

# ESE535: Electronic Design Automation

Day 12: March 2, 2015  
Placement II  
(Simulated Annealing)

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## Preclass

- Squared wirelength for top placement?
- Squared wirelength for bottom placement?
- Number of swaps?
- Squared wirelength after swap for each of these cases?
  - Sample from class
  - (everyone assigned 1 or 2)

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## Preclass Lesson

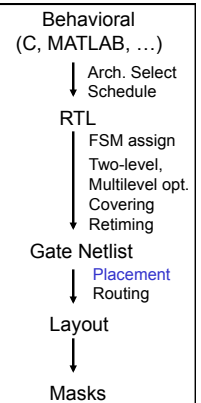
- Why can't we find an improving swap?

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## Today

- Placement
- Improving Quality
  - Cost functions
  - Avoiding local minima
- Technique:
  - Simulated Annealing



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## Simulated Annealing

- Physically motivated approach
- Physical world has similar problems
  - objects/atoms seeking minimum cost arrangement
  - at high temperature (energy) can move around
    - E.g. it melts
  - at low temperature, no free energy to move
  - cool quickly → freeze in defects (weak structure)
    - glass
  - cool slowly → allow to find minimum cost
    - crystal

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## Key Benefit

- Avoid Local Minima
  - Allowed to take locally non-improving moves in order to avoid being stuck



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## Simulated Annealing

- At high temperature can move around
  - not trapped to only make "improving" moves
  - free energy from "temperature" allows exploration of non-minimum states
  - avoid being trapped in local minima
- As temperature lowers
  - less energy available to take big, non-minimizing moves
  - more local / greedy moves

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## Design Optimization

### Components:

1. "Energy" (Cost) function to minimize
  - represent **entire** state, drives system forward
2. Moves
  - local rearrangement/transformation of solution
3. Cooling schedule
  - initial temperature
  - temperature steps (sequence)
  - time at each temperature

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## Basic Algorithm Sketch

- Pick an **initial solution**
- Set temperature (T) to **initial value**
- while ( $T > T_{\min}$ )
  - for **time** at T
    - pick a **move** at random
    - compute  $\Delta\text{cost}$
    - if less than zero, accept
    - else if ( $\text{random}() < e^{-\Delta\text{cost}/T}$ ), accept
  - **update T**

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## Cost Function

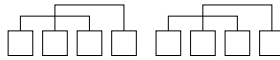
- Can be very general
  - Combine area, timing, energy, routability...
- Desirable characteristics:
  1. drive entire solution in right direction
    - reward **every** good move
  2. cheap to compute delta costs
    - e.g. FM
    - Ideally  $O(1)$

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## Bad Cost Functions

- **Not reward** every move:
  - size < threshold ?
  - Anything using max
    - channel width
    - critical path delay
    - How apply to example at right?
- **Expensive** update cost
  - rerun router on every move
  - rerun static timing analysis
    - E.g. recalculate critical path delay

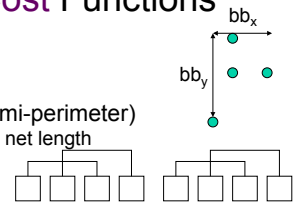


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## Example Cost Functions

- Total Wire Length
  - Linear, quadratic...
- $\Sigma$  Bounding Box (semi-perimeter)
  - Surrogate for routed net length
- $\Sigma (e^{\text{channel\_density}})$ 
  - Dominate by largest density  $\rightarrow$  approximate max
  - Rewards improvement in non-maximum channel
  - But reward is larger for denser channels
  - Can be computed incrementally



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## Cost Functions in Use

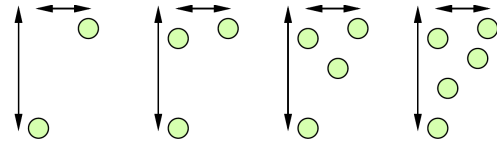
- Next few slides will look at cost functions in use by VPR
  - Versatile Placement and Routing
  - Widely used, open-source placement and routing tool for FPGAs
  - From Univ. of Toronto
  - Now part of VTR (Verilog-to-Routing) suite
- More complicated than earlier examples
  - We'll try to make sense of components

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## Bounding Box

- Why might not be satisfied with bounding box?
  - Should these all contribute same cost?
    - 2, 3, 4, or 5 terminals on same net



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## Example: VPR Wire Costs

- VPR Bounding Box

$$Cost = \sum_{i=1}^{Nets} \left( q(i) \times [bb_x(i) + bb_y(i)] \right)$$

Num Terminals	Correction Factor	Num Terminals	Correction Factor
1-3	1.00	15	1.69
4	1.08	20	1.89
5	1.15	25	2.07
6	1.22	30	2.23
7	1.28	35	2.39
8	1.34	40	2.54
9	1.40	45	2.66
10	1.45	50	2.79

Swartz, Betz, & Rose  
FPGA 1998

Original table:  
Cheng ICCAD 1994

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## Example: VPR Timing Costs

