

ESE 531: Digital Signal Processing

Lecture 7: February 3, 2022
Sampling and Reconstruction



Lecture Outline

- ❑ Sampling
 - Frequency Response of Sampled Signal
- ❑ Reconstruction
- ❑ Anti-aliasing Filter

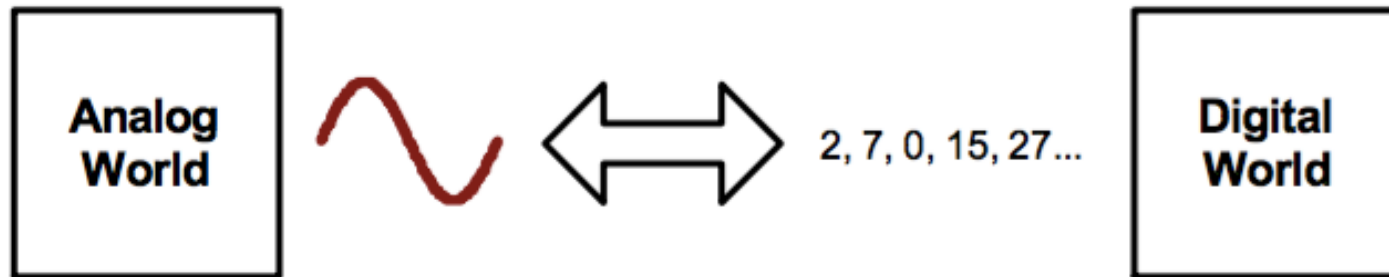


Video Example



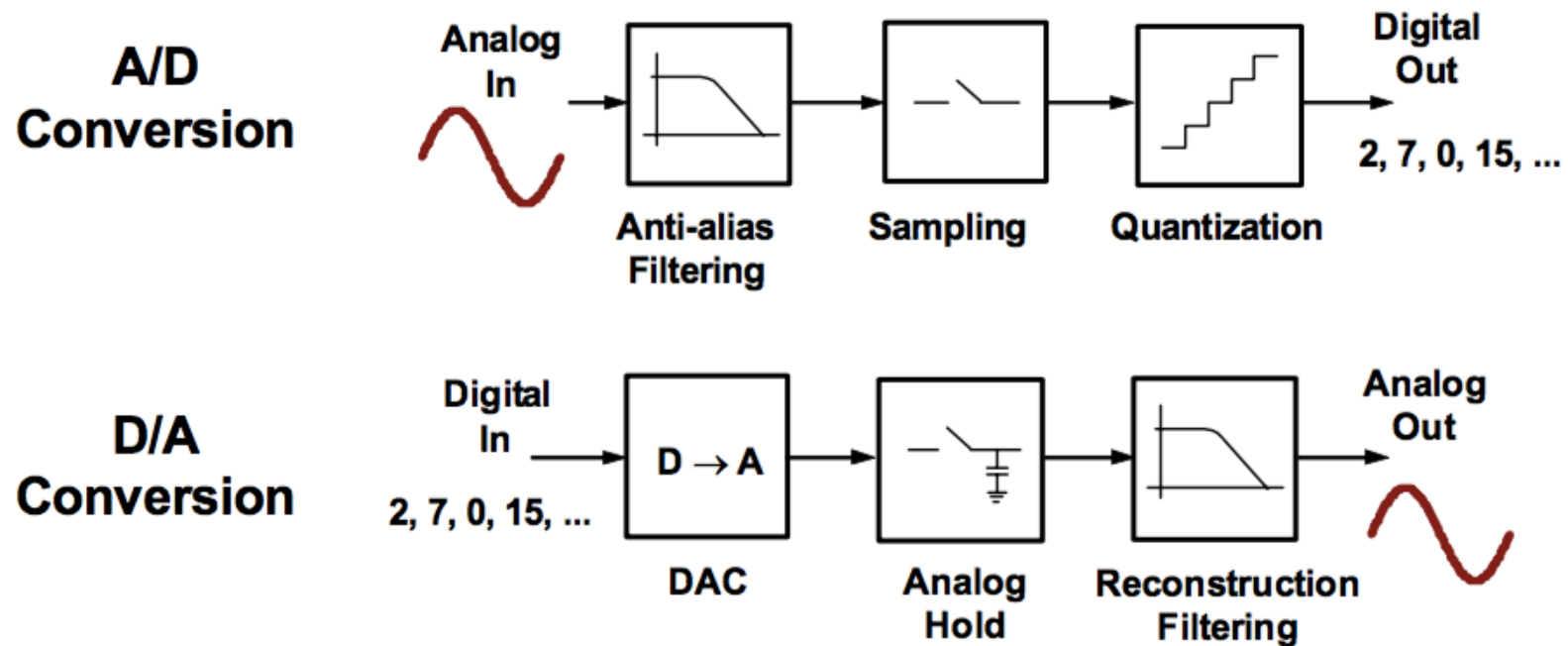
❑ <https://www.youtube.com/watch?v=ByTsISFXUoY>

The Data Conversion Problem



- ❑ Real world signals
 - Continuous time, continuous amplitude
- ❑ Digital abstraction
 - Discrete time, discrete amplitude
- ❑ Two problems
 - How to go discretize in time and amplitude
 - A/D conversion
 - How to "undescretize" in time and amplitude
 - D/A conversion

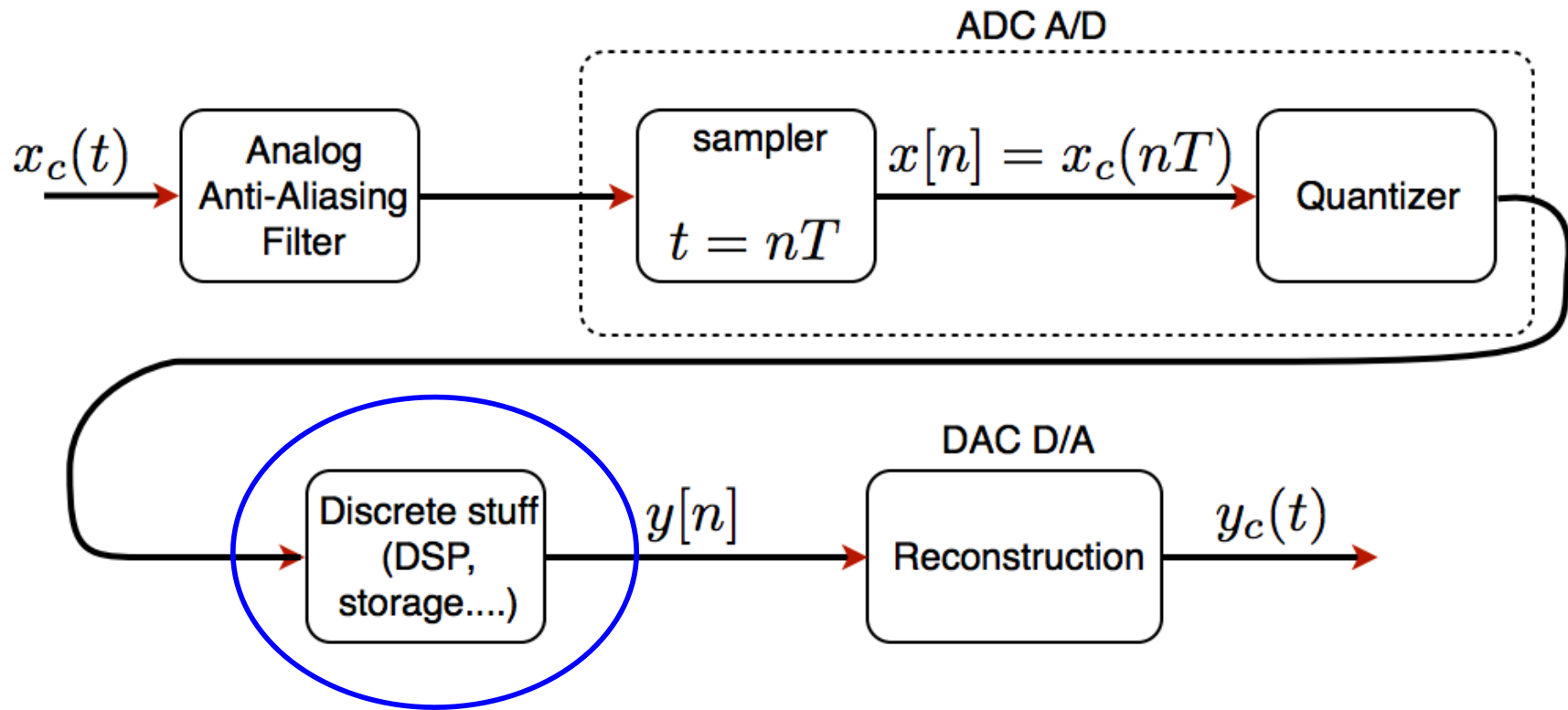
Overview



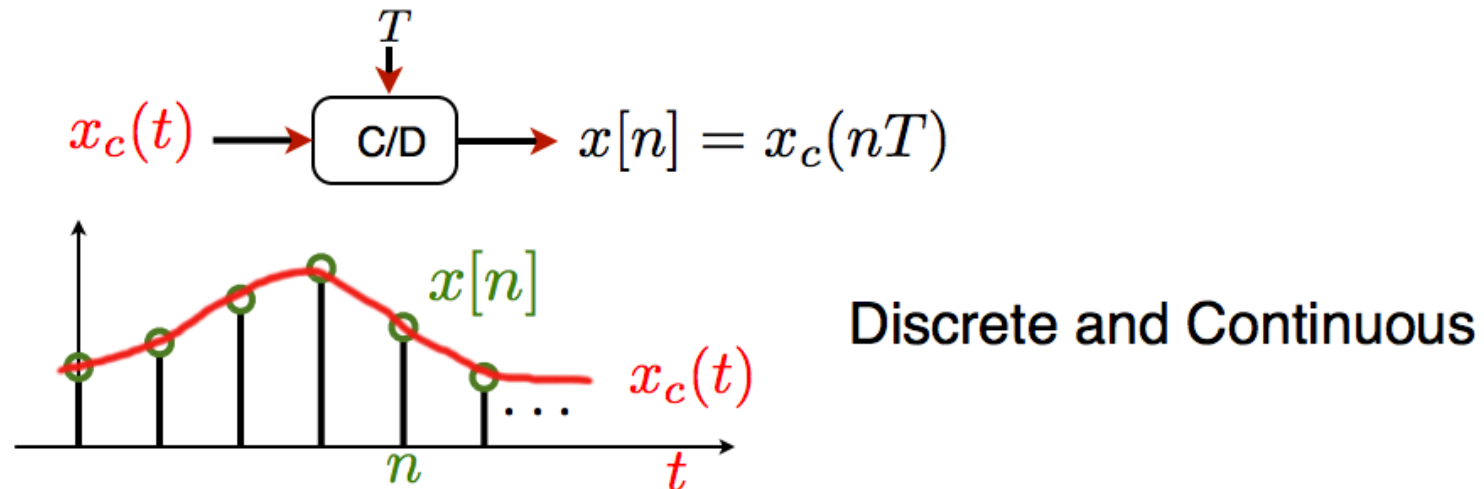
- We'll first look at these building blocks from a functional, "black box" perspective



DSP System

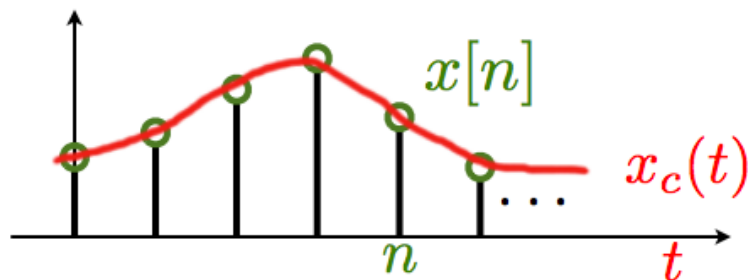
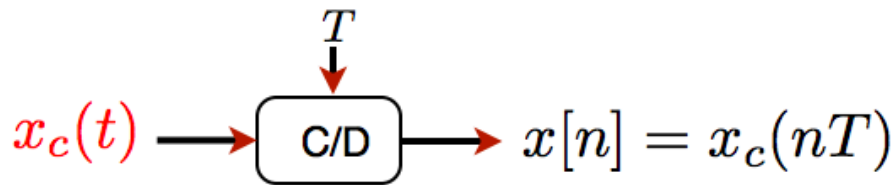


Ideal Sampling Model



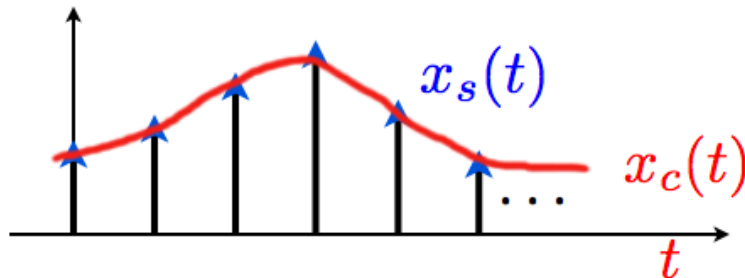
- ❑ Ideal continuous-to-discrete time (C/D) converter
 - T is the sampling period
 - $f_s = 1/T$ is the sampling frequency
 - $\Omega_s = 2\pi/T$

Ideal Sampling Model



Discrete and Continuous

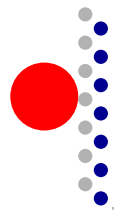
define impulsive sampling:



Continuous

$$x_s(t) = \cdots + x_c(0)\delta(t) + x_c(T)\delta(t - T) + \cdots$$

$$x_s(t) = x_c \sum_{n=-\infty}^{\infty} \delta(t - nT)$$



Ideal Sampling Model

$$x_s(t) = x_c \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

- Dirac delta function, $\delta(t)$
 - Infinitely high and thin, area of 1
 - Not physical—for modeling

$$x[n] \leftrightarrow x_s(t) \leftrightarrow x_c(t)$$

- Three signals. How are they related? In time? In frequency?



