

## ESE5320: System-on-a-Chip Architecture

Day 9: October 2, 2023  
High-Level Synthesis (HLS)  
C-to-gates  
More accurate: C-for-gates



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## Today

- Motivation
- Spatial Computations from C specification
  - Variables and expression (pre-lecture)
  - Simple Conditionals (Part 1)
  - Functions (part 2)
  - Globals
  - Loops and Arrays (Part 3)

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## Message

- C (or any programming language) specifies a computation
- C can describe spatial computation
  - A dataflow graph with physical operators for each operation
- Underlying semantics is sequential
  - Watch for unintended sequentialization
  - Write C for spatial differently than write C for processors

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## Coding Accelerators

- Want to exploit FPGA logic on Zynq to accelerate computations
- Traditionally has meant develop accelerators in
  - Hardware Description Language (HDL)
    - E.g. Verilog → see in CIS4710, CIS5710
  - Directly in schematics

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## Course “Hypothesis”

- C-to-gates synthesis mature enough to use to specify hardware
  - Leverage fact everyone knows C
    - (must, at least, know C to develop embedded code)
  - Avoid taking time to teach Verilog or VHDL
    - Or making Verilog a pre-req.
  - Focus on teaching how to craft hardware
    - Using the C already know
    - ...may require thinking about the C differently

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## Discussion [open]

- Is it obvious we can write C to describe hardware?
- What parts of C translate naturally to hardware?
- What parts of C might be problematic?
- What parts of hardware design might be hard to describe in C?

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## Three Perspectives

1. How express spatial/hardware computations in C
  - May want to avoid some constructs in C
2. How express computations
  - Hopefully, equally accessible to spatial and sequential implementations
3. Given C code: how could we implement in spatial hardware
  - Some corner cases and technicalities make tricky

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## Advantage

- Use C for hardware and software
  - Test out functionality entirely in software
    - Debug code before put on hardware
      - where harder to observe what's happening
      - ...without spending time in place and route
        - ...which you soon see is slow...
  - Explore hardware/software tradeoffs by targeting same code to either hardware or software

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## Context

- C most useful for describing behavior of operators
- C alone doesn't naturally capture task parallelism

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## Preclass F

- Ready for preclass f?
- Skip to preclass f

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## C Primitives Arithmetic Operators

- Unary Minus (Negation)       $-a$
- Addition (Sum)                 $a + b$
- Subtraction (Difference)     $a - b$
- Multiplication (Product)     $a * b$
- Division (Quotient)           $a / b$
- Modulus (Remainder)          $a \% b$

Things might have a hardware operator for...

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## C Primitives Bitwise Operators

- Bitwise Left Shift               $a << b$
- Bitwise Right Shift             $a >> b$
- Bitwise One's Complement     $\sim a$
- Bitwise AND                     $a \& b$
- Bitwise OR                     $a | b$
- Bitwise XOR                     $a ^ b$

Things might have a hardware operator for...

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## C Primitives Comparison Operators

- Less Than  $a < b$
- Less Than or Equal To  $a \leq b$
- Greater Than  $a > b$
- Greater Than or Equal To  $a \geq b$
- Not Equal To  $a \neq b$
- Equal To  $a == b$
- Logical Negation  $\neg a$
- Logical AND  $a \& b$
- Logical OR  $a \parallel b$

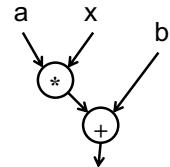
Things might have a hardware operator for...

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## Expressions: combine operators

- $a * x + b$



A connected set of operators  
→ Graph of operators

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## Expressions: combine operators

- $a * x + b$
- $a * x * b * x + c$
- $a * (x+b) * x + c$
- $((a+10)*b < 100)$

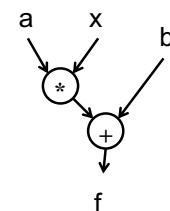
A connected set of operators  
→ Graph of operators

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## C Assignment

- Basic assignment statement is:  
Location = expression
- $f = a * x + b$



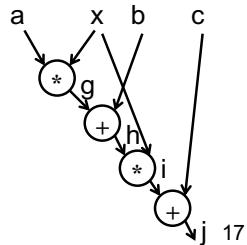
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## Straight-line code

- a sequence of assignments
- What does this mean?

