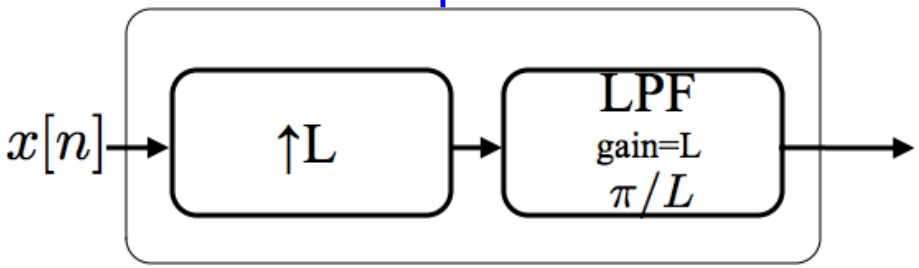


# Interpolation and Decimation

decimator

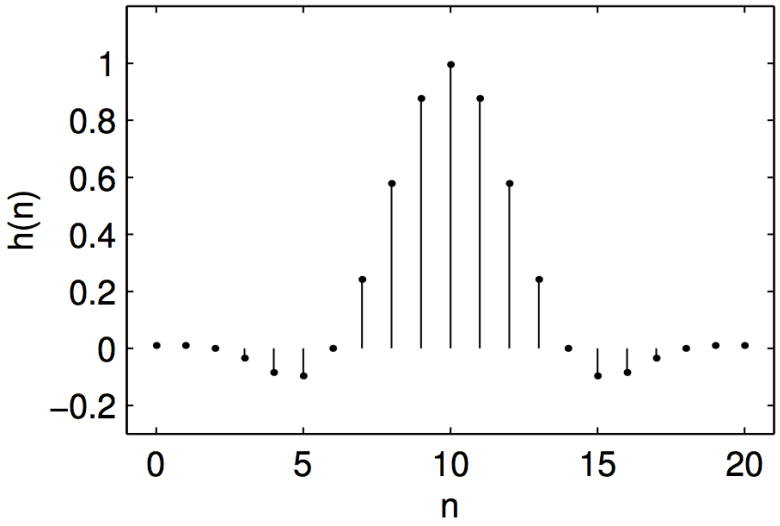


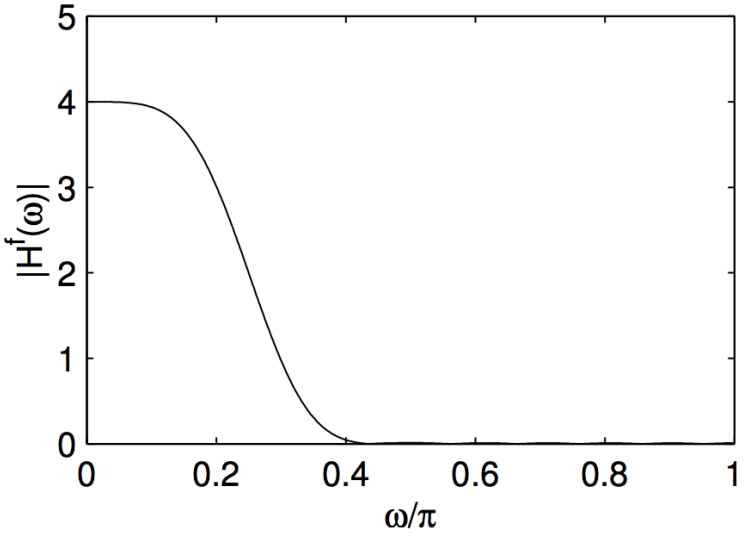

interpolator



# Interpolation Filter Example 1

- In this example, we interpolate a signal x(n) by a factor of 4.
- We use a linear phase Type I FIR lowpass filter of length 21.



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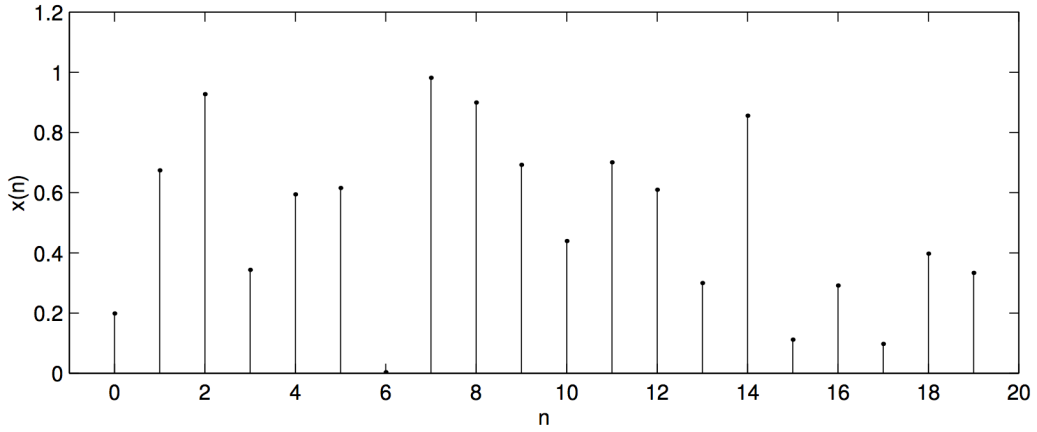

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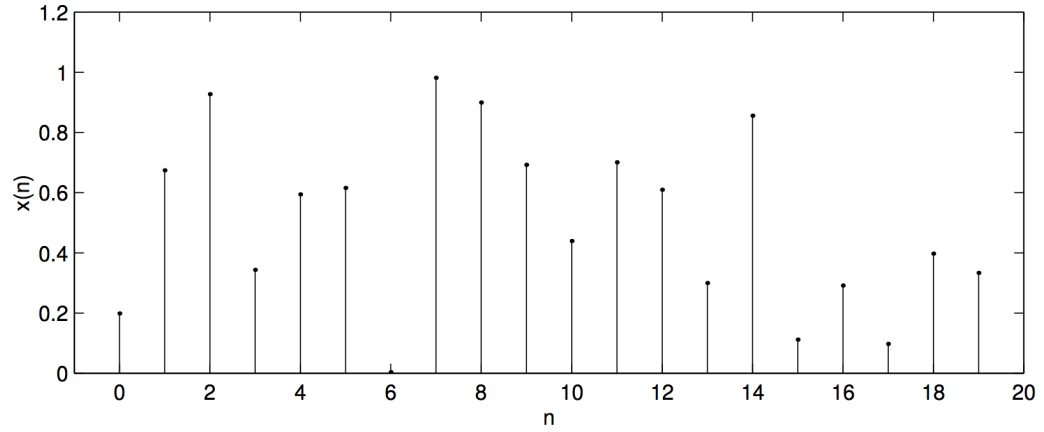