Reminder: Laplace Transform

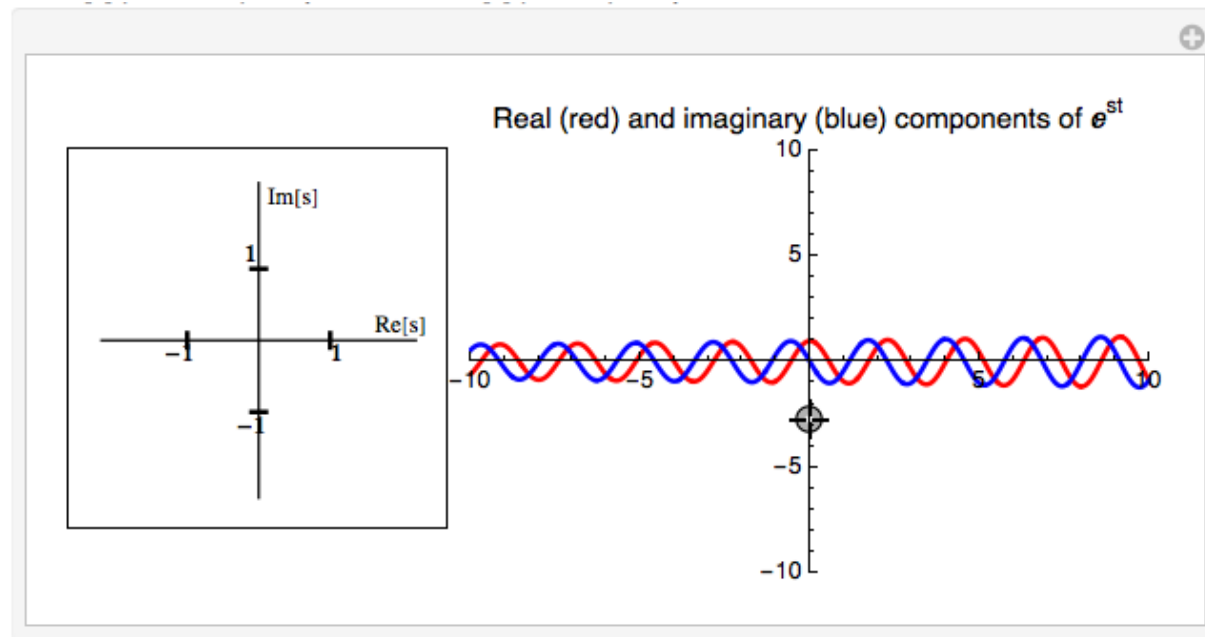
- ❑ The Laplace transform takes a function of time, t , and transforms it to a function of a complex variable, s .
- ❑ Because the transform is invertible, no information is lost, and it is reasonable to think of a function $f(t)$ and its Laplace transform $F(s)$ as two views of the same phenomenon.
- ❑ Each view has its uses, and some features of the phenomenon are easier to understand in one view or the other.



S-Plane

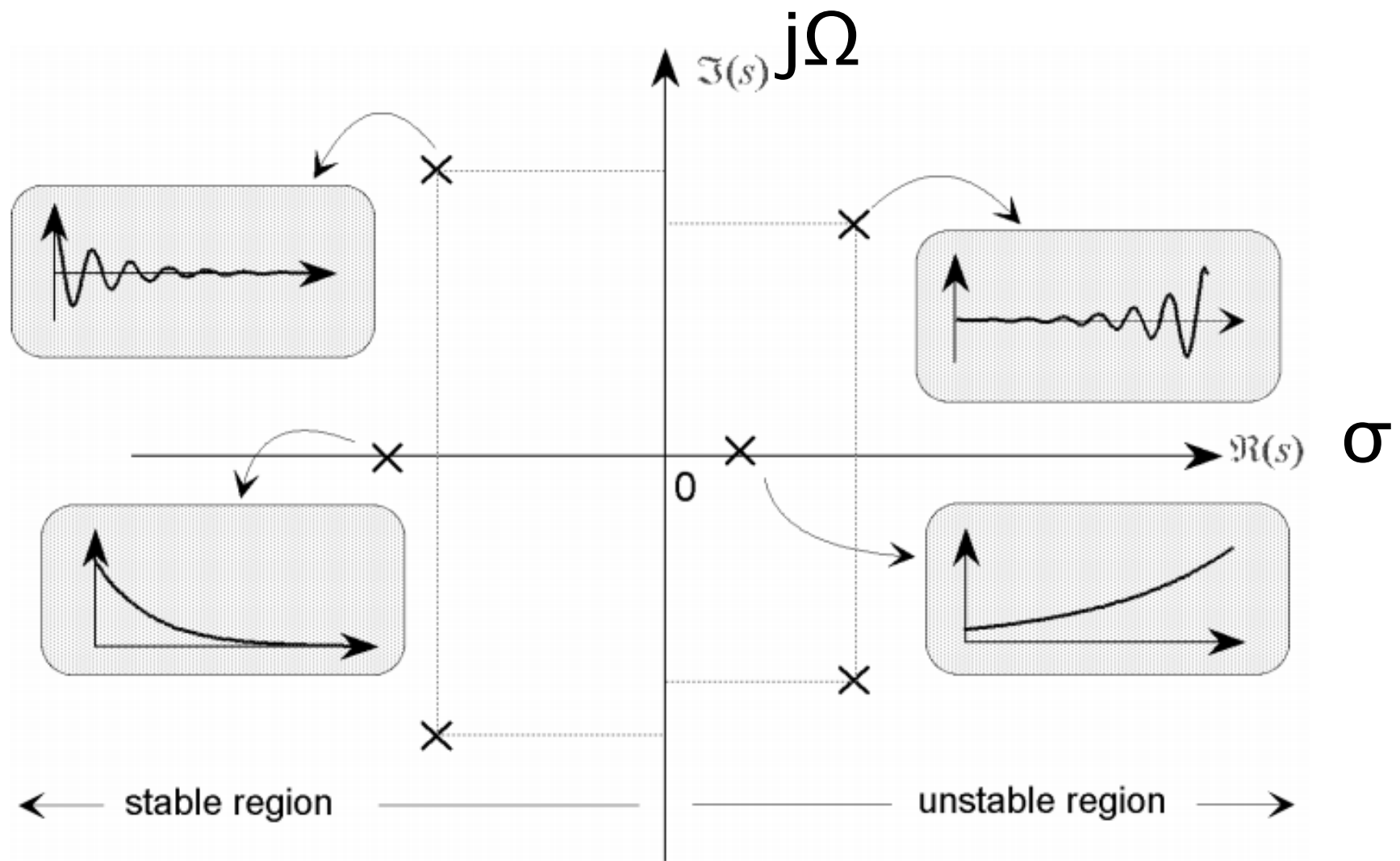
□ $s = \sigma + j\Omega$

□ Wolfram Demo

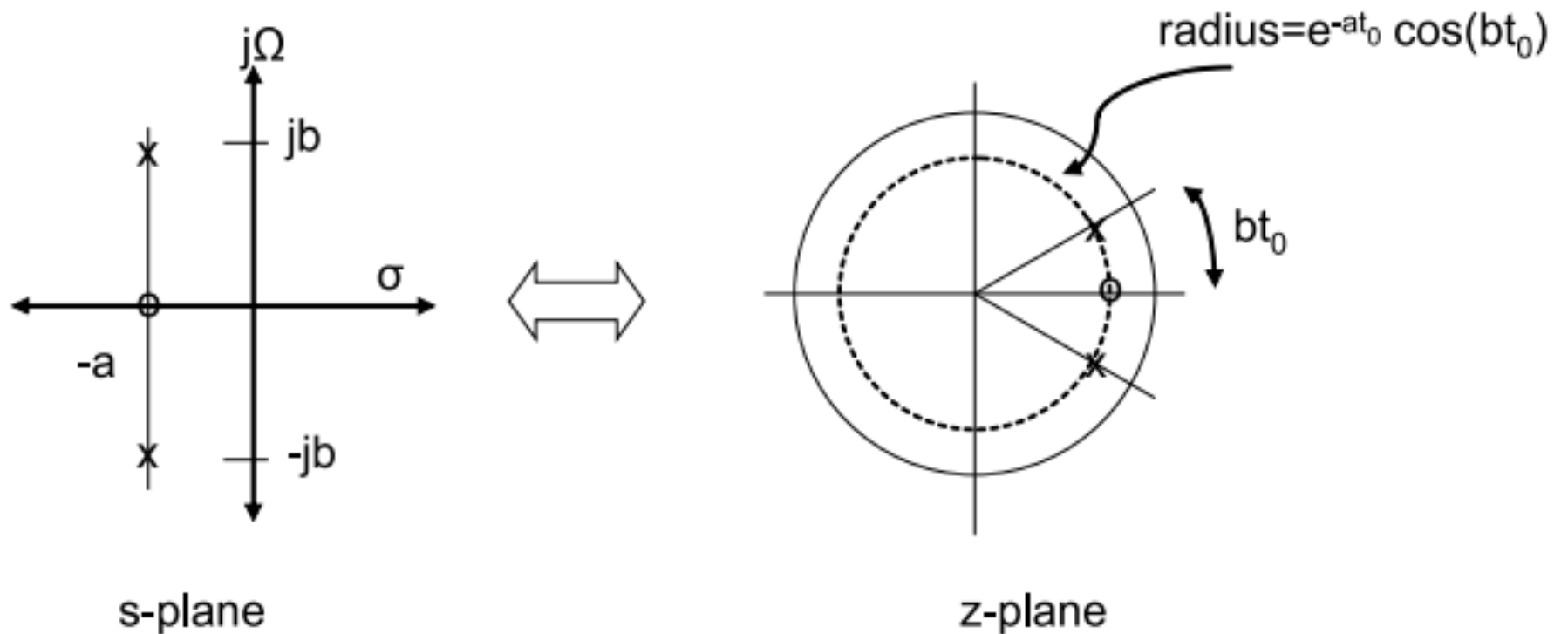




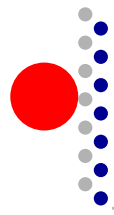
S-plane and stability



S-Plane Mapping to Z-Plane



t_0 = sampling period



Frequency Domain Analysis

- How is $x[n]$ related to $x_s(t)$ in frequency domain?

$$x[n] = x_c(nT) \qquad x_s(t) = x_c \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

Frequency Domain Analysis

- How is $x[n]$ related to $x_s(t)$ in frequency domain?

