

# ESE532: System-on-a-Chip Architecture

Day 10: October 2, 2019  
Coding HLS for Accelerators



## Previously

- We can describe computational operations in C
  - Primitive operations (add, sub, multiply, and, or)
  - Dataflow graphs primitives
  - To bit level
  - Conditionals and loops
  - Function abstraction
  - Loops, Arrays

## Today

- Arrays and Memory Sequentialization (from last time)
- Pragmas in Vivado HLS C
- Controlling Memories in Vivado HLS C
- Time permitting
  - malloc, pointers, more dependencies

## Message

- Can specify HW computation in C
- Vivado HLS gives control over how design mapped (area-time, streaming...)
- Code may need some care and stylization to feed data efficiently
- Read Design Productivity Guide (UG 1197)
  - C-based IP development
- Reference Vivado HLS Users Guide (902)
  - Design Optimization

## Arrays and Memories

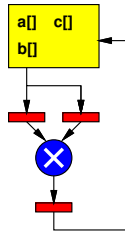
## Loop Interpretations

- What does a loop describe?
  - Sequential behavior [when execute]
  - Spatial construction [when create HW]
  - Data Parallelism [sameness of compute]
- We will want to use for all 3
- C allows expressive loops
  - Some expressiveness
    - Not compatible with spatial hardware construction

## Arrays as Memory Banks

- If single memory has only one port
  - Can perform only one memory operation per cycle
  - What if if a, b, c all in bigmem?

```
for (i=0;i<1024;i++)
    c[i]=a[i]*b[i];
```



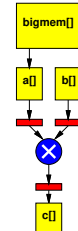
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## Arrays as Memory Banks

- Hardware expression: Sometimes we will want to describe computations with separate memory banks

```
int a[1024], b[1024],
    c[1024];
for(i=0;i<1024;i++)
    a[i]=bigmem[offset+i];
for (i=0;i<1024;i++)
    c[i]=a[i]*b[i];
```



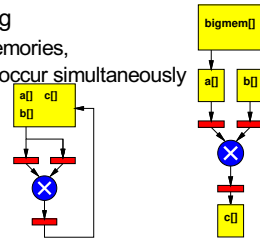
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## Physical Memory Port as Limited Shared Resource

- Typically single memory port
  - Must sequentialize on use of memory port
  - Reason for banking
    - Put in separate memories, so operations can occur simultaneously

Ultra96 DRAM 1 port  
Virtex BRAM 2 ports

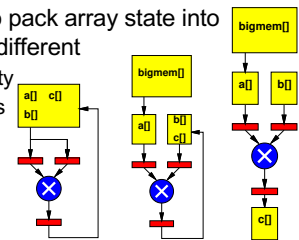


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## Arrays as things to put in Memory Banks

- Computational expression:
  - sometimes it is useful to express computation
  - **then** decide how to pack array state into memory banks for different
    - Hardware availability
    - Area-Time tradeoffs



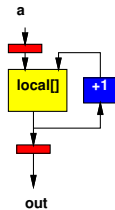
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## Arrays as Local Memory

- Hardware/Computational expression: natural way of describing local state

```
hist(int a[SIZE], out[EVENTS]) {
    int local[EVENTS];
    for(i=0;i<EVENTS;i++)
        local[i]=0;
    for(i=0;i<SIZE;i++)
        local[a[i]]++;
    for(i=0;i<EVENTS;i++)
        out[i]=local[i];
}
```



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## Arrays as Inputs and Outputs

- Computational Expression: arrays are often a natural way of expression set of inputs and outputs

```
int c=12;
while(true)
{
    int aval=astream.read();
    int bval=bstream.read();
    int res=a*b+c;
    resstream.write(res);
}

void op(int a[BLOCK], int
        b[BLOCK], int out[BLOCK]) {
    for (i=0;i<BLOCK;i++)
    {
        out[i]=a[i]*b[i]+c;
    }
}
```

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## Array Interpretations

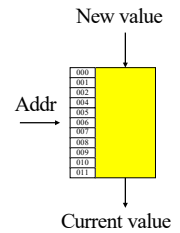
- What does an array describe?
  1. Compact expression [write less code]
  2. Memory banks [where place data]
    - Things put in separate memory banks
  3. Local memory [not need to be shared]
  4. I/O [source and sink of data]
- We will want to use for all 4
- C allows expressive use of arrays/memories
  - Some expressiveness will inhibit efficient hardware

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## C Memory Model

- One big linear address space of locations
- Most recent definition to location is value
- Sequential flow of statements

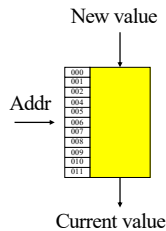


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## Challenge: C Memory Model

- One big linear address space of locations
- Assumes all arrays live in same memory
- Assumes arrays may overlap?

