

ESE 5310: Digital Signal Processing

Lecture 9: February 20, 2024

Non-Integer and Multi-rate Sampling

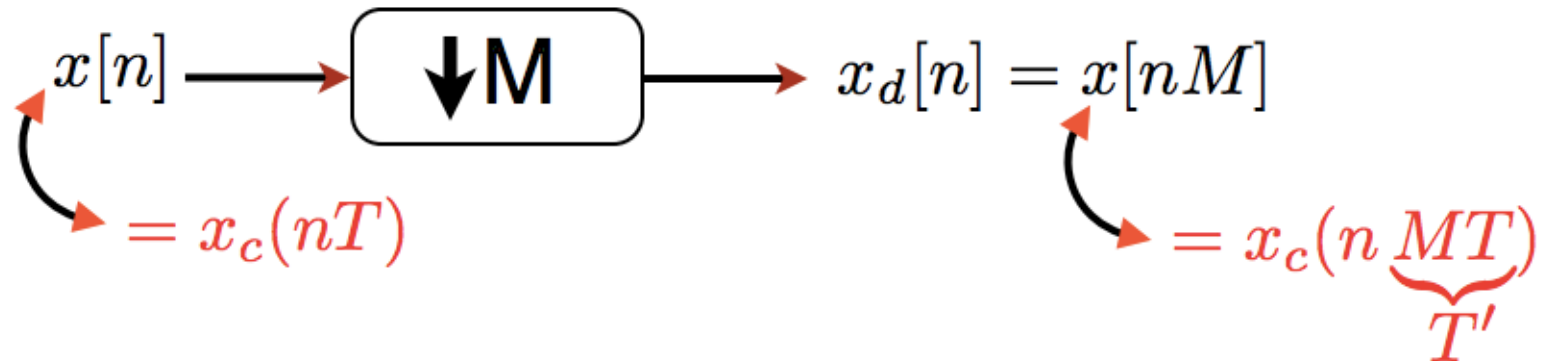


Lecture Outline

- ❑ Review: Downsampling/Upsampling
- ❑ Non-integer Resampling
- ❑ Multi-Rate Processing
 - Interchanging Operations
 - Filter cost

Downsampling

- Definition: Reducing the sampling rate by an integer number

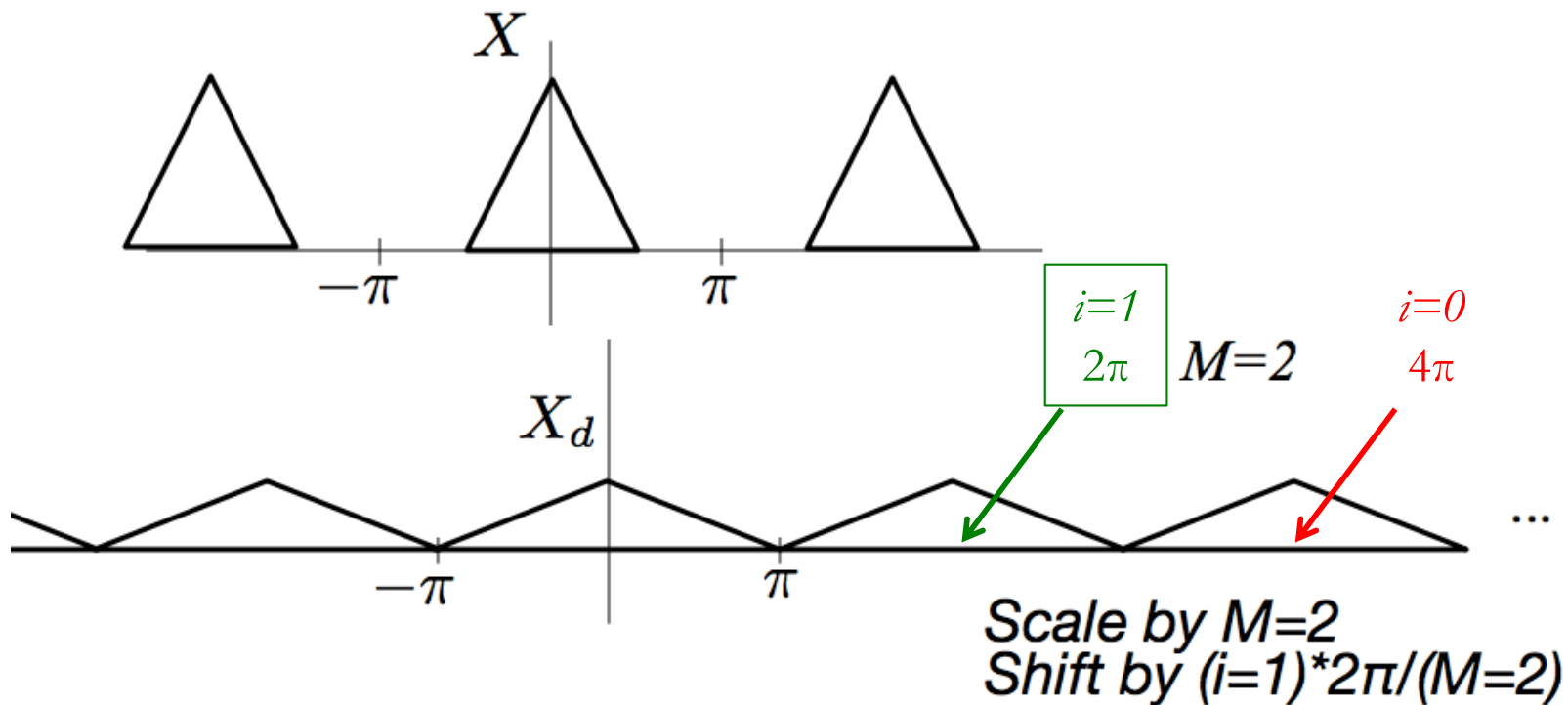


$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X(e^{j(\frac{\omega}{M} - \frac{2\pi}{M}i)})$$

stretch by M replicate

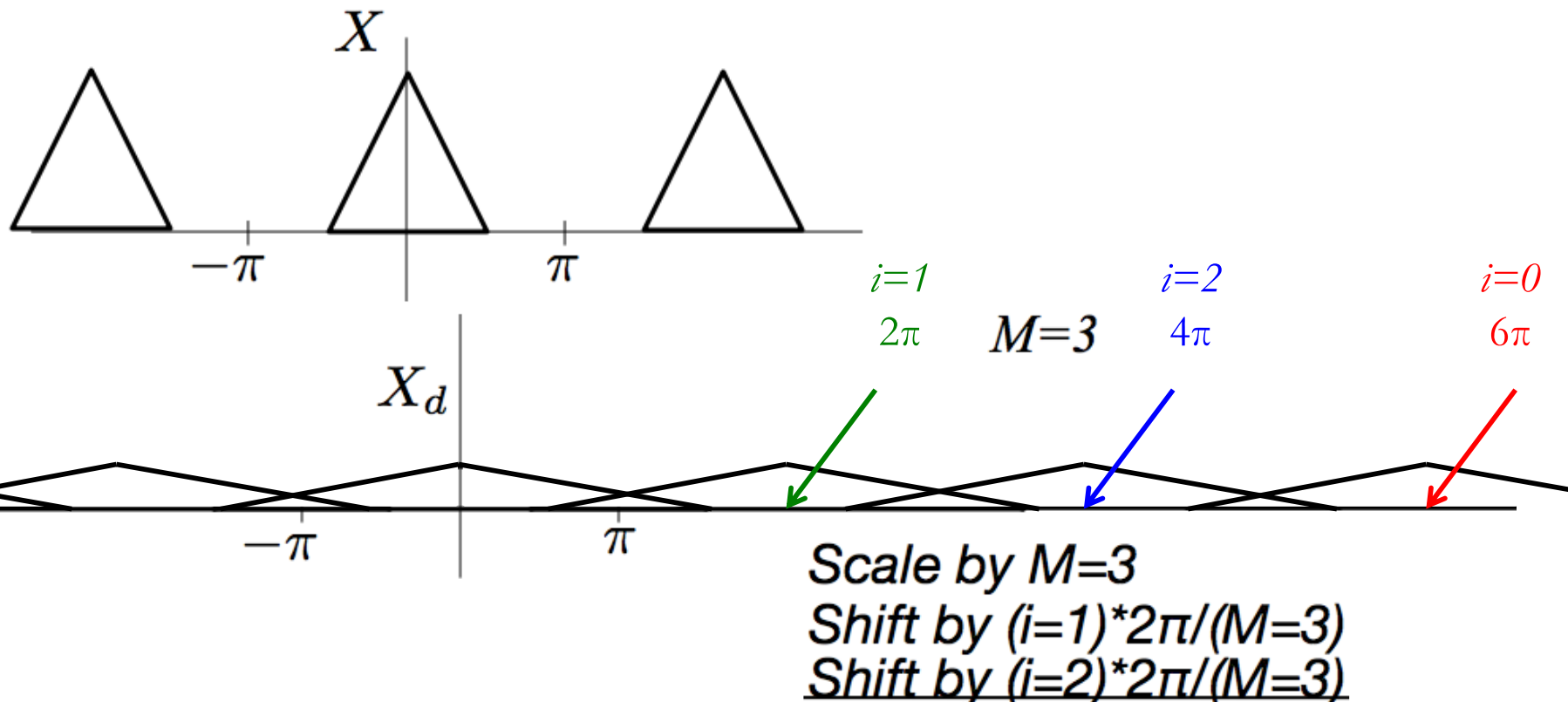
Example

$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X \left(e^{j \left(\frac{\omega}{M} - \frac{2\pi}{M} i \right)} \right)$$

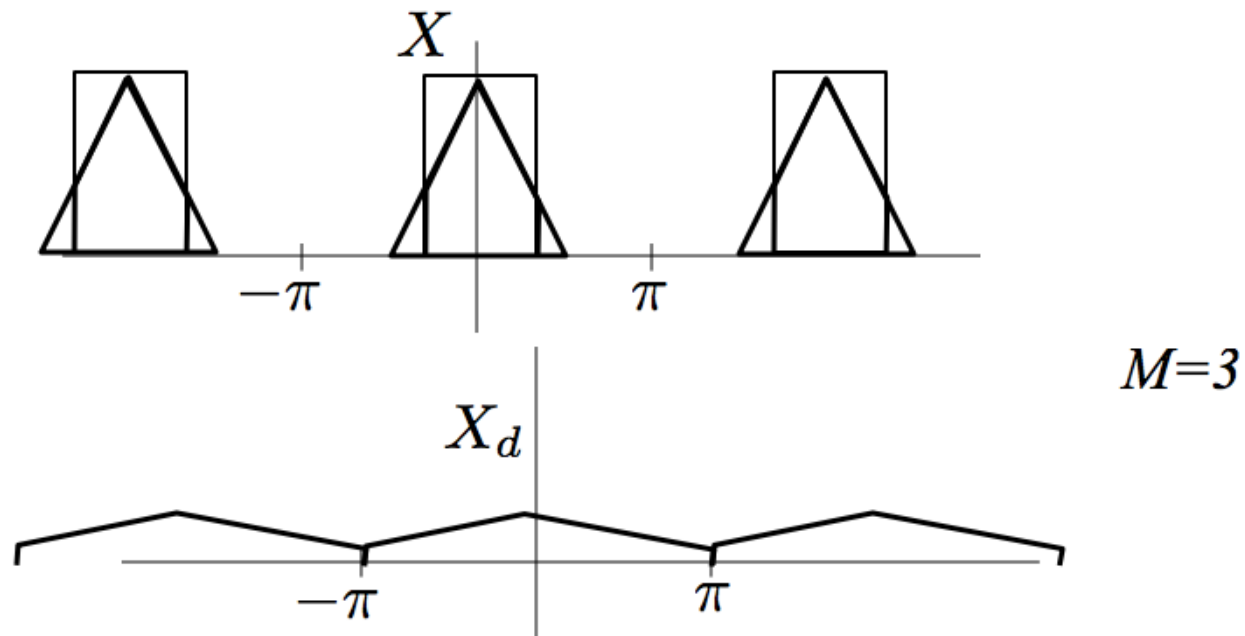
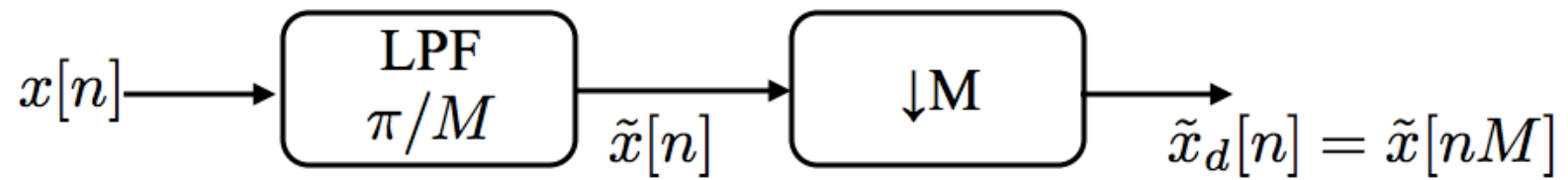


Example

$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X \left(e^{j \left(\frac{\omega}{M} - \frac{2\pi}{M} i \right)} \right)$$



Example





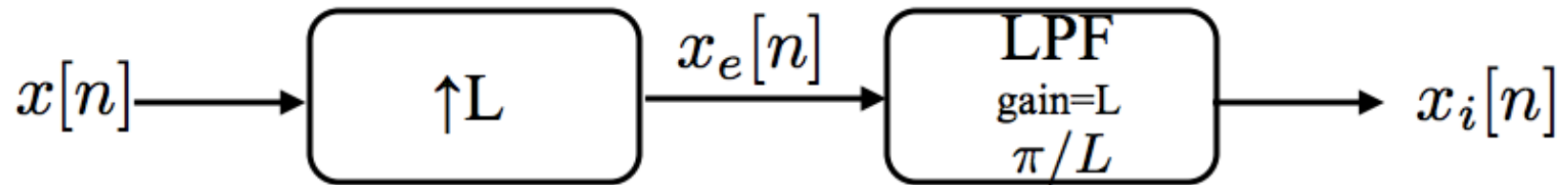
Upsampling

- Definition: Increasing the sampling rate by an integer number

$$x[n] = x_c(nT)$$

$$x_i[n] = x_c(nT') \quad \text{where } T' = \frac{T}{L} \quad L \text{ integer}$$

