

ESE 531: Digital Signal Processing

Week 9

Lecture 16: March 14th, 2021

Min Phase Decomposition



Lecture Outline

- Minimum Phase Systems

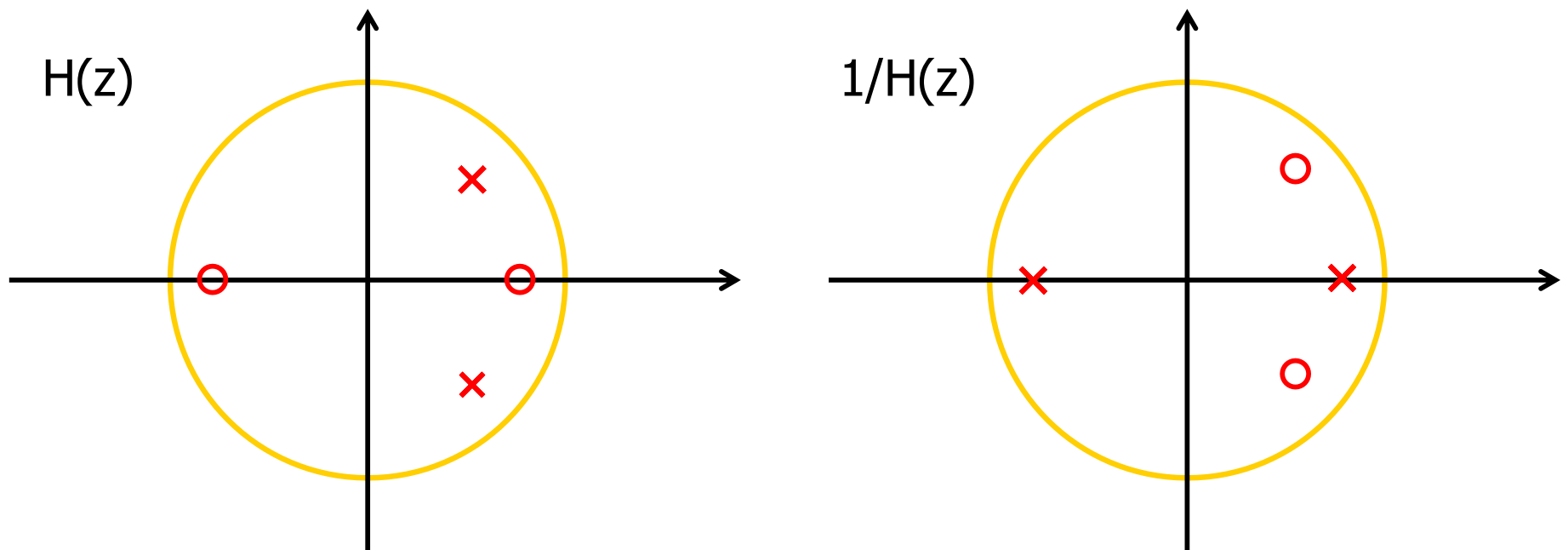


Minimum-Phase Systems

- Definition: A stable and causal system $H(z)$ (i.e. poles inside unit circle) whose inverse $1/H(z)$ is also stable and causal (i.e. zeros inside unit circle)

Minimum-Phase Systems

- Definition: A stable and causal system $H(z)$ (i.e. poles inside unit circle) whose inverse $1/H(z)$ is also stable and causal (i.e. zeros inside unit circle)
 - All poles and zeros inside unit circle





All-Pass Min-Phase Decomposition

- Any stable, causal system can be decomposed to:

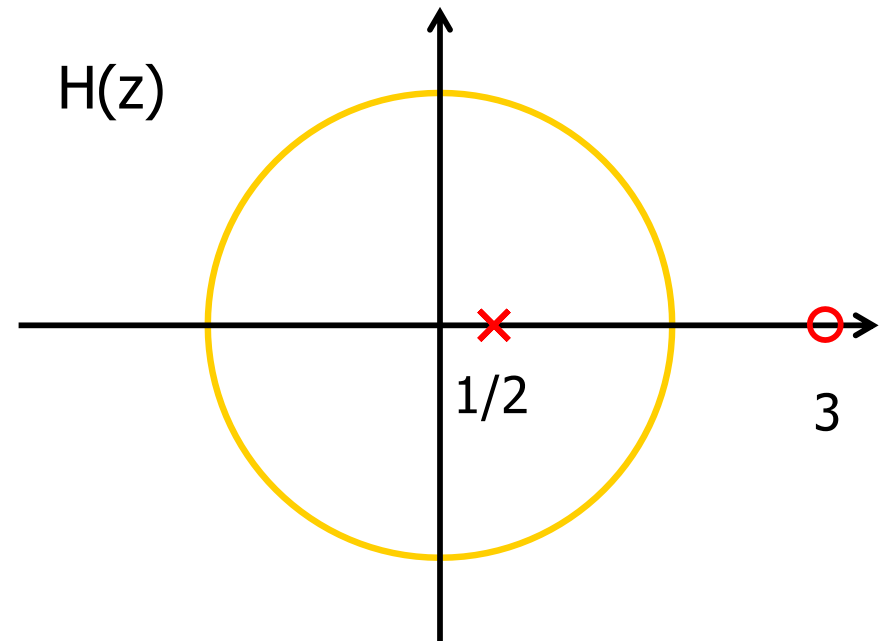
$$H(z) = H_{\min}(z) \cdot H_{ap}(z)$$

- Approach:
 - (1) First construct H_{ap} with all zeros outside unit circle
 - (2) Compute

$$H_{\min}(z) = \frac{H(z)}{H_{ap}(z)}$$

Min-Phase Decomposition Example

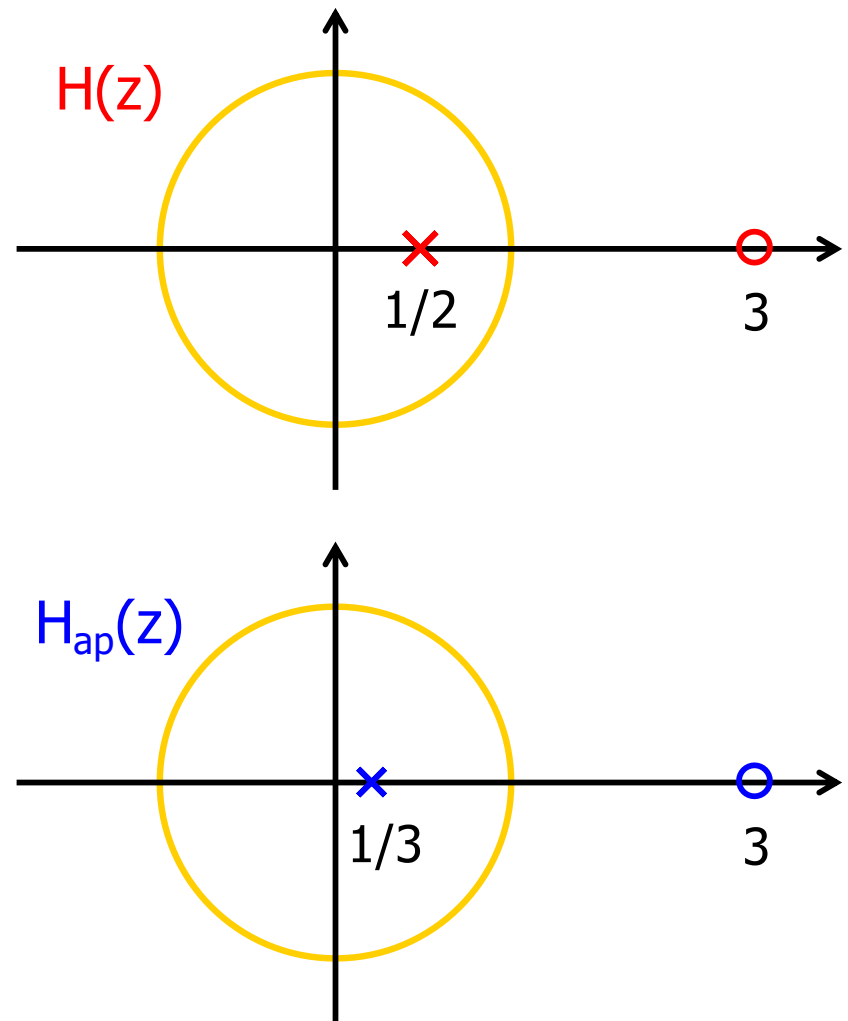
$$H(z) = \frac{1 - 3z^{-1}}{1 - \frac{1}{2}z^{-1}}$$



