

ESE 531: Digital Signal Processing

Week 12

Lecture 22: Apr 4, 2021

Discrete Fourier Transform, Pt 2



Today

- Review:
 - Discrete Fourier Transform (DFT)
 - Circular Convolution
- Fast Convolution Methods
- Discrete Cosine Transform

Discrete Fourier Transform

□ The DFT

$$W_N \triangleq e^{-j2\pi/N}$$

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] W_N^{-kn} \quad \text{Inverse DFT, synthesis}$$

$$X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn} \quad \text{DFT, analysis}$$

□ It is understood that,

$$x[n] = 0 \quad \text{outside } 0 \leq n \leq N - 1$$

$$X[k] = 0 \quad \text{outside } 0 \leq k \leq N - 1$$



DTFT Vs. DFT

DTFT:

$$X(e^{j\omega}) = \sum_{k=-\infty}^{\infty} x[k]e^{-j\omega k}$$

$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})e^{j\omega n} d\omega$$

DFT:

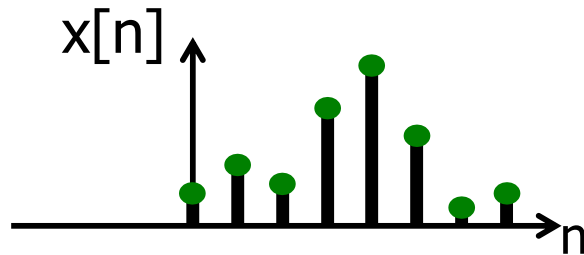
$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k]W_N^{-kn}$$

$$X[k] = \sum_{n=0}^{N-1} x[n]W_N^{kn}$$



DFT Intuition

Time

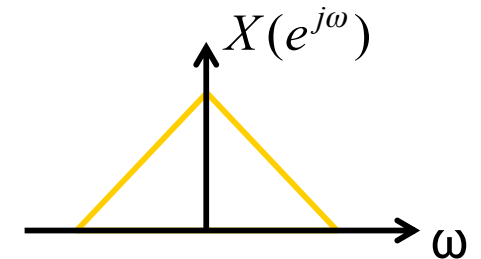


Transform

DTFT

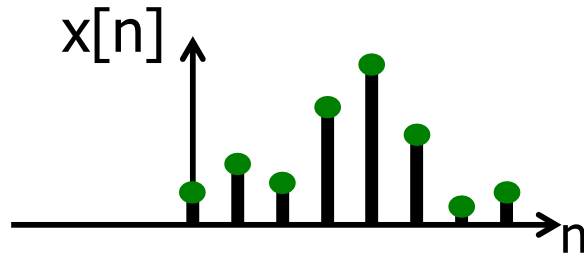
$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega$$

Frequency



DFT Intuition

Time

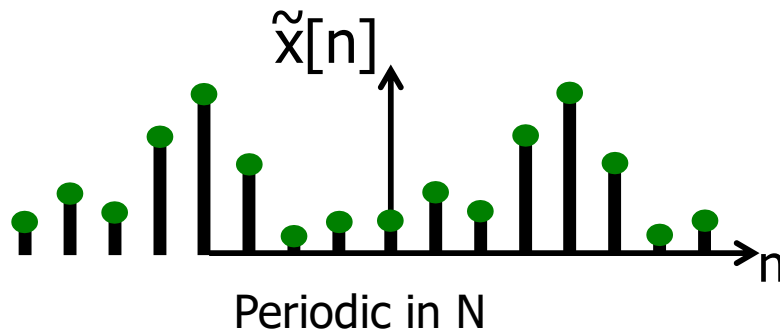
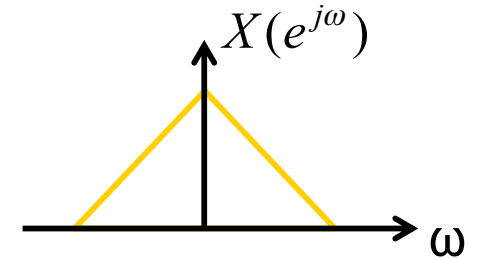


Transform

DTFT

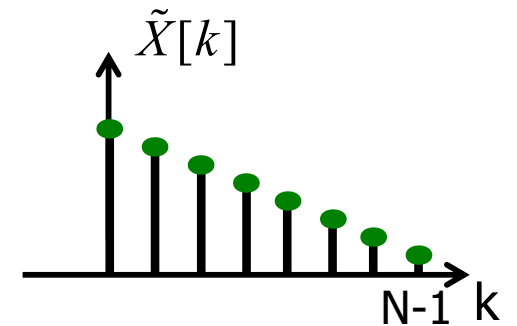
$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega$$

Frequency



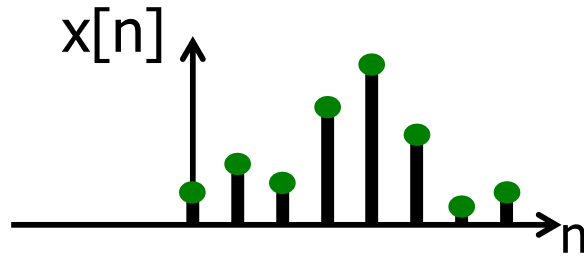
DFS

$$\tilde{x}[n] = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}[k] W_N^{-kn}$$



DFT Intuition

Time

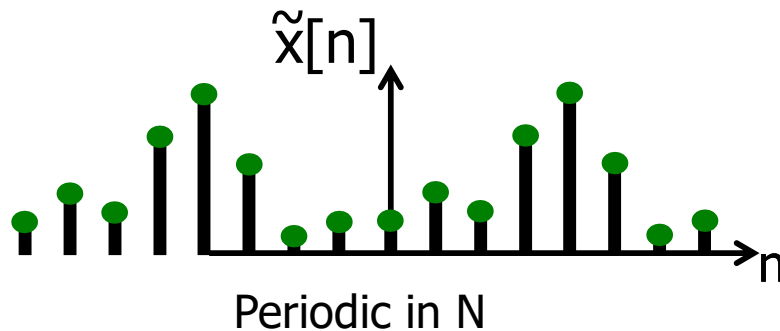
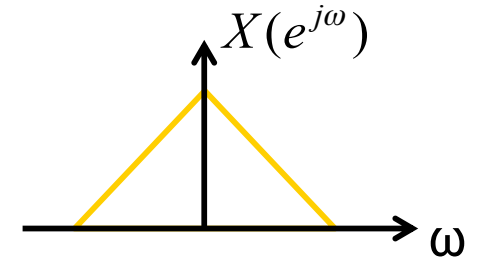


Transform

DTFT

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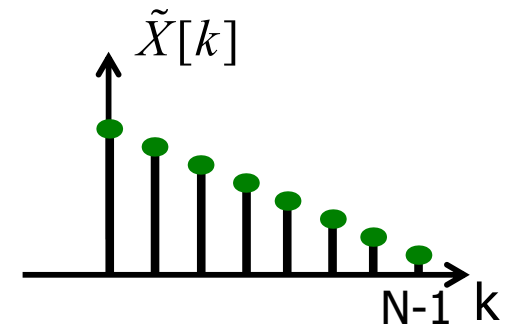
Frequency



DFS

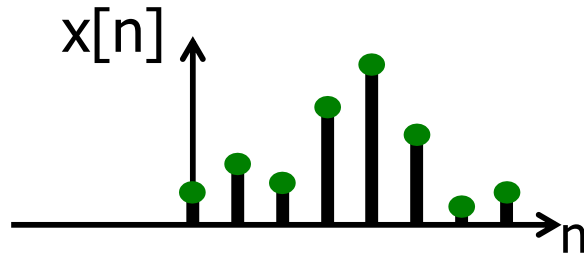
$$\tilde{x}[n] = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}[k] W_N^{-kn}$$

$$W_N = e^{-j\frac{2\pi}{N}}$$



DFT Intuition

Time

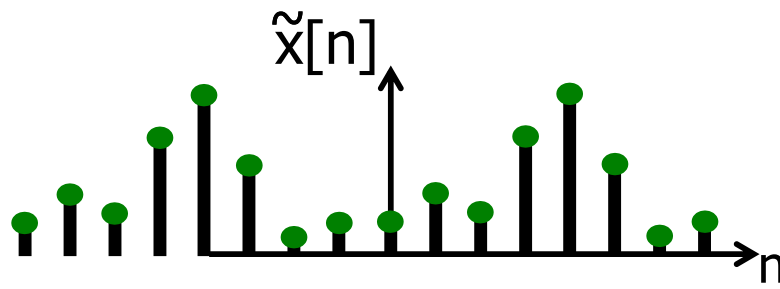
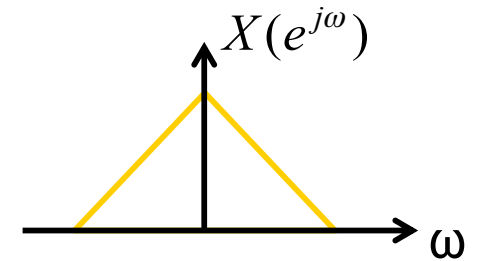


Transform

DTFT

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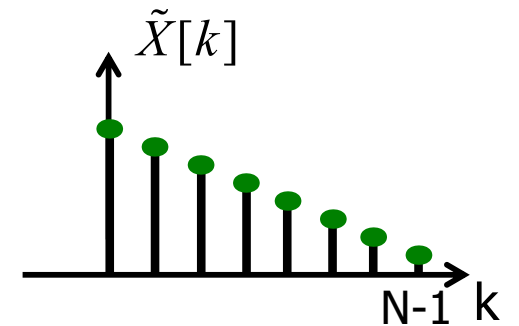
Frequency