$$x[n] = x_c(nT) \qquad x_s(t) = x_c \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

$$x_s(t) \quad : \text{C.T.}$$

$$X_s(j\Omega) = \sum_n x_c(nT) e^{-j\Omega nT}$$

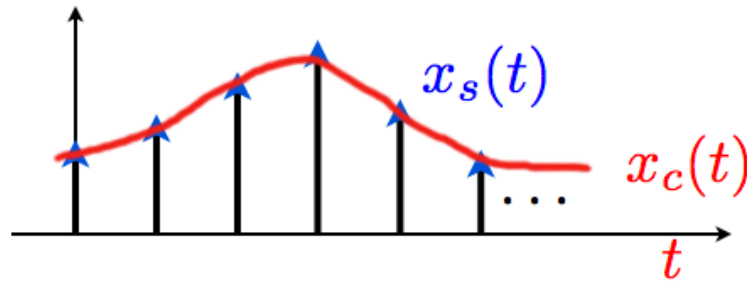
$$x[n] \quad : \text{D.T.}$$

$$X(e^{j\omega}) = \sum_n x[n] e^{-j\omega n} \qquad \omega = \Omega T$$

$$X(e^{j\omega}) = X_s(j\Omega)|_{\Omega=\omega/T}$$

$$X_s(j\Omega) = X(e^{j\omega})|_{\omega=\Omega T}$$

Frequency Domain Analysis



Continuous

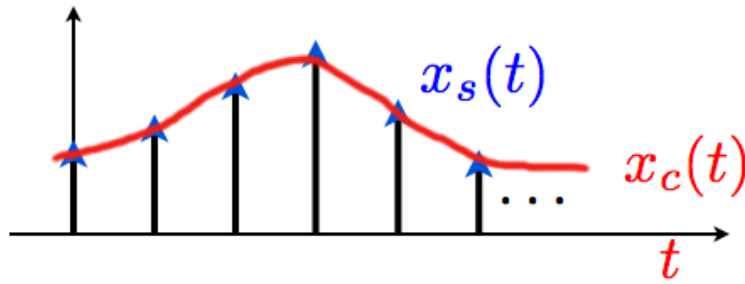
$$x_s(t) = \cdots + x_c(0)\delta(t) + x_c(T)\delta(t - T) + \cdots$$

$$x_s(t) = x_c \underbrace{\sum_{n=-\infty}^{\infty} \delta(t - nT)}_{\triangleq s(t)}$$

$$s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$$



Frequency Domain Analysis



Continuous

$$x_s(t) = \cdots + x_c(0)\delta(t) + x_c(T)\delta(t - T) + \cdots$$

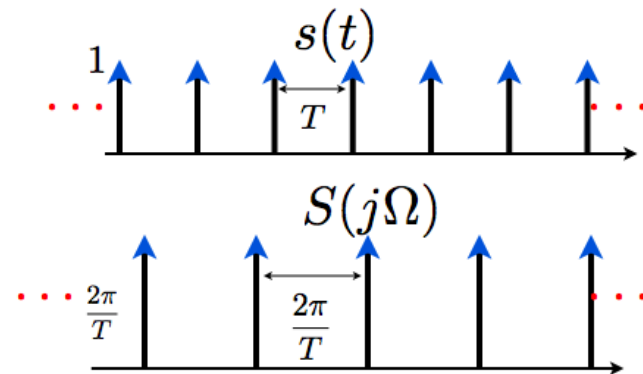
$$x_s(t) = x_c \underbrace{\sum_{n=-\infty}^{\infty} \delta(t - nT)}_{\triangleq s(t)}$$

$$s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

$$s(t) \leftrightarrow S(j\Omega)$$

$$S(j\Omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\Omega - \frac{2\pi}{T}k)$$

$\frac{2\pi}{T} \triangleq \Omega_s$





Frequency Domain Analysis

$$x_s(t) = s(t) \cdot x_c(t)$$



Frequency Domain Analysis

$$x_s(t) = s(t) \cdot x_c(t)$$

$$X_s(j\Omega) = \frac{1}{2\pi} X_c(j\Omega) * S(j\Omega)$$



Frequency Domain Analysis

$$x_s(t) = s(t) \cdot x_c(t)$$

$$X_s(j\Omega) = \frac{1}{2\pi} X_c(j\Omega) * S(j\Omega)$$

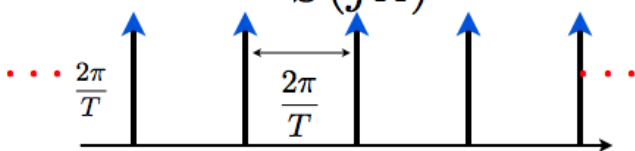
$$S(j\Omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\Omega - \frac{2\pi}{T}k)$$

Diagram illustrating the frequency domain representation of the sampling function $S(j\Omega)$. The impulses are spaced at intervals of $\frac{2\pi}{T}$. The label Ω_s is shown in red, indicating the sampling frequency.

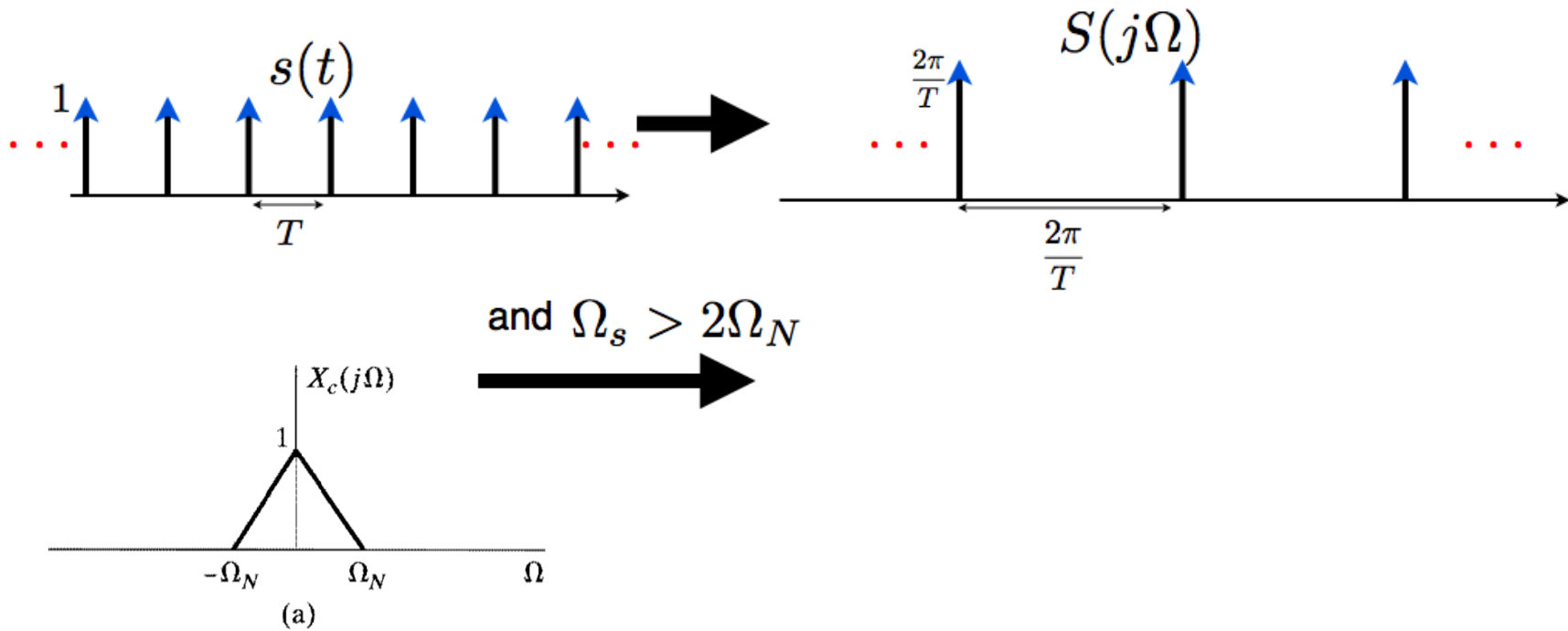
Frequency Domain Analysis

$$x_s(t) = s(t) \cdot x_c(t)$$

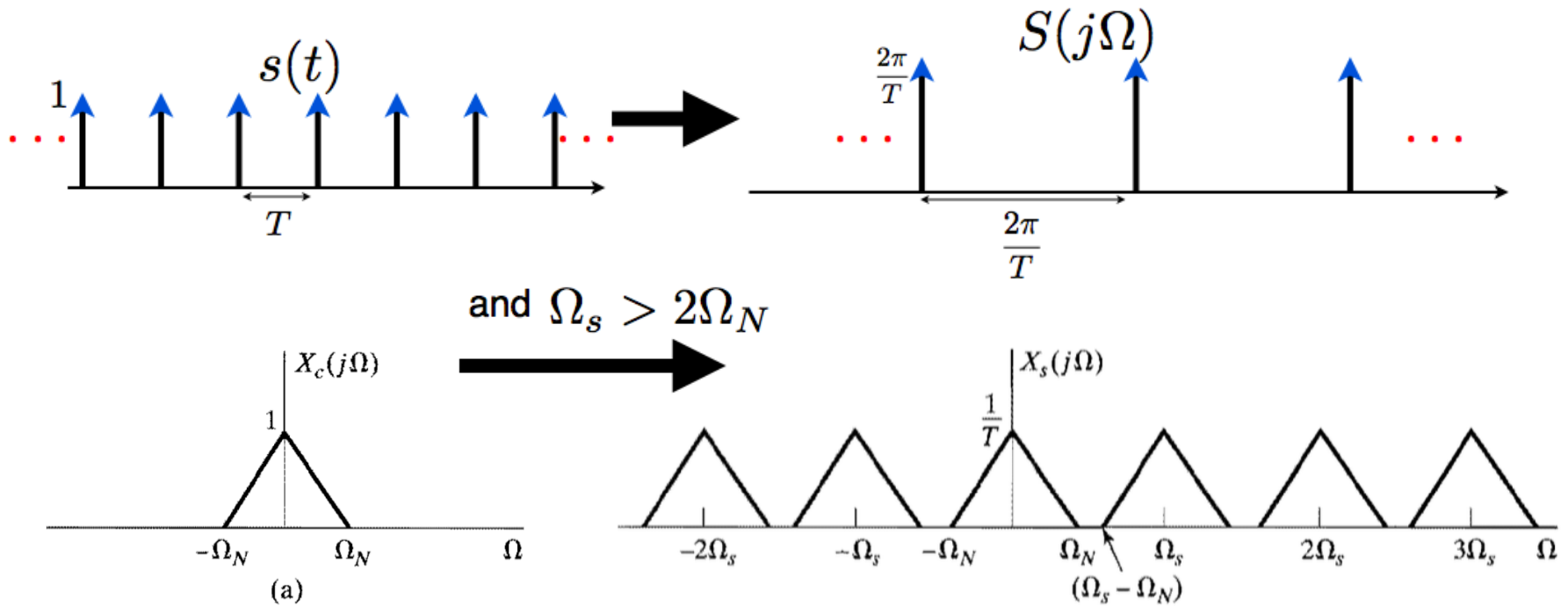
$$\begin{aligned} X_s(j\Omega) &= \frac{1}{2\pi} X_c(j\Omega) * S(j\Omega) \\ &= \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s)) \quad | \quad \Omega_s = \frac{2\pi}{T} \end{aligned}$$

$$S(j\Omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\Omega - \frac{2\pi}{T}k)$$


