# ESE535: Electronic Design Automation

Day 10: February 18, 2015 Architecture Synthesis (Provisioning, Allocation)

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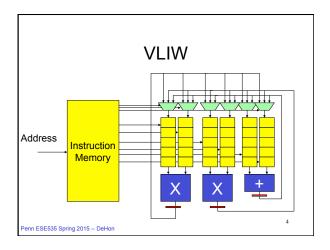
### Behavioral (C, MATLAB, ...) Today Arch. Select RTL FSM assign • Problem Two-level, Multilevel opt. • Brute-Force/Exhaustive Covering Greedy Retiming Gate Netlist Estimators Placement Routing · Analytical Provisioning Layout · ILP Schedule and Provision Masks

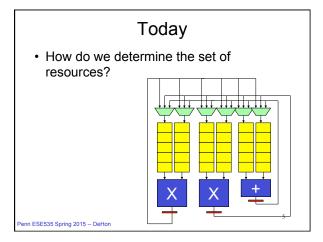
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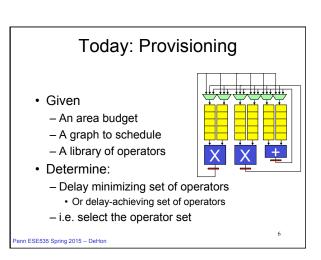
# Previously

- General formulation for scheduled operator sharing
  - VLIW
- Fast algorithms for scheduling onto fixed resource set
  - List Scheduling
- More extensive algorithms for timeconstrained
  - Force Directed, Branch-and-Bound

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### Exhaustive

- 1. Identify all area-feasible operator sets
  - E.g. preclass exercise
- 2. Schedule for each
- 3. Select best
- → optimal
- Drawbacks?

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### Exhaustive

- How large is space of feasible operator sets?
  - As function of
    - operator types O
      - Types: add, multiply, divide, ....
    - Maximum number of operators of type m

 $m^{O}$ 

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# Implication

 Feasible operator space can be too large to explore exhaustively

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### **Greedy Incremental**

- · Start with one of each operator
- · While (there is area to hold an operator)
  - Which single operator
    - Can be added without exceeding area limit?
    - Schedule (maybe list-schedule?)
    - Calculate benefit (maybe  $\Delta T/\Delta A$ ?)
    - Pick largest benefit
  - Add one operator of that type
- How long does this run?
  - T<sub>schedule</sub>(E)\* O(operator-types \* A)

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# **Greedy Incremental**

- Work Preclass with greedy incremental
  - For each step

• half class evaluate each candidate resource

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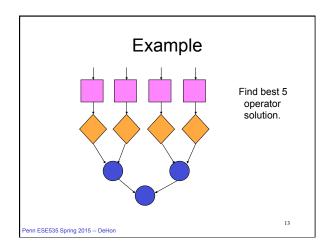
# Greedy Incremental

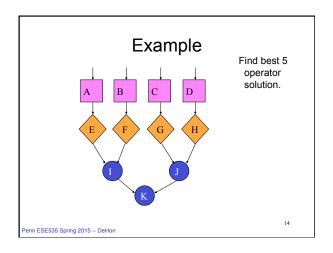
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    - Schedule (maybe list-schedule?)
    - Calculate benefit (maybe  $\Delta T/\Delta A$ ?)
    - Pick largest benefit
  - Add one operator of that type
- · Weakness?