Min-Phase Decomposition Example

$$H(z) = \frac{1 - 3z^{-1}}{1 - \frac{1}{2}z^{-1}}$$

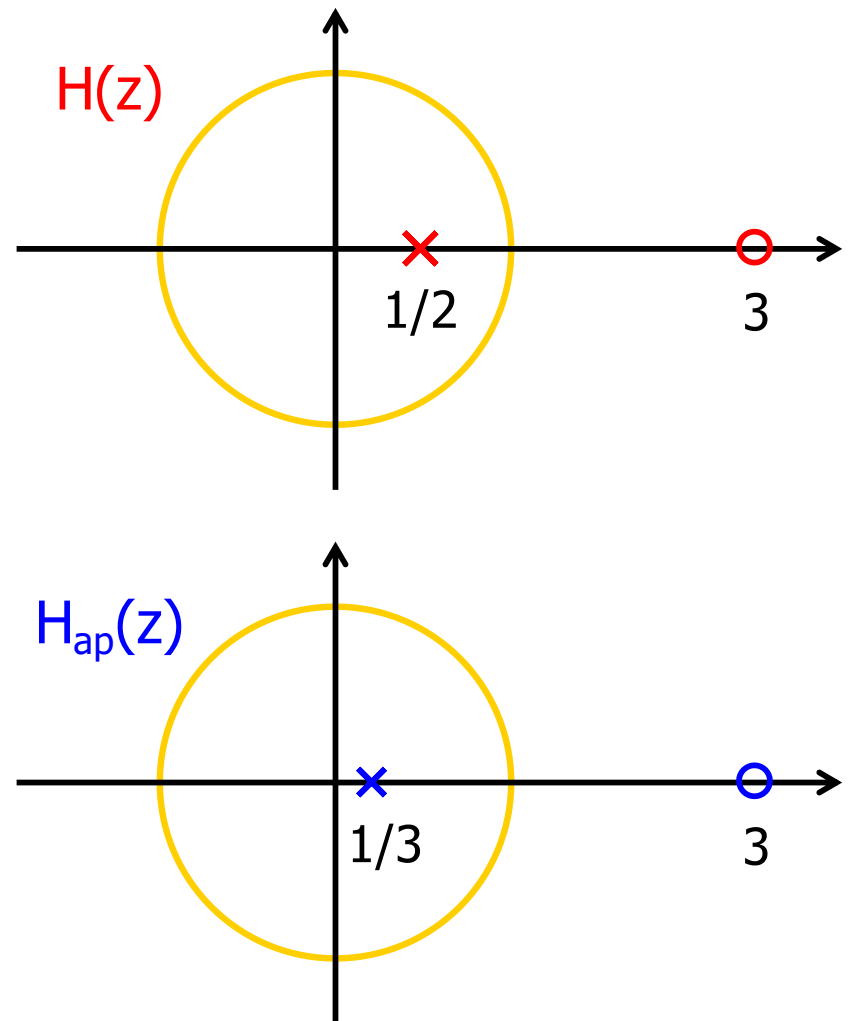
□ Set $H_{ap}(z) = \frac{z^{-1} - a^*}{1 - az^{-1}}$