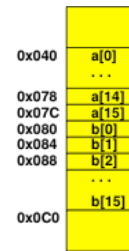


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## Example

- Assume a, b live in same memory
- Placed in sequence as shown
- What happens when
  - int a[16];
  - int b[16];
  - Read from a[17]
  - Read from b[-2]
- Can inhibit separation into memory banks, parallelism



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## Memory Operation Challenge

- Memory is just a set of location
- But **memory expressions** in C can refer to variable locations
  - Does A[i], B[j] refer to same location?
  - A[f(i)], B[g(i)] ?
- Can inhibit banking, parallelism
  - Or add expensive interconnect

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## C Memory/Pointer Sequentialization

- Must preserve ordering of memory operations
  - A read cannot be moved before write to memory which may redefine the location of the read
    - Conservative: any write to memory
    - Sophisticated analysis may allow us to prove independence of read and write
  - Writes which may redefine the same location cannot be reordered

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## C Memory/Pointer Sequentialization

- Must preserve ordering of memory operations
  - A read cannot be moved before write to memory which may redefine the location of the read
  - Writes which may redefine the same location cannot be reordered
- True for read/write to single array even if know arrays isolated
  - Does A[B[i]] refer to same location as A[C[i]]?
  - So expression issue broader than C

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## Consequence

- **Expressions and operations** through variables (whose address is never taken) can be executed at any time
  - Just preserve the dataflow
- **Memory assignments** must execute in strict order
  - Ideally: partial order
  - Conservatively: strict sequential order of C

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## More at end of lecture

- If time permits, more on Sequentialization and Dependencies

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## Vivado HLS Mapping Control

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## Preclass 2

- What dataflow graph does this describe?

```
while(true) {
    i=read_input();
    fA(i,t1);
    fB(t1,t2);
    fC(t2,out);
    write_output(out);
}
```

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## Vivado HLS Pragma DATAFLOW

- Enables streaming data between functions and loops
- Allows concurrent streaming execution
- Requires data be produced/consumed sequentially
  - i.e. can connect with FIFO;
  - not need reorder

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## Dataflow with Arrays

```
int i[100];
int t1[100], t2[100];
int out[100];
while(true) {
    read_input(i, 100);
    fA(i, t1);
    fB(t1, t2);
    fC(t2, out);
    write_output(out, 100);
}
```

## Streamable

- Processes input and output in order

```
void fA (int in[100], int out[100])
{
    out[0]=in[0];
    for (int i=1;i<100;i++)
        out[i]=(in[i]+in[i-1])/2;
}
```

## Cannot Stream Input

- Why?

```
void fB (int in[100], int out[100])
{
    for (int i=1;i<100;i++)
        out[i]=in[100-i];
}
```

## Streamable?

- Can stream input?
- Can stream output?

```
void fC (int in[100], int out[100])
{
    for (int i=1;i<100;i++)
        out[i]=0;
    for (int i=1;i<100;i++)
        out[in[i]%100]++;
}
```

## Vivado HLS Pragma DATAFLOW

- Enables streaming data between functions and loops
- Allows concurrent streaming execution
- Requires data be produced/consumed sequentially
  - i.e. can connect with FIFO; not need reorder
- Useful to use stream data type between functions – communicates sequence
  - hls::stream<TYPE>

## Streaming Operations

- Functions can have stream inputs and outputs
  - Must pass a pointers
    - hls::stream<Type> &strm
- Vivado HLS expressiveness to define hardware streaming operation pipelines

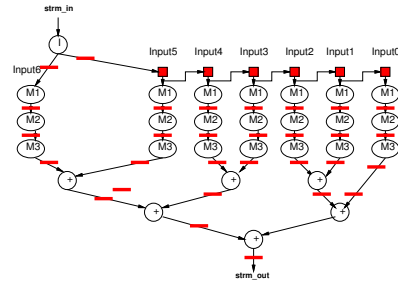


```

void stream_filter (
    hls::stream<uint16_t> &strm_out,
    hls::stream<uint16_t> &strm_in
)
while(true) {
    yout=0;
    Input5=Input6;
    Input4=Input5;
    Input3=Input4;
    Input2=Input3;
    Input1=Input2;
    Input0=Input1;
    strm_in.read(Input0);
    Sum = Coefficients_0 * Input0 +
          Coefficients_1 * Input1 +
          Coefficients_2 * Input2 +
          Coefficients_3 * Input3 +
          Coefficients_4 * Input4 +
          Coefficients_5 * Input5 +
          Coefficients_6 * Input6;
    strm_out.write(Sum>>8);
}