Periodic in N

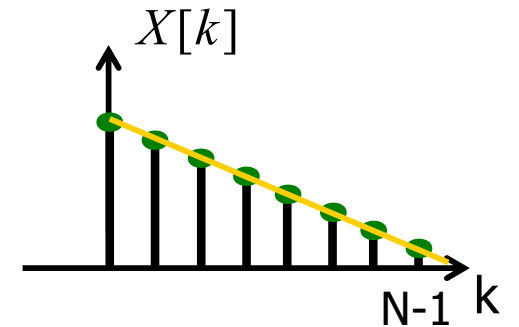
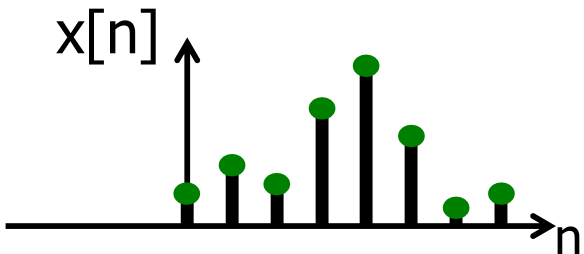
DFS

$$\tilde{x}[n] = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{X}[k] W_N^{-kn}$$



DFT

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] W_N^{-kn}$$

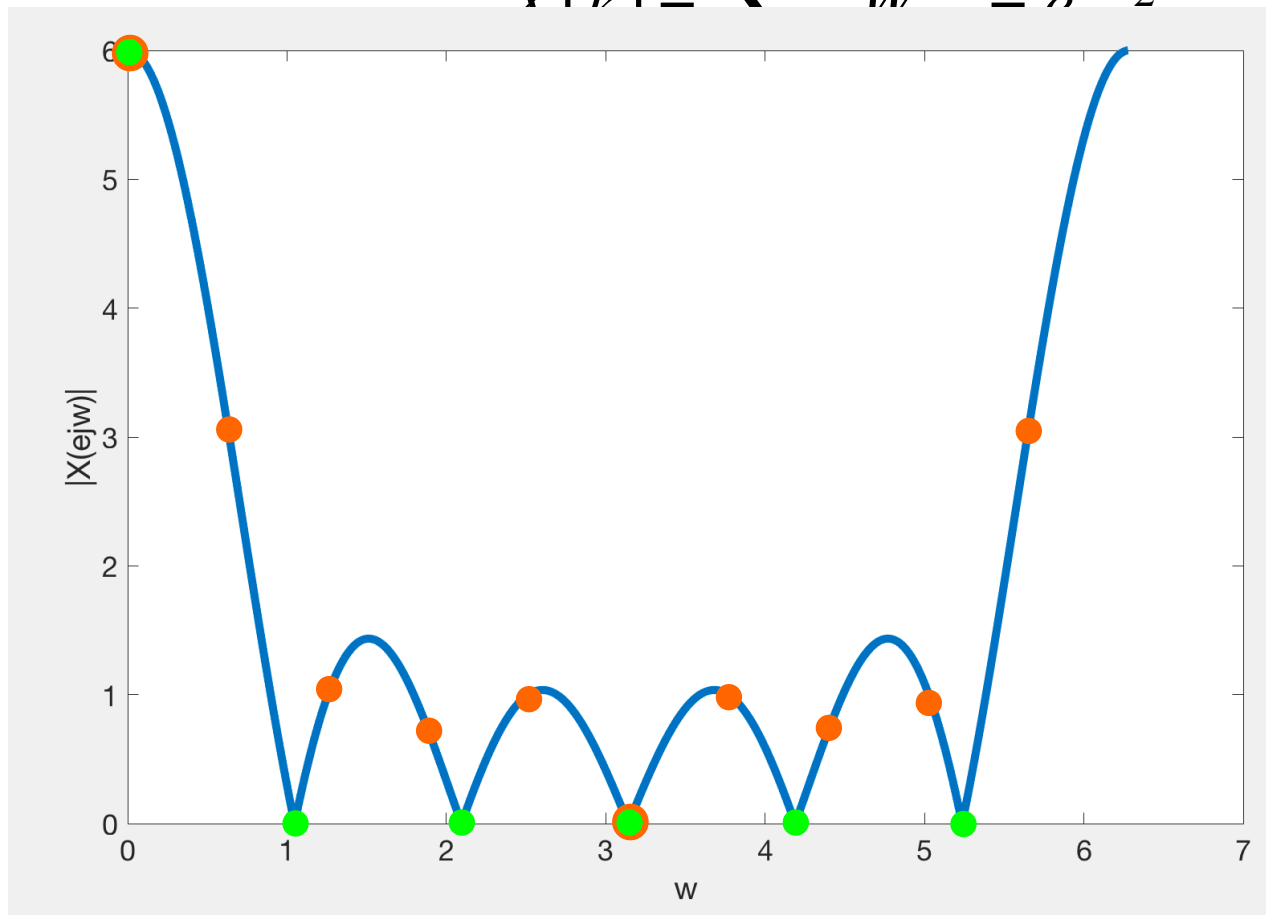




DFT vs DTFT

□ Back to example

$$X[k] = \sum_{n=0}^5 M[nk] e^{-j\frac{\pi}{2}nk} = \frac{\sin\left(\frac{3\pi}{5}k\right)}{\sin\left(\frac{\pi}{10}k\right)}$$



"6-point" DFT

"10-point" DFT

Use `fftshift`
to center
around dc

Circular Convolution

□ Circular Convolution:

$$x_1[n] \circledN x_2[n] \triangleq \sum_{m=0}^{N-1} x_1[m] x_2[((n - m))_N]$$

For two signals of length N

Note: Circular convolution is commutative

$$x_2[n] \circledN x_1[n] = x_1[n] \circledN x_2[n]$$



Linear Convolution

- Next....
 - Using DFT, circular convolution is easy
 - Matrix multiplication
 - But, linear convolution is useful, not circular
 - So, show how to perform linear convolution with circular convolution
 - Use DFT to do linear convolution (via circular convolution)



Linear Convolution

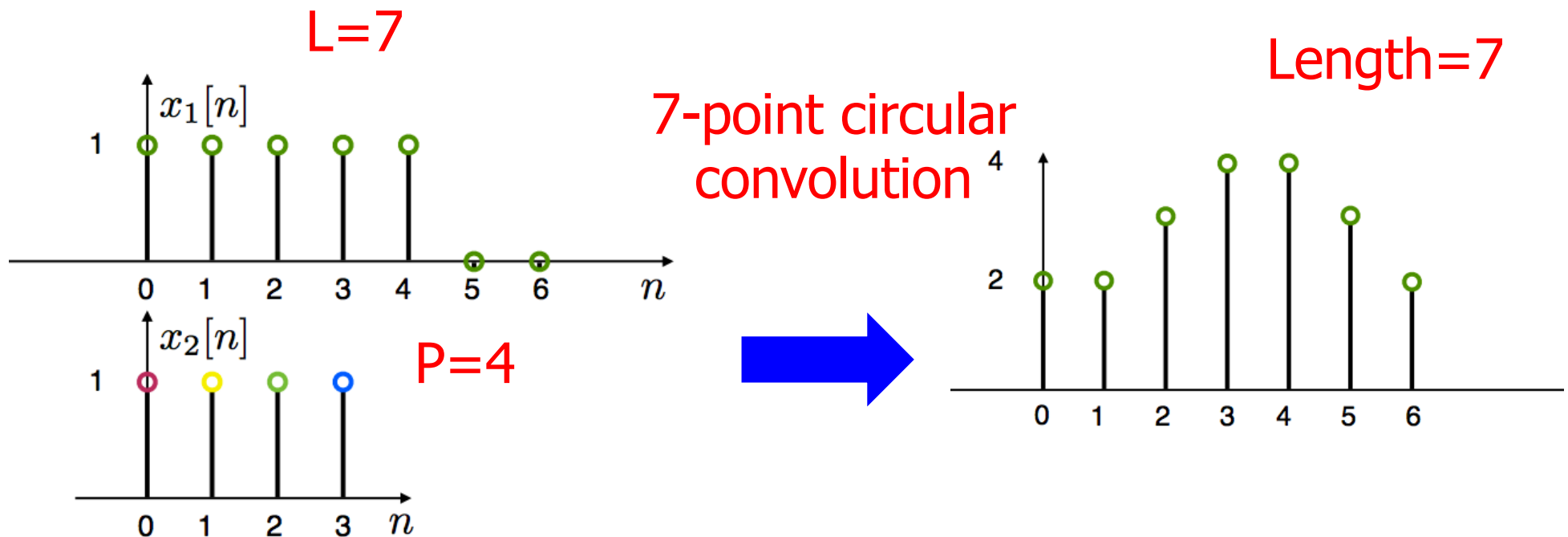
- We start with two non-periodic sequences:

$$x[n] \quad 0 \leq n \leq L - 1$$

$$h[n] \quad 0 \leq n \leq P - 1$$

- E.g. $x[n]$ is a signal and $h[n]$ a filter's impulse response

Compute Circular Convolution Sum



$$x_1[n] \circledast x_2[n] \triangleq \sum_{m=0}^{N-1} x_1[m] x_2[((n - m))_N]$$



Linear Convolution

- We start with two non-periodic sequences:

$$x[n] \quad 0 \leq n \leq L - 1$$

$$h[n] \quad 0 \leq n \leq P - 1$$

- E.g. $x[n]$ is a signal and $h[n]$ a filter's impulse response
- We want to compute the linear convolution:

$$y[n] = x[n] * h[n] = \sum_{m=0}^{L-1} x[m]h[n-m]$$

- $y[n]$ is nonzero for $0 \leq n \leq L+P-2$ (ie. length $M=L+P-1$)

Requires $L \cdot P$ multiplications

Linear Convolution via Circular Convolution

- ❑ Zero-pad $x[n]$ by $P-1$ zeros

$$x_{zp}[n] = \begin{cases} x[n] & 0 \leq n \leq L-1 \\ 0 & L \leq n \leq L+P-2 \end{cases}$$

- ❑ Zero-pad $h[n]$ by $L-1$ zeros

$$h_{zp}[n] = \begin{cases} h[n] & 0 \leq n \leq P-1 \\ 0 & P \leq n \leq L+P-2 \end{cases}$$

