

ESE535: Electronic Design Automation

Day 17: March 30, 2015
High Level Synthesis II
Dataflow Graph Sharing

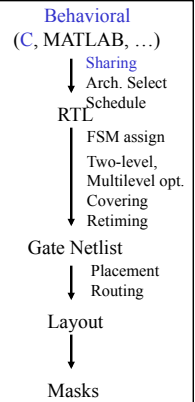


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Today

Sharing

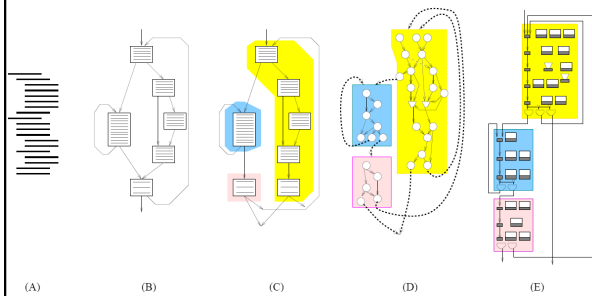
- Dataflow subgraph
 - Pattern identification
 - Pattern selection



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Flow Review



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Additional Concerns?

What are we still not satisfied with?

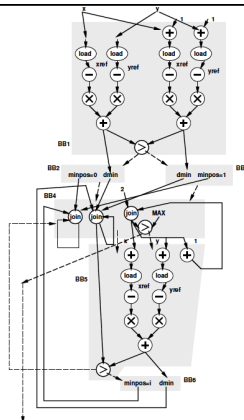
- Parallelism in hyperblock
 - Especially if memory sequentialized
 - Disambiguate memories?
 - Allow multiple memory banks?
- Only one hyperblock active at a time
 - Share hardware between blocks?
- Data only used from one side of mux
 - Share hardware between sides?
- Most logic in hyperblock idle?
 - Couldn't we pipeline execution?

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Preclass

- Common subgraphs?
- How would we like to share?
 - If trying to avoid slowdown
 - If willing to make area-time tradeoffs?

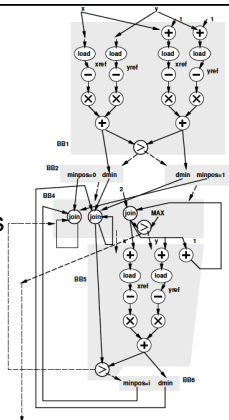


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Subgraph Sharing

- Can potentially share identical subgraphs
- Can share similar subgraphs



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Evaluating Subgraph Sharing

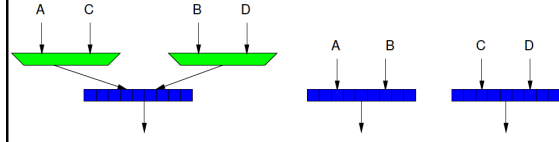
- What do we have to do to share subgraphs?
- When is it worthwhile?
 - How big does graph need to be?
 - How much overhead to share?

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Example

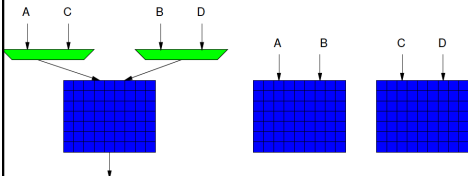
- Muxes on inputs to an adder
 - Probably bigger than just having two adders
 - $2(A_{mux}) + A_{add} > 2(A_{add})$
 - On FPGA:
 - ~LUT per Adder bit
 - ~LUT per Mux bit



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Example

- Muxes on input to multiplier
 - Probably smaller than two multipliers
 - $2(A_{mux}) + A_{mpy} < 2(A_{mpy})$
 - General
 - $Area(A_{mux}) \sim O(N)$
 - $Area(A_{mpy}) \sim O(N^2)$



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Extreme Case

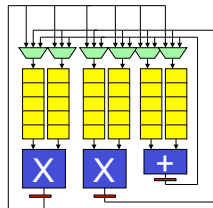
- If ignored multiplexing overhead, what would we get?
 - What would we select at the resources and how connected?

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VLIW Extreme

- Sketch
 - Each basic block requires a set of operators to achieve minimum path length
 - Union sets over all basic blocks
 - Keep track of max number of each operator type
 - Build VLIW with that operator set



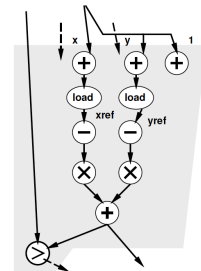
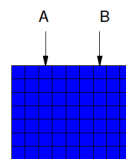
- Why unsatisfying?

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Favorable Subgraphs

- Particularly beneficial when I/O into subgraph small
 - Overhead for muxing proportional to inputs



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Approach

- Find candidate, reusable subgraphs → patterns
- Select a cover set of patterns
- Assign original graph to patterns
 - Assess benefits of sharing
- Patch together pattern cover with control and multiplexing

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Terms

- Subgraph
 - A piece of original computational graph
- Pattern
 - Common (reusable) subgraph
- Want to find small set of patterns that can efficiently cover the original graph

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Approach

- Find **patterns**
- Select a cover set of patterns
- Assign original graph to patterns
 - Assess benefits of sharing
- Patch together pattern cover with control and multiplexing

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Find Recurring Patterns

- How might we identify the set of candidate patterns?