Min-Phase Decomposition Example

$$H(z) = \frac{1 - 3z^{-1}}{1 - \frac{1}{2}z^{-1}}$$

□ Set $H_{ap}(z) = \frac{z^{-1} - \frac{1}{3}}{1 - \frac{1}{3}z^{-1}}$

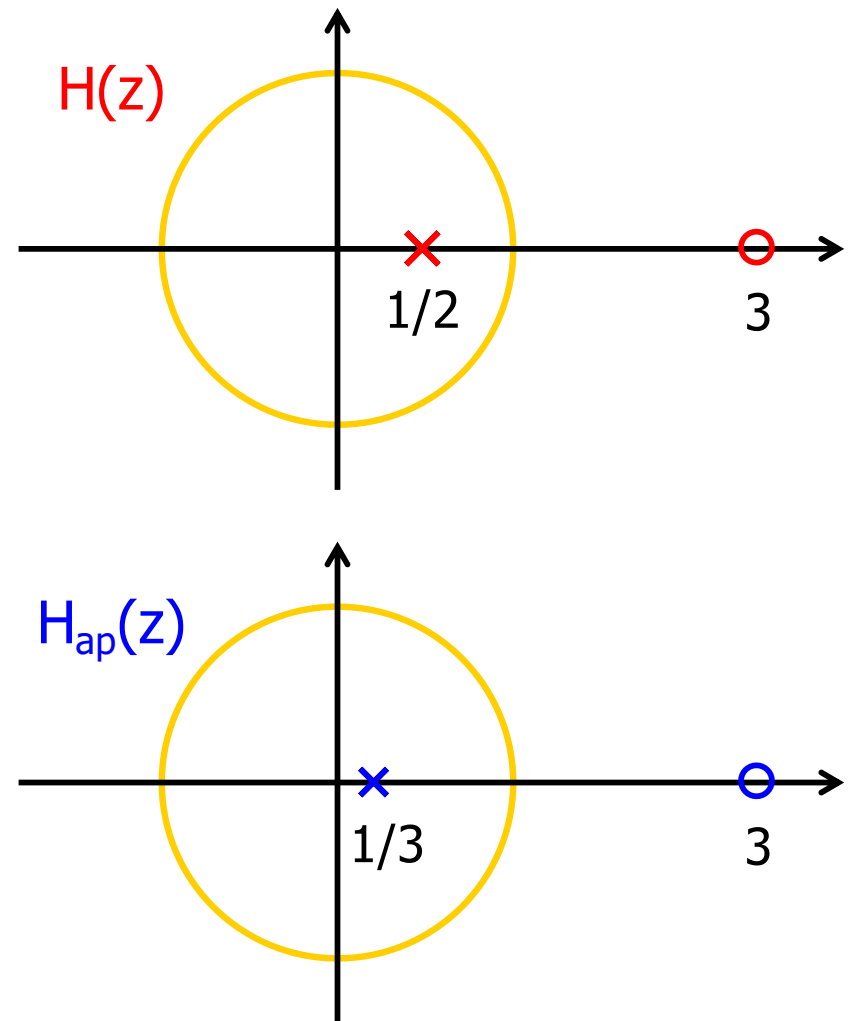


Min-Phase Decomposition Example

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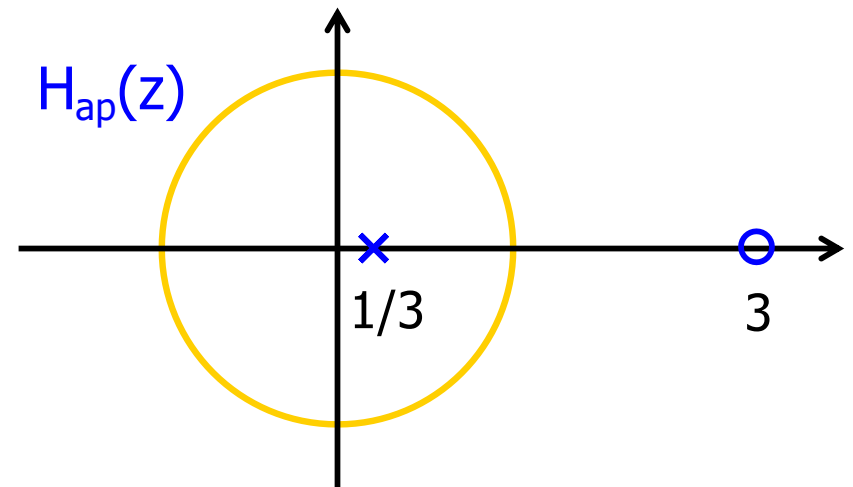
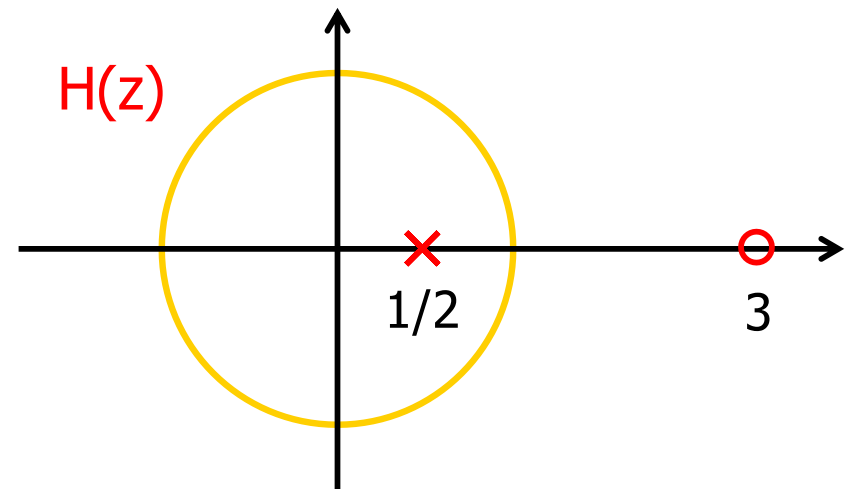
□ Set $H_{ap}(z) = \frac{z^{-1} - \frac{1}{3}}{1 - \frac{1}{3}z^{-1}}$

$$H_{\min}(z) = \frac{1 - 3z^{-1}}{1 - \frac{1}{2}z^{-1}} \left(\frac{z^{-1} - \frac{1}{3}}{1 - \frac{1}{3}z^{-1}} \right)^{-1}$$



Min-Phase Decomposition Example

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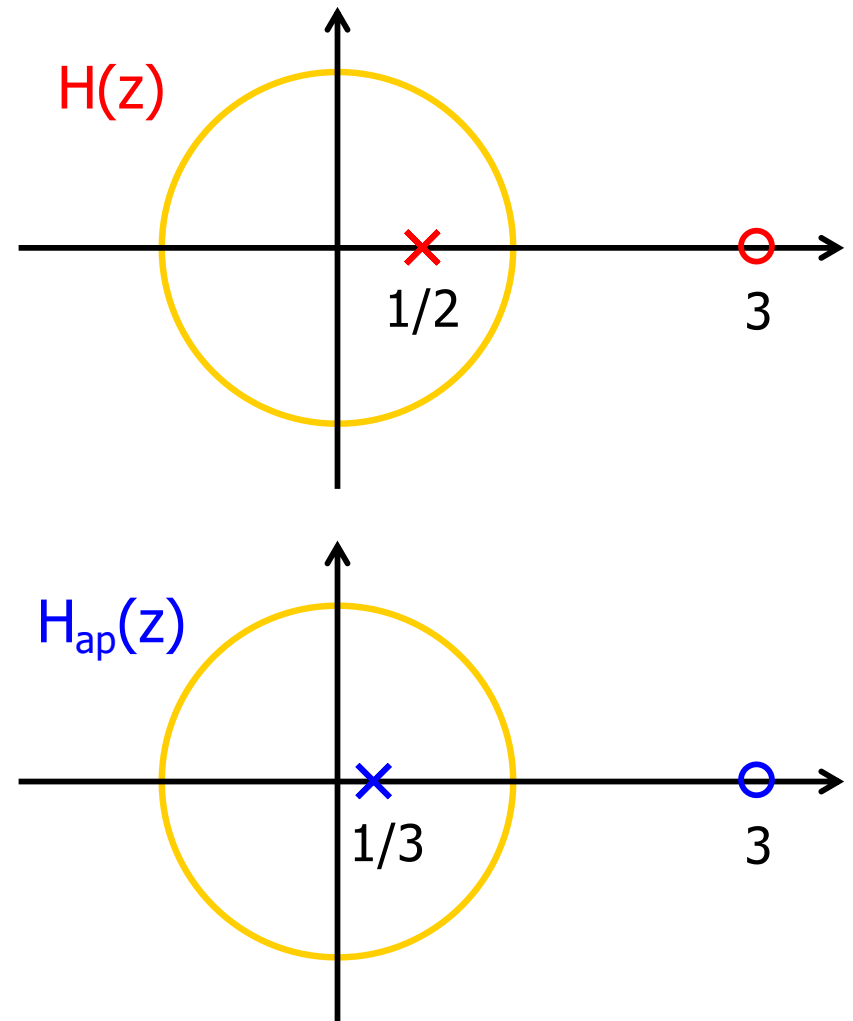


