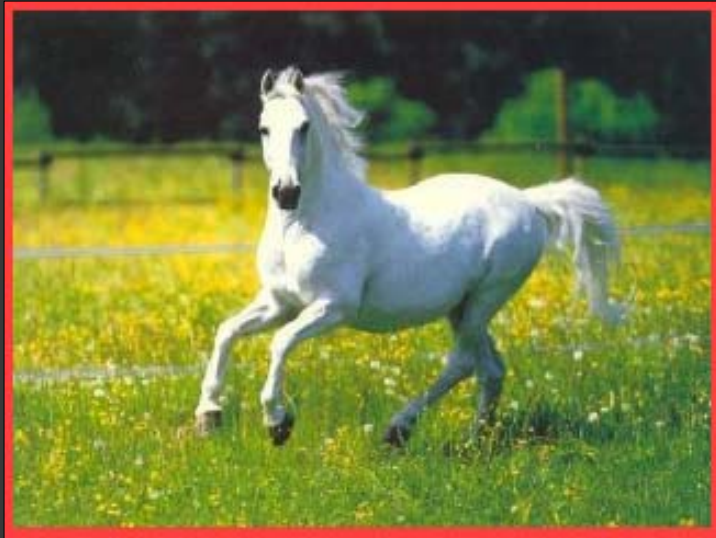


Untangling Cycles for Contour Grouping

Qihui Zhu, Gang Song and Jianbo Shi

GRASP Laboratory
University of Pennsylvania

Finding Salient Contours by Grouping Edges



Input image

Edge
Detection



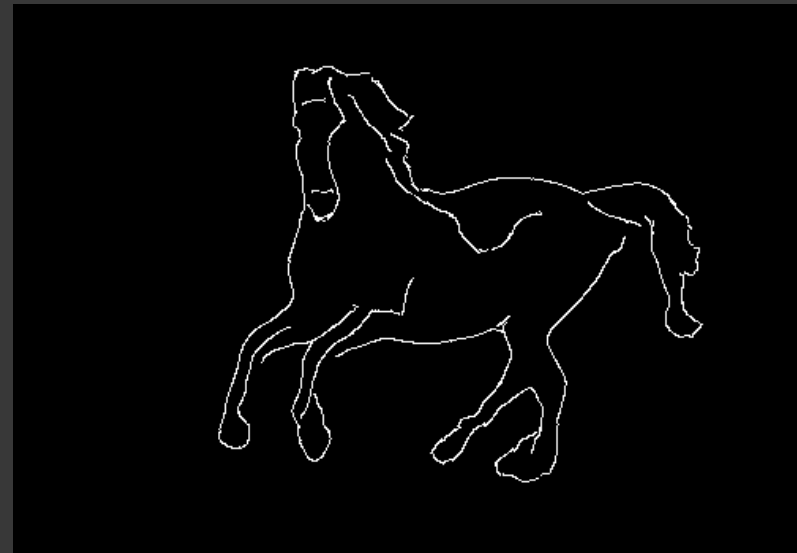
Edgels

Finding Salient Contours by Grouping Edges



edgels

Contour
Grouping



contours

“Long contours are nice to look at”,
K. Koffka. *Principles of Gestalt Psychology*.

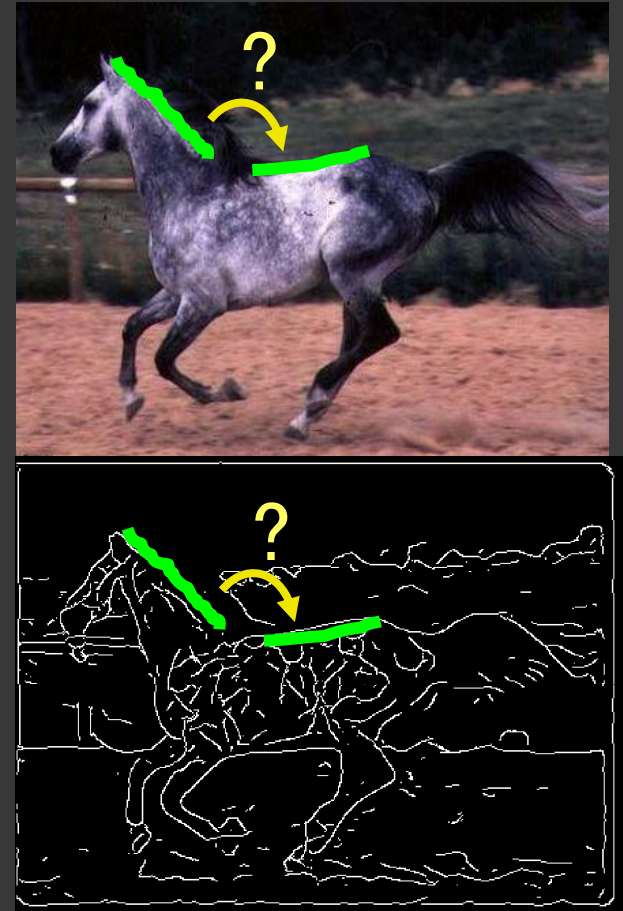
- S. Ullman and A. Shashua.** Structural saliency: The detection of globally salient structures using a locally connected network. In *MIT AI Memo*, 1988.
- S. Mahamud, L. Williams, K. Thornber, and K. Xu.** Segmentation of multiple salient closed contours from real images. *PAMI*, 2003.
- T. D. Alter and R. Basri.** Extracting salient curves from images: An analysis of the saliency network. *CVPR*, 1996.
- A. Amir and M. Lindenbaum.** Grouping-based nonadditive verification. *PAMI*, 20(2):186–192, 1998.
- B. Fischer and J. M. Buhmann.** Path-based clustering for grouping of smooth curves and texture segmentation. *PAMI*, 25(4):513–518, 2003.
- D. W. Jacobs.** Robust and efficient detection of salient convex groups. *PAMI*, 18(1):23–37, 1996.
- G. G. Medioni and G. Guy.** Inferring global perceptual contours from local features. In *IJW*, 1993.
- S. Sarkar and P. Soundararajan.** Supervised learning of large perceptual organization: Graph spectral partitioning and learning automata. *PAMI*, 22(5):504–525, 2000.
- J. H. Elder and S. W. Zucker.** Computing contour closure. *Lecture Notes in Computer Science*, 1064, 1996.