$g = a * x;$   
 $h = b + g;$   
 $i = h * x;$   
 $j = i + c;$



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## Variable Reuse

- Variables (locations) define flow between computations
  - Locations (variables) are reusable
- ```

t = a * x;
r = t * x;
t = b * x;
r = r + t;
r = r + c;
  
```

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## Variable Reuse

- Variables (locations) define flow between computations
- Locations (variables) are reusable  
 $t=a^*x; \quad t=a^*x;$   
 $r=t^*x; \quad r=t^*x;$   
 $t=b^*x; \quad t=b^*x;$   
 $r=r+t; \quad r=r+t;$   
 $r=r+c; \quad r=r+c;$
- Sequential assignment semantics tell us which definition goes with which use.  
– Use gets most recent preceding definition.

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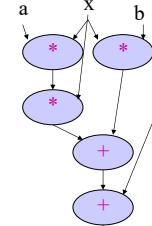
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## Dataflow

- Can turn sequential assignments into dataflow graph through def→use connections

```
t=a*x;  t=a*x;
r=t*x;  r=t*x;
t=b*x;  t=b*x;
r=r+t;  r=r+t;
r=r+c;  r=r+c;
```



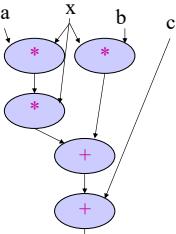
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## Dataflow Height

- $t=a^*x; \quad t=a^*x;$   
 $r=t^*x; \quad r=t^*x;$   
 $t=b^*x; \quad t=b^*x;$   
 $r=r+t; \quad r=r+t;$   
 $r=r+c; \quad r=r+c;$
- Height (delay) of DF graph may be less than # sequential instructions.



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## Lecture Checkpoint

- ```
int f(int a, int b)
{
    int t, c, d;
    a=a&(0x0f);
    b=b&(0x0f);
    t=b+3;
    c=a^t;
    t=a-2;
    d=b^t;
    return(d);
}
```
- Happy with ?
    - Straight-line code
    - Variables
  - Graph for preclass f

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## Straight Line Code

- C is fine for expressing straight-line code and variables
  - Has limited data types
    - Address with tricks like masking
    - Address with user-defined types

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## Optimizations can probably expect compiler to do

- Constant propagation:  $a=10; b=c[a];$
- Copy propagation:  $a=b; c=a+d; \rightarrow c=b+d;$
- Constant folding:  $c[10*10+4]; \rightarrow c[104];$
- Identity Simplification:  $c=1*a+0; \rightarrow c=a;$
- Strength Reduction:  $c=b^2; \rightarrow c=b<<1;$
- Dead code elimination
- Common Subexpression Elimination:
  - $- C[x*100+y]=A[x*100+y]+B[x*100+y]$
  - $- t=x*100+y; C[t]=A[t]+B[t];$
- Operator sizing: for ( $i=0; i<100; i++$ )  $b[i]=(a\&0xff+i);$

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## Conditionals

- What can we do for simple conditionals?

```
if (a>b)
  c=b*c;
else
  c=a*c;
```

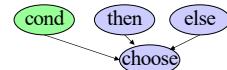
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## Simple Control Flow

- If (cond) { ... } else { ... }
- Assignments become conditional
- In simplest cases (no memory ops), can treat as dataflow node



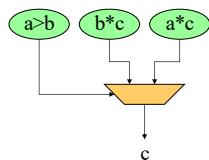
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## Simple Conditionals: Mux Conversion

```
if (a>b)
  c=b*c;
else
  c=a*c;
```



