

# ESE 531: Digital Signal Processing

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Week 7

Lecture 13: February 28, 2021

Data Converters, Noise Shaping



# Lecture Outline

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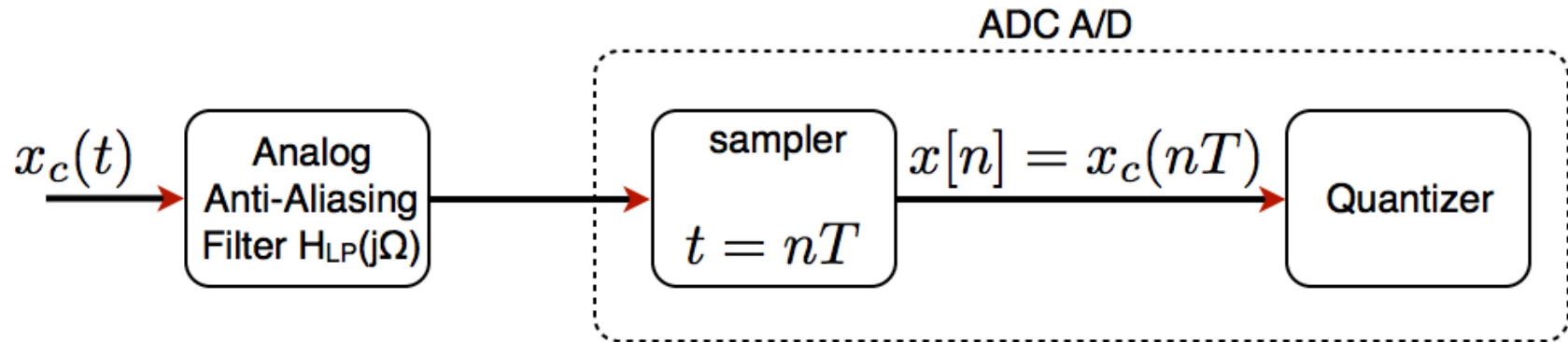
- ❑ Data Converters
  - Anti-aliasing
  - ADC
    - Quantization
  - Practical DAC
- ❑ Noise Shaping

# ADC

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## Analog to Digital Converter

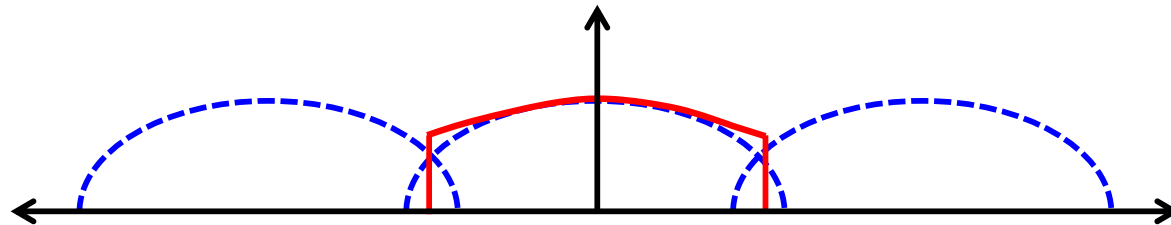
# Anti-Aliasing Filter with ADC





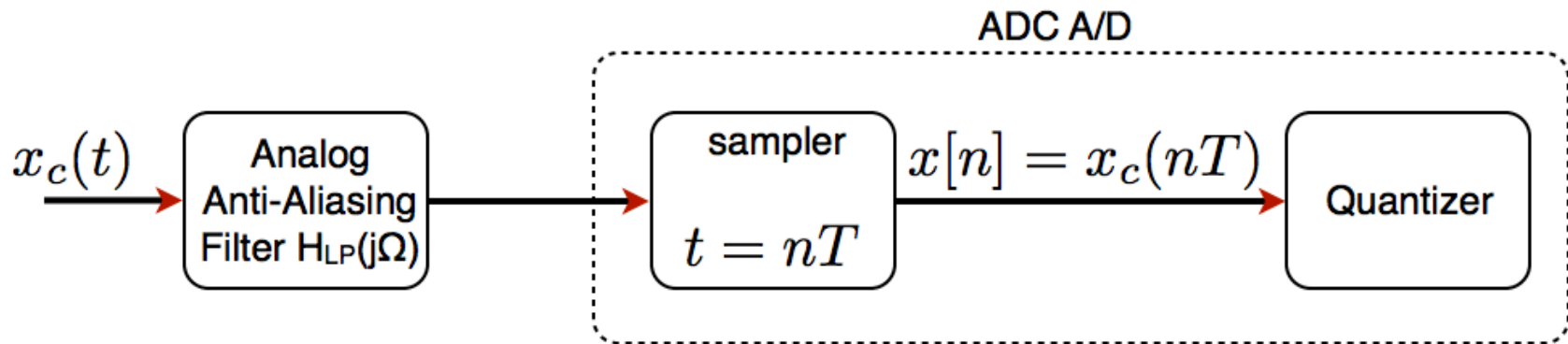
# Aliasing

- If  $\Omega_N > \Omega_s/2$ ,  $x_r(t)$  an aliased version of  $x_c(t)$

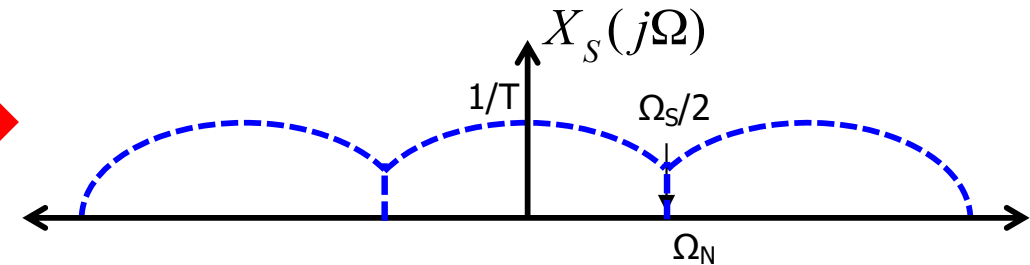
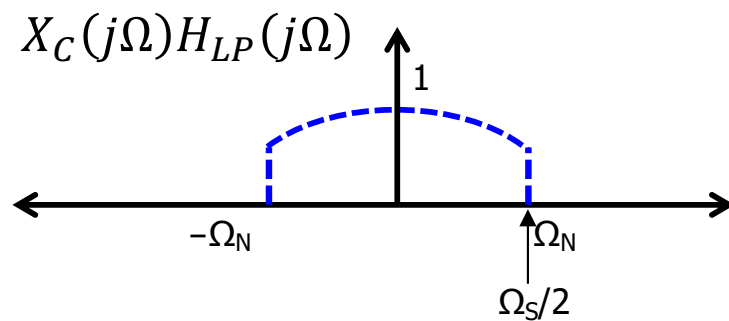
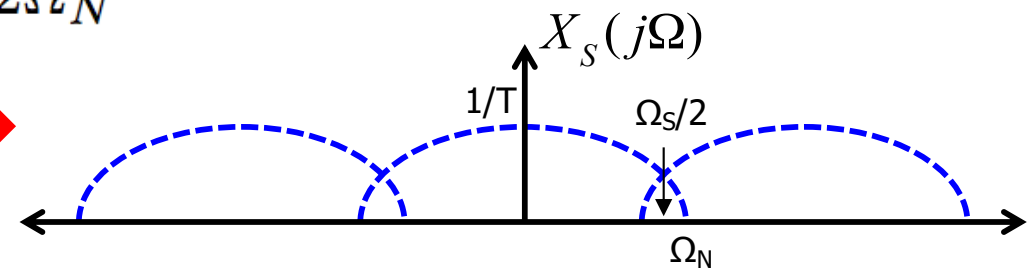
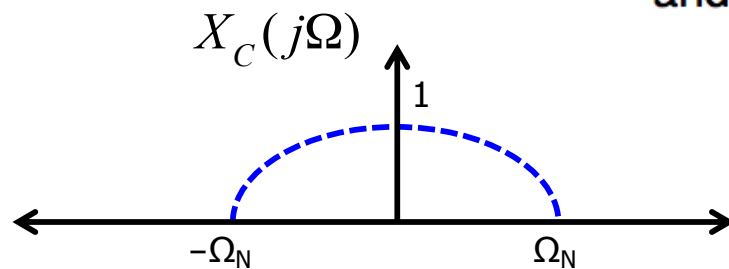


$$X_r(j\Omega) = \begin{cases} TX_s(j\Omega) & \text{if } |\Omega| \leq \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