Challenges in Real Images

Edge linking fails in clutter:



2D clutter



Gap

Our Goal

Group salient 1D structures robust to 2D clutter



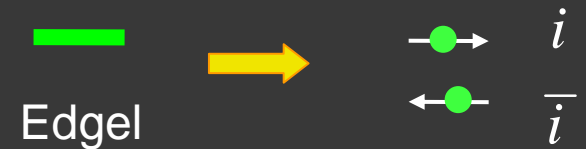
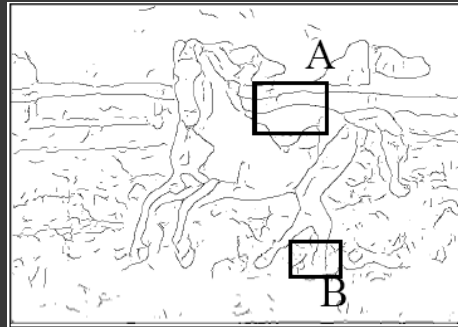
Image

Edges and
detected contours

Image

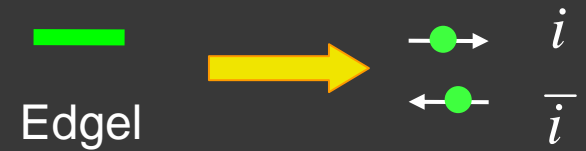
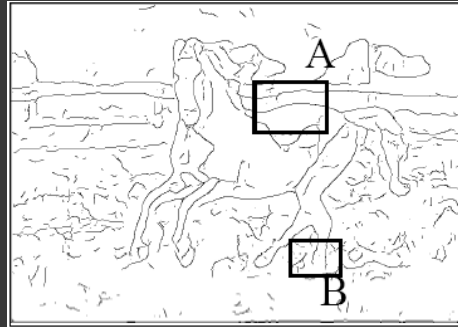
Edges and
detected contours

Directed Graph for Grouping $G=(V,E,W)$



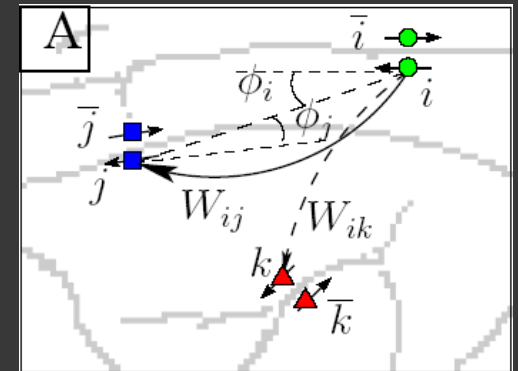
- V Duplicate each edge to (i, \bar{i})
- W Collinearity
 - Elastic energy

Directed Graph for Grouping $G=(V,E,W)$

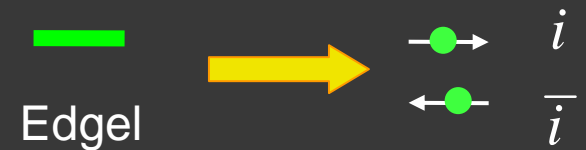
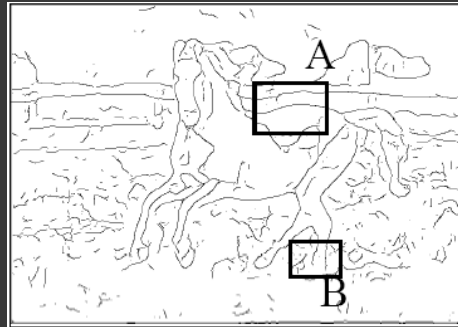


- V Duplicate each edge to (i, \bar{i})
- W Collinearity
 - Elastic energy

$$W_{ij} = e^{-(1 - \cos(|\phi_i| + |\phi_j|)) / \sigma^2}$$



Directed Graph for Grouping $G=(V,E,W)$



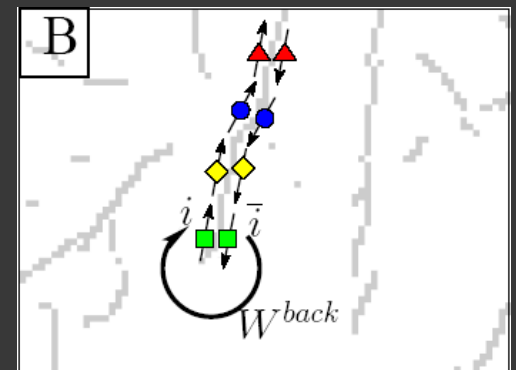
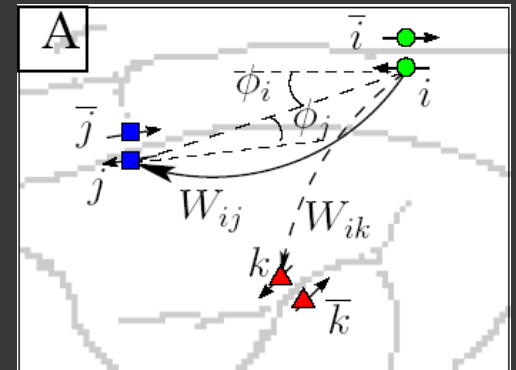
– V Duplicate each edge to (i, \bar{i})

– W Collinearity

• Elastic energy

$$W_{ij} = e^{-(1 - \cos(|\phi_i| + |\phi_j|)) / \sigma^2}$$

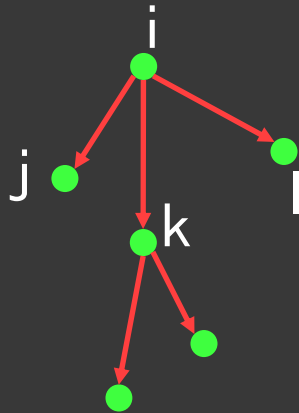
• Backward connection W_{ij}^{back}
open contour: chain \rightarrow graph cycle



