ESE535: Electronic Design Automation

Day 3: January 27, 2008
Clustering
(LUT Mapping, Delay)

Please work preclass example before we start lecture.

Mapping Results

- What delay were you able to achieve?
  - What area?
- How did you approach mapping?

Background Question

- Experience with FPGAs?
- What provides programmable logic in an FPGA?

Today

- How do we map to LUTs?
- What happens when delay dominates?
- Lessons…
  - for non-LUTs
  - for delay-oriented partitioning

LUT Mapping

- **Problem**: Map logic netlist to LUTs
  - minimizing area
  - minimizing delay
- Old problem?
  - Technology mapping? (Last Wednesday)
  - How big is the library?
    - 2^{2^K} gates in library

Simplifying Structure

- K-LUT can implement any K-input function

Cost Function

- **Delay:** number of LUTs in critical path
  - doesn't say delay in LUTs or in wires
  - does assume uniform interconnect delay
- **Area:** number of LUTs
  - Assumes adequate interconnect to use LUTs

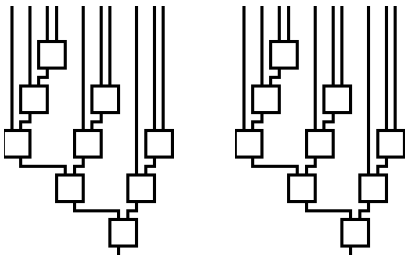
LUT Mapping

- NP-Hard in general
- Fanout-free -- can solve optimally *given* decomposition
  - (but which one?)
- Delay optimal mapping achievable in Polynomial time
- Area w/ fanout NP-complete

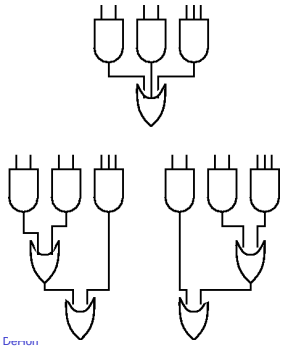
Preliminaries

- What matters/makes this interesting?
  - Area / Delay target
  - Decomposition
  - Fanout
    - replication
    - reconvergent

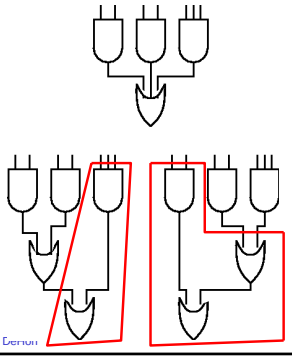
Area vs. Delay



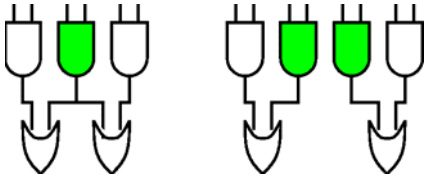
Decomposition



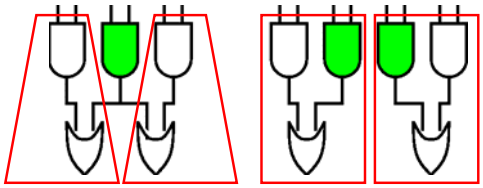
Decomposition



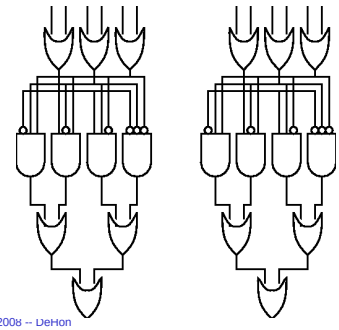
Fanout: Replication



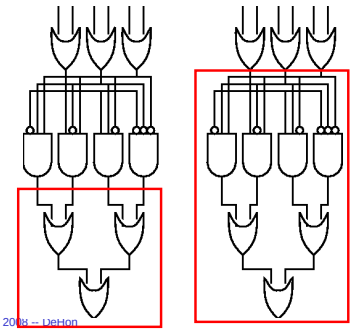
Fanout: Replication



Fanout: Reconvergence



Fanout: Reconvergence

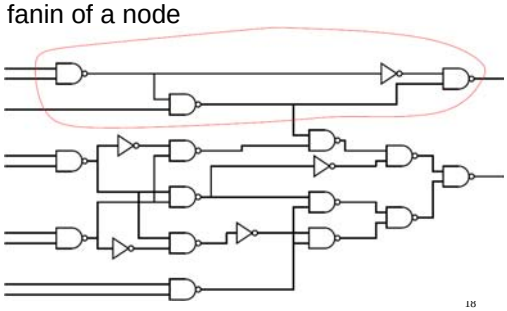


Monotone Property

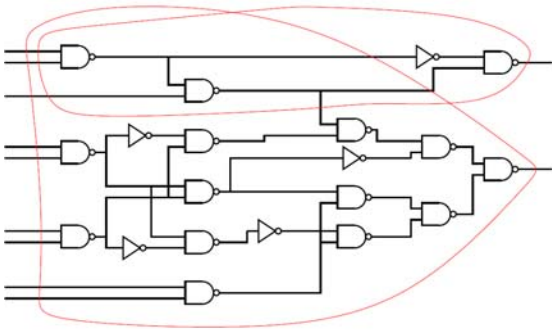
- Does cost function increase monotonicly as more of the graph is included? (do all subsets have property)
  - gate count?
  - I/o?
- Important?
  - How far back do we need to search?