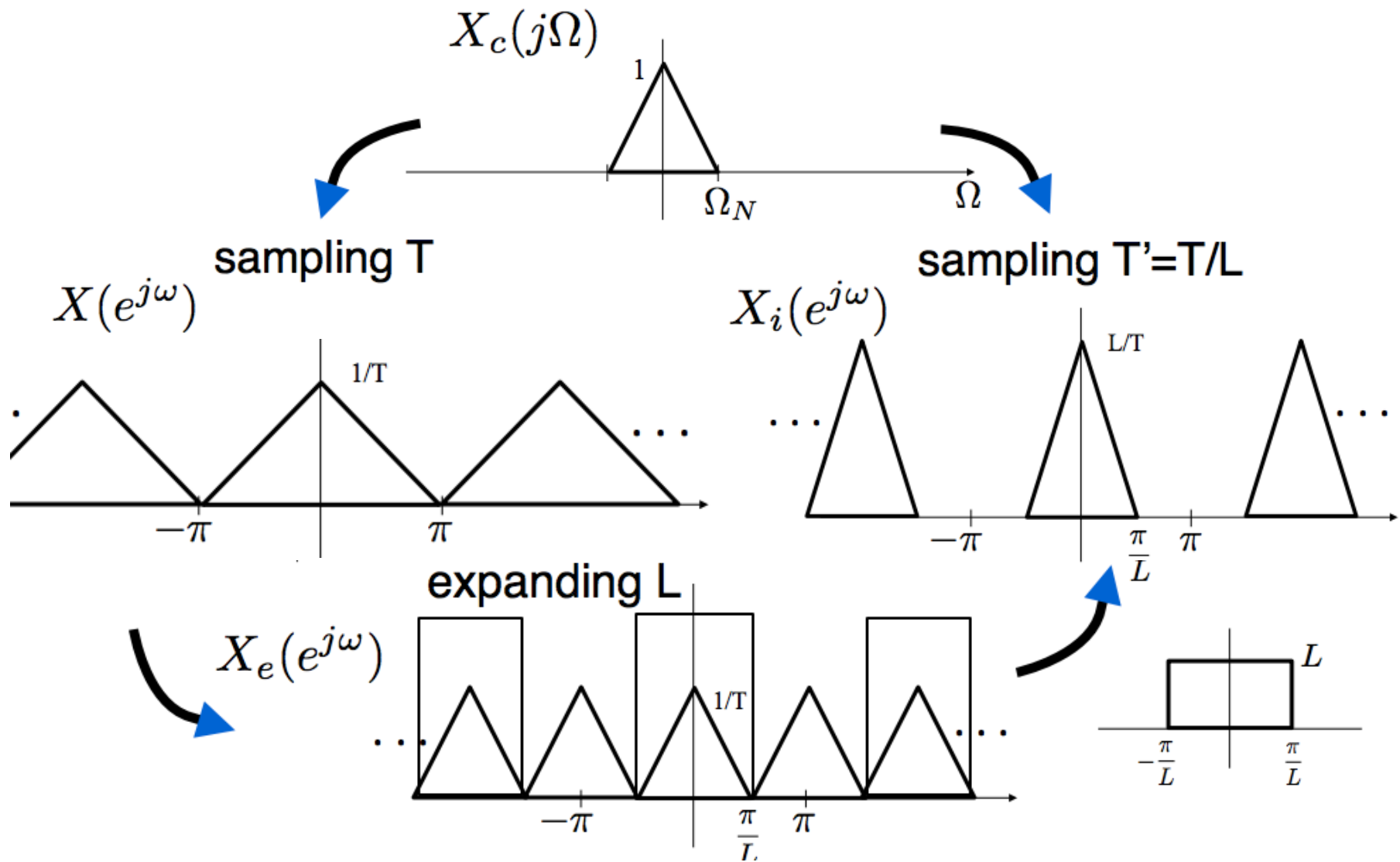
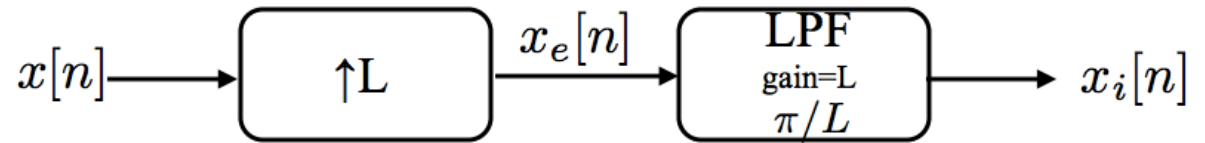
Frequency Domain Interpretation



$$\begin{aligned} X_e(e^{j\omega}) &= \sum_{n=-\infty}^{\infty} \underbrace{x_e[n]}_{\neq 0 \text{ only for } n=mL \text{ (integer } m)} e^{-j\omega n} \\ &= \sum_{m=-\infty}^{\infty} \underbrace{x_e[mL]}_{=x[m]} e^{-j\omega mL} = X(e^{j\omega L}) \end{aligned}$$

Compress DTFT by a factor of L!

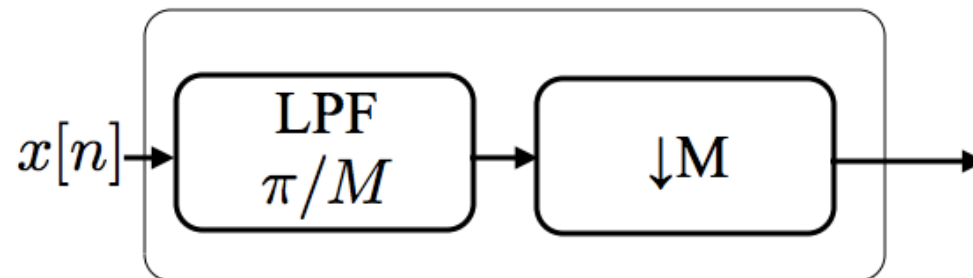
Example



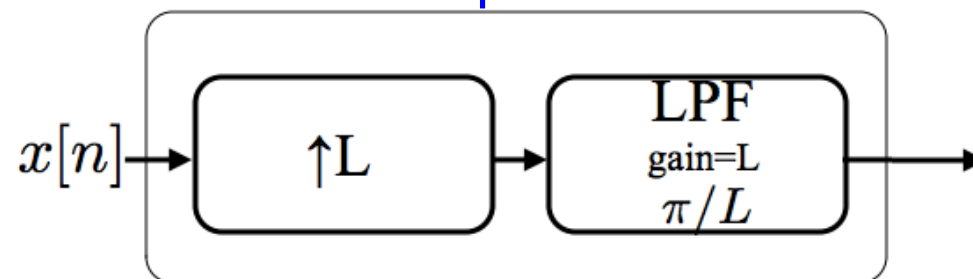


Interpolation and Decimation

decimator

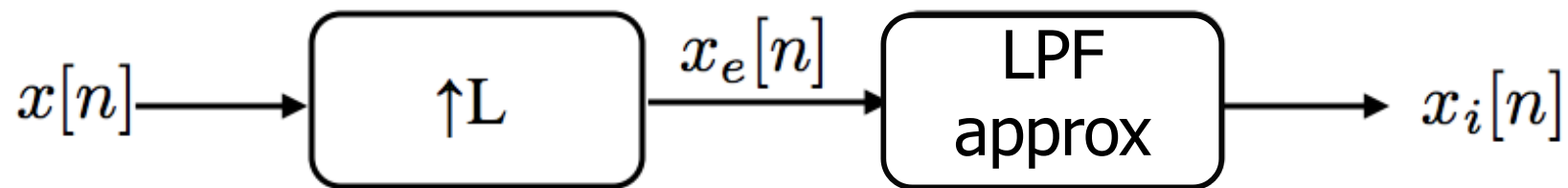


interpolator

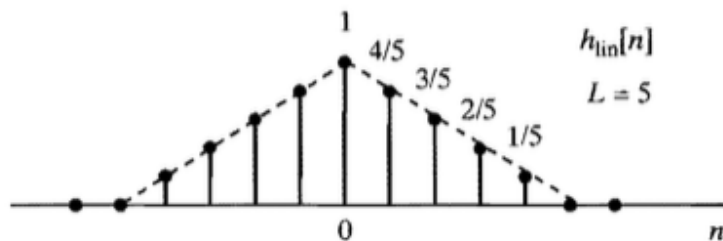


Linear Interpolation -- Frequency Domain

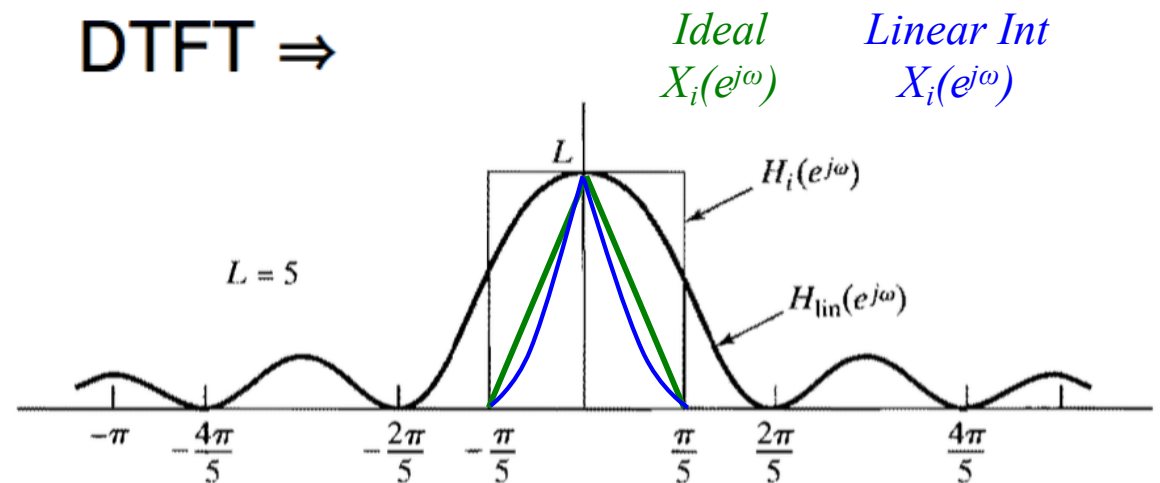
$$x_i[n] = x_e[n] * h_{lin}[n]$$



$$h_{lin}[n] = \begin{cases} 1 - |n|/L, & |n| \leq L, \\ 0, & \text{otherwise,} \end{cases}$$

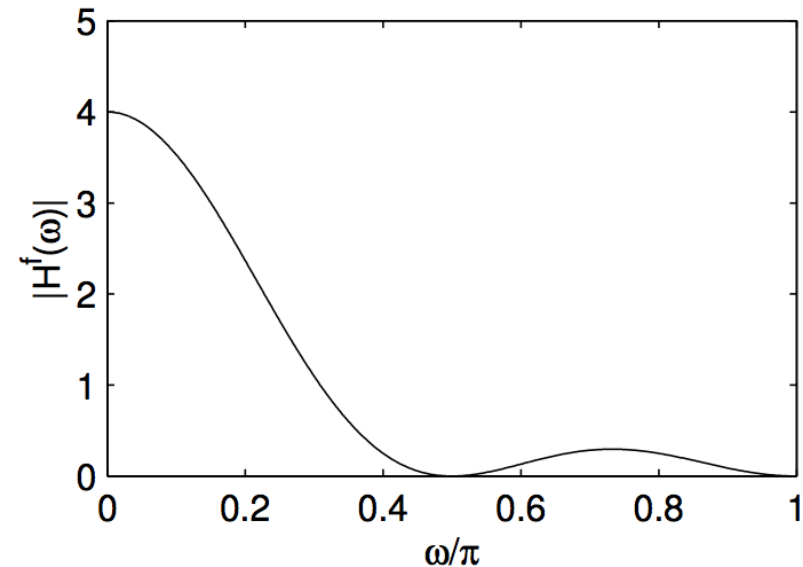
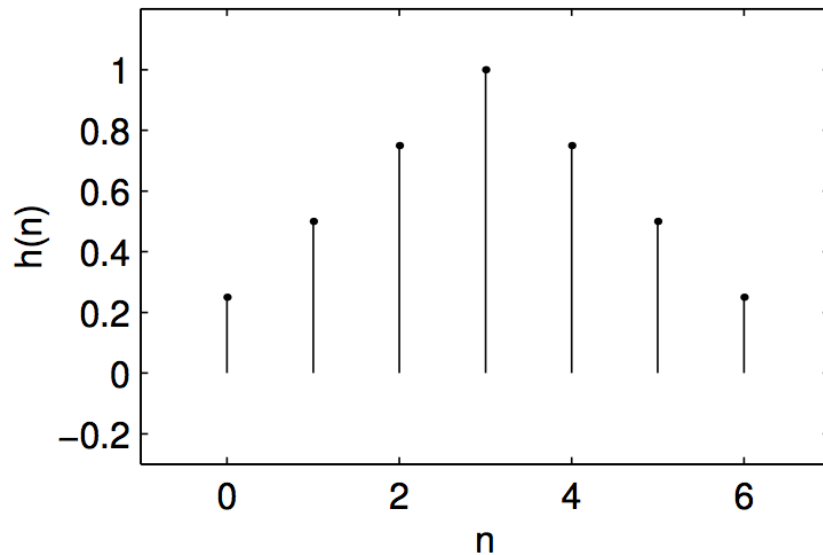


DTFT \Rightarrow



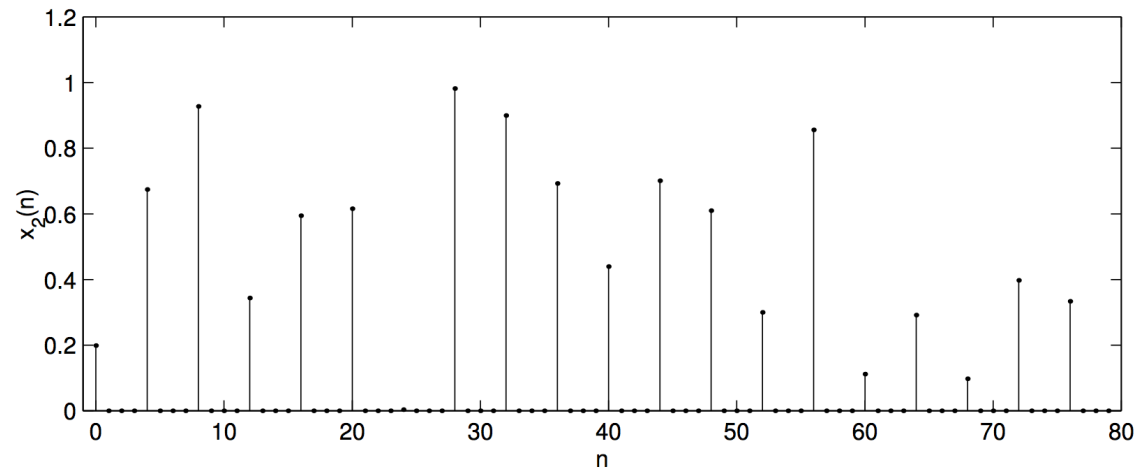
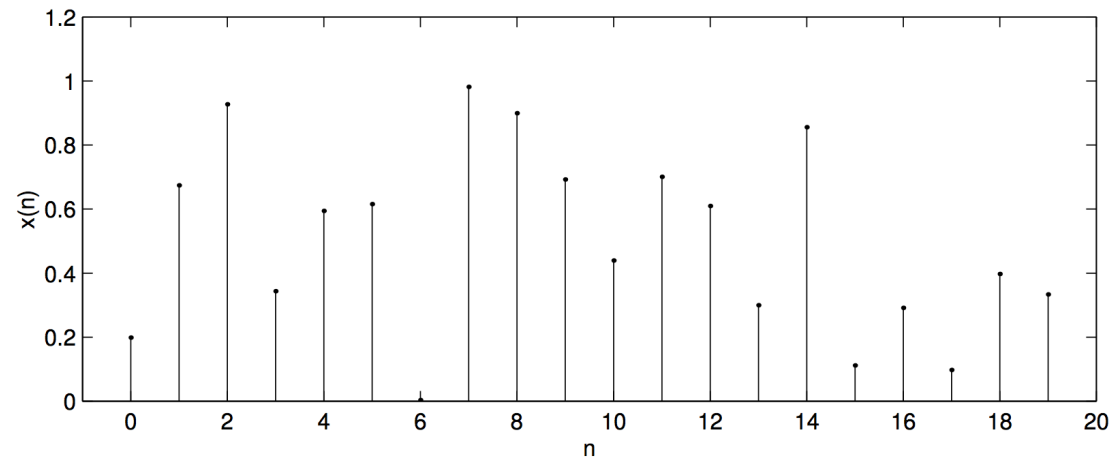
Interpolation Filter Example 1

