

# ESE535: Electronic Design Automation

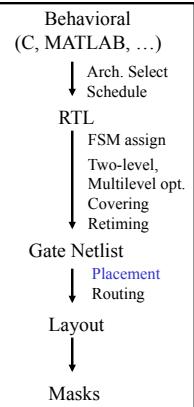
Day 11: February 25, 2015  
Placement  
(Intro, Constructive)



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## Today

- 2D Placement Problem
- Partitioning → Placement
- Quadrisection
- Refinement



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## Placement

- **Problem:** Pick locations for all building blocks
  - minimizing energy, delay, area
  - really:
    - minimize wire length
    - minimize channel density

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## Bad Placement

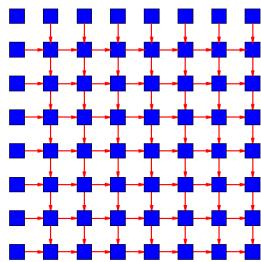
- How bad can it be?
  - Area
  - Delay
  - Energy

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## Preclass Channel Widths

- **Channel Width for Problem 1?**

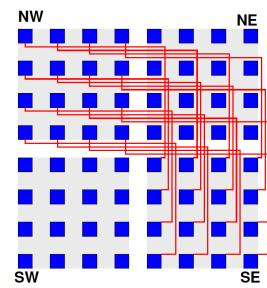


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## Preclass Channel Widths

- **Channel Width for Problem 2?**

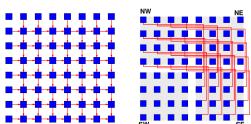


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## Bad: Area

- All wires cross bisection
- $O(N^2)$  area
- good:  $O(N)$

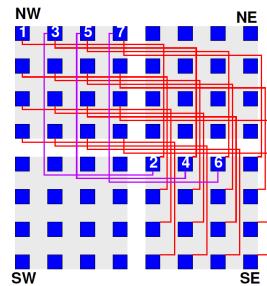


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## Delay

- How bad can delay be?

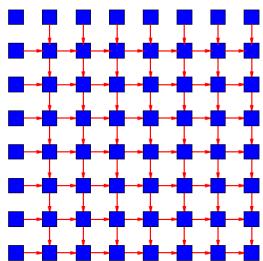


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## Delay

- How good can delay be?

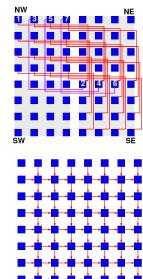


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## Bad: Delay

- All critical path wires cross chip
- Delay =  $O(|PATH| * 2 * L_{side})$   
– [and  $L_{side}$  is  $O(N)$ ]
- good:  $O(|PATH| * L_g)$
- compare 10ps gates to many nanoseconds to cross chip

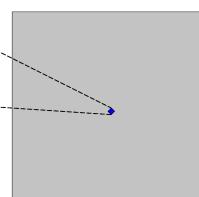


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## Clock Cycle Radius

- Radius of logic can reach in one cycle (45 nm)
  - 1 Cycle Radius = 10
    - Few hundred PEs
  - Chip side 1,000 PE
    - million PEs
  - 100s of cycles to cross



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## Bad: Energy

- All wires cross chip:  
 $O(L_{side})$  long  $\rightarrow O(L_{side})$  capacitance per wire
  - Recall Area  $\rightarrow O(N^2)$
  - So  $L_{side} \rightarrow O(N)$
  - $\times O(N)$  wires  $\rightarrow O(N^2)$  capacitance
- Good:  
 $O(1)$  long wires  $\rightarrow O(N)$  capacitance

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Manhattan

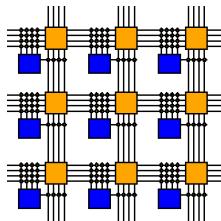
## Manhattan Distance

- Horizontal and Vertical Routing:  
Manhattan distance

$$|X_i - X_j| + |Y_i - Y_j|$$

- Contrast:  
Euclidean distance

$$\sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$$

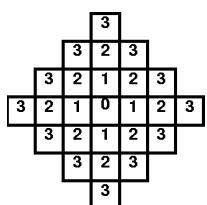


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## Distance

- Can we place everything close?