Definition

- **Cone:** set of nodes in the recursive fanin of a node



Example Cones



Delay

Dynamic Programming

- Optimal covering of a logic cone is:
  - Minimum cost (all possible coverings)
- Evaluate costs of each node based on:
  - cover node
  - cones covering each fanin to node cover
- Evaluate node costs in topological order
- **Key**: are calculating optimal solutions to subproblems
  - only have to evaluate covering options at each node

Flowmap

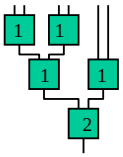
- **Key Idea**:
  - LUT holds anything with K inputs
  - Use network flow to find cuts
    - ≡ logic can pack into LUT including reconvergence
    - …allows replication
  - Optimal depth arise from optimal depth solution to subproblems

MaxFlow

- Set all edge flows to zero
  - F[u,v]=0
- While there is a path from s,t
  - (breadth-first-search)
  - for each edge in path f[u,v]=f[u,v]+1
  - f[v,u]=-f[u,v]
  - When c[v,u]=f[v,u] remove edge from search
- O(|E|*cutsize)
- [Our problem simpler than general case CLRS]

Flowmap

- Delay objective:
  - minimum height, K-feasible cut
  - *I.e.* cut no more than K edges
  - start by bounding fanin ≤ K
- Height of node will be:
  - height of predecessors *or*
  - one greater than height of predecessors
- Check shorter first

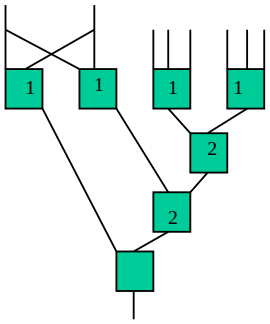


Flowmap

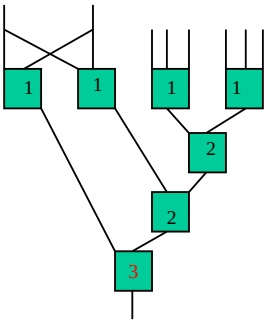
- Construct flow problem
  - sink ← target node being mapped
  - source ← start set (primary inputs)
  - flow infinite into start set
  - flow of one on each link
  - to see if height same as predecessors
    - collapse all predecessors of maximum height into sink (single node, cut must be above)
    - height +1 case is trivially true

Example Subgraph

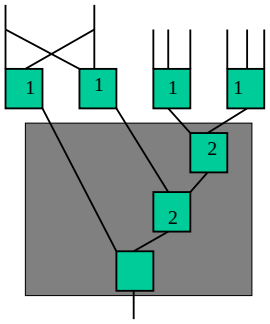
Target: K=4



Trivial: Height +1

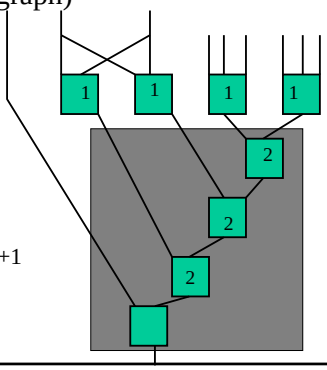


Collapse at max height



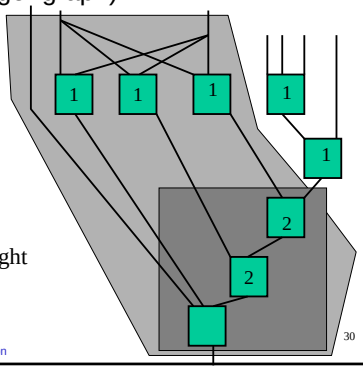
Collapse not work (different/larger graph)

Forced to label height+1



Reconvergent fanout (different/larger graph)

Can label at height

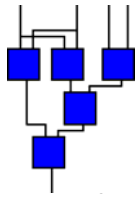


Flowmap

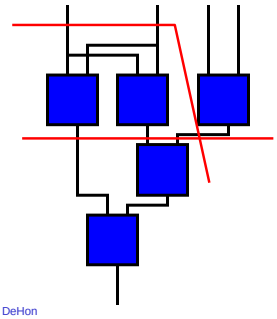
- Max-flow Min-cut algorithm to find cut
- Use augmenting paths to until discover max flow > K
- O(K|e|) time to discover K-feasible cut
  - (or that does not exist)
- Depth identification: O(KN|e|)