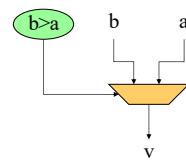
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## Simple Conditionals

```
v=a;
if (b>a)
  v=b;
```



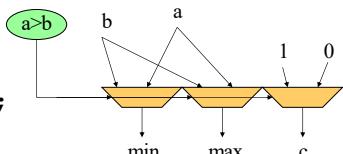
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## Simple Conditionals

```
max=a;
min=a;
if (a>b)
  {min=b;
   c=1;}
else
  {max=b;
   c=0;}
• May (re)define many values on each branch.
```



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## Preclass G

```
int g(int a, int b)
{
  int t, c, d;
  // same as above
  a=a&(0x0f);
  b=b&(0x0f);
  t=b+3;
  c=a*t;
  t=a-2;
  d=b^t;
  //added (not in f)
  if (a<b)
    d=c;
  // end added
  return(d);
}
```

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## Part 2

### Functions and Globals

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## Function Call

- What computation is this describing?

```
int f(int a, int b)
    return(sqrt(a*a+b*b));

for(i=0;i<MAX;i++)
    D[i]=f(A[i],B[i]);
```

- What role does the function call play?

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## Inline Transformation

- Inline a function
  - Copy the body of function
  - Into the point of call
  - Replacing the function arguments
  - With the arguments supplied in the call

```
int f(int a, int b)
    return(sqrt(a*a+b*b));  for(i=0;i<MAX;i++)
for(i=0;i<MAX;i++)      D[i]=sqrt(A[i]*A[i]
                                +B[i]*B[i]);
    D[i]=f(A[i],B[i]);
```

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## Inline

```
int p(int a)
    return(a*a+2*a-1);
    for(i=0;i<MAX;i++)
        D[i]=A[i]*A[i]+2*A[i]-1
for(i=0;i<MAX;i++)
    D[i]=p(A[i])-p(B[i]);
    for(i=0;i<MAX;i++)
        D[i]=(A[i]-B[i])
                                *(A[i]-B[i])
    D[i]=p(A[i]-B[i]);
                                +2*((A[i]-B[i])-1)
```

Functions provide descriptive convenience and compactness.  
...but don't need to force implementation.

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## Treat as data flow

- Implement function as an operation
  - Send arguments as input tokens
  - Get result back as token
- 
- The diagram illustrates a data flow model for function calls. It features three main components: 'Caller Prefix' (top left), 'Callee' (center), and 'Caller Post' (bottom). Data flows from 'Caller Prefix' to 'Callee', and from 'Callee' to 'Caller Post'. Additionally, there is a feedback loop from 'Caller Post' back to 'Caller Prefix'.
- Functions provide potential division between substrates? Assign different functions to different substrate (proc, fpga)

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## Shared Function

```
F1(A,B);
// Transpose(A,Aprime);
// matmul(Aprime,c1,B);
F2(B,C);
// matmul(B,c2,Cprime);
// normalize(Cprime,C);

if(A<B)
{
    matmul(A,c1,B);
}
else
{
    matmul(D,c3,E);
}
```

Functions express shared operators.

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## Recursion?

```
int fib(int x) {
    if ((x==0) ||
        (x==1))
        return(1);
    else
        return(
            fib(x-1) +
            fib(x-2));
}
```

- In general won't work.
  - Problem?
    - Try Inline?
    - How much hardware do we build?
- Smart compiler might be able to turn some cases into iterative loop.
- ...but don't count on it.
  - Vitis HLS will not

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## Global Variables

- Variables not declared in a function resolve to outer context

```
int a=0;
int f1(int *A) {
    for (int i=0;i<a;i++)
        sum+=A[i];
    return(sum); }

void f2(int *A) {
    while (A[a]!=0);
        a++;
    }

f2(input);
isum=f1(input);
```

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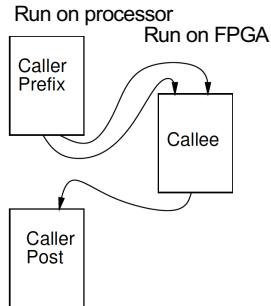
## Treat as data flow

Functions provide potential division between substrates.