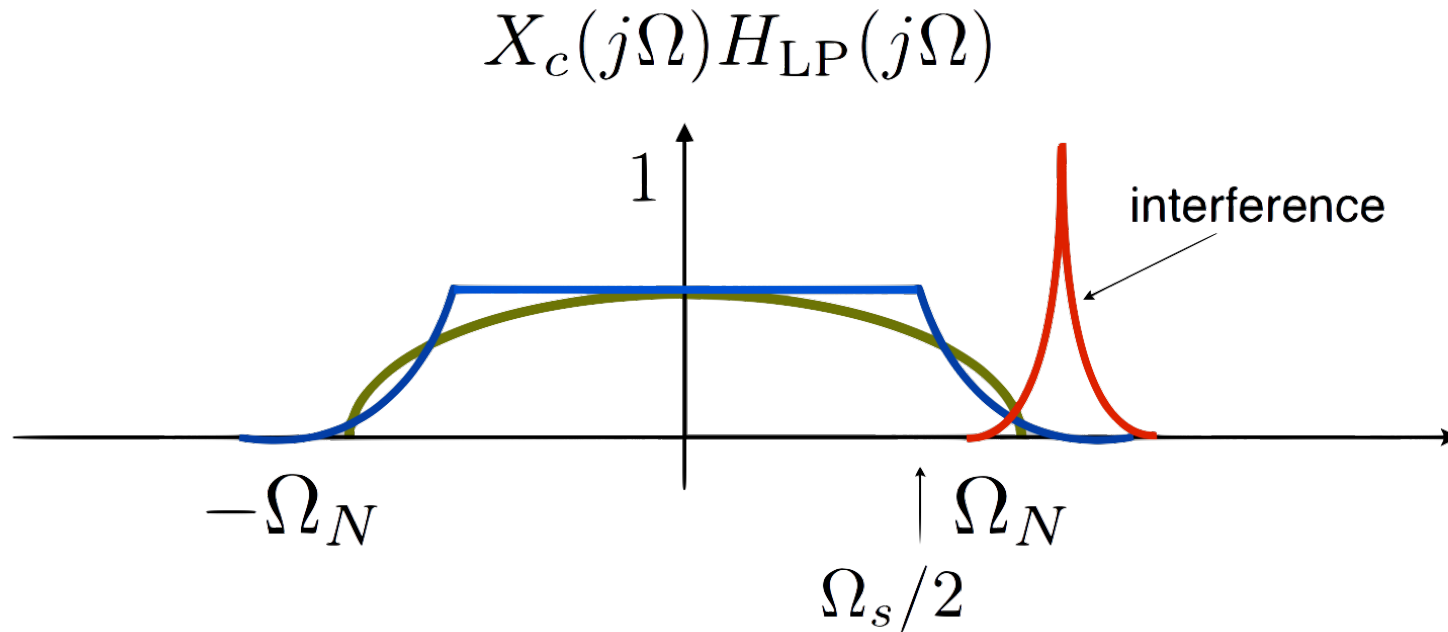
# Anti-Aliasing Filter with ADC



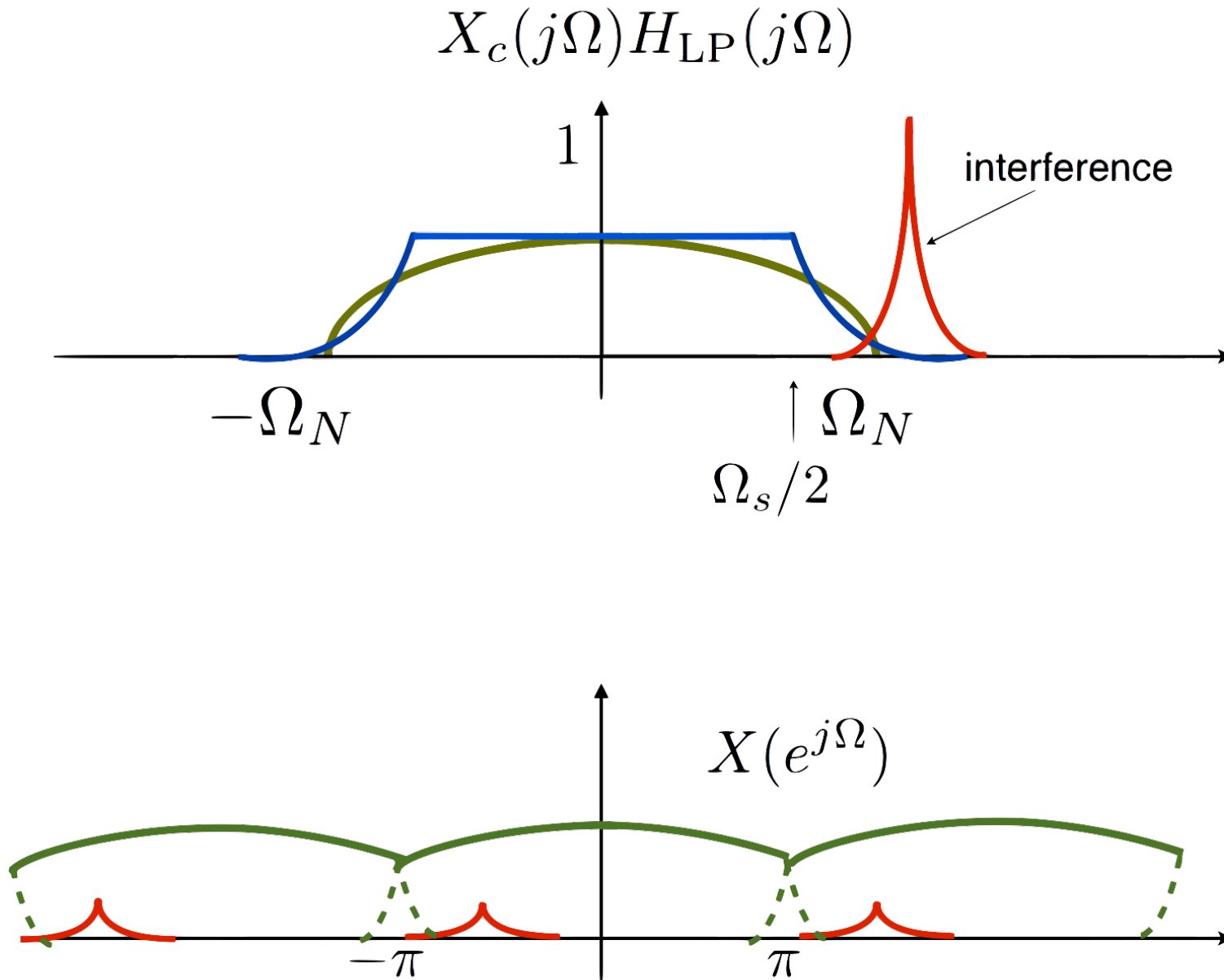
and  $\Omega_s < 2\Omega_N$



# Non-Ideal Anti-Aliasing Filter

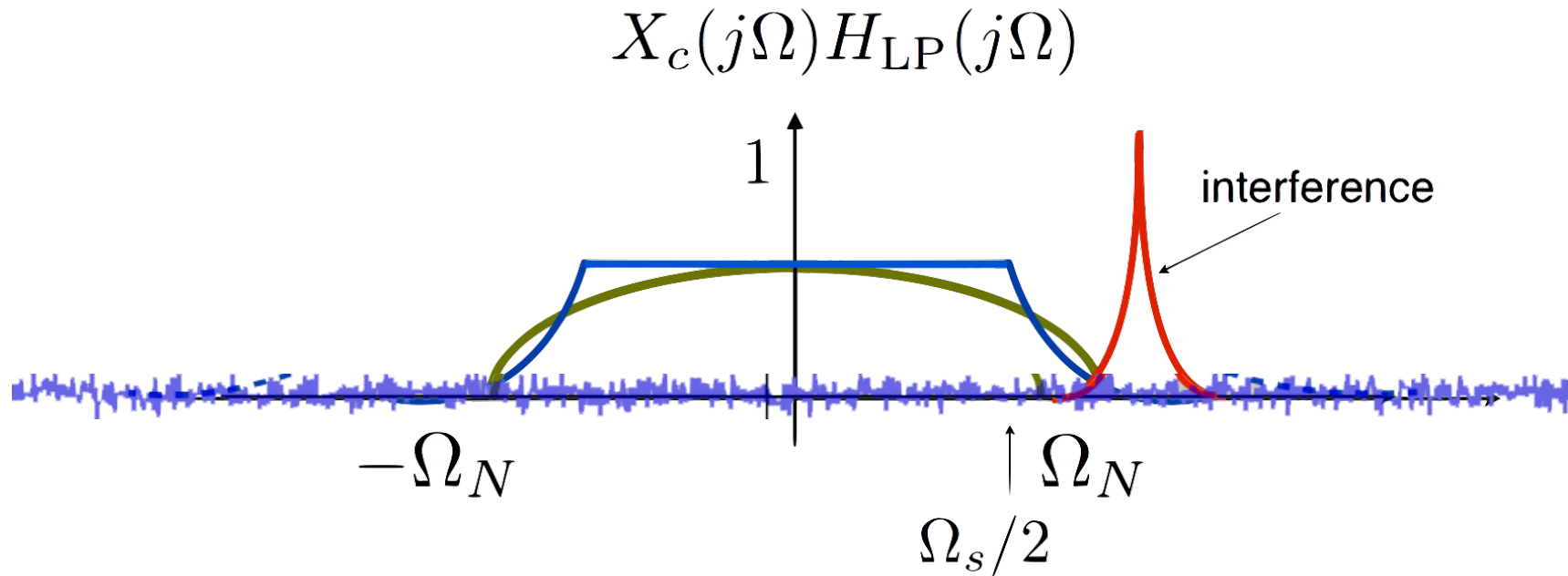


# Non-Ideal Anti-Aliasing Filter



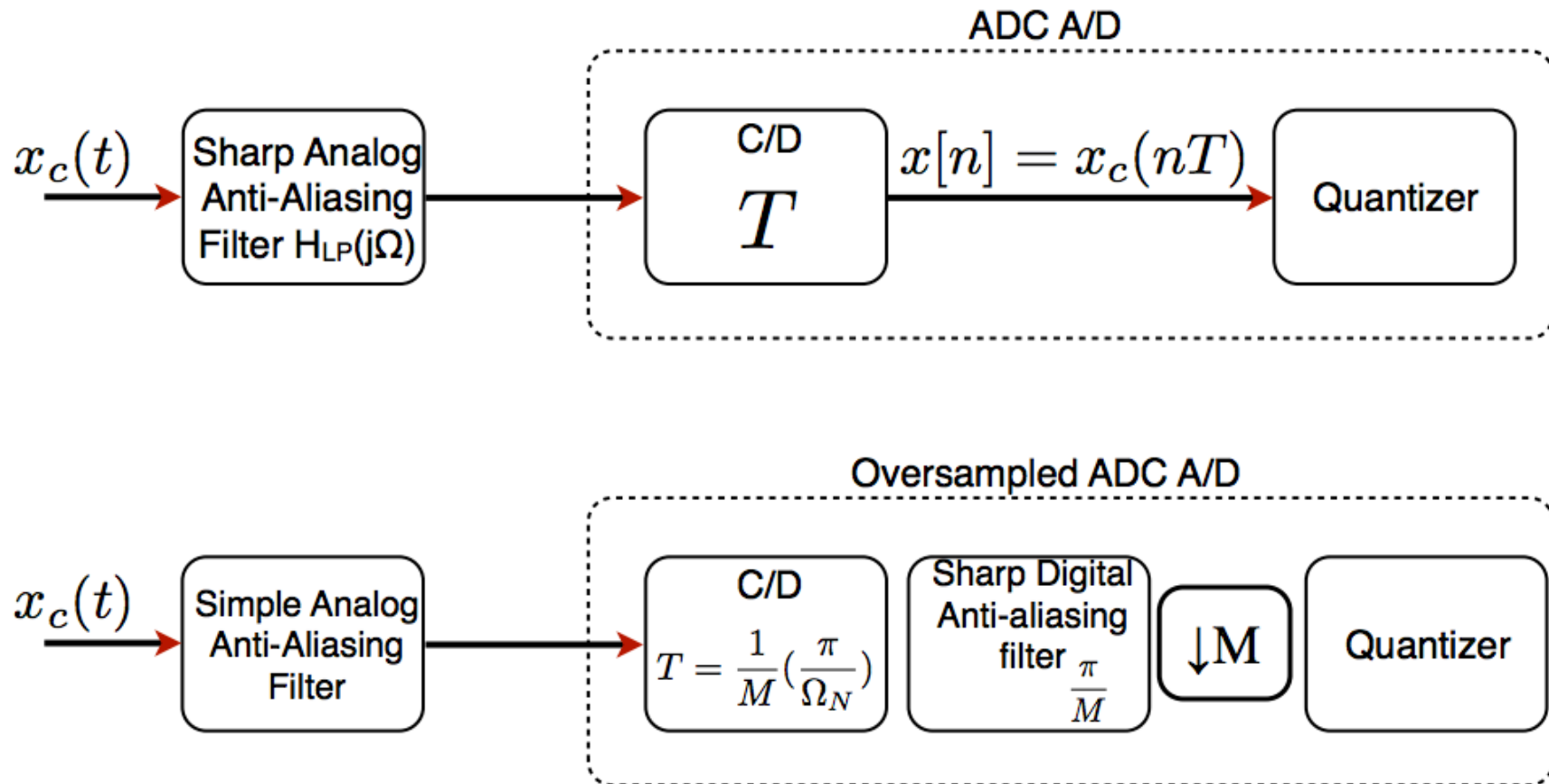


# Non-Ideal Anti-Aliasing Filter

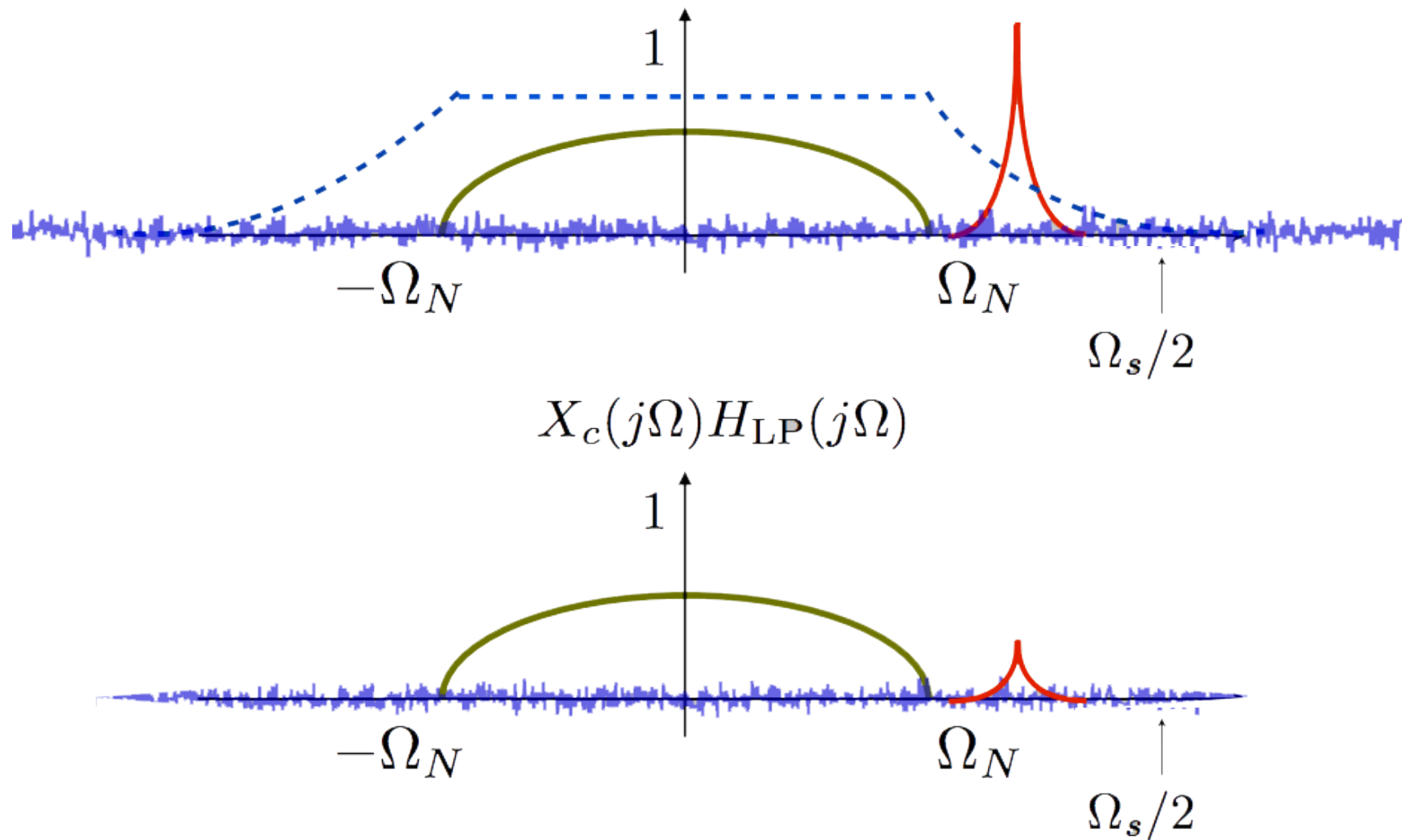


- ❑ Problem: Hard to implement sharp analog filter
- ❑ Consequence: Crop part of the signal and suffer from noise and interference