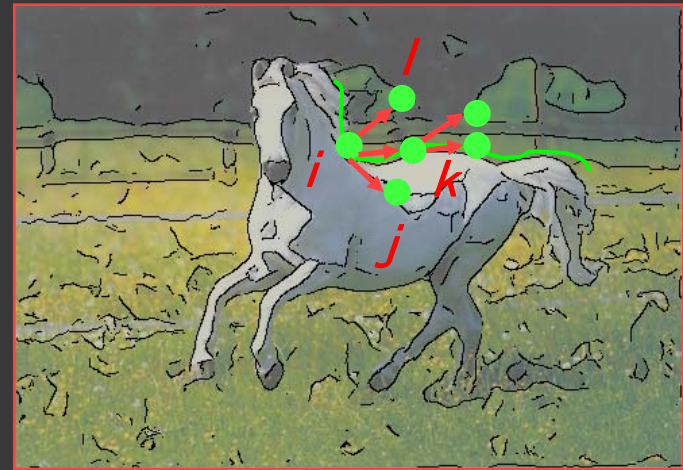
Directed Random Walk

$$P = D^{-1}W$$

$$D = \text{Diag}(W \cdot \mathbf{1})$$



$$P_1(j|i) + P_1(k|i) + P_1(l|i) = 1$$



$P_1(j|i)$ probability of jumping
from i to j in one step

Directed Random Walk

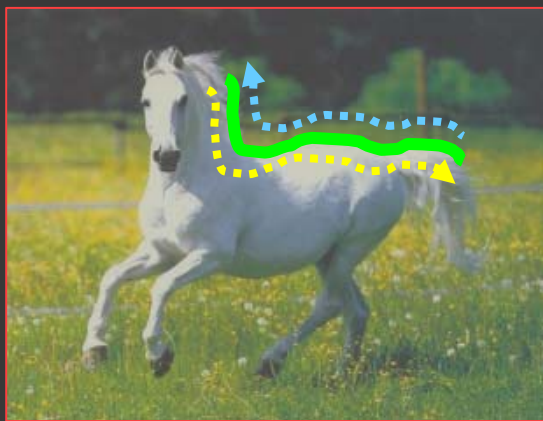
$$P = D^{-1}W$$

$$D = \text{Diag}(W \cdot \mathbf{1})$$

Image contour



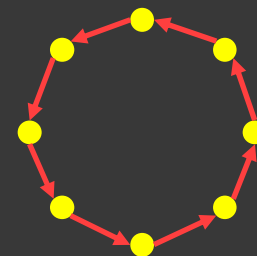
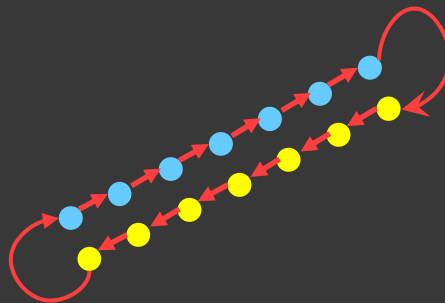
Graph cycle



Open contour



Closed contour



Untangling Cycle Algorithm



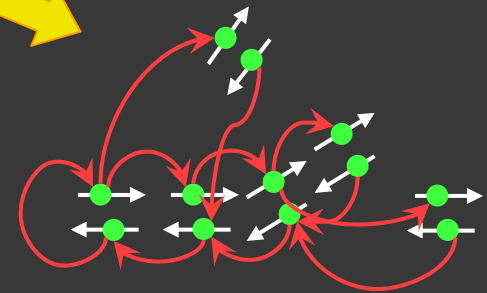
Input image

① Edge detection



Edgels

② Construct G



③ Find salient graph cycles

Contour Saliency

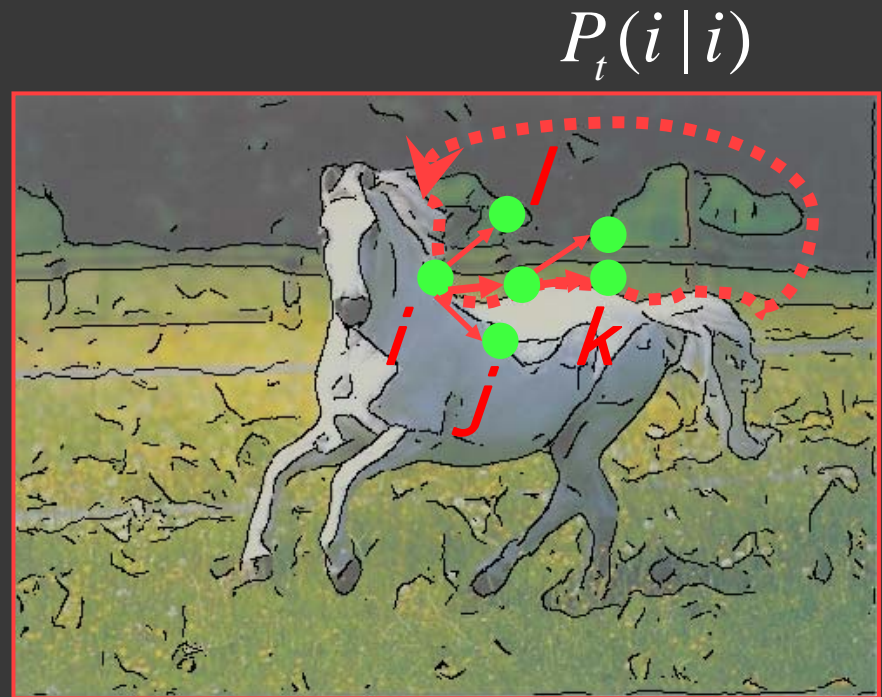
Q: What is the appropriate saliency measure for good cycles (1D contour) and bad cycles (2D clutter)?

Shortest cycle? Longest cycle? Shortest average cycle? ...

Persistency of a Random Walk Cycle

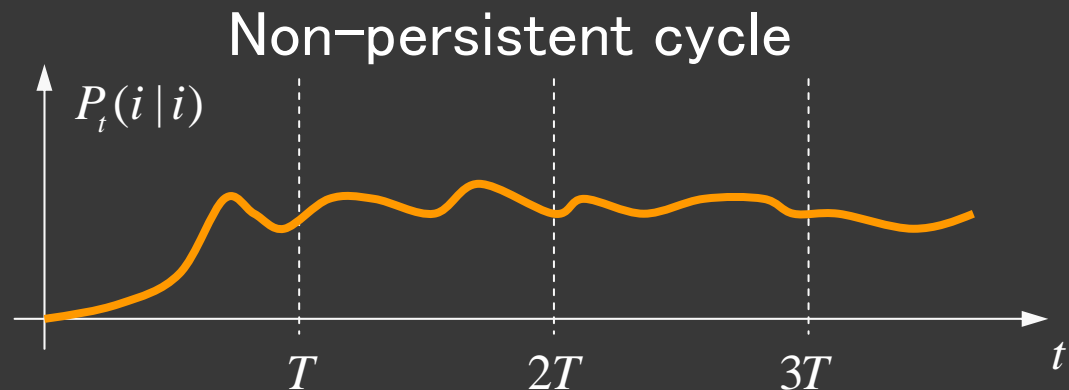
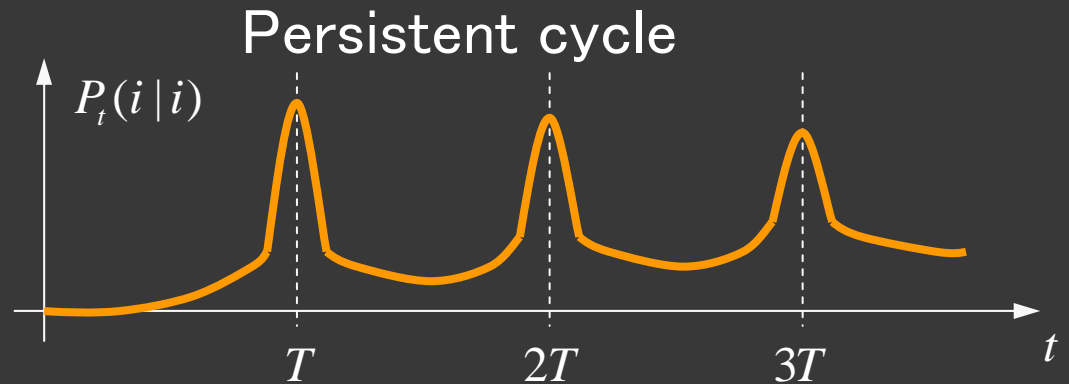
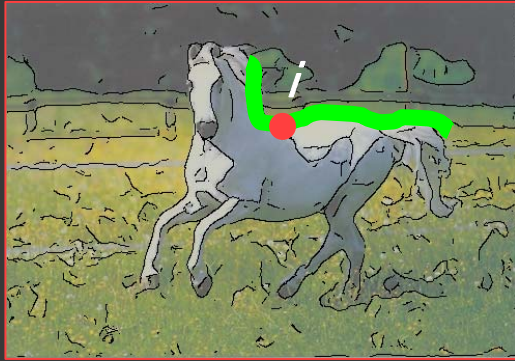
$P_t(i | i)$ probability of cycling $i \rightarrow i$ in t steps