Min-Phase Decomposition Example

$$H(z) = \frac{1 - 3z^{-1}}{1 - \frac{1}{2}z^{-1}}$$

□ Set $H_{ap}(z) = \frac{z^{-1} - \frac{1}{3}}{1 - \frac{1}{3}z^{-1}}$

$$H_{\min}(z) = -3 \frac{1 - \frac{1}{3}z^{-1}}{1 - \frac{1}{2}z^{-1}}$$

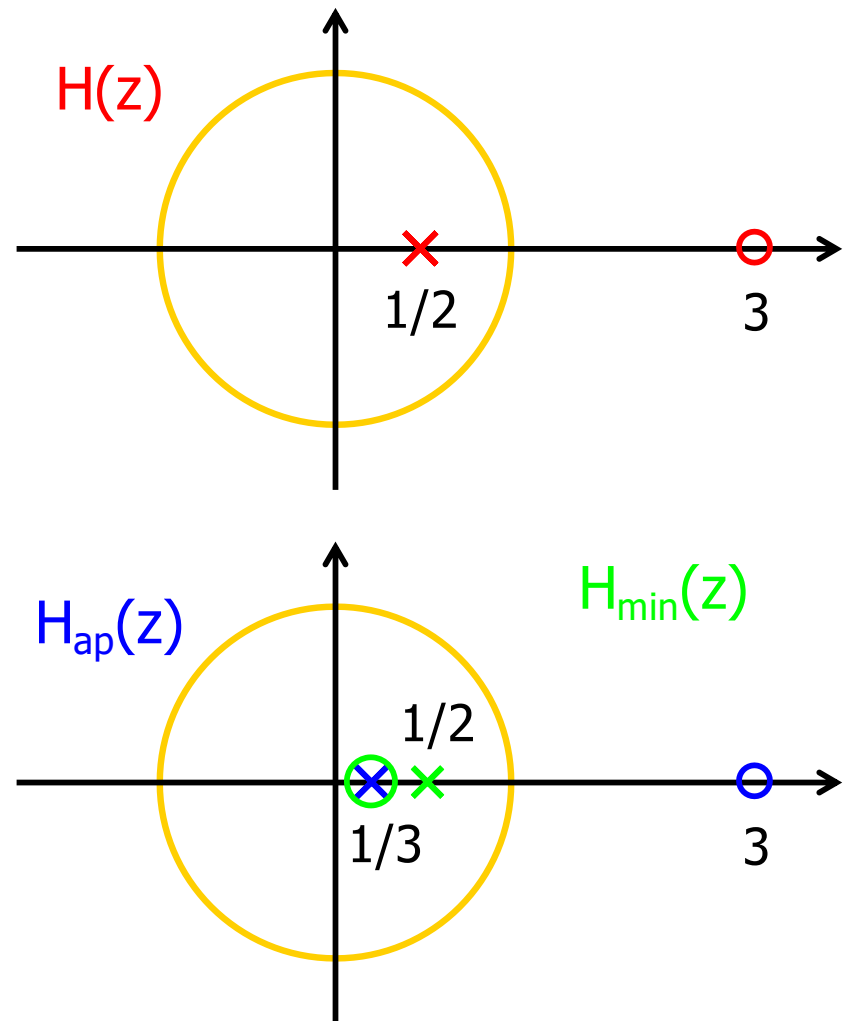


Min-Phase Decomposition Example

$$H(z) = \frac{1 - 3z^{-1}}{1 - \frac{1}{2}z^{-1}}$$

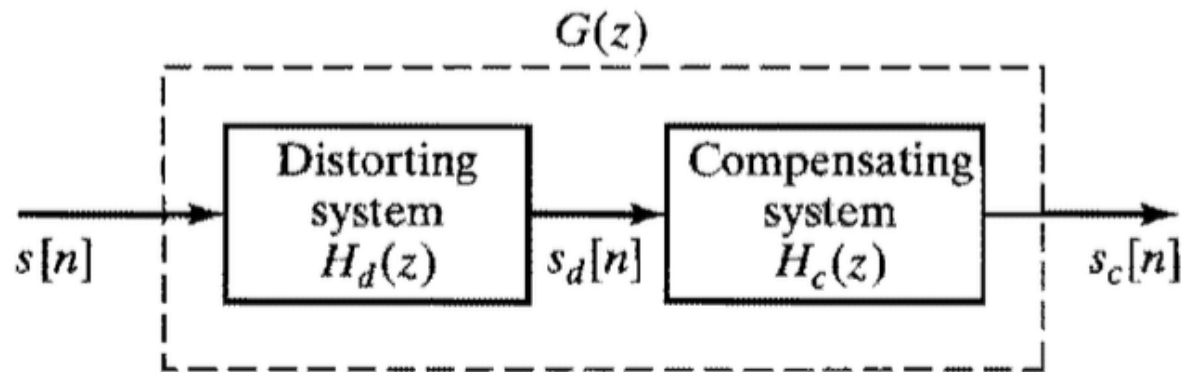
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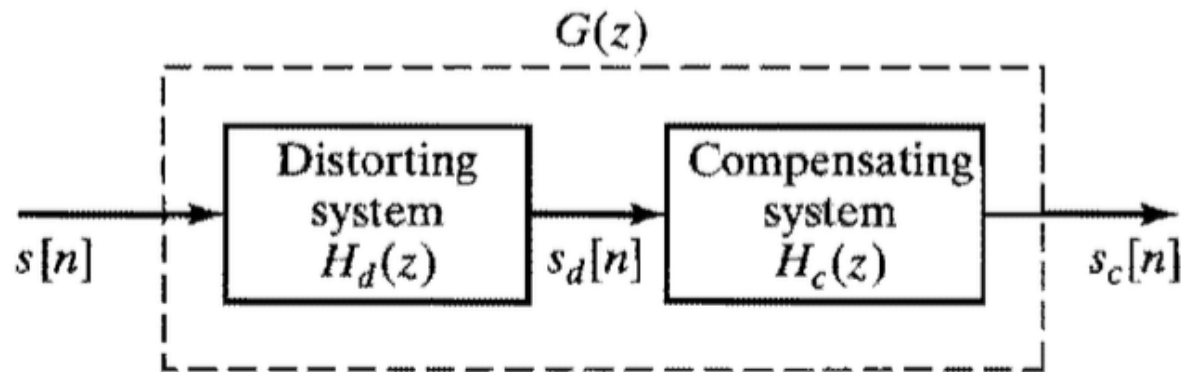
Min-Phase Decomposition Purpose

- Have some distortion that we want to compensate for:



Min-Phase Decomposition Purpose

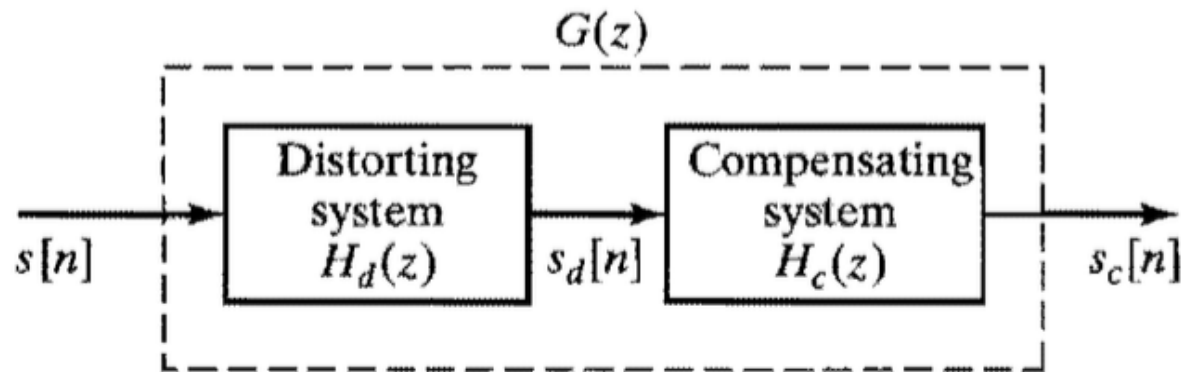
- Have some distortion that we want to compensate for:



- If $H_d(z)$ is min phase, easy:
 - $H_c(z) = 1/H_d(z)$ ← also stable and causal