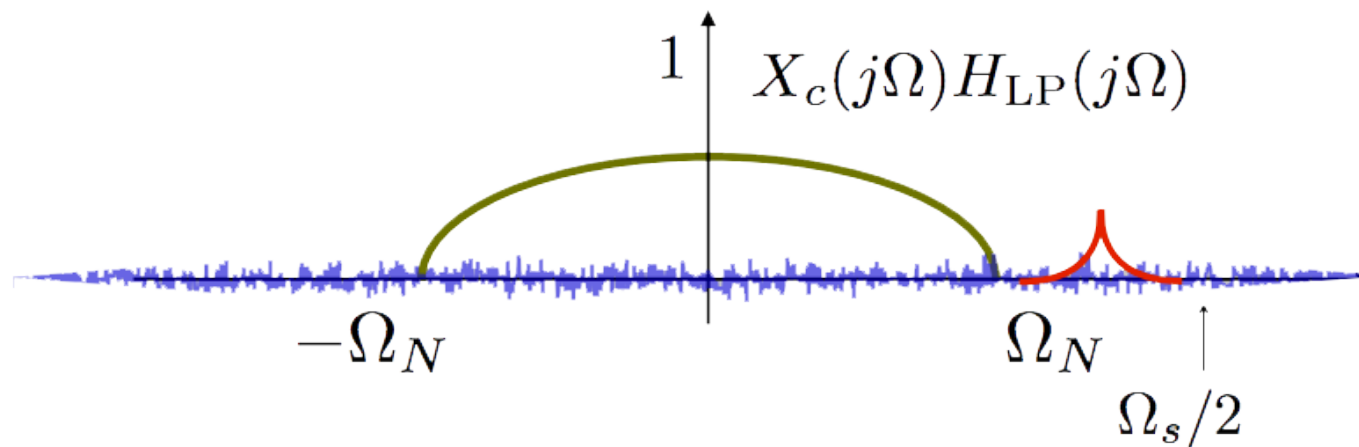
# Oversampled ADC



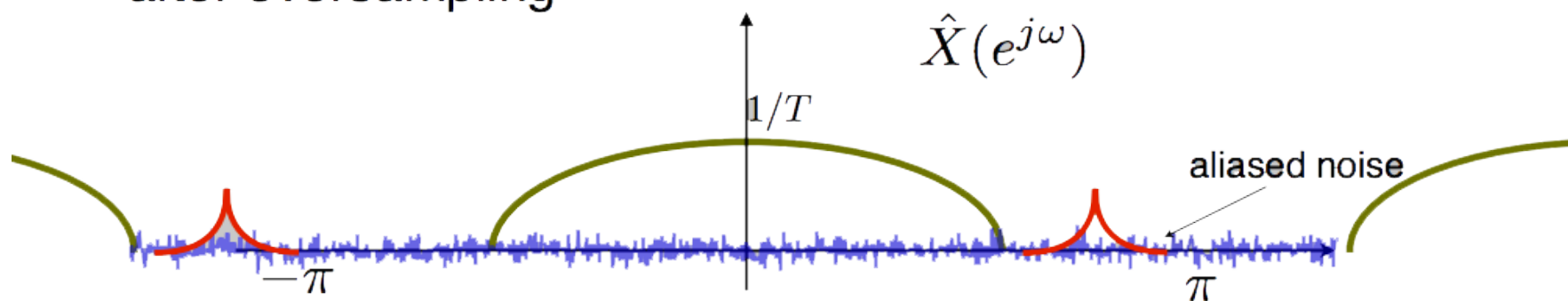
# Oversampled ADC – Simple filter



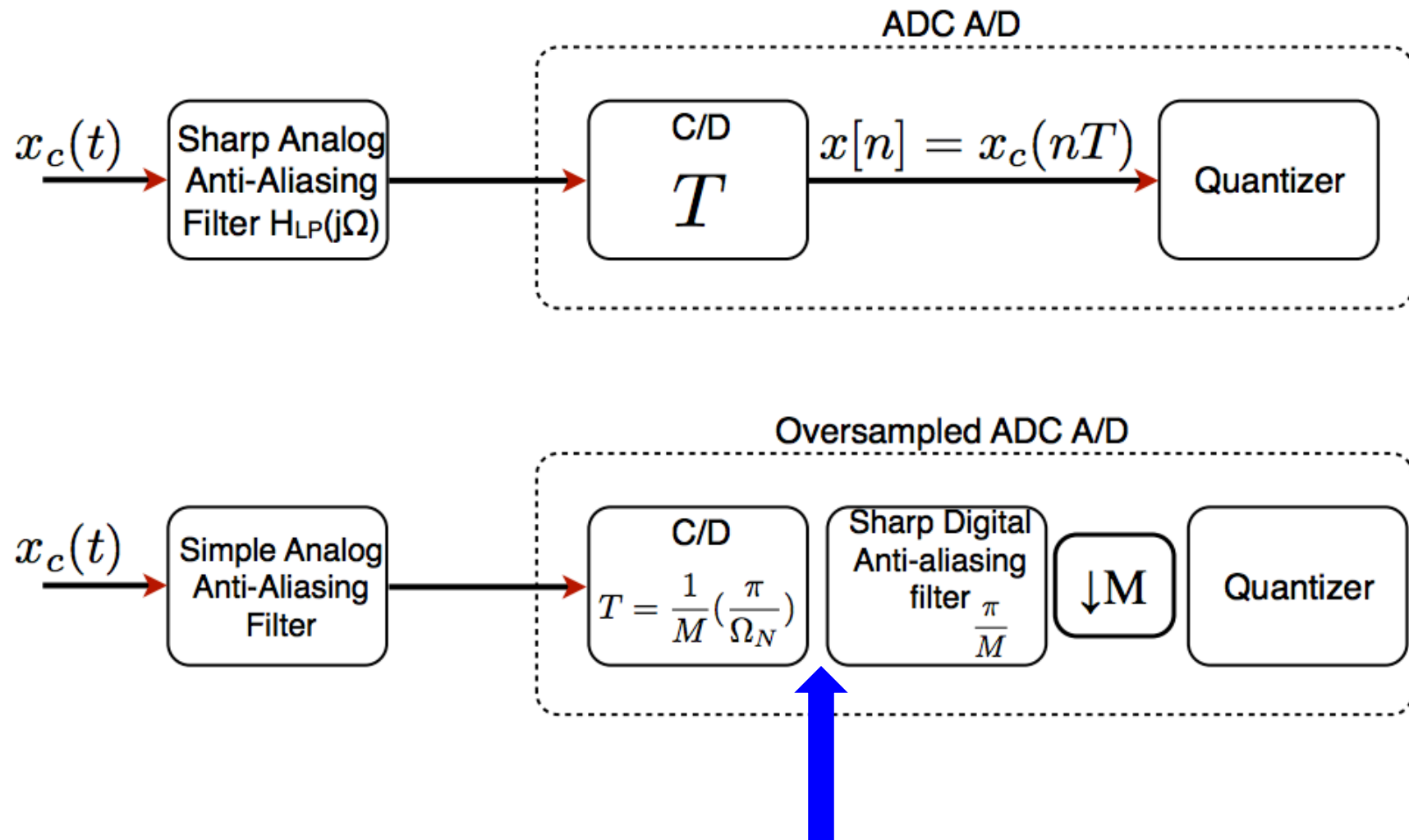
# Oversampled ADC – $M=2$



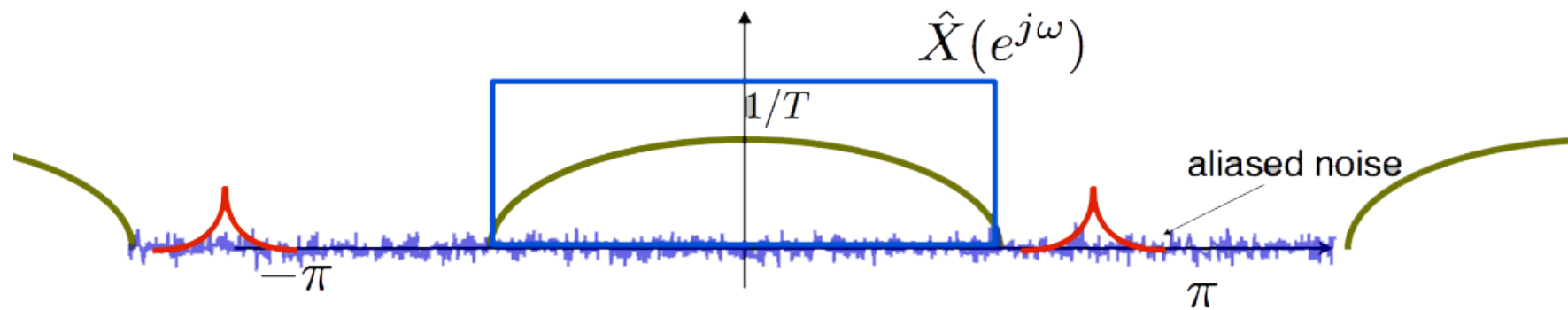
after oversampling



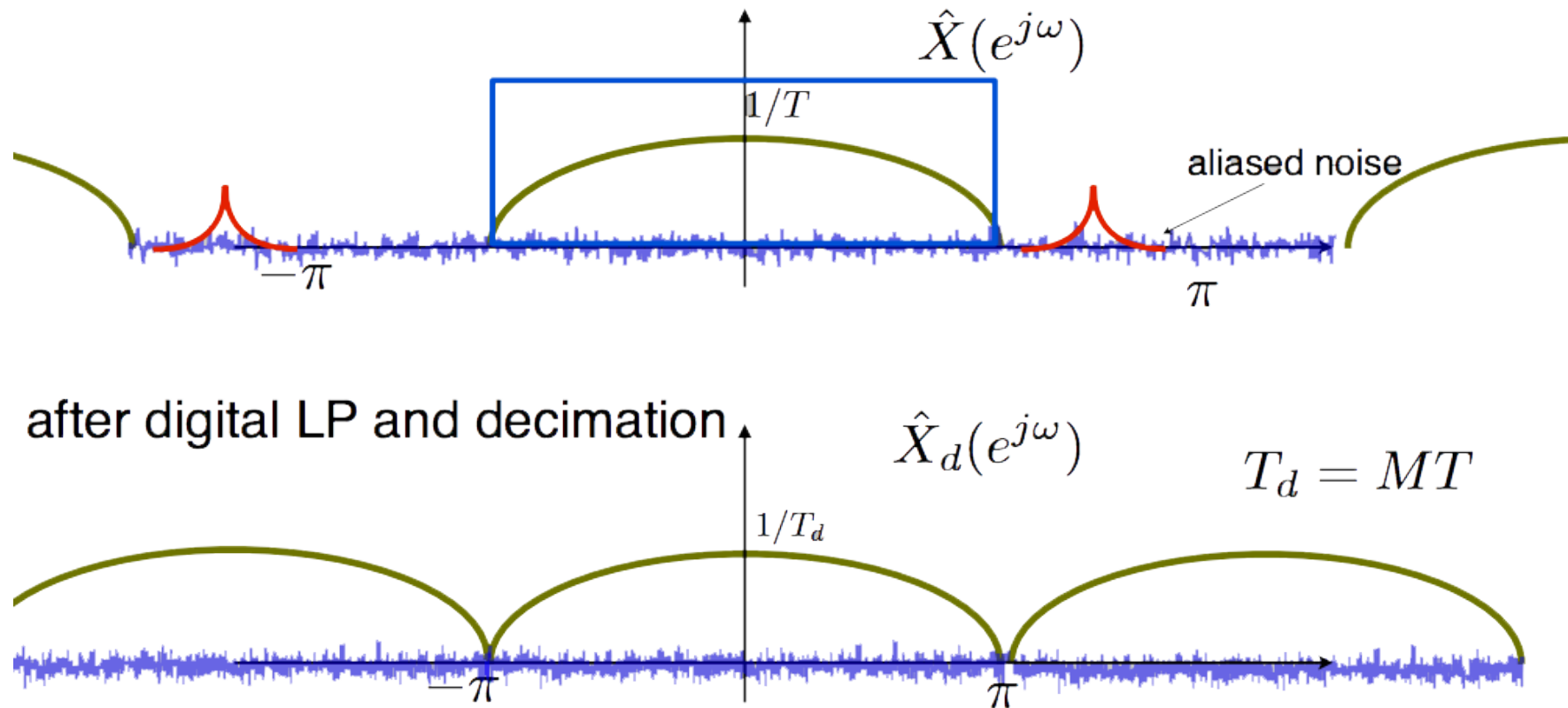
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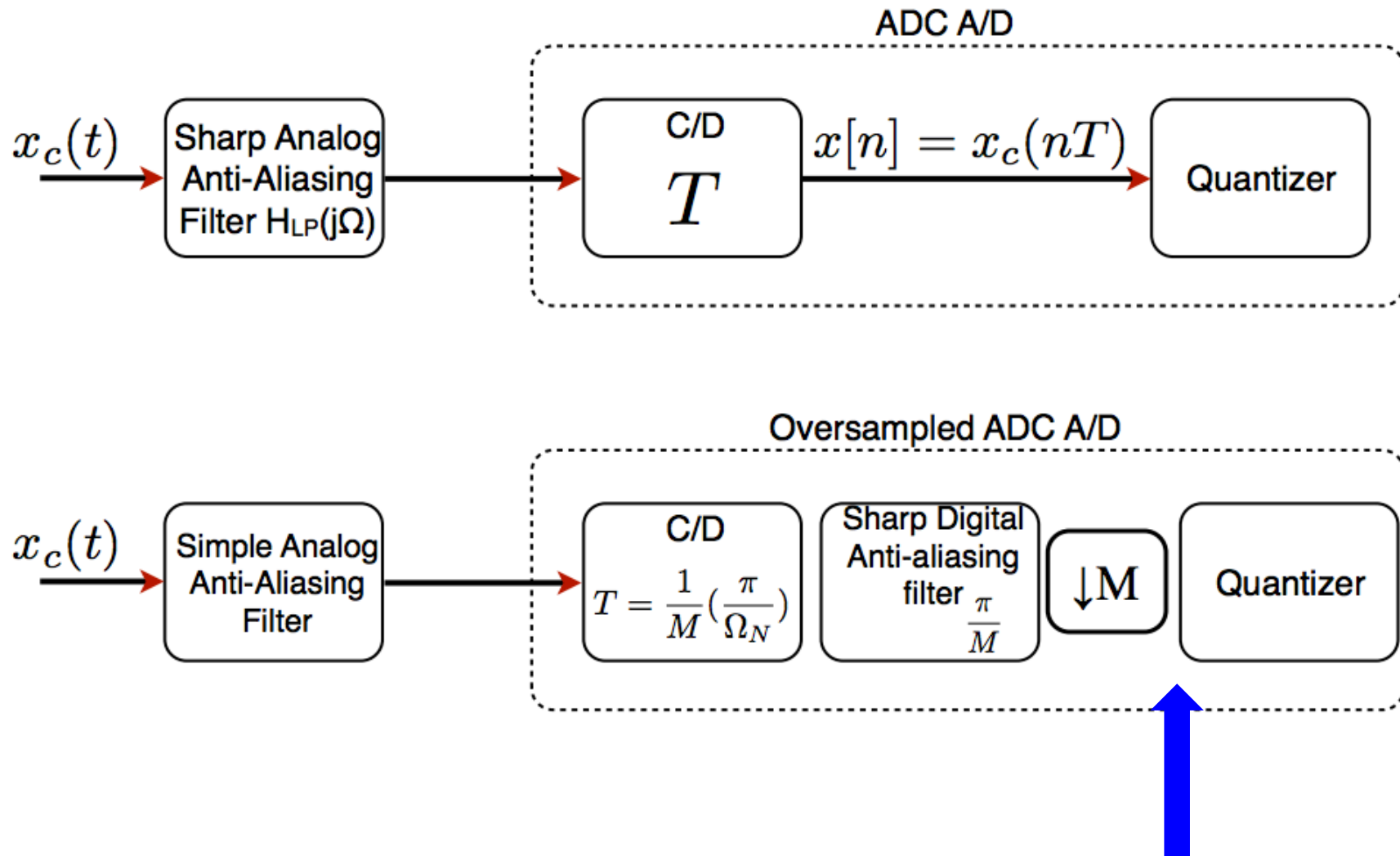
# Oversampled ADC – Sharp digital filter/Downsample



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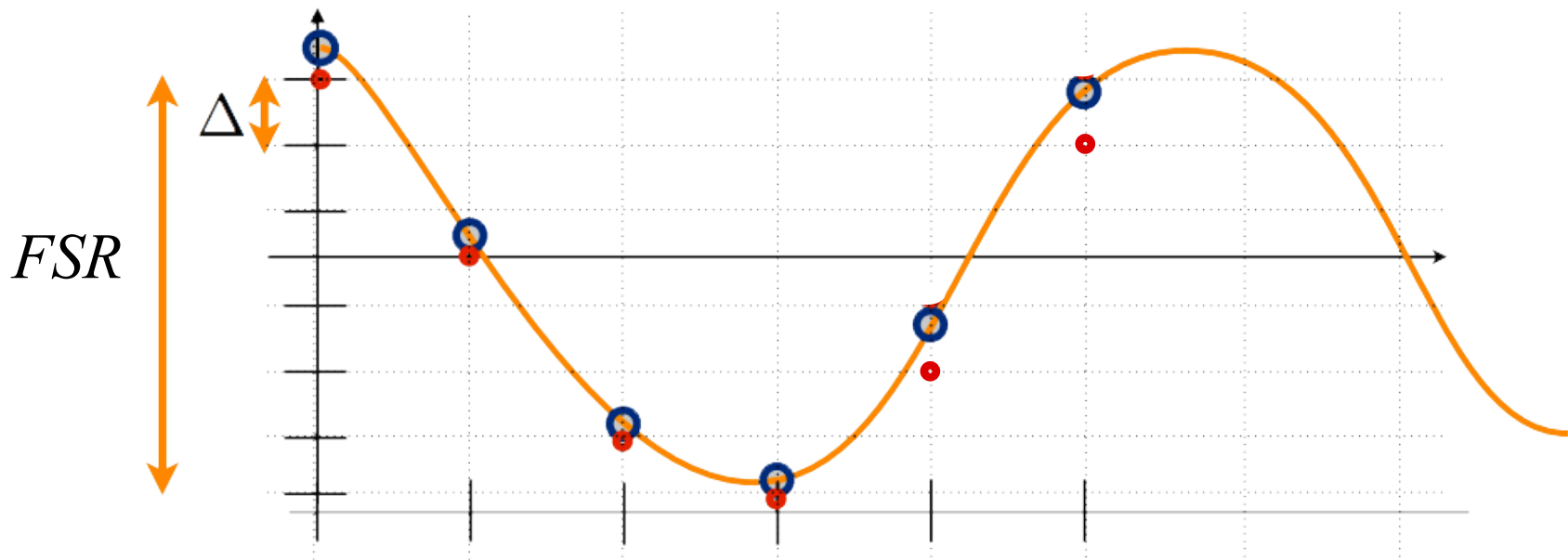
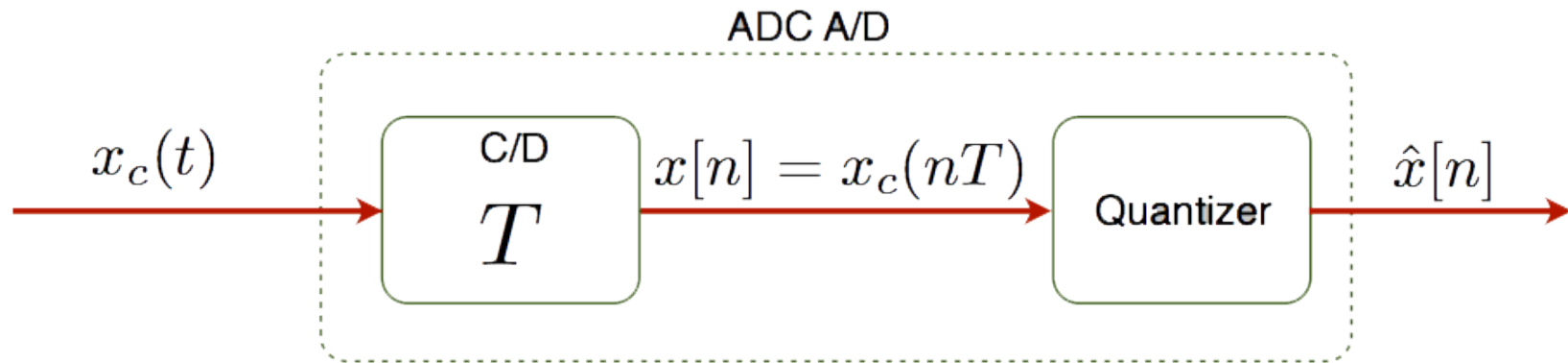


