CS137: Electronic Design Automation

Day 1: January 16, 2008 Introduction

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Apple Pie Intro (1)

- How do we design modern computational systems?
 - Billions of devices
 - used in everything
 - billion dollar businesses
 - rapidly advancing technology
 - more "effects" to address
 - rapidly developing applications and uses

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Apple Pie Intro (2)

- · Options:
 - A. human handles all the details
 - B. human solves problem, machine checks
 - C. human defines something about the solution and machine fills in the details
- · Remember:
 - billions of devices, changing world, TTM

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Apple Pie Intro (3)

- Human brain power is the bottleneck
 - to producing new designs
 - to creating new things
 - (applications of technology)
 - (to making money)

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Apple Pie Intro (4)

- How do we unburden the human?
 - Take details away from him
 - raise the level of abstraction at which he specifies computation
 - Pick up the slack
 - machine take over the details

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Central Questions

- How do we make the machine fill in the details (elaborate the design)?
- How well can it solve this problem?
- How fast can it solve this problem?

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Outline

- Apple Pie Intro (done)
- Instructor
- The Problem
- Decomposition
- Costs
- · Not Solved
- · This Class

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Instructor

- VLSI/CAD user + Novel Tech. consumer
 - Architect, Computer Designer
- · Avoid tedium
- Analyze Architectures
 - necessary to explore
 - costs different (esp. in new technologies)
- · Requirements of Computation

Problem

- Map from a problem specification down to an efficient implementation on a particular computational substrate.
- · What is
 - a specification
 - a substrate
 - have to do during mapping

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Problem: Specification

- · Recall: basic tenant of CS theory
 - we can specify computations precisely
 - Universal languages/building blocks exist
 - Turing machines
 - nand gates

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Specifications

- netlist
- logic gates
- FSM
- programming language
 - C, C++, Lisp, Java, block diagram
- DSI
 - MATLAB, Snort
- RTL
 - Register Transfer Level

 - (e.g. subsets of Verilog, VHDL)

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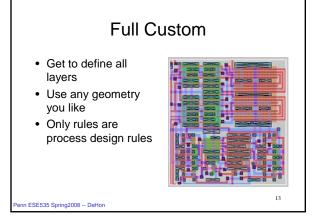
- behavioral dataflow graph
- layout
- SPICE netlist

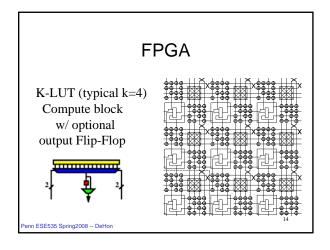
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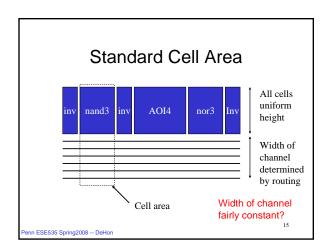
Substrate

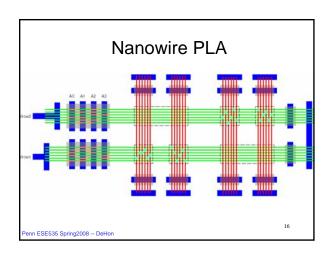
- · metal-only gate-array
- Processor (scalar, VLIW, Vector)
- Array of Processors (SoC, {multi,many}core)
- · billiard balls
- · molecules
- DNA

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What are we throwing away? (what does mapping have to recover?)

- layout
- TR level circuits
- logic gates / netlist
- FSM
- RTL
- behavioral
- programming language
 - C, C++, Lisp, Java
- DSL: MATLAB

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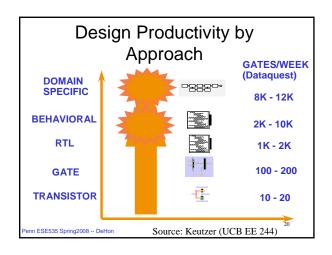
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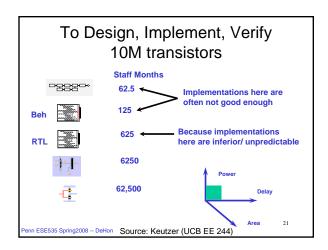
Specification not Optimal

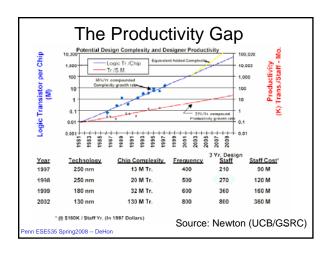
- Y = a*b*c + a*b*/c + /a*b*c
- Multiple representations with the same semantics (computational meaning)
- Only have to implement the semantics, not the "unimportant" detail
- Exploit to make smaller/faster/cooler

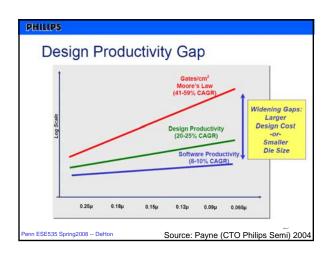
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Problem Revisited • Map from some "higher" level down to substrate • Fill in details: - device sizing, placement, wiring, circuits, gate or functional-unit mapping, timing, encoding, data movement, scheduling, resource sharing









Decomposition • Conventionally, decompose into phases: - provisioning, scheduling, assignment -> RTL - retiming, sequential opt. -> logic equations - logic opt., covering -> gates - placement-> placed gates - routing->mapped design • Good abstraction, manage complexity

Decomposition (easy?)