- ❑ Now, both sequences are length $M=L+P-1$

Linear Convolution via Circular Convolution

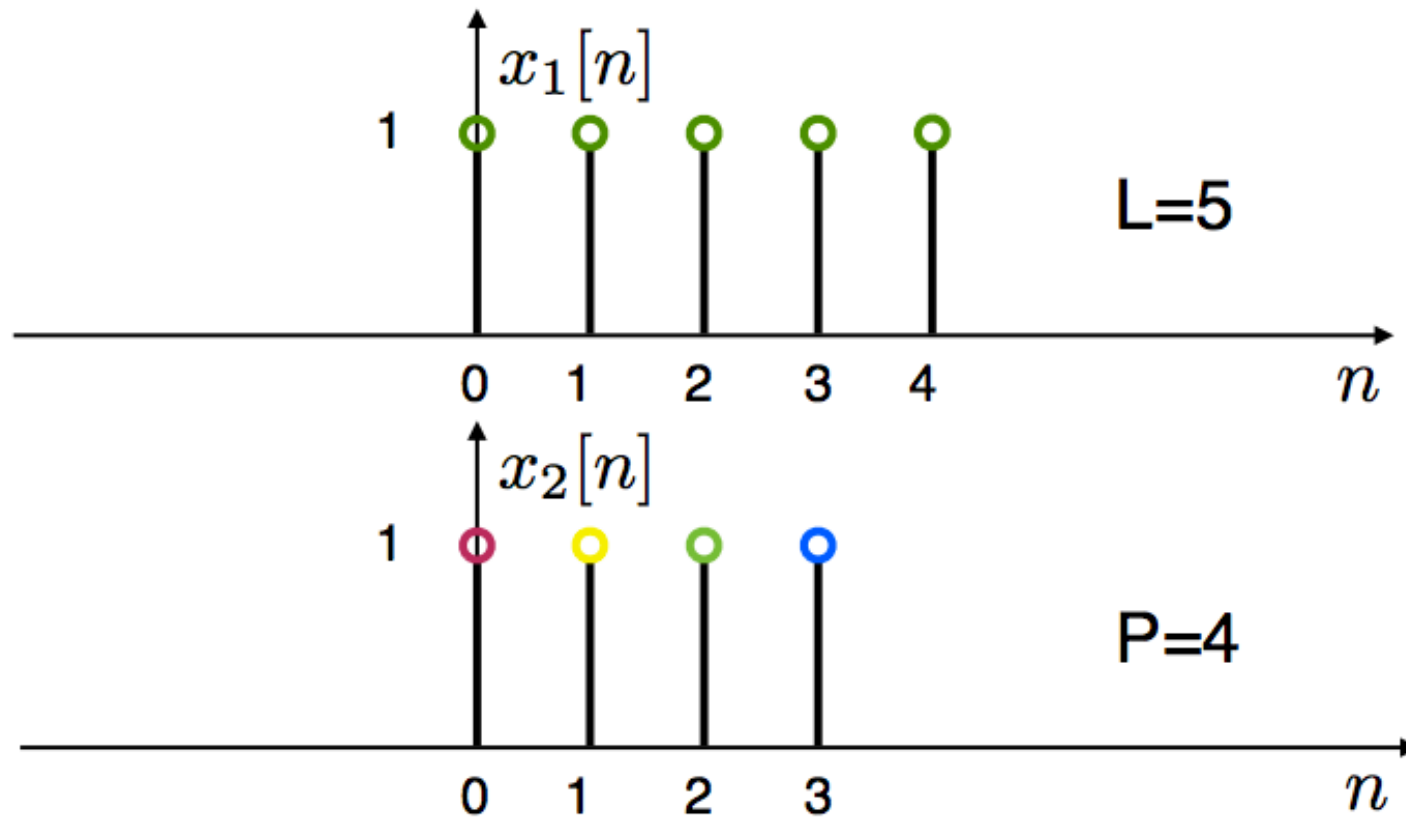
- Now, both sequences are length $M=L+P-1$
- We can now compute the linear convolution using a circular one with length $M=L+P-1$

Linear convolution via circular

$$y[n] = x[n] * y[n] = \begin{cases} x_{zp}[n] \circledast h_{zp}[n] & 0 \leq n \leq M-1 \\ 0 & \text{otherwise} \end{cases}$$



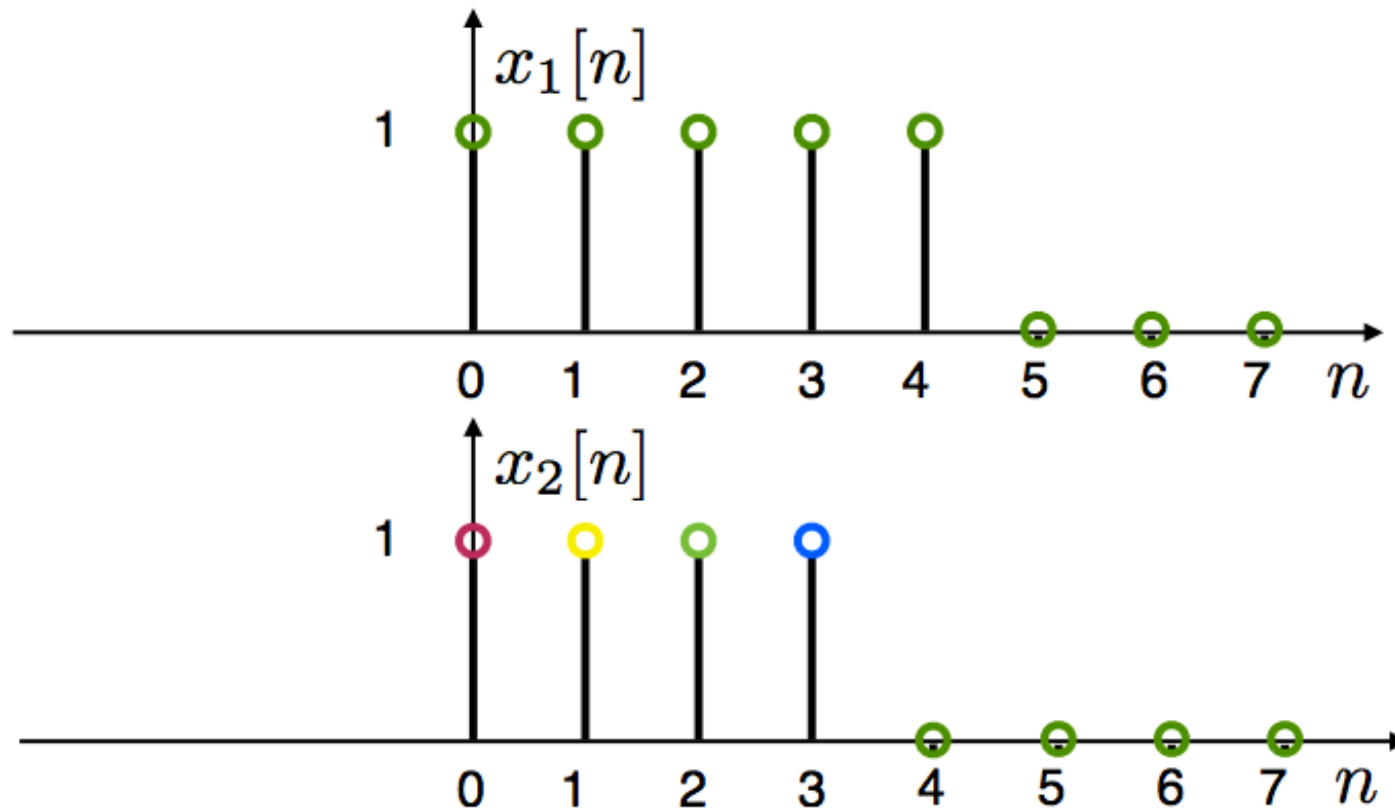
Example



$$M = L + P - 1 = 8$$

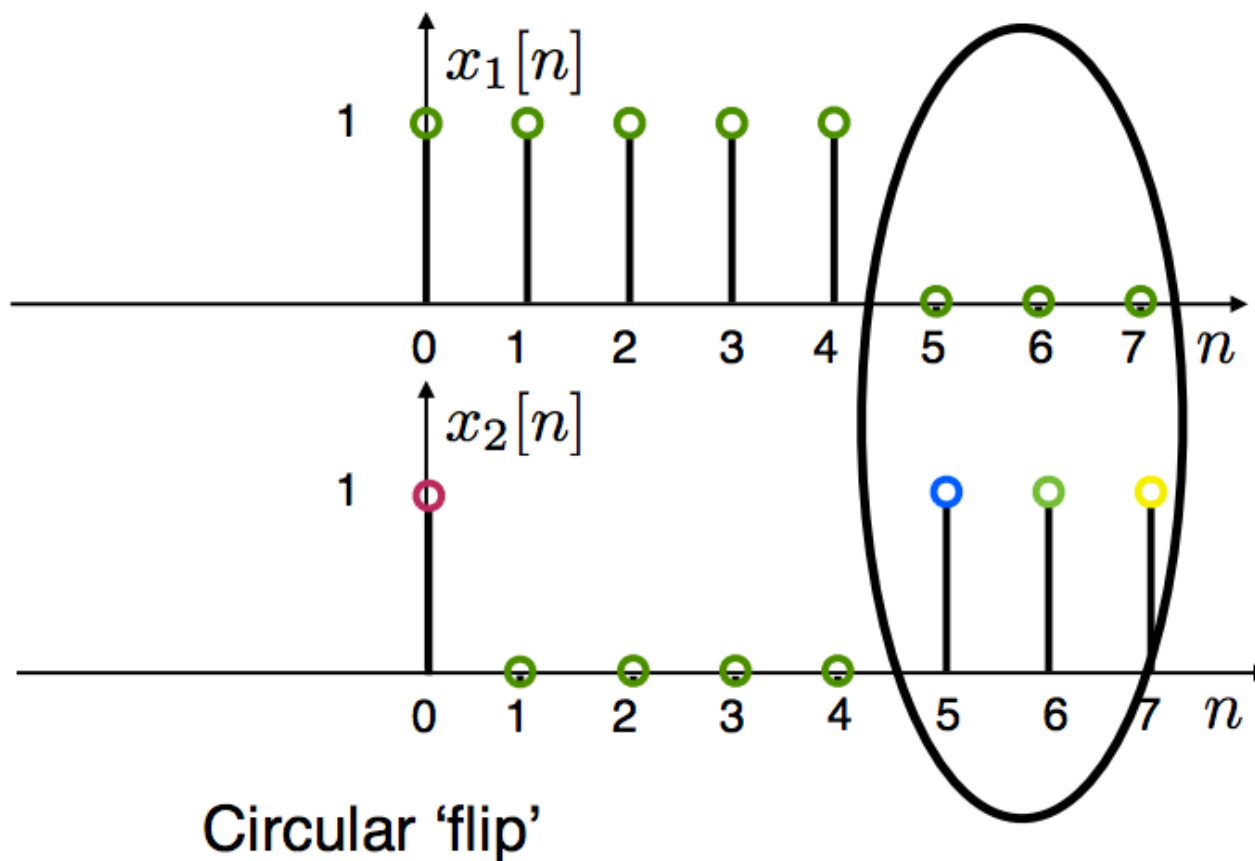


Example



$$M = L + P - 1 = 8$$

Example



$$M = L + P - 1 = 8$$

$$y[n] = x_1[n] \text{ } \textcircled{8} \text{ } x_2[n] = x_1[n] * x_2[n]$$

Linear Convolution with DFT

- In practice we can implement a circular convolution using the DFT property:

$$\begin{aligned}x[n] * h[n] &= x_{zp}[n] \textcircled{M} h_{zp}[n] \\ &= \mathcal{DFT}^{-1} \{ \mathcal{DFT} \{ x_{zp}[n] \} \cdot \mathcal{DFT} \{ h_{zp}[n] \} \} \\ &\text{for } 0 \leq n \leq M-1, M=L+P-1\end{aligned}$$



Linear Convolution with DFT

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- **Advantage:** DFT can be computed with $N \log_2 N$ complexity (FFT algorithm later!)