# Oversampled ADC





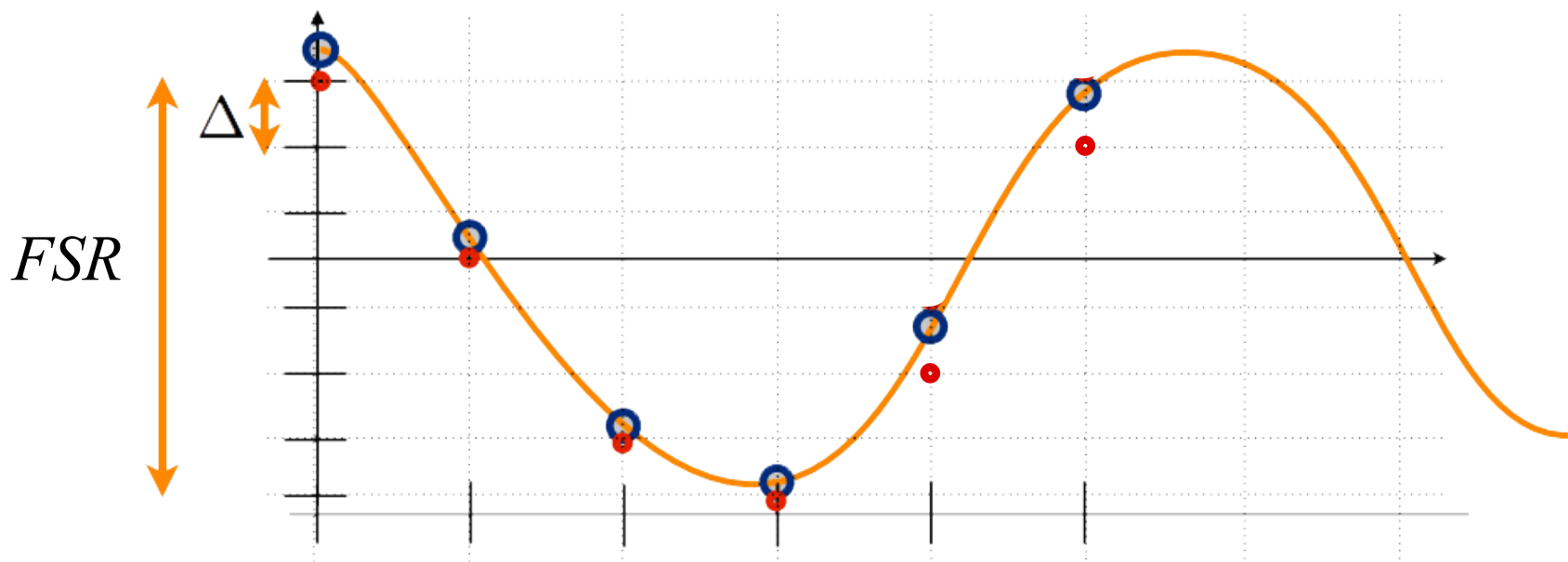
# Sampling and Quantization



# Sampling and Quantization

- For an input signal with  $V_{pp} = \text{FSR}$  with B bits

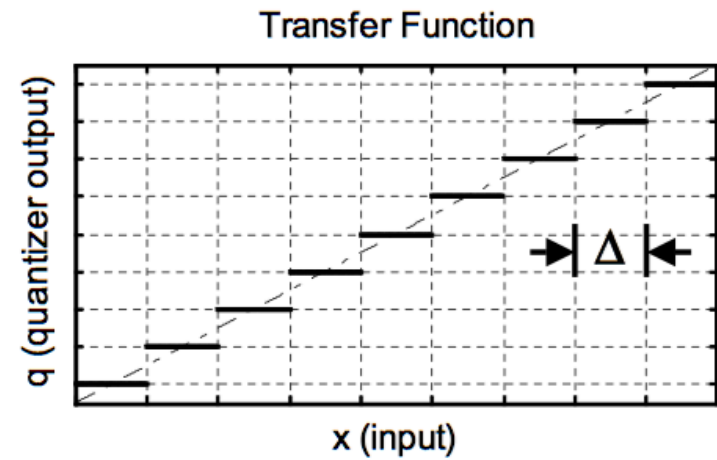
$$\Delta = \frac{\text{FSR}}{2^B}$$





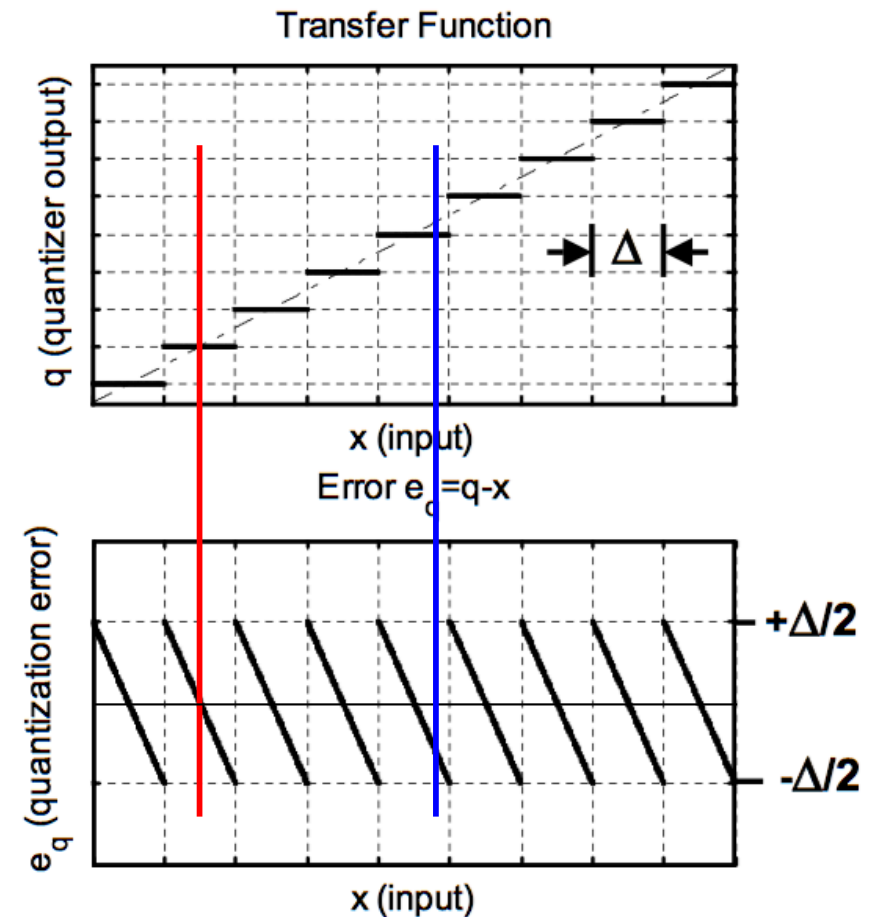
# Ideal Quantizer

- Quantization step  $\Delta$



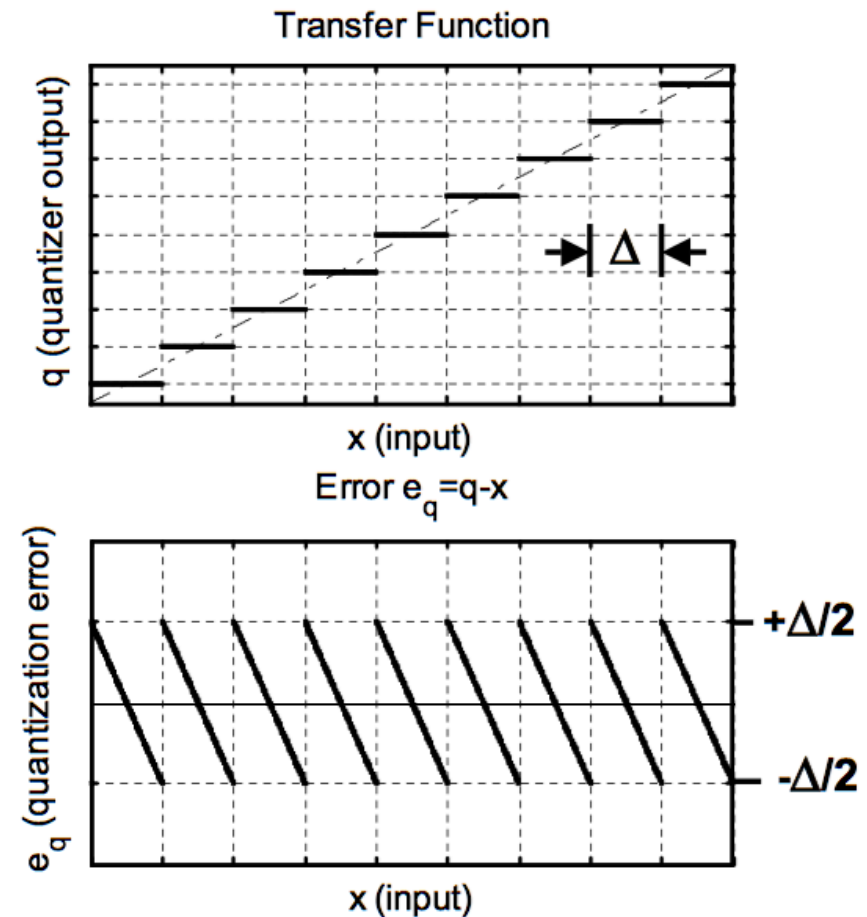
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- Quantization step  $\Delta$
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  - Bounded by  $-\Delta/2, +\Delta/2$



# Ideal Quantizer

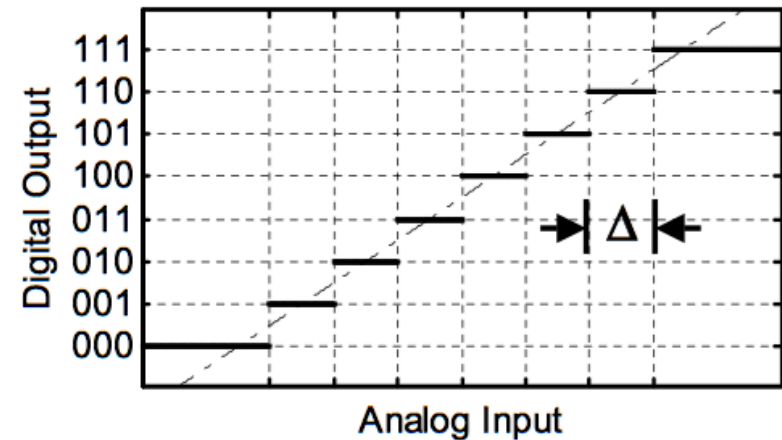
- Quantization step  $\Delta$
- Quantization error has sawtooth shape
  - Bounded by  $-\Delta/2, +\Delta/2$
- Ideally infinite input range and infinite number of quantization levels





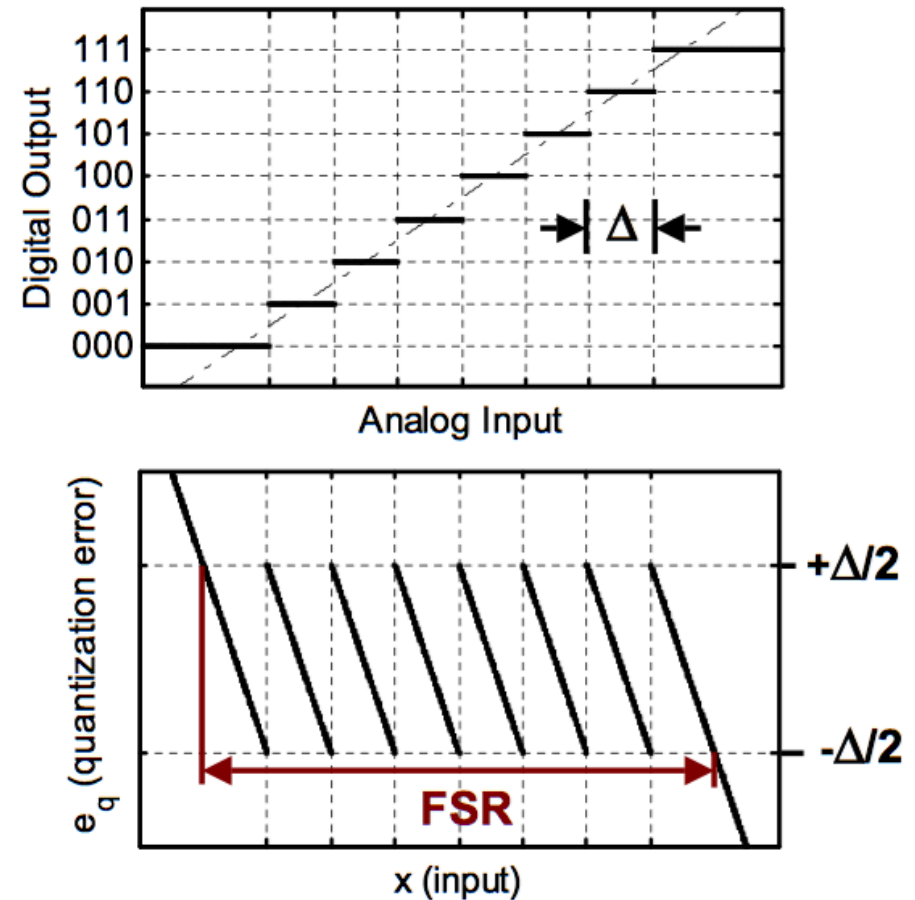
# Ideal B-bit Quantizer

- ❑ Practical quantizers have a limited input range and a finite set of output codes
- ❑ E.g. a 3-bit quantizer can map onto  $2^3=8$  distinct output codes



# Ideal B-bit Quantizer

- ❑ Practical quantizers have a limited input range and a finite set of output codes
- ❑ E.g. a 3-bit quantizer can map onto  $2^3=8$  distinct output codes
- ❑ Quantization error grows out of bounds beyond code boundaries
- ❑ We define the full scale range (FSR) as the maximum input range that satisfies  $|e_q| \leq \Delta/2$ 
  - Implies that  $\text{FSR} = 2^B \cdot \Delta$





# Effect of Quantization Error on Signal

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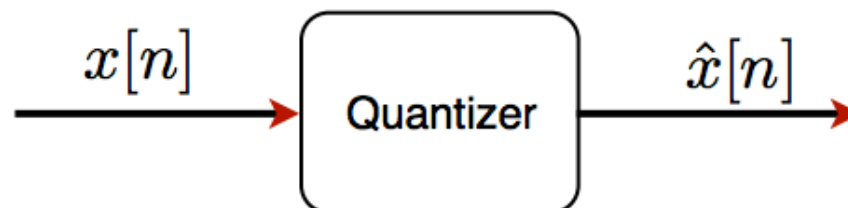
- ❑ Quantization error is a deterministic function of the signal
  - Consequently, the effect of quantization strongly depends on the signal itself
- ❑ Unless, we consider fairly trivial signals, a deterministic analysis is usually impractical
  - More common to look at errors from a statistical perspective
  - "Quantization noise"
- ❑ Two aspects
  - How much noise power (variance) does quantization add to our samples?
  - How is this noise distributed in frequency?





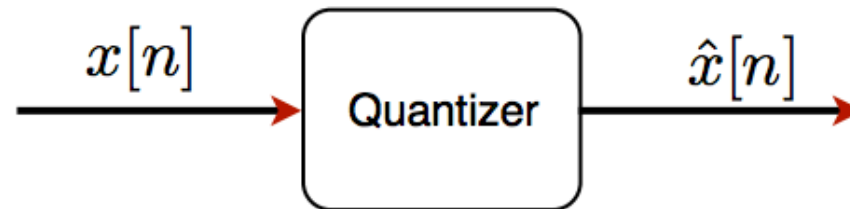
# Quantization Error

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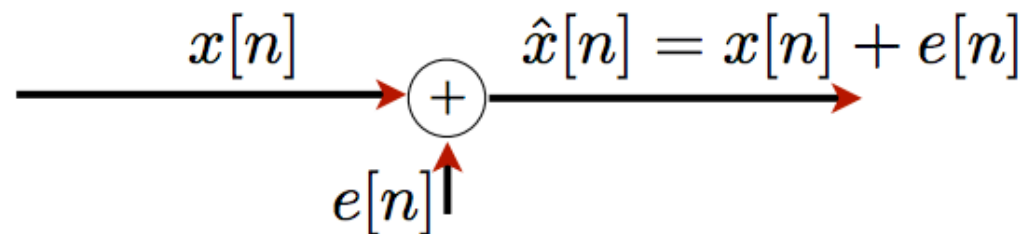


- ❑ Model quantization error as noise:

# Quantization Error



- ❑ Model quantization error as noise:

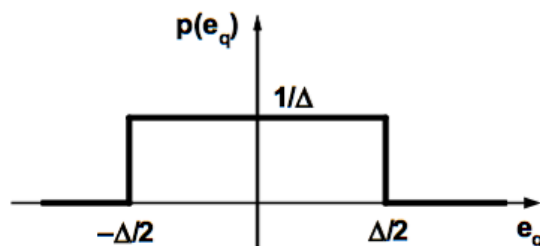


- ❑ In that case:

$$-\Delta/2 \leq e[n] < \Delta/2$$

# Quantization Error Statistics

- ❑ Crude assumption:  $e_q(x)$  has uniform probability density
- ❑ This approximation holds reasonably well in practice when
  - Signal spans large number of quantization steps
  - Signal is "sufficiently active"
  - Quantizer does not overload



**Mean**

$$\overline{e} = \int_{-\Delta/2}^{+\Delta/2} \frac{e}{\Delta} de = 0$$

**Variance**

$$\overline{e^2} = \int_{-\Delta/2}^{+\Delta/2} \frac{e^2}{\Delta} de = \frac{\Delta^2}{12}$$



# Noise Model for Quantization Error

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## □ Assumptions:

- Model  $e[n]$  as a sample sequence of a stationary random process
- $e[n]$  is not correlated with  $x[n]$
- $e[n]$  not correlated with  $e[m]$  where  $m \neq n$
- $e[n] \sim U[-\Delta/2, \Delta/2]$  (uniform pdf)

## □ Result:

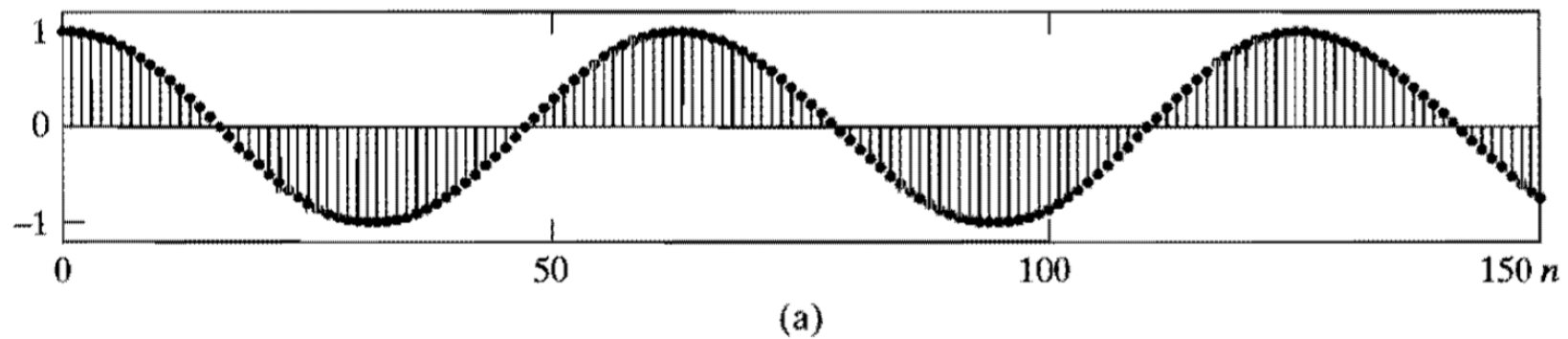
□ Variance is:  $\sigma_e^2 = \frac{\Delta^2}{12}$

- Assumptions work well for signals that change rapidly, are not clipped, and for small  $\Delta$



# Quantization Noise

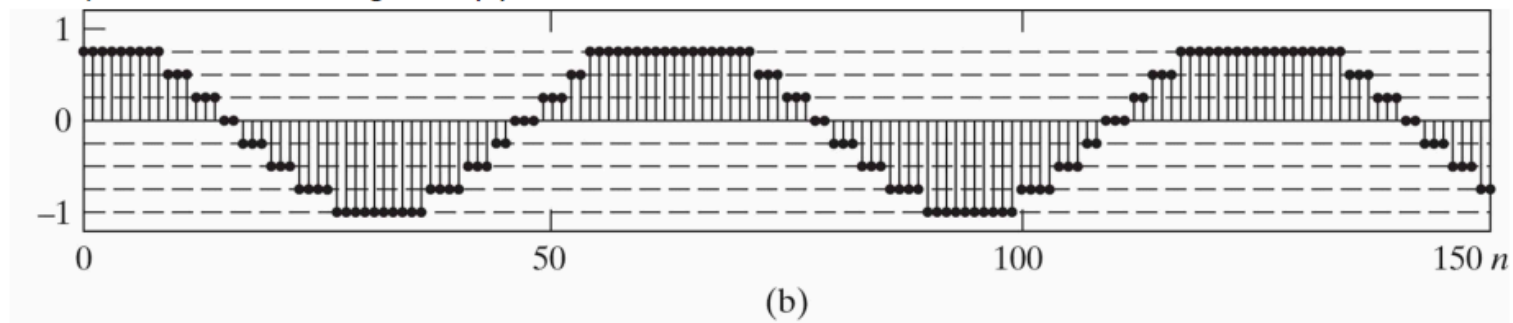
- **Figure 4.57** Example of quantization noise. (a) Unquantized samples of the signal  $x[n] = 0.99\cos(n/10)$ .





# Quantization Noise

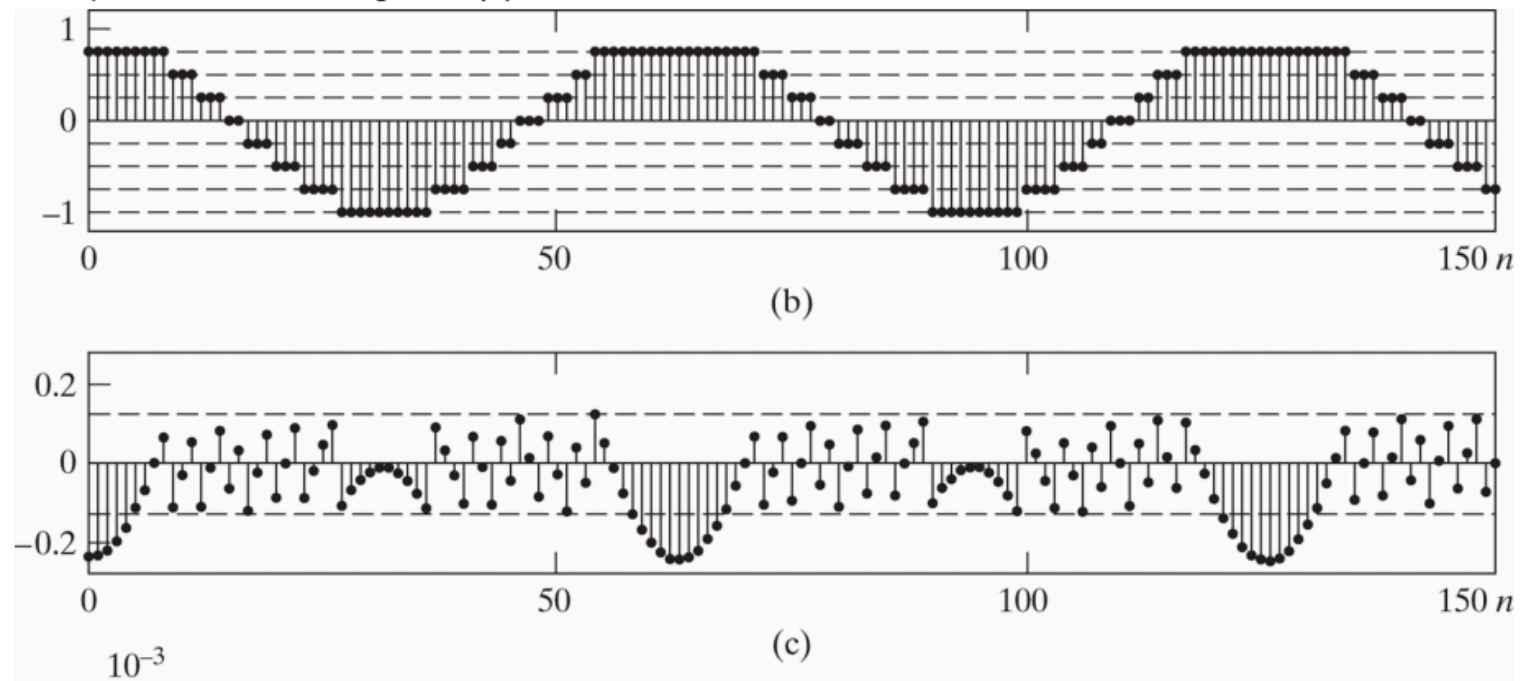
- Figure 4.57(continued) (b) Quantized samples of the cosine waveform in part (a) with a 3-bit quantizer.