- All steps are (in general) NP-hard.
 - routing
 - placement
 - partitioning
 - covering
 - logic optimization
 - scheduling
- What do we do about NP-hard problems?
 - Return to this problem in a few slides...

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Decomposition

- + Easier to solve
 - only worry about one problem at a time
- + Less computational work
 - smaller problem size
- Abstraction hides important objectives
 - solving 2 problems optimally in sequence often not give optimal result of simultaneous solution

Costs

Once get (preserve) semantics, trying to minimize the cost of the implementation.

Mapping and Decomposition

- Two important things to get back to
 - disentangling problems
 - coping with NP-hardness

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- (none of the problems would be NP-hard) · What costs?

- Typically: EDA [:-)]
 - Energy
- Delay (worst-case, expected....)

- Otherwise this would be trivial

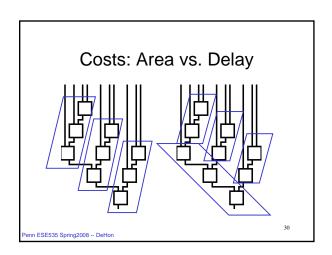
- Future
 - Yield
 - Reliability - Operational Lifetime

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Costs

- Different cost critera (e.g. E,D,A)
 - behave differently under transformations
 - lead to tradeoffs among them
 - [LUT cover example next slide]
 - even have different optimality/hardness
 - e.g. optimally solve delay covering in poly time, but not area mapping
 - (dig into on Day 2)

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Costs

- Cannot, generally, solve a problem independent of costs
 - costs define what is "optimal"
 - e.a
 - (A+B)+C vs. A+(B+C)
 - [cost=pob. Gate output is high]
 - A,B,C independent
 - P(A)=P(B)=0.5, P(C)=0.01
 - P(A)=0.1, P(B)=P(C)=0.5

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Costs may also simplify problem

- · Often one cost dominates
 - Allow/supports decomposition
 - Solve dominant problem/effect first (optimally)
 - Cost of other affects negligible
 - total solution can't be far from optimal
 - e.g.
 - · Delay (area) in gates, delay (area) in wires
 - Require: formulate problem around relative costs
- · Simplify problem at cost of generality

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Coping with NP-hard Problems

- simpler sub-problem based on dominant cost or special problem structure
- · problems exhibit structure
 - optimal solutions found in reasonable time in practice
- · approximation algorithms
 - Can get within some bound of optimum
- · heuristic solutions
- high density of good/reasonable solutions?
 - Try many ... filter for good ones

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Not a solved problem

- · NP-hard problems
 - almost always solved in suboptimal manner
 - or for particular special cases
- · decomposed in suboptimal ways
- quality of solution changes as dominant costs change
 - ...and relative costs are changing!
- new effects and mapping problems crop up with new architectures, substrates

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Big Challenge

- · Rich, challenging, exciting space
- · Great value
 - practical
 - theoretical
- · Worth vigorous study
 - fundamental/academic
 - pragmatic/commercial

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This Class

- · Toolkit of techniques at our disposal
- Common decomposition and subproblems
- · Big ideas that give us leverage
- Formulating problems and analyze success
- Cost formulation

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This Class: Toolkit

- Dynamic Programming
- Linear Programming (LP, ILP)
- Graph Algorithms
- Greedy Algorithms
- Randomization
- Search
- Heuristics
- · Approximation Algorithms
- SAT

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This Class: Decomposition

- Scheduling
- Logic Optimization
- · Covering/gate-mapping
- Partitioning
- Placement
- Routing
- Select composition

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Student Requirements

- Reading
- Class
- Homework
- Projects
 - Implement algorithm
 - One ~ 2 weeks
 - One ~ 4 weeks
- · Essentially something due every 2 weeks

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Graduate Class

- · Assume you are here to learn
 - Motivated
 - Mature
 - Not just doing minimal to get by and get a grade

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Materials

- Reading
 - Mostly online (some handouts)
 - If online, linked to reading page on web;
 I assume you will download/print/read.
- Lecture slides (after today)
 - I'll try to link to web page by 10am (maybe 9am?); you can print

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Misc.

- Web page
 - http://www.seas.upenn.edu/~ese535/
- [make sure get names/emails]
 - Discuss programming experience
 - Discuss optimization problems
 - ...goals from experience/research

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Questions?

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Today's Big Ideas

- Human time limiter
- Leverage: raise abstraction+fill in details
- Problems complex (human, machine)
- Decomposition necessary evil (?)
- Implement semantics
 - but may transform to reduce costs
- · Dominating effects
- Problem structure
- Optimal solution depend on cost (objective)

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