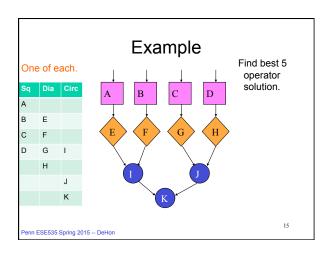
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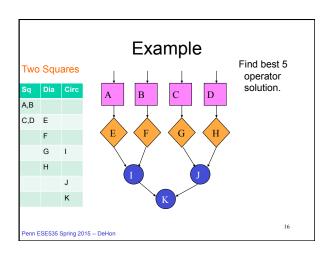
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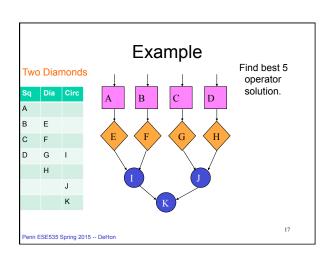
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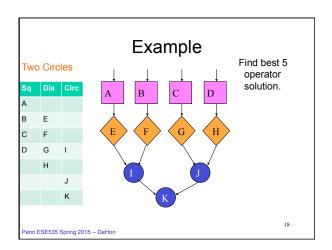


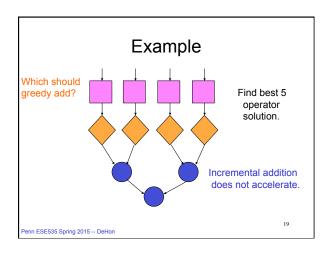


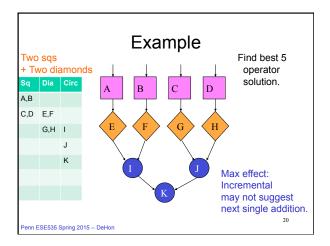












### **Analytic Formulation**

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## Challenge

- · Scheduling expensive
  - -O(|E|) or O(|E|\*log(|V|)) using list-schedule
- · Results not analytic
  - Cannot write an equation around them
- · Bounds are sometimes useful
  - No precedence → is resource bound
  - Often one bound dominates
- Latency bound unaffected by operator count

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### **Estimations**

- Step 1: estimate with resource bound - O(|E|) vs. O(|V|) evaluation
- · Step 2: use estimate in equations  $- T=max(N_1/M_1, N_2/M_2,...)$
- · Most useful when RB>>CP

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### Constraints

- · Let A<sub>i</sub> be area of operator type i
- Let M<sub>i</sub> by number of operators of type i

$$\sum A_i \times M_i \leq Area$$

(start summary of variables on board)

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### **Achieve Time Target**

- · Want to achieve a schedule in T cycles
- What constraint equation does that imply? (what property must hold?)
- Each resource bound must be less than T cycles:
  - $N_i/M_i \le T$

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### Algebraic Solve

- · Set of equations
  - $-N_i/M_i \leq T$
  - Σ A<sub>i</sub> M<sub>i</sub> ≤ Area
- · Assume equality for time bound
- $N_i/M_i=T \rightarrow M_i=N_i/T$

$$\frac{\sum A_i \times N_i}{T} \le Area_{26}$$

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### Rearranging

$$\frac{\sum A_i \times N_i}{T} \leq Area$$

$$\frac{\sum A_i \times N_i}{Area} \le T$$

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### Bounding T

· Gives Lower Bound on T

$$\frac{\sum A_i \times N_i}{Area} \le T$$

Intuition: N of each is right balance given unbounded area; Scale to area available.

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### **Preclass**

What is T<sub>lower</sub> for preclass?

$$\frac{\sum A_i \times N_i}{A_{rea}} \le T$$

$$T \ge \frac{1 \times 8 + 2 \times 4}{7} = \frac{16}{7} \approx 2.3$$
  $T \ge 3$ 

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Back Substitute from T to x

• 
$$M_i = N_i / T$$

$$\frac{\sum A_i \times N_i}{4\pi a \pi} \le T$$

Area

- M<sub>i</sub> won't necessarily be integer
  - Round down definitely feasible solution
  - May have room to move a few up by 1
- · Reduces range may need to search
  - (just over the residual area once rounded down)