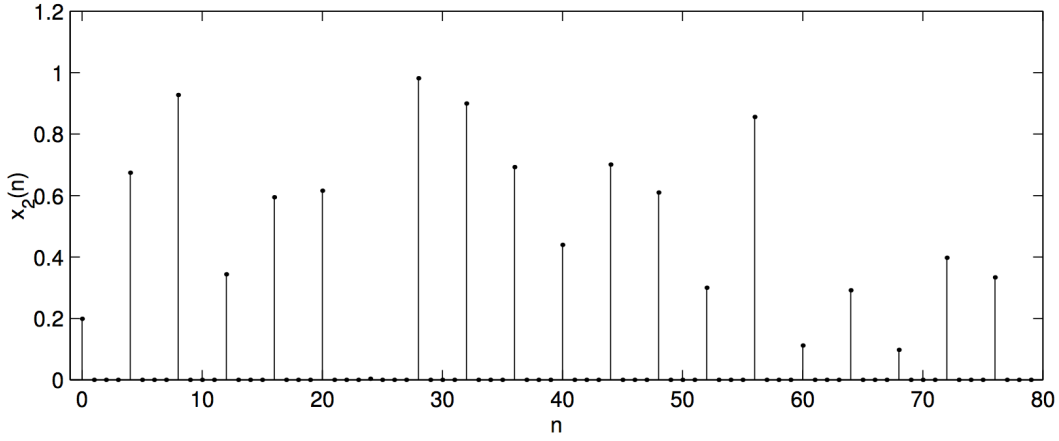

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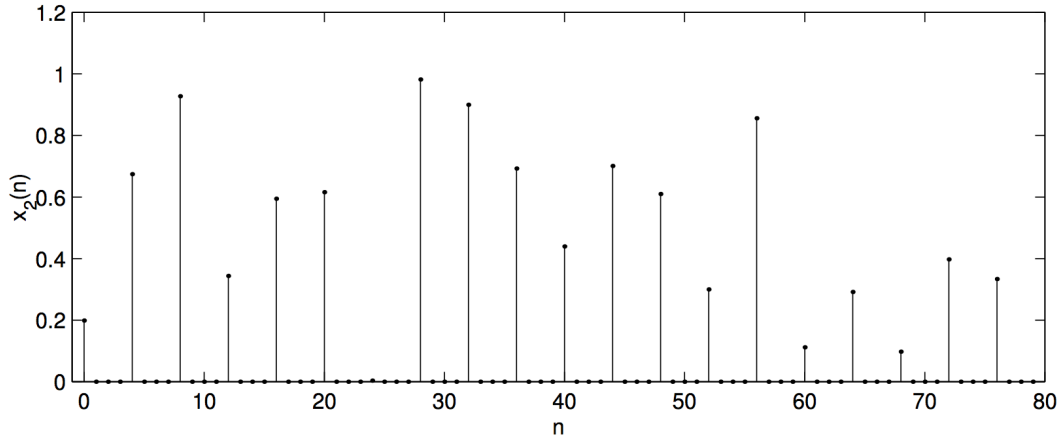
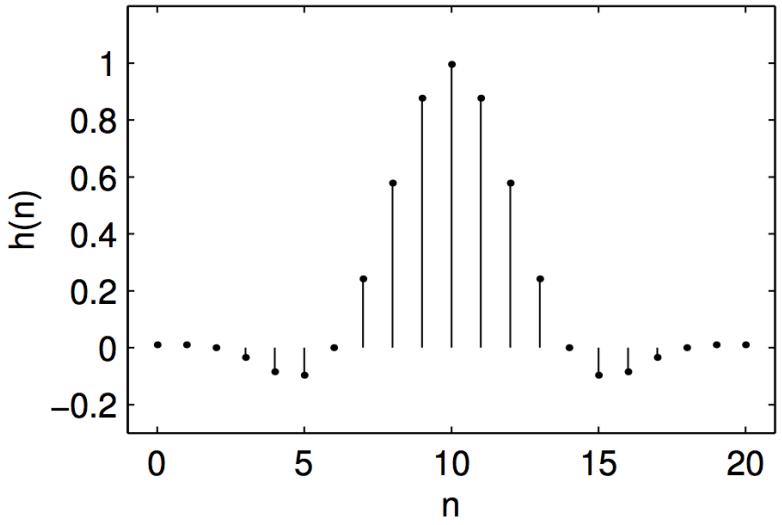
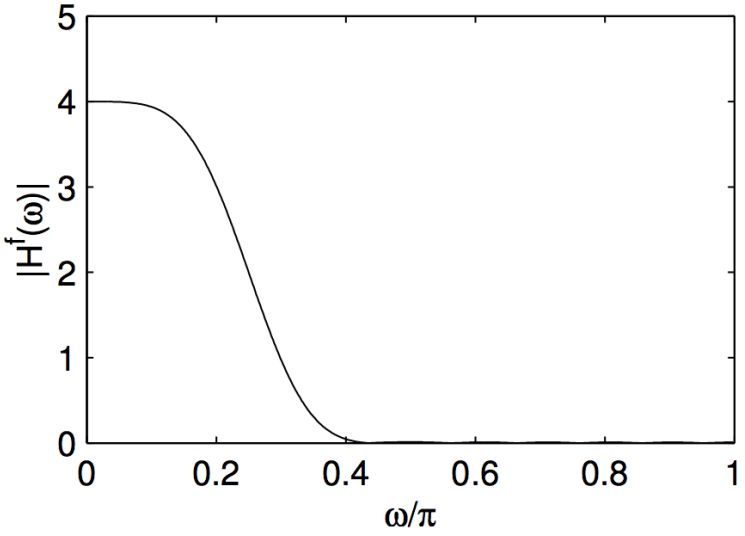



$*$

(convolve)



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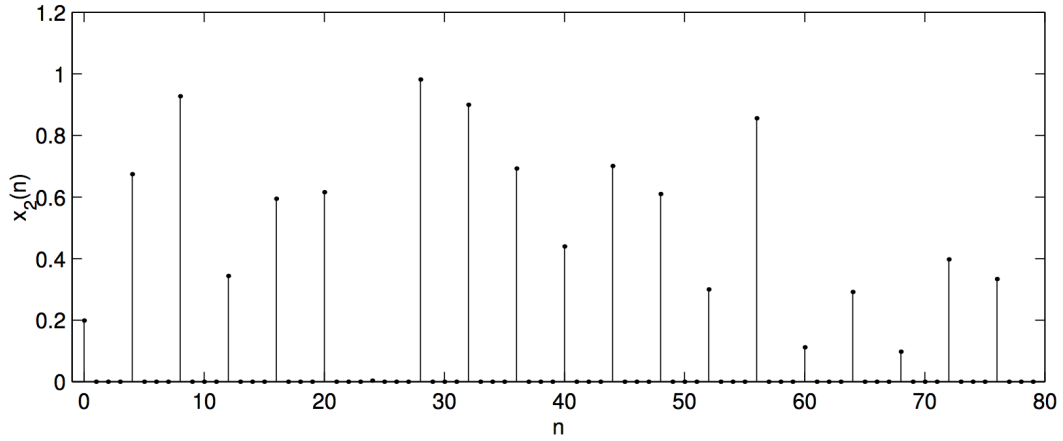


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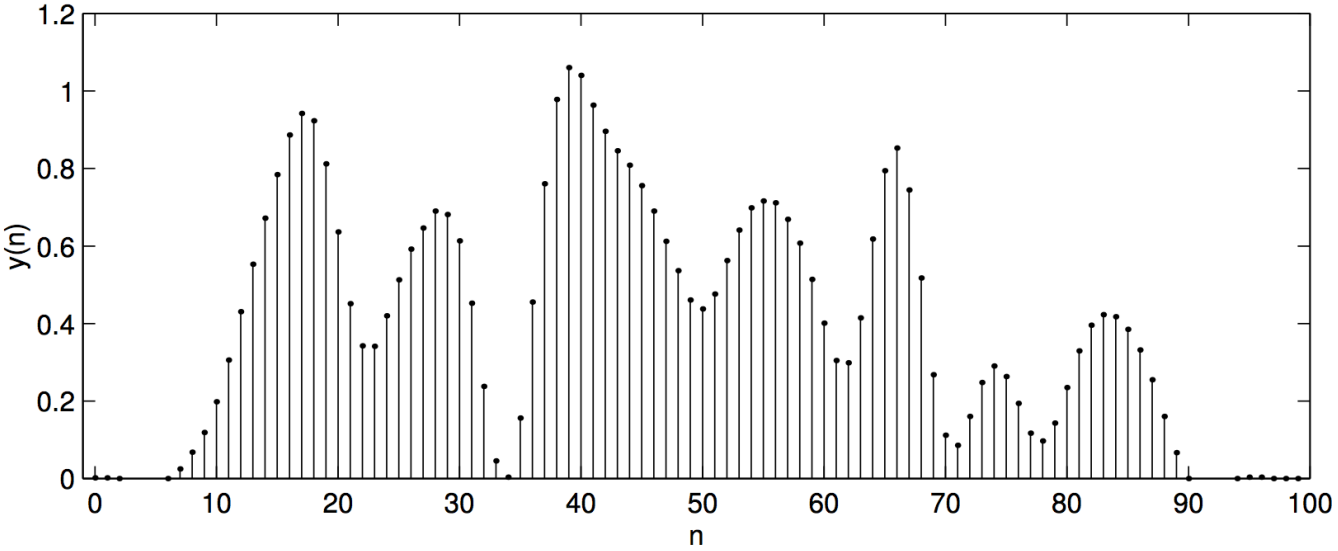
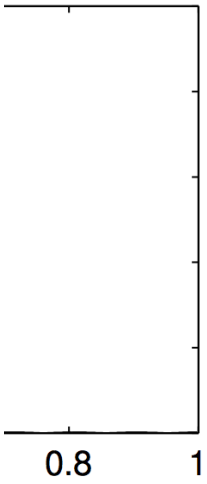
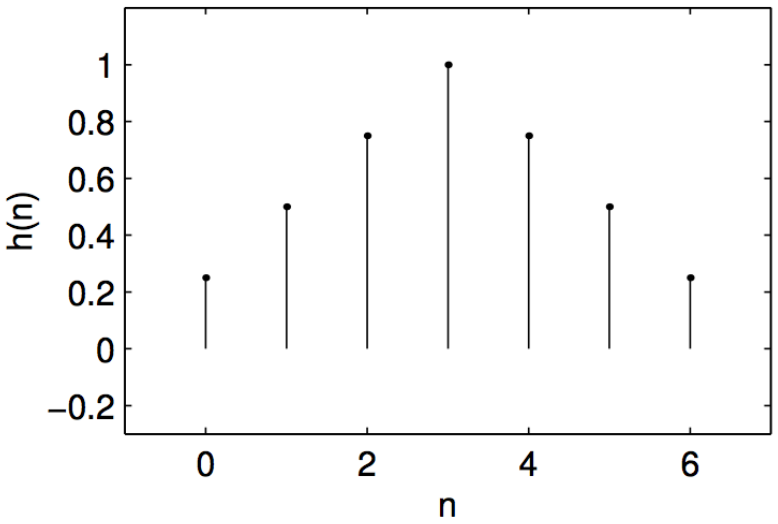
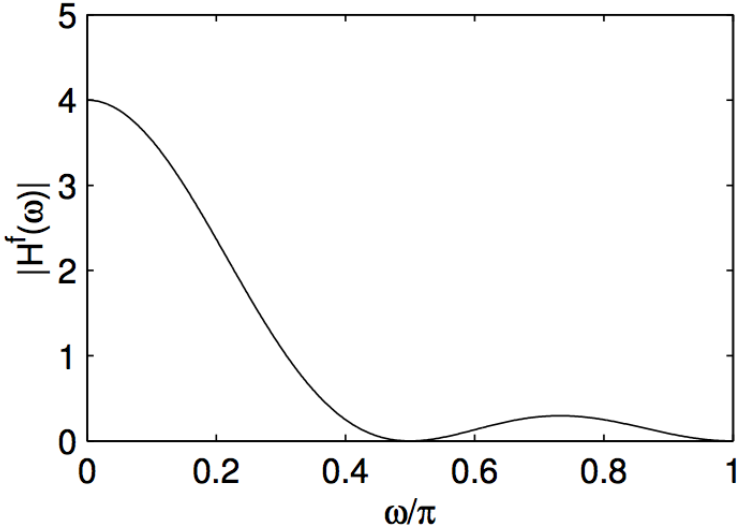