Linear Convolution with DFT

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- **Advantage:** DFT can be computed with $N \log_2 N$ complexity (FFT algorithm later!)
- **Drawback:** Must wait for all the samples -- huge delay -- incompatible with real-time filtering



Block Convolution

□ Problem:

- An input signal $x[n]$, has very long length (could be considered infinite)
- An impulse response $h[n]$ has length P
- We want to take advantage of DFT/FFT and compute convolutions in blocks that are shorter than the signal

□ Approach:

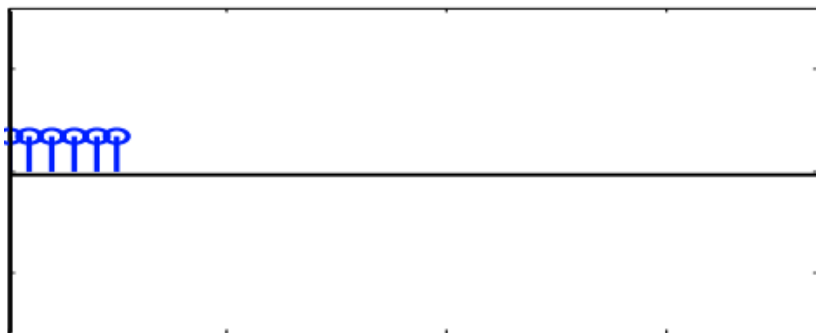
- Break the signal into small blocks
- Compute convolutions (via DFT)
- Combine the results
 - Overlap-add
 - Overlap-save



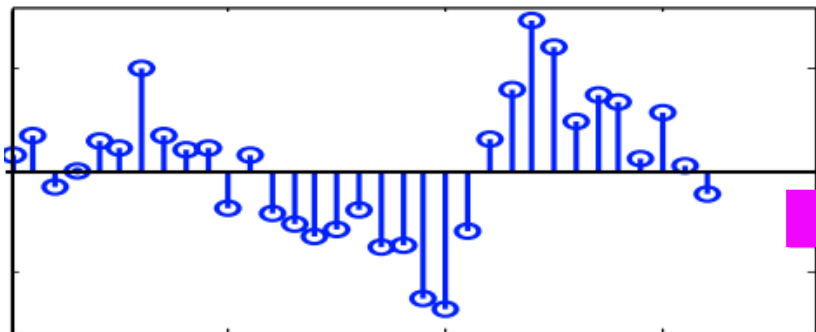
Block Convolution

Example:

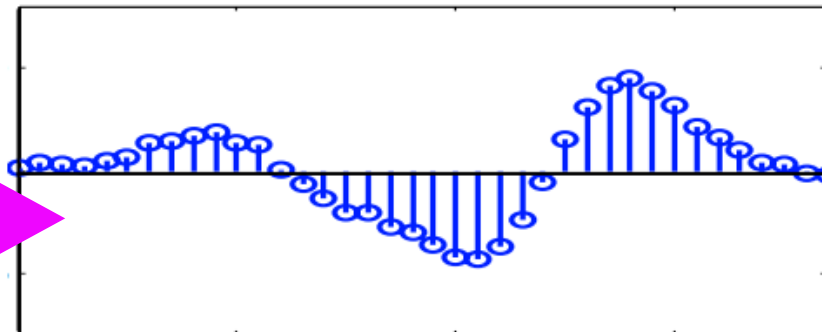
$h[n]$ Impulse response, Length $P=6$



$x[n]$ Input Signal, Length $P=33$



$y[n]$ Output Signal, Length $P=38$





Overlap-Add Method

- Decompose into non-overlapping segments

$$x_r[n] = \begin{cases} x[n] & rL \leq n < (r+1)L \\ 0 & \text{otherwise} \end{cases}$$

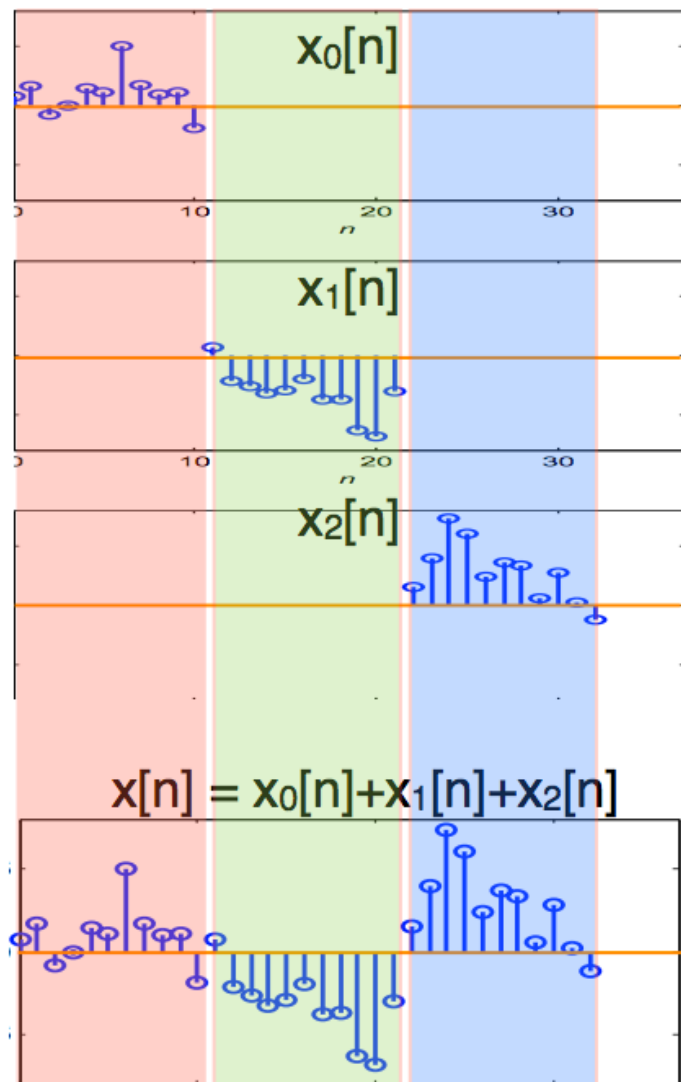
- The input signal is the sum of segments

$$x[n] = \sum_{r=0}^{\infty} x_r[n]$$



Example

$L=11$





Overlap-Add Method

$$x[n] = \sum_{r=0}^{\infty} x_r[n]$$

□ The output is:

$$y[n] = x[n] * h[n] = \sum_{r=0}^{\infty} x_r[n] * h[n]$$

- Each output segment $x_r[n] * h[n]$ is length $M=L+P-1$
 - $h[n]$ has length P
 - $x_r[n]$ has length L



Overlap-Add Method

- ❑ We can compute $x_r[n] * h[n]$ using circular convolution with the DFT
- ❑ Using the DFT:
 - Zero-pad $x_r[n]$ to length M
 - Zero-pad $h[n]$ to length M and compute $\text{DFT}_M\{h_{zp}[n]\}$
 - Only need to do once!



Overlap-Add Method

- ❑ We can compute $x_r[n] * h[n]$ using circular convolution with the DFT
- ❑ Using the DFT:
 - Zero-pad $x_r[n]$ to length M
 - Zero-pad $h[n]$ to length M and compute $\text{DFT}_N\{h_{zp}[n]\}$
 - Only need to do once!
 - Compute:

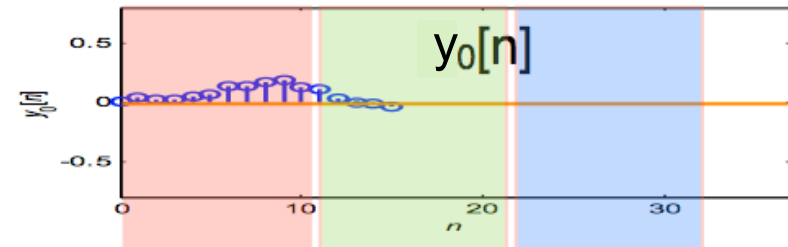
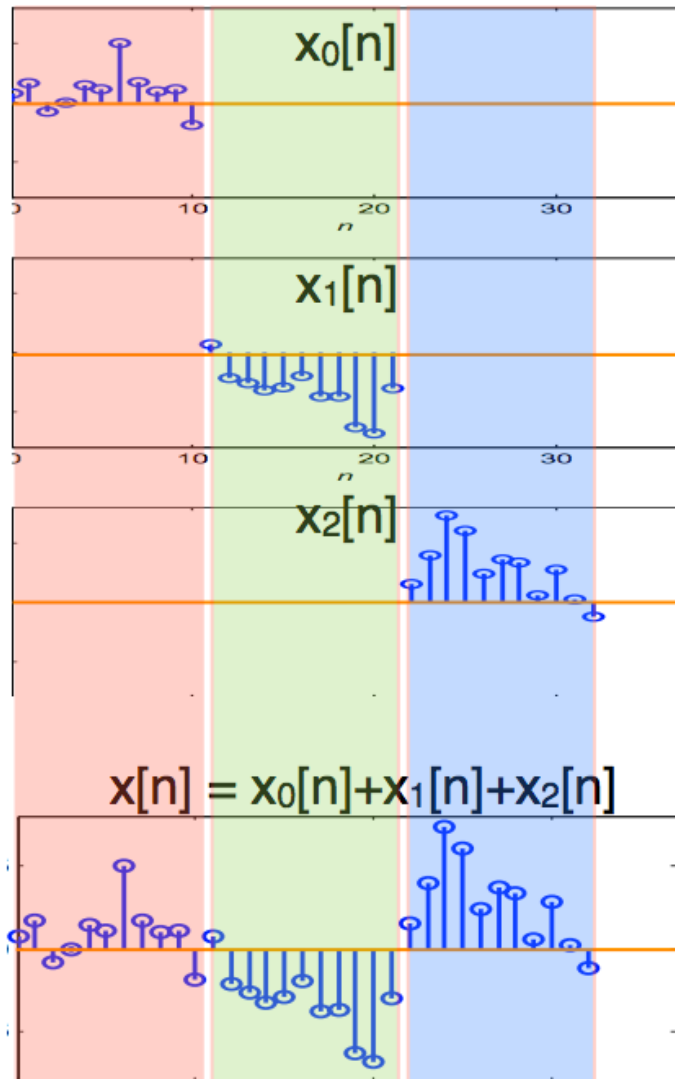
$$x_r[n] * h[n] = \text{DFT}^{-1} \{ \text{DFT}\{x_{r,zp}[n]\} \cdot \text{DFT}\{h_{zp}[n]\} \}$$

- ❑ Results are of length $M=L+P-1$
 - Neighboring results overlap by $P-1$
 - Add overlaps to get final sequence

Example of Overlap-Add

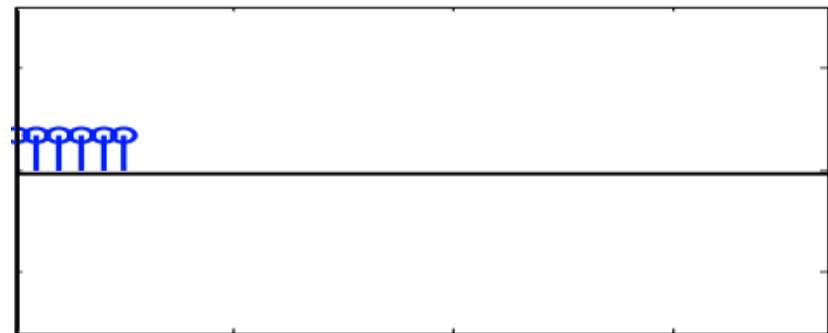
$$L+P-1=16$$

$L=11$



Example:

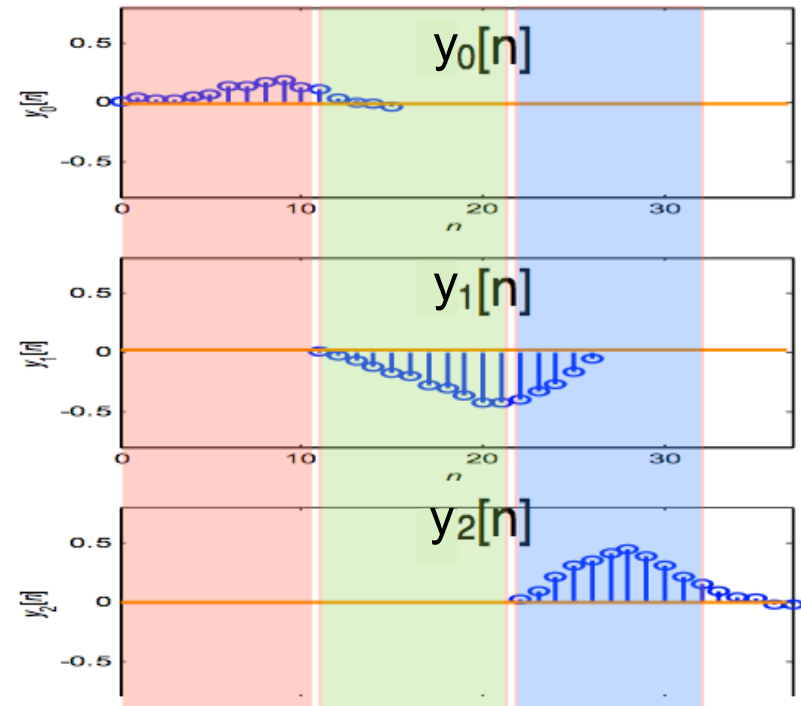
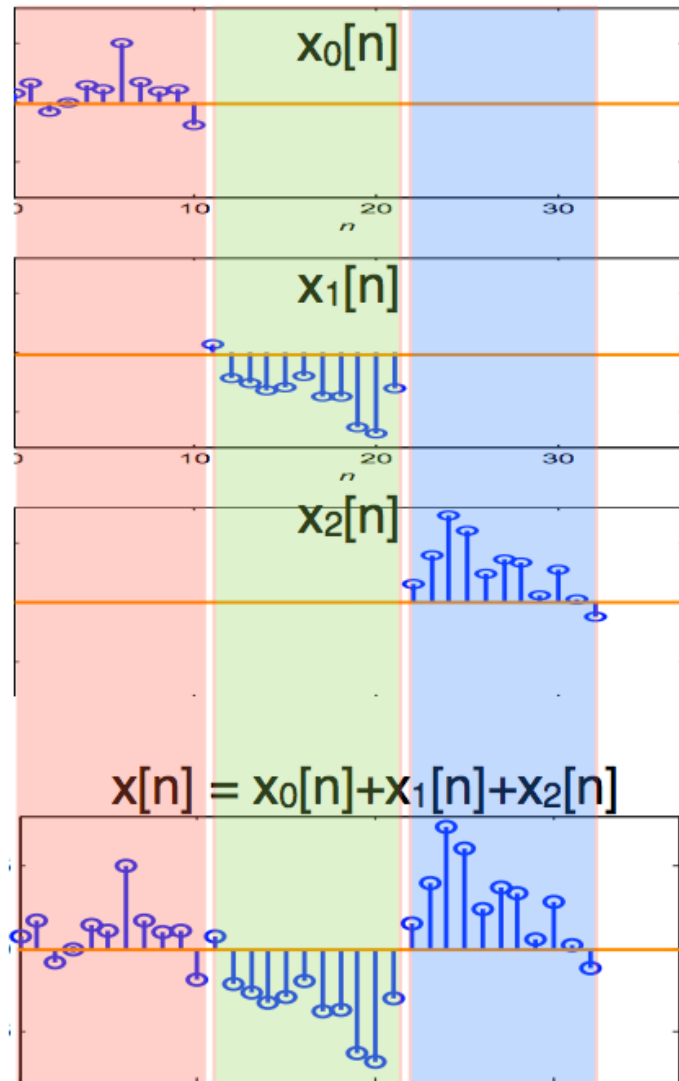
$h[n]$ Impulse response, Length $P=6$



Example of Overlap-Add

$$L+P-1=16$$

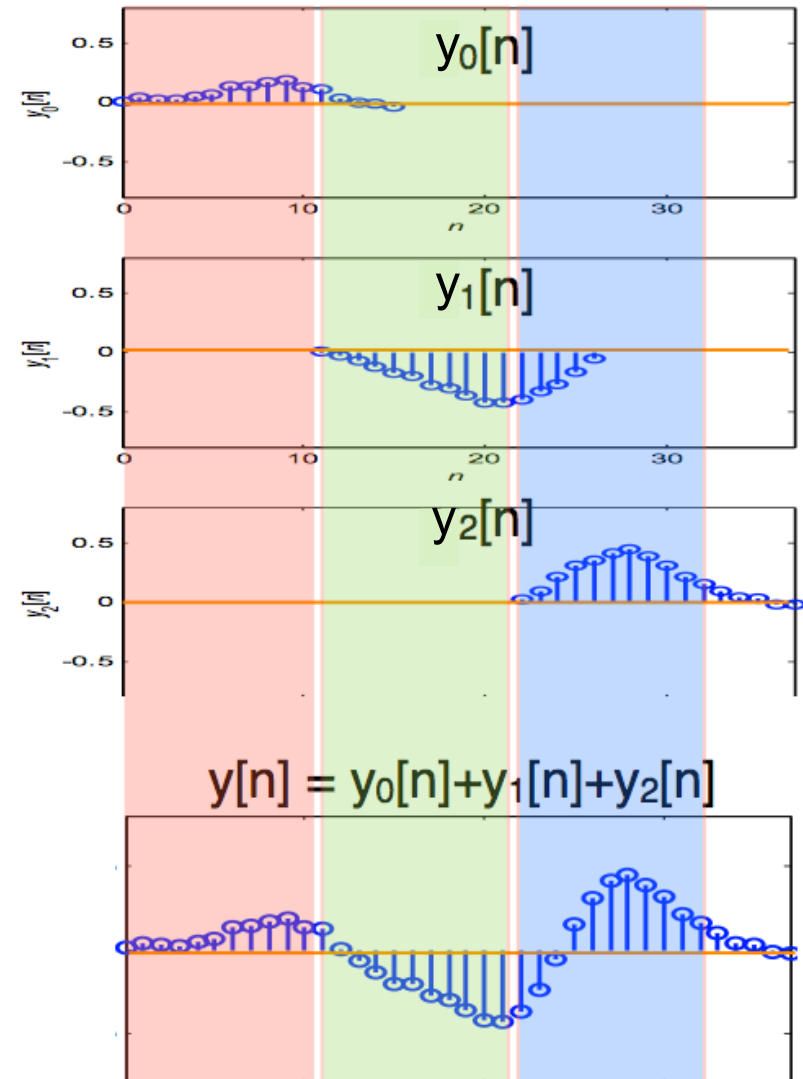
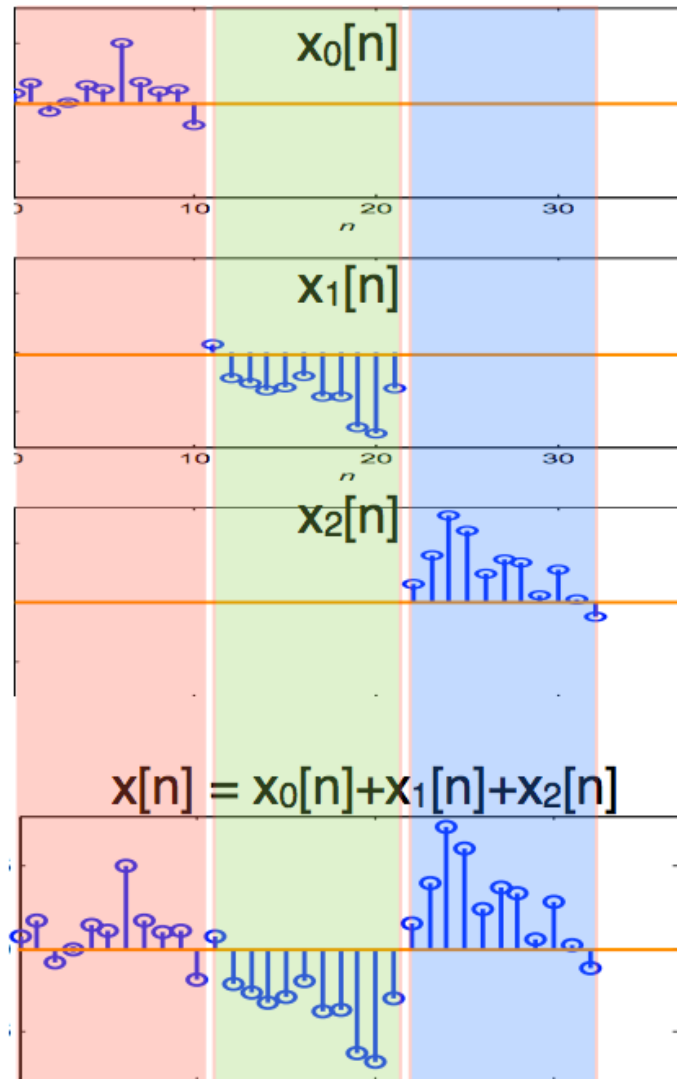
$$L=11$$