- Criticality(e)=1-Slack(e)/Dmax
- TCost(e)=Delay(e)\*Criticality(e)<sup>CriticalityExp</sup>
- Keep all edge Criticalities in a table
- Recompute Net Criticality at each Temperature

Criticality Exponent	Placement Estimated Critical Path (ns) (20 Circuit Geometric Average)	Wiring Cost (20 Circuit Geometric Average)
1	38.9	342.0
2	37.1	343.4
3	35.9	344.0
4	34.8	344.7
5	34.7	345.7
6	34.8	341.6
7	34.3	339.6
8	34.3	340.1
9	33.8	339.6
10	34.3	337.9
11	34.3	336.3

Marquardt, Betz, & Rose  
FPGA2000

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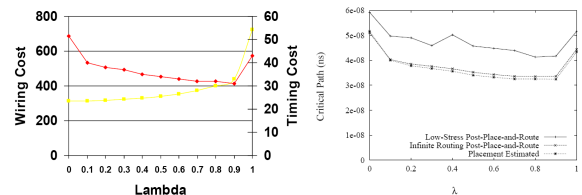
## Different Costs

- How might we deal with multiple costs?
  - E.g. Wire cost and Timing costs?

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## VPR Balance Wire and Time Cost



Anneal Cost is weighted linear sum of Wire and Time

$$\Delta Cost = \lambda \left( \frac{\Delta TCost}{Old TCost} \right) + (1 - \lambda) \left( \frac{\Delta WCost}{Old WCost} \right)$$

Marquardt, Betz, & Rose FPGA2000

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## Basic Algorithm Sketch (review)

- Pick an initial solution
- Set temperature (T) to initial value
- while ( $T > T_{\min}$ )
  - for time at T
    - pick a move at random
    - compute  $\Delta\text{cost}$
    - if less than zero, accept
    - else if  $(\text{random}()) < e^{-\Delta\text{cost}/T}$ , accept
  - update T

## Moves

- Swap two cells
  - Within some distance limit? (ex. to come)
- Swap regions
  - ...rows, columns, subtrees, cluster
- Rotate cell (when feasible)
- Flip (mirror) cell
- Permute cell inputs (equivalent inputs)

## Legality Constraints

- Examples:
  - Limit on number of LUTs/PE (position)
  - Limit on number of Inputs/cluster (region)
- Options:
  1. Force all moves to be legal
    - Force initial placement to be legal
    - Illegal moves rejected
  2. Allow illegal placement/moves
    - Set cost function to make undesirable
    - Make less desirable (more costly) over time

## Basic Algorithm Sketch (review)

- Pick an initial solution
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- while ( $T > T_{\min}$ )
  - for time at T
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  - update T

## Initial Solution

- Random
- Spectral Placement
- Constructive Placement
  - Fast placers start at lower temperature; assume constructive got global right.
    - But may be stuck in minima region defined by constructive placement

## Basic Algorithm Sketch (review)

- Pick an initial solution
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## Details

- **Initial Temperature**
  - $T_0 = -\Delta_{avg} / \ln(P_{accept})$
  - $e^{-\Delta_{cost}/T}$
  - $e^{-\Delta_{cost}/T_0} = e^{-\Delta_{cost}/(-\Delta_{avg}/\ln(P_{accept}))}$
  - Average move  $\rightarrow e^{\ln(P_{accept})}$ 
    - Accepted with Probability  $P_{accept}$
- When  $P_{accept} = 1$ , moves randomize

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## Details

- **Cooling schedule: options**
  - fixed ratio:  $T = \lambda T$ 
    - (e.g.  $\lambda = 0.85$ )
  - temperature dependent
  - function of both temperature and acceptance rate
    - example to come
- **Time at each temperature: options**
  - fixed number of moves?
  - fixed number of rejected moves?
  - fixed fraction of rejected moves?

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## VPR Cooling Schedule

- Moves at Temperature =  $cN^{4/3}$
- Temperature Update
  - $T_{new} = T_{old} \times \gamma$
  - **Idea:** advance slowly in good  $\alpha$  range
  - $\alpha$  is measured acceptance rate

$\alpha$	$\gamma$
$\alpha > 0.96$	0.5
$0.8 < \alpha \leq 0.96$	0.9
$0.15 < \alpha \leq 0.8$	0.95
$\alpha \leq 0.15$	0.8

Betz, Rose, & Marquardt  
Kluwer 1999

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## Basic Algorithm Sketch

- **Pick an initial solution**
  - Set temperature (T) to **initial value**
  - while ( $T > T_{min}$ )
    - for **time** at T
      - pick a **move** at random
      - compute  $\Delta_{cost}$
      - if less than zero, accept
      - else if  $(\text{random}()) < e^{-\Delta_{cost}/T}$ , accept
    - **update T**
- What happens when  $T \rightarrow 0$  ?