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Finding Subgraphs

- Keep set of subgraphs of size k
- Create subgraphs of size $k+1$ from subgraphs of size k
 - By adding a neighboring node
 - Maybe several such expansions for each k -subgraph
- Careful: can end up with exponential subgraphs

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Optimization

- Compute candidate graph patterns during subgraph generation
 - Each subgraph may become a candidate
 - Keep track of subgraphs that might match with candidate patterns
 - As add subgraph, compare it with candidate patterns and add to list if “close” enough
 - At end of a given graph size, prune out patterns with too few potential matches

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Close enough?

- **Conceptually:** not too expensive to use the candidate pattern
- **Concretely:** compute a distance metric between graph and pattern
 - Minimum cost of edits to morph one graph into another
 - E.g. relabel nodes, remove nodes
 - Want to capture potential cost of adding muxes and control

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Algorithm 1 HPR Algorithm

```

1: P → set of discovered patterns
2: Sk → set of size k subgraph
3: INST(P) → instances of a pattern P
4: ledit → edit distance limit
5: lcount → frequency limit
6:
7: travel all DFGs, add size 1 patterns and instances to P and S1
8: for k ← 2, N do
9:   for all sk ∈ Sk do
10:    adding a neighbor to expand sk to sk+1
11:    if sk is the primary subgraph of sk+1 and convex then
12:     calculate CV(sk+1)
13:     get list of patterns Pi s.t. ||CV(Pi) - CV(sk+1)||1 ≤ 4 + ledit using LSH
14:     calculate edit distance of sk+1 with each Pi
15:     if d(Pi, sk+1) < ledit then
16:      add sk+1 to INST(Pi)
17:     else
18:      create a new pattern based on sk+1, add to P
19:     end if
20:   add sk+1 to Sk+1
21: end for
22: for all new pattern Pi ∈ P do
23:   if |INST(Pi)| < lcount && size(Pi) ≤ (k + 1 - ledit) then
24:    remove Pi from P
25:   else
26:    remove INST(Pi) from Sk+1
27:   end if
28: end for
29: end for
    
```

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[Cong & Jiang / FPGA 2008]

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Potential Optimization

- Canonicalize subgraphs so recognize when encounter same subgraph again
 - Keep set of subgraphs small
- How might we identify/match subgraphs?

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Subgraph Canonicalization (similar to Common Subexpression)

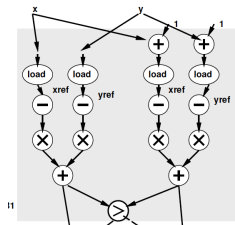
- In topological order (inputs to outputs)
- Give name for single operator
- Each node, need name for subgraph rooted at this node
 - Since named/canonicalize all predecessors
 - Looking for name for a pattern with same operator at the output, and the same subgraph on inputs
 - Compare existing patterns end with output operator
 - Hash operator+inputs → only check things that match hash
 - Match → use that name, else allocate name

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Subgraph Canonicalization

- Problem
 - Matches partial patterns from inputs
 - Not match partial pattern omit part of inputs

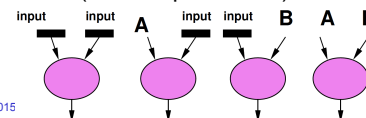


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Subgraph Canonicalization

- Problem
 - Matches partial patterns from inputs
 - Not match partial pattern omit part of inputs
- Approach
 - Also create/name patterns at each node with a subset of the inputs
 - Means each node has multiple pattern candidates (could explode here)



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Cover Subgraphs

- One have candidate patterns, need to cover the original graph.
- What's our goal?
 - (cost function)

Cover Goal

- Minimize area

$$\sum_P A(p) + \sum_{BB} A_{use}(p \in P)$$

- Minimum added latency
 - Delay of BB covered by p in P
- Minimize energy?

Cover Subgraph

- Given a proposed set of pattern graphs, how can we cover?

Cover Subgraph

- How many sets if we explored them all?

Greedy Cover Subgraph

- How might we cover greedily?

Greedy Cover Subgraph

- Select "most beneficial" pattern
- Assign it to the stuff it covers
 - Add logic to share accommodate
 - Remove those as things that need to be covered
- Repeat until all covered or no benefit

Most Beneficial Pattern

- How would we define pattern benefit?

Beneficial Pattern

- N – number of patterns can apply to
- Area: save muxes inside pattern

$$\frac{N * (mux(io) + mux(inside)) + area(P)}{N * mux(io) + area(P)}$$

- Latency: prefer parallel (low depth)

$$\frac{|P|}{latency(P)}$$

Pattern and Graph Statistics

Size	#Subgraph	#Pattern	#Inst	#Calc
2	62	3	62	0.96
3	108	12	108	1.08
4	195	20	161	1.48
5	366	26	248	1.49
6	701	35	404	1.9
7	1357	58	579	2.6
8	2533	76	714	3.18
9	4517	86	762	3.82
10	7800	94	793	4.43
11	13112	101	668	7.04
12	21365	73	348	7.89
13	33316	32	87	5.03
14	49040	3	6	1.7

#Calc –
Average
number of
edit-distance
calculations
per subgraph
match

Energy Impact?

- What are the energy impacts of sharing?

Big Ideas:

- Sharing
- Estimation
- Techniques
 - Graph Matching
 - Covering
 - Greedy

Admin

- Project Formulation Proposal Due Thursday
 - Office Hours or schedule time if want to discuss
- Reading for Wednesday online