# Quantization Noise

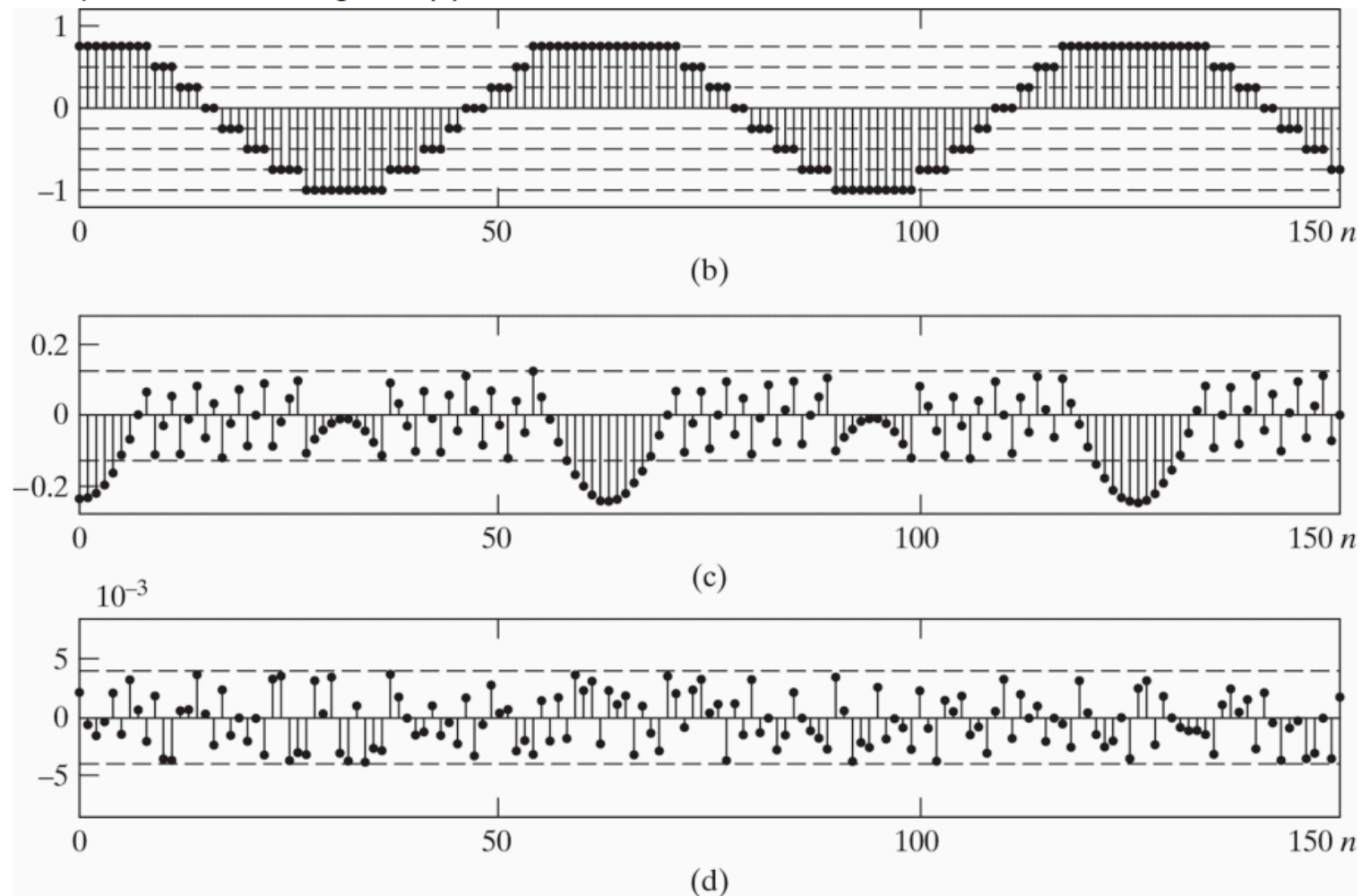
- **Figure 4.57**(continued) (b) Quantized samples of the cosine waveform in part (a) with a 3-bit quantizer. (c) Quantization error sequence for 3-bit quantization of the signal in (a).





# Quantization Noise

- **Figure 4.57**(continued) (b) Quantized samples of the cosine waveform in part (a) with a 3-bit quantizer. (c) Quantization error sequence for 3-bit quantization of the signal in (a). (d) Quantization error sequence for 8-bit quantization of the signal in (a).







# Signal-to-Quantization-Noise Ratio

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- For uniform B bits quantizer

$$SNR_Q = 10 \log_{10} \left( \frac{\sigma_x^2}{\sigma_e^2} \right)$$

# Signal-to-Quantization-Noise Ratio

- For uniform B bits quantizer

$$\begin{aligned} SNR_Q &= 10 \log_{10} \left( \frac{\sigma_x^2}{\sigma_e^2} \right) \\ &= 10 \log_{10} \left( \frac{12 \cdot 2^{2B} \sigma_x^2}{FSR^2} \right) \end{aligned}$$

$$SNR_Q = 6.02B + 10.8 - 20 \log_{10} \left( \frac{FSR}{\sigma_x} \right) \begin{matrix} \text{Quantizer range} \\ \text{rms of amp} \end{matrix}$$

# Signal-to-Quantization-Noise Ratio

---

$$\text{SNR}_Q = 6.02B + 10.8 - 20 \log_{10} \left( \frac{\text{Quantizer range}}{\sigma_x \text{ rms of amp}} \right)$$

- ❑ Improvement of 6dB with every bit
- ❑ The range of the quantization must be adapted to the rms amplitude of the signal
  - Tradeoff between clipping and noise!
  - Often use pre-amp
  - Sometimes use analog auto gain controller (AGC)

# Signal-to-Quantization-Noise Ratio

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- Assuming full-scale sinusoidal input, we have

$$\text{SNR}_Q = 6.02B + 10.8 - 20 \log_{10} \left( \frac{\text{Quantizer range}}{\sigma_x \text{ rms of amp}} \right)$$



# Signal-to-Quantization-Noise Ratio

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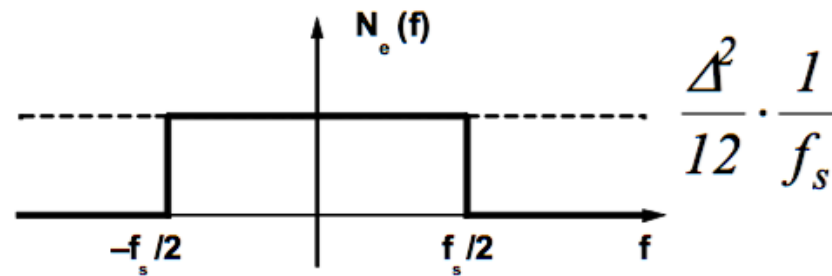
- Assuming full-scale sinusoidal input, we have

$$\text{SNR}_Q = 6.02B + 1.76 \text{ dB}$$

<b>B (Number of Bits)</b>	<b>SQNR</b>
8	50dB
12	74dB
16	98dB
20	122dB

# Quantization Noise Spectrum

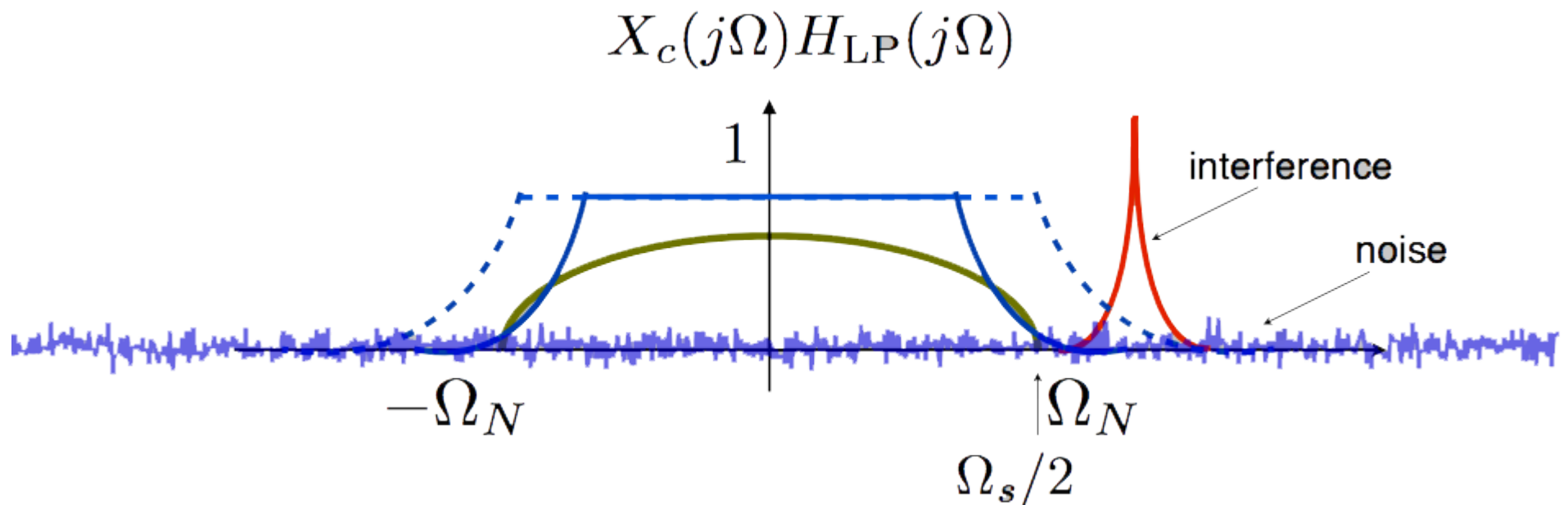
- If the quantization error is "sufficiently random", it also follows that the noise power is uniformly distributed in frequency



## References

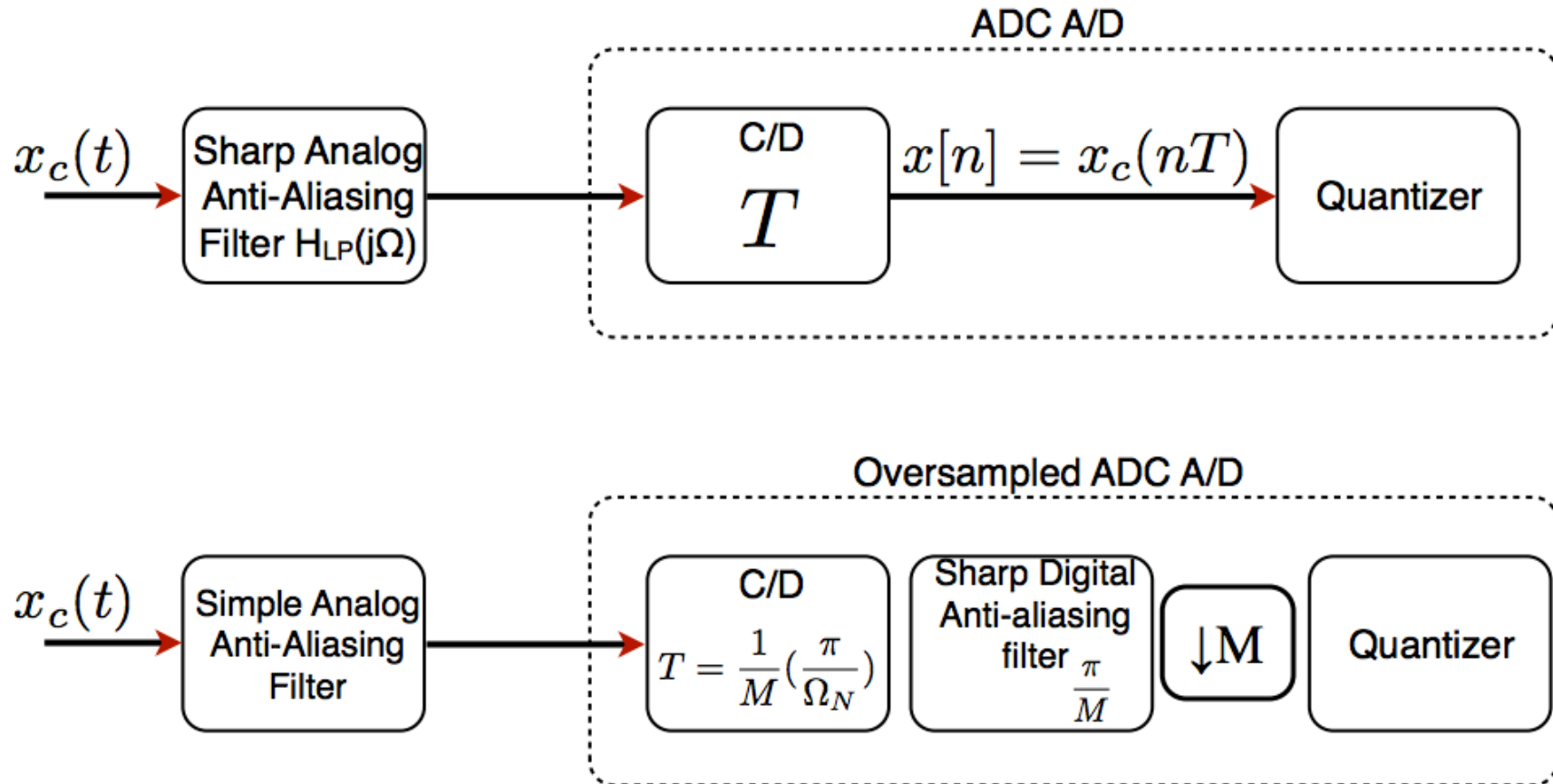
- W. R. Bennett, "Spectra of quantized signals," Bell Syst. Tech. J., pp. 446-72, July 1988.
- B. Widrow, "A study of rough amplitude quantization by means of Nyquist sampling theory," IRE Trans. Circuit Theory, vol. CT-3, pp. 266-76, 1956.