- This time we use a filter of length 7 with the effect of linear interpolation

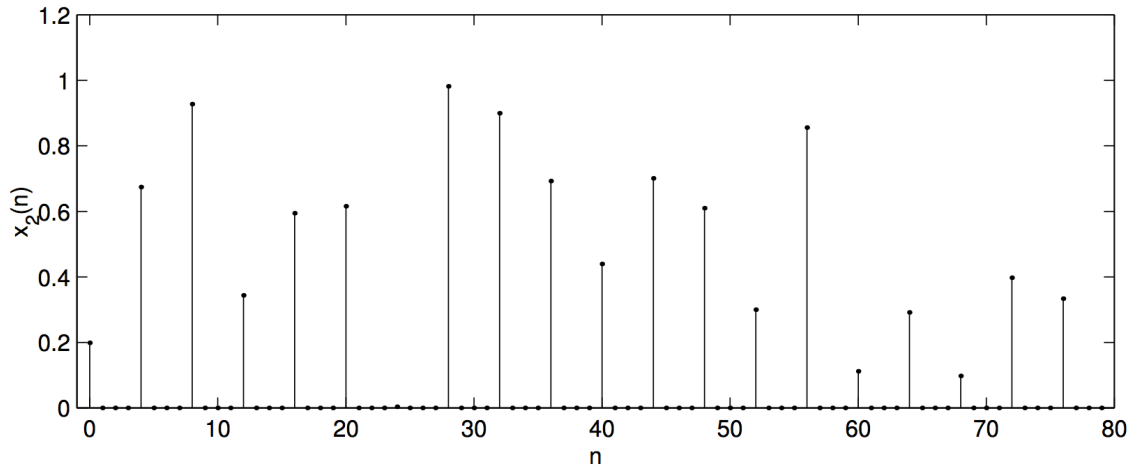




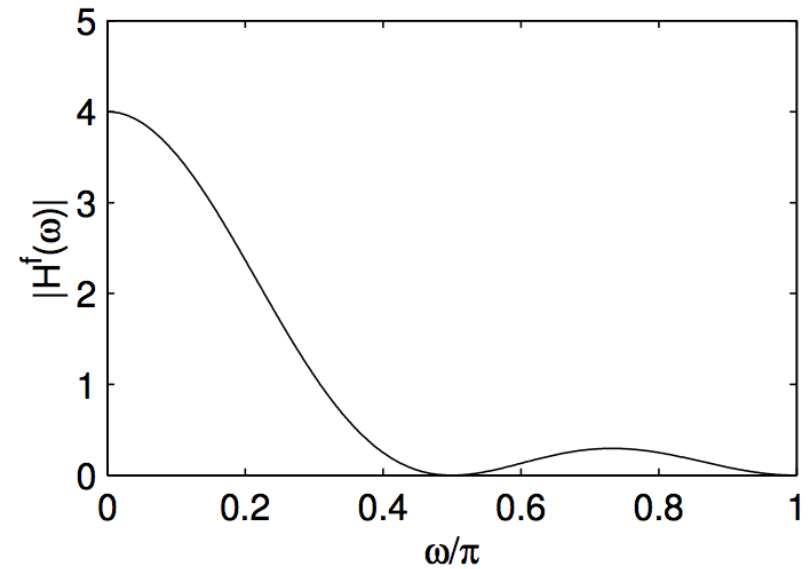
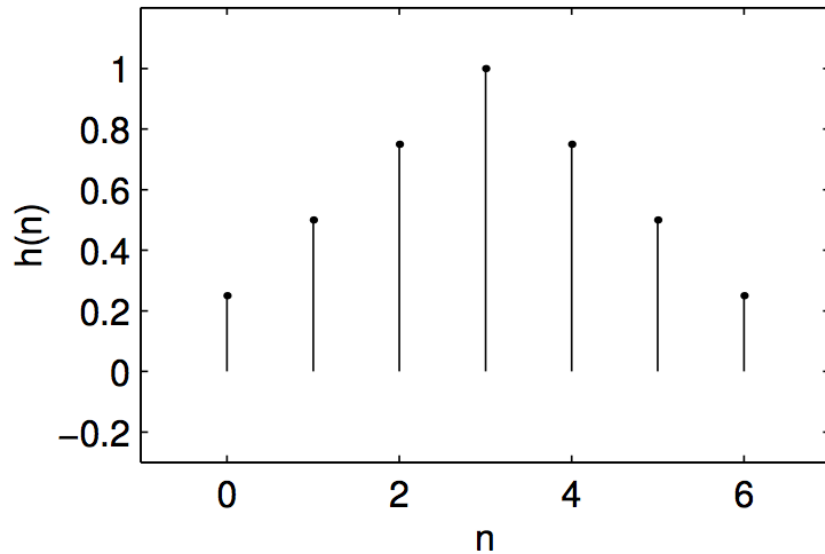
Interpolation Filter Example 1



Interpolation Filter Example 1

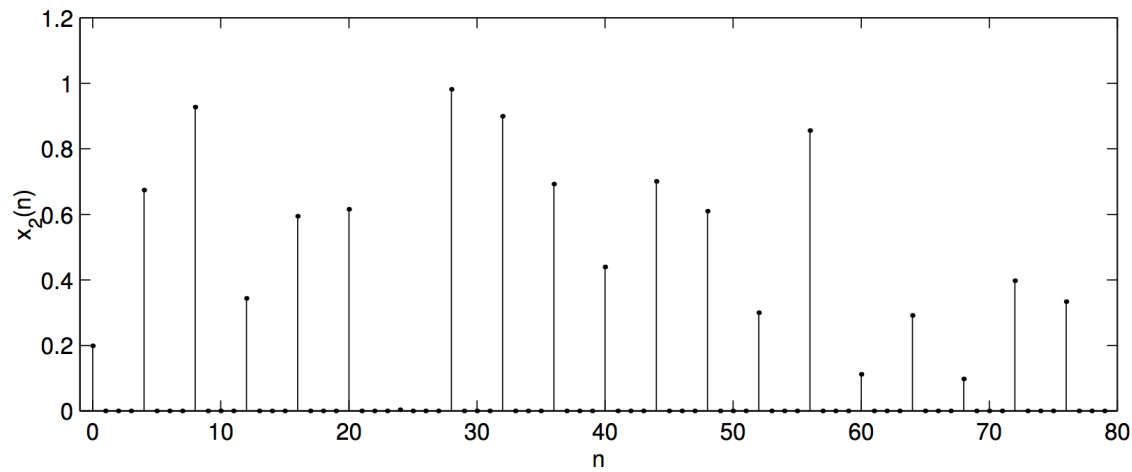


$*$
(convolve)

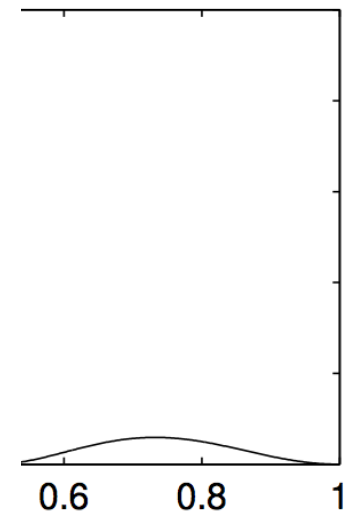
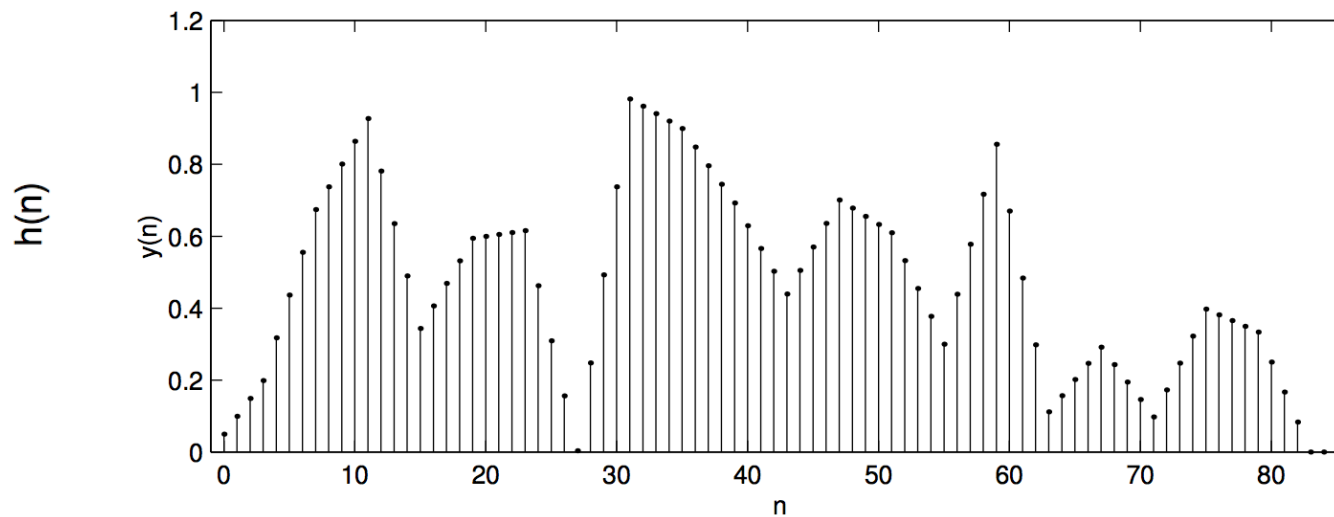




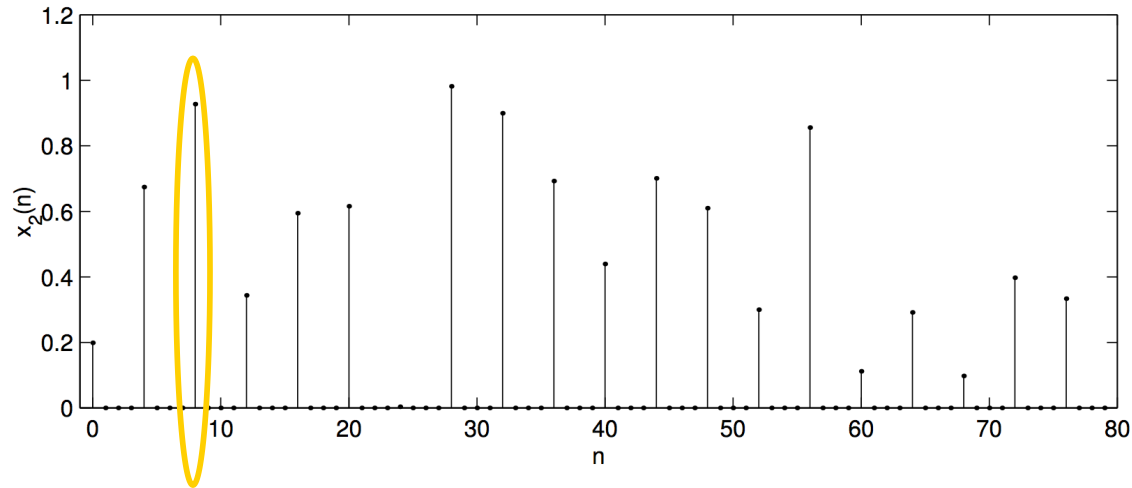
Interpolation Filter Example 1



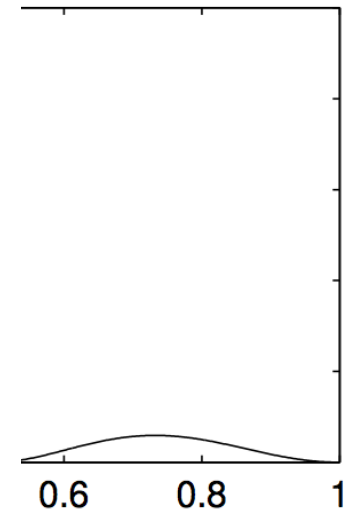
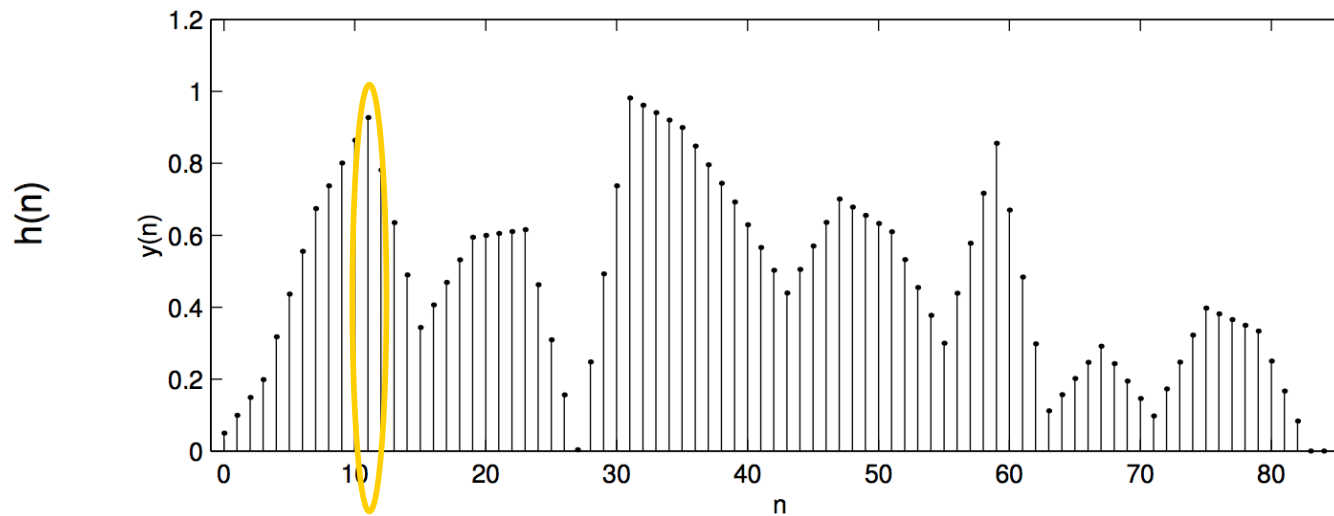
$*$
(convolve)



Interpolation Filter Example 1

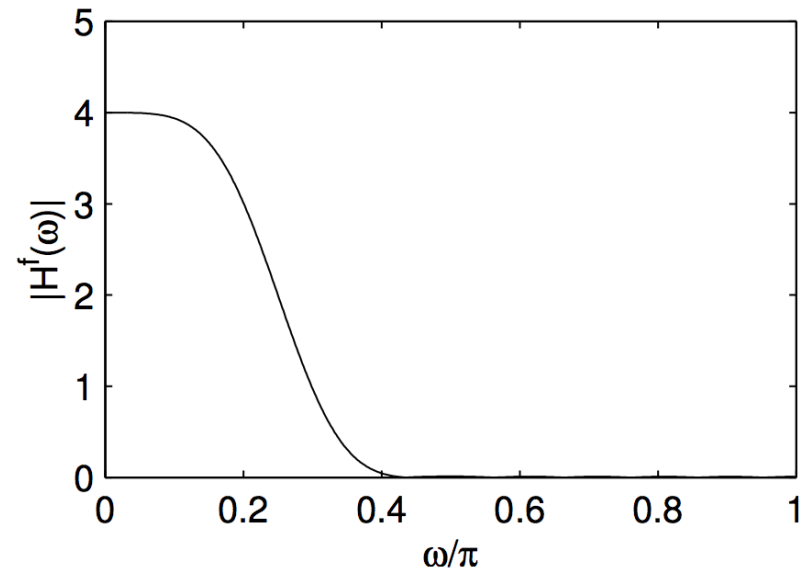
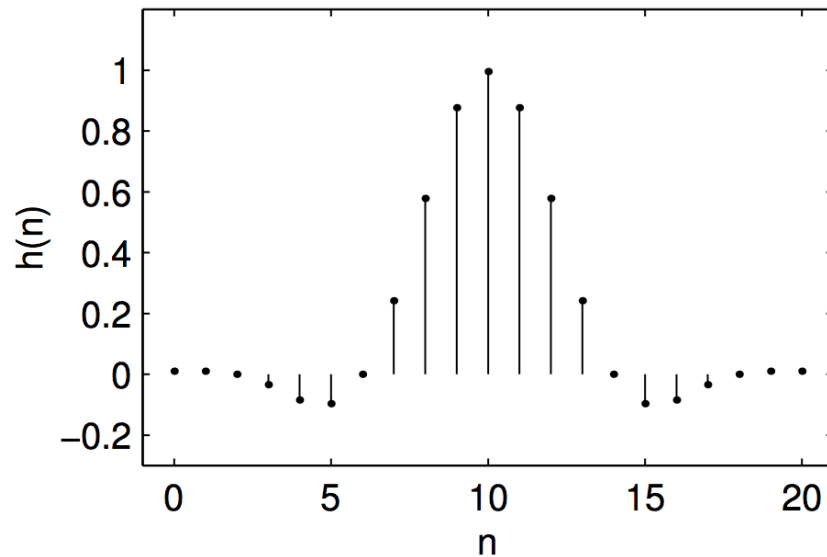


$*$
(convolve)



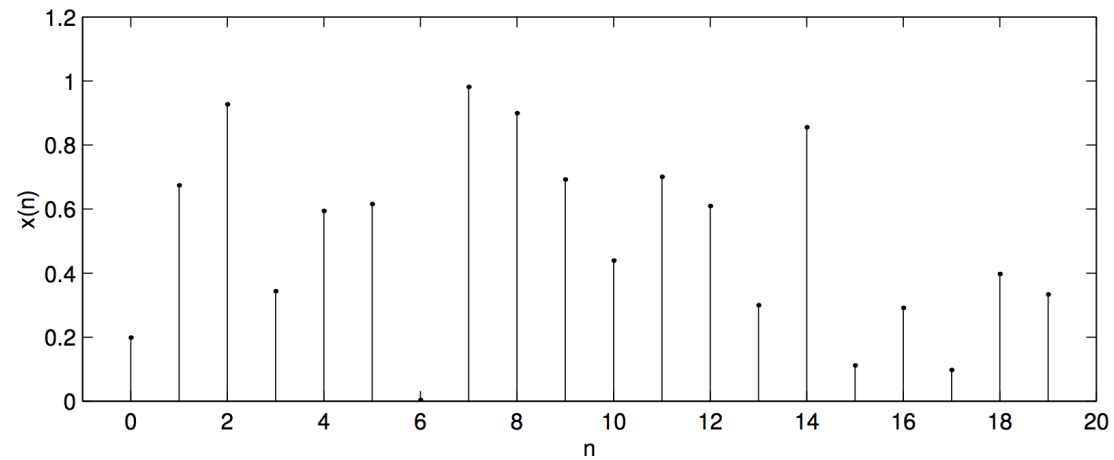
Interpolation Filter Example 2

- ❑ In this example, we interpolate a signal $x(n)$ by a factor of 4.
- ❑ We use a linear phase Type I FIR lowpass filter of length 21.