- Impact on global variables?

```
int a=0;
int f1(int *A) {
    for (int i=0;i<a;i++)
        sum+=A[i];
    return(sum); }
void f2(int *A) {
    while (A[a]!=0);
        a++;
    }
f2(input);
isum=f1(input);
```

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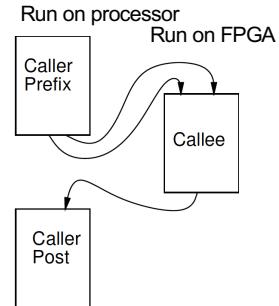
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## Treat as data flow

Functions provide potential division between substrates.

- Impact on global variables?
- Correct thing
  - Reflect change in variable between substrates
- Evidence Vitis HLS
  - Not synchronized with host C on globals



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## Global Variables

- Globals generally considered **bad coding practice**

- Obfuscate flow of

data even for human

- Avoid Globals

```
int a=0;
int f1(int *A) {
    for (int i=0;i<a;i++)
        sum+=A[i];
    return(sum); }

void f2(int *A) {
    while (A[a]!=0);
        a++;
    }

f2(input);
isum=f1(input);
```

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## Global Variables

### Bad

```
int a=0;
int f1(int *A) {
    for (int i=0;i<a;i++)
        sum+=A[i];
    return(sum); }

int f1(int *A, int len) {
    for (int i=0;i<len;i++)
        sum+=A[i];
    return(sum); }

int f2(int *A) {
    int len=0;
    while (A[len]!=0);
        len++;
    }
    return(len);

f2(input);
isum=f1(input);
len=f2(input);
isum=f1(input,len);
```

### Better

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## Part 3

### Loops and Arrays

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## Loops...

- From an *express computation* standpoint, have several roles
  - Compact code
  - Unbounded computation
- From *describe hardware*
  - Compact expression of parallel hardware
  - Express pipelines
  - Express data-level parallelism
  - Express area-time tradeoff

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## Loop Compact Expression

- What express?
  - Sequential, fully unrolled, partially unrolled?

```
sum=0;
for (i=0;i<32;i++) {
    sum+=(0-(b%2)) & a;
    b=b>>1;
    a=a<<1;
}
```

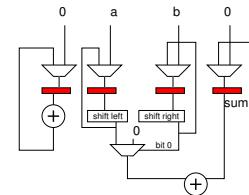
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## Sequential

```
sum=0;
for (i=0;i<32;i++) {
    sum+=(0-(b%2)) & a;
    b=b>>1;
    a=a<<1;
}
```



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## Spatial = fully unrolled

```
sum=0;
for (i=0;i<32;i++) {
    sum+=(0-(b%2)) & a;
    b=b>>1;
    a=a<<1;
}
```

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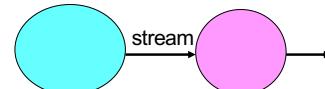
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## Stream

- Logical abstraction of a persistent point-to-point communication link between operators
  - Has a (single) source and sink
  - Carries data presence / flow control
  - Provides in-order (FIFO) delivery of data from source to sink

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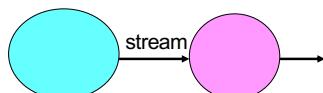


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## Stream

- For the moment assume way to read and write to streams:
  - stream.read() – return next value on stream
  - stream.write(val); put val onto stream

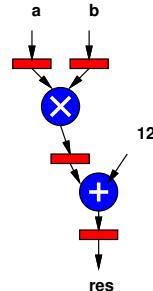


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## Unbounded, Pipelined Operator

What C code describe?