# Non-Ideal Anti-Aliasing Filter



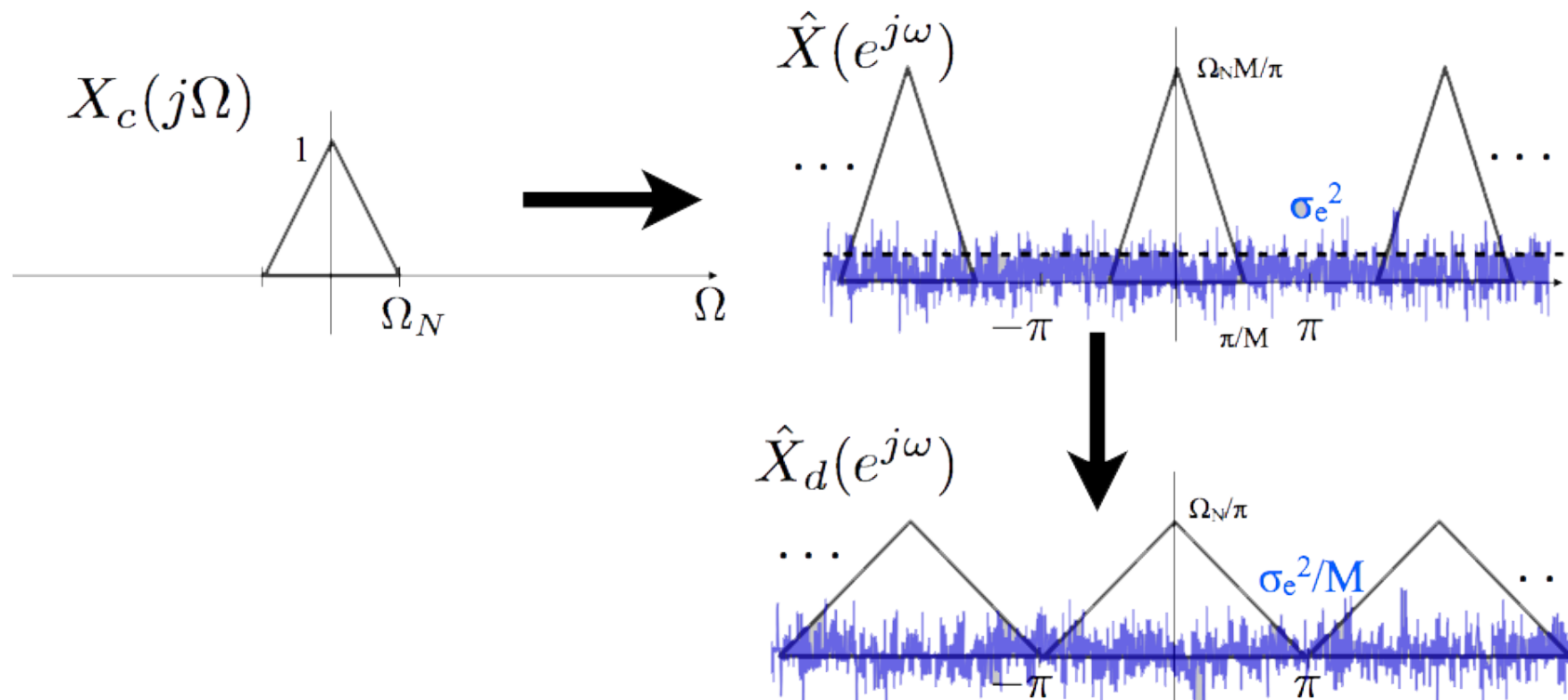
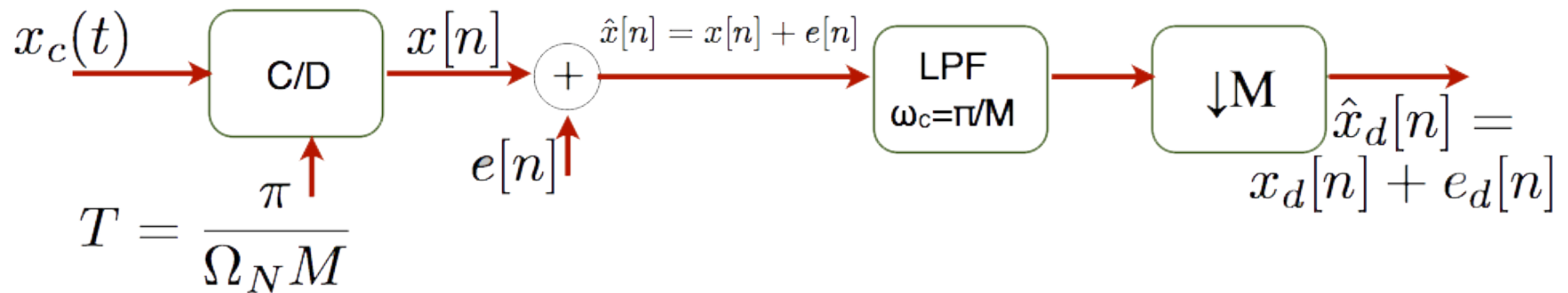
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- ❑ Consequence: Crop part of the signal and suffer from noise and interference

# Oversampled ADC





# Quantization Noise with Oversampling



# Quantization Noise with Oversampling

- ❑ Energy of  $x_d[n]$  equals energy of  $x[n]$ 
  - No filtering of signal!
- ❑ Noise variance is reduced by factor of  $M$

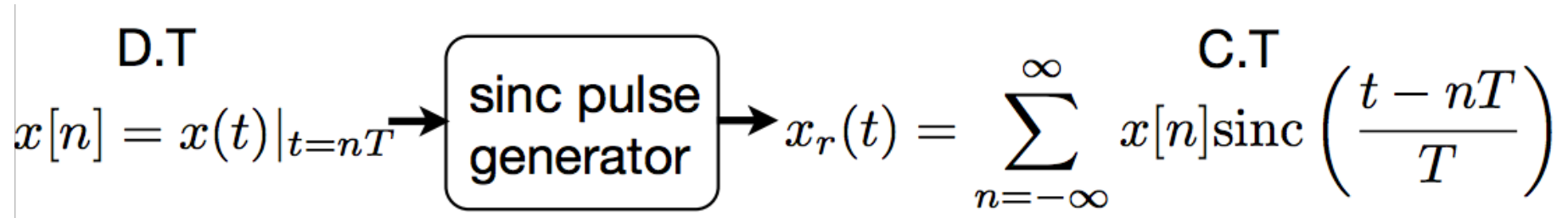
$$\text{SNR}_Q = 6.02B + 10.8 - 20 \log_{10} \left( \frac{FSR}{\sigma_x} \right) + 10 \log_{10} M$$

- ❑ For doubling of  $M$  we get 3dB improvement, which is the same as 1/2 a bit of accuracy
  - With oversampling of 16 with 8bit ADC we get the same quantization noise as 10bit ADC!

# Practical DAC

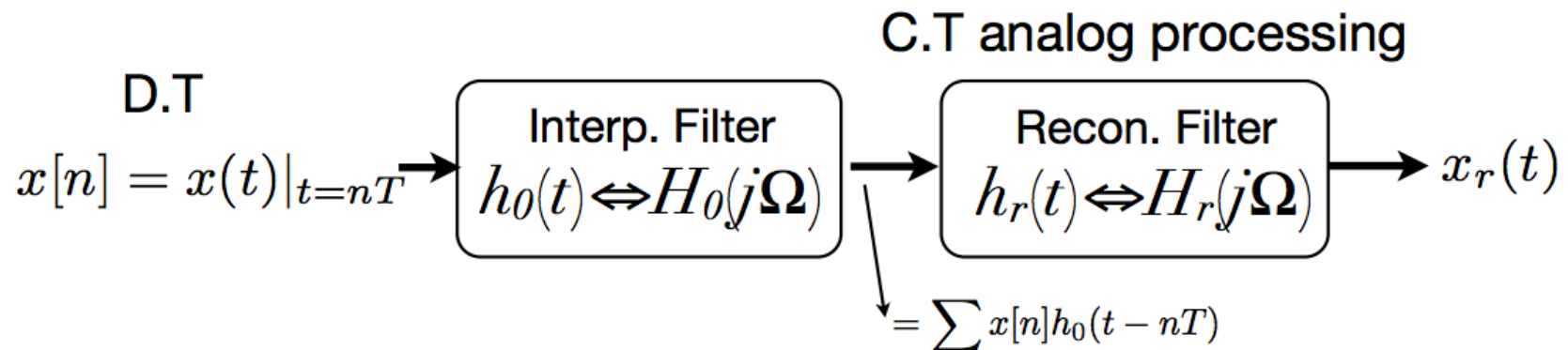
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# Practical DAC

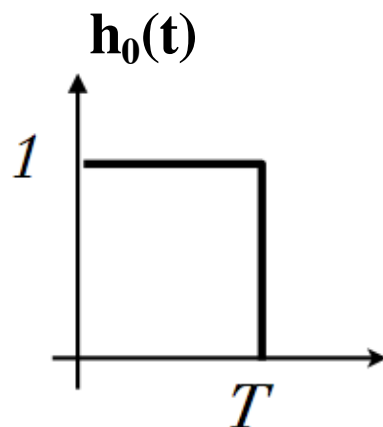


- ❑ Scaled train of sinc pulses
- ❑ Difficult to generate sinc  $\rightarrow$  Too long!

# Practical DAC



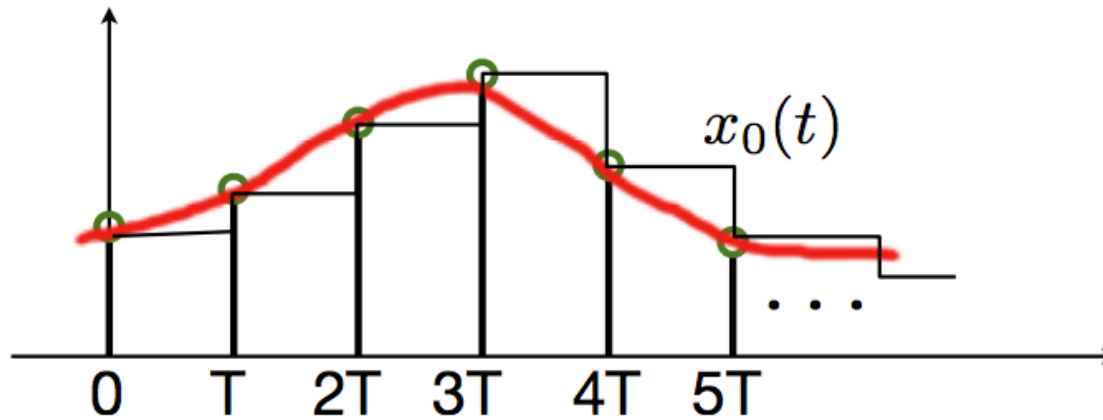
- ❑  $h_0(t)$  is finite length pulse  $\rightarrow$  easy to implement
- ❑ For example: zero-order hold



$$H_0(j\Omega) = T e^{-j\Omega \frac{T}{2}} \text{sinc}\left(\frac{\Omega}{\Omega_s}\right)$$

# Practical DAC

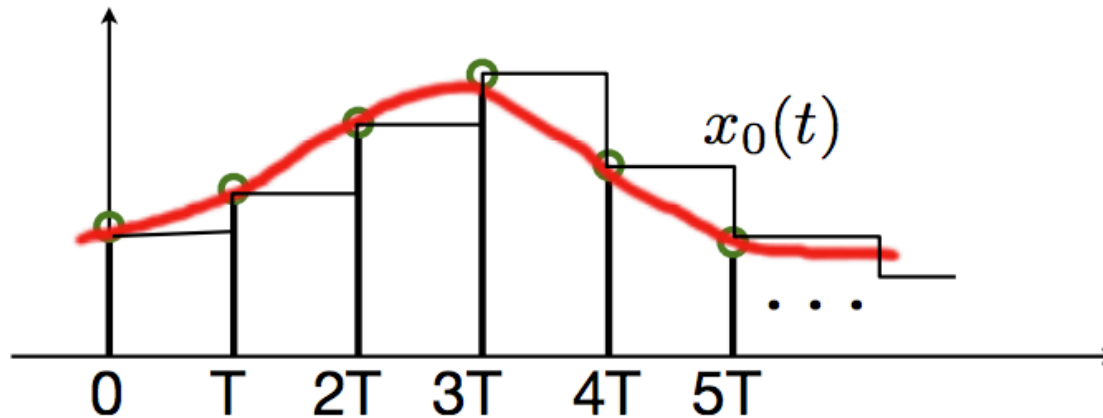
Zero-Order-Hold interpolation



$$x_0(t) = \sum_{n=-\infty}^{\infty} x[n]h_0(t - nT) = h_0(t) * x_s(t)$$

# Practical DAC

## Zero-Order-Hold interpolation



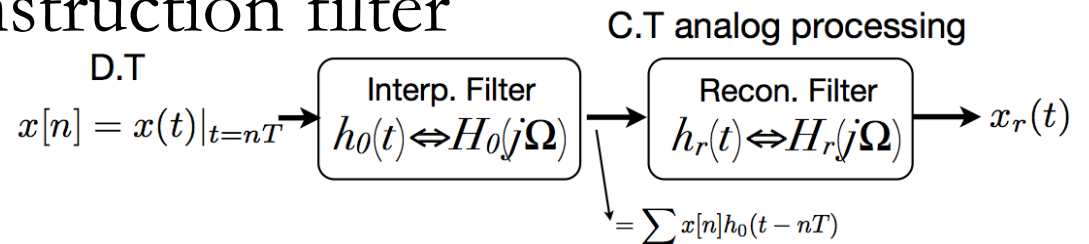
$$x_0(t) = \sum_{n=-\infty}^{\infty} x[n]h_0(t - nT) = h_0(t) * x_s(t)$$

Taking a FT:

$$\begin{aligned} X_0(j\Omega) &= H_0(j\Omega)X_s(j\Omega) \\ &= H_0(j\Omega)\frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(\Omega - k\Omega_s)) \end{aligned}$$

# Practical DAC

## □ Output of the reconstruction filter

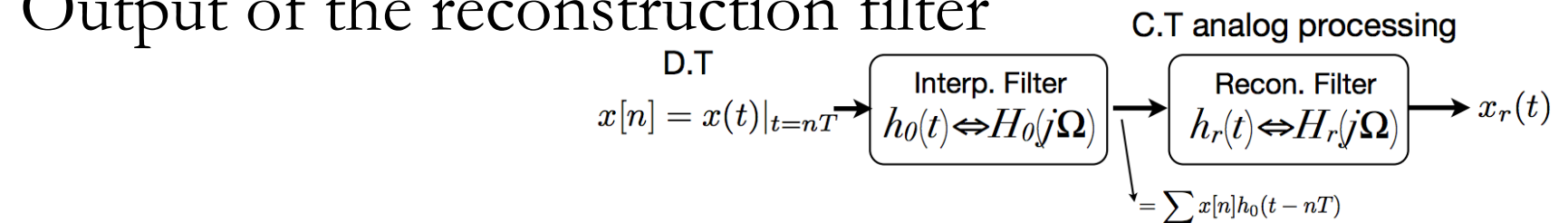


$$X_r(j\Omega) = H_r(j\Omega) \cdot H_0(j\Omega) \cdot X_s(j\Omega)$$



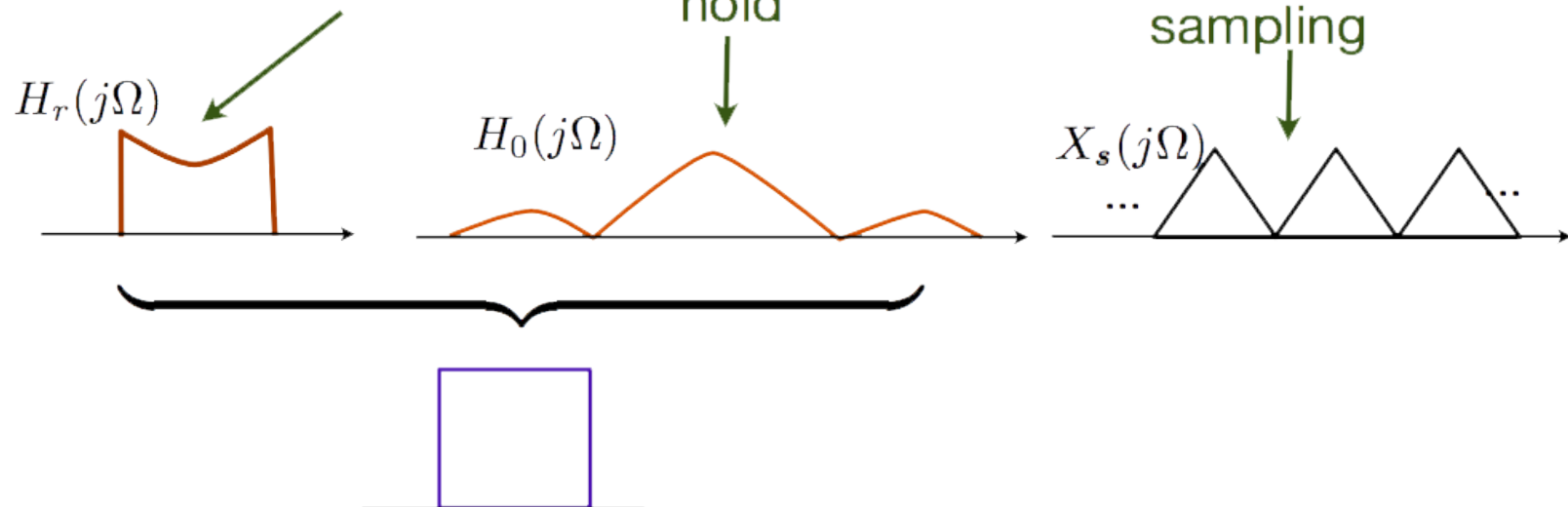
# Practical DAC

## □ Output of the reconstruction filter



$$X_r(j\Omega) = H_r(j\Omega) \cdot H_0(j\Omega) \cdot X_s(j\Omega)$$

$$= \underbrace{H_r(j\Omega)}_{\text{recon filter}} \cdot \underbrace{T e^{-j\Omega \frac{T}{2}} \text{sinc}\left(\frac{\Omega}{\Omega_s}\right)}_{\text{from zero-order hold}} \cdot \underbrace{\frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(\Omega - k\Omega_s))}_{\text{Shifted copies from sampling}}$$

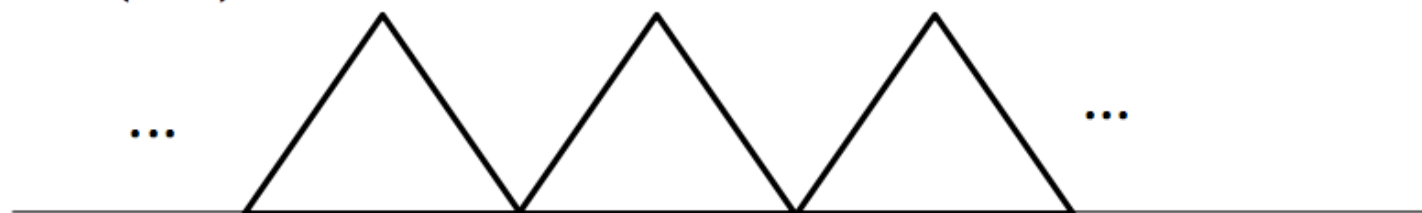




# Practical DAC

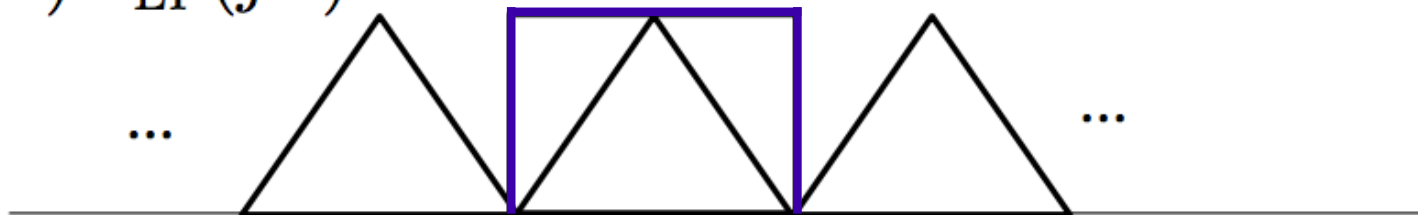
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$$X_s(j\Omega)$$