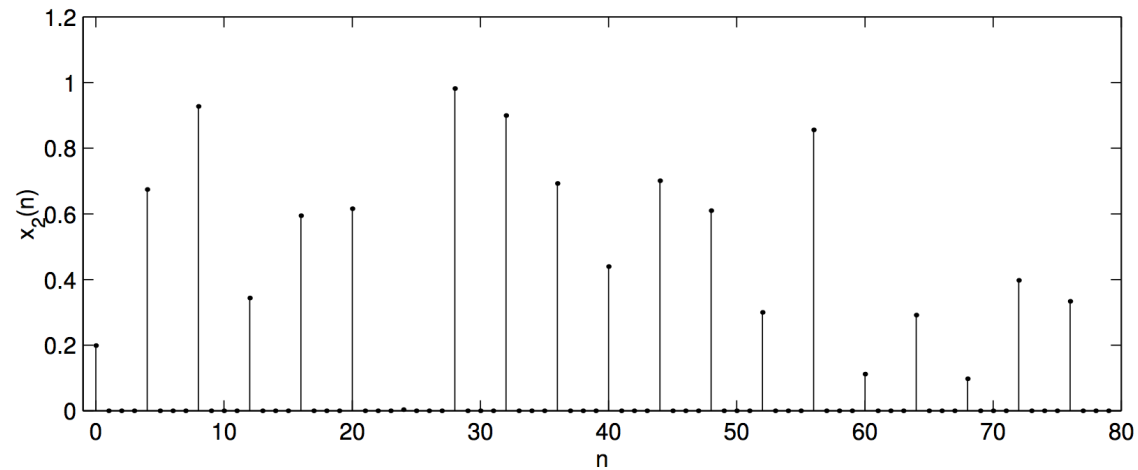
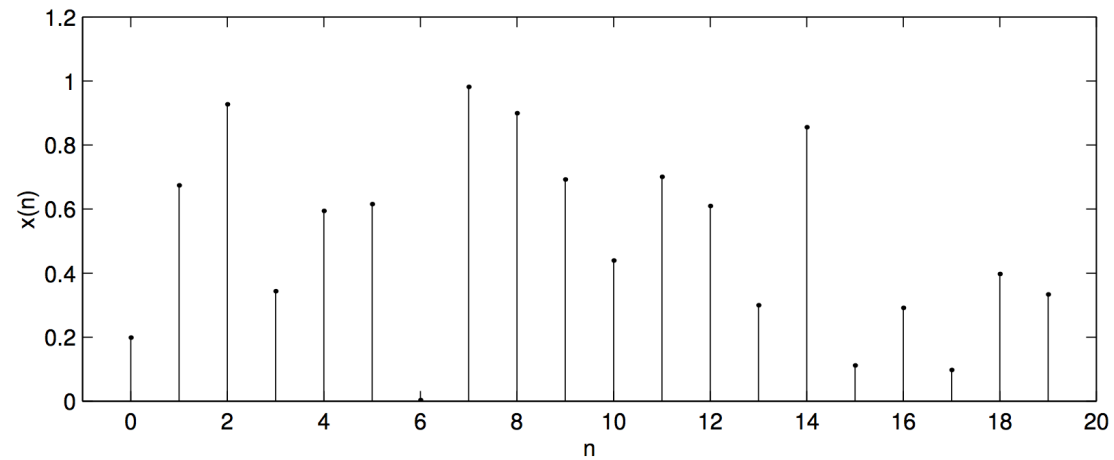


Interpolation Filter Example 2

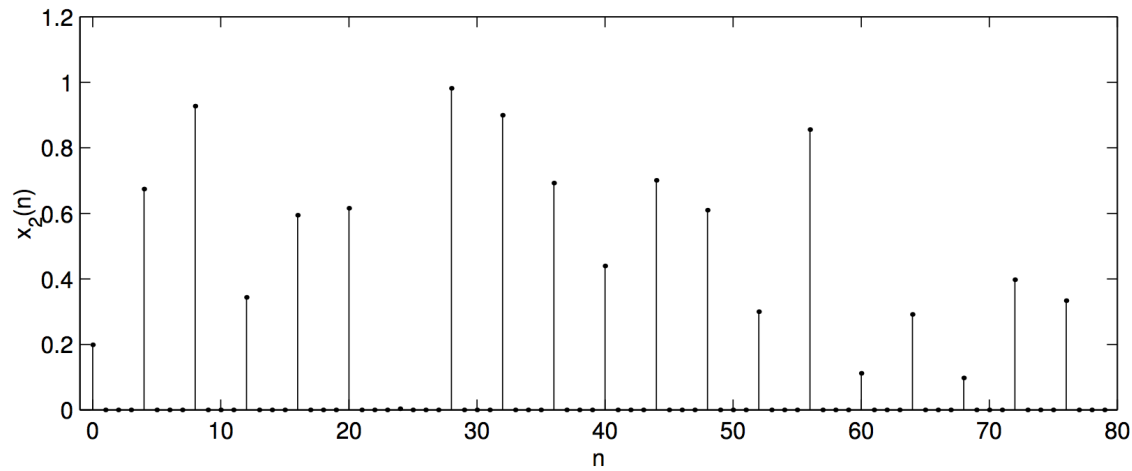




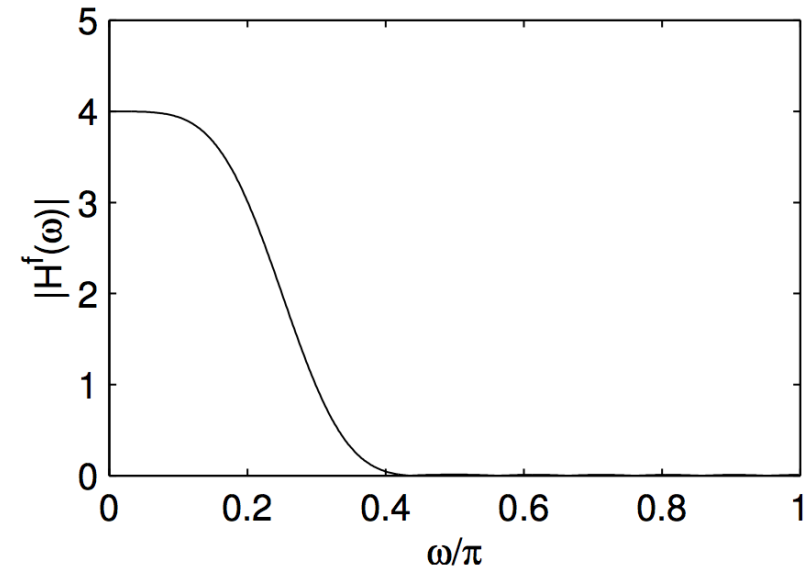
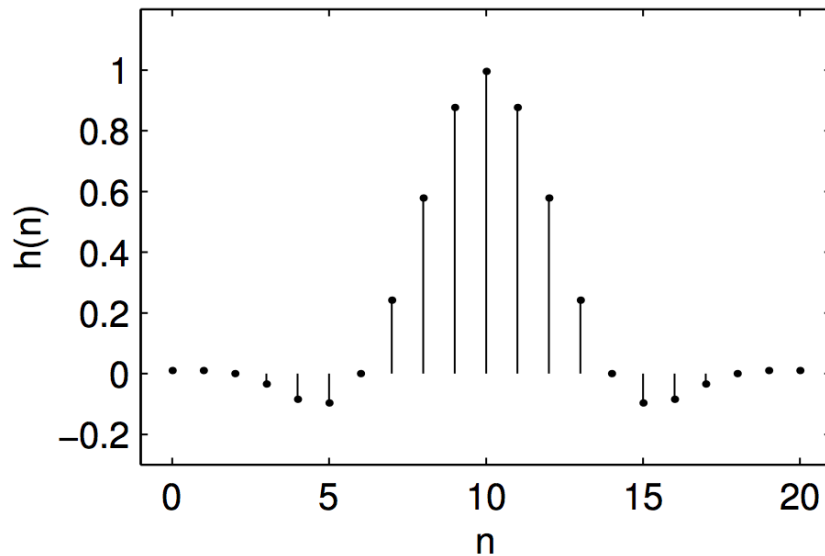
Interpolation Filter Example 2



Interpolation Filter Example 2

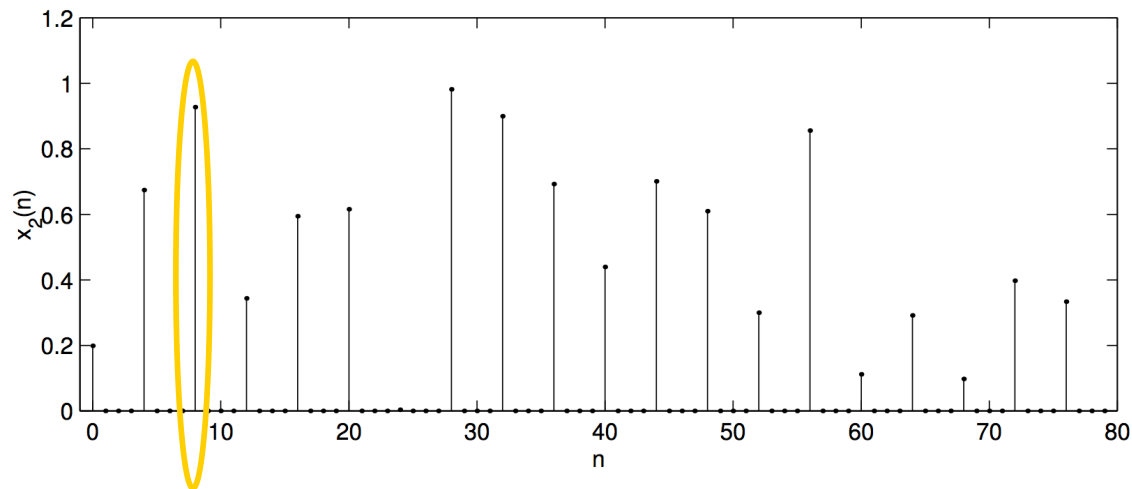


$*$
(convolve)

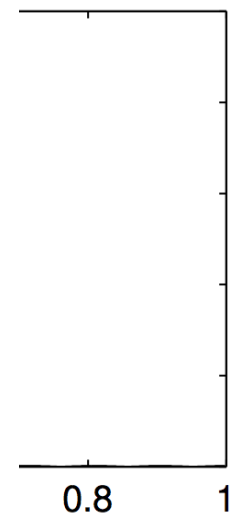
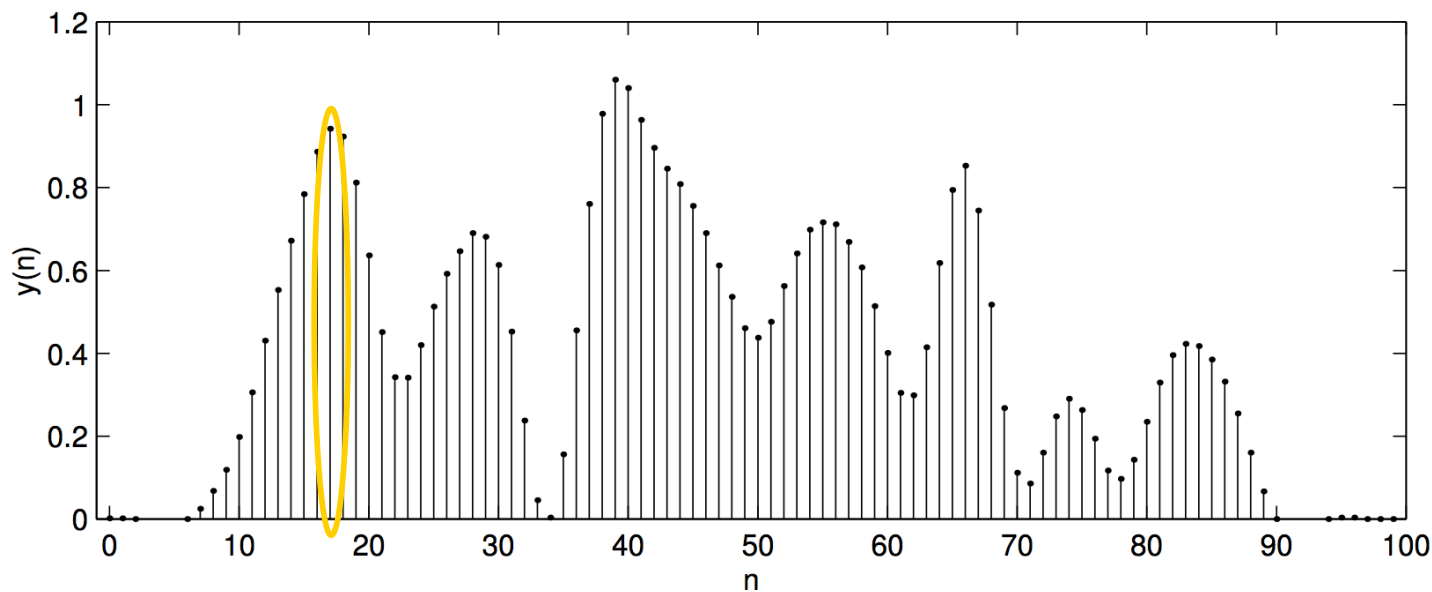