Check how likely a
random walk cycle back
to starting points after
some time t



Observation: Persistent Cycles

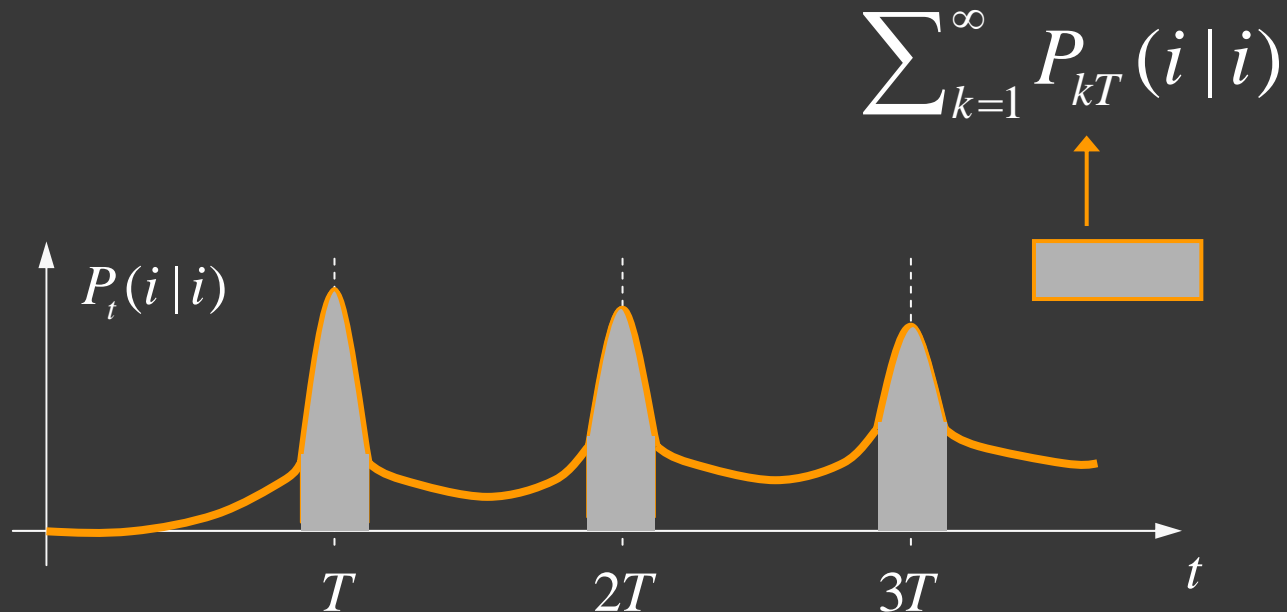
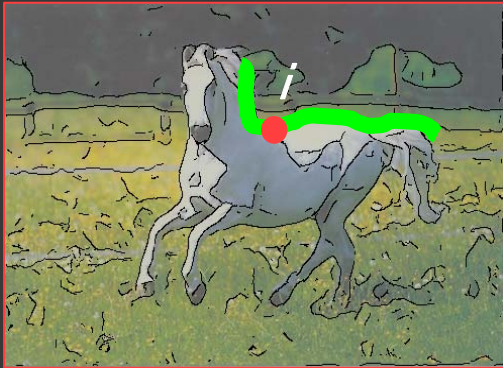
Image contour = Persistent cycles



Persistent Cycle Measure

- ‘Peakiness’ of returning probability: $P_t(i|i)$

$$R(i, T) = \frac{\sum_{k=1}^{\infty} P_{kT}(i|i)}{\sum_{k=0}^{\infty} P_k(i|i)}$$



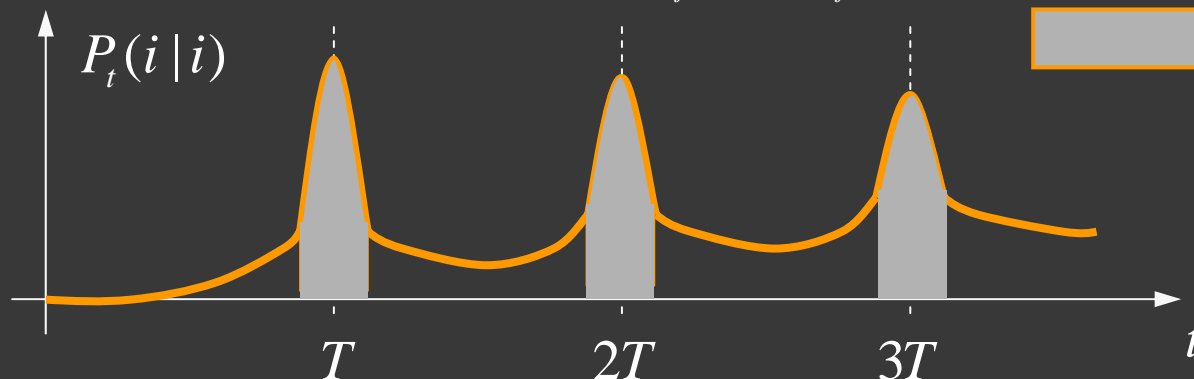
Theorem 'Peakiness': $R(i,T)$ can be computed:

$$R(i,T) = \frac{\sum_j \operatorname{Re}\left(\frac{\lambda_j^T}{1 - \lambda_j^T} \cdot U_{ij} V_{ij}\right)}{\sum_j \operatorname{Re}\left(\frac{\lambda_j}{1 - \lambda_j} \cdot U_{ij} V_{ij}\right)}$$