Ideally:

$$X_s(j\Omega)H_{LP}(j\Omega)$$

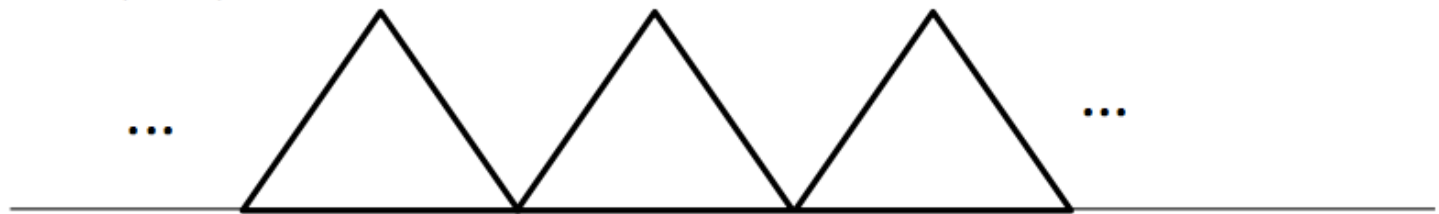




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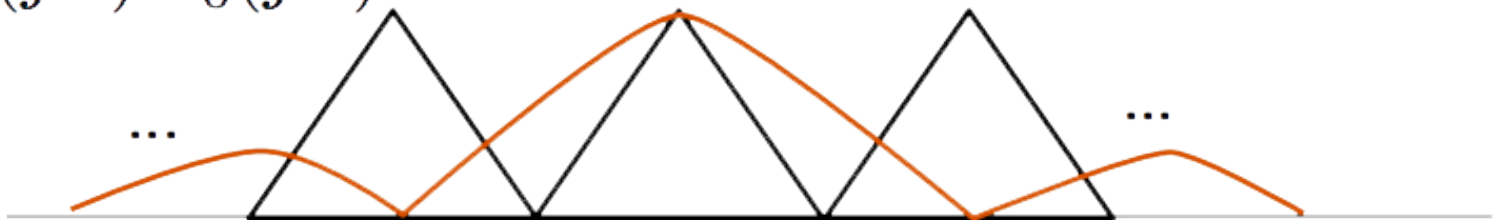
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$$X_s(j\Omega)$$



Practically:

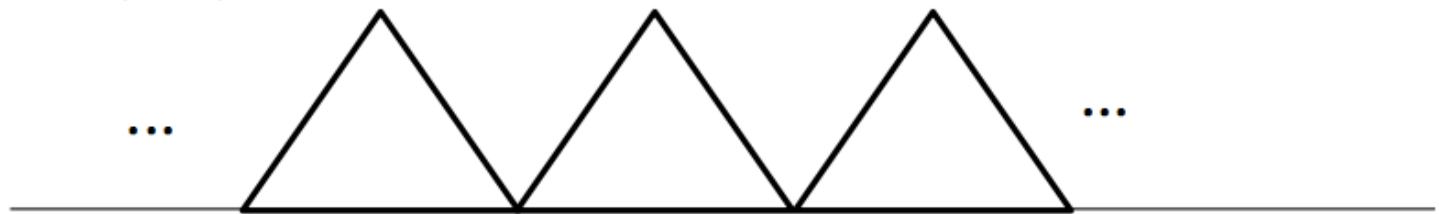
$$X_s(j\Omega)H_0(j\Omega)$$





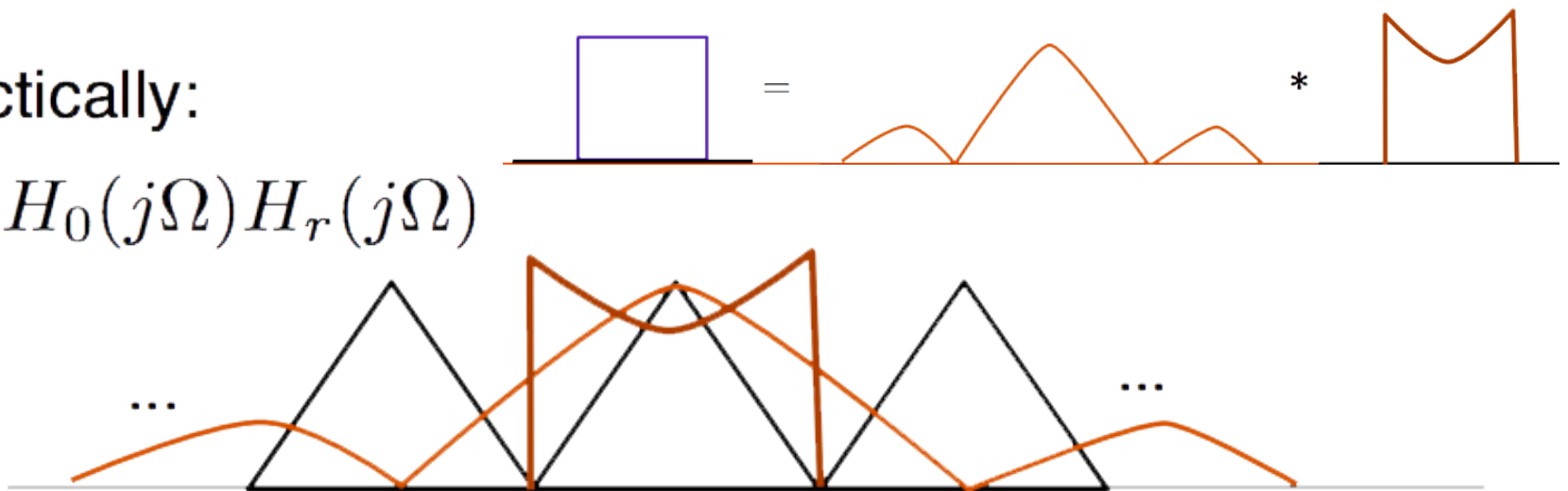
# Practical DAC

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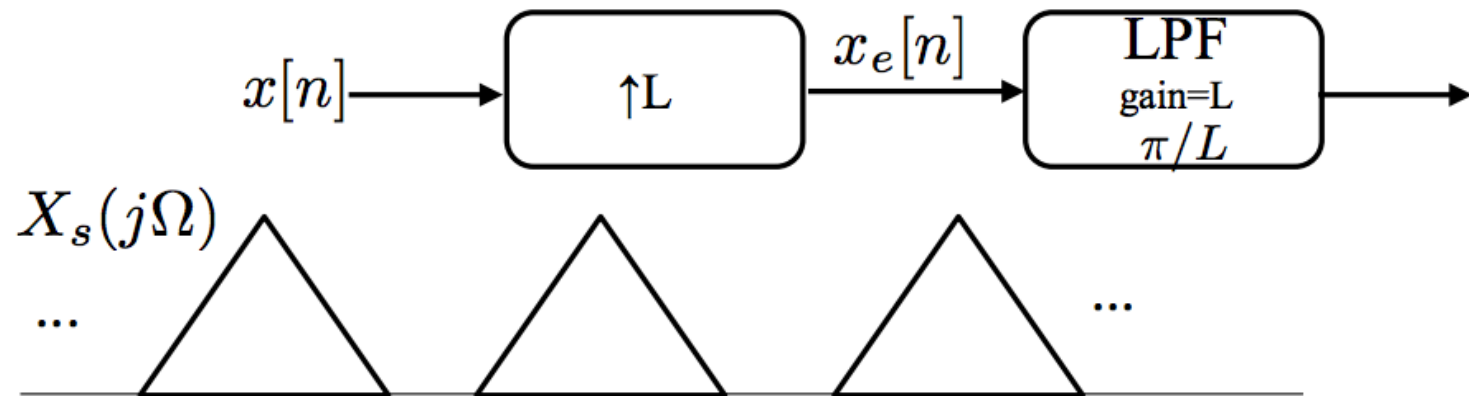


Practically:

$$X_s(j\Omega)H_0(j\Omega)H_r(j\Omega)$$

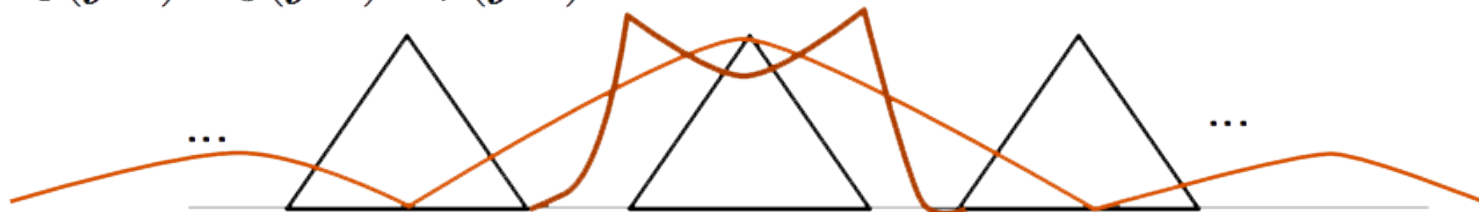


# Practical DAC with Upsampling



Practically:

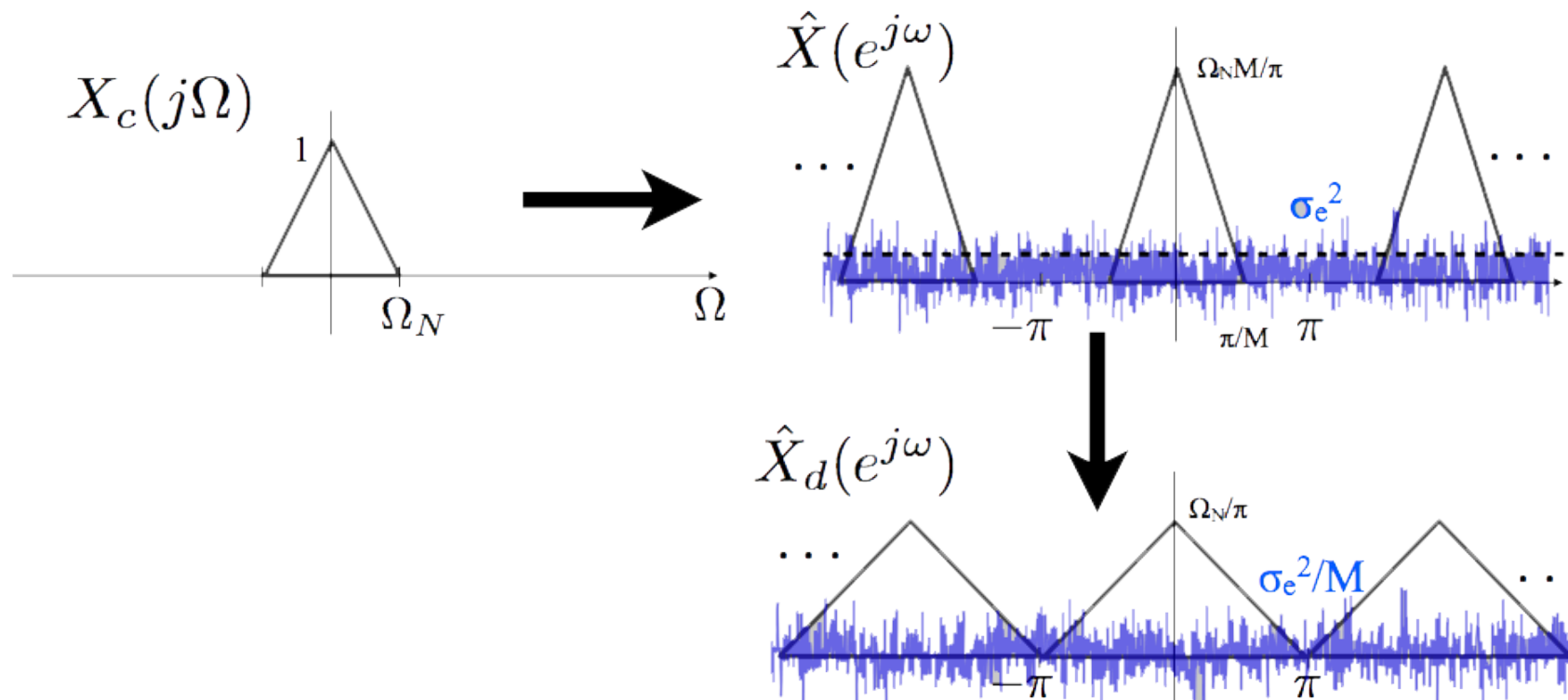
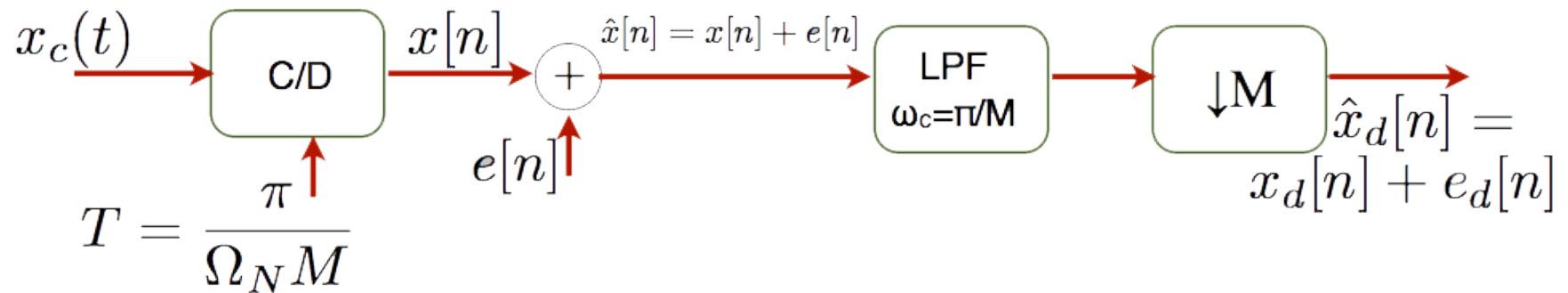
$$X_s(j\Omega) H_0(j\Omega) H_r(j\Omega)$$



# Noise Shaping

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# Quantization Noise with Oversampling



# Quantization Noise with Oversampling

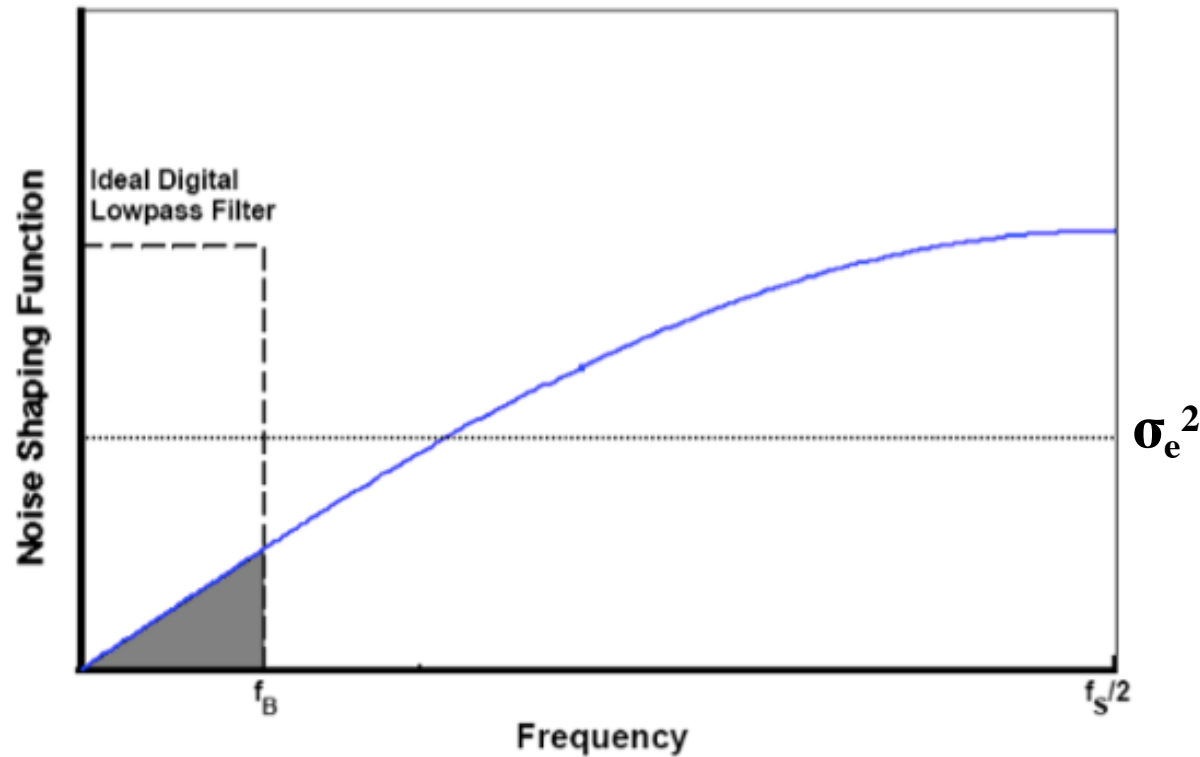
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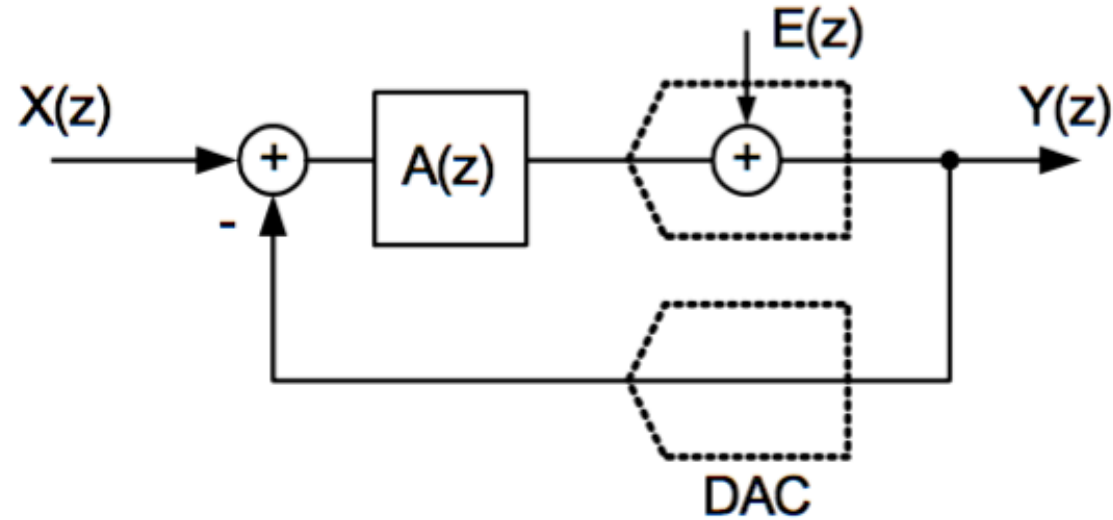


