

ESE 531: Digital Signal Processing

Lec 10: February 18, 2020
Non-Integer and Multi-rate Sampling



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Lecture Outline

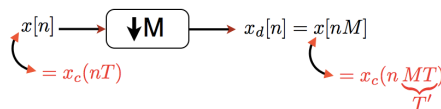
- Review: Downsampling/Upsampling
- Interpolation
- Non-integer Resampling
- Multi-Rate Processing
 - Interchanging Operations

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2

Downsampling

- Definition: Reducing the sampling rate by an integer number



$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X(e^{j(\frac{\omega}{M} - \frac{2\pi}{M}i)})$$

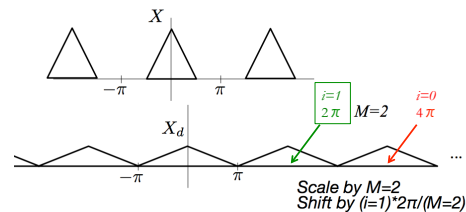
stretch by M replicate

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3

Example

$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X(e^{j(\frac{\omega}{M} - \frac{2\pi}{M}i)})$$

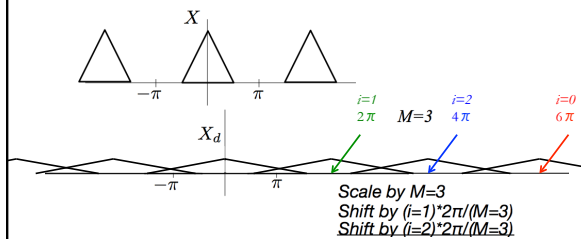


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4

Example

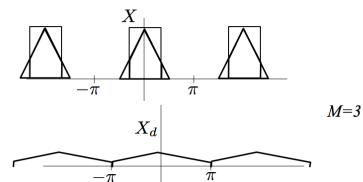
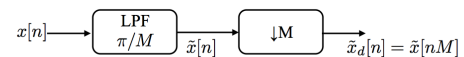
$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X(e^{j(\frac{\omega}{M} - \frac{2\pi}{M}i)})$$



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5

Example



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6

Upsampling

- Definition: Increasing the sampling rate by an integer number

$$x[n] = x_c(nT)$$

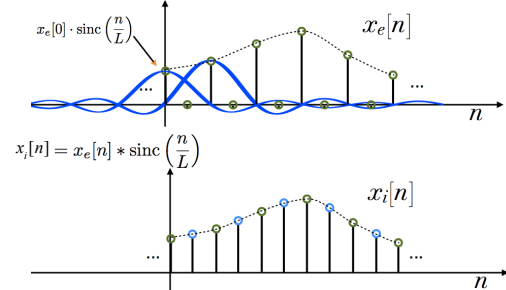
$$x_i[n] = x_c(nT') \quad \text{where } T' = \frac{T}{L} \quad L \text{ integer}$$

Obtain $x_i[n]$ from $x[n]$ in two steps:

$$(1) \text{ Generate: } x_e[n] = \begin{cases} x[n/L] & n = 0, \pm L, \pm 2L, \dots \\ 0 & \text{otherwise} \end{cases}$$

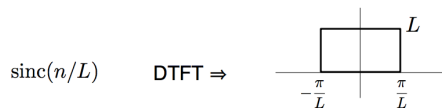
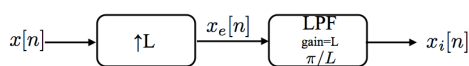
Upsampling

(2) Obtain $x_i[n]$ from $x_e[n]$ by bandlimited interpolation:

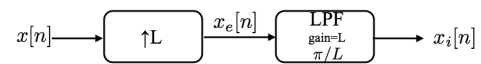


Frequency Domain Interpretation

$$x_i[n] = x_e[n] * \text{sinc}(n/L)$$



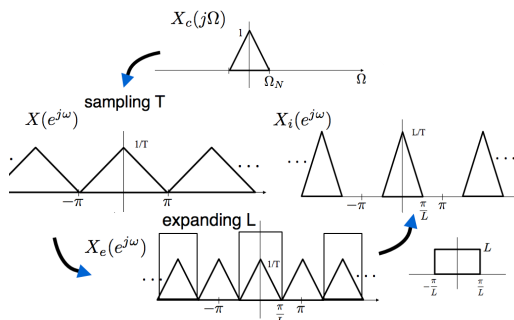
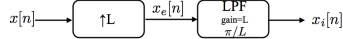
Frequency Domain Interpretation



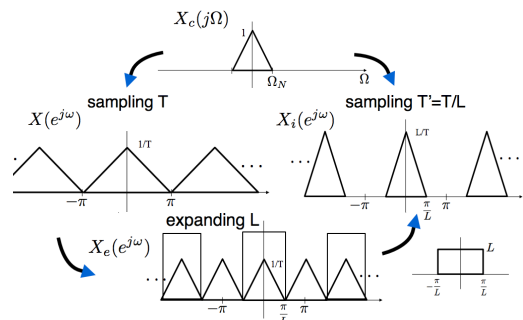
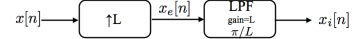
$$\begin{aligned} X_e(e^{j\omega}) &= \sum_{n=-\infty}^{\infty} x_e[n] e^{-j\omega n} \\ &\neq 0 \text{ only for } n=mL \text{ (integer } m) \\ &= \sum_{m=-\infty}^{\infty} x_e[mL] e^{-j\omega mL} = X(e^{j\omega L}) \end{aligned}$$

Compress DTFT by a factor of L!

Example



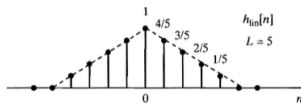
Example



Practical Interpolation

- Interpolate with simple, practical filters
 - Linear interpolation – samples between original samples fall on a straight line connecting the samples
 - Convolve with triangle instead of sinc

$$h_{lin}[n] = \begin{cases} 1 - |n|/L, & |n| \leq L, \\ 0, & \text{otherwise,} \end{cases}$$

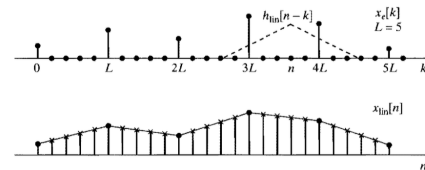


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13

Practical Interpolation

- Interpolate with simple, practical filters
 - Linear interpolation – samples between original samples fall on a straight line connecting the samples
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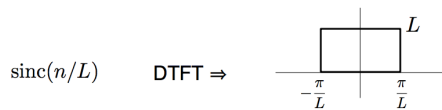
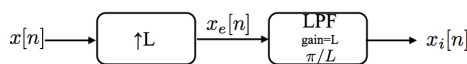


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14

Frequency Domain Interpretation

$$x_i[n] = x_e[n] * \text{sinc}(n/L)$$

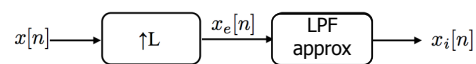


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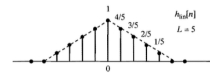
15

Linear Interpolation -- Frequency Domain

$$x_i[n] = x_e[n] * h_{lin}[n]$$



$$h_{lin}[n] = \begin{cases} 1 - |n|/L, & |n| \leq L, \\ 0, & \text{otherwise,} \end{cases}$$

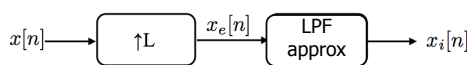


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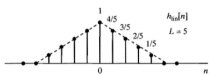
16

Linear Interpolation -- Frequency Domain

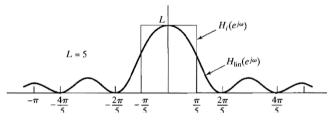
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DTFT $\Rightarrow$