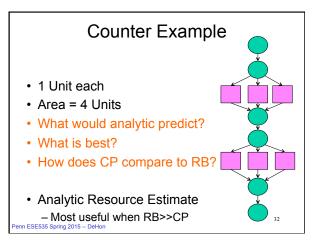
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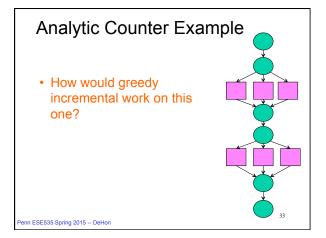


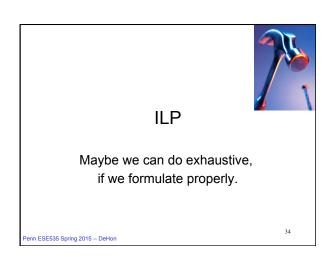
- M<sub>i</sub>=N<sub>i</sub>/T
- T>=3
- M<sub>add</sub>, M<sub>mpv</sub> ?
- $M_{add} = 8/3 \rightarrow 2 \text{ or } 3$
- $M_{mpy} = 4/3 \rightarrow 1 \text{ or } 2$

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### **ILP**

- · Integer Linear Programming
- Formulate set of linear equation constraints (inequalities)
  - $Ax_0 + Bx_1 + Cx_2 \le D$
  - $x_0 + x_1 = 1$
  - A,B,C,D constants
  - x<sub>i</sub> variables to satisfy
  - No products on variables, just linear weighted sums
- · Can constrain variables to integers
- No polynomial time guarantee
  - But often practical
  - Solvers exist (significant piece on April 1 (seriously))

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# ILP Provision and Schedule Now to make it look like an ILP nail... • Formulate operator selection and scheduling as ILP problem

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### **Formulation**

- Integer variables M<sub>i</sub>
  - number of operators of type i
- 0-1 (binary) variables x<sub>i,i</sub>
  - 1 if node i is scheduled into timestep j
  - 0 otherwise
- Variable assignment completely specifies operator selection and schedule
- This formulation for achieving a target time T (time constrained)
  - j ranges 0 to T-1

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# Target T → Min T

- · Formulation targets T
- What if we don't know T?
  - Want to minimize T?
- · Do binary search for minimum T
  - How does that impact solution time?

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### Constraints

# What properties must hold true for a solution to be valid?

- 1. Total area constraints
- 2. Not assign too many things to a timestep
- 3. Assign every node to some timestep
- 4. Maintain precedence

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### (1) Total Area

· Same as before

$$\sum A_i \times M_i \leq Area$$

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# (2) Not overload timestep

- For each timestep j
  - For each operator type k

$$\sum_{o_i \in FU_k} x_{i,j} \le M_k$$

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# (3) Node is scheduled

• For each node in graph

$$\sum_{i} x_{i,j} = 1$$

Can narrow to sum over slack window.

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### (4) Precedence Holds

• For each edge from node src to node snk

$$\sum_{j} j \times x_{src,j} - \sum_{j} j \times x_{snk,j} \le -1$$

Can narrow to sum over slack windows.

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### Example (Time Permitting)

- · What are the ILP equations for the preclass example?
  - 1. Total area constraints
  - 2. Not assign too many things to a timestep
  - 3. Assign every node to some timestep
  - 4. Maintain precedence

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### Constraints

- 1. Total area constraints
- 2. Not assign too many things to a timestep
- 3. Assign every node to some timestep
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### **ILP Solver**

- · ILP Solver can take these constraints and find a solution (satisfying assignment)
- · On Wednesday, will see how to start to make this practical

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### Round up Algorithms and Runtimes

- · Exhaustive Schedule
- · Greedy Schedule
- · Analytic Estimates
- ILP formulation

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Estimators

· Dominating Effects

· Reformulate as a problem we already have a solution for

Big Ideas:

- ILP

· Technique: Greedy · Technique: ILP

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# Admin

- Assignment 5 Thursday
- No class on Monday
  - Will have class on Wednesday
- No assignment 6 supplement
  - Focus on project and writeup
- Reading for Wednesday online

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