# Noise Shaping

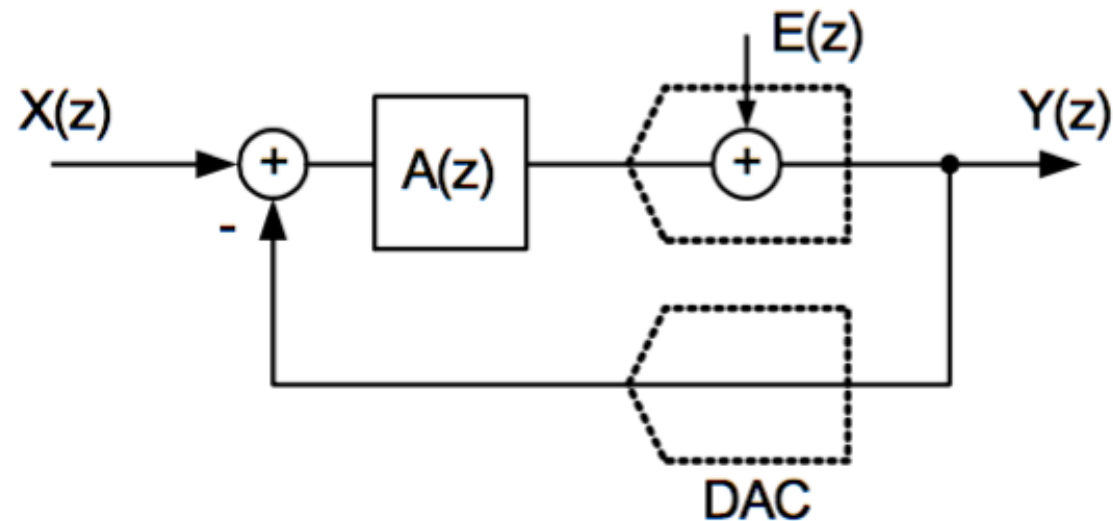


- ❑ Idea: "Somehow" build an ADC that has most of its quantization noise at high frequencies
- ❑ Key: Feedback

# Noise Shaping Using Feedback



# Noise Shaping Using Feedback



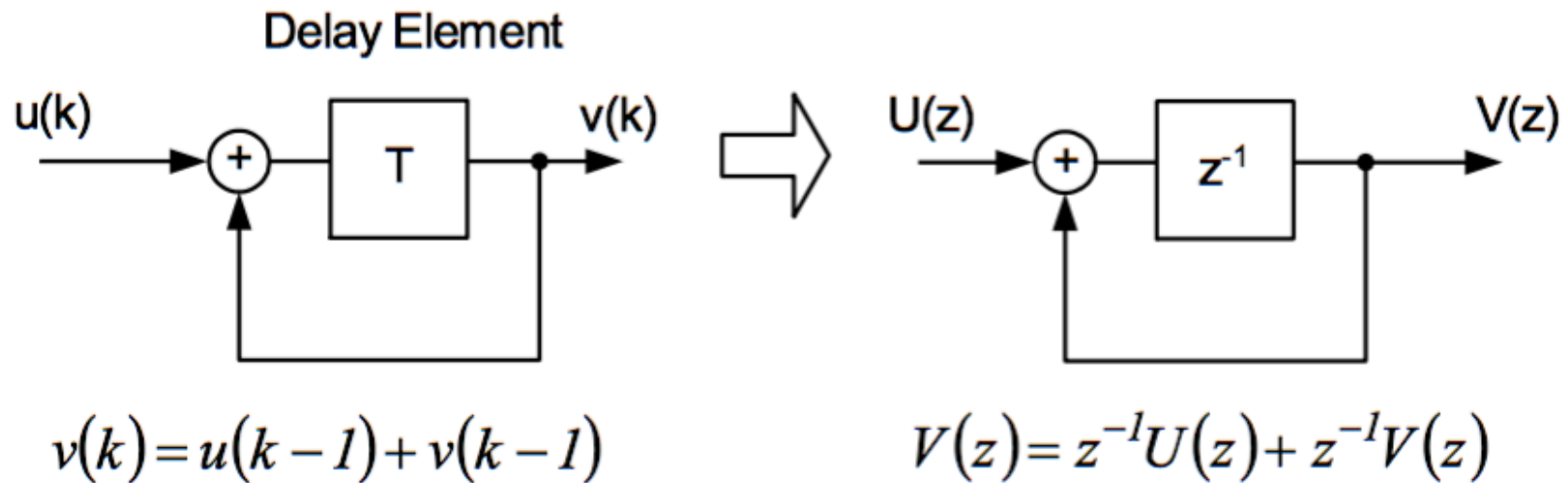
$$\begin{aligned} Y(z) &= E(z) + A(z)X(z) - A(z)Y(z) \\ &= E(z) \frac{1}{1 + A(z)} + X(z) \frac{A(z)}{1 + A(z)} \\ &= E(z) \underbrace{H_E(z)}_{\text{Noise Transfer Function}} + X(z) \underbrace{H_X(z)}_{\text{Signal Transfer Function}} \end{aligned}$$

# Noise Shaping Using Feedback

$$Y(z) = E(z) \underbrace{\frac{1}{1 + A(z)}}_{\text{Noise Transfer Function}} + X(z) \underbrace{\frac{A(z)}{1 + A(z)}}_{\text{Signal Transfer Function}}$$

- ❑ Objective
  - Want to make STF unity in the signal frequency band
  - Want to make NTF "small" in the signal frequency band
- ❑ If the frequency band of interest is around DC ( $0 \dots f_B$ ) we achieve this by making  $|A(z)| \gg 1$  at low frequencies
  - Means that  $\text{NTF} \ll 1$
  - Means that  $\text{STF} \cong 1$

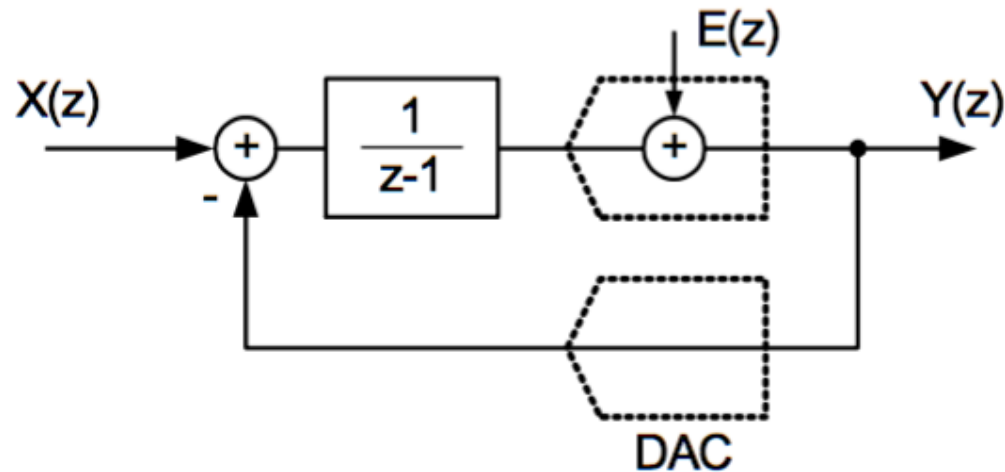
# Discrete Time Integrator



$$\frac{V(z)}{U(z)} = \frac{z^{-1}}{1 - z^{-1}} = \frac{1}{z - 1} \quad z = e^{j\omega T}$$

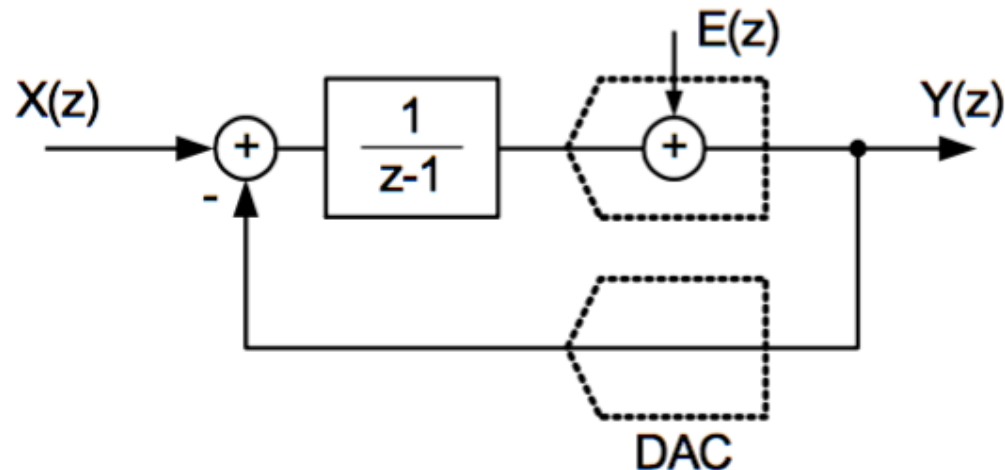
❑ "Infinite gain" at DC ( $\omega=0$ ,  $z=1$ )

# First Order Sigma-Delta Modulator



$$Y(z) = E(z) \frac{1}{1 + \frac{1}{z-1}} + X(z) \frac{\frac{1}{z-1}}{1 + \frac{1}{z-1}}$$

# First Order Sigma-Delta Modulator



$$Y(z) = E(z) \frac{1}{1 + \frac{1}{z-1}} + X(z) \frac{\frac{1}{z-1}}{1 + \frac{1}{z-1}}$$
$$= E(z)(1 - z^{-1}) + X(z)z^{-1}$$

- ❑ Output is equal to delayed input plus filtered quantization noise



# NTF Frequency Domain Analysis

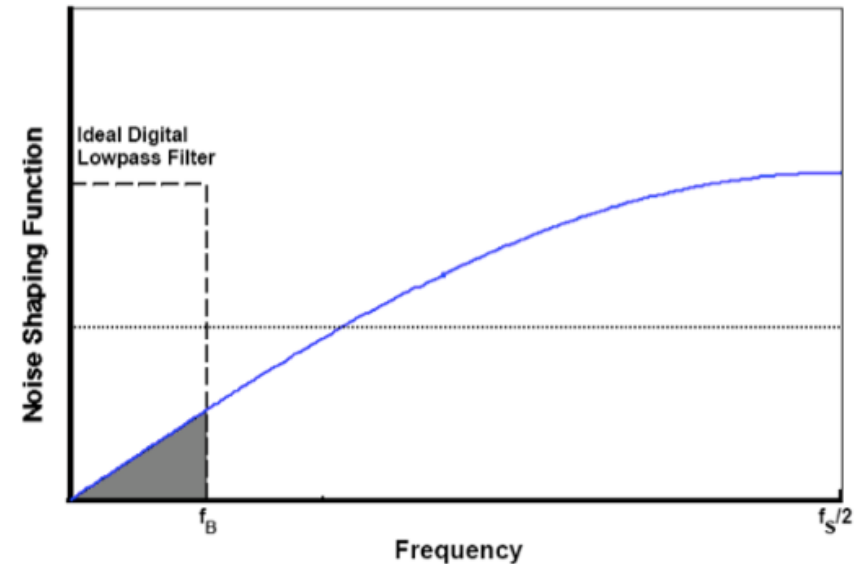
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$$H_e(z) = 1 - z^{-1}$$



# NTF Frequency Domain Analysis

$$\begin{aligned}H_e(z) &= 1 - z^{-1} \\H_e(j\omega) &= (1 - e^{-j\omega T}) = 2e^{-j\omega T/2} \left( \frac{e^{j\omega T/2} - e^{-j\omega T/2}}{2} \right) \\&= 2e^{-j\frac{\omega T}{2}} \left( j \sin\left(\frac{\omega T}{2}\right) \right) = 2 \sin\left(\frac{\omega T}{2}\right) e^{-j\frac{\omega T - \pi}{2}} \\|H_e(f)| &= 2 \left| \sin(\pi f T) \right| = 2 \left| \sin\left(\pi \frac{f}{f_s}\right) \right|\end{aligned}$$

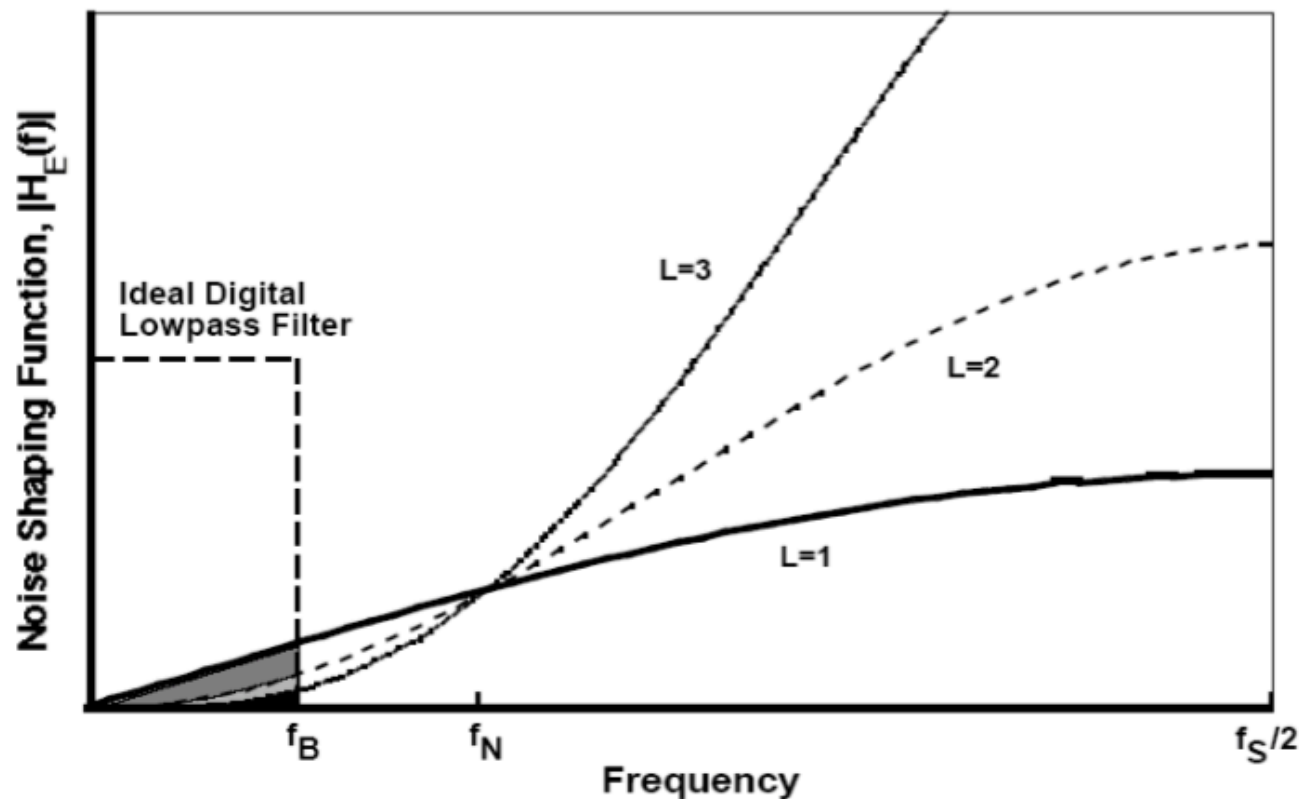


- ❑ "First order noise Shaping"
  - Quantization noise is attenuated at low frequencies, amplified at high frequencies

# Higher Order Noise Shaping

- $L^{\text{th}}$  order noise transfer function

$$H_E(z) = (1 - z^{-1})^L$$





# Big Ideas

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- ❑ Quantizers
  - Introduces quantization noise
- ❑ Data Converters
  - Oversampling to reduce interference and quantization noise → increase ENOB (effective number of bits)
  - Practical DACs use practical interpolation and reconstruction filters with oversampling
- ❑ Noise Shaping
  - Use feedback to reduce oversampling factor