Interpolation Filter Example 2

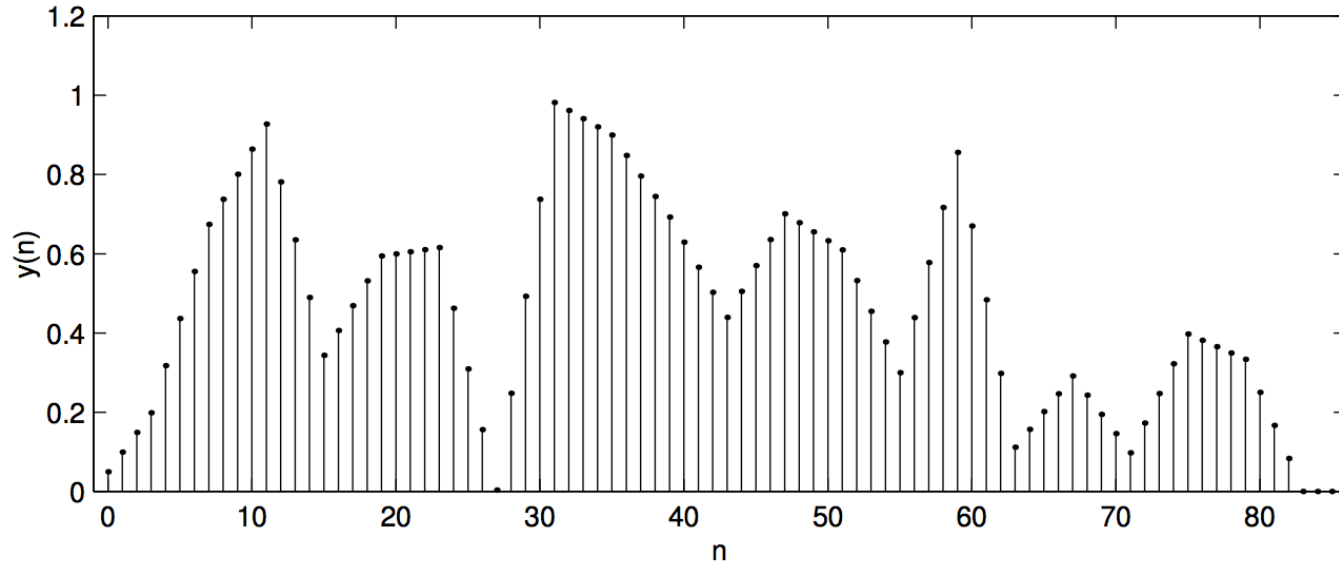


$*$
(convolve)

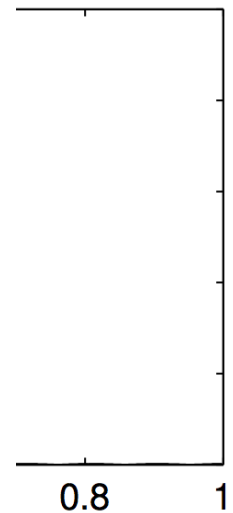
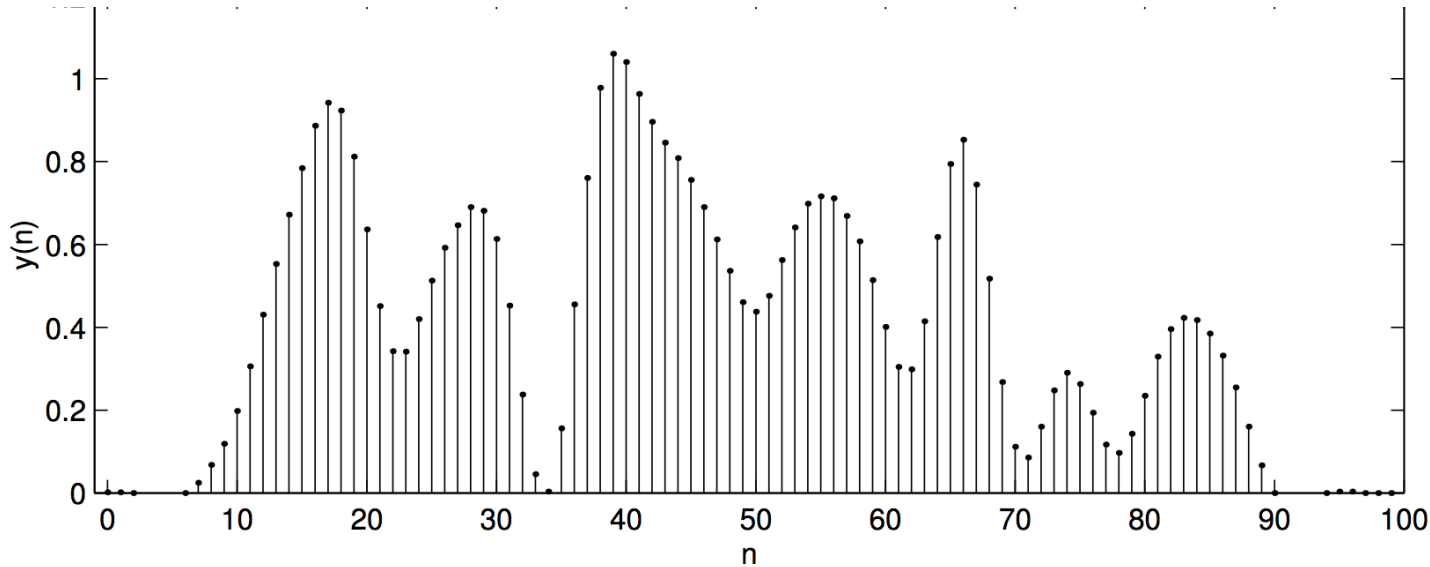




Interpolation Filter Example 2



$*$
(involve)





Interpolation Filter Example 3

- ❑ When interpolating a signal $x(n)$, the interpolation filter $h(n)$ will in general change the samples of $x(n)$ in addition to filling in the zeros.
- ❑ Can a filter be designed so as to preserve the original samples $x(n)$?



Interpolation Filter Example 3

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- ❑ Can a filter be designed so as to preserve the original samples $x(n)$?
- ❑ To be precise, if $y(n) = h(n) * [\uparrow 2] x(n)$ then can we design $h(n)$ so that $y(2n) = x(n)$?



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- ❑ Can a filter be designed so as to preserve the original samples $x(n)$?
- ❑ To be precise, if $y(n) = h(n) * [\uparrow 2] x(n)$ then can we design $h(n)$ so that $y(2n) = x(n)$?
 - Or more generally, so that $y(2n + n_o) = x(n)$?

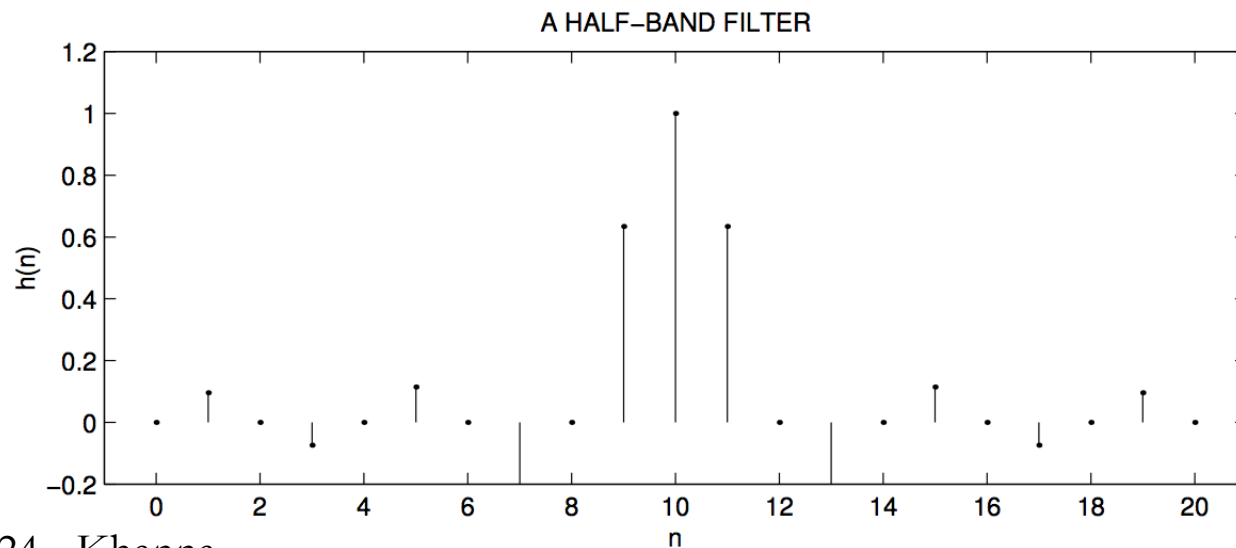


Interpolation Filter Example 3

- When interpolating by a factor of 2, if $h(n)$ is a half-band filter, then it will not change the samples $x(n)$.
- A n_o -centered half-band filter $h(n)$ is a filter that satisfies:

$$h(n) = \begin{cases} 1, & \text{for } n = n_o \\ 0, & \text{for } n = n_o \pm 2, 4, 6, \dots \end{cases}$$

- That means, every second value of $h(n)$ is zero, except for one such value, as shown in the figure.

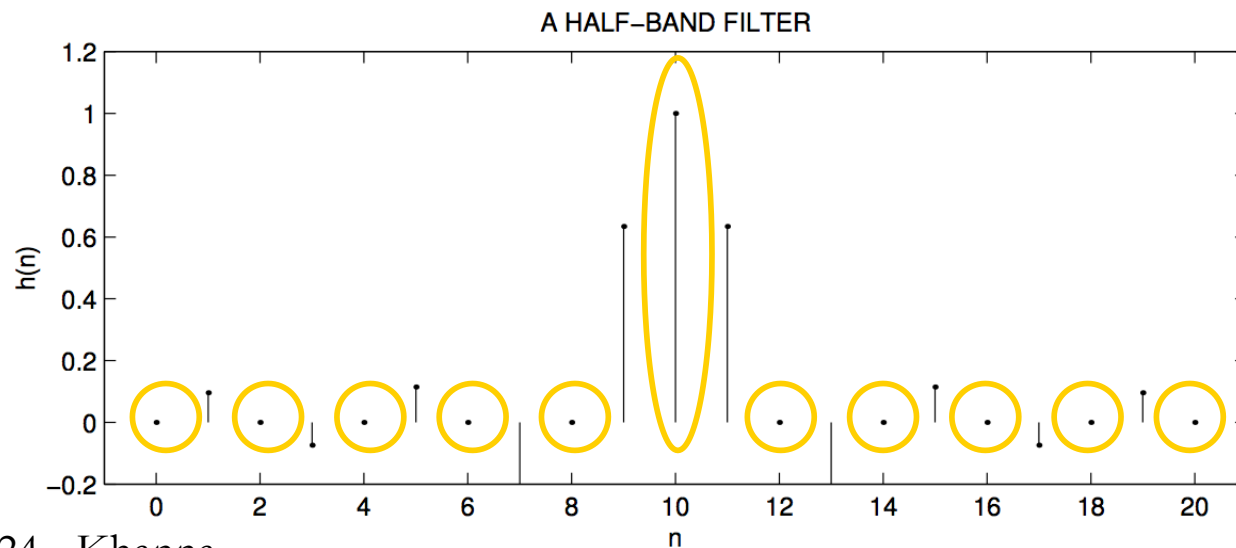


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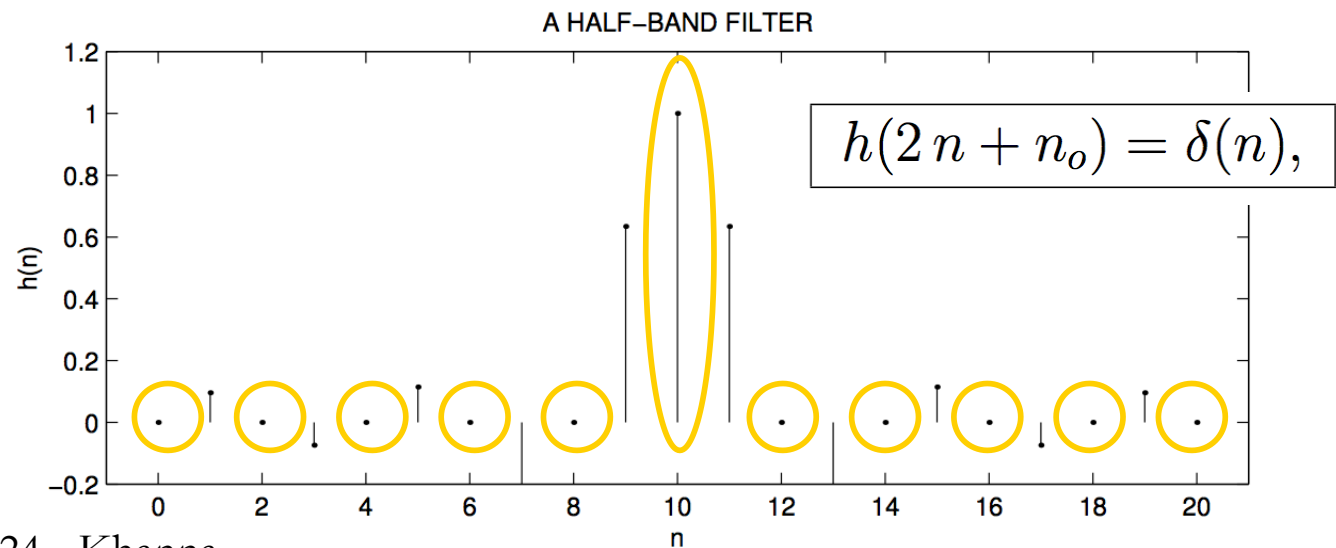


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Interpolation Filter Example 4

- ❑ When interpolating a signal $x(n)$ by a factor L , the original samples of $x(n)$ are preserved if $h(n)$ is a Nyquist- L filter.
- ❑ A Nyquist- L filter simply generalizes the notion of the halfband filter to $L > 2$.



Interpolation Filter Example 4

- ❑ When interpolating a signal $x(n)$ by a factor L , the original samples of $x(n)$ are preserved if $h(n)$ is a Nyquist- L filter.
- ❑ A Nyquist- L filter simply generalizes the notion of the halfband filter to $L > 2$.
- ❑ A (0-centered) Nyquist- L filter $h(n)$ is one for which

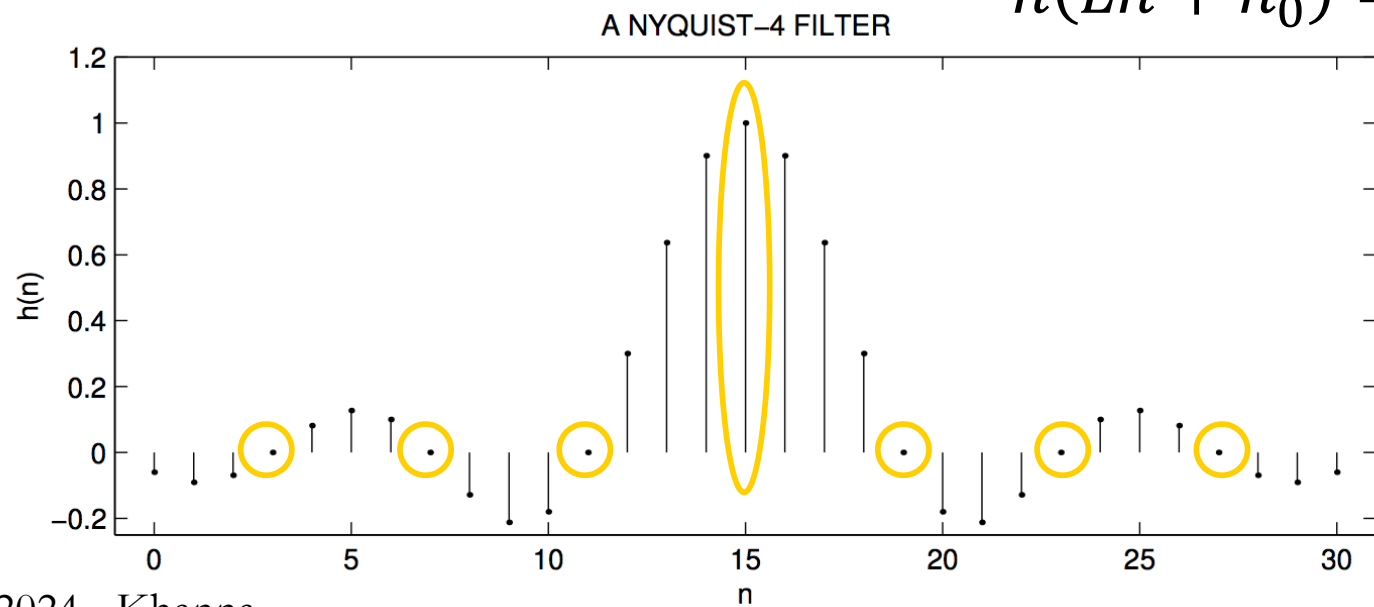
$$h(Ln) = \delta(n).$$

Interpolation Filter Example 4

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- ❑ A Nyquist- L filter simply generalizes the notion of the halfband filter to $L > 2$.
- ❑ A (0-centered) Nyquist- L filter $h(n)$ is one for which

