

ESE532: System-on-a-Chip Architecture

Day 15: October 25, 2021

Development by
Incremental Refinement



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Today

- Incremental Refinement
 - Demand
 - Benefits
 - Simplifications (Part 2)
 - Example: render
 - Interfaces (Part 3)
 - Defensive Programming
- Source Code Repositories

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Message

- Focus on interfaces early
 - Integrate first
- Start with something simple that works end-to-end and incrementally refine
 - May lack features
 - May perform poorly
 - ...but it lets you resolve interfaces early

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Common Mistake

- Build pieces, then integrate at the end
- Spend most of available time on components
 - Then try to integrate for first time near deadline
 - Not enough time to integrate/debug at end
 - Worst-case don't have a working solution
 - Spend more time fixing than if had identified incompatibilities early

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Standard Chip Aphorism

- Almost all ASICs work when first fabricated
 - ...until you put them on the board.
 - Then maybe 50%
- [usually say “first spin” – where each “spin” is a separate manufacturing run]
- ASIC: Application Specific Integrated Circuit
 - (custom chip)

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Recommended Approach

- Decompose problem
- Focus on how components interact
- Figure out simplified functionality easy to assemble
- Get minimum functionality end-to-end system running early
 - Even if means cut corners, solve simplified piece of problem
- Chart path to refine pieces to goal

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Benefits

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Benefits: Overview

- Agree on interfaces up front
- Supports parallel development, testing, debugging
- Confidence-boosting win of having something that works
- Digest problem -- supports work in small bursts

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Interface First

- Agree on interfaces up front
- Each component knows interface
- Can replace each component independently
- Simple baseline provides scaffolding

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Parallel Development

- With interfaces defined...
- Each component can be (mostly) independently developed and refined
- Simple baseline provides scaffolding
 - Framework to test each component independently as develop and refine
- Particularly important for team
 - ...helpful for individual, too
 - Contains what need to think about at a time

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Confidence Boost

- Get to see it working
- Know you have something
 - Just a question of how sophisticated can you make it?

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Digested Problem

- Easier to concentrate on what need to do for this piece
- Can make tangible process in short bursts
 - ...time can find between lectures...

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Continuous Integration

- Pieces always fit into interface scaffold
- Add pieces, functionality as available
- See improvement
- Identify interface problems early
 - ...and refine them

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Part 2: Example

Rendering

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Rendering Example

- Create a 2D (video) image of a 3D object (set of objects)
- For: computer-generated graphics
 - Movies
 - Video games

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Rendering

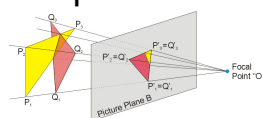
- Input:
 - collection of triangles (with color)
 - Each 3 (x,y,z) positions
 - Viewpoint
 - Another (x,y,z) point
- Output
 - 2D raster image (what you see on screen)
 - Showings what's visible
 - Some things will be hidden behind others

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Rendering Decomposed

- Pipeline of
 - Projection
 - Where do the points of this triangle end up in the viewed image?
 - Matrix-multiplication to translate points



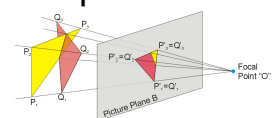
https://commons.wikimedia.org/wiki/File:Perspective_Projection_Principle.jpg

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Rendering Decomposed

- Pipeline of
 - Projection
 - Where do the points of this triangle end up in the viewed image?
 - Matrix-multiplication to translate points
 - Rasterization
 - Turn into pixels
 - Fill pixels for triangle

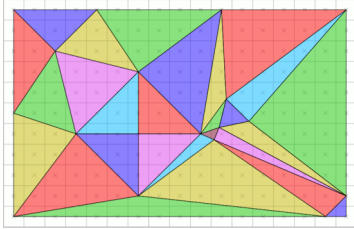


https://commons.wikimedia.org/wiki/File:Raster_graphic_fish_20x23squares_sdtv-example.png
https://commons.wikimedia.org/wiki/File:Renderer_Distortion_Andreas_horn_Holm-Bildwerkstatt.jpg

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Rasterization



By Drummyfish - Own work, CC0, <https://commons.wikimedia.org/w/index.php?curid=80204437>

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Rendering Decomposed

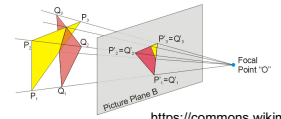
- Pipeline of

- Projection

- Where do the points of this triangle end up in the viewed image?
- Matrix-multiplication to translate points