# Interpolation Filter Example 2

- This time we use a filter of length 7 with the effect of linear interpolation



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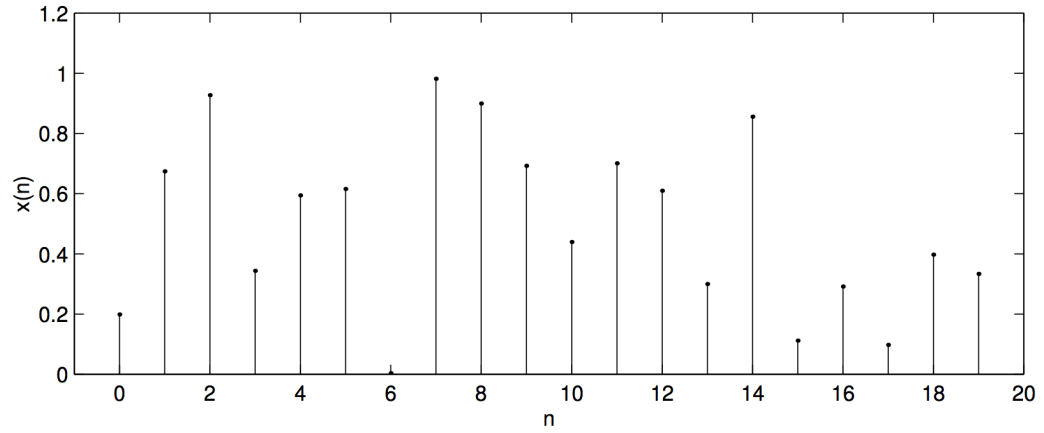


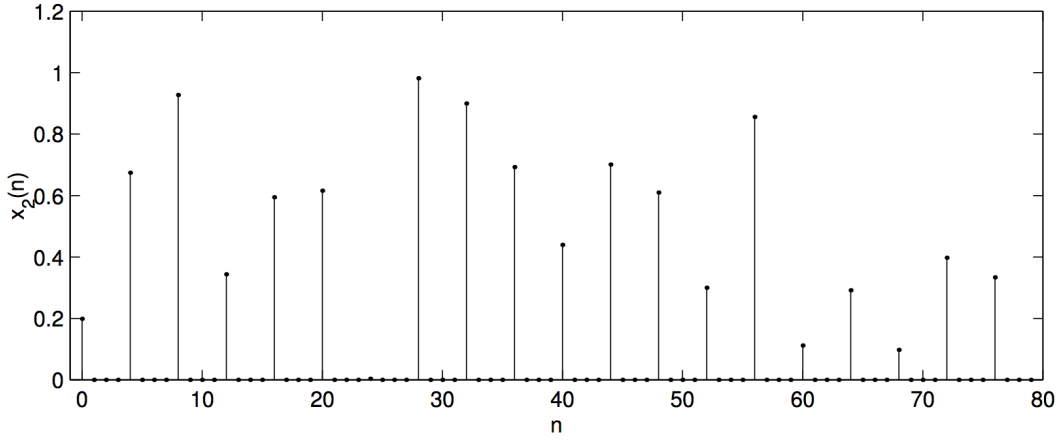

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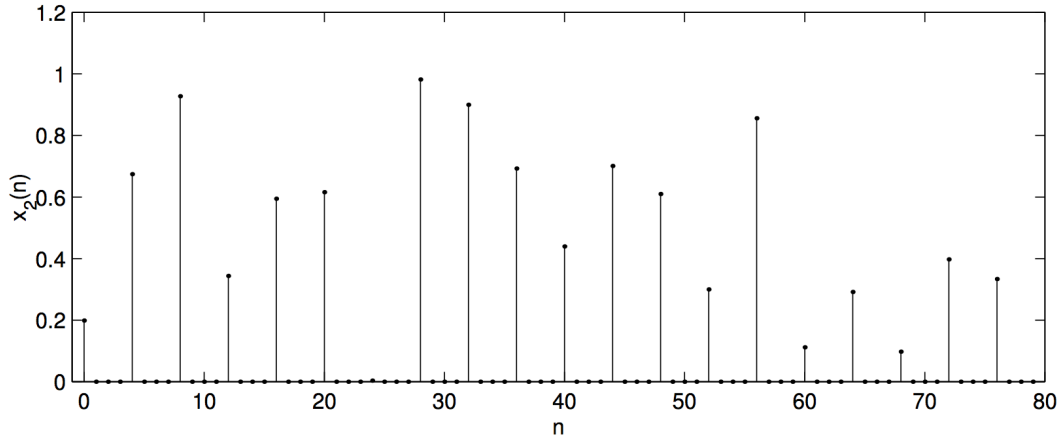
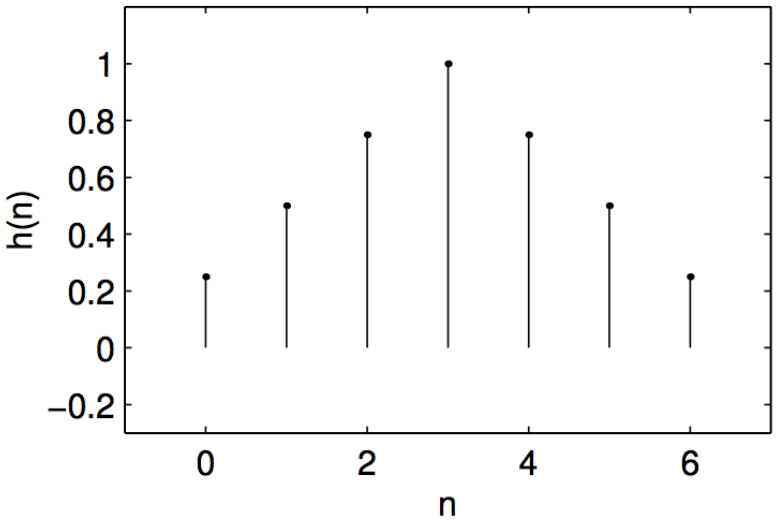
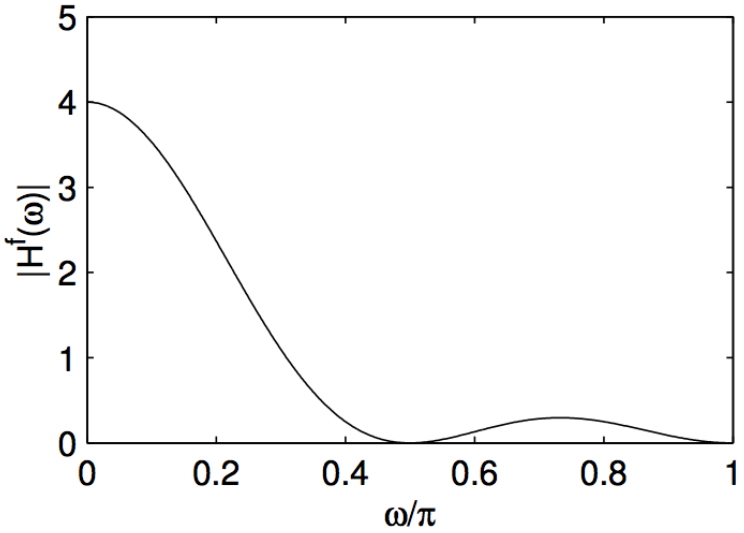



$*$

(convolve)



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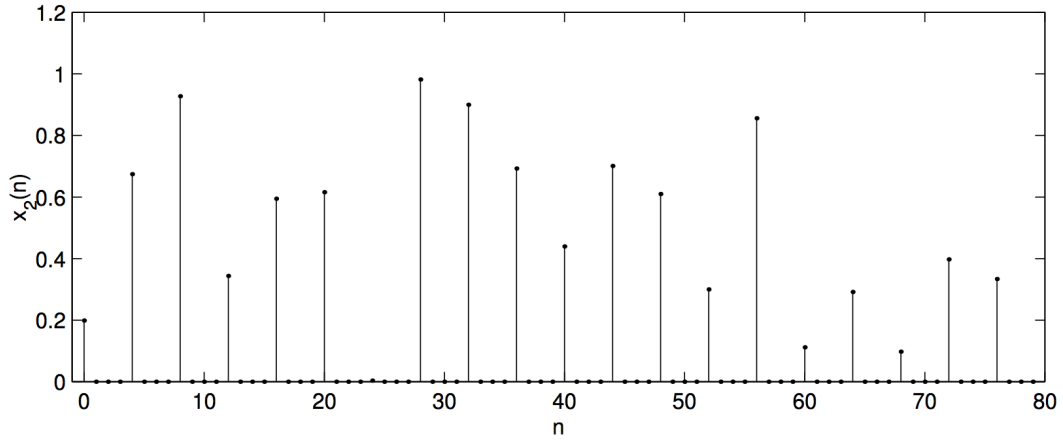


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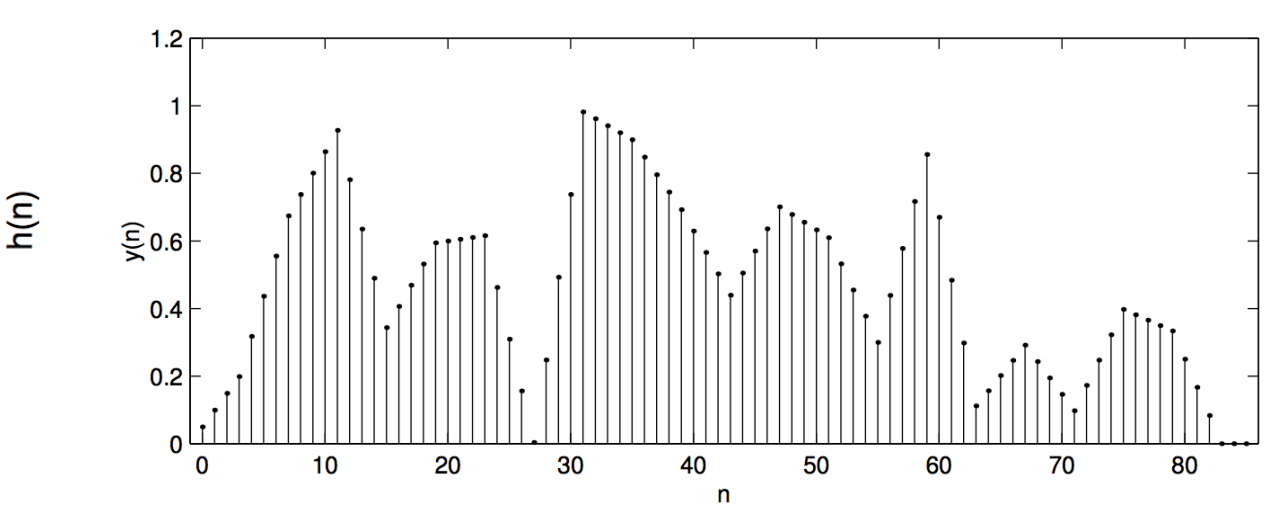