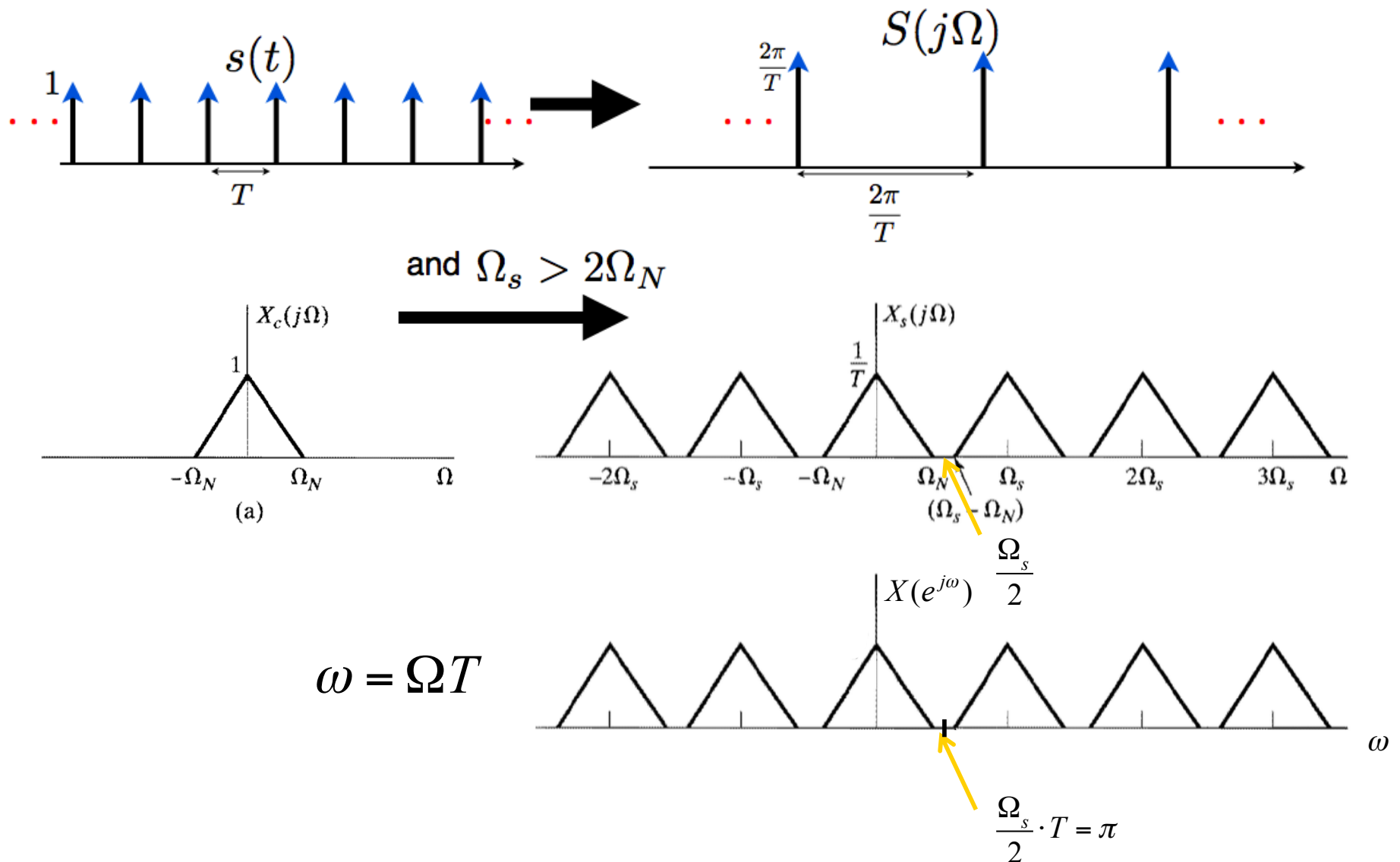
Frequency Domain Analysis



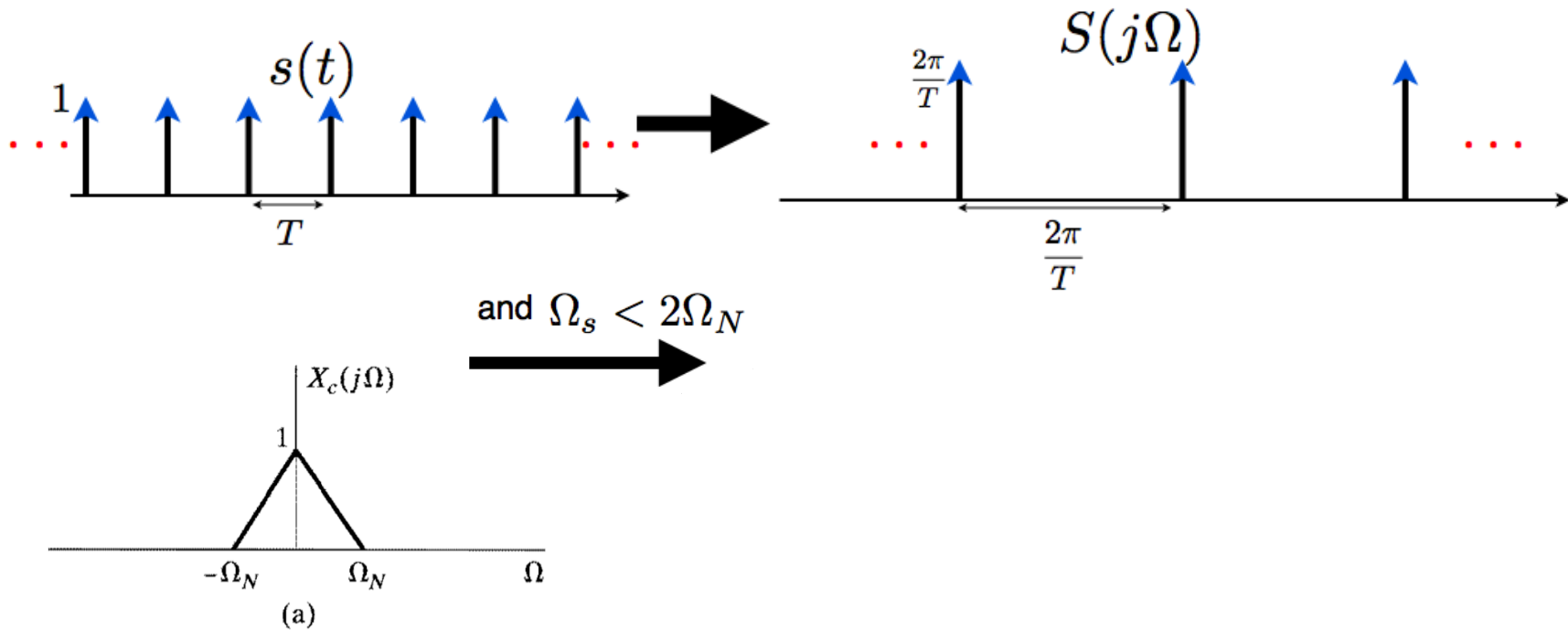
Frequency Domain Analysis



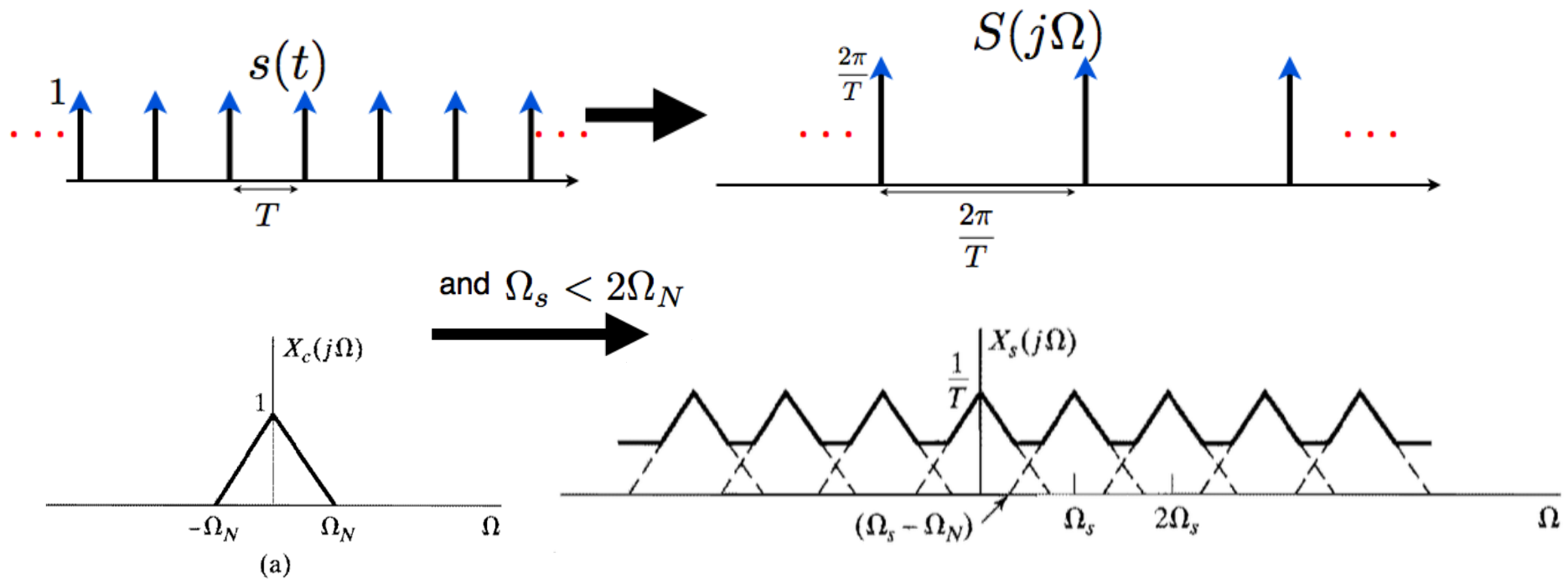
Frequency Domain Analysis



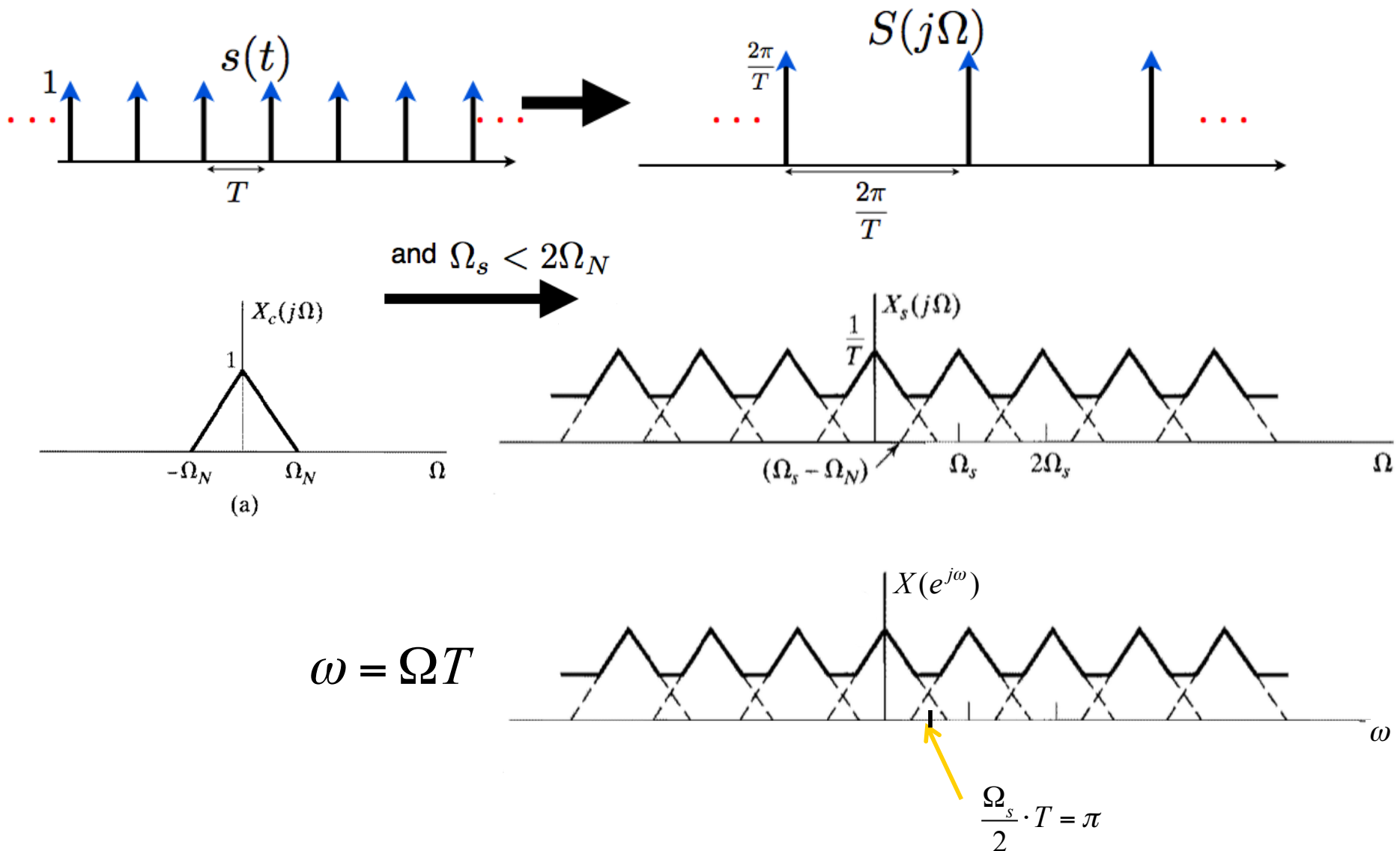
Frequency Domain Analysis w/ Aliasing

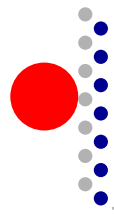


Frequency Domain Analysis w/ Aliasing



Frequency Domain Analysis w/ Aliasing





Example: Cosine Input

- Sample the continuous-time signal $x_c(t) = \cos(4000\pi t)$ with sampling period $T = 1/6000$ s ($f_s = 6$ kHz)

$$\begin{aligned} X_s(j\Omega) &= \frac{1}{2\pi} X_c(j\Omega) * S(j\Omega) \\ &= \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s)) \quad | \quad \Omega_s = \frac{2\pi}{T} \end{aligned}$$