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## Range Limit

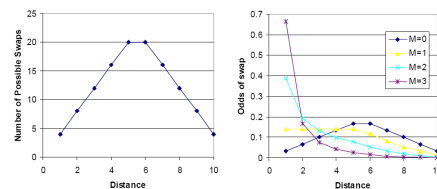
- Want to tune so accepting 44% of the moves – Lam and Delosme DAC 1988
- VPR
  - Define Rlimit – defines maximum  $\Delta x$  and  $\Delta y$  accepted
  - Tune Rlimit to maintain acceptance rate
  - $Rlimit^{new} = Rlimit^{old} \times (1 - 0.44 + \alpha)$ 
    - $\alpha$  is measured acceptance rate

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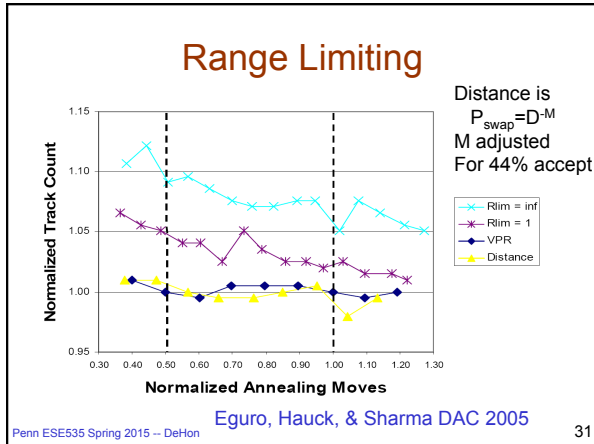
## Range Limiting?

- Eguro alternate [DAC 2005]
  - define  $P = D^{-M}$
  - Tune M to control  $\alpha$



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### Recall: VPR Timing Costs

- $\text{Criticality}(e) = 1 - \text{Slack}(e) / D_{\text{max}}$
- $\text{TCost}(e) = \text{Delay}(e) * \text{Criticality}(e)^{\text{CriticalityExp}}$
- Keep all edge criticalities in a table
- **Recompute Net Criticality at each Temperature**
- **Why might be a problem?**

Criticality Exponent	Placement Estimated Critical Path (ns) (20 Circuit Geometric Average)	Wireing Cost (20 Circuit Geometric Average)
1	38.9	342.0
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Marquardt, Betz, & Rose  
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### Changing Criticality

- Consider: Initial Critical Path  $D \rightarrow E \rightarrow F$   
– Secondary Path  $A \rightarrow B \rightarrow C$

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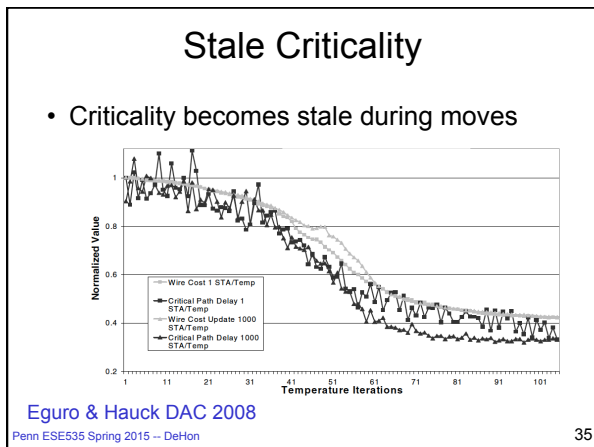
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### Changing Criticality

- After moves

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## Variant: “Rejectionless”

- Order moves by cost
  - compare FM
- Pick random number first
- Use random to define range of move costs will currently accept
- Pick randomly within this range
- **Idea:** never pick a costly move which will be rejected

## Simulated Annealing Theory

- If stay long enough at each cooling stage
  - will achieve tight error bound
- If cool long enough
  - will find optimum
- ...but is it any less work than exhaustive exploration?
  - Good to have a continuum....

## Practice

- Good results
  - ultimately, what most commercial tools use...what vpr uses...
- Slow convergence
- Tricky to pick schedules to accelerate convergence
  - Too slow → runs too long
  - Too fast → freezes prematurely → local min → low quality

## Pragmatic Approach

- Good way to find out what optimization is possible
  - Run for long time and cool slowly
  - If can slow down cooling and get improvement
    - Demonstration haven't found optimum, yet
- Once know good result this way
  - Can try to accelerate convergence
  - w/out sacrificing quality

## Big “Hammer”

- Costly, but general
- Works for most all problems
  - (part, placement, route, retime, schedule...)
- Can have hybrid/mixed cost functions
  - as long as weight to single potential
  - (e.g. wire/time from VPR)
- With care, can attack multiple levels
  - place and route
- **Ignores structure of problem**
  - resignation to finding/understanding structure



## Summary

- Simulated Annealing
  - use randomness to explore space
  - accept “bad” moves to avoid local minima
  - decrease tolerance over time
- General purpose solution
  - costly in runtime

## Big Ideas:

- Use randomness to explore large (non-convex) space
  - Sample various parts of space
  - Avoid becoming trapped in local minimum
- Technique
  - Simulated Annealing

## Admin

- Reading for Wednesday online
- Assignment 6 due Thursday