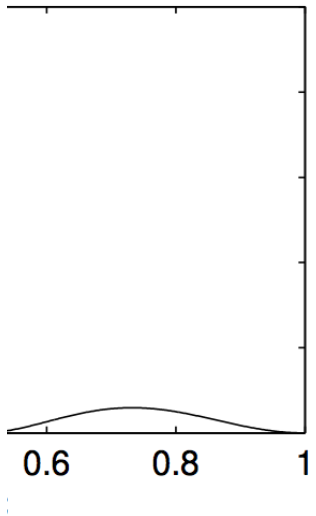

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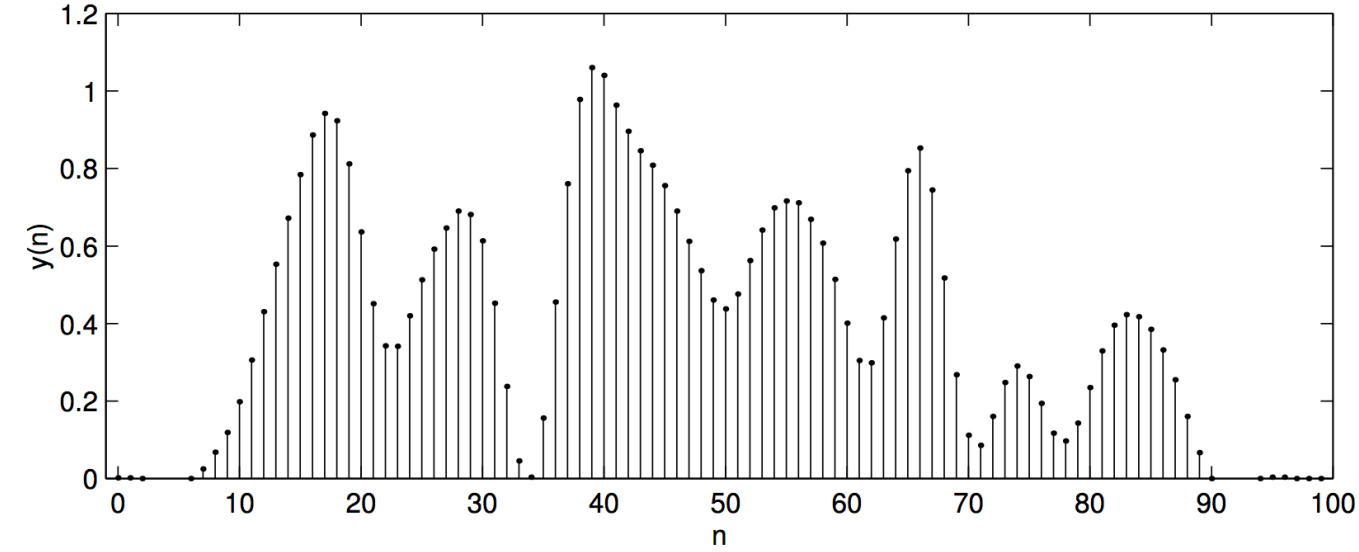
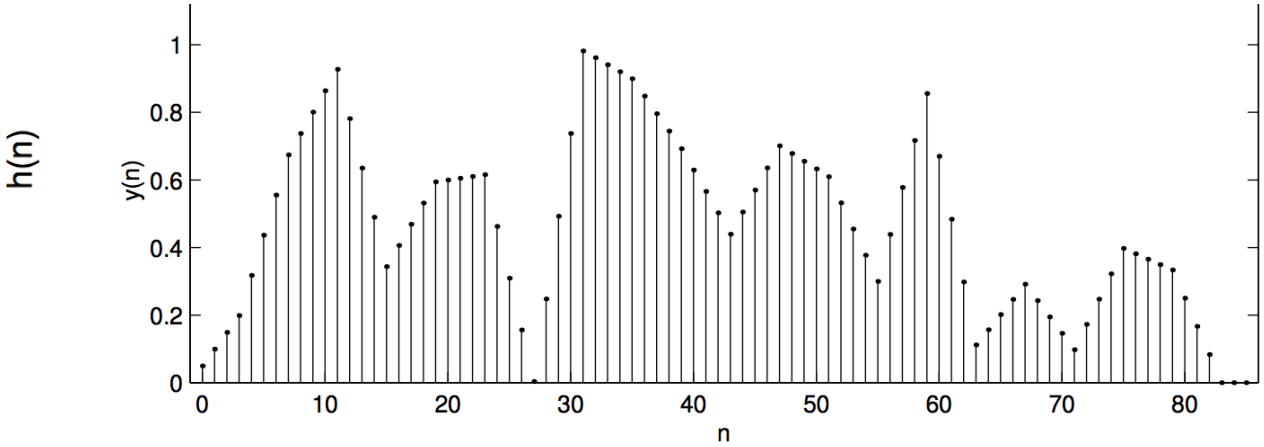
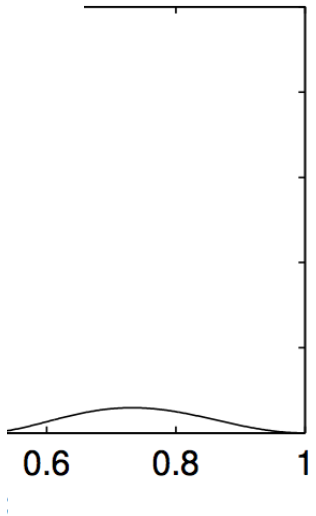



∗

nvolve)



# Interpolation Filter Example 3

- When interpolating a signal x(n), the interpolation filter h(n) will in general change the samples of x(n) in addition to filling in the zeros.
- Can a filter be designed so as to preserve the original samples x(n)?

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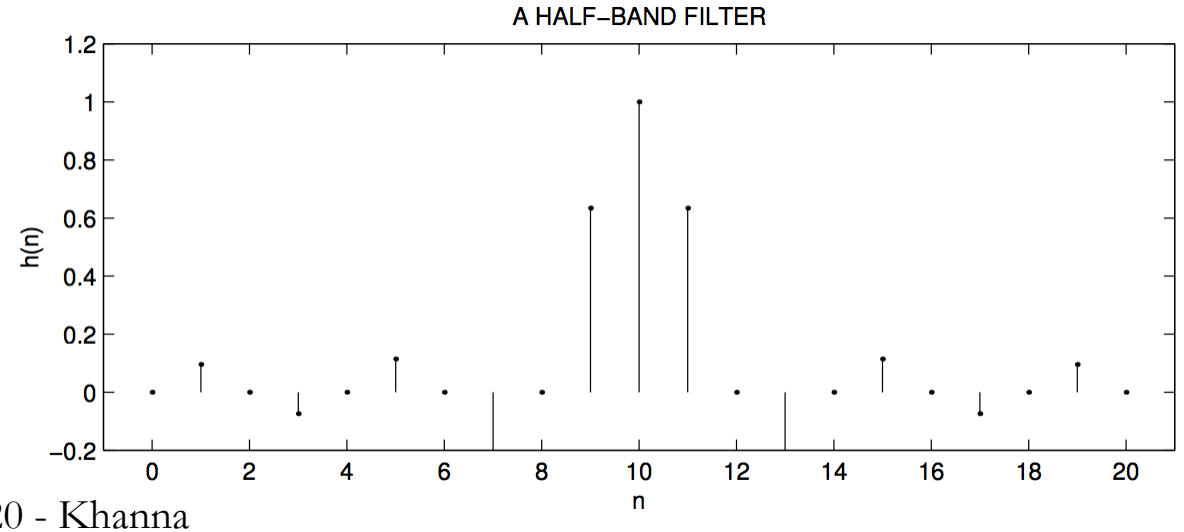
- To be precise, if $y(n) = h(n) * [\uparrow 2]\, x(n)$ then can we design h(n) so that $y(2n) = x(n)$?
  - Or more generally, so that $y(2n + n_o) = x(n)$ ?

# Interpolation Filter Example 3

- When interpolating by a factor of 2, if h(n) is a half-band filter, then it will not change the samples x(n).
- A $n_o$-centered half-band filter h(n) is a filter that satisfies:

$$h(n) = \begin{cases} 1, & \text{for } n = n_o \\ 0, & \text{for } n = n_o \pm 2, 4, 6, \ldots \end{cases}$$

- That means, every second value of h(n) is zero, except for one such value, as shown in the figure.