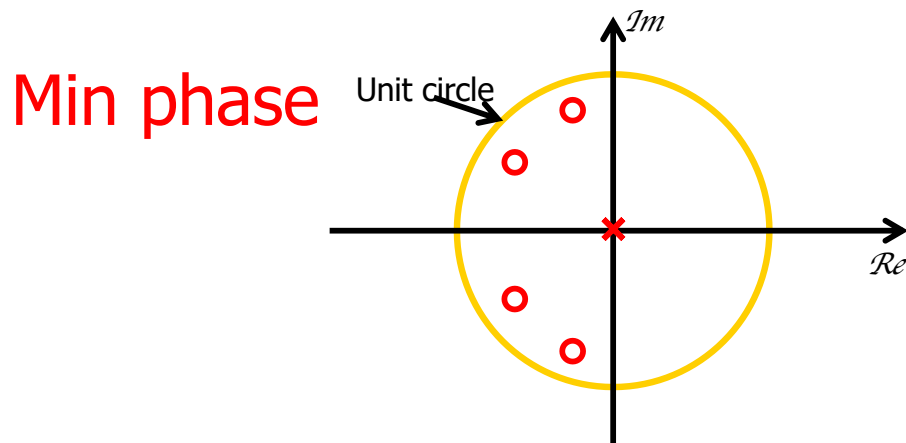
Min-Phase Decomposition Purpose

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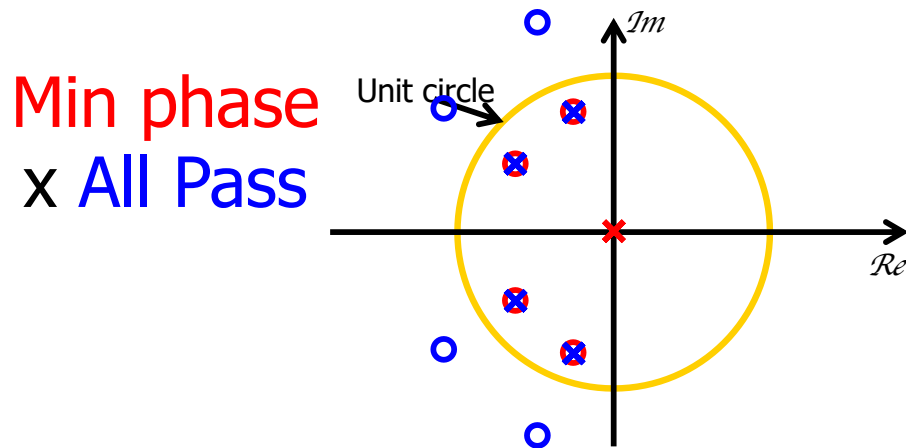


- If $H_d(z)$ is min phase, easy:
 - $H_c(z) = 1/H_d(z) \leftarrow$ also stable and causal
- Else, decompose $H_d(z) = H_{d,\min}(z) H_{d,\text{ap}}(z)$
 - $H_c(z) = 1/H_{d,\min}(z) \rightarrow H_d(z)H_c(z) = H_{d,\text{ap}}(z)$
 - Compensate for magnitude distortion

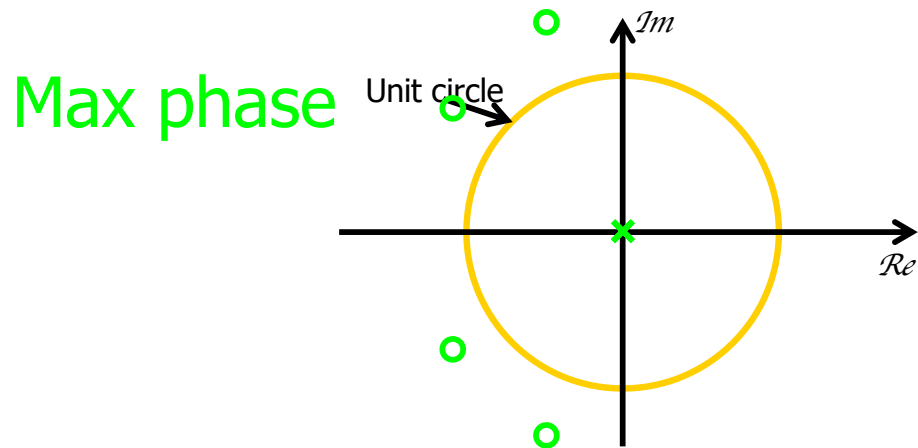
Minimum Phase to Max Phase



Minimum Phase to Max Phase

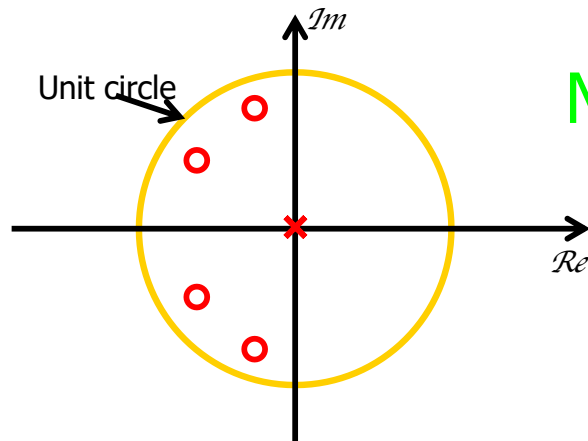


Minimum Phase to Max Phase

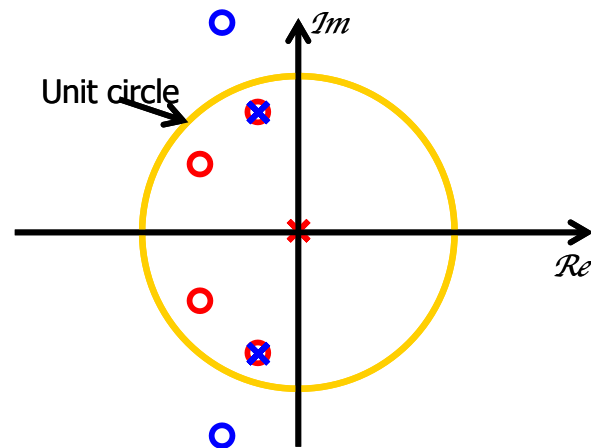
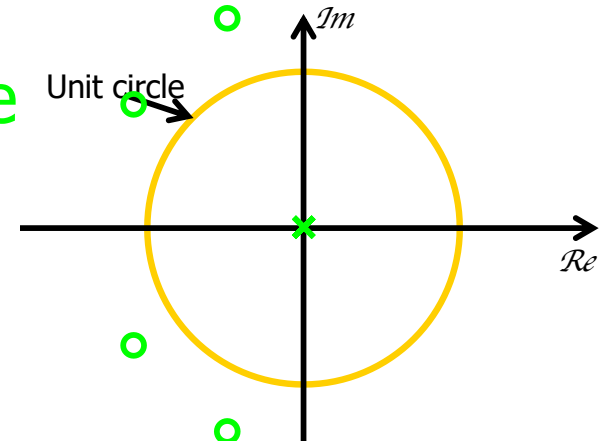