Example of Overlap-Add

$$L+P-1=16$$

$L=11$





Overlap-Save Method

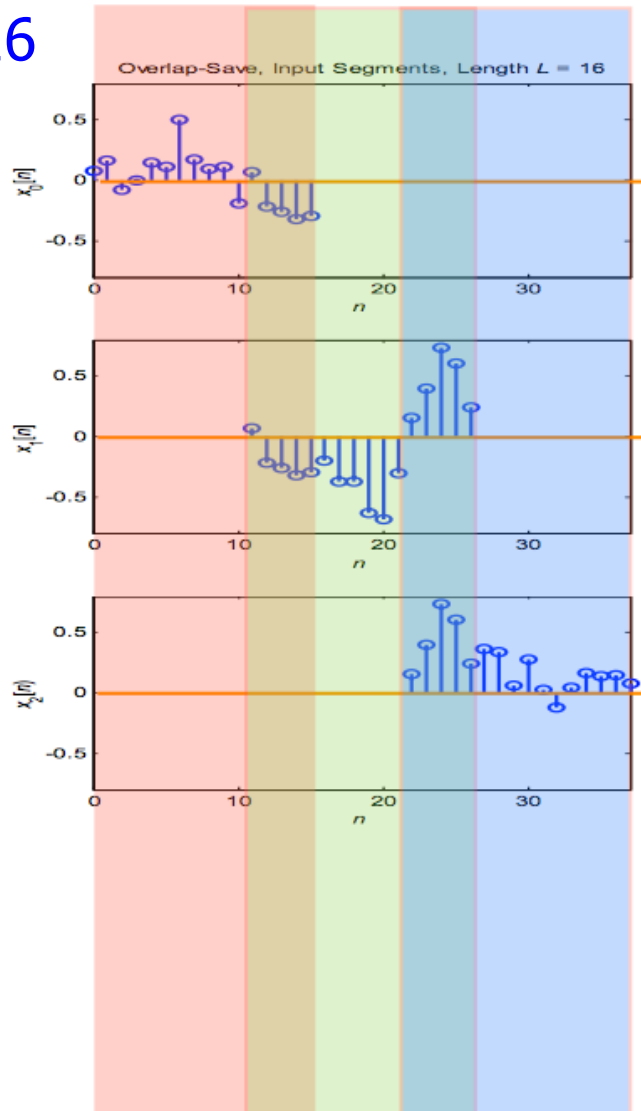
- ❑ Basic idea:
- ❑ Split input into overlapping segments with length $L+P-1$
 - $P-1$ sample overlap

$$x_r[n] = \begin{cases} x[n] & rL \leq n < (r+1)L + P \\ 0 & \text{otherwise} \end{cases}$$

- ❑ Perform circular convolution in each segment, and keep the L sample portion which is a valid linear convolution

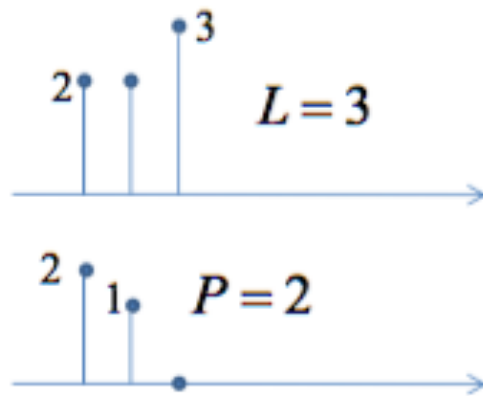
Example of Overlap-Save

$$L+P-1=16$$



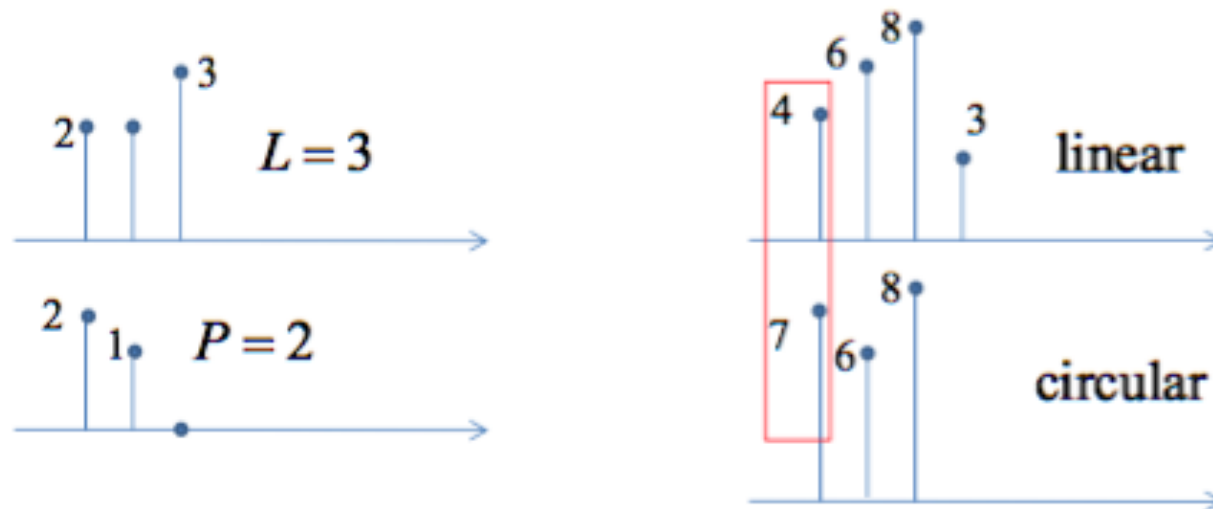
Circular to Linear Convolution

- ❑ An L -point sequence circularly convolved with a P -point sequence
 - with $L - P$ zeros padded, $P < L$
- ❑ gives an L -point result with
 - the first $P - 1$ values *incorrect* and
 - the next $L - P + 1$ the *correct* linear convolution result



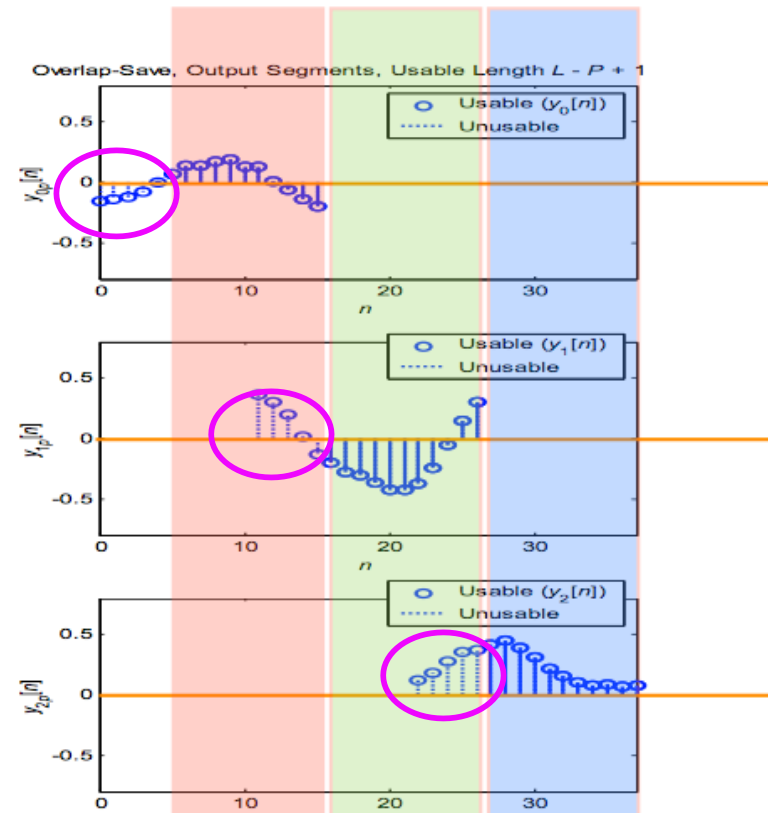
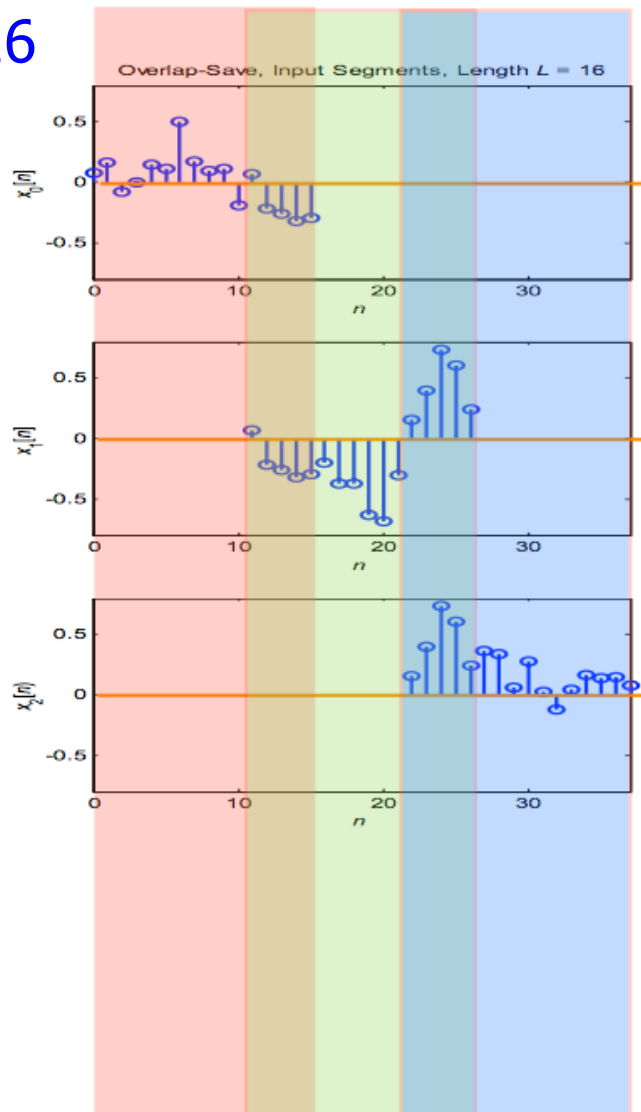
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Example of Overlap-Save