```

## stream\_filter Pipeline



## Dataflow Streaming

- Works between loops, as well

## Between Loops

```

int data_in[N], data_out[N*256];
hls::stream<int> ystream;
short val, res, copies;
int current;

#pragma HLS dataflow

for (i=0; i<N; i++) {
    pair=data_in[i];
    copies=(pair>>16) &0x0fff;
    val=pair&0x0ffff;
    for (j=0; j<copies; j++)
        ystream.write(val);
}

for (int i=0; i<N*256; i++)
{
    ystream.read(res);
    current=current+res;
    data_out[i]=current;
}

```

## Vivado HLS Pragma PIPELINE

- Direct a function or loop to be pipelined
- Ideally start one loop or function body per cycle
  - Can control II

```

for (i=0; i<N; i++)
    yout=0;
#pragma HLS PIPELINE
for (j=0; j<K; j++)
    yout+=in[i+j]*w[j];
y[i]=yout;

```

Which solution from preclass 3?

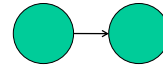
## Dataflow and pipelining

- Dataflow allows coarse-grained pipelining among loops and functions
- Pipeline causes loop bodies to be pipelined

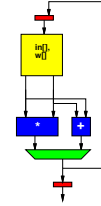
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## Dataflow and Pipelining



- Cycles for top loop unpipelined?



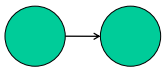
```
for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}
```

```
for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}
```

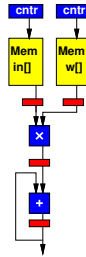
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## Dataflow and Pipelining



- Cycles for top loop pipelined?



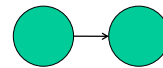
```
for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}
```

```
for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}
```

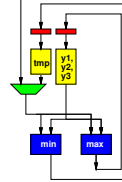
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## Dataflow and Pipelining



- Cycles for bottom loop unpipelined?



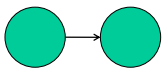
```
for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}
```

```
for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}
```

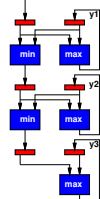
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## Dataflow and Pipelining



- Cycles for bottom loop pipelined?



```
for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}
```

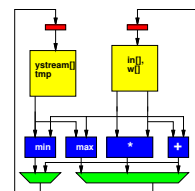
```
for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}
```

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## Dataflow and Pipelining

- Composite time, no dataflow, no pipelining?



```
for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}
```

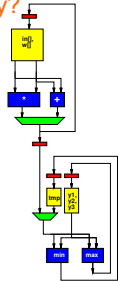
```
for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}
```

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## Dataflow and Pipelining

- Composite time dataflow only?

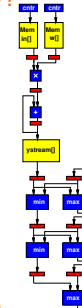


```
for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}
```

```
for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}
```

## Dataflow and Pipelining

- Composite time pipelining only?

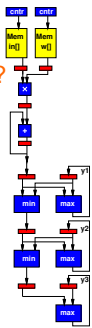


```
for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}
```

```
for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}
```

## Dataflow and Pipelining

- Composite time dataflow and pipelining?

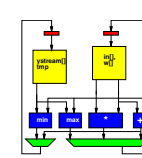


```
for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}
```

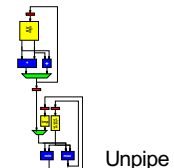
```
for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}
```

## Compare Cases

No Dataflow

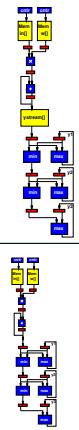


Dataflow



Unpipe

Pipe



## Unroll

- Vivado HLS has pragmas for unrolling
- UG902: Vivado Design Suite HLS User's Guide
  - P139—142 (2018.3)
- #pragma HLS UNROLL factor=...**
  - [https://www.xilinx.com/support/documentation/sw\\_manuals/xilinx2018\\_3/ug902-vivado-high-level-synthesis.pdf](https://www.xilinx.com/support/documentation/sw_manuals/xilinx2018_3/ug902-vivado-high-level-synthesis.pdf)
- Use to control area-time points
  - Use of loop for spatial vs. temporal description