$U_{:j} \ V_{:j}$: left & right eigenvectors of P

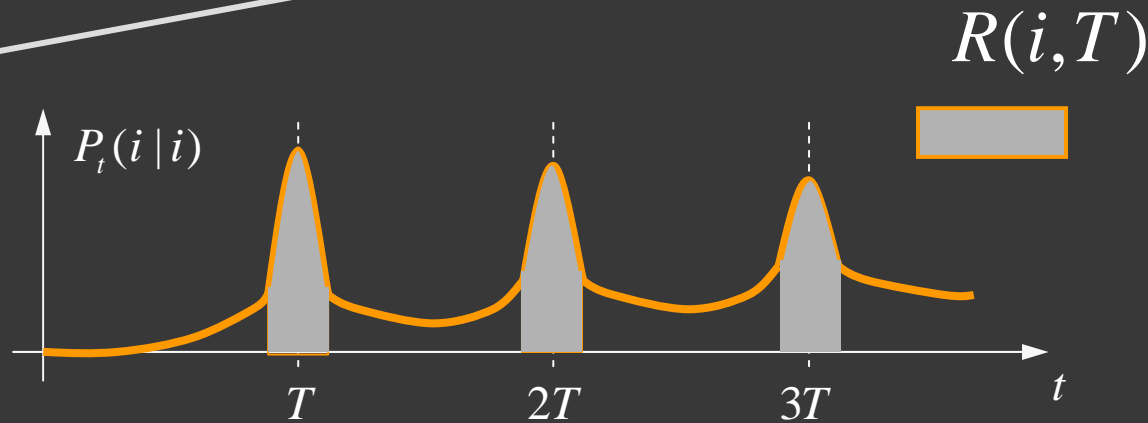
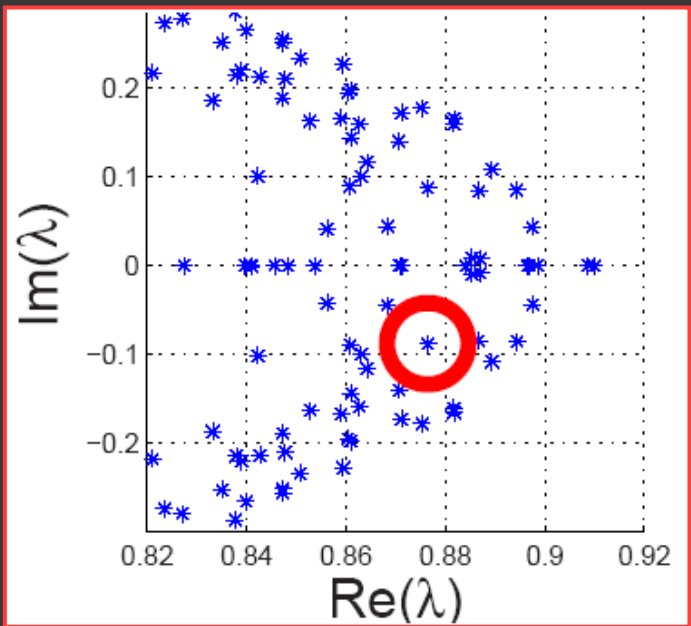
$R(i,T)$: dominated by complex eigenvalues λ_j

$\left(\frac{\lambda_j^T}{1 - \lambda_j^T}\right) / \left(\frac{\lambda_j}{1 - \lambda_j}\right)$ large for complex λ_j



Complex Eigenvalues of Random Walk

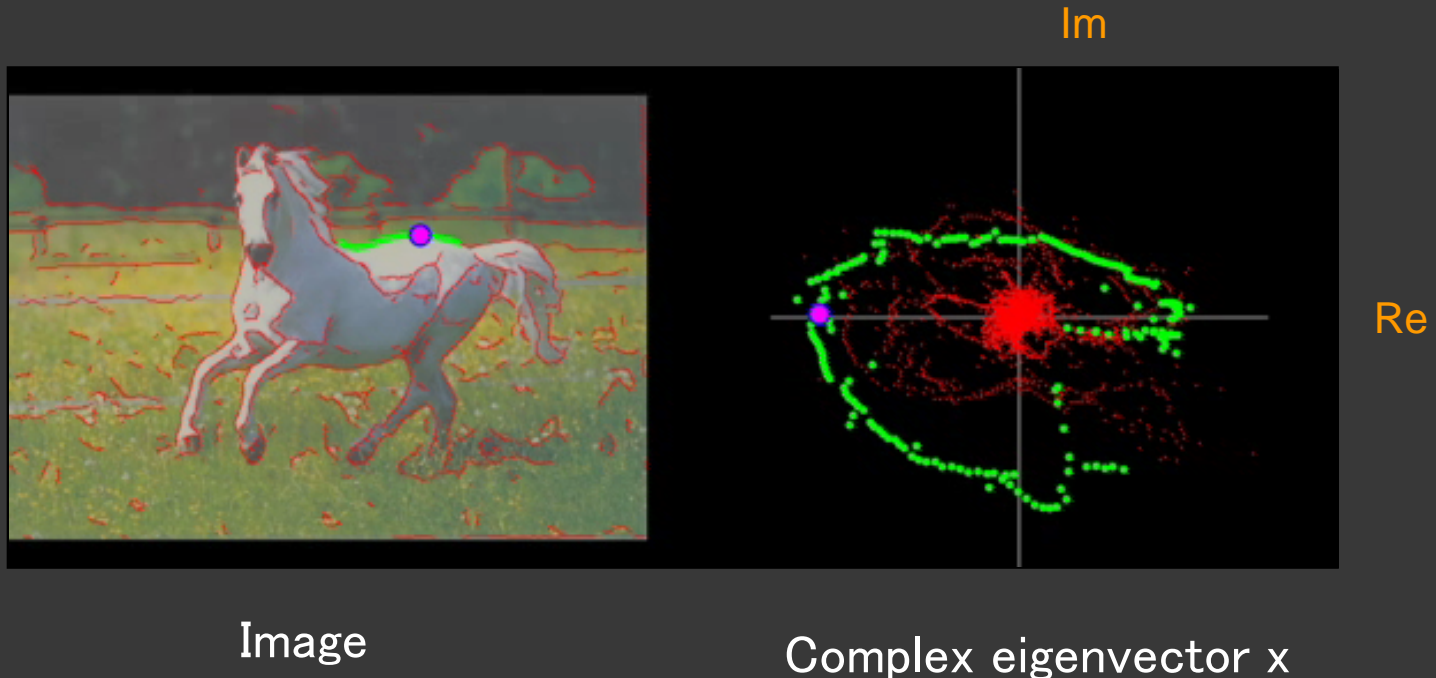
One step random walk $\leftarrow P^T \cdot x \leftrightarrow \boxed{\lambda} \cdot x$



Complex Eigenvector of Random Walk

One step random walk $\leftarrow P^T \cdot x \leftrightarrow \lambda \cdot x \rightarrow$ Rotation in complex vector:

Complex eigenvectors encode both cyclic ordering and likelihood on cycles



Untangling Cycle Algorithm



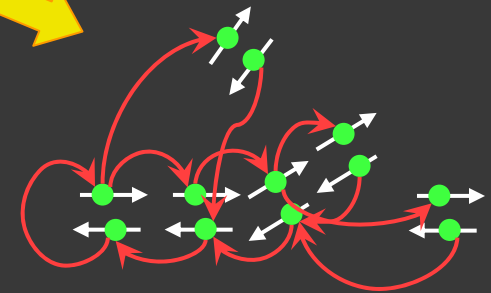
Input image

① Edge detection



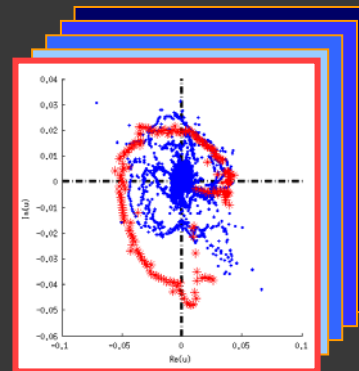
Edgels

② Construct G



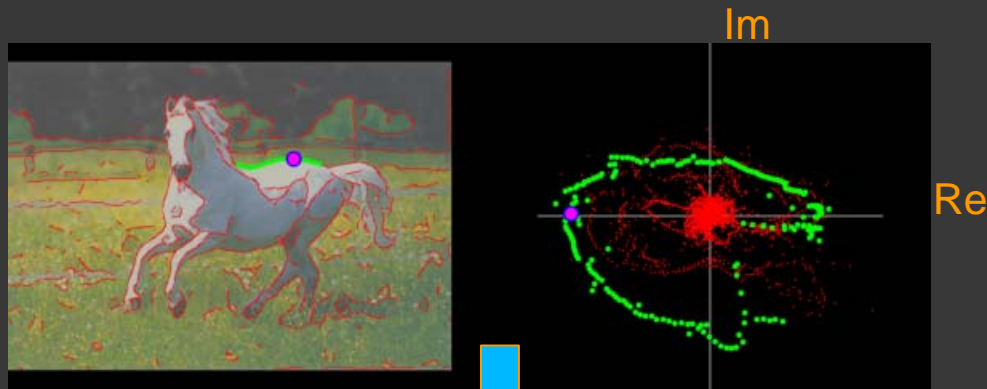
Contour directed graph G

③ Compute complex eigenvectors

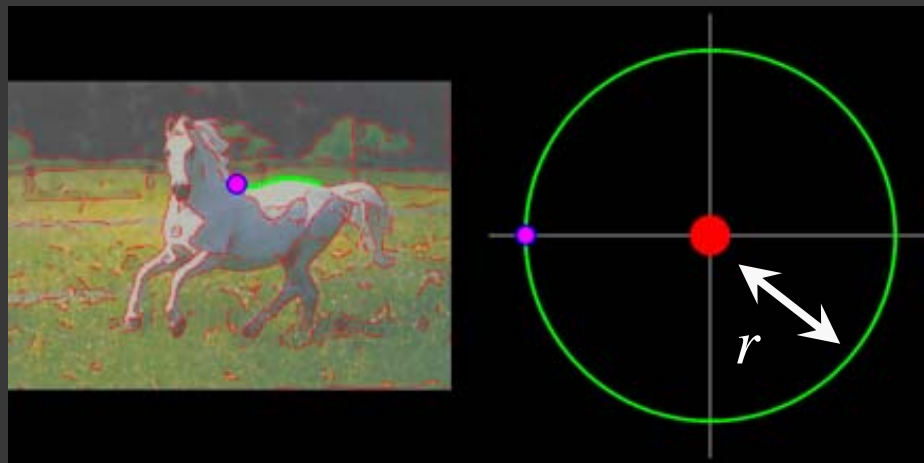


Complex embedding

Ideal Cost for Circular Embedding



Each complex eigenvector gives a circular embedding of the original graph



For a point x in complex plane

$$x(r, \theta) = r \cdot e^{i\theta}$$

Image

Ideal circular embedding

Ideal Cost for Circular Embedding

One step random walk $\leftarrow P^T \cdot x \leftrightarrow \lambda \cdot x \rightarrow$ Rotation in circular embedding:
in circular embedding:

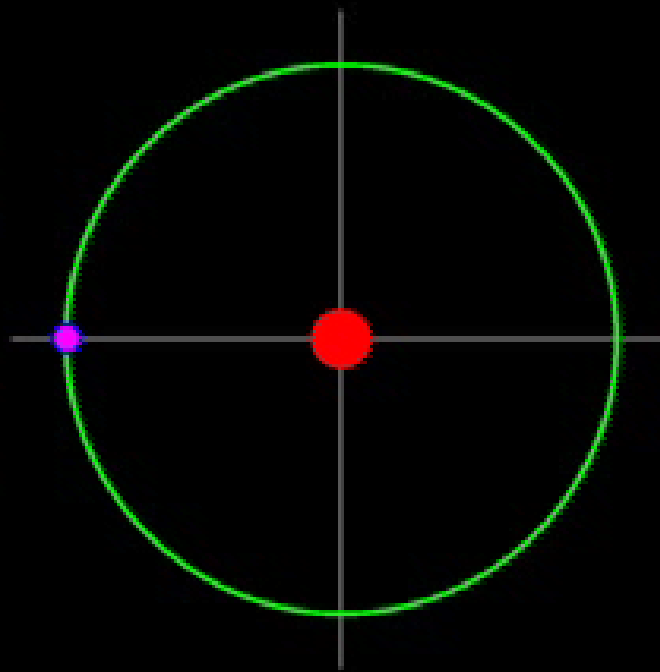
$$x \rightarrow P^T \cdot x$$

$$x(r, \theta) = r \cdot e^{i\theta}$$

$$x \rightarrow \lambda \cdot x$$



Image



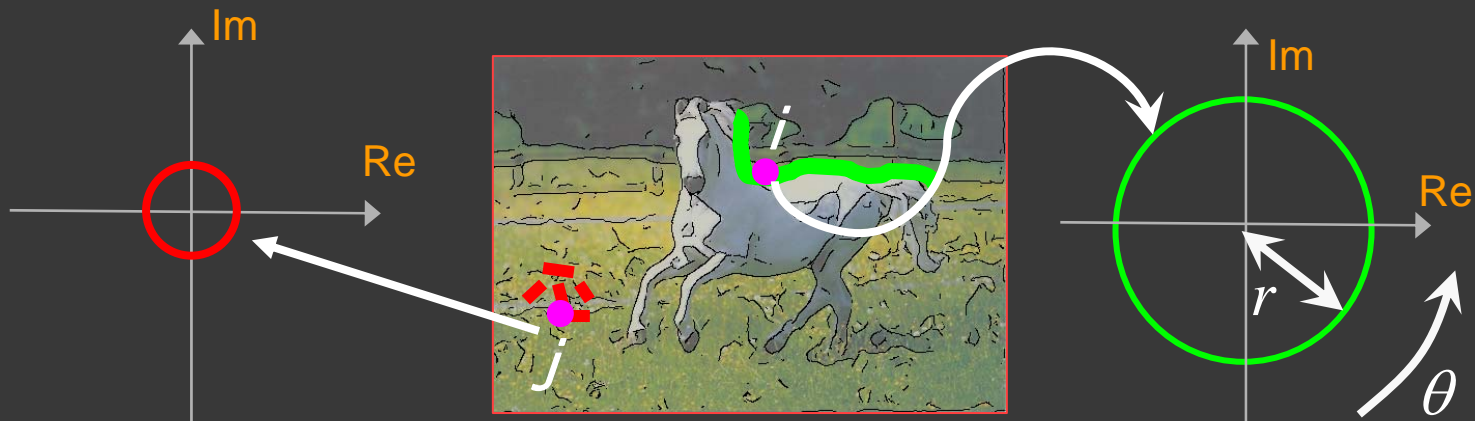
Ideal circular embedding

Ideal Cost of Circular Embedding

we want:

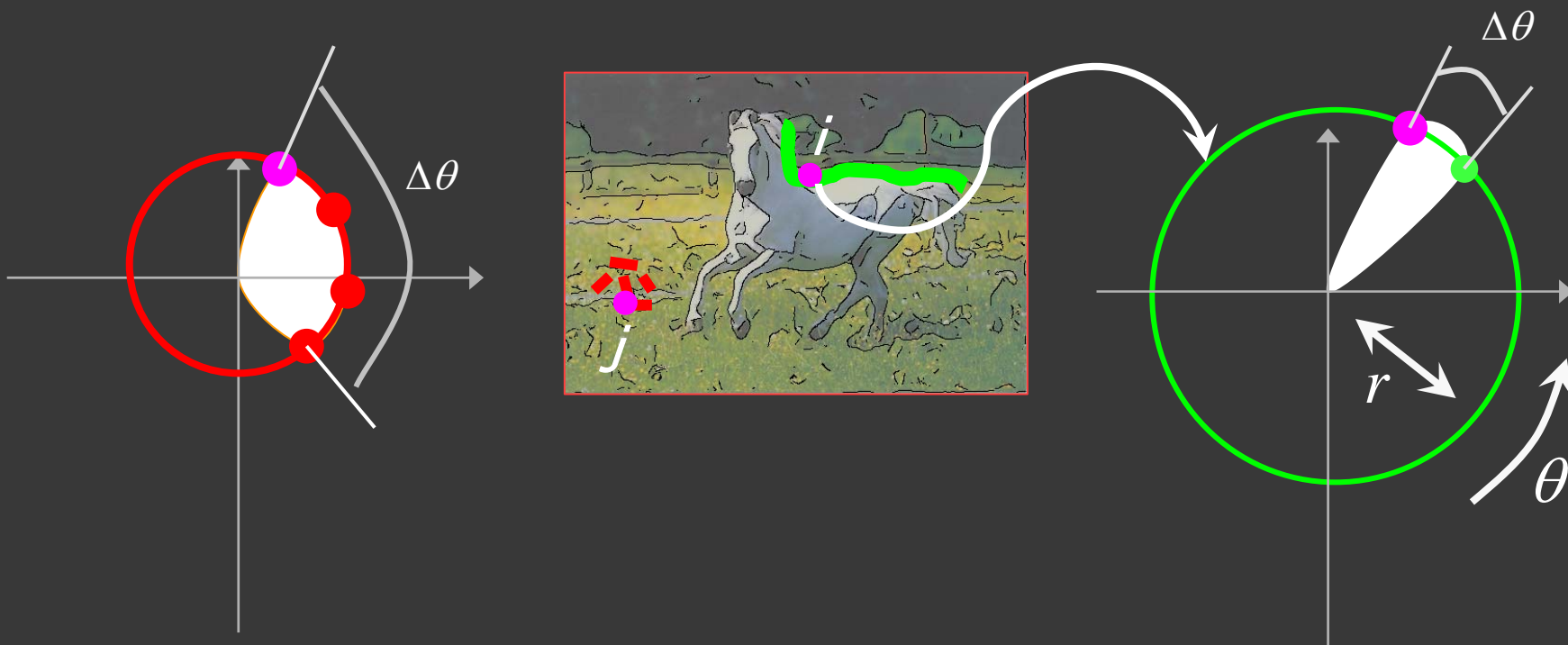
- **Good Contour** → large circle according to cyclic ordering
- **Bad Clutter** → core around the origin

$$x(r, \theta) = r \cdot e^{i\theta}$$



Ideal Cost of Circular Embedding

$$r * \Delta\theta = \text{constant}$$



In clutter, $P(j,:)$ many immediate neighbors for each random walk step

In contour, $P(i,:)$ few immediate neighbors for each random walk step

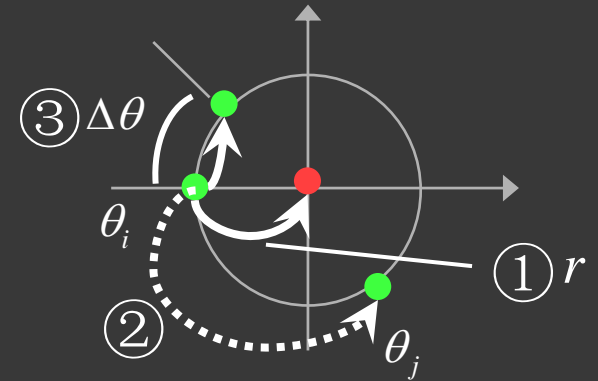
Circular Embedding Score

We conjecture the ideal circular embedding Max.

$$C_e(r, \theta, \Delta\theta) = \sum_{\substack{\theta_i < \theta_j \leq \theta_i + 2\Delta\theta \\ r_i > 0, r_j > 0}} P_{ij} / |S| \cdot \frac{1}{\Delta\theta}$$

$$S = \{(r, \theta) \mid r = r_0\}$$

- r Circle indicator with $r_i \in \{r_0, 0\}$
- θ Phase angles on cycles specifying an ordering
- $\Delta\theta$ Average jumping angle $\Delta\theta = \overline{\theta_j - \theta_i}$



Solution: Complex Eigenvector

$$C_e(r, \theta, \Delta\theta) = \sum_{\substack{\theta_i < \theta_j \leq \theta_i + 2\Delta\theta \\ r_i > 0, r_j > 0}} P_{ij} / |S| \cdot \frac{1}{\Delta\theta}$$

Continuous relaxation

$$\begin{aligned} \max_{u, v \in \mathbb{C}^n} \quad & \text{Re}(u^H P v) \\ \text{s.t.} \quad & u^H v = c \end{aligned}$$

Solution: Complex Eigenvector

$$C_e(r, \theta, \Delta\theta) = \sum_{\substack{\theta_i < \theta_j \leq \theta_i + 2\Delta\theta \\ r_i > 0, r_j > 0}} P_{ij} / |S| \cdot \frac{1}{\Delta\theta}$$

Continuous relaxation

$$\begin{aligned} \max_{u, v \in \mathbb{C}^n} \quad & \text{Re}(u^H P v) \\ \text{s.t.} \quad & u^H v = c \end{aligned}$$