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## Illustration

- Consider a complete tree
  - nand2's, no fanout
  - N nodes
- Logical circuit depth?
- Circuit Area?
- Side Length?
- Average wire length between nand gates? (lower bound)

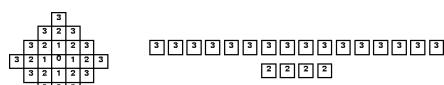
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## “Closeness”

- Try placing “everything” close

Manhattan Distance	Places	Transitive Fanin
1	4	4
2	8	16
3	12	64
i	i	i
n	$4n$	$4^n$

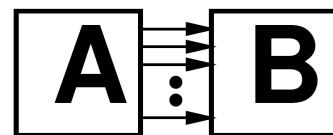


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## Preclass 5

- 2400 unit side, 4 unit x unit gates
- Wire length lower bound?

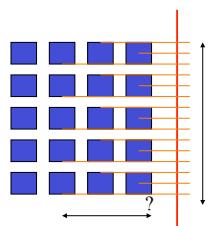


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## Generalizing Preclass 5

- What's minimum length for longest wires?



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## Generalizing Interconnect Lengths

- $P > 0.5$
- Side is  $\sqrt{N}$
- IO crossing it is  $N^P$
- What's minimum length for longest wires?
- Implication:
  - Wire lengths grow at least as fast as  $N^{(p-0.5)}$

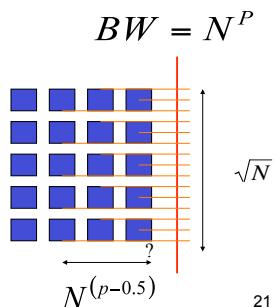
$$BW = N^P$$

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## Generalizing Interconnect Lengths

- Large cut widths imply long wires



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## Placement Problem Characteristics

- Familiar
  - NP Complete
  - local, greedy not work
  - greedy gets stuck in local minima

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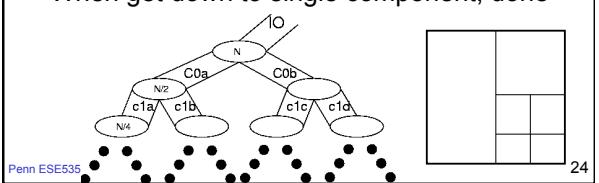
## Constructive Placement

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## Basic Idea

- Partition (bisect) to define halves of chip
  - minimize wire crossing
- Recurse to refine
- When get down to single component, done



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## Adequate?

- Does recursive bisection capture the primary constraints of two-dimensional placement?

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## Problems

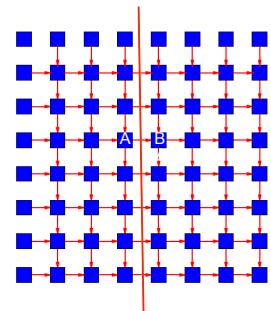
- Greedy, top-down cuts
  - maybe better pay cost early?
- Two-dimensional problem
  - (often) no real cost difference between H and V cuts
- Interaction between subtrees
  - not modeled by recursive bisect

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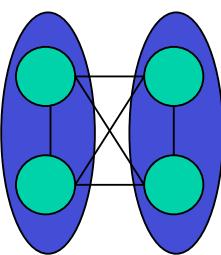
## Example

- Think of this (right) as logical graph.
- Assume we find the “right” bisection (shown)
- Where do A and B go?
- How does recursive partitioning enforce/ encourage this?