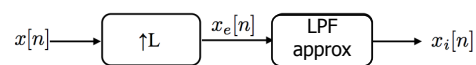


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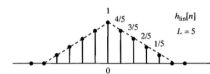
17

Linear Interpolation -- Frequency Domain

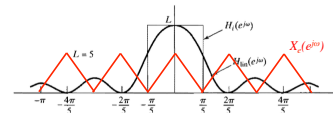
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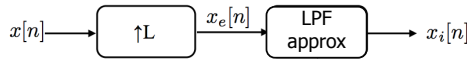


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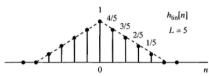
18

Linear Interpolation -- Frequency Domain

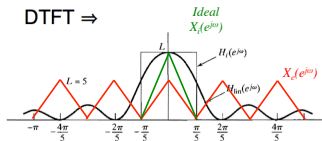
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DTFT $\Rightarrow$

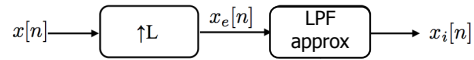


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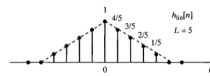
19

Linear Interpolation -- Frequency Domain

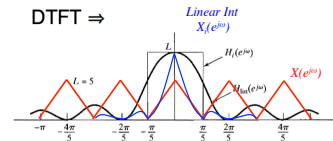
$$x_i[n] = x_e[n] * h_{lin}[n]$$



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DTFT $\Rightarrow$

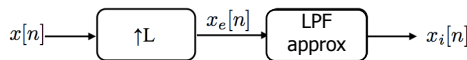


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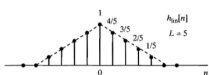
20

Linear Interpolation -- Frequency Domain

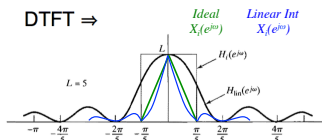
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DTFT $\Rightarrow$

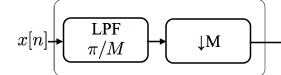


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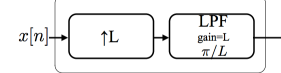
21

Interpolation and Decimation

decimator



interpolator

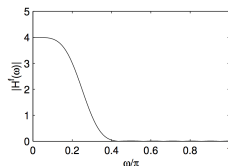
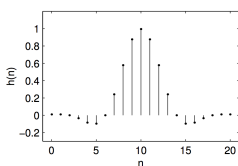


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22

Interpolation Filter Example 1

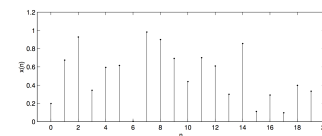
- In this example, we interpolate a signal $x(n)$ by a factor of 4.
- We use a linear phase Type I FIR lowpass filter of length 21.