- Rasterization

- Turn into pixels
- Fill pixels for triangle



https://commons.wikimedia.org/wiki/File:Perspective_Picture_Principle.jpg
https://commons.wikimedia.org/wiki/File:Raster_graphic_fish_20x23squares_sdv-example.png
https://commons.wikimedia.org/wiki/File:Rendering_Diskussion_Andreas_Horn_-_Hornes_Rastergraphik.jpg

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Rendering Decomposed

- Pipeline of

- Projection

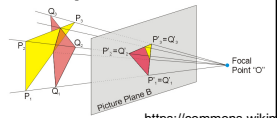
- Where do the points of this triangle end up in the viewed image?
- Matrix-multiplication to translate points

- Rasterization

- Turn into pixels
- Fill pixels for triangle

- Z-buffer

- Keep only the ones on top (not hidden)
- 2D image + Z-depth – keep smallest



https://commons.wikimedia.org/wiki/File:Perspective_Picture_Principle.jpg
https://commons.wikimedia.org/wiki/File:Raster_graphic_fish_20x23squares_sdv-example.png
https://commons.wikimedia.org/wiki/File:Rendering_Diskussion_Andreas_Horn_-_Hornes_Rastergraphik.jpg

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What's Hard (Preclass 1)

- What's hard about each part?

- Projection?
- Rasterization?
- Z-Buffering?

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Simplifications

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Simplification: Overview

- Solve simpler problem
- Handle special subset of cases
 - Avoid hard corner cases
- Don't worry about performance
- Placeholder – stand in for real task
 - Do minimal thing
 - Use existing code

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Simple Placeholder

- Identity function work?
 - Pass input to output
- Get form right in simple way?
 - E.g. compression
 - Drop samples/images/pixels to get down?

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Simplify (Preclass 3)

- How could we simplify
 - Projection?
 - Rasterization?
 - Z-Buffering?

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Simplified Projection Example

- Projection as identity function?
 - Will definitely give wrong image
 - Except when viewpoint 0,0,0....
 - And all triangles at same depth...
 - But the output of projection is triangles
 - ...so has right form for communication

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Simplified Rasterization

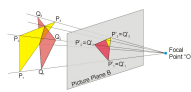
- Maybe: Just put output pixels for triangle corners?
 - Definitely wrong
 - Has right form

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Simplified Z-Buffer Example

- Intended
 - Z-buffer
 - Keep only the ones on top (not hidden)
 - 2D image + Z-depth – keep smallest
- Simplified
 - Just keep last value given
 - If nothing overlaps → correct
 - test with non-overlapping objects
 - Even if overlap
 - Looks wrong, but data has correct output form



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Solve Subset

- Are there cases that are easier and cases that are harder?
 - Can arrange input/tests to only include easier cases first
- Solve the simple cases first
 - E.g. non-overlapping objects in Z-buffer
- Add support for harder cases later

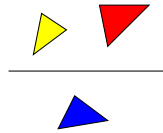


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Parallel Rendering Example

- Exploit data parallelism in rasterization
 - Cut image into pieces
 - Simplest: top half, bottom half
 - Separate threads to rasterize each piece

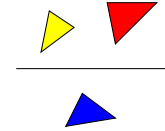


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Parallel Rendering

- Maybe ideal: rasterization sends triangle to appropriate rasterization thread
 - If in top half
 - send to top
 - Else
 - Send to bottom
- What could make hard?

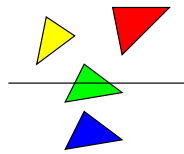


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Parallel Rasterization

- Simple
 - Triangles exclusively in one region
 - One half
 - Send to appropriate half
- Hard
 - Triangle in both halves
 - Send to all (both)
 - Or compute what goes in each and send triangles to each



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Parallel Rasterization Refinement

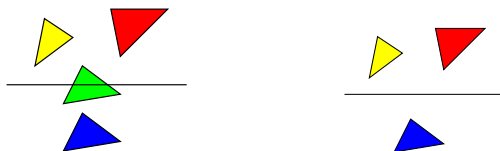
- Start simple
 - Assume only in one half, and only send there
 - Use test cases split by halves
- Incrementally get more sophisticated
 - Sometimes send to both
- Incrementally more
 - Compute triangles for each region

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What makes hard?

- Can avoid that on initial pass?
 - E.g. – avoid computing what part of triangle is in each region



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Solve Small Instances?