Flowmap

- Min-cut may not be unique

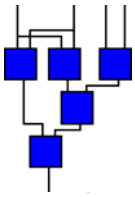


Two 3-cuts

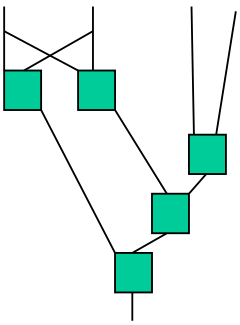


Flowmap

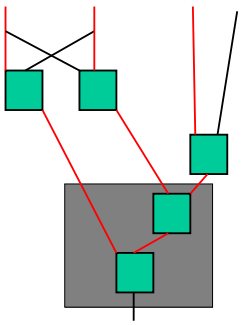
- Min-cut may not be unique
- To minimize area achieving delay optimum
  - find max volume min-cut
    - Compute max flow ⇒ find min cut
    - remove edges consumed by max flow
    - DFS from source
    - Compliment set is max volume set



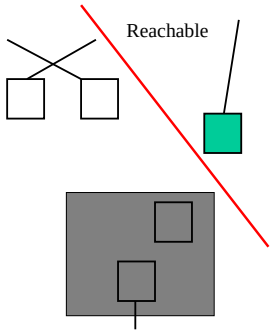
Graph



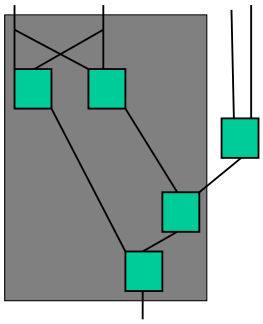
Graph: maxflow (K=3)



Graph: BFS source



Max Volume min-cut



Flowmap

- Covering from labeling is straightforward
  - process in reverse topological order
  - allocate identified K-feasible cut to LUT
  - remove node
  - postprocess to minimize LUT count
- Notes:
  - replication implicit (covered multiple places)
  - nodes purely internal to one or more covers may not get their own LUTs

Flowmap Roundup

- Label
  - Work from inputs to outputs
  - Find max label of predecessors
  - Collapse new node with all predecessors at this label
  - Can find flow cut $\leq$ K?
    - Yes: mark with label (find max-volume cut extent)
    - No: mark with label+1
- Cover
  - Work from outputs to inputs
  - Allocate LUT for identified cluster/cover
  - Recurse covering selection on inputs to identified LUT

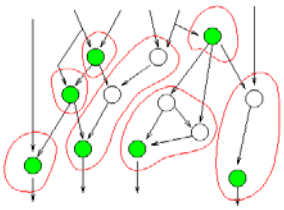
Area

DF-Map

- Duplication Free Mapping
  - can find optimal area under this constraint
  - (but optimal area may not be duplication free)

[Cong+Ding, IEEE TR VLSI Sys. V2n2p137]