$$h(Ln) = \delta(n).$$

$$h(Ln + n_0) = \delta(n)$$



Non-integer Resampling





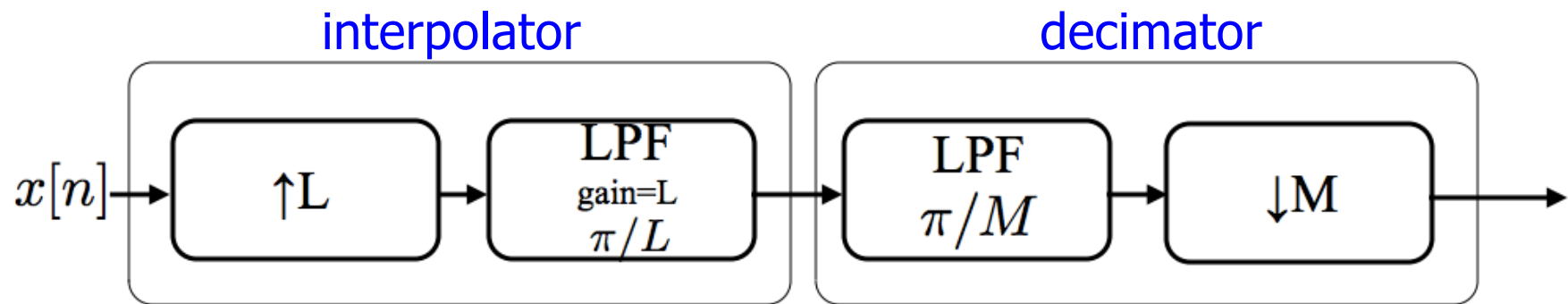
Non-integer Resampling

□ $T' = TM/L$

Non-integer Resampling

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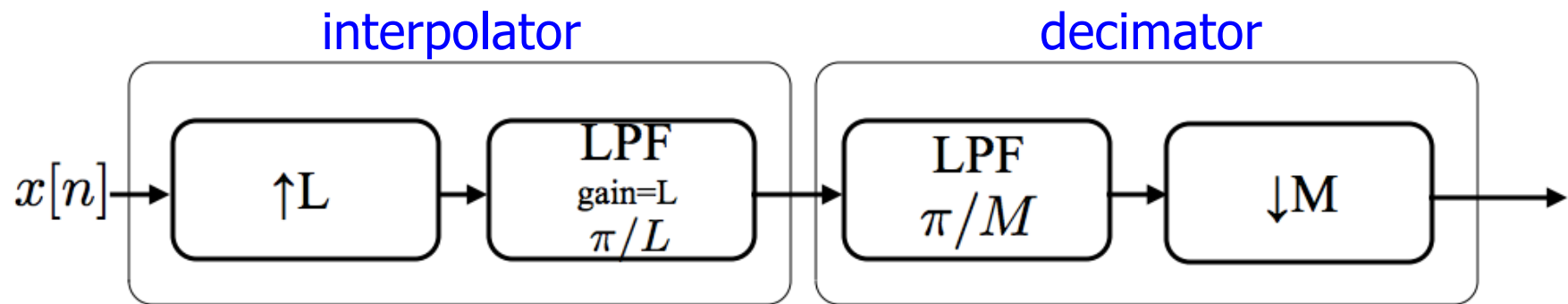
- Upsample by L , then downsample by M



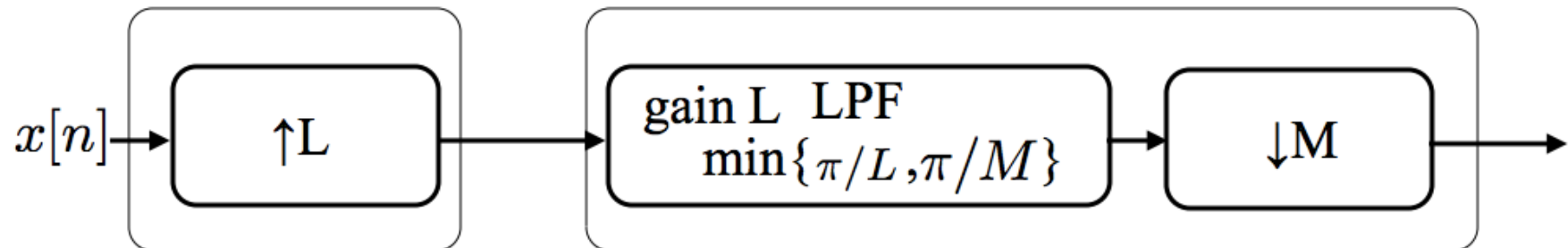
Non-integer Resampling

□ $T' = TM/L$

- Upsample by L , then downsample by M

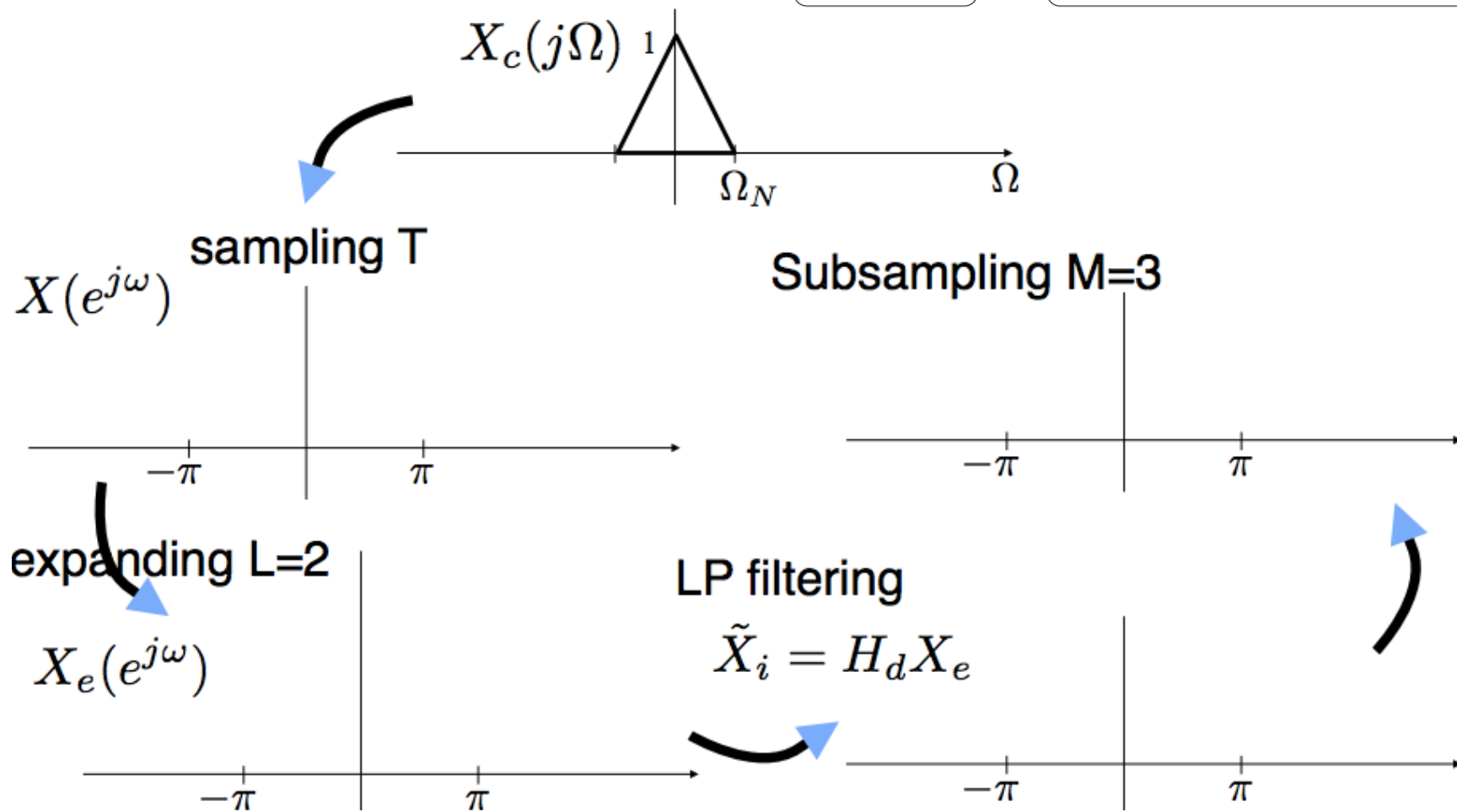
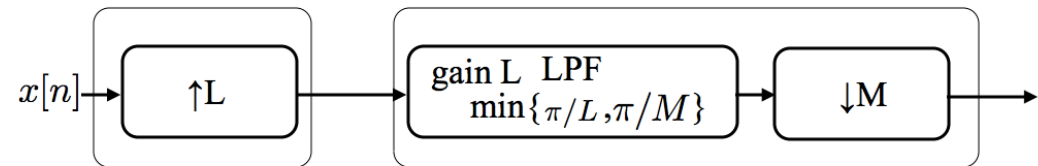


Or,



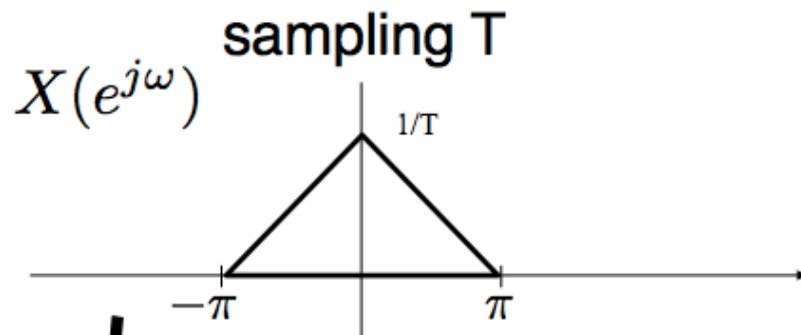
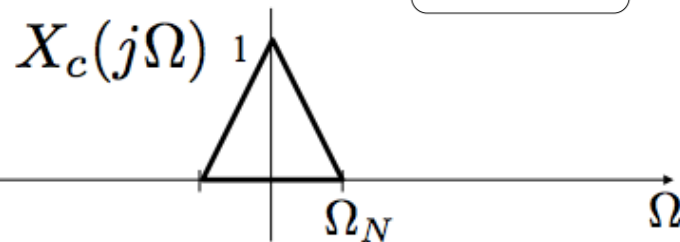
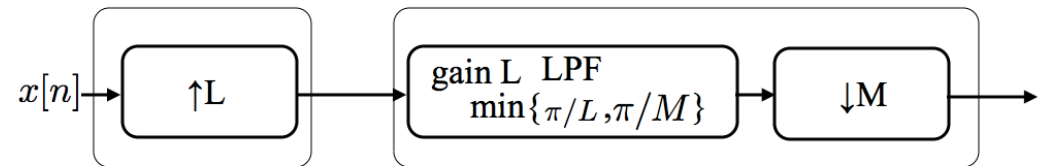
Example

□ $T' = 3/2T \rightarrow L=2, M=3$

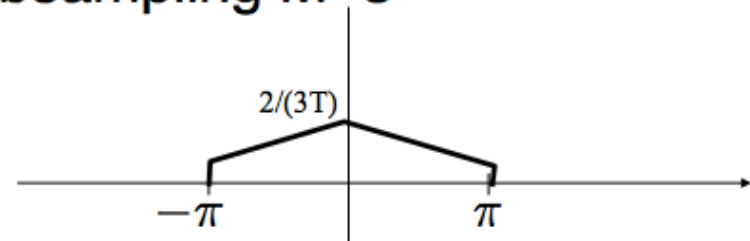


Example

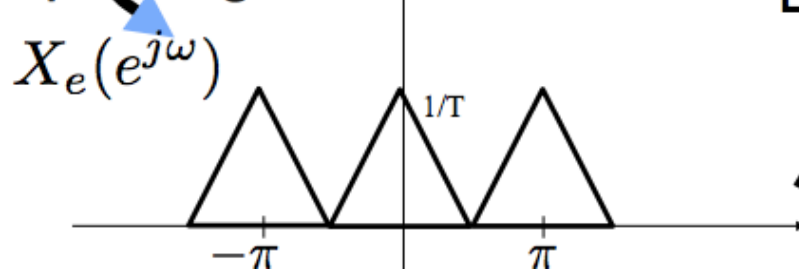
□ $T' = 3/2T \rightarrow L=2, M=3$



Subsampling $M=3$

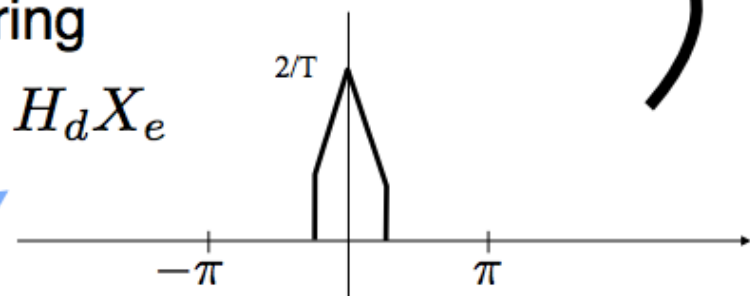


expanding $L=2$



LP filtering

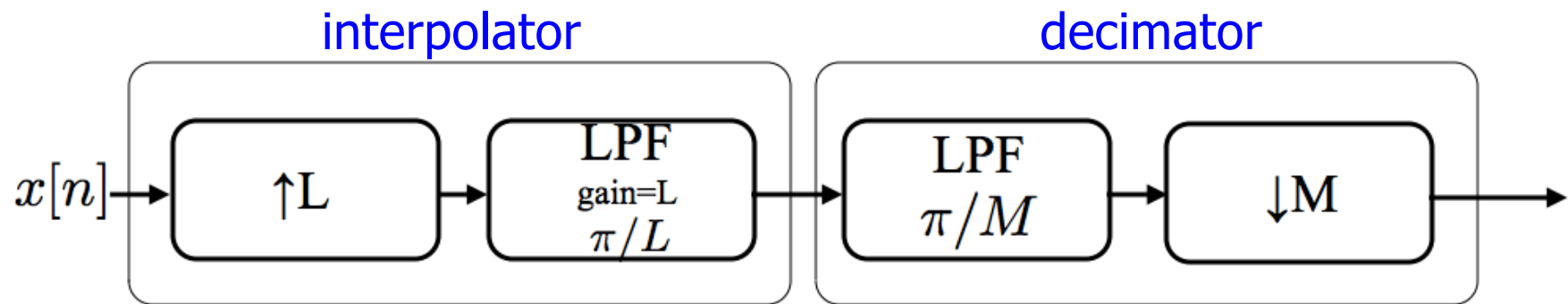
$$\tilde{X}_i = H_d X_e$$



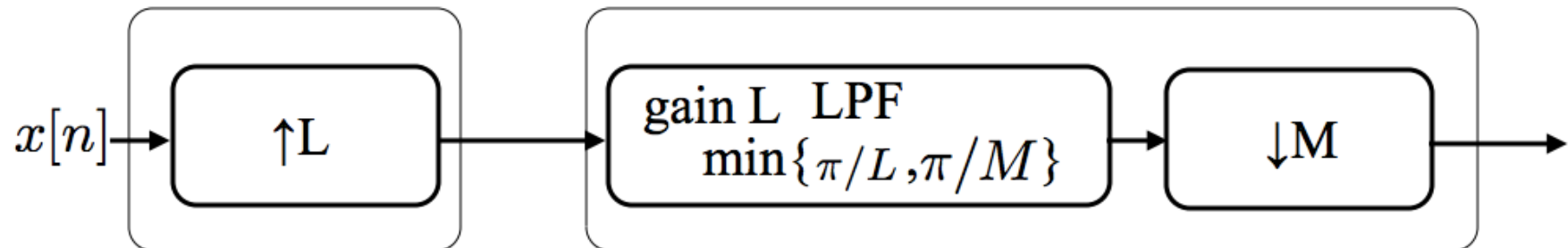
Non-integer Sampling

□ $T' = TM/L$

- Downsample by M , then upsample by L ?