Example: Cosine Input

□ $x_c(t) = \cos(4000\pi t)$, $T = 1/6000$ s ($f_s = 6\text{kHz}$)

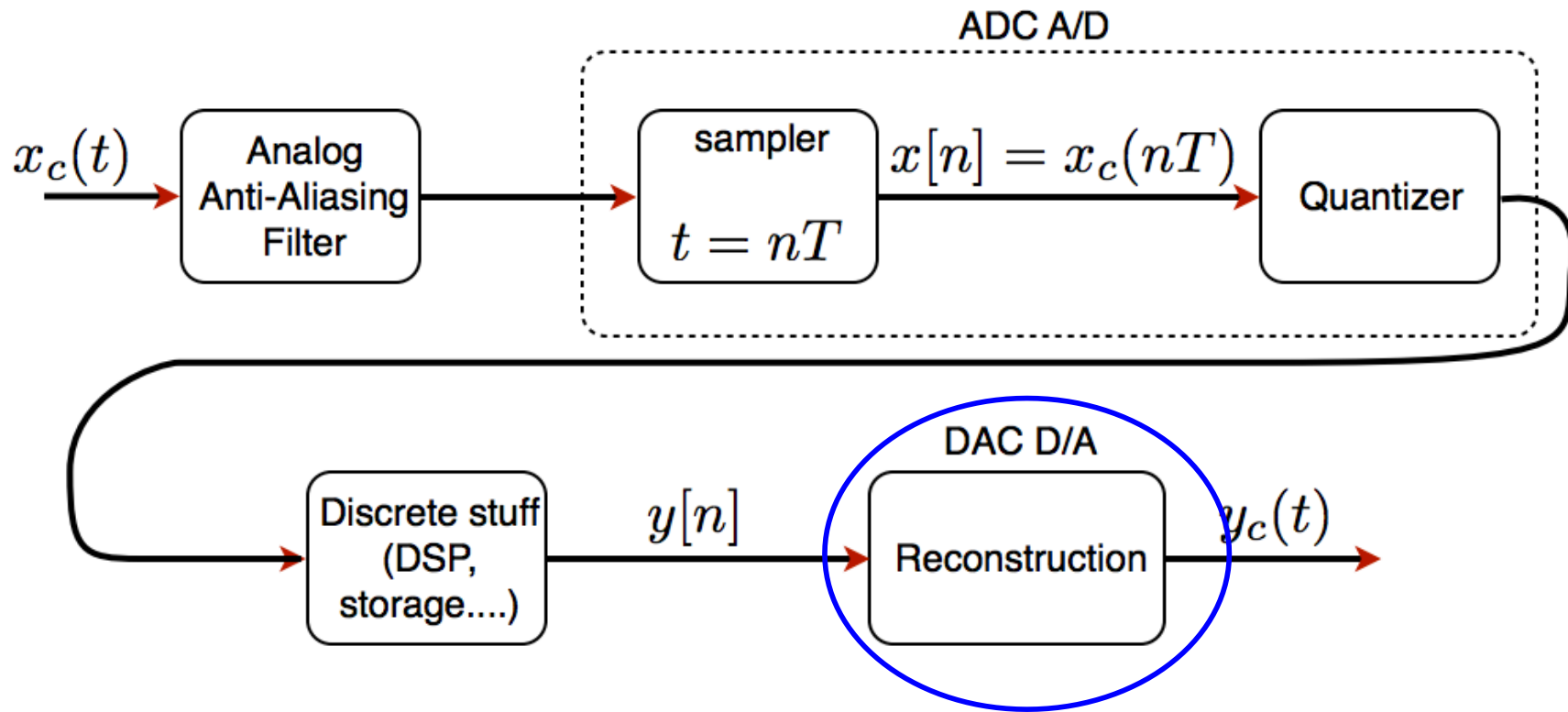


Example: Cosine Input

- Sample the continuous-time signal $x_c(t) = \cos(16000\pi t)$ with sampling period $T = 1/6000$ ($f_s = 6\text{kHz}$)



DSP System

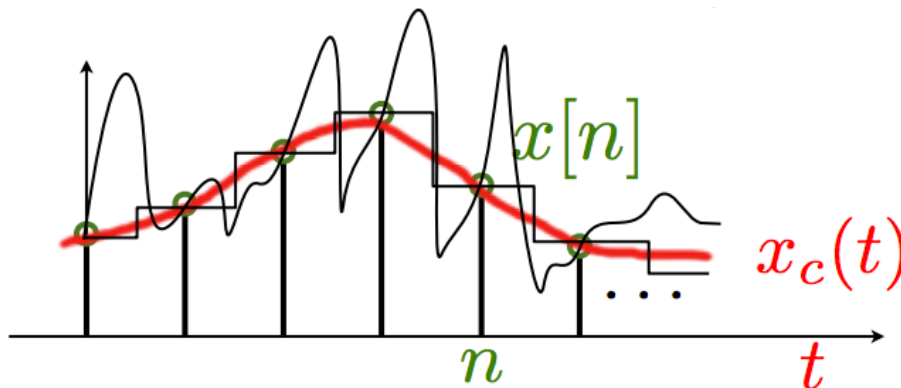


Reconstruction of Bandlimited Signals

- ❑ Nyquist Sampling Theorem: Suppose $x_c(t)$ is bandlimited. I.e.

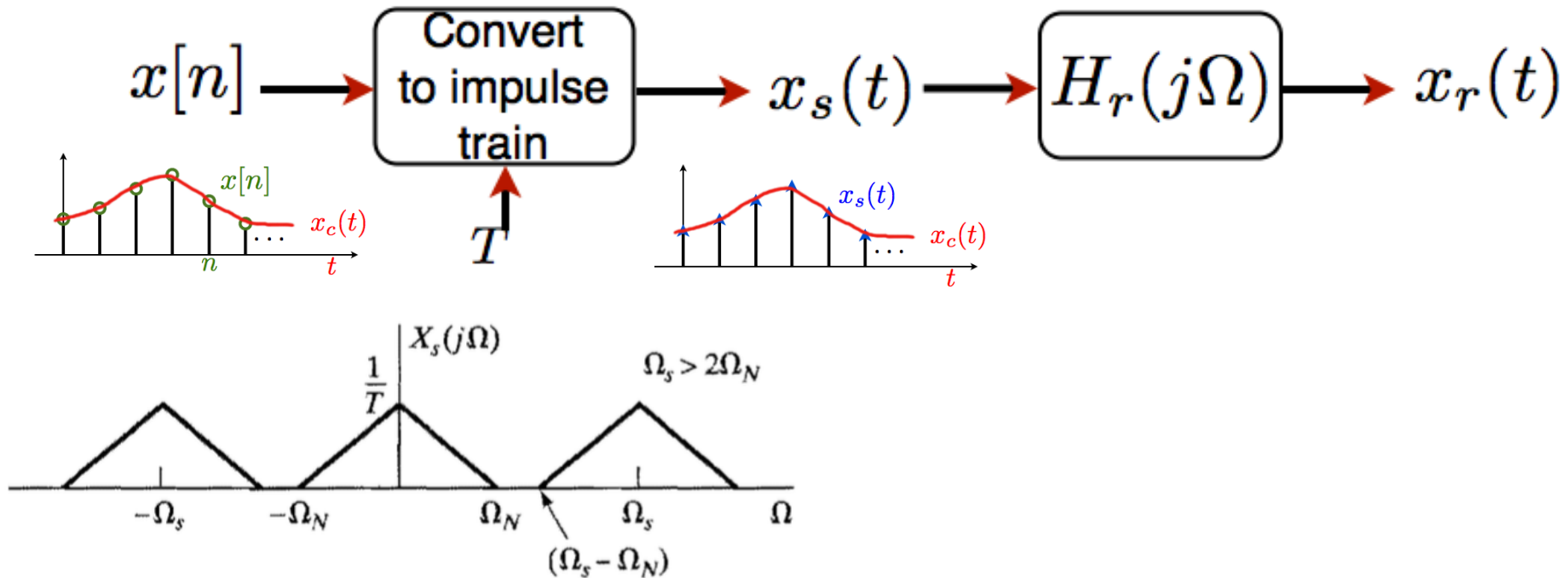
$$X_c(j\Omega) = 0 \quad \forall \quad |\Omega| \geq \Omega_N$$

- ❑ If $\Omega_s \geq 2\Omega_N$, then $x_c(t)$ can be uniquely determined from its samples $x[n] = x_c(nT)$
- ❑ Bandlimitedness is the key to uniqueness

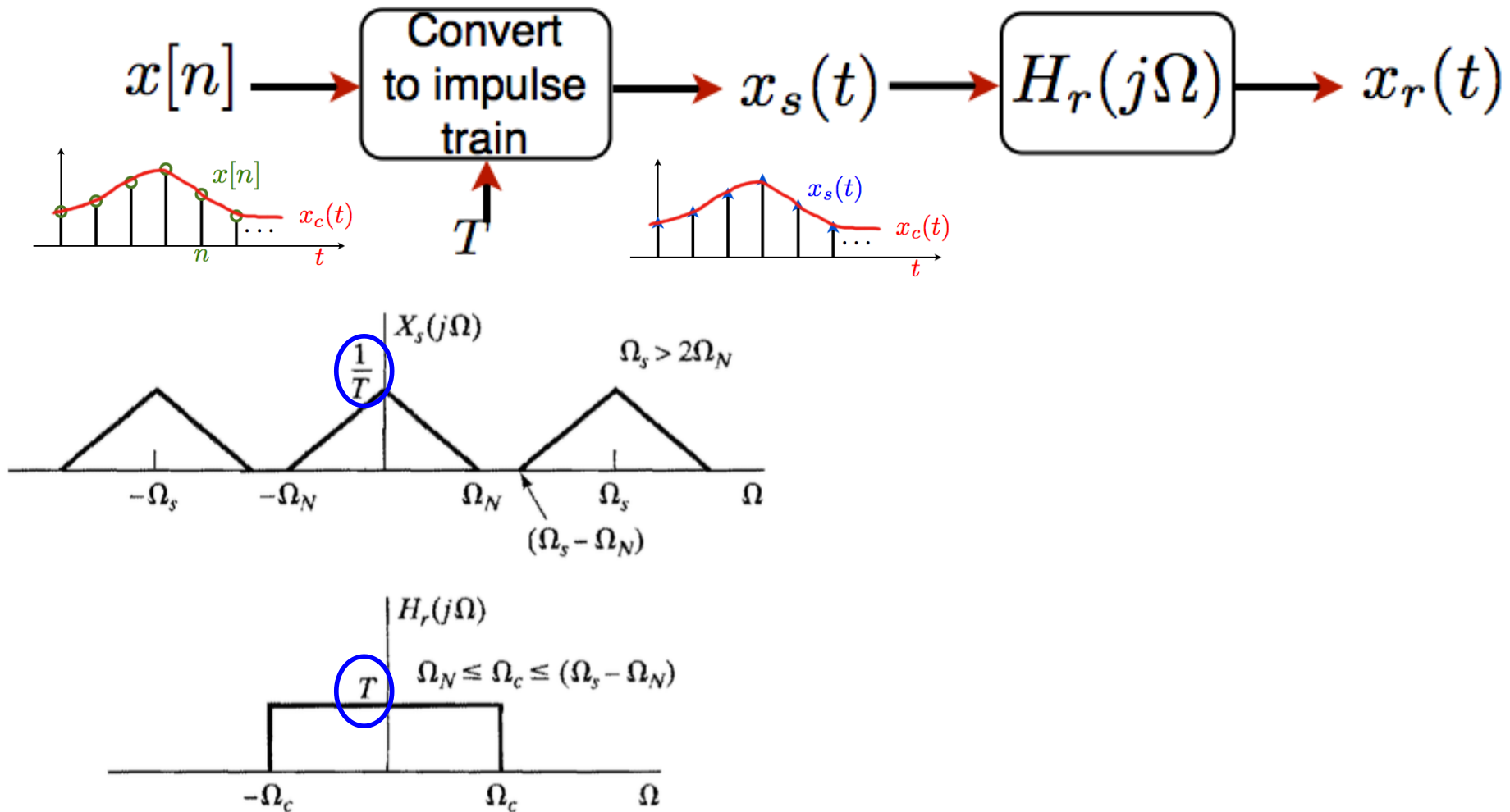


Multiple signals go through the samples, but only one is bandlimited within our sampling band