Maximum Fanout Free Cones

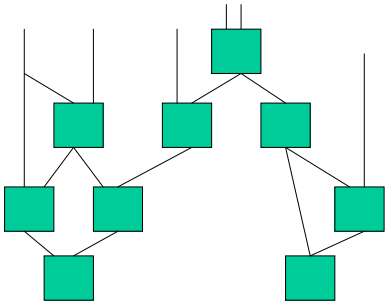


MFFC: bit more general than trees

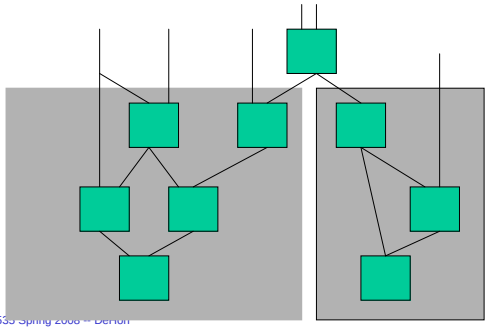
MFFC

- Follow cone backward
- end at node that fans out (has output) outside the code

MFFC example



MFFC example

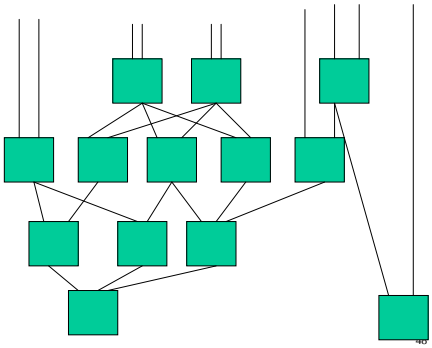


DF-Map

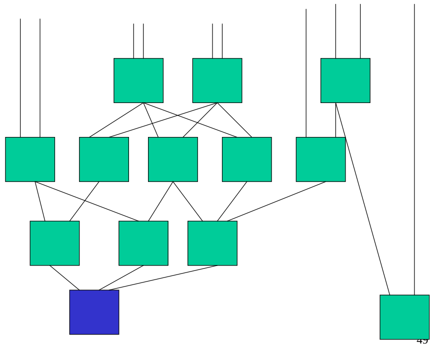
- Partition into graph into MFFCs
- Optimally map each MFFC
- In dynamic programming
  - for each node
    - examine **each** K-feasible cut
      - **note:** this is very different than flowmap where only had to examine a single cut
    - pick cut to minimize cost
      - 1 + Σ MFFCs for fanins

DF-Map Example

Cones?



DF-Map Example



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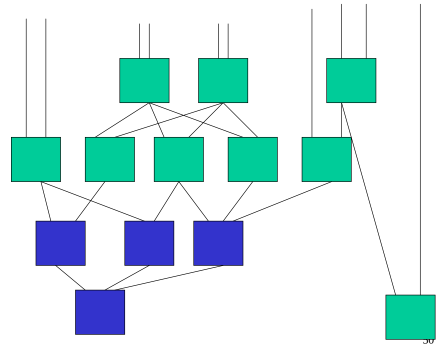

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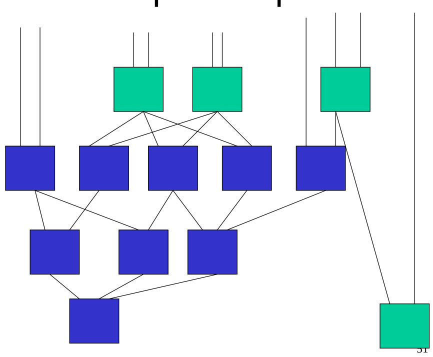

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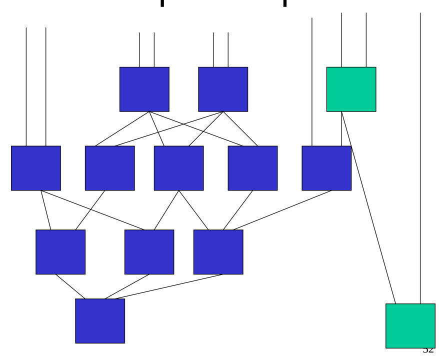

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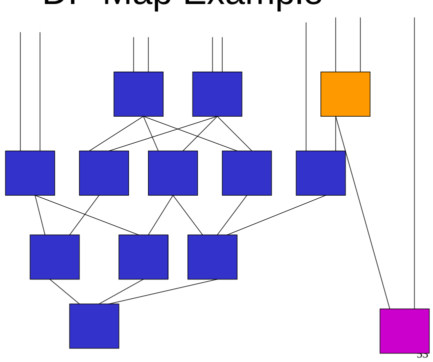
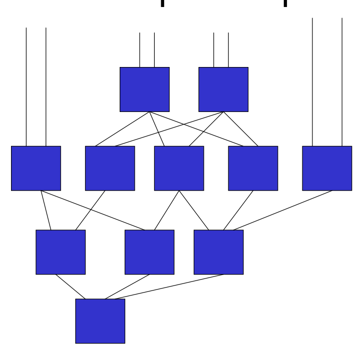


DF-Map Example

Start mapping cone



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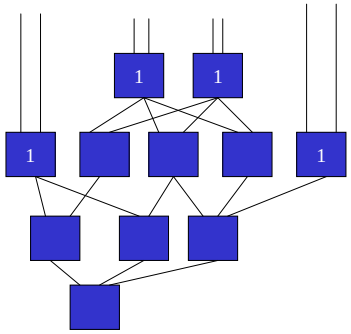

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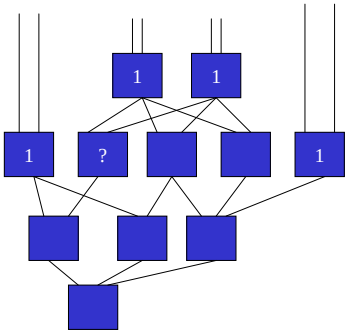

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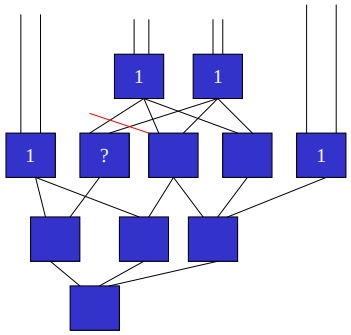

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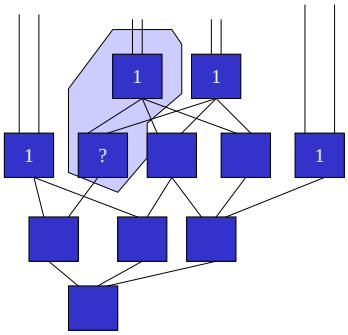