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## Unbounded, Pipelined Operator

What describe?

```

int c=12;
while(true)
{
    int aval=astream.read();
    int bval=bstream.read();
    int res=aval*bval+c;
    resstream.write(res);
}
  
```

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## With function call, loop in function

```

sum=0;
for (i=0;i<32;i++) {
    sum+=(0-(b%2)) & a;
    b=b>>1;
    a=a<<1;
}
int aval=astream.read();
int bval=bstream.read();
int res=multiply(aval,bval)+c;
resstream.write(res);
  
```

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## Compact Expression: Arrays

- Useful to be able to refer to different values (a large number of values) with the same code.
- Arrays + Loops: give us a way to do that
- Useful:
  - general expression
  - hardware description

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## Compact Expression: Arrays+Logic

- Vector sum:
  - $c_3 = a_3 + b_3; c_2 = a_2 + b_2; c_1 = a_1 + b_1; c_0 = a_0 + b_0;$
  - $\text{for}(i=0;i<3;i++) c[i] = a[i] + b[i];$
- Chose small length to fit non-array on slide
  - $\#define K 16$
  - $\text{for}(i=0;i<K;i++) c[i] = a[i] + b[i];$

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## Compact Expression: Arrays+Logic

- Dot Product:
  - $Y = a_3 * b_3 + a_2 * b_2 + a_1 * b_1 + a_0 * b_0;$
  - $Y = 0; \text{ for}(i=0; i<3; i++) Y += a[i] * b[i];$

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## Compact Expression: Arrays+Logic

- Vector sum:
  - $c_3 = a_3 + b_3; c_2 = a_2 + b_2; c_1 = a_1 + b_1; c_0 = a_0 + b_0;$
  - $\text{for}(i=0; i<3; i++) c[i] = a[i] + b[i];$
- These array elements may be nodes in dataflow graph, just like the variables we saw for function f
  - Express large dataflow graphs
  - Make area-time choices for implementation

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## Foreshadowing: C Array Challenge

- C programmers think of arrays as memory (or memory as arrays)
  - ...and sometimes we will want to
- Be careful understanding (and expressing) arrays that don't have to be memories
  - ...and treated with memory semantics

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## Loop Interpretations

- What does a loop describe?
  1. Sequential behavior [when to execute]
  2. Spatial construction [when create HW]
  3. Data Parallelism [sameness of compute]
- We will want to use for all 3
- Sometimes need to help the compiler understand which we want

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## Easy Loop (for contrast)

- ```
for (i=0; i<10; i++)
    sum+=a[i];
```
- How many times loop execute?
  - If unroll, which i for each loop instance?

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## Loop Bounds

- Loops without constant bounds

```
while (sum+a[i]<100) {
    sum+=a[i];
    i++;
}
```
- How many times loop execute?
- Typically forces sequentialization
  - Cannot unroll into hardware

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## Loop Increment

- Loops with variable increment also force sequentialization

```
for (i=0; i<100; i+=f[i])
    { b[i]=a[i]; sum+=a[i]; }
```
- What are values of i for which evaluate body?

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## Loop Interpretations

- What does a loop describe?
  - Sequential behavior [when execute]
  - Spatial construction [when create HW]
  - Data Parallelism [sameness of compute]
- We will want to use for all 3
- C allows expressive loops
  - Some expressiveness
    - Not compatible with spatial hardware construction

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## Unroll

- Vitis HLS has pragmas for unrolling
- UG1399: Vitis HLS User's Guide
- **#pragma HLS UNROLL factor=...**
- Use to control area-time points
  - Use of loop for spatial vs. temporal description
- In general – *pragmas* – directives to the compiler telling how to compile; does not change meaning of program

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## Big Ideas:

- C (any prog lang) specifies a computation
- Can describe spatial computation
  - Has some capabilities that don't make sense in hardware
    - Shared memory pool, globals, recursion
    - Watch for unintended sequentialization
- C for spatial is coded differently from C for processor
  - ...but can still run on processor
- Good for leaf functions (operations)
  - Limiting for full task

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## Admin

- Feedback, incl. HW4
- Reading for Wednesday online
- HW5 due Friday
  - Several long compiles; start early

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