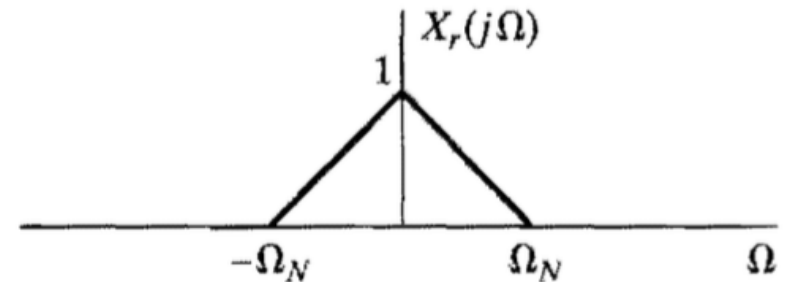
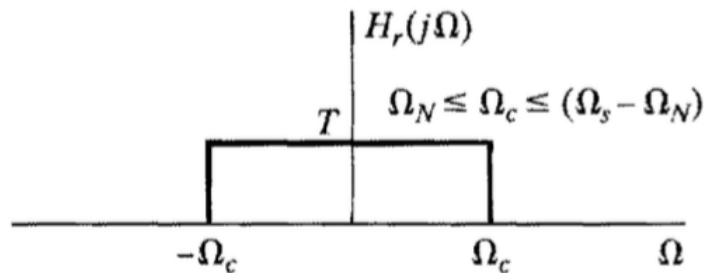
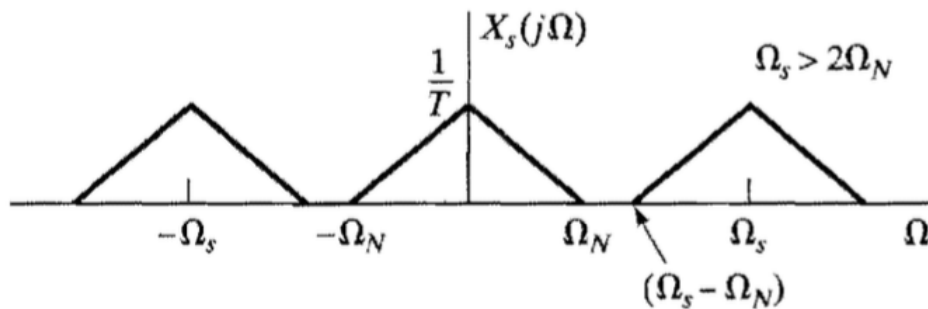
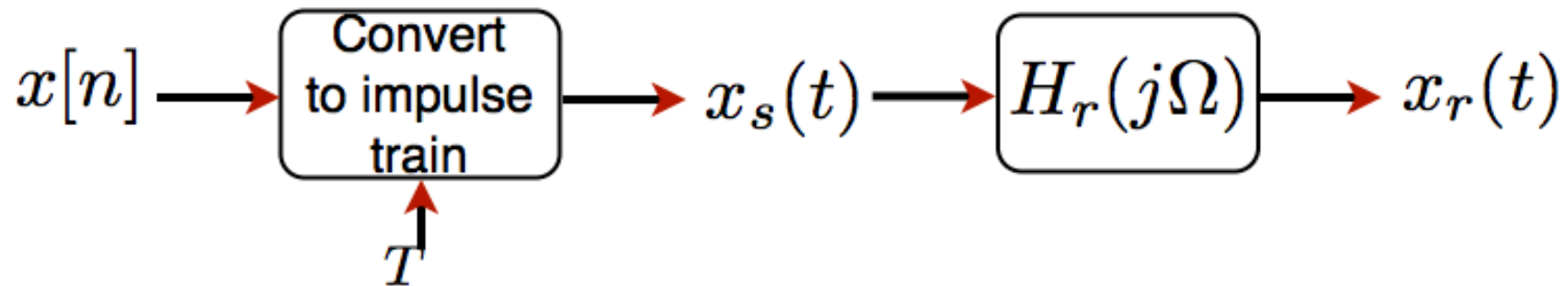
Reconstruction in Frequency Domain



Reconstruction in Frequency Domain



Reconstruction in Frequency Domain





Example: Cosine Input

- Sample and reconstruct the continuous-time signal $x_c(t) = \cos(4000\pi t)$ with sampling period $T = 1/6000$ s ($f_s = 6$ kHz)

$$\begin{aligned} X_s(j\Omega) &= \frac{1}{2\pi} X_c(j\Omega) * S(j\Omega) \\ &= \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s)) \quad | \quad \Omega_s = \frac{2\pi}{T} \end{aligned}$$

- Sample and reconstruct the continuous-time signal $x_c(t) = \cos(16000\pi t)$ with sampling period $T = 1/6000$ ($f_s = 6$ kHz)



Example: Cosine Input

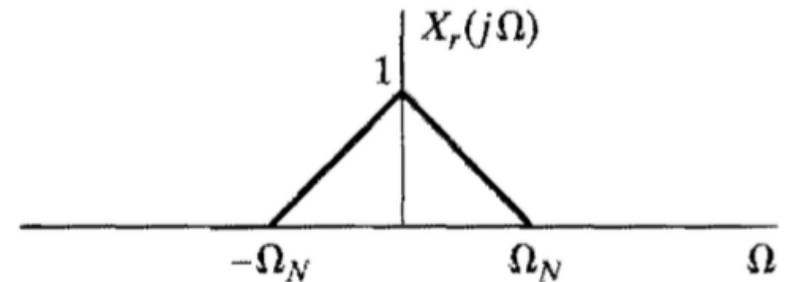
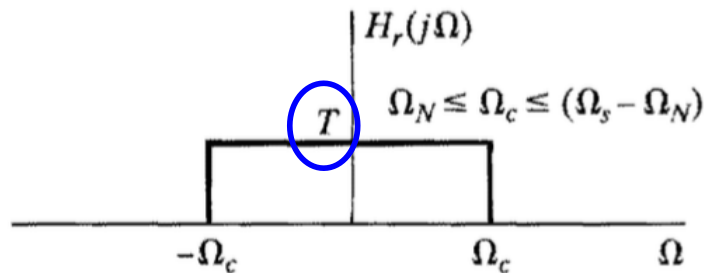
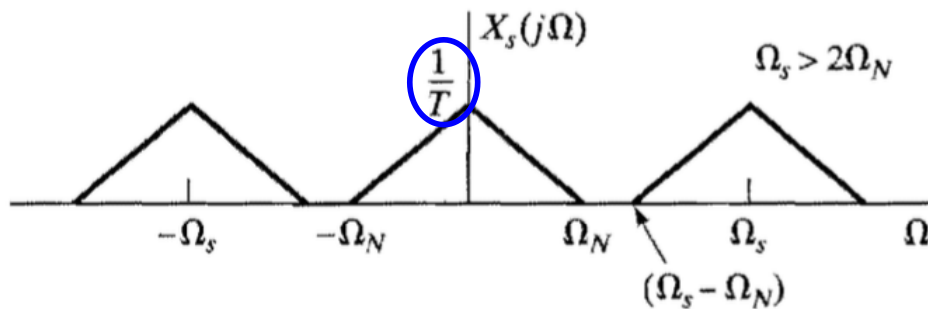
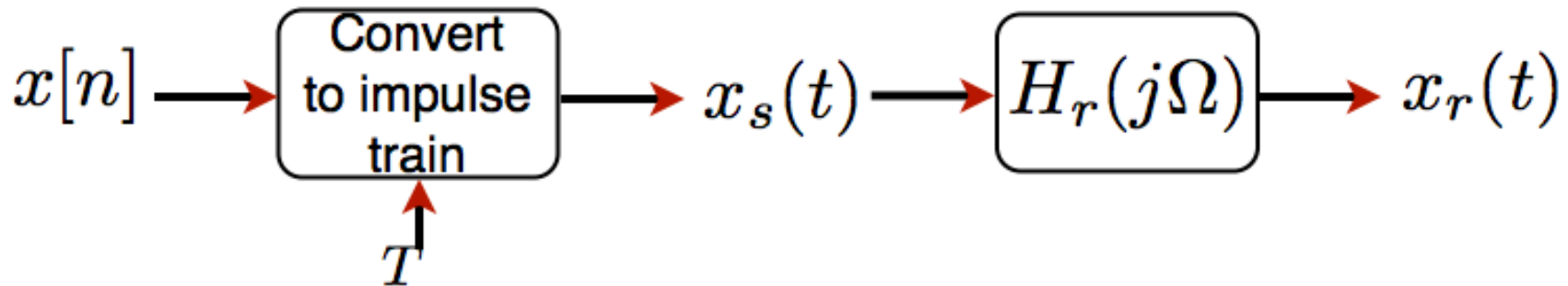
- Sample and reconstruct the continuous-time signal $x_c(t) = \cos(4000\pi t)$ with sampling period $T = 1/6000$ s ($f_s = 6\text{kHz}$)



Example: Cosine Input

- Sample and reconstruct the continuous-time signal $x_c(t) = \cos(16000\pi t)$ with sampling period $T = 1/6000$ s ($f_s = 6\text{kHz}$)

Reconstruction in Frequency Domain



$$2\Omega_N = \Omega_s$$

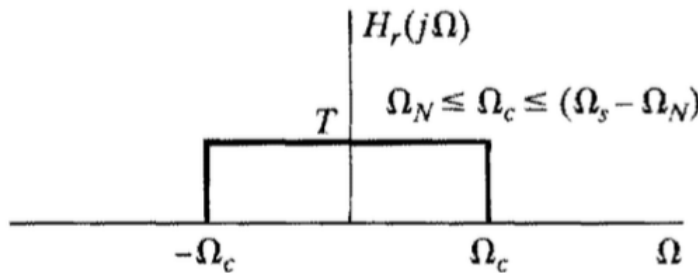
$$\Omega_N = \Omega_C = \Omega_s/2$$

Sample at Nyquist
and filter at signal
bandwidth



Reconstruction in Time Domain

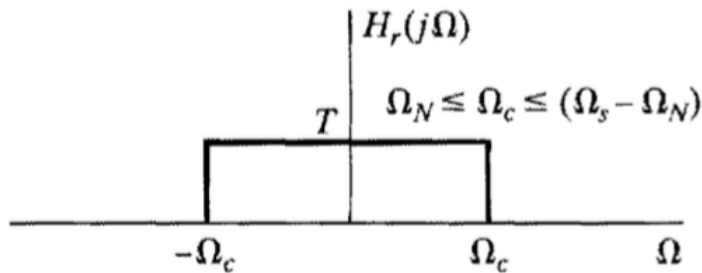
$$\Omega_N = \Omega_C = \Omega_s/2$$



$$h_r(t) = \frac{1}{2\pi} \int_{-\Omega_s/2}^{\Omega_s/2} T e^{j\Omega t} d\Omega$$

Reconstruction in Time Domain

$$\Omega_N = \Omega_C = \Omega_s/2$$

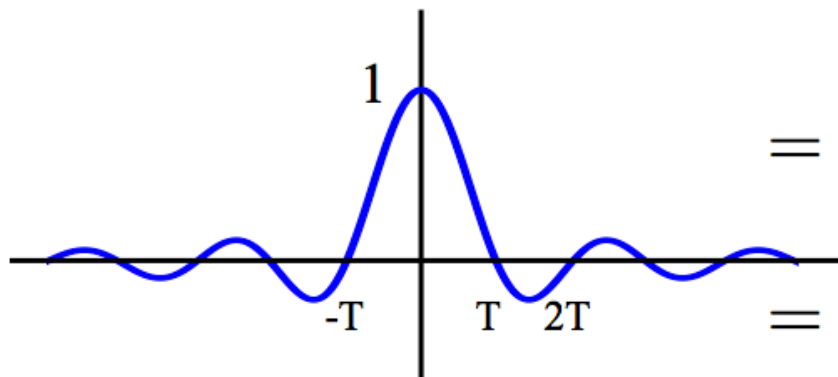


$$h_r(t) = \frac{1}{2\pi} \int_{-\Omega_s/2}^{\Omega_s/2} T e^{j\Omega t} d\Omega$$

$$= \frac{T}{2\pi} \frac{1}{jt} e^{j\Omega t} \Big|_{-\Omega_s/2}^{\Omega_s/2}$$

$$= \frac{T}{\pi t} \frac{e^{j\frac{\Omega_s}{2}t} - e^{-j\frac{\Omega_s}{2}t}}{2j}$$