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23

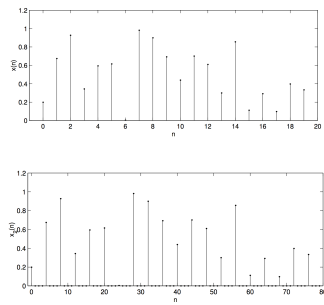
Interpolation Filter Example 1



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24

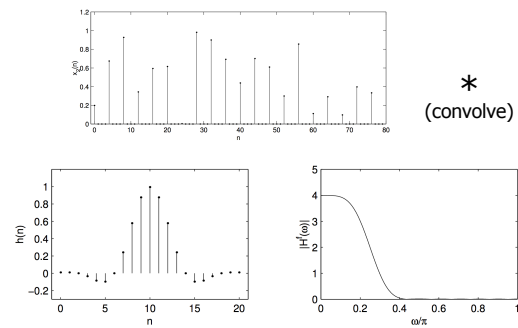
Interpolation Filter Example 1



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25

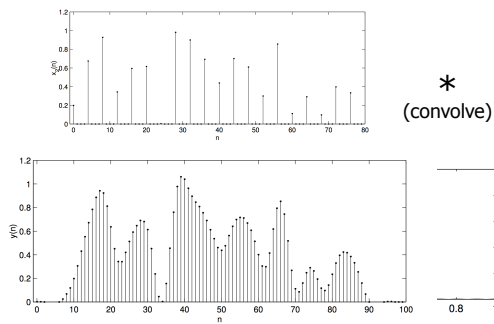
Interpolation Filter Example 1



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26

Interpolation Filter Example 1

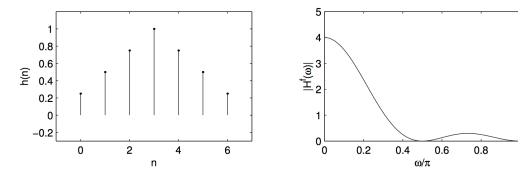


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27

Interpolation Filter Example 2

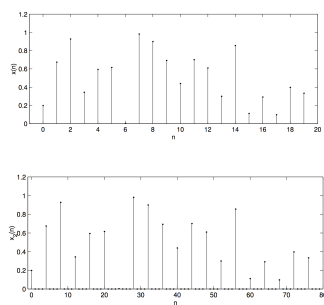
□ This time we use a filter of length 7 with the effect of linear interpolation



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28

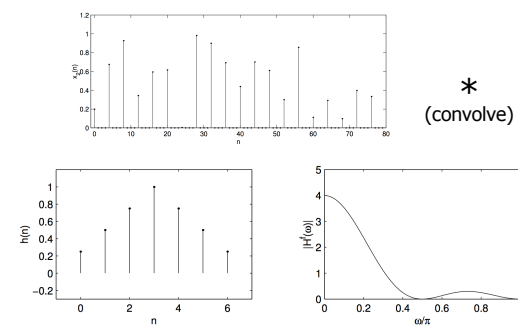
Interpolation Filter Example 2



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29

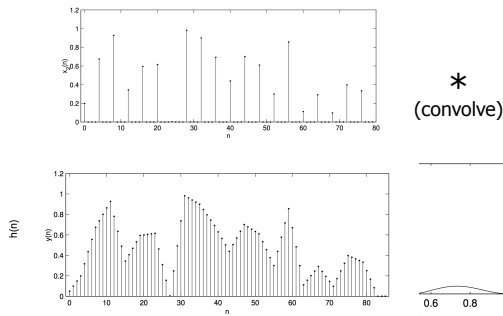
Interpolation Filter Example 2



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30

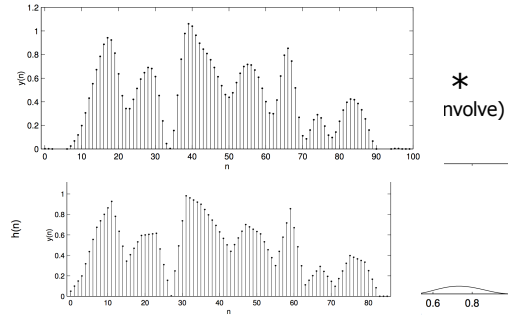
Interpolation Filter Example 2



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31

Interpolation Filter Example 2



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32

Interpolation Filter Example 3

- When interpolating a signal $x(n)$, the interpolation filter $h(n)$ will in general change the samples of $x(n)$ in addition to filling in the zeros.
- Can a filter be designed so as to preserve the original samples $x(n)$?

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33

Interpolation Filter Example 3

- When interpolating a signal $x(n)$, the interpolation filter $h(n)$ will in general change the samples of $x(n)$ in addition to filling in the zeros.
- Can a filter be designed so as to preserve the original samples $x(n)$?
- To be precise, if $y(n) = h(n) * [\uparrow 2] x(n)$ then can we design $h(n)$ so that $y(2n) = x(n)$?