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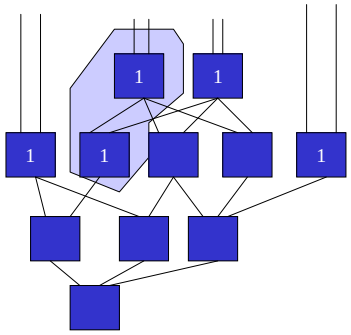
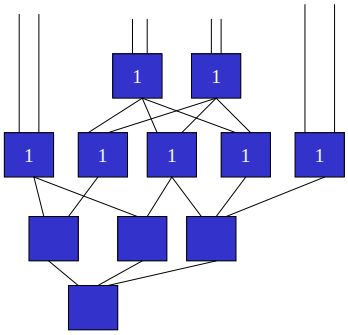


DF-Map Example

Similar to previous



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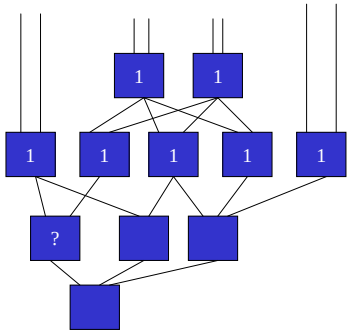

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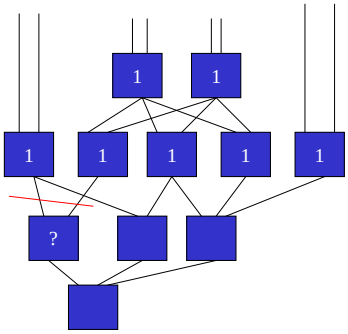

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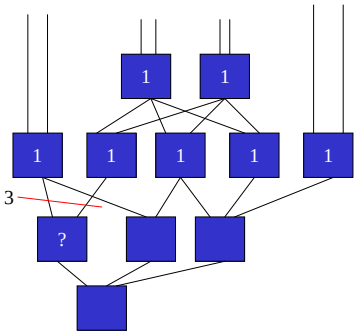

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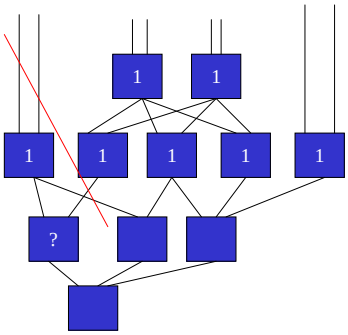

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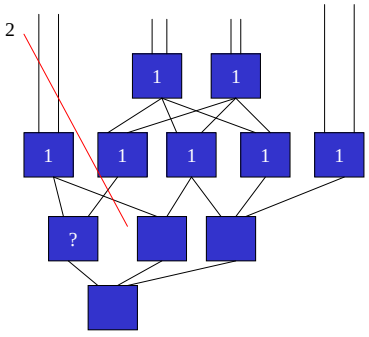

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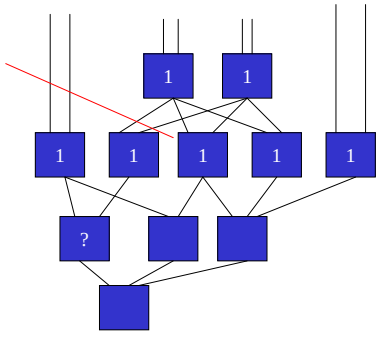

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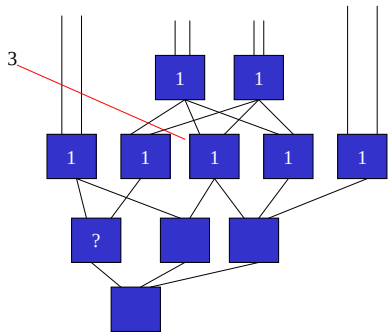

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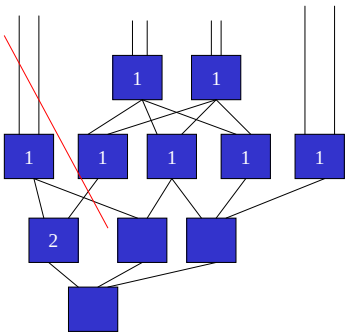

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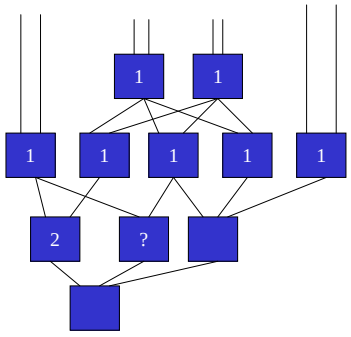