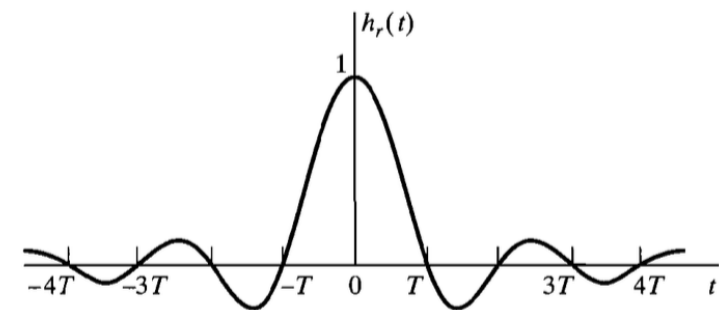
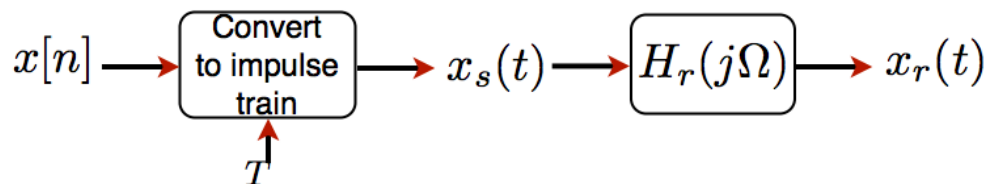
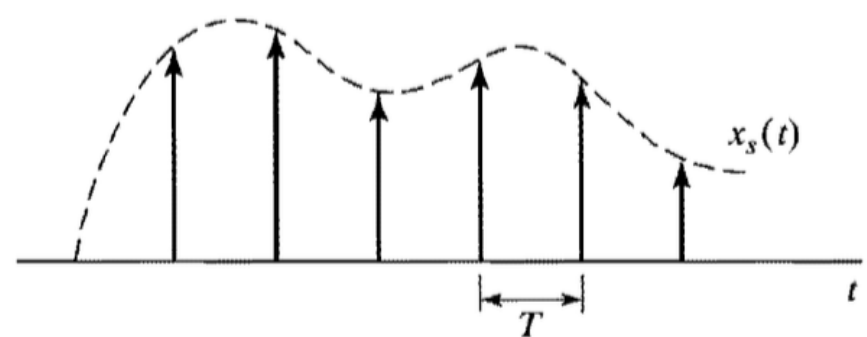
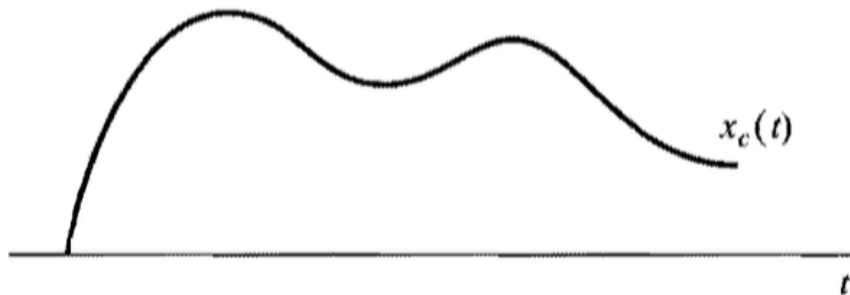
$$= \frac{T}{\pi t} \sin\left(\frac{\Omega_s}{2}t\right) = \frac{T}{\pi t} \sin\left(\frac{\pi}{T}t\right)$$



$$= \text{sinc}\left(\frac{t}{T}\right)$$

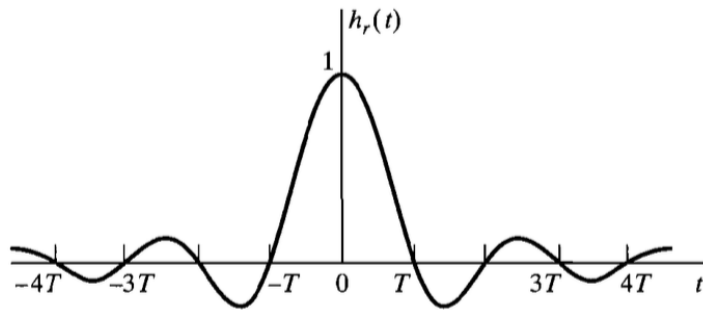
Reconstruction in Time Domain

$$\begin{aligned}
 x_r(t) = x_s(t) * h_r(t) &= \left(\sum_n x[n] \delta(t - nT) \right) * h_r(t) \\
 &= \sum_n x[n] h_r(t - nT)
 \end{aligned}$$

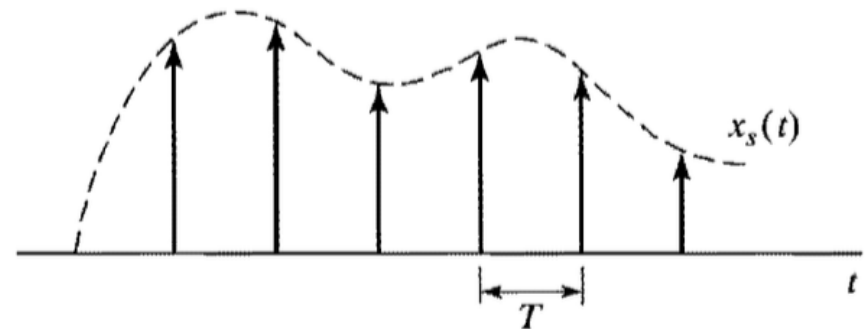


Reconstruction in Time Domain

$$\begin{aligned}x_r(t) = x_s(t) * h_r(t) &= \left(\sum_n x[n] \delta(t - nT) \right) * h_r(t) \\&= \sum_n x[n] h_r(t - nT)\end{aligned}$$



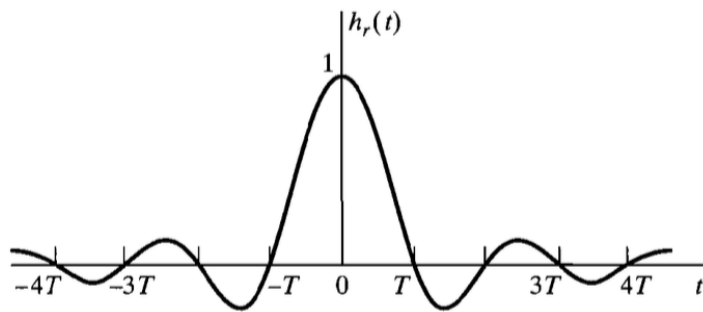
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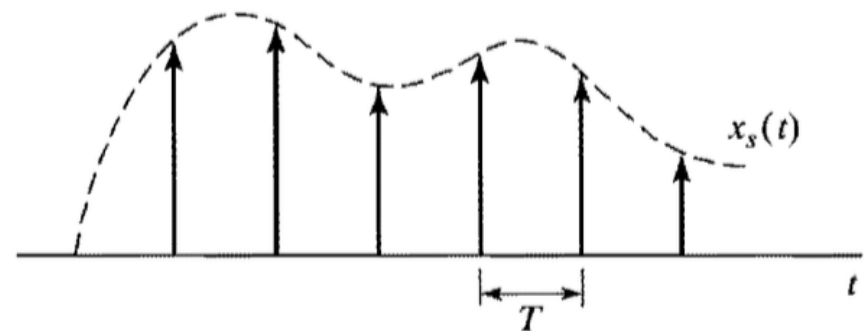
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Reconstruction in Time Domain

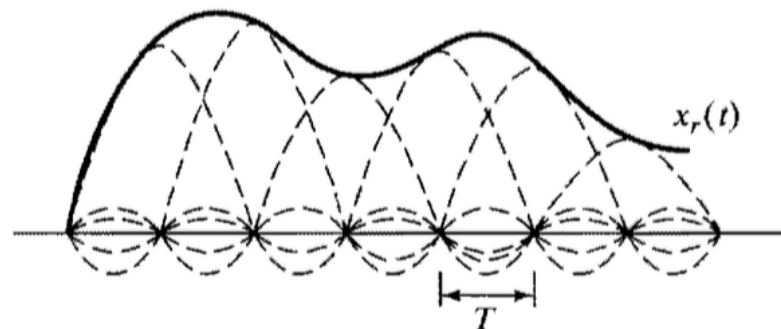
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 \end{aligned}$$



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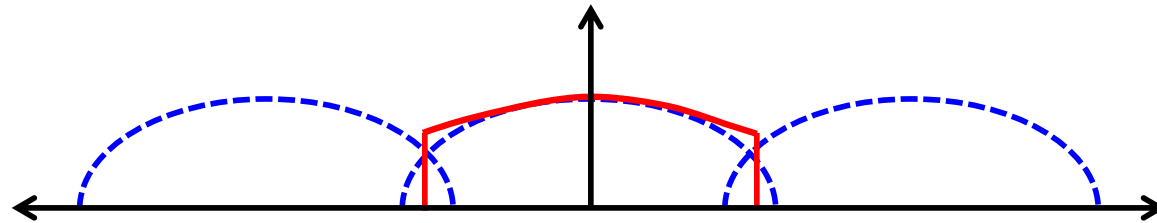


The sum of "sincs" gives $x_r(t) \rightarrow$ unique signal that is bandlimited by sampling bandwidth



Aliasing

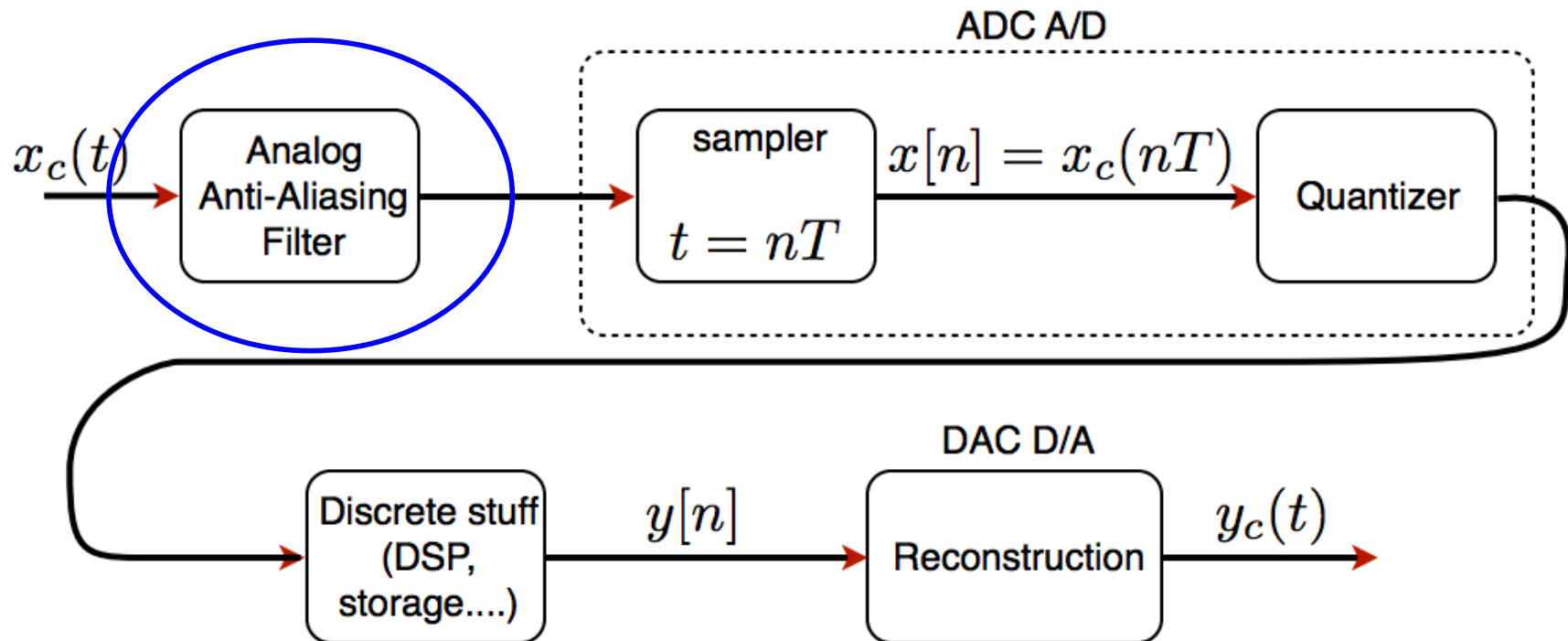
- If $\Omega_N > \Omega_s/2$, $x_r(t)$ is an aliased version of $x_c(t)$