Or,





Example

- What if we want to resample by 1.01T?



Example

- What if we want to resample by 1.01T?
 - Upsample by $L=100$
 - Filter $\pi/101$
 - Downsample by $M=101$



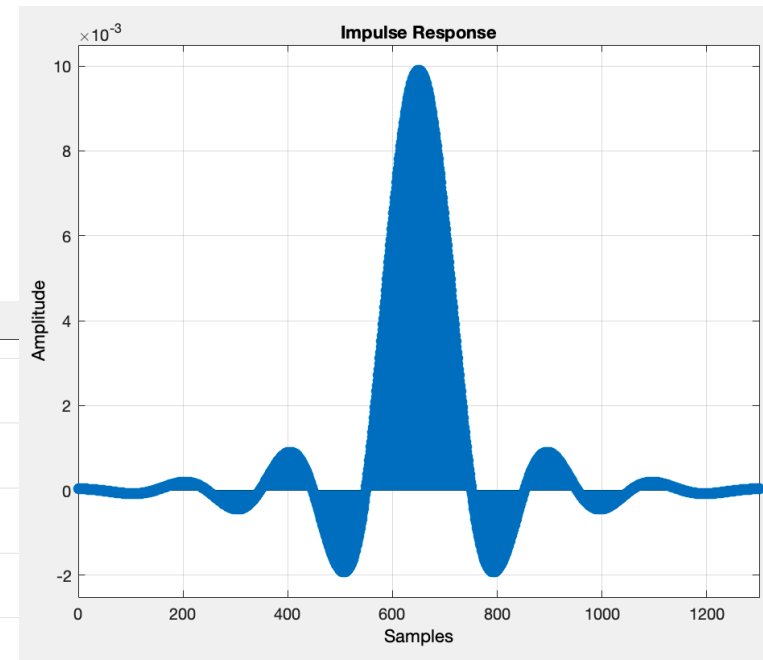
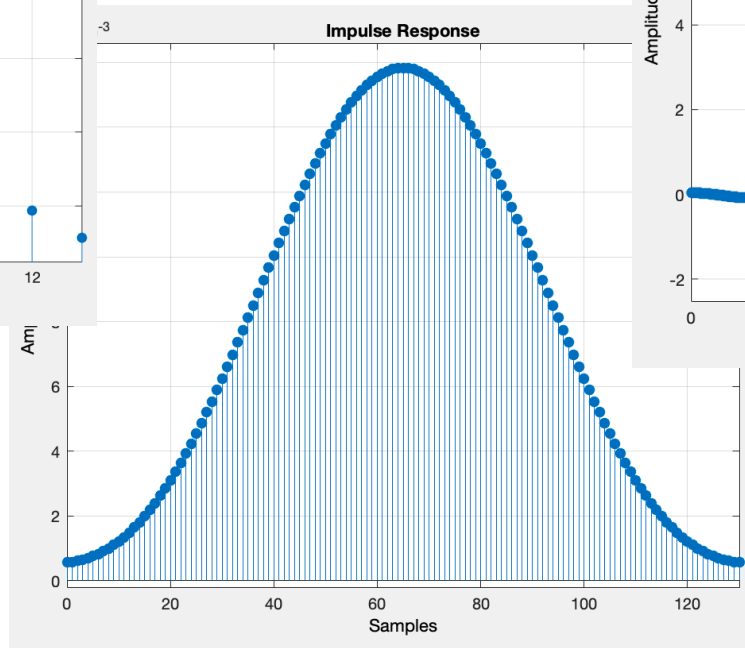
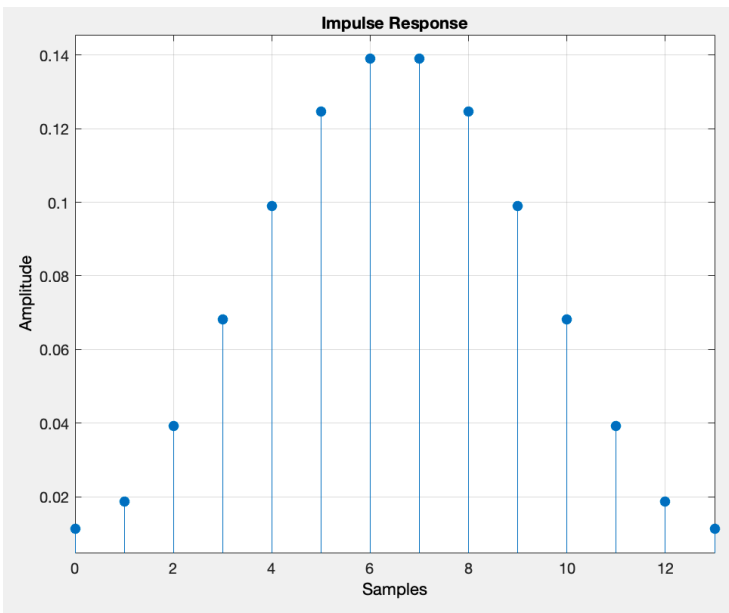
Example

- ❑ What if we want to resample by 1.01T?
 - Upsample by $L=100$
 - Filter $\pi/101$ (\$\$\$\$\$)
 - Downsample by $M=101$

- ❑ Fortunately there are ways around it!
 - Called multi-rate signal processing
 - Uses compressors, expanders and filtering

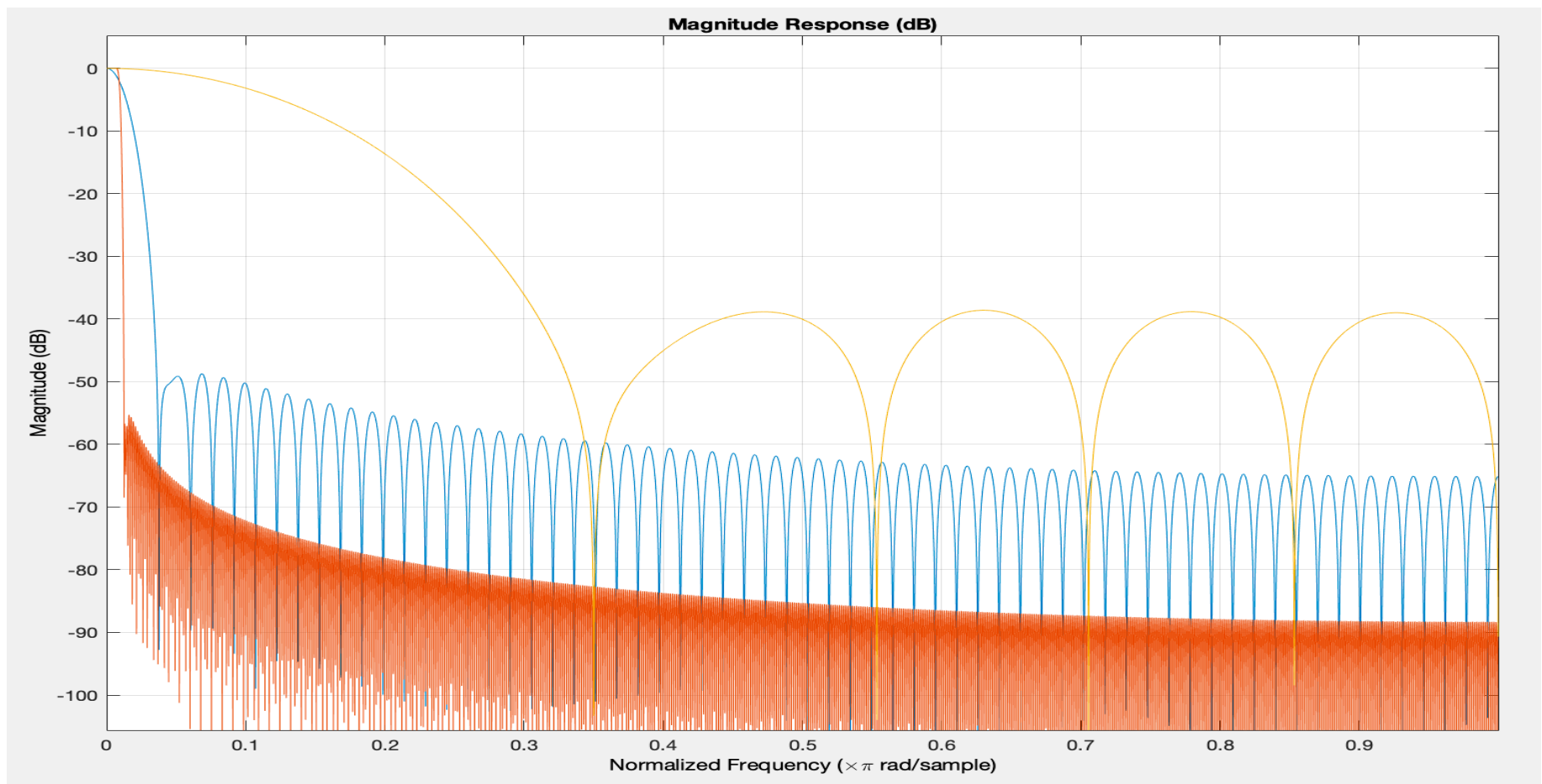
Filter Cost

- Design filter with cutoff frequency of $\pi/101 = 0.01\pi$:
- Compare 3 filters: length 13, 130, and 1300



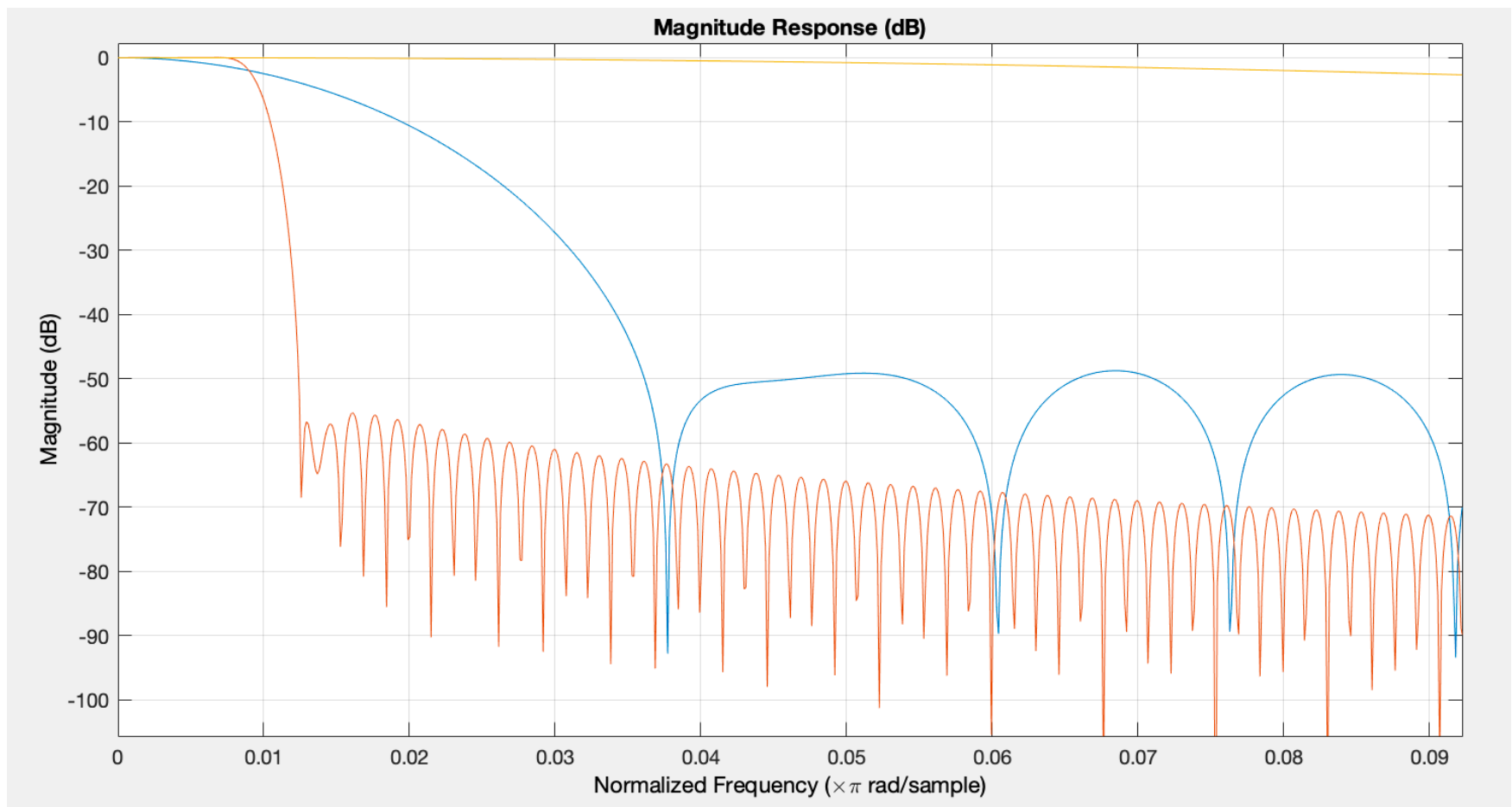
Filter Cost

- Design filter with cutoff frequency of $\pi/101 = 0.01\pi$:
 - Compare 3 filters: length 13, 130, and 1300



Filter Cost

- Design filter with cutoff frequency of $\pi/101 = 0.01\pi$:
 - Compare 3 filters: length 13, 130, and 1300



Filter Cost

- Design filter with cutoff frequency of $\pi/101=0.01\pi$:
 - Compare 3 filters: length 13, 130, and 1300

```
>> cost(firFilt3)
```

```
ans =
```

```
[ struct with fields:
```

```
                NumCoefficients: 14
                NumStates: 13
MultiplicationsPerInputSample: 14
AdditionsPerInputSample: 13
```

```
>> cost(firFilt1)
```

```
ans =
```

```
[ struct with fields:
```

```
                NumCoefficients: 131
                NumStates: 130
MultiplicationsPerInputSample: 131
AdditionsPerInputSample: 130
```

```
>> cost(firFilt2)
```

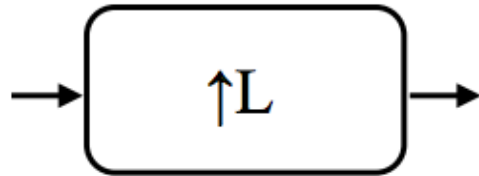
```
ans =
```

```
[ struct with fields:
```

```
                NumCoefficients: 1301
                NumStates: 1300
MultiplicationsPerInputSample: 1301
AdditionsPerInputSample: 1300
```

Interchanging Operations

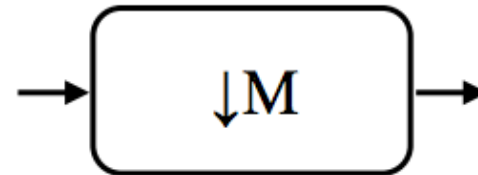
LTI?



“expander”

Upsampling

- expanding in time
- compressing in frequency



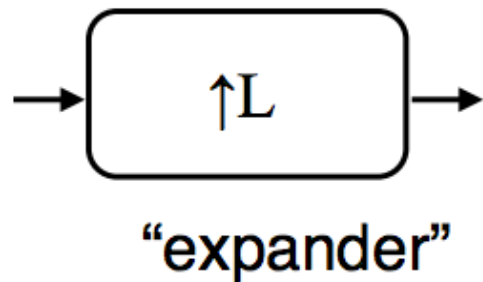
“compressor”

Downsampling

- compressing in time
- expanding in frequency

not LTI!

