

ESE532: System-on-a-Chip Architecture

Day 9: October 1, 2018
Real Time



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Today

Real Time

- Demands
- Challenges
 - Algorithms
 - Architecture
- Disciplines to achieve

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Message

- Real-Time applications demand different discipline from best-effort tasks
- Look more like synchronous circuits
- Can sequentialize, like processor
 - But must avoid/rethink typical general-purpose processor common-case optimizations

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Real Time

- “Real” – refers to physical time
 - Connection to Real or Physical World
- Contrast with “virtual” or “variable” time
- Handles events with absolute guarantees on timing

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Real-Time Tasks

- What timing guarantees might you like for the following tasks?
 - Push a fire button on a video game
 - Delay to recognize and shoots bullet
 - Turn steering wheel on a drive-by-wire car
 - Delay to recognized and car turns
 - Self-driving car detects an object in its path
 - Delay from object appearing to detection
 - Pacemaker stimulates your heart
 - Video playback (frame to frame delay)

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Real-Time Guarantees

- Attention/processing within fixed interval
 - Sample new value every XX ms
 - Produce new frame every 30 ms
 - Both: schedule to act and complete action
- Bounded response time
 - Respond to keypress within 20 ms
 - Detect object within 100 ms
 - Return search results within 200 ms

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Computer Response

- What do these things indicate?
 - When will the computer complete the task?



https://en.wikipedia.org/wiki/File:Windows_8_%2B_10_wait_cursor.gif
<https://en.wikipedia.org/wiki/File:WaitCursor-300p.gif>

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Real-Time Response

- What if your car gave you a spinning wait wheel for 5 seconds when you
 - Turned the wheel?
 - Stepped on the brakes?



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Synchronous Circuit Model

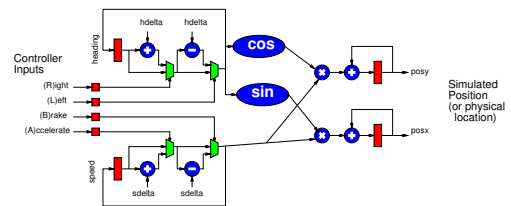
- A simple synchronous circuit is a good “model” for real-time task
 - Run at fixed clock rate
 - Take input every “cycle”
 - Produce output every “cycle”
 - Complete computation between input and output
 - Designed to run at fixed-frequency
 - Critical path meets frequency requirement

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Preclass 2

- Worst-case delay from (L)eft press to change in heading?
- Cycle rate could operate?



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Historically

- Real-Time concerns grew up in EE
 - Because an analog circuit was the only way could meet frequency demands
 - ...later a dedicated digital circuit...
- Applications
 - Signal processing, video, control, ...

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Technological Change

- Why not be satisfied with this answer today?
 - That is, for real-time task need dedicated synchronous circuit?
 - Hint: What does preclass 2b suggest?

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Performance Scaling

- As circuit speeds increased
 - Can meet real-time performance demands with heavy sequentialization
- Circuit and processor clocks
 - from MHz to GHz
- Many real-time task rates unchanged
 - 44KHz audio, 33 frames/second video
- Even 100MHz processor
 - Can implement audio in a small fraction of its computational throughput capacity

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HW/SW Co-Design

- Computer Engineers – know can implement anything as hardware or software
- Want freedom to move between hardware and software to meet requirements
 - Performance, costs, energy

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Real-Time Challenge

- Meet real-time demands / guarantees
 - Economically using programmable architectures
- Sequentialize and share resources with deterministic, guaranteed timing

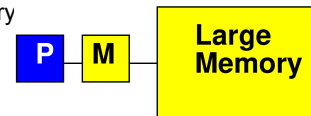
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Processor Data Caches

Day 3

- Traditional Processor Data Caches are a heuristic instance of this
 - Add a small memory local to the processor
 - It is fast, low latency
 - Store anything fetched from large/remote memory in local memory
 - Hoping for reuse in near future
 - On every fetch, check local memory before go to large memory



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Processor Data Caches

Day 3

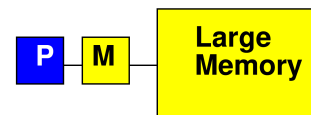
- Demands more than a small memory
 - Need to sparsely store address/data mappings from large memory
 - Makes more area/delay/energy expensive than just a simple memory of capacity
- Don't need explicit data movement
- Cannot control when data moved/saved
 - Bad for determinism
- Limited ability to control what stays in small memory simultaneously

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Processor Data Caches

- Traditional Processor Data Caches are a heuristic instance of this
 - Store anything fetched from large/remote memory in local memory
 - Hoping for reuse in near future
 - On every fetch, check local memory before go to large memory
 - Stall processor while waiting for data



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Preclass 3:

Processor Cache Timing

- Assume
 - cache miss (go to large memory) takes 10 cycles
 - Cache hit (small memory) takes 1
 - Start with empty cache
- Due to memory delay, **how long to execute:**

```
b=a[0]+a[1];          b=a[i]+a[j];
c=a[1]+a[2];          c=a[k]+a[l];
d=a[2]+a[0];          d=a[m]+a[n];
```

Observe

- Instructions on “General Purpose” processors take variable number of cycles

Preclass 4

- **How many cycles?**
 - sin, cos 100 cycles each
 - Assignments 1

```
old_sh=sh; old_ch=ch;
if (!left || !right)
    {sh=old_sh;ch=old_ch;}
else
    {sh=sine(heading);
    ch=cosine(heading);}
```

Preclass 5

- **How many cycles?**

```
sum=0;
for (i=0;i<32;i++) {
    sum+=(0-(b%2)) & a;
    b=b>>1;
    a=a<<1;
}
```

Preclass 5

- **How many cycles?**

```
sum=0;
for (;b!=0;b=b>>1) {
    if (b%2==1)
        sum+=a;
    a=a<<1;
}
```

Observe

- Data-dependent branching, looping
 - Means variable time for operations

Two Challenges

1. Architecture – Hardware have variable (data-dependent) delay
 - Esp. for General-Purpose processors
 - Instructions take different number of cycles
2. Algorithm – computational specification have variable (data-dependent) operations
 - Different number of instructions

$$Time = \sum_i Cycles(i)$$

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Algorithm

- What programming constructs are data-dependent (variable delay)?

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Programming Constructs

- Conditionals: if/then/else
- Loops without compile-time determined bounds
 - While with termination expressions
 - For with data-dependent bounds
- Data-dependent recursion
- Interrupts
 - I/O events, time-slice

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Programming Constructs

- Dynamic Dataflow (from Day 5)
 - Variable rates
 - Switch/select operators

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Architecture

- What processor constructs are variable delay?

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Processor Variable Delay

- Caches
- Dynamic arbitration for shared resources
 - Bus, I/O, Crossbar output, memory, ...
- Data hazards
- Data-dependent branching / branch delays
- Speculative issue
 - Out-of-Order, branch prediction

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Hardware Architecture

- Some typical (371, 501) processor “optimizations” can cause variable delay
 - Caches
 - Common-case optimizations
 - Pipeline stalls

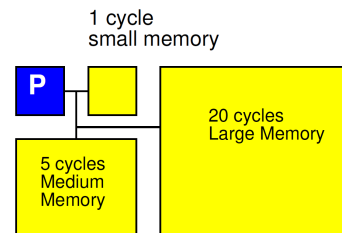
What can we do to make architecture more deterministic?

- Explicitly managed memory
- Eliminate Branching (too severe?)
- Unpipelined processors
- Fixed-delay pipelines
 - Offline-scheduled resource sharing
 - Multi-threaded
- Deadlines

Explicitly Managed Memory

- Make memory hierarchy visible
 - Use Scratchpad memories instead of caches
- Explicitly move data between memories
 - E.g. movement into local memory
- Already do for Register File in Processor
 - Load/store between memory and RF slot
 - ...but don't do for memory hierarchy

Explicitly Managed Memory



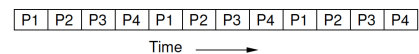
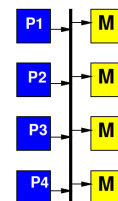
Offline Schedule Resource Sharing

- Don't arbitrate
- Decide up-front when each shared resource can be used by each thread or processor
 - Simple fixed schedule
 - Detailed Schedule
- What
 - Memory bank, bus, I/O, network link, ...

Time-Multiplexed Bus

Fixed by hardware master

- 4 masters share a bus
- Each master gets to make a request on the bus every 4th cycle
 - If doesn't use it, goes idle



Time-Multiplexed Bus

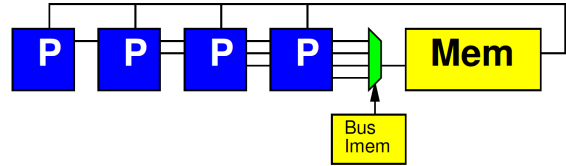
- Regular schedule
- Fixed bus slot schedule of length $N >$ masters
 - (probably a multiple)
- Assign owner for each slot
 - Can assign more slots to one
- E.g. $N=8$, for 4 masters
 - Schedule (1 2 1 3 1 2 1 4)

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Fully Scheduled

- At extreme, fully schedule which tasks gets resource on each cycle

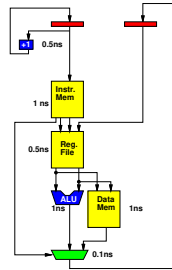


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Simple Deterministic Processor

- No branching
- Unpipelined
- Every operation completes in fixed time
- Cycle time?