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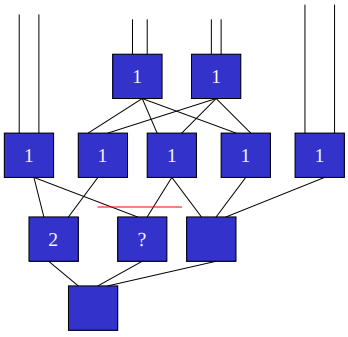

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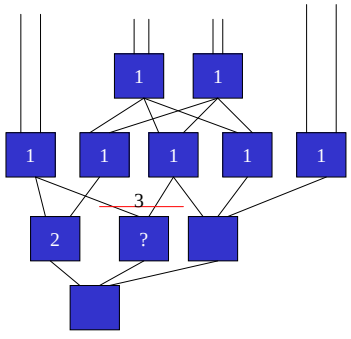
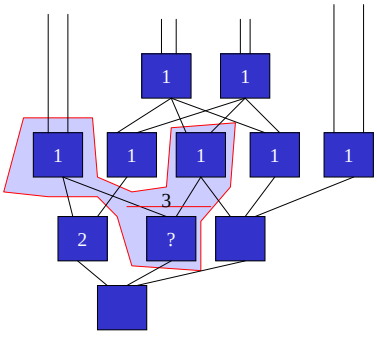


DF-Map Example



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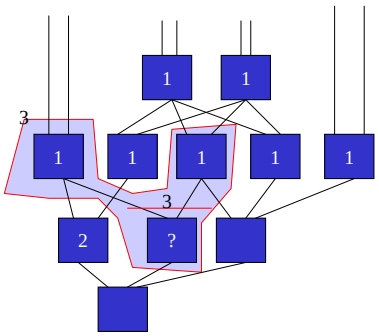

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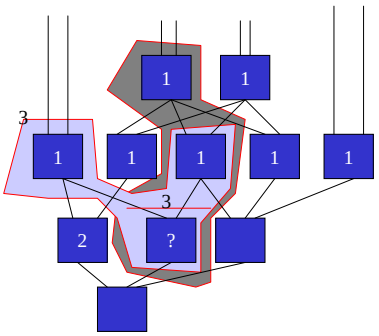

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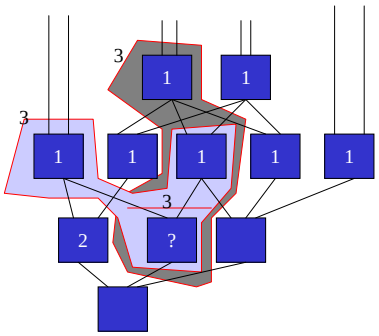

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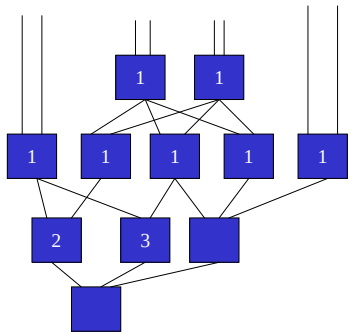

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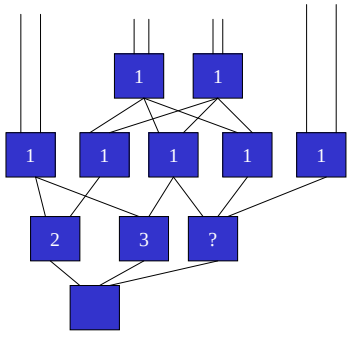

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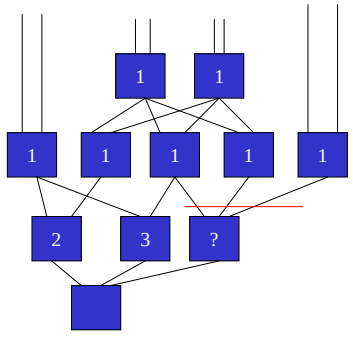

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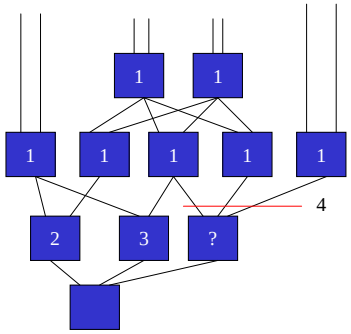

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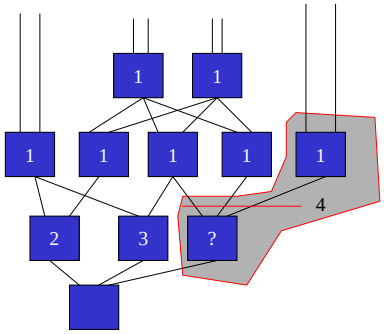