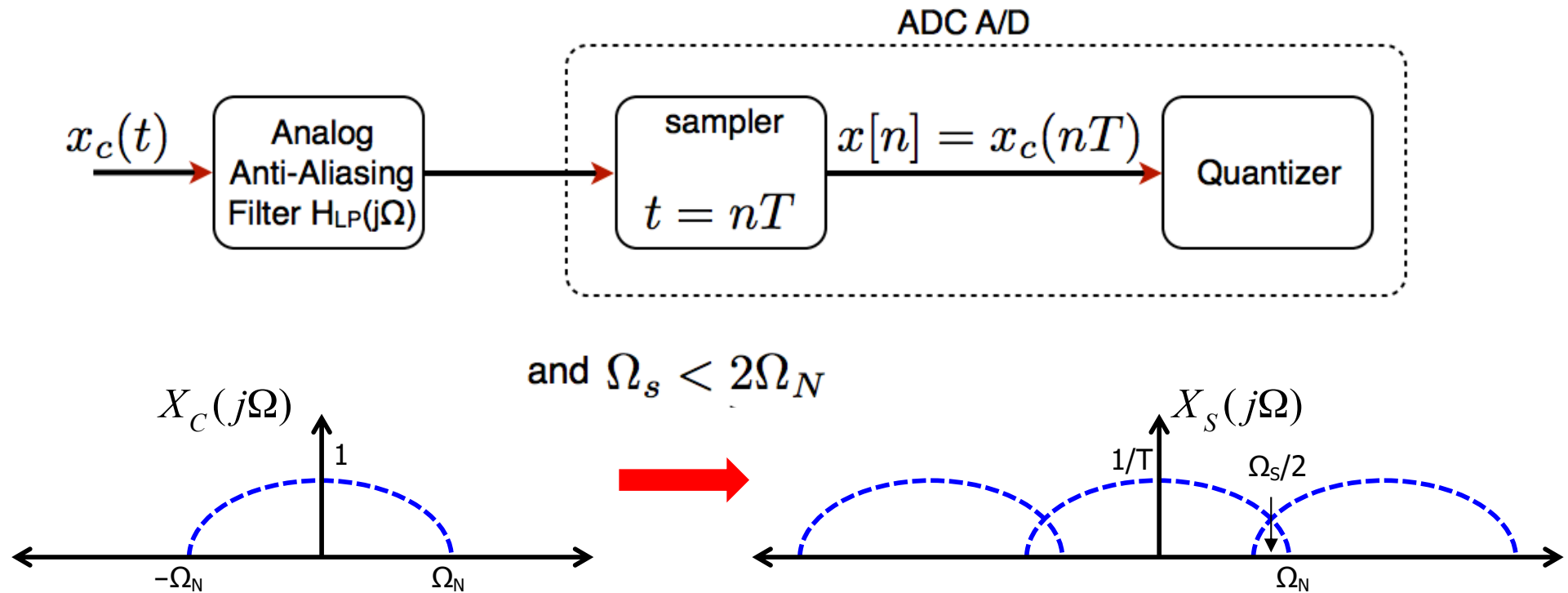
$$X_r(j\Omega) = \begin{cases} TX_s(j\Omega) & \text{if } |\Omega| \leq \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$



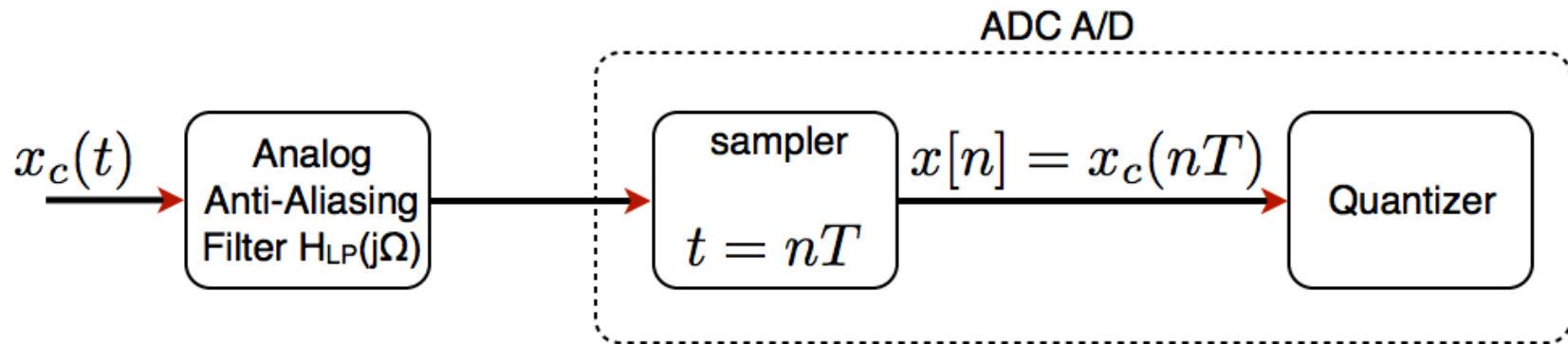
DSP System



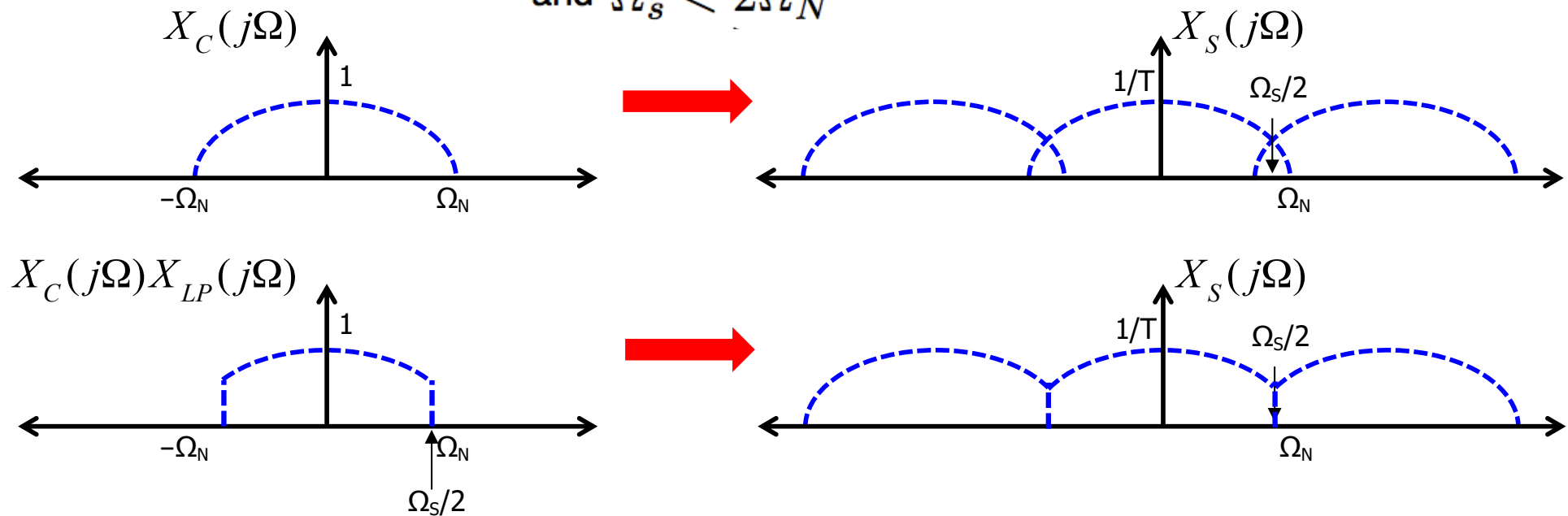
Anti-Aliasing Filter



Anti-Aliasing Filter

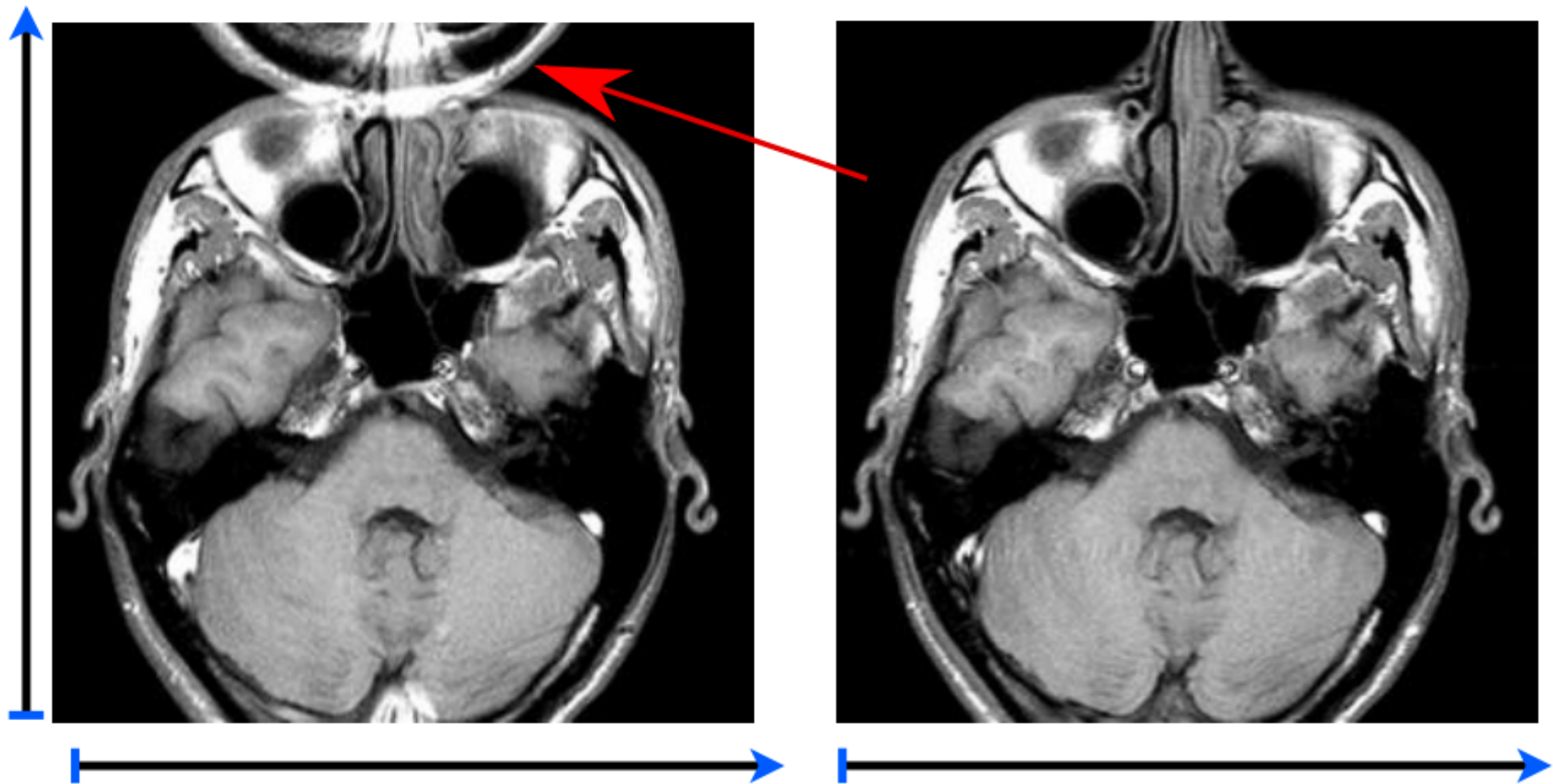


and $\Omega_s < 2\Omega_N$





MRI aliasing example





MRI anti-aliasing example





MRI anti-aliasing example





Big Ideas

- ❑ Sampling
 - Ideal sampling modeled as impulsive sampling
 - Sample at Nyquist rate for recovery of unique bandlimited signal (i.e. avoid aliasing)
- ❑ Frequency Response of Sampled Signal
 - Sampled signal is period replicated input CT signal
- ❑ Reconstruction
 - Low pass/reconstruction filter results in sum of sincs
- ❑ Anti-aliasing filtering
 - Force input signal to be bandlimited



Admin

- ❑ HW 2 out due Sunday 2/6 at midnight
 - Double check that your submission by viewing it!