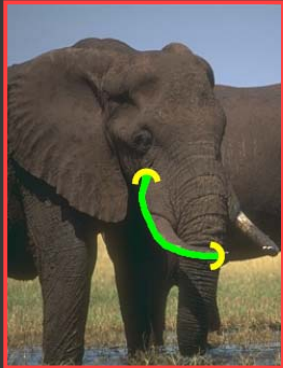
Theorem: All critical points (local maxima) (u_{\max}, v_{\max}) of the above are left and right eigenvectors of P

$$P v_{\max} = \lambda v_{\max} \quad P^T u_{\max}^* = \lambda u_{\max}^*$$

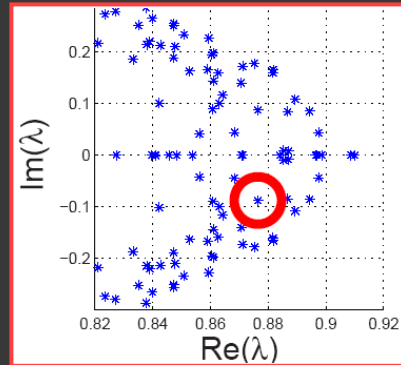
Maximum values are $\max_{\lambda} (\text{Re}(\lambda \cdot c))$

Discretization

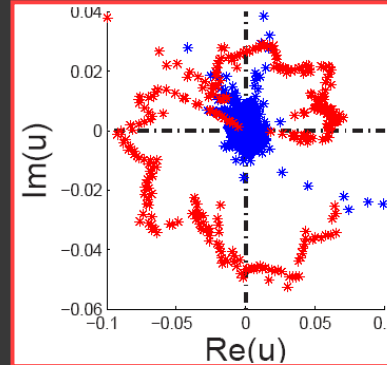
Image



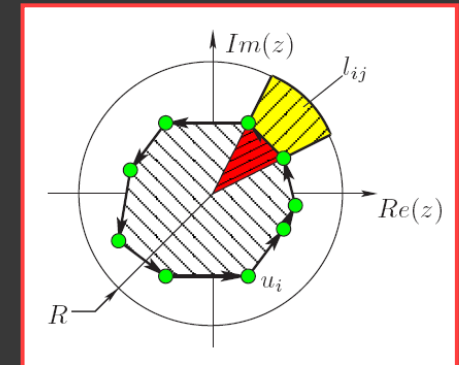
Eigenvalues



One eigenvector



Maximal circular cover



Find embedding cycles with large radius

- Maximal cover area

$$\max_{s_1, \dots, s_k} \sum_{j=1}^k A(u_{s_j}, u_{s_{j+1}})$$

$$A(u_{s_j}, u_{s_{j+1}}) = \frac{1}{2} \text{Im}(u_{s_j}^* \cdot u_{s_{j+1}})$$

Section area spanned by $u_{s_j}, u_{s_{j+1}}$

- Compute shortest paths in the embedding space

Untangling Cycle Algorithm



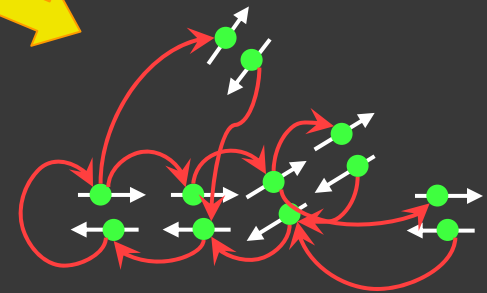
Input image

① Edge detection



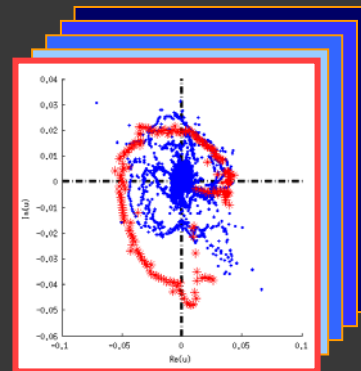
Edgels

② Construct G



Contour directed graph G

③ Compute complex eigenvectors



Complex embedding

④ Discretization

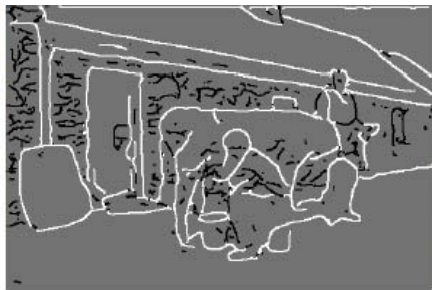
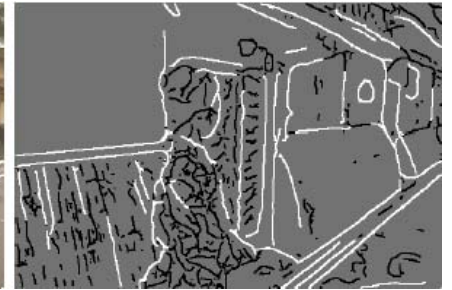


Contours

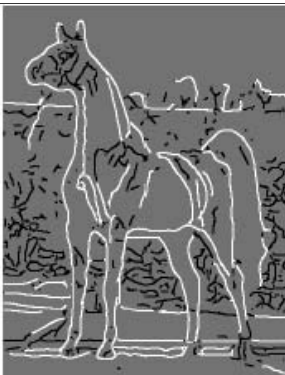
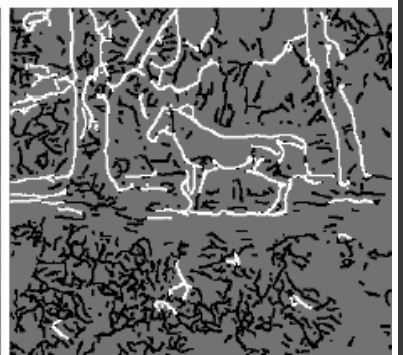
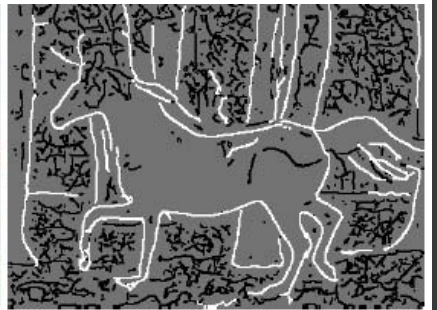
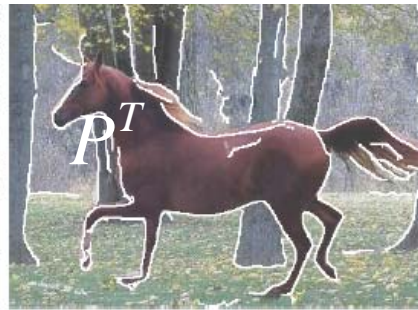