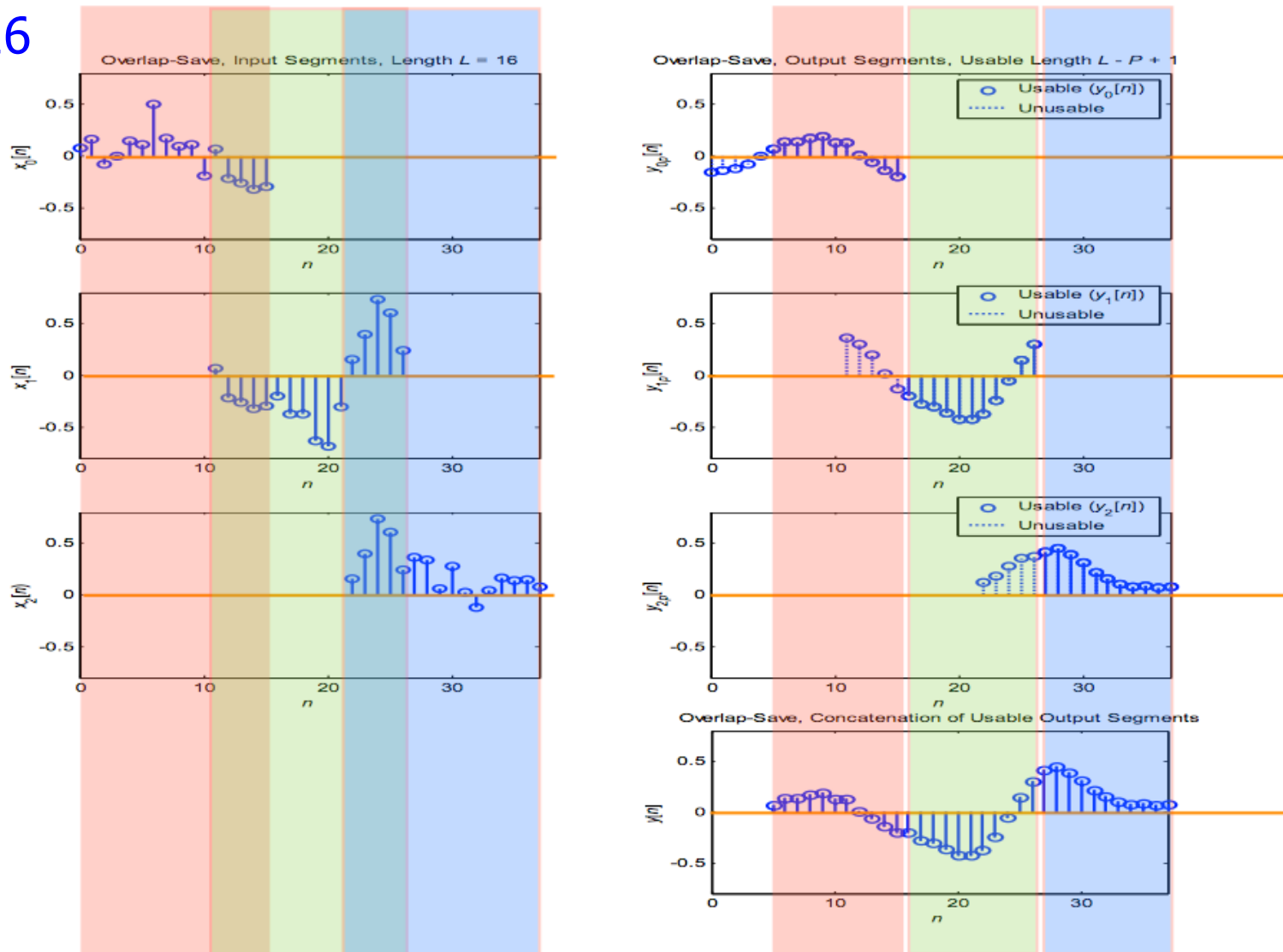
$$L+P-1=16$$




$P-1=5$
Overlap
samples

Example of Overlap-Save

$$L+P-1=16$$



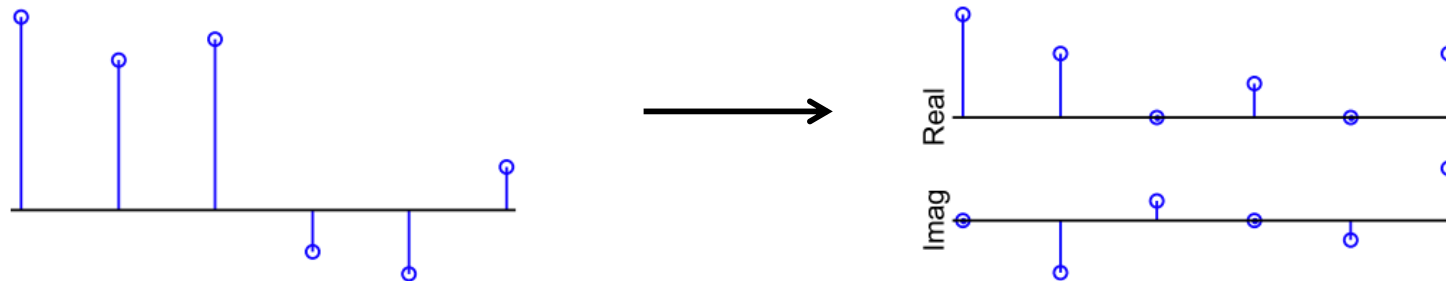


Discrete Cosine Transform

- ❑ Similar to the discrete Fourier transform (DFT), but using only real numbers
- ❑ Widely used in lossy compression applications (eg. Mp3, JPEG)
- ❑ Why use it?

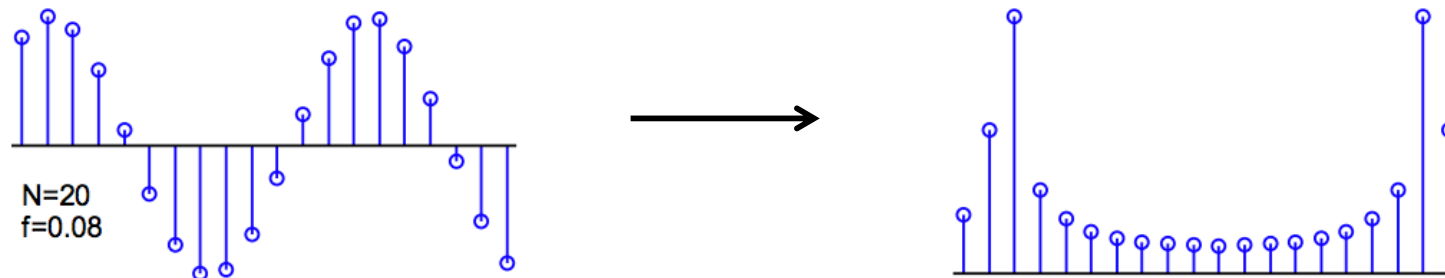
DFT Problems

- ❑ For processing 1-D or 2-D signals (especially coding), a common method is to divide the signal into “frames” and then apply an invertible transform to each frame that compresses the information into few coefficients.
- ❑ The DFT has some problems when used for this purpose:
 - N real $x[n] \leftrightarrow N$ complex $X[k]$: 2 real, $N/2 - 1$ conjugate pairs
 - DFT is of the periodic signal formed by replicating $x[n]$




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 - N real $x[n] \leftrightarrow N$ complex $X[k]$: 2 real, $N/2 - 1$ conjugate pairs
 - DFT is of the periodic signal formed by replicating $x[n]$
 \Rightarrow Spurious frequency components from boundary discontinuity



The Discrete Cosine Transform (DCT) overcomes these problems.