Minimum Phase

Min phase

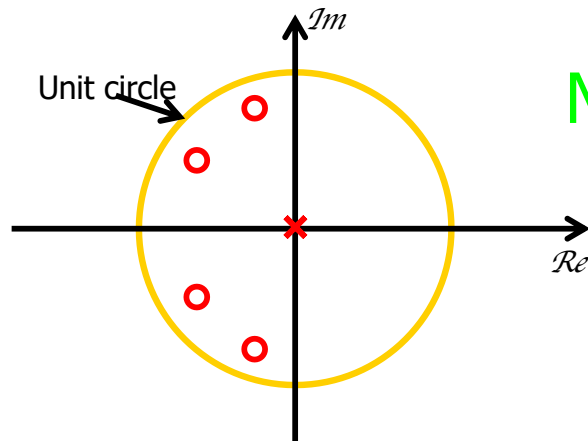


Max phase

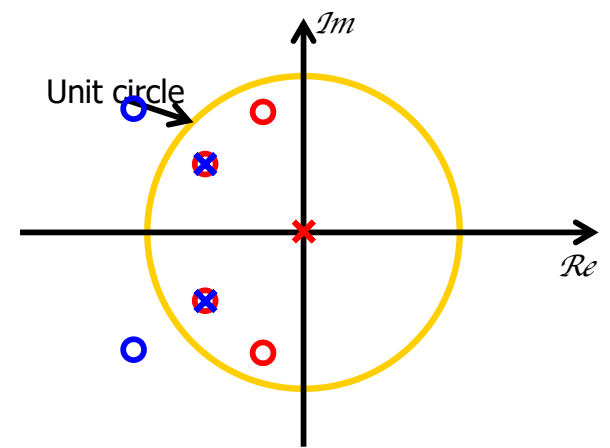
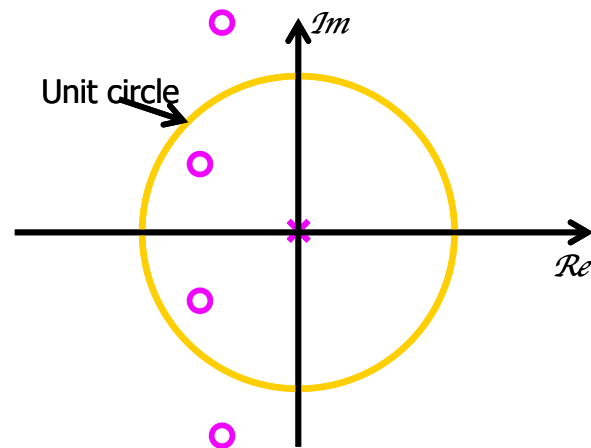
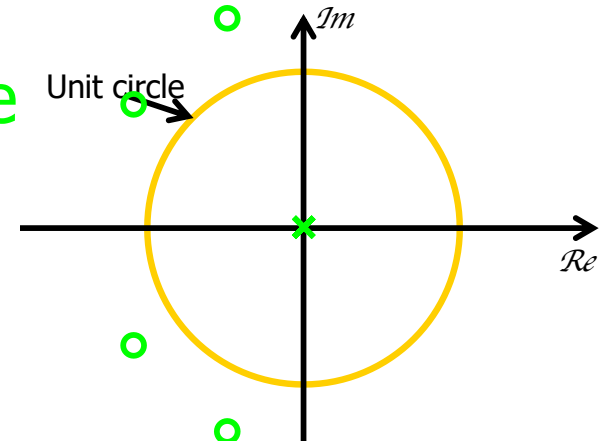


Minimum Phase

Min phase

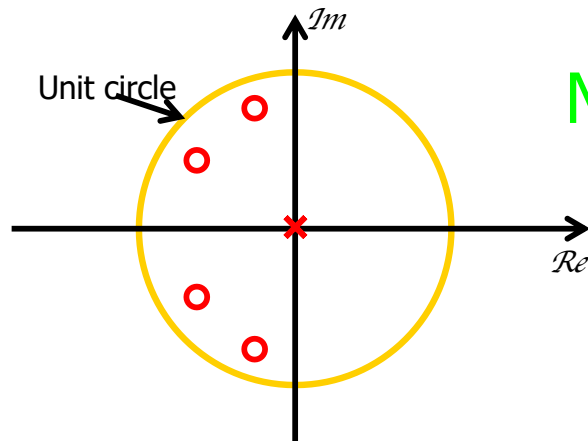


Max phase

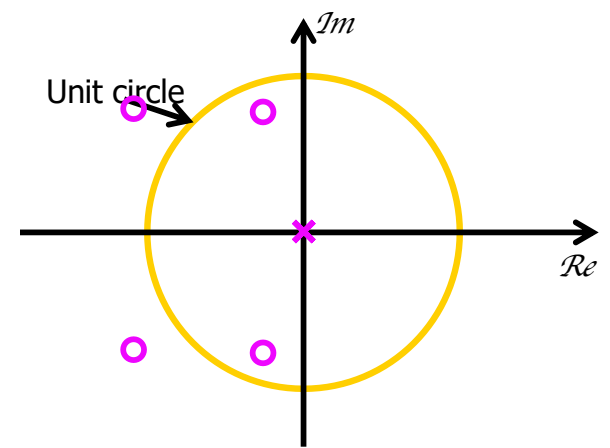
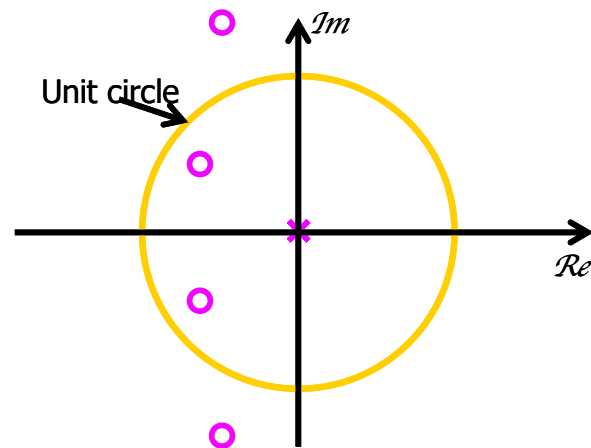
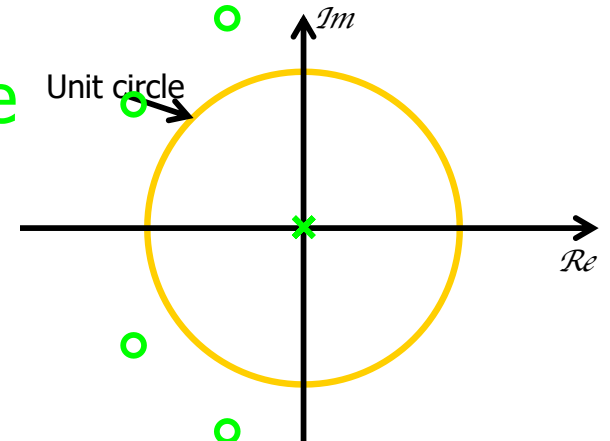


Minimum Phase

Min phase



Max phase





Minimum Phase Lag Property

- All pass properties
 - $\arg[H_{ap}(e^{j\omega})] \leq 0$
 - $\text{grd}[H_{ap}(e^{j\omega})] > 0$

Minimum Phase Lag Property

□ All pass properties

■ $\arg[H_{ap}(e^{j\omega})] \leq 0$

■ $\text{grd}[H_{ap}(e^{j\omega})] > 0$

□
$$\begin{aligned}\arg[H_{\max}(e^{j\omega})] &= \arg[H_{\min}(e^{j\omega}) * H_{ap}(e^{j\omega})] \\ &= \arg[H_{\min}(e^{j\omega})] + \arg[H_{ap}(e^{j\omega})] \\ &= \arg[H_{\min}(e^{j\omega})] + \leq 0\end{aligned}$$