## Vivado HLS Pragma UNROLL

- Unroll loop into spatial hardware
  - Can control level of unrolling
- Any loops inside a pipelined loop gets unrolled by the PIPELINE directive



```

for (i=0;i<N;i++)
  yout=0;
#pragma HLS UNROLL
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  y[i]=yout;

```

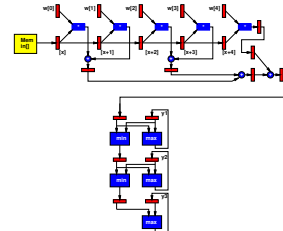
Which solution  
from preclass 3?

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## Dataflow, Unrolling, & Pipelining

- Cycles unroll K-loop, dataflow, pipeline?



```

for (i=0;i<N;i++) {
  yout=0;
  for (j=0;j<K;j++)
    yout+=in[i+j]*w[j];
  ystream.write(yout);
}

```

```

for (i=0;i<N;i++) {
  ystream.read(d);
  y1=max(d,y1);
  tmp=min(d,y1);
  y2=max(tmp,y2);
  tmp=min(tmp,y2);
  y3=max(tmp,y3);
}

```

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## Unroll

- Can perform partial unrolling
- **#pragma HLS UNROLL factor=...**
- Use to control area-time points
  - Use of loop for spatial vs. temporal description

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## Vivado HLS Pragma INLINE

- Collapse function body into caller
  - Eliminates interface code
  - Allows optimization of inline code
- Recursive option to inline a hierarchy
  - Maybe useful when explore granularity of accelerator

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## Zynq BRAM

- 36Kb of memory
  - Configurable width up to 72b
    - 512x72 or ... 32Kx1
  - Dual port
- Can be operated as 2x18Kb memory banks
  - Configurable width up to 36b
    - 512x36 or ... 16Kx1
  - Each memory dual port
- Xilinx UGu73, UltraScale Architecture Memory Resources User Guide

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## Vivado HLS Pragma ARRAY\_PARTITION

- Spread out array over multiple BRAMs
  - By default placed in single BRAM
    - At most 2 ports
  - Use to remove memory bottleneck that prevents pipelining (limits II)

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## Memory Bottleneck Example

```
#include "bottleneck.h"

dout_t bottleneck(din_t mem[N]) {

    dout_t sum=0;
    int i;

    SUM_LOOP: for(i=3;i<N;i=i+4)
    #pragma HLS PIPELINE
    sum += mem[i] + mem[i-1] + mem[i-2] + mem[i-3];

    return sum;
}
```

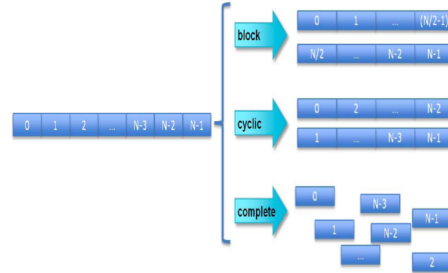
What problem if put mem  
in single BRAM?

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Xilinx UG1197 (2017.1) p. 50

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## Array Partition



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Xilinx UG902 p. 195 (145 in 2017.1 version) 56

## Array Partition Example

```
#pragma ARRAY_PARTITION variable=mem cyclic factor=4

#include "bottleneck.h"

dout_t bottleneck(din_t mem[N]) {

    dout_t sum=0;
    int i;

    SUM_LOOP: for(i=3;i<N;i=i+4)
    #pragma HLS PIPELINE
    sum += mem[i] + mem[i-1] + mem[i-2] + mem[i-3];

    return sum;
}
```

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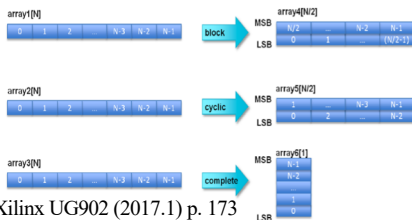
## Vivado HLS Pragma ARRAY\_RESHAPE

- Pack data into BRAM to improve access (reduce BRAMs)
  - May provide similar benefit to partitioning without using more BRAMs