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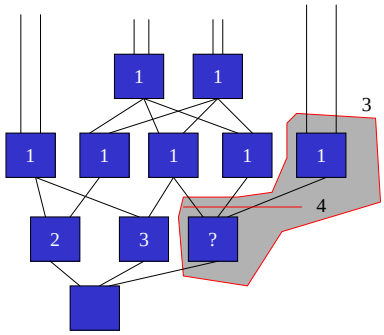

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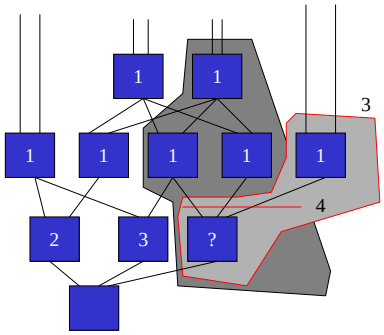

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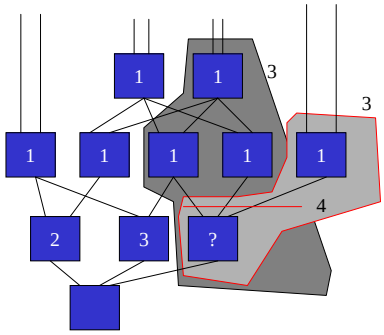

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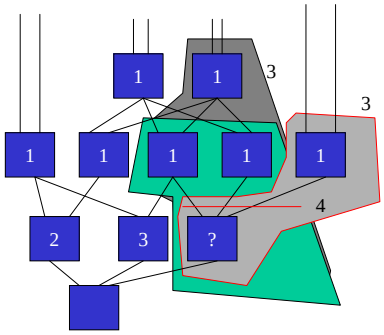

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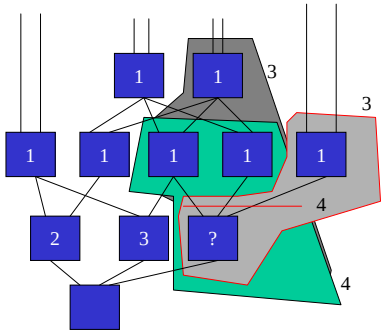

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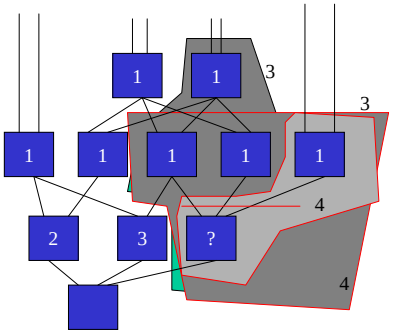

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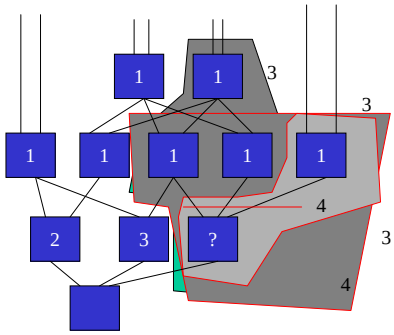

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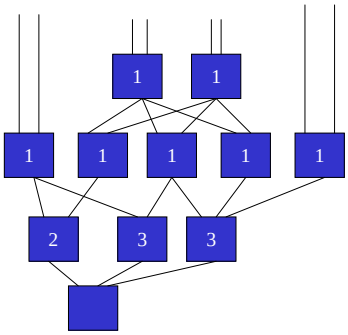

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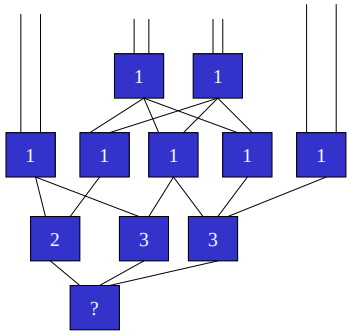

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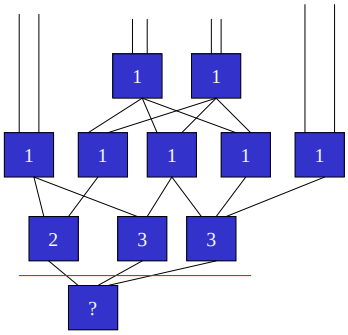

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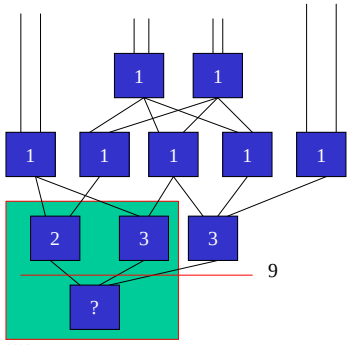