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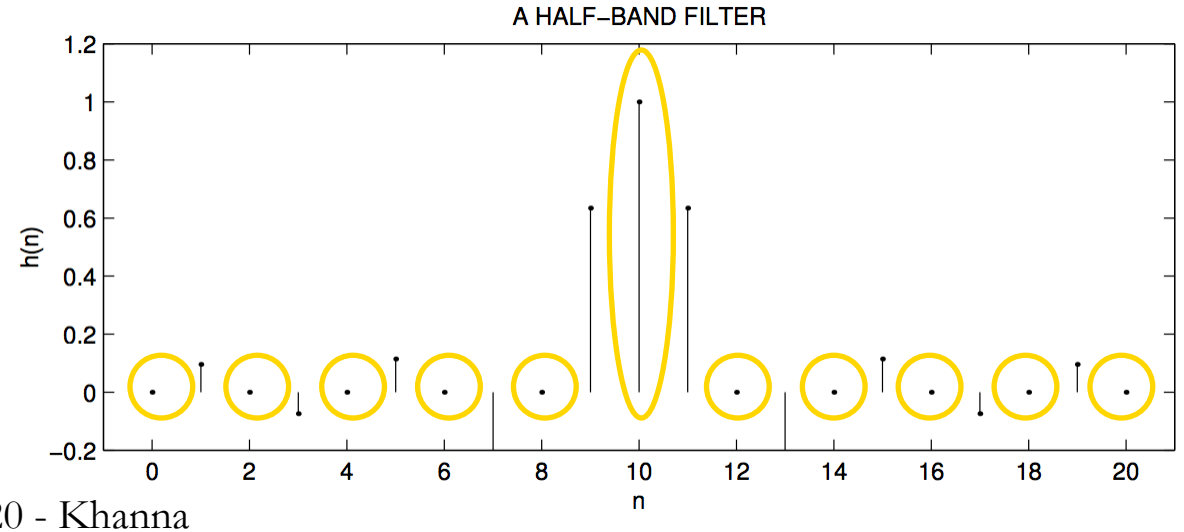

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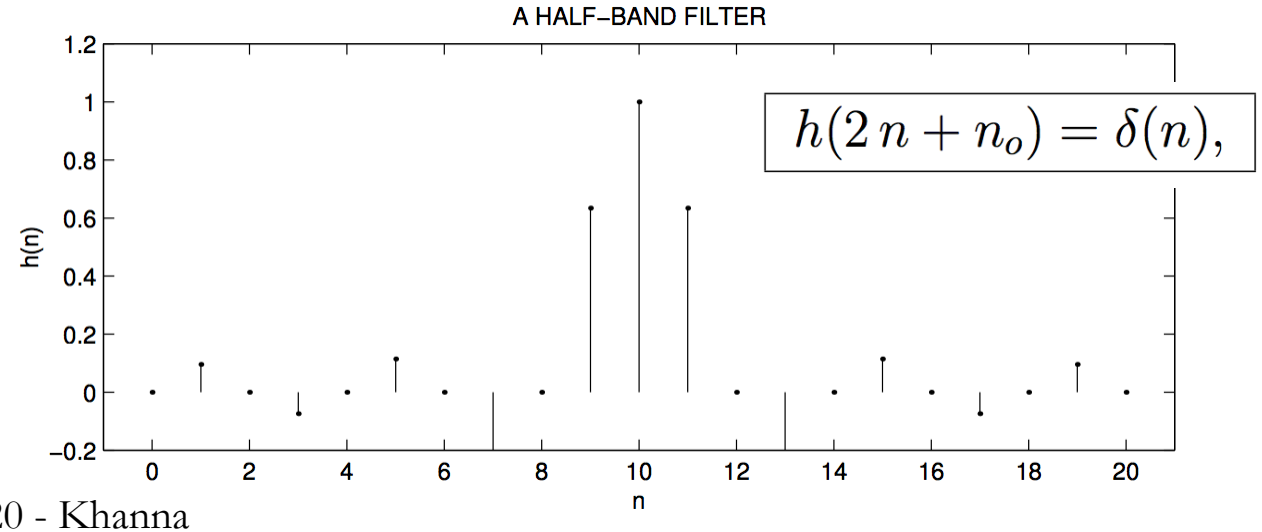

# Interpolation Filter Example 4

- When interpolating a signal x(n) by a factor L, the original samples of x(n) are preserved if h(n) is a Nyquist-L filter.
- A Nyquist-L filter simply generalizes the notion of the halfband filter to L > 2.

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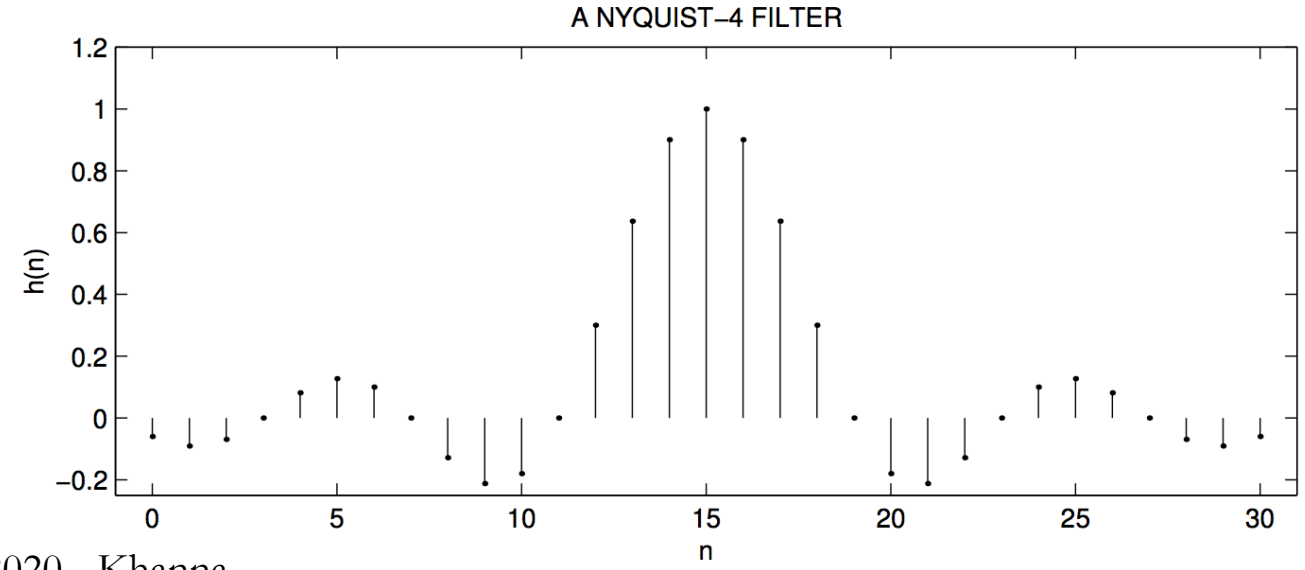
- A (0-centered) Nyquist-L filter h(n) is one for which

$$h(Ln) = \delta(n).$$



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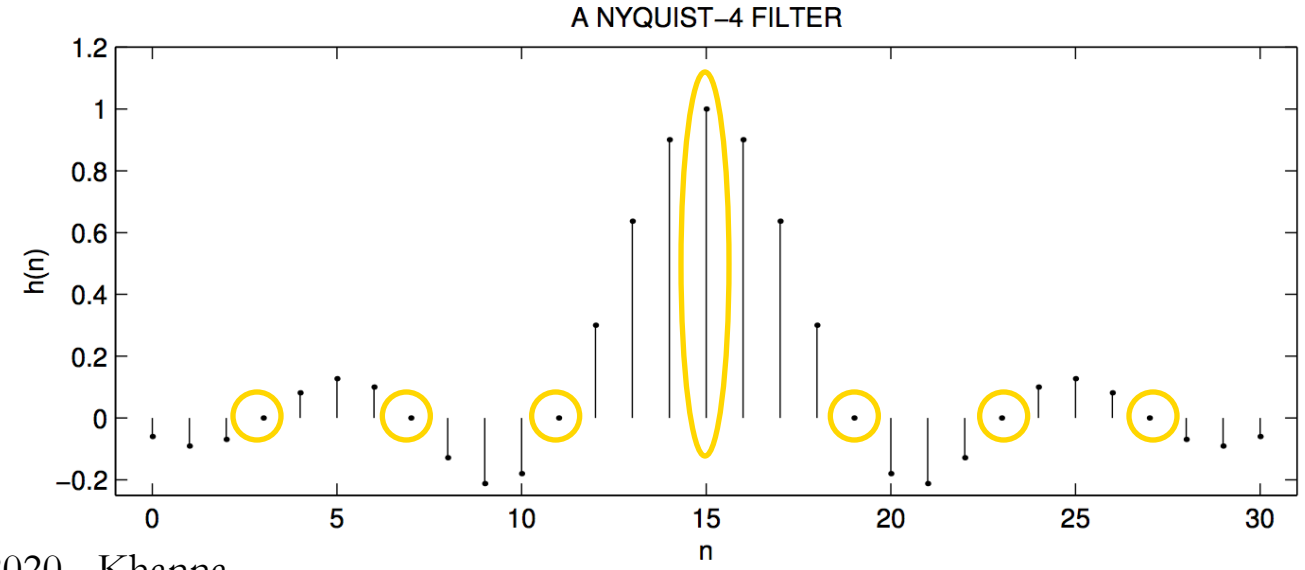

# Non-integer Resampling

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- T'=TM/L

# Non-integer Resampling

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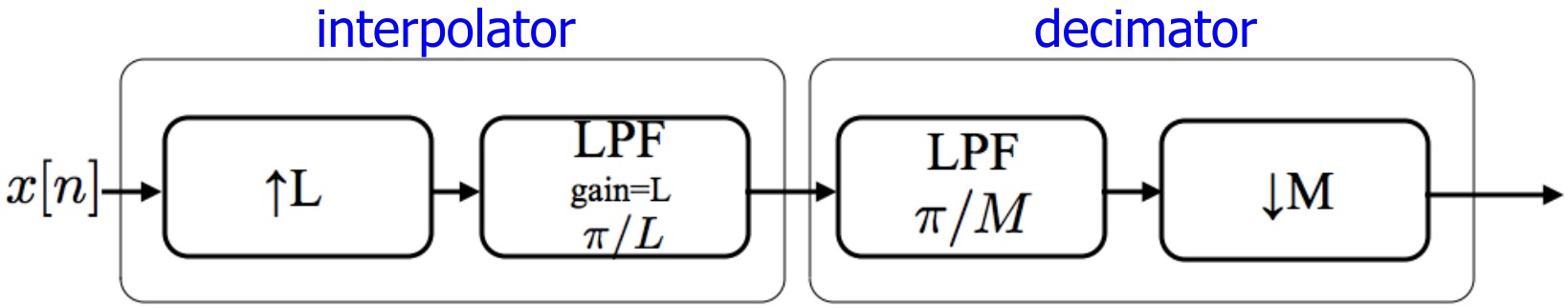
  - Upsample by L, then downsample by M