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34

Interpolation Filter Example 3

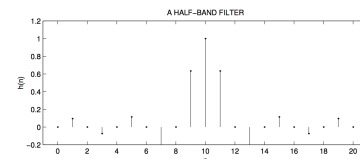
- When interpolating a signal $x(n)$, the interpolation filter $h(n)$ will in general change the samples of $x(n)$ in addition to filling in the zeros.
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- To be precise, if $y(n) = h(n) * [\uparrow 2] x(n)$ then can we design $h(n)$ so that $y(2n) = x(n)$?
 - Or more generally, so that $y(2n + n_0) = x(n)$?

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35

Interpolation Filter Example 3

- When interpolating by a factor of 2, if $h(n)$ is a half-band filter, then it will not change the samples $x(n)$.
 - A n_0 -centered half-band filter $h(n)$ is a filter that satisfies:
- $$h(n) = \begin{cases} 1, & \text{for } n = n_0 \\ 0, & \text{for } n = n_0 \pm 2, 4, 6, \dots \end{cases}$$
- That means, every second value of $h(n)$ is zero, except for one such value, as shown in the figure.



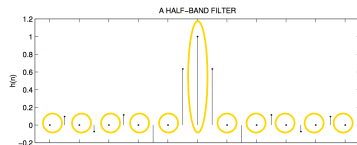
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36

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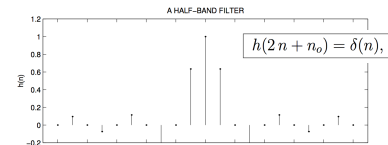
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37

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38

Interpolation Filter Example 4

- When interpolating a signal $x(n)$ by a factor L , the original samples of $x(n)$ are preserved if $h(n)$ is a Nyquist-L filter.
- A Nyquist-L filter simply generalizes the notion of the halfband filter to $L > 2$.

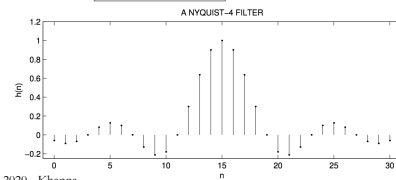
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39

Interpolation Filter Example 4

- When interpolating a signal $x(n)$ by a factor L , the original samples of $x(n)$ are preserved if $h(n)$ is a Nyquist-L filter.
- A Nyquist-L filter simply generalizes the notion of the halfband filter to $L > 2$.
- A (0-centered) Nyquist-L filter $h(n)$ is one for which

$$h(Ln) = \delta(n).$$



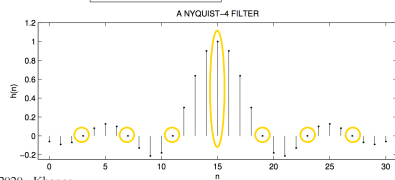
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40

Interpolation Filter Example 4

- When interpolating a signal $x(n)$ by a factor L , the original samples of $x(n)$ are preserved if $h(n)$ is a Nyquist-L filter.
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41

Non-integer Resampling



Non-integer Resampling

□ $T' = TM/L$

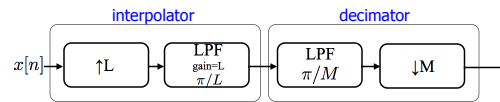
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43

Non-integer Resampling

□ $T' = TM/L$

- Upsample by L, then downsample by M



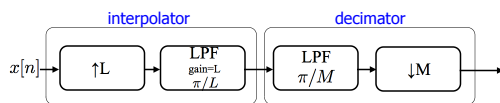
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44