- If challenge is scale (handling large problems)
 - Solve small problems first
 - E.g. work on 64x64 image
 - If trying to hit real time, easier with small image
 - Small image may fit in BRAM (on-chip memory)
 - Avoid complexities of data movement initially

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Non-Optimized Implementation

- Often complexity comes from optimized implementation
 - Start with simplest, non-optimized version as placeholder
 - E.g.
 - Brute force solution instead of clever algorithm
 - Perhaps my most common mistake
 - Large, inefficient data structure
 - Instead of a more complicated, compact one

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Window Filter

Day 14

- Compute based on neighbors
- for (y=0;y<YMAX;y++)
 - for (x=0;x<XMAX;x++)
 - o[y][x]=F(d[y-1][x-1],d[y-1][x],d[y-1][x+1],
d[y][x-1],d[y][x],d[y][x+1],
d[y+1][x-1],d[y+1][x],d[y+1][x+1]);

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Window Filter

Day 14

- Single read and write from dym, dy
- for (y=0;y<YMAX;y++)
 - for (x=0;x<XMAX;x++) {
 - dypxm=dypx; dypx=dnew; dnew=d[y+1][x+1];
 - dyxm=dyx; dyx=dyxp; dyxp=dy[x+1];
 - dymxm=dymx; dymx=dymxp; dymxp=dym[x+1];
 - o[y][x]=F(dymxm,dymx,dymxp,
dyxm,dyx,dyxp,
dypxm,dypx,dnew);
 - dym[x-1]=dyxm;dy[x-1]=dypxm; }

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Software First

- Functional placeholder in software first

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Leverage Existing Solutions

- Run some existing package, library to get the right answer
 - E.g.
 - call MATLAB to solve a matrix
 - Invoke unix sort routine to get sorted data
 - Invoke stand-alone image compressor or renderer

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What components depend upon?

- Can a component output any data (random data?) and be adequate to exercise components interacts with?
 - E.g. if feed into an integrator/accumulator
- Need to output data of a given size?
- Output need to maintain some property?
 - Sorted?
 - Unique?
- Ok if doesn't do its intended job well?
 - E.g. intended to compress...

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Interfaces

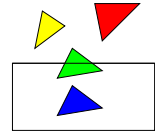
Part 3

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Division of Task

- Who is expected to do what?
 - E.g.,
 - Which piece discards duplicates?
 - Which piece removes/flags invalid input?
 - E.g. Renderer
 - Does Projection only send in-bound triangles to each region rasterizer?
 - Or does each region rasterizer need to deal with out-of-bounds triangle coordinates?



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Need to Know

- What information does each component need to know?
- How do we get that information to each component?

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Rendering Interface (Preclass 4)

- What need to communicate between
 - Projection → Rasterization
 - Rasterization → Z-Buffering

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3D Rendering: Need to Know

- Projection
 - How many triangles (int)
 - Triangle points (x,y,z) triples (float)+ color (short)
 - Viewpoint x,y,z (float)
- Rasterization
 - How many triangles (for region)
 - Triangle points (x,y,z) triples + color (short)
 - When done
- Z-buffer
 - (x,y,z,color) points – short
 - How many (when done)?

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How Communicate?

- Arrays
- Streams
- Shared memory locations?
- Variable lengths?

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3D Rendering

- All naturally streaming
- All potentially variable
 - Number of triangles depend on object complexity and number of objects
 - Projected triangles depend on number in each region
 - Not know in advance
 - Pixels sent depends on size of projected triangles which changes with viewpoint
 - Not know in advance

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3D Rendering

- Triangles and pixels unknown up front
- How might we communicate number of triangles/pixels – communicate when done?

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3D Rendering

- Triangles and pixels unknown up front
 - How communicate?
 - Send a record that means end-of-image?
 - Extra bit?
- ```

struct send_triangle {
 short p1x,p1y,p1z,
 p2x,p2y,p2z,
 p3x,p3y,p3z,
 color;
 Boolean last; }

```
- 161b

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## 3D Rendering

- Triangles and pixels unknown up front
  - How communicate?
    - Send a record that means end-of-image?
      - Extra bit?
    - Send in blocks with maximum size
      - Accompany each block with a length
      - Length is a separate stream from data
- ```

For(i=0;i<TRIANGLES;i+=5)
  -block_size.write(5);
  -For(j=0;j<5;j++) triangles.write(t[i+j]);
If (i!=TRIANGLES)
  -block_size.write(TRIANGLES-i);
for(j=0;j<TRIANGLES-I;j++)
  
```

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Properties components can assume?

- Sorted?
 - If Z-buffer could assume sorted
 - Just keep first at location (last if decreasing)
- Non-duplicate?
- All in-bound?
- Bound on input size in a block?