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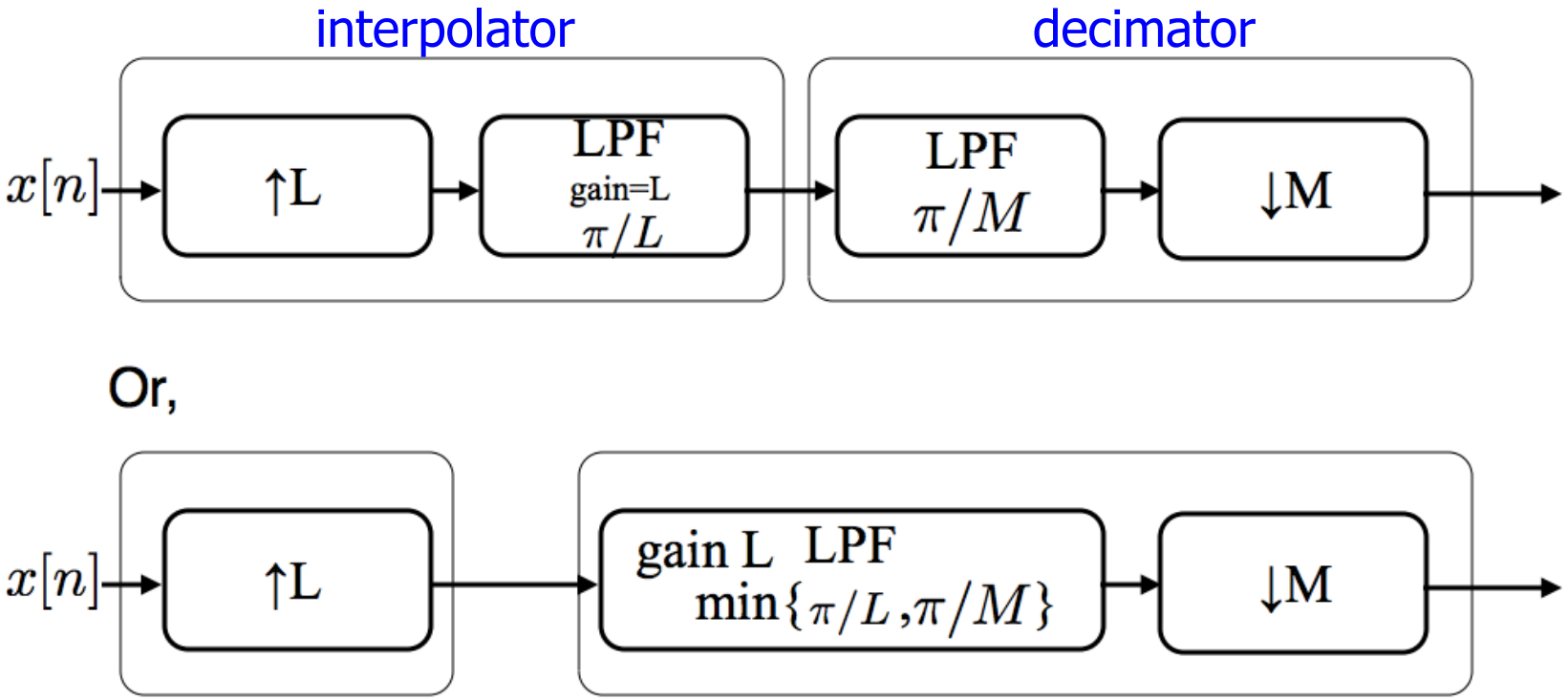
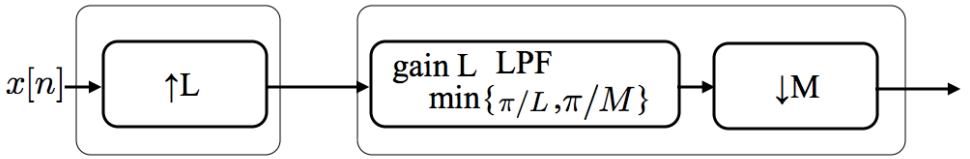
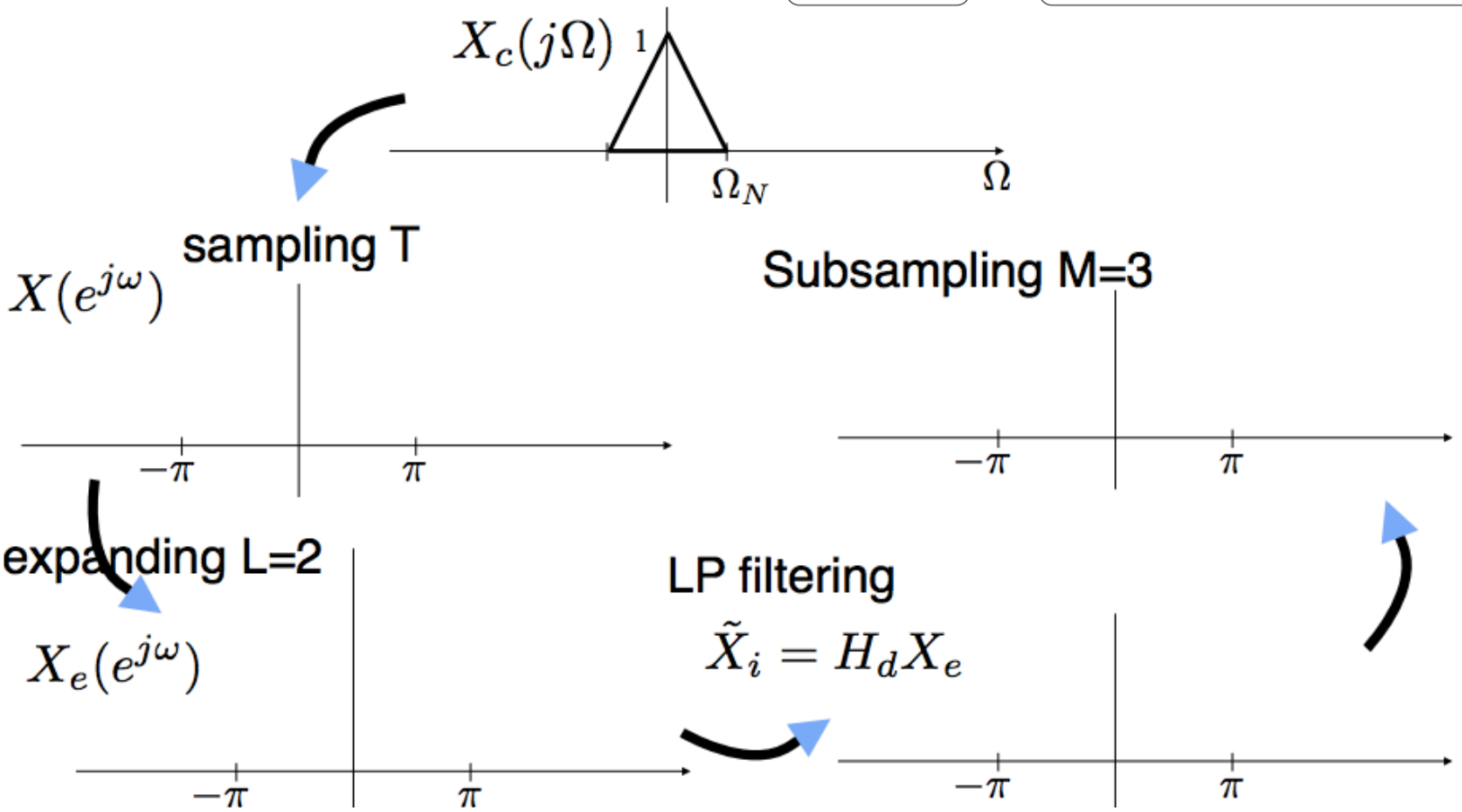