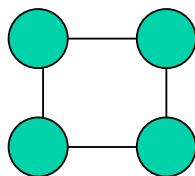
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## Interaction

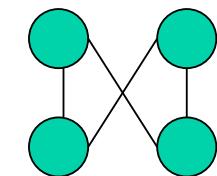


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## Example



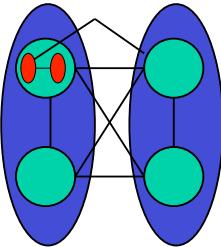
Ideal split  
(not typical)



“Equivalent” split  
ignoring external constraints  
Practically -- makes all H  
cuts also be V cuts

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## Interaction



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## Problem

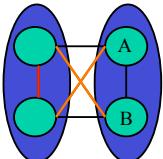
- Need to keep track of where things are
  - outside of current partition
  - include costs induced by above
- ...but don't necessarily know where things are
  - still solving problem

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## Improvement: Ordered

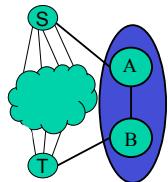
- Order operations
- Keep track of existing solution
- Use to constrain or pass costs to next subproblem



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## Improvement: Ordered

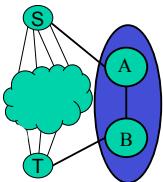
- Order operations
- Keep track of existing solution
- Use to constrain or pass costs to next subproblem
- Flow cut
  - use existing in src/sink
  - A nets = src, B nets = sink



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## Improvement: Ordered

- Order operations
- Keep track of existing solution
- Use to constrain or pass costs to next subproblem
- Flow cut
  - use existing in src/sink
  - A nets = src, B nets = sink
- FM: start with fixed, unmovable nets for side-biased inputs



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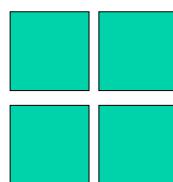
## Improvement: Constrain

- Partition once
- Constrain movement within existing partitions
- Account for both H and V crossings
- Partition next
  - (simultaneously work parallel problems)
  - easy modification to FM

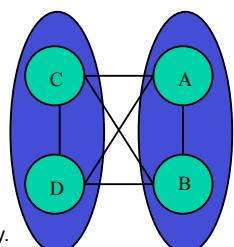
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## Constrain Partition



Solve AB and CD concurrently.



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## Improvement: Quadrisect

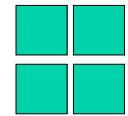
- Solve more of problem at once
- Quadrisection:
  - partition into 4 bins simultaneously
  - keep track of costs all around

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## Quadrisect

- Modify FM to work on multiple buckets
- k-way has:
  - $k(k-1)$  buckets
  - $|from| \times |to|$
  - quad  $\rightarrow 12$
- reformulate gains
- update still  $O(1)$



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## Quadrisect

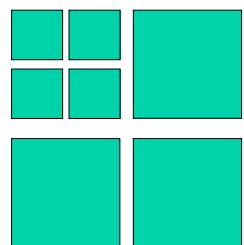
- Cases (15):
  - (1 partition)  $\rightarrow 4$
  - (2 part)  $\rightarrow 6 = (4 \text{ choose } 2)$
  - (3 part)  $\rightarrow 4 = (4 \text{ choose } 3)$
  - (4 part)  $\rightarrow 1$

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## Recurse

- Keep outside constraints
  - (cost effects)
- **Problem?**
  - Don't know detail place
- **What can we do?**
  - Model as at center of unrefined region

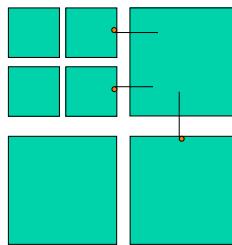


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## Option: Terminal Propagation

- Abstract inputs as terminals
- Partition based upon
- Represent cost effects on placement/refinement decisions

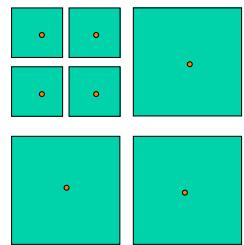


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## Option: Refine

- Keep refined placement
- Use in cost estimates

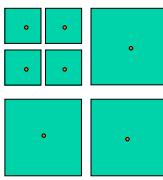


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## Problem

- Still have ordering problem
- **What is the problem?**
- Earlier subproblems solved with weak constraints from later
  - (cruder placement estimates)
- Solved previous case by flattening
- **Why might not be satisfied with that?**
- In extreme give up divide and conquer
- **Alternative?**