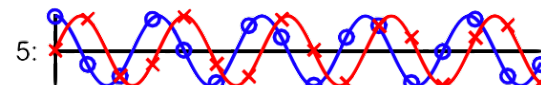
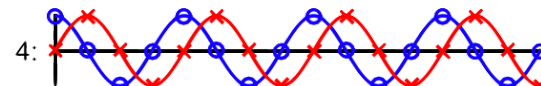
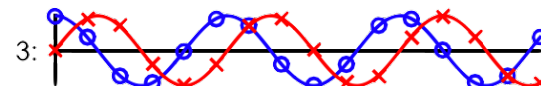
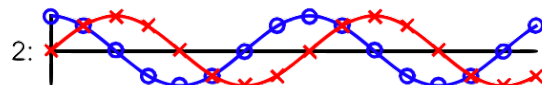
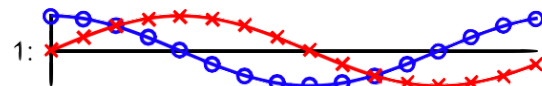
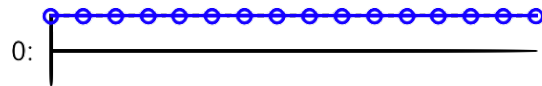
Discrete Cosine Transform

Forward DCT: $X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$ for $k = 0 : N - 1$

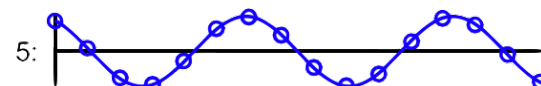
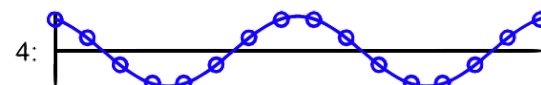
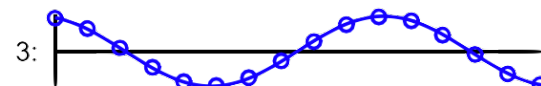
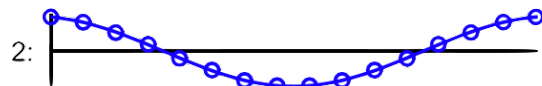
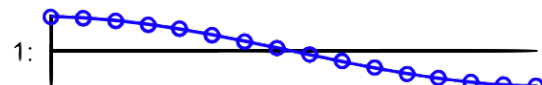
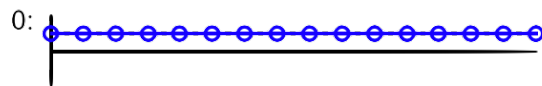
Inverse DCT: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$

Basis Functions

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$

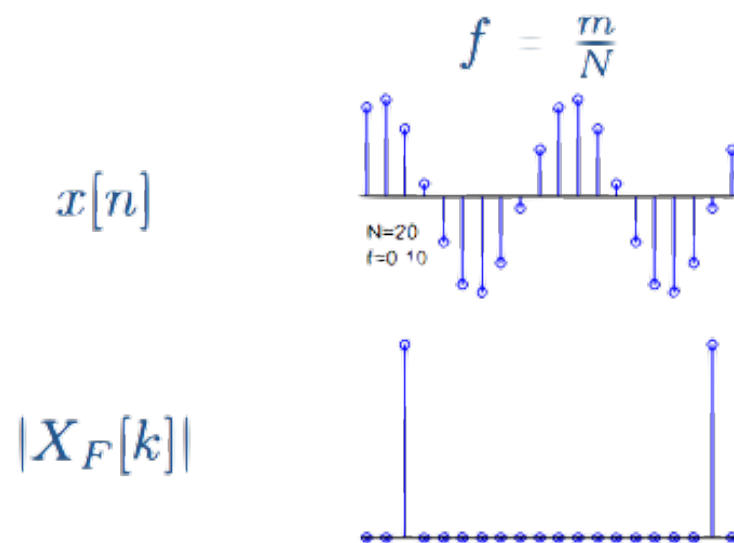


DCT basis functions: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$

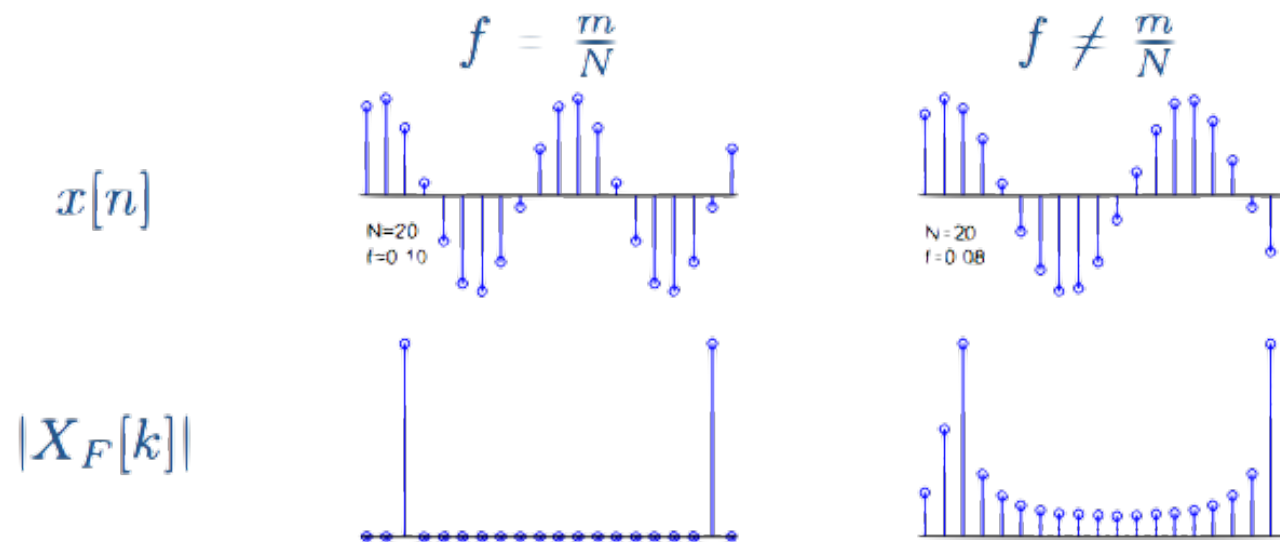




DFT of Sine Wave

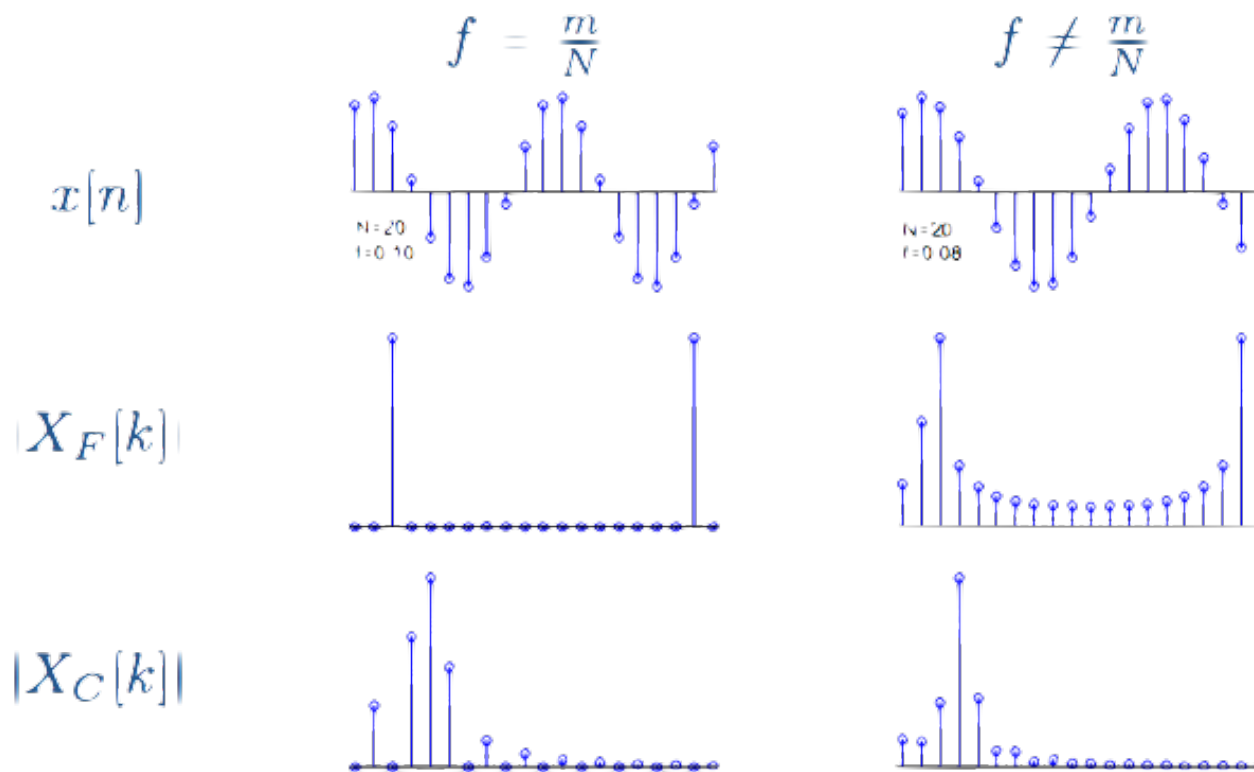


DFT of Sine Wave



DFT: Real \rightarrow Complex; Freq range $[0, 1]$; Poorly localized unless $f = \frac{m}{N}$; $|X_F[k]| \propto k^{-1}$ for $Nf < k \ll \frac{N}{2}$

DCT of Sine Wave



- DFT:** Real \rightarrow Complex; Freq range $[0, 1]$; Poorly localized unless $f = \frac{m}{N}$; $|X_F[k]| \propto k^{-1}$ for $Nf < k \ll \frac{N}{2}$
- DCT:** Real \rightarrow Real; Freq range $[0, 0.5]$; Well localized $\forall f$; $|X_C[k]| \propto k^{-2}$ for $2Nf < k < N$



Big Ideas

- ❑ Discrete Fourier Transform (DFT)
 - For finite signals assumed to be zero outside of defined length
 - N-point DFT is sampled DTFT at N points
 - DFT properties inherited from DFS, but circular operations!
- ❑ Fast Convolution Methods
 - Use circular convolution (i.e DFT) to perform fast linear convolution
 - Overlap-Add, Overlap-Save
- ❑ DCT useful for frame rate compression of large signals



Admin

- ❑ Project 1
 - Due Monday 4/5 (can turn in by 4/9 with no penalty)
- ❑ HW 7 out now