# Example

- T'=3/2T → L=2, M=3



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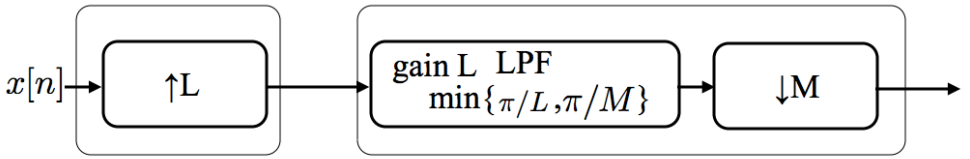
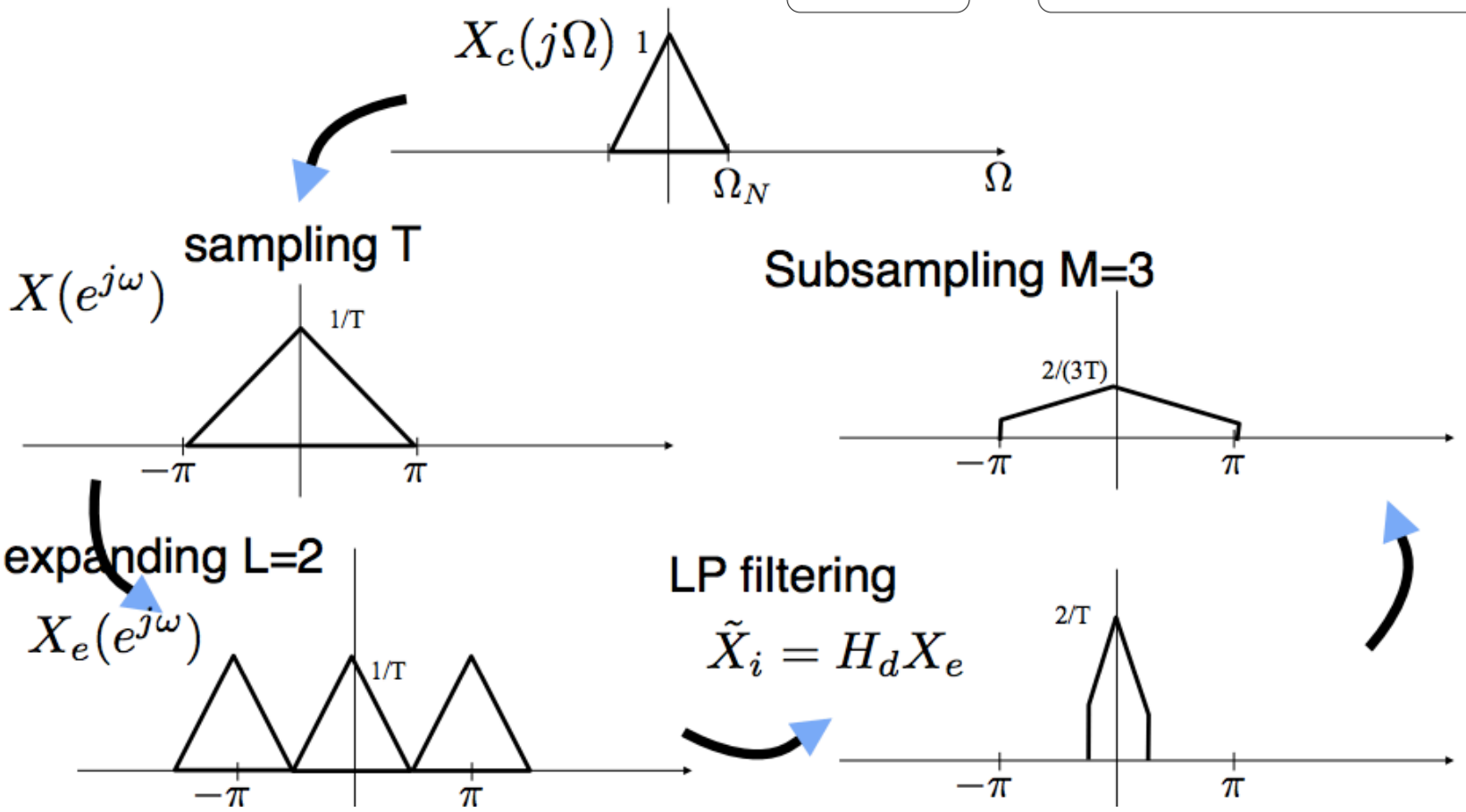
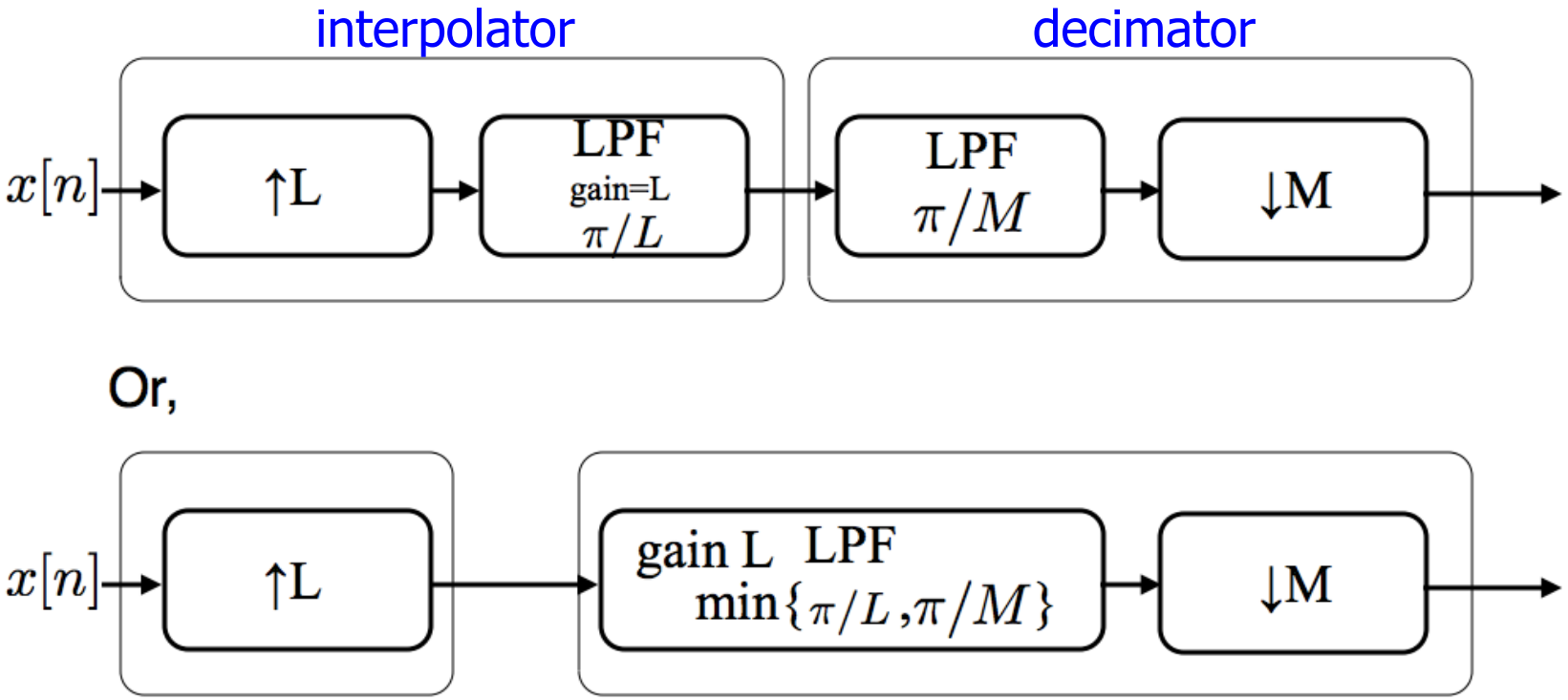


# Non-integer Sampling

- T'=TM/L
  - Downsample by M, then upsample by L?



# Example

- What if we want to resample by 1.01T?

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  - Upsample by L=100
  - Filter $\pi/101$
  - Downsample by M=101

# Example

- What if we want to resample by 1.01T?
  - Upsample by L=100
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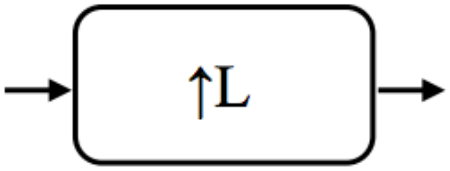
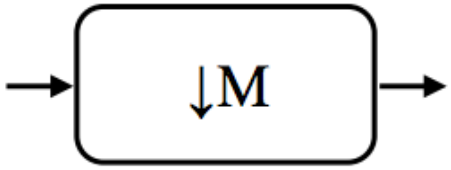
- Fortunately there are ways around it!
  - Called multi-rate signal processing
  - Uses compressors, expanders and filtering

# Interchanging Operations




"expander"

Upsampling
-expanding in time
-compressing in frequency

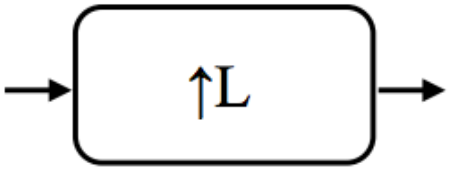



"compressor"

Downsampling
-compressing in time
-expanding in frequency

not LTI!

# Interchanging Operations - Expander

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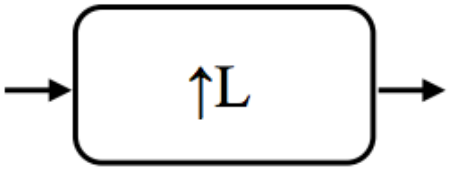


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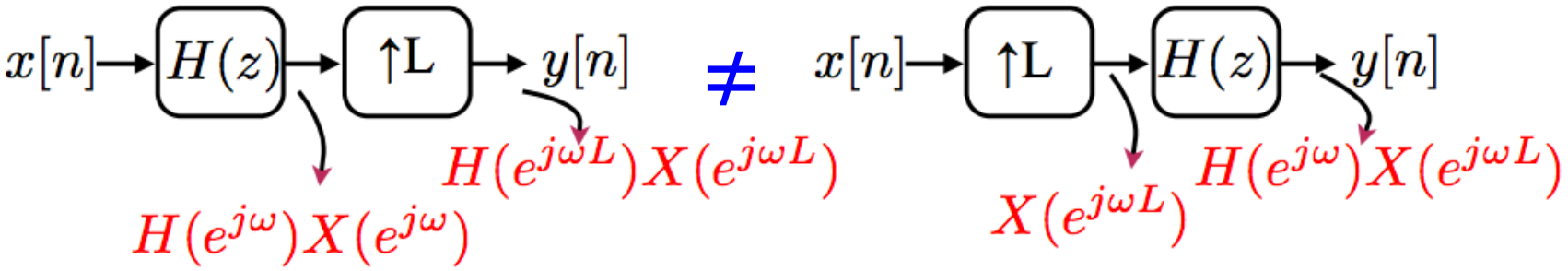

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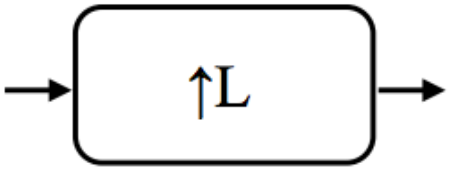