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```
void foo (...) {
    int array1[N];
    int array2[N];
    int array3[N];
    #pragma HLS ARRAY_RESHAPE variable=array1 block factor=2 dim=1
    #pragma HLS ARRAY_RESHAPE variable=array2 cycle factor=2 dim=1
    #pragma HLS ARRAY_RESHAPE variable=array3 complete dim=1
    ...
}
```



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BRAM can be configured  
for 72b wide output

```
#include "bottleneck.h"

dout_t bottleneck(din_t mem[N]) {

    dout_t sum=0;
    int i;

    SUM_LOOP: for(i=3;i<N;i=i+4)
    #pragma HLS PIPELINE
    sum += mem[i] + mem[i-1] + mem[i-2] + mem[i-3];

    return sum;
}
```

How fix if dint\_t is 16b?

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## Array Reshape Example

```
#pragma ARRAY_RESHAPE variable=mem cyclic factor=4 dim=1
(if din_t 16b)
#include "bottleneck.h"

dout_t bottleneck(din_t mem[N]) {

    dout_t sum=0;
    int i;

    SUM_LOOP: for(i=3;i<N;i=i+4)
#pragma HLS PIPELINE
    sum += mem[i] + mem[i-1] + mem[i-2] + mem[i-3];

    return sum;
}
```

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## HLS Pragma Summary

- pragmas allow us to control hardware mapping
  - How interpret loops (spatial hw vs. temporal)
  - Turn area-time knobs
  - Specify how arrays get mapped to memories
- Could have rewritten code by hand
  - Unroll, separate arrays...
  - Pragmas automate; we just need to provide instruction

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## Midterm

- Analysis
  - Bottleneck
  - Amdahl's Law Speedup
  - Computational requirements
  - Resource Bounds
  - Critical Path
  - Latency/throughput/II
- Will be calculating/estimating runtimes
- From Code
- Forms of Parallelism
- Dataflow, SIMD, hardware pipeline, threads
- Pipelining/Retiming
- Map/schedule task graph to (multiple) target substrates
- Memory assignment and movement
- Area-time points

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## Midterm

- Closed book, notes, etc.
- Calculators allowed (encouraged)
- Last three midterms, final online
  - Both without answers (for practice)
  - ...and with answers (check yourself)
  - Check syllabus for previous terms

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## Memory Allocation

Simple answer: "Don't do it!"

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## Demand for malloc()

- Data-dependent object (array) size
- Data-dependent number of objects

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## Hardware Memory

- Typically small, fixed, local memory blocks
  - E.g. 36Kb BRAMs
- Reuse memory blocks
  - Not allocate new blocks
  - Cannot make data-dependent memory sized blocks
  - Cannot hold arbitrary-sized data

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## No malloc()

- Generally don't want to use malloc with
  - Hardware Accelerated functions
  - Real-time computations
- Vivado HLS won't let you use malloc()
  - For C running on FPGA array
- **Instead:** statically declare arrays of maximum size data may be

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## Pointer Passing

Be careful...

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## Pointer Passing

- What does it mean to pass a pointer into a function?

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## Pointer Passing Interpretations

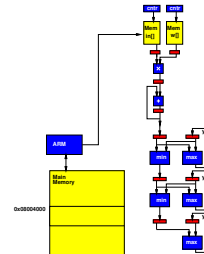
- Multiple uses we may want to express
  1. Specify which data to work on
    - Ok to copy that data to private accelerator memory and work with it
    - But, how much data to copy? (length)
  2. Want to mutate data and have other (parallel) tasks see it
    - OR want to see data mutated by other (parallel tasks)
    - Not OK to copy to private accelerator memory
    - Force use from large, shared memory
    - Forces sequentialization

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## Pointer Passing

- What if accelerator doesn't have access to the memory holding the data pointed to by the pointer?



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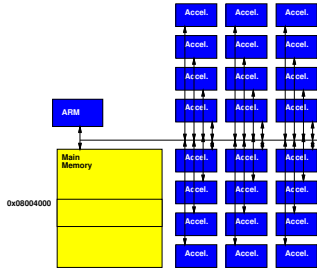
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### Pointer Passing

Maybe only reading data that will not change.

What happens if we give accelerators access to common memory holding data for pointer, but

- There's only one port into memory
- Memory is 10 cycles away
- And there are 100 accelerators that may need access
- Memory can only handle one memory op per cycle



### Avoid Pointer Passing

- Tend to copy data into / move data among hardware accelerator memories rather than passing pointers.

### Memory Sequentialization and Data Dependencies

(unlikely to cover in class;  
Review on own)

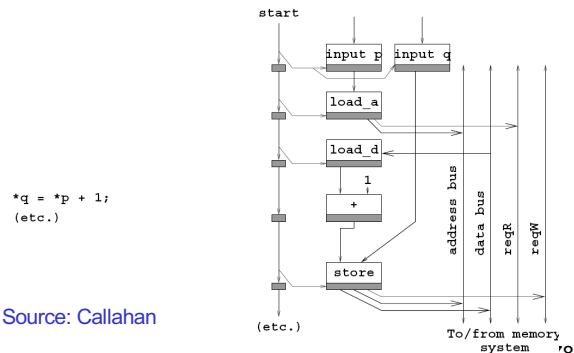
### C Memory Consequence

- **Expressions and operations** through variables (whose address is never taken) can be executed at any time
  - Just preserve the dataflow
- **Memory assignments** must execute in strict order
  - Ideally: partial order
  - Conservatively: strict sequential order of C

### Forcing Sequencing

- Demands we introduce some discipline for deciding when operations occur
  - Could be a FSM
  - Could be an explicit dataflow token
  - Callahan (reading) uses control register
- Other uses for timing control
  - Control
  - Variable delay blocks
  - Looping

### Scheduled Memory Operations



Source: Callahan

## Hardware/Parallelism Challenge

- Can we give enough information to the compiler to
  - allow it to reorder?
  - allow to put in separate embedded memories (separate banks)?
- Is the compiler smart enough to exploit?

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## Mux Conversion and Memory

- What might go wrong if we mux-converted the following:

```
if (cond)
    a[i]=0;
else
    b[i]=0;
```

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## Mux Conversion and Memory

- What might go wrong if we mux-converted the following:

```
if (cond)
    a[i]=0;
else
    b[i]=0;
```

- Don't want memory operations in non-taken branch to occur.

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## Mux Conversion and Memory

```
if (cond)
    a[i]=0;
else
    b[i]=0;
```

Don't want memory operations in non-taken branch to occur.

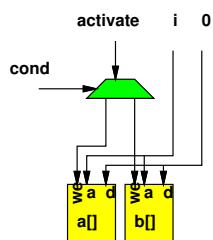
- **Conclusion:** cannot mux-convert blocks with memory operations (without additional care)

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## Conditions and Memory

```
if (cond)
    a[i]=0;
else
    b[i]=0;
```



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## Dependence in Loops

```
for(i=0;i<K;i++)
    Y[i]=a[i]*Y[i-1];
```

If a value needed by one instance of the loop is written by another instance, can create cyclic dependence.

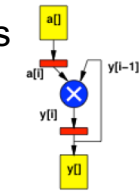
→ limit parallelism (pipeline II)

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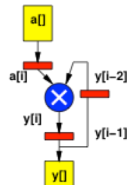
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## Dependence in Loops

```
for(i=0;i<K;i++)  
  Y[i]=a[i]*Y[i-1];
```



```
for(i=0;i<K;i++)  
  Y[i]=a[i]*Y[i-2];
```



Dependence distance same as  
# registers in cycle.

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## Dependence Fixed/Predictable?

```
for(i=0;i<K;i++)  
  Y[i]=a[i]*Y[i-1]+Y[i-2];
```

```
for(i=0;i<K;i++)  
  Y[i]=a[i]*Y[b[i]];
```

If dependence data-dependent, forced to  
sequentialize.

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## Dependence Fixed/Predictable?

```
for(i=0;i<K;i++)  
  Y[i]=a[i]*Y[i-1]+Y[i-2];
```

```
for(i=0;i<K;i++)  
  Y[i]=a[i]*Y[2*i+3];
```

If dependence linear, aggressive compilers  
may be able to resolve.

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## Dependence Fixed/Predictable?

```
for(i=0;i<K;i++)  
  Y[i]=  
  a[i]*Y[ceil(sqrt(i)*sin(2i))];
```

If dependence too complicated, compiler not  
solve and will force sequential execution.

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## Big Ideas

- Can specify HW computation in C
- Create streaming operations
  - Run on processor or FPGA
- Vivado HLS gives control over how map to hardware
  - Area-time point

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## Admin

- Reading for Monday
  - on web
  - and Zynq book
- HW5 due Friday
- HW6 not out yet
  - Hope to have out soon
- Midterm on Wednesday, class time
  - Review Tuesday office hours

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