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Interfaces May Change

- Interface first
 - Means less surprise later
 - Doesn't mean know everything up front
- Experience making simple work ... and refining simple
 - Often best way to understand needs of problem
- Refine the interfaces incrementally, too

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3D Rendering Start

- Might start
 - Projection = identity (convert short)
 - Rasterization = triangle corners
 - Z-buffer = save last
 - Connect with streams
 - Streams data has one bit for last triangle, pixel
- Can put together quickly

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Rendering Start Placeholder

```
for(int i=0;i<TRIANGLES;i++)
    struct triangle2d t2d;
    t2d.plx=tr[i].plx;
    t2d.ply=tr[i].ply;
    t2d.plz=tr[i].plz;
    // same for p2, p3
    t2d.color=tr[i].color;
    t2d.last=(i==TRIANGLES-1);
    rasterize_in.write(t2d);
```

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Rendering Start Placeholder

```
while (true)
    rt2d=rasterize_in.read();
    pt.x=rt2d.plx; pt.y=rt2d.ply; // and z
    pt.last=false; pt.color=r2d.color;
    zin.write(pt);
    pt.x=rt2d.p2x; pt.y=rt2d.p2y; // z
    pt.last=false; pt.color=r2d.color;
    zin.write(pt);
    pt.x=rt2d.p3x; pt.y=rt2d.p3y; // z
    pt.last=tr2d.last; pt.color=r2d.color;
    zin.write(pt);
    if (tr2d.last) break;
```

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Rendering Start Placeholder

```
while (true)
    zpt=zin.read()
    image[zpt.y][zpt.x]=zpt.color;
    if (zpt.last) break;
```

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Rendering Start Refine

```
while (true)
    zpt=zin.read()
    if (z[zpt.y][zpt.x]>zpt.z) {
        image[zpt.y][zpt.x]=zpt.color;
        z[zpt.y][zpt.x]=zpt.z;    }
    if (zpt.last) break;
```

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Rendering Start Refine

```
// initialize z[] to MAXVAL
while (true)
    zpt=zin.read()
    if (z[zpt.y][zpt.x]>zpt.z) {
        image[zpt.y][zpt.x]=zpt.color;
        z[zpt.y][zpt.x]=zpt.z;    }
    if (zpt.last) break;
// large image -- may need to split?
// ... move off chip?
// represent in clever way
```

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3D Rendering Independent Refinement

- Projection – actually calculate projected coordinates
- Rasterization – calculate pixels per triangle
 - Test just fine using identity from projection
- Z-buffer – add in Z-ordering
 - Also testable with placeholder results

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3D Rendering Refinement

- Put them back together and work with interface defined
- Could decide to change to communicating with blocks
- Could refine for parallel rasterization
 - ...and could do that in pieces

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Defensive Programming

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Validate Assumptions/Requirements

- If require a property on input of a module
 - Good to have (optional) code to test for it
 - [add that code second]
 - Adds code/complexity to check
 - E.g. check actually is in-bounds if should be
 - Condition it in #ifdef so can disable for production, and re-enable for debug
 - Good to catch invalid assumptions early
 - ...rather than spend time debugging to discover
 - Setup discussion about interface...which part got it wrong

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Swap Modules

- Make it easy to swap out implementations
 - Swap between placeholders and refined implementations
 - Swap among implementation versions
 - Good to understand where problems introduced

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Source Code Repositories

git, svn

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Repository Message

- When working on a project, especially with other people, want to use a source code repository
- We've encouraged you to use for HWs
- Start one for project group as soon as you create a project team

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Basic Idea

- Central authoritative home for code
 - Everyone can access
 - Even if someone gets sick, laptop crashes
- Keeps track of all versions
 - As iterate and refine
- Maybe keep track of multiple, in-use versions at once → branches

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Basic Benefits

- Keep organized
 - Common place for everything
- Keep track of history
 - Can go back to previous versions
 - If screw up; if thought worked before
 - Lowers chance of accidentally deleting
 - ...or losing when laptop disk crashes
- Able to work on independently
 - Share/integrate as stable
- Branches
 - Experiment without breaking main version

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E.g. change an interface

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Big Ideas:

- Integrate first
 - Focus on interfaces early
- Start simple
 - Something that works end-to-end
- Improve incrementally and iteratively

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Admin

- Feedback
- Wednesday: Project out and introduction
- HW6 due Friday
- Talk Monday by Randy Huang, Amazon
 - 12:00pm, in Towne 319, ESE539
 - (flight canceled, won't be in person)
 - Zoom Meeting ID: 968 220 8162
 - Passcode: ese539amaz
 - Won't be recorded (promises to be candid)
- practical engineering in industry

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