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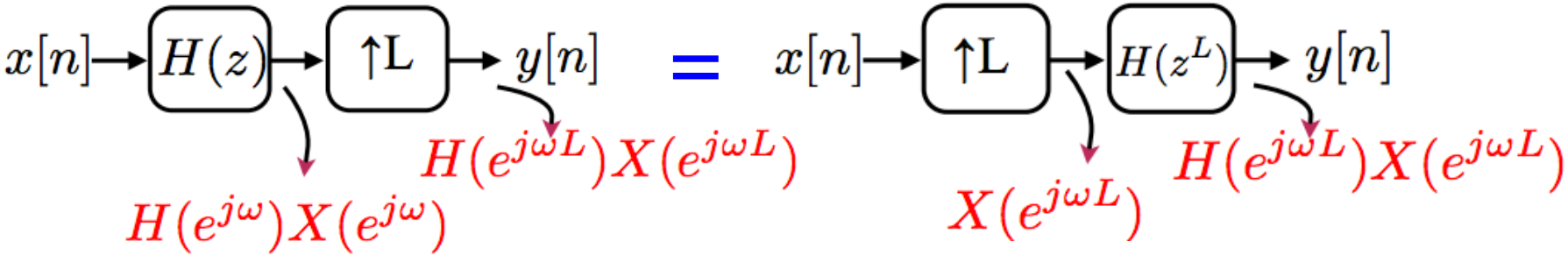
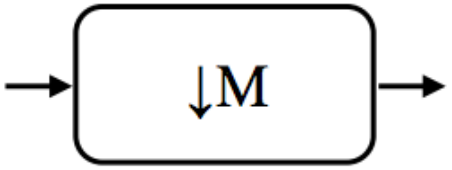


# Interchanging Operations - Compressor

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Downsampling
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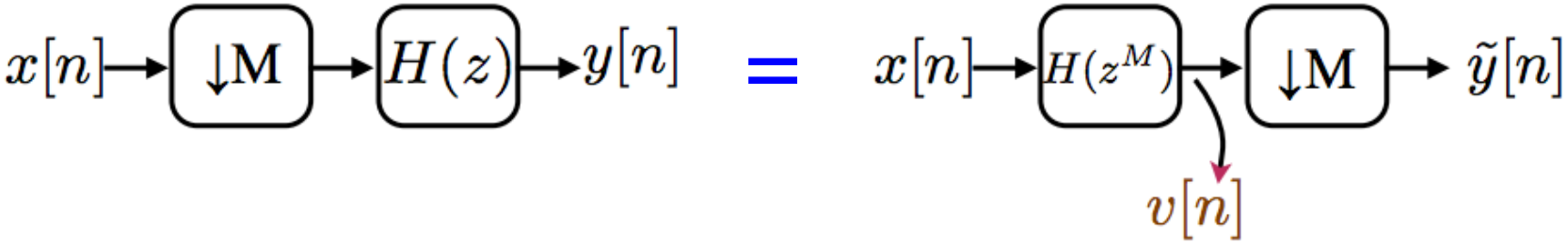

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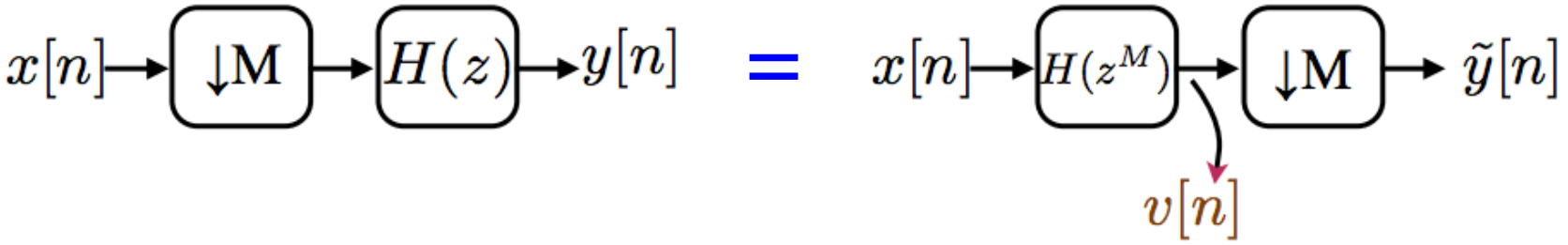
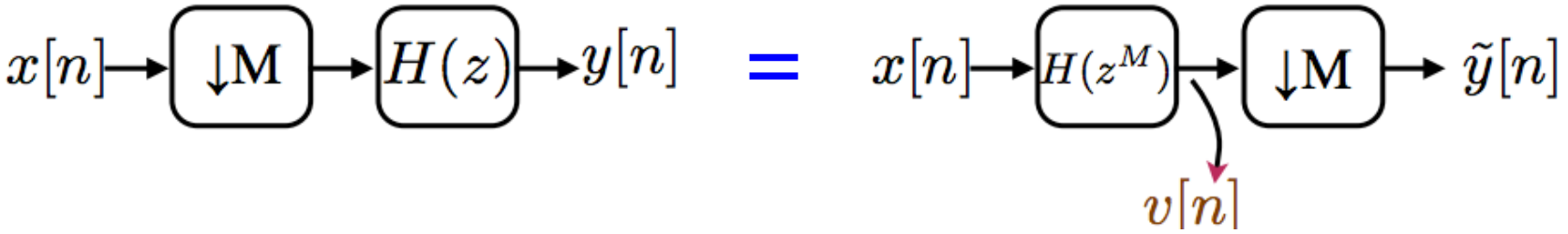



$$Y(e^{j\omega}) = H(e^{j\omega})\left(\frac{1}{M}\sum_{i=0}^{M-1} X\left(e^{j(\frac{\omega}{M}-\frac{2\pi i}{M})}\right)\right)$$

$$= \frac{1}{M}\sum_{i=0}^{M-1} \underbrace{H\left(e^{j(\omega-2\pi i)}\right)}_{H(e^{j\omega})} X\left(e^{j(\frac{\omega}{M}-\frac{2\pi i}{M})}\right)$$

$$= \frac{1}{M}\sum_{i=0}^{M-1} H\left(e^{jM(\frac{\omega}{M}-\frac{2\pi i}{M})}\right) X\left(e^{j(\frac{\omega}{M}-\frac{2\pi i}{M})}\right)$$

# Interchanging Operations - Compressor




$$Y(e^{j\omega}) = \frac{1}{M}\sum_{i=0}^{M-1} H\left(e^{jM(\frac{\omega}{M}-\frac{2\pi i}{M})}\right) X\left(e^{j(\frac{\omega}{M}-\frac{2\pi i}{M})}\right)$$

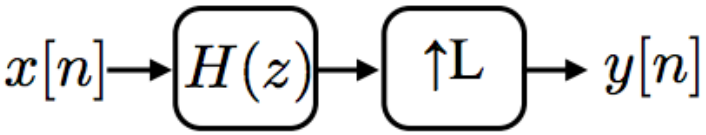
$$V(e^{j\omega}) = H(e^{j\omega M})X(e^{j\omega})$$

=

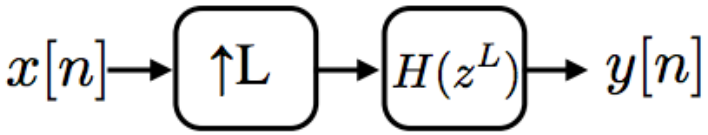
$$\tilde{Y}(e^{j\omega}) = \frac{1}{M}\sum_{i=0}^{M-1} V\left(e^{j(\frac{\omega}{M}-\frac{2\pi i}{M})}\right)$$

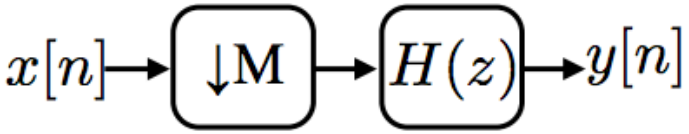
# Interchanging Operations - Summary

Filter and expander

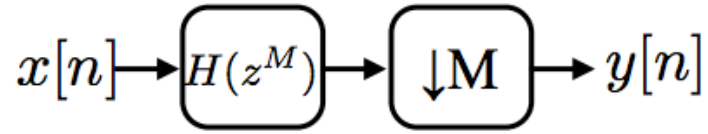



Expander and expanded filter*




Compressor and filter




Expanded filter* and compressor

*Expanded filter = expanded impulse response, compressed freq response

# Multi-Rate Signal Processing

- What if we want to resample by 1.01T?
  - Expand by L=100
  - Filter $\pi/101$ ($$$$$)
  - Compress by M=101

- Fortunately there are ways around it!
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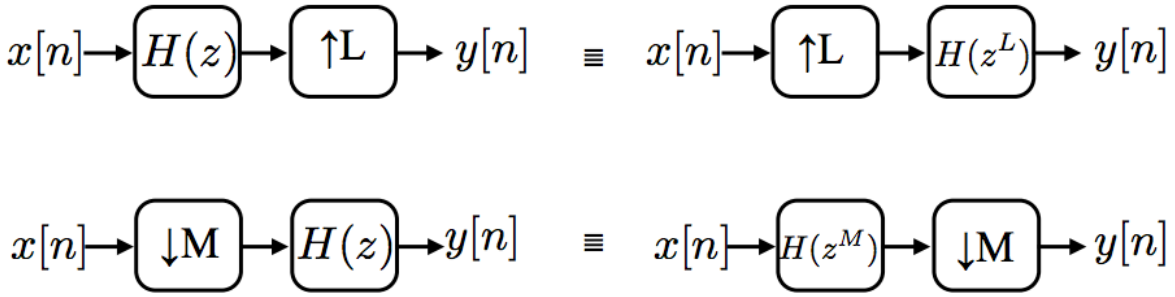
# Big Ideas

- Downsampling/Upsampling
- Practical Interpolation
- Non-integer Resampling
- Multi-Rate Processing
  - Interchanging Operations



# Admin

- HW 4 due Sunday