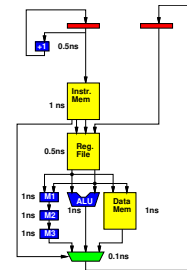


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Simple Deterministic Processor with Multiplier

- No branching
- Unpipelined
- Every operation completes in fixed time
- Cycle time?
- What's unfortunate about this?

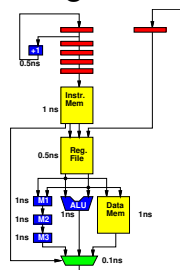


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Simple Deterministic Processor with some Pipelining

- No branching
- Every operation completes in fixed time
- Retimed cycle time?
- How pipelines added change behavior?

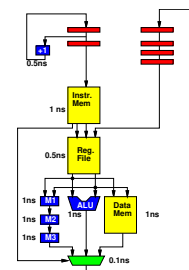


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Simple Deterministic Pipelined Processor

- No branching
- Every operation completes in fixed time
- Retimed cycle time?
- How pipelines added change behavior?
 - Hint R1 value

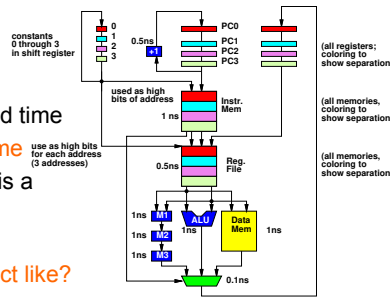


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Multithreaded Processor

- No branching
- Every operation completes in fixed time
- **Retimed cycle time**
- Each PC (color) is a separate thread
- How interact?
- What does this act like?
- Compare unpipe?

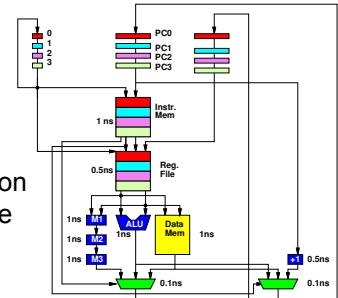


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Branching?

- Could add branching
- Architecture deterministic
- Need to reason about variable timing from branching

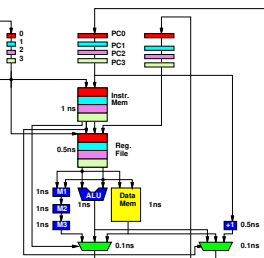


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Multithreaded Pipeline

- Non-real-time threads can share
- Timing of threads not impact each other
- Non-real-time threads take variable time
 - Not interfere with real-time thread slots



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Deadline Instruction

- Deal with algorithmic (branching) variability
- Set a hardware counter for thread
- Demand counter reach 0 before thread allowed to continue at deadline instruction
- Model: fixed rate of attention
 - Stall if get there early
 - Similar to flip-flop on a logic path
 - Wait for clock edge to change or sample value
- Model: fixed execution time

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WCET

- WCET – Worst-Case Execution Time
- Analysis when working with algorithms and architectures with data-dependent delay
 - Need to meet real time
 - Calculate the worst-case runtime of a task
 - Like calculating the critical path (but harder)
 - Worst-case delay of instructions
 - Worst-case path through code
 - Worst-case # loop iterations
 - Rationale for setting Deadlines
 - (like a cycle time)

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Deterministic Pipelines

- Not how ARM, Intel (371, 501) processor are pipelined
- Those include operations that make timing variable
 - dynamic data hazards, branch speculation
- Here, data becomes available after a predictable time
- Branches take effect at a fixed time
 - Likely delayed
- Schedule to delays to get correct data

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Different Goals

Real-Time

- Willing to recompile to new hardware
- Want time on hardware predictable
- Willing to schedule for delays in particular hardware

General Purpose/Best Effort

- ISA fixed
- Want to run same assembly on different implementations
- Tolerate different delays for different hardware
- Run faster on newer, larger implementations

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SoC Opportunity

- Can choose which resources are shared
- Can dedicate resources to tasks
- Isolate real-time tasks/portions of tasks from best-effort
 - Separate hardware/processors
 - Separate memories, network

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Big Ideas:

- Real-Time applications demand different discipline from best-effort tasks
- Look more like synchronous circuits and hardware discipline
- Avoid or use care with variable delay programming constructs
- Can sequentialize, like processor
 - But must avoid/rethink typical processor common-case optimizations
 - Offline calculate static schedule for computation and sharing

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- Instead of dynamic arbitration, interlocks

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Admin

- Wednesday/Day 10 reading on Canvas + Zynq Book
- We are here Wednesday
 - Do have office hours Monday, Tuesday
- Fall Break – Thursday and Friday
 - No Office Hours Thursday (10/4)
 - No HW due this Friday (10/5)
- HW5 due 10/12
 - Will involve some long Vivado HLS/SDSoC tool times

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