Minimum Group Delay Property

□ All pass properties

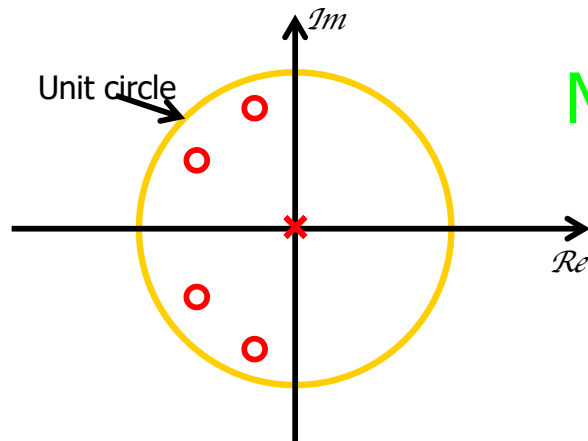
■ $\arg[H_{ap}(e^{j\omega})] \leq 0$

■ $\text{grd}[H_{ap}(e^{j\omega})] > 0$

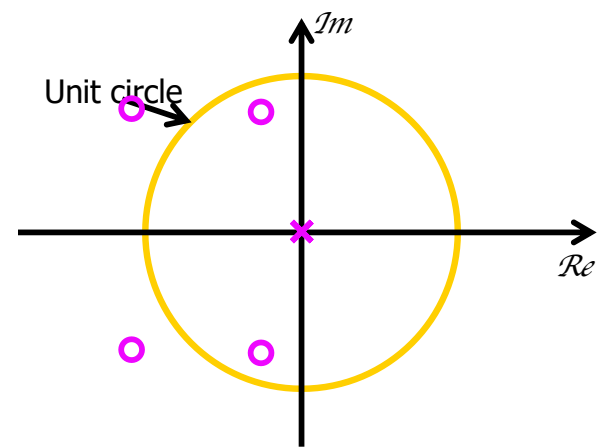
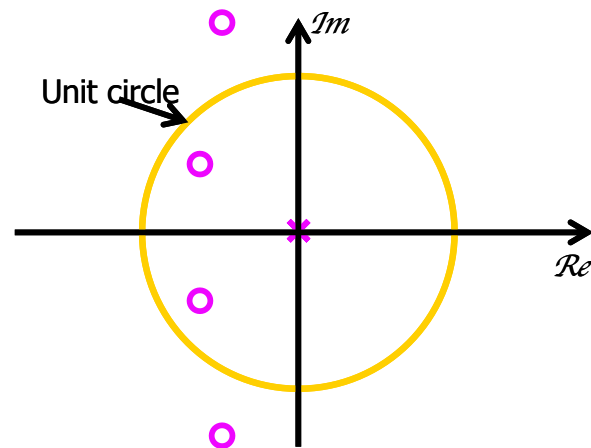
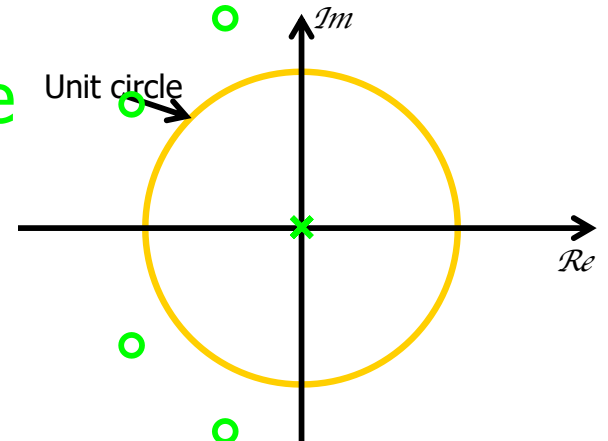
□
$$\begin{aligned}\text{grd}[H_{\max}(e^{j\omega})] &= \text{grd}[H_{\min}(e^{j\omega}) * H_{ap}(e^{j\omega})] \\ &= \text{grd}[H_{\min}(e^{j\omega})] + \text{grd}[H_{ap}(e^{j\omega})] \\ &= \text{grd}[H_{\min}(e^{j\omega})] + \geq 0\end{aligned}$$

Minimum Phase

Min phase

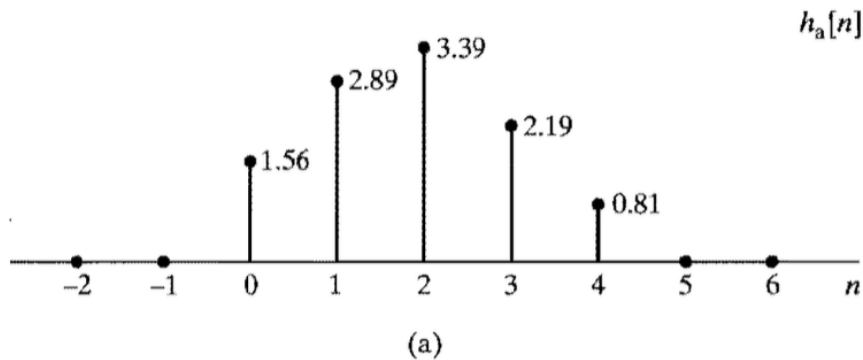


Max phase

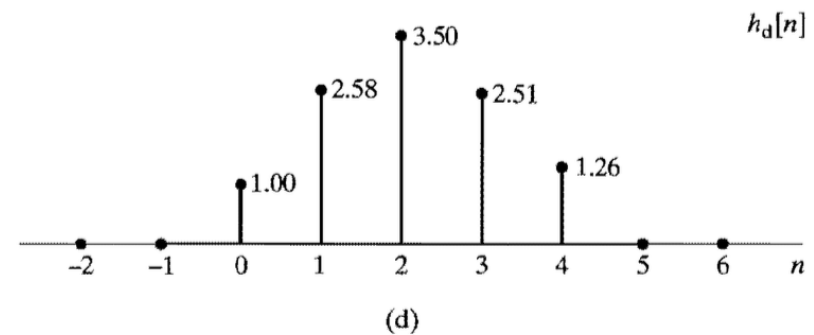
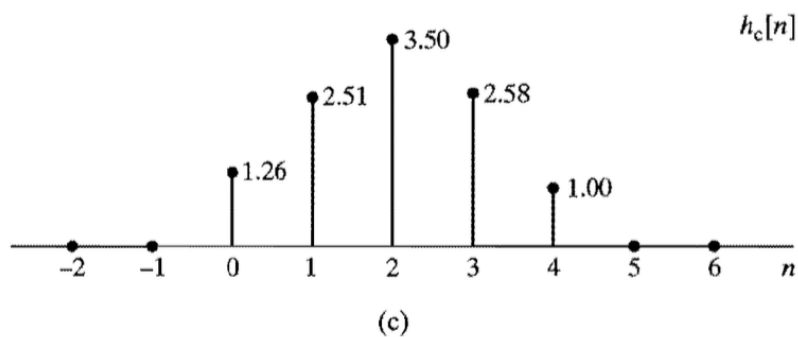
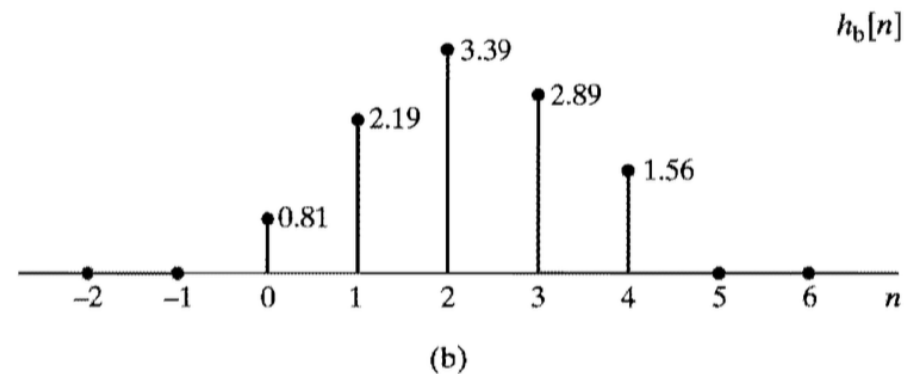