Interchanging Operations - Expander



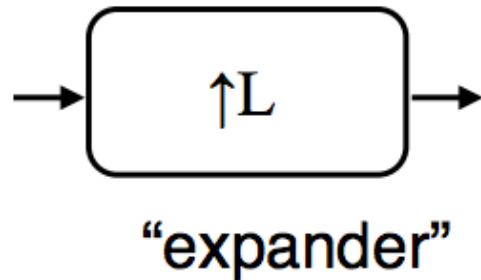
Upsampling

-expanding in time

-compressing in frequency



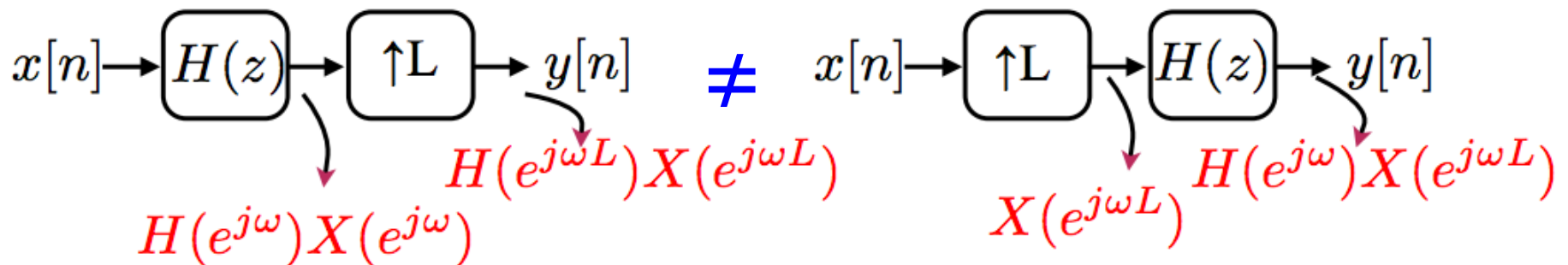
Interchanging Operations - Expander



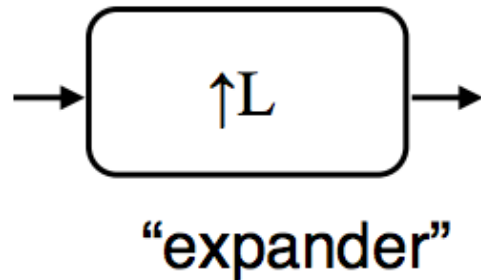
Upsampling

-expanding in time

-compressing in frequency



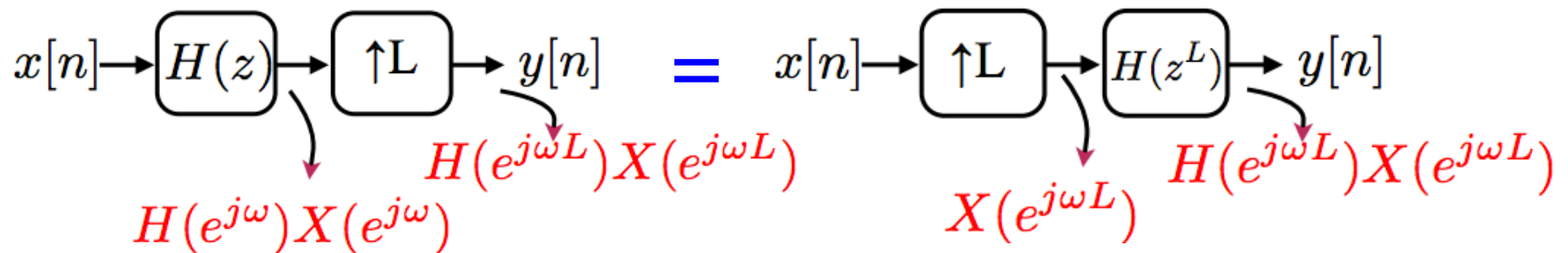
Interchanging Operations - Expander



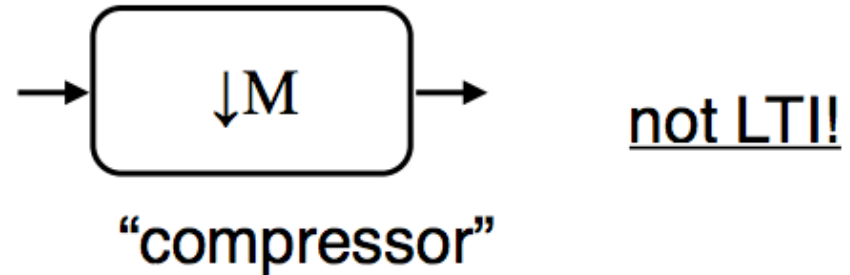
Upsampling

-expanding in time

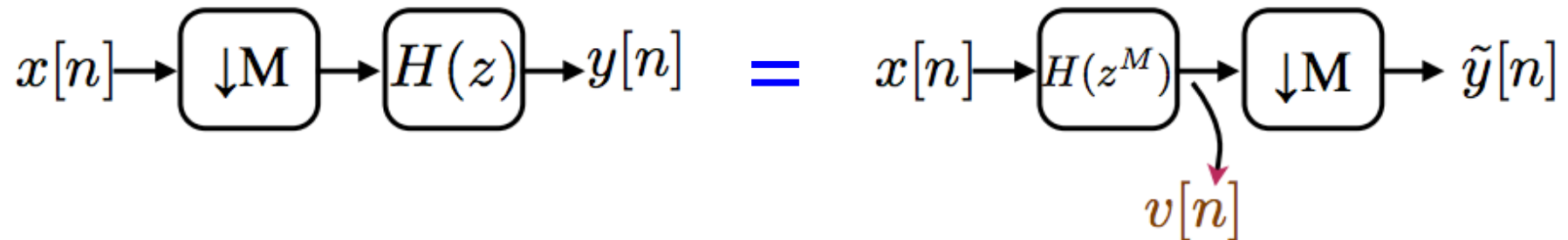
-compressing in frequency



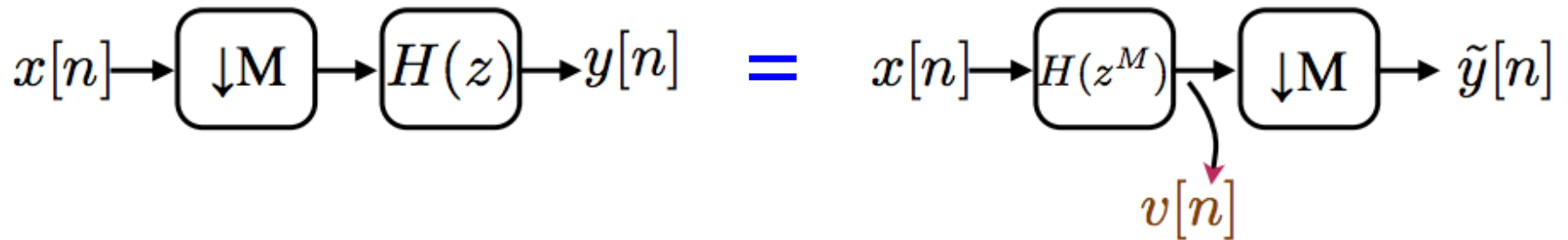
Interchanging Operations - Compressor



Downsampling
-compressing in time
-expanding in frequency

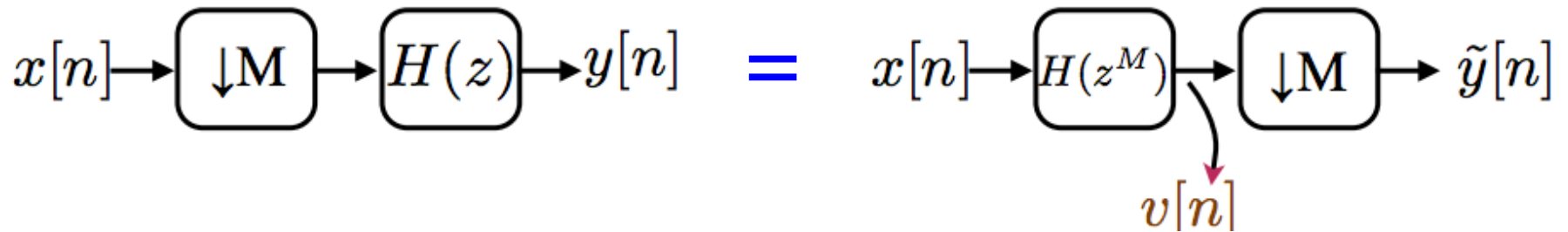


Interchanging Operations - Compressor



$$\begin{aligned}
 Y(e^{j\omega}) &= H(e^{j\omega}) \left(\frac{1}{M} \sum_{i=0}^{M-1} X \left(e^{j(\frac{\omega}{M} - \frac{2\pi i}{M})} \right) \right) \\
 &= \frac{1}{M} \sum_{i=0}^{M-1} \underbrace{H \left(e^{j(\omega - 2\pi i)} \right)}_{H(e^{j\omega})} X \left(e^{j(\frac{\omega}{M} - \frac{2\pi i}{M})} \right) \\
 &= \frac{1}{M} \sum_{i=0}^{M-1} H \left(e^{jM(\frac{\omega}{M} - \frac{2\pi i}{M})} \right) X \left(e^{j(\frac{\omega}{M} - \frac{2\pi i}{M})} \right)
 \end{aligned}$$

Interchanging Operations - Compressor



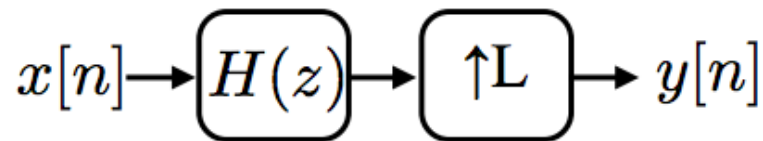
$$Y(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} H\left(e^{jM\left(\frac{\omega}{M} - \frac{2\pi i}{M}\right)}\right) X\left(e^{j\left(\frac{\omega}{M} - \frac{2\pi i}{M}\right)}\right)$$

$$V(e^{j\omega}) = H(e^{j\omega M})X(e^{j\omega}) \quad =$$

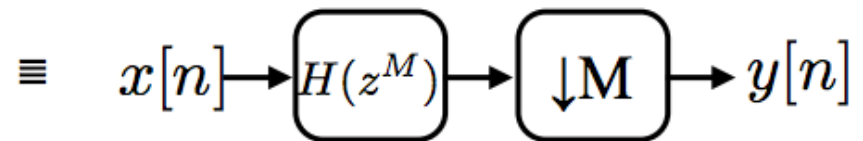
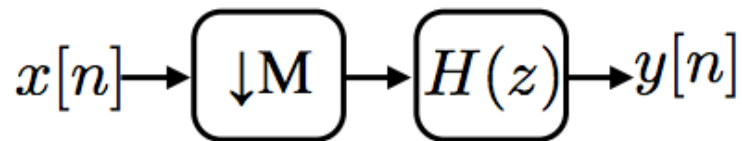
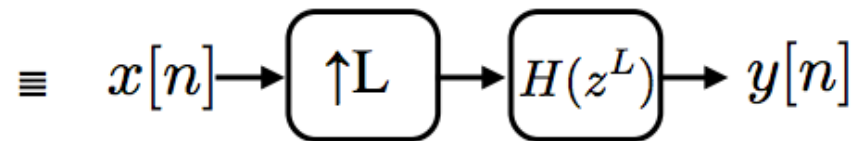
$$\tilde{Y}(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} V\left(e^{j\left(\frac{\omega}{M} - \frac{2\pi i}{M}\right)}\right)$$

Interchanging Operations - Summary

Filter and expander



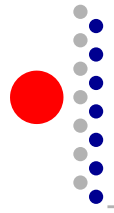
Expander and expanded filter*



Compressor and filter

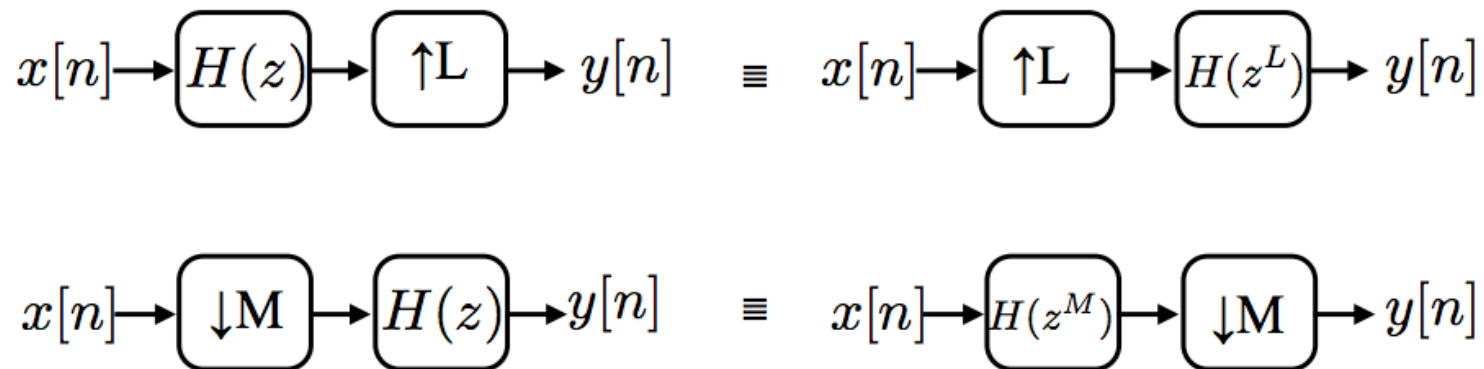
Expanded filter* and compressor

*Expanded filter = expanded impulse response, compressed freq response



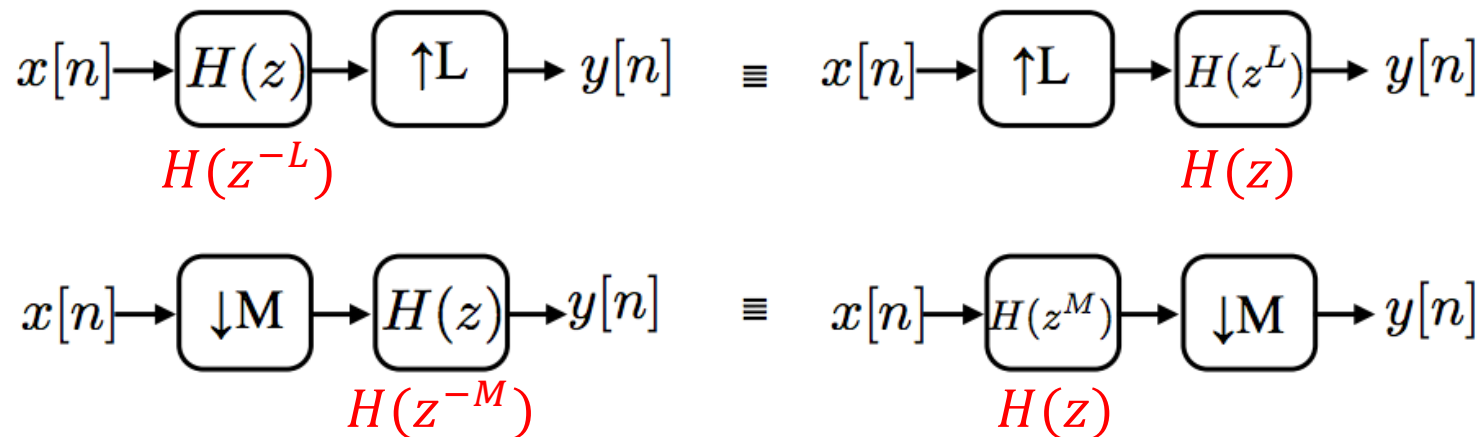
Multi-Rate Signal Processing

- What if we want to resample by $1.01T$?
 - Expand by $L=100$
 - Filter $\pi/101$ (\$\$\$\$\$)
 - Compress by $M=101$



Multi-Rate Signal Processing

- What if we want to resample by 1.01T?
 - Expand by $L=100$
 - Filter $\pi/101$ (\$\$\$\$\$)
 - Compress by $M=101$





Big Ideas

- ❑ Non-integer Resampling
- ❑ Multi-Rate Processing
 - Interchanging Operations

$$x[n] \rightarrow H(z) \rightarrow \uparrow L \rightarrow y[n] \quad \equiv \quad x[n] \rightarrow \uparrow L \rightarrow H(z^L) \rightarrow y[n]$$

$$x[n] \rightarrow \downarrow M \rightarrow H(z) \rightarrow y[n] \quad \equiv \quad x[n] \rightarrow H(z^M) \rightarrow \downarrow M \rightarrow y[n]$$



Admin

- ❑ HW 4 due Sunday