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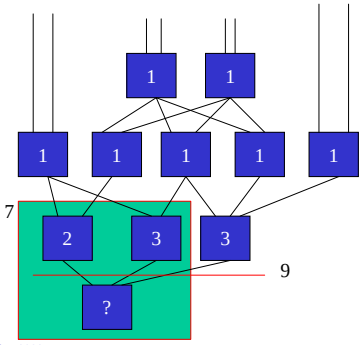

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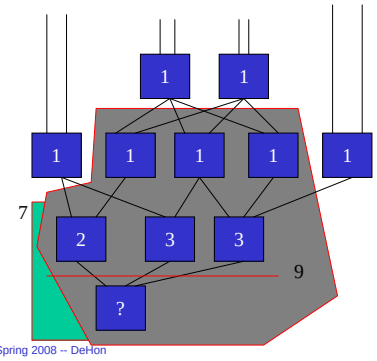

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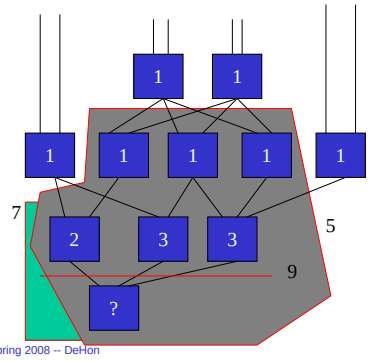

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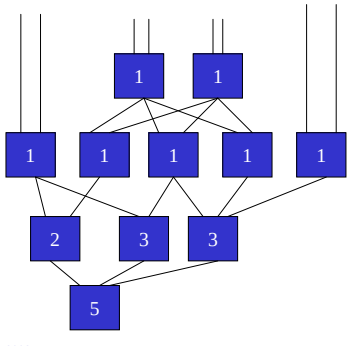

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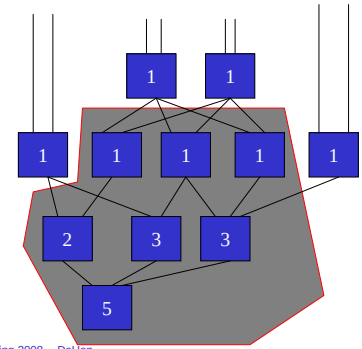


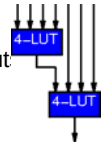
Composing

- Don't need minimum delay off the critical path
- Don't always want/need minimum delay
- Composite:
  - map with flowmap
  - Greedy decomposition of "most promising" non-critical nodes
  - DF-map these nodes

Variations on a Theme

Applicability to Non-LUTs?

- *E.g.* LUT Cascade
  - can handle some functions of K input
- How apply?



Adaptable to Non-LUTs

- Sketch:
  - Initial decomposition to nodes that will fit
  - Find max volume, min-height K-feasible cut
  - ask if logic block will cover
    - yes ⇒ done
    - no ⇒ exclude one (or more) nodes from block and repeat
      - exclude == collapse into start set nodes
      - this makes heuristic

Partitioning?

- Effectively partitioning logic into clusters
  - LUT cluster
    - unlimited internal "gate" capacity
    - limited I/O (K)
    - simple delay cost model
      - 1 cross between clusters
      - 0 inside cluster

Partitioning

- Clustering
  - if strongly I/O limited, same basic idea works for partitioning to components
    - typically: partitioning onto multiple FPGAs
    - assumption: inter-FPGA delay >> intra-FPGA delay
  - w/ area constraints
    - similar to non-LUT case
      - make min-cut
      - will it fit?
      - Exclude some LUTs and repeat

Clustering for Delay

- W/ no IO constraint
- area is monotone property
- DP-label forward with delays
  - grab up largest labels (greatest delays) until fill cluster size
- Work backward from outputs creating clusters as needed

Area and IO?

- Real problem:
  - FPGA/chip partitioning
- Doing both optimally is NP-hard
- Heuristic around IO cut first should do well
  - (*e.g.* non-LUT slide)
  - [Yang and Wong, FPGA'94]

Partitioning

- To date:
  - primarily used for 2-level hierarchy
    - I.e. intra-FPGA, inter-FPGA
- Open/promising
  - adapt to multi-level for delay-optimized partitioning/placement on fixed-wire schedule
    - localize critical paths to smallest subtree possible?

Summary

- Optimal LUT mapping NP-hard in general
  - fanout, replication, ….
- K-LUTs makes delay optimal feasible
  - **single constraint:** IO capacity
  - **technique:** max-flow/min-cut
- Heuristic adaptations of basic idea to capacity constrained problem
  - promising area for interconnect delay optimization

Today's Big Ideas:

- IO may be a dominant cost
  - limiting capacity, delay
- Exploit structure: K-LUTs
- Mixing dominant modes
  - multiple objectives
- Define optimally solvable subproblem
  - duplication free mapping