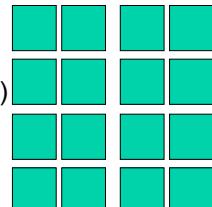


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## Iterate

- After solve later problems
- “Relax” solution
- Solve earlier problems again with refined placements (cost estimates)
- Repeat until converge



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## Iteration/Cycling

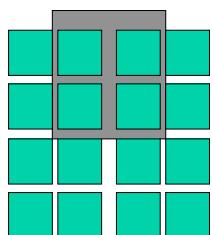
- General technique to deal with *phase-ordering* problem
  - what order do we perform transformations, make decisions?
  - How get accurate information to everyone
- Still basically greedy

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## Refinement

- Relax using overlapping windows
- Deal with edging effects
- Huang&Kahng claim 10-15% improve
  - cycle
  - overlap



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## Possible Refinement

- Allow unbalanced cuts
  - most things still work
  - just distort refinement groups
  - allowing unbalance using FM quadrisection looks a bit tricky
  - gives another 5-10% improvement

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## Runtime

- Each gain update still  $O(1)$ 
  - (bigger constants)
  - so, FM partition pass still  $O(N)$
- $O(1)$  iterations expected
- assume  $O(1)$  overlaps exploited
- $O(\log(N))$  levels
- Total:  $O(N \log(N))$ 
  - very fast compared to typical annealing
    - (annealing next time)

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Gordian-L: Analytic global placer DOMINO: network flow detail					
Case	GORD-L MSTx100	DOMINO MSTx100	QUAD	Impr. GOR-L	Impr. DOMI
prim1	10500	10059	10208	2.8%	-1.5%
prim2	45994	43705	44478	3.3%	-1.8%
ind2	436300	417264	380194	12.9%	8.9%
ind3	1121000	1048673	970068	13.5%	7.5%
fract	400	383	380	5.0%	0.8%
C1908	1858	1767	1830	1.5%	-3.6%
C5315	6220	5922	6185	0.6%	-4.4%
C6288	8794	8339	8312	5.5%	0.3%
s1423	2334	2208	2265	3.0%	-2.6%
s1488	2680	2558	2470	7.8%	3.4%
s5378	8609	8182	8208	4.7%	-0.3%
s9234	14848	14023	13848	6.7%	1.3%
s13207	31284	29995	28161	9.9%	6.1%
s15850	37020	35591	33625	9.2%	5.5%
struct	4160	3967	4196	-0.9%	-5.8%
biomed	34677	33712	33787	2.6%	-0.2%
avq_s	95648	92355	95867	-0.2%	-3.8%
avq_d	100650	97825	101930	-1.3%	-1.2%
Impr.				4.8%	0.3%

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[Huang&Kahng/ISPD1997]

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## Quality: Delay

- Weight edges based on criticality
  - Periodic, interleaved timing analysis

Case	Measure	Max Intrinsic Path Delay	TW7.0	Timing-QUAD
fract	Delay MSTx100		10.6	17.9 349
struct	Delay MSTx100		40.0	78.8 5130
avq_s	Delay MSTx100		37.3	61.4 46763

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## Uses

- Good by self
- Starting point for simulated annealing
  - speed convergence
- With synthesis (both high level and logic)
  - get a quick estimate of physical effects
  - (play role in estimation/refinement at larger level)
- Early/fast placement
  - before willing to spend time looking for best
- For fast placement where time matters
  - FPGAs, online placement?

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## Summary

- Partition to minimize cut size
- Additional constraints to do well
  - Improving constant factors
- Quadrisection
- Keep track of estimated placement
- Relax/iterate/Refine

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## Big Ideas:

- Potential dominance of interconnect
- Divide-and-conquer
- Successive Refinement
- Phase ordering: estimate/relax/iterate

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## Admin

- Reading for Monday
  - Online (JSTOR): classic paper on Simulated Annealing

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