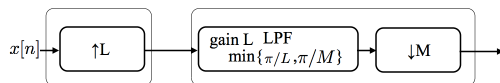
Non-integer Resampling

□ $T' = TM/L$

- Upsample by L, then downsample by M



Or,

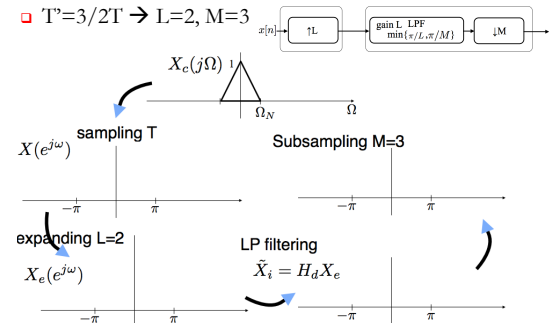


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45

Example

□ $T' = 3/2T \rightarrow L=2, M=3$

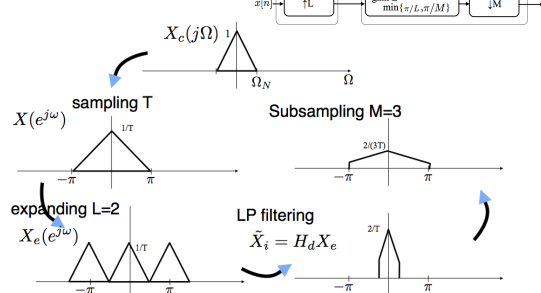


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46

Example

□ $T' = 3/2T \rightarrow L=2, M=3$



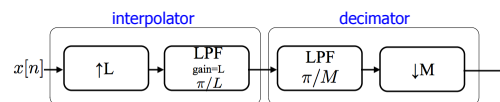
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47

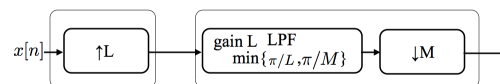
Non-integer Sampling

□ $T' = TM/L$

- Downsample by M, then upsample by L



Or,



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48

Example

- What if we want to resample by $1.01T$?

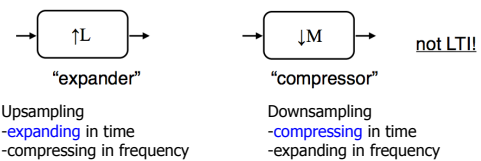
Example

- What if we want to resample by $1.01T$?
 - Upsample by $L=100$
 - Filter $\pi/101$
 - Downsample by $M=101$

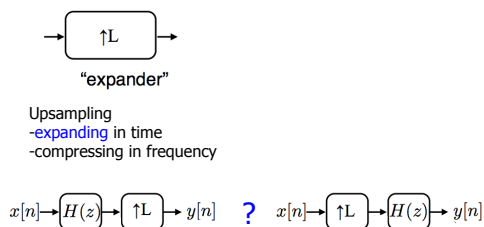
Example

- What if we want to resample by $1.01T$?
 - Upsample by $L=100$
 - Filter $\pi/101$ (\$\$\$\$)
 - Downsample by $M=101$
- Fortunately there are ways around it!
 - Called multi-rate signal processing
 - Uses compressors, expanders and filtering

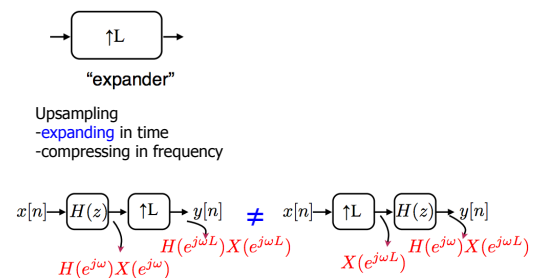
Interchanging Operations



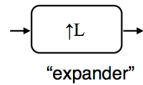
Interchanging Operations - Expander



Interchanging Operations - Expander



Interchanging Operations - Expander



Upsampling
-expanding in time
-compressing in frequency

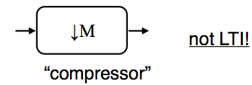
$$x[n] \rightarrow H(z) \rightarrow \uparrow L \rightarrow y[n] = x[n] \rightarrow \uparrow L \rightarrow H(z^L) \rightarrow y[n]$$

$H(e^{j\omega L})X(e^{j\omega L})$ $X(e^{j\omega L})$ $H(e^{j\omega L})X(e^{j\omega L})$