Minimum Energy-Delay Property

Min phase



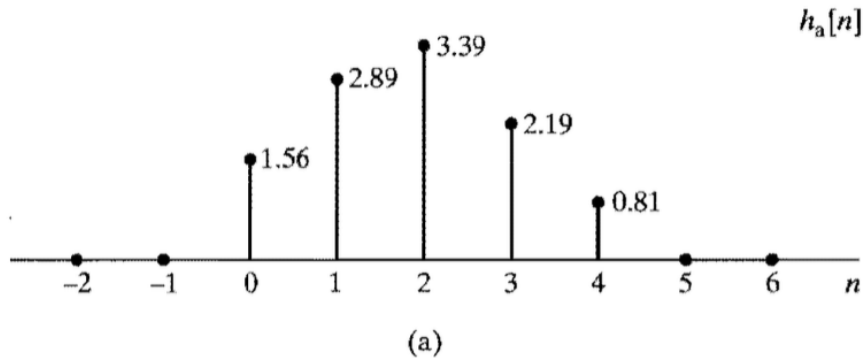
Max phase



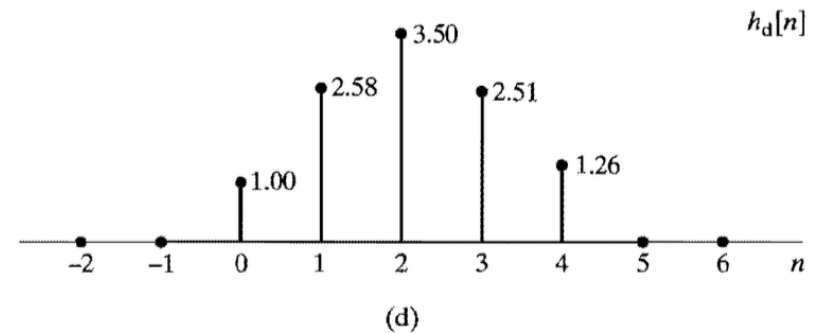
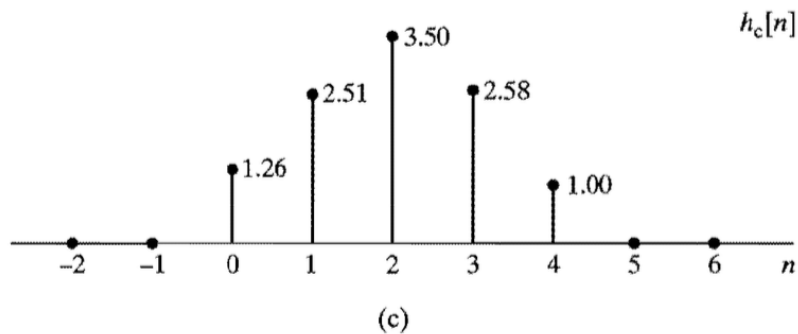
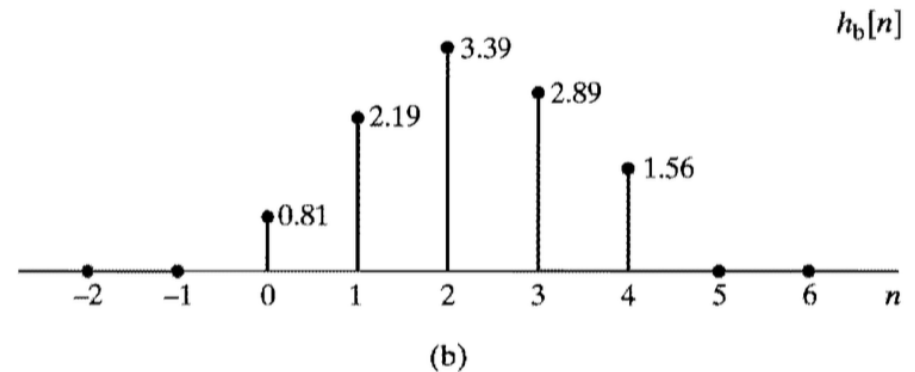
Total energy: $E = \sum_{n=0}^{\infty} |h[n]|^2$

Minimum Energy-Delay Property

Min phase

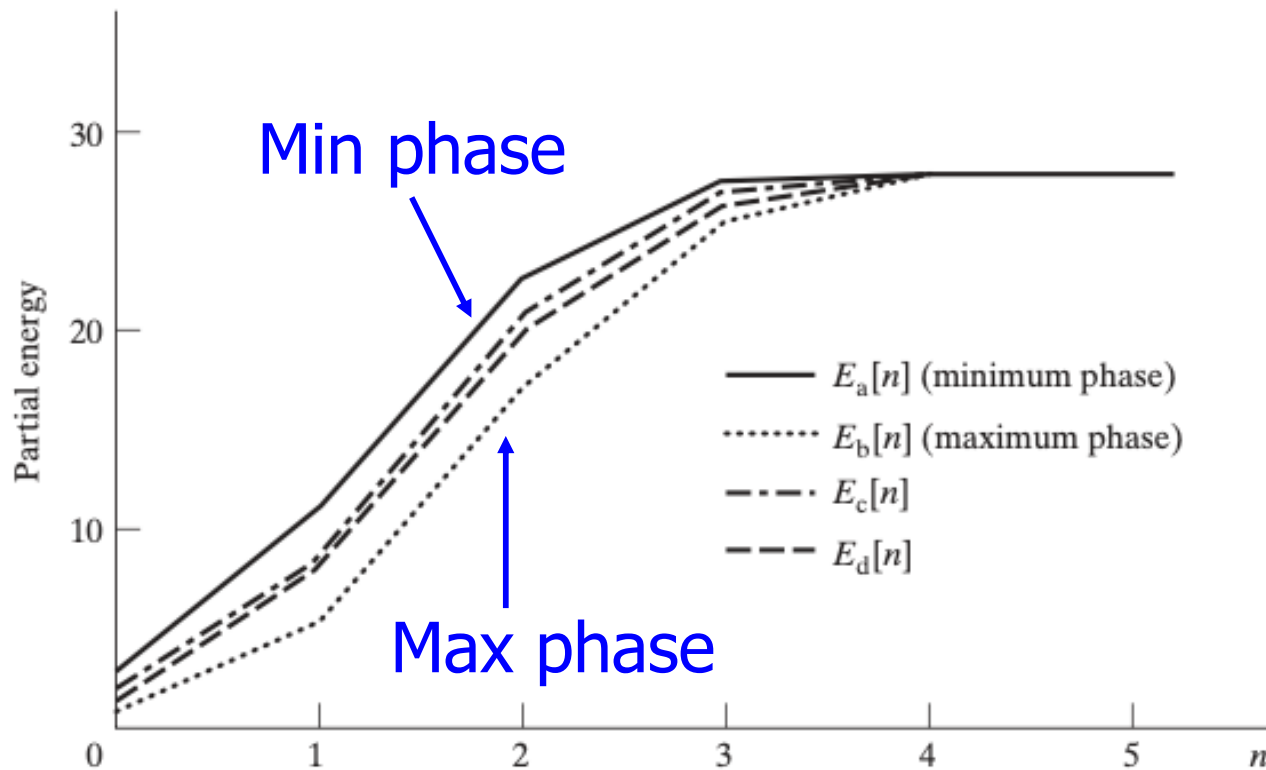


Max phase



Partial energy: $E[n] = \sum_{m=0}^n |h[m]|^2$

Minimum Energy-Delay Property



Partial energy: $E[n] = \sum_{m=0}^n |h[m]|^2$



Big Ideas

- Minimum Phase Systems
 - Can compensate for magnitude distortion
 - Minimum energy-delay property



Admin

- ❑ HW 5
 - Due Monday 3/15
- ❑ HW 6
 - Due Sunday 3/22