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55

Interchanging Operations - Compressor



Downsampling
-compressing in time
-expanding in frequency

$$x[n] \rightarrow \downarrow M \rightarrow H(z) \rightarrow y[n] = x[n] \rightarrow H(z^M) \rightarrow \downarrow M \rightarrow \tilde{y}[n]$$

$v[n]$

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56

Interchanging Operations - Compressor

$$x[n] \rightarrow \downarrow M \rightarrow H(z) \rightarrow y[n] = x[n] \rightarrow H(z^M) \rightarrow \downarrow M \rightarrow \tilde{y}[n]$$

$v[n]$

$$\begin{aligned}
 Y(e^{j\omega}) &= H(e^{j\omega}) \left(\frac{1}{M} \sum_{i=0}^{M-1} X(e^{j(\frac{\omega}{M} - \frac{2\pi i}{M})}) \right) \\
 &= \frac{1}{M} \sum_{i=0}^{M-1} \underbrace{H(e^{j(\omega - 2\pi i)})}_{H(e^{j\omega})} X(e^{j(\frac{\omega}{M} - \frac{2\pi i}{M})}) \\
 &= \frac{1}{M} \sum_{i=0}^{M-1} H(e^{jM(\frac{\omega}{M} - \frac{2\pi i}{M})}) X(e^{j(\frac{\omega}{M} - \frac{2\pi i}{M})})
 \end{aligned}$$

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57

Interchanging Operations - Compressor

$$x[n] \rightarrow \downarrow M \rightarrow H(z) \rightarrow y[n] = x[n] \rightarrow H(z^M) \rightarrow \downarrow M \rightarrow \tilde{y}[n]$$

$v[n]$

$$\begin{aligned}
 Y(e^{j\omega}) &= \frac{1}{M} \sum_{i=0}^{M-1} H(e^{jM(\frac{\omega}{M} - \frac{2\pi i}{M})}) X(e^{j(\frac{\omega}{M} - \frac{2\pi i}{M})}) \\
 V(e^{j\omega}) &= H(e^{j\omega M}) X(e^{j\omega}) \\
 \tilde{Y}(e^{j\omega}) &= \frac{1}{M} \sum_{i=0}^{M-1} V(e^{j(\frac{\omega}{M} - \frac{2\pi i}{M})})
 \end{aligned}$$

=

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58

Interchanging Operations - Summary

Filter and expander Expander and expanded filter*

$$x[n] \rightarrow H(z) \rightarrow \uparrow L \rightarrow y[n] \equiv x[n] \rightarrow \uparrow L \rightarrow H(z^L) \rightarrow y[n]$$

Compressor and filter Expanded filter* and compressor

$$x[n] \rightarrow \downarrow M \rightarrow H(z) \rightarrow y[n] \equiv x[n] \rightarrow H(z^M) \rightarrow \downarrow M \rightarrow y[n]$$

*Expanded filter = expanded impulse response, compressed freq response

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59

Multi-Rate Signal Processing

- What if we want to resample by 1.01T?
 - Expand by L=100
 - Filter $\pi/101$ (\$\$\$\$)
 - Compress by M=101
- Fortunately there are ways around it!
 - Called multi-rate
 - Uses compressors, expanders and filtering

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60

Big Ideas

- ❑ Downsampling/Upsampling
- ❑ Practical Interpolation
- ❑ Non-integer Resampling
- ❑ Multi-Rate Processing
 - Interchanging Operations

$$x[n] \rightarrow [H(z)] \rightarrow [\uparrow L] \rightarrow y[n] \quad \equiv \quad x[n] \rightarrow [\uparrow L] \rightarrow [H(z^L)] \rightarrow y[n]$$

$$x[n] \rightarrow [\downarrow M] \rightarrow [H(z)] \rightarrow y[n] \quad \equiv \quad x[n] \rightarrow [H(z^M)] \rightarrow [\downarrow M] \rightarrow y[n]$$

Admin

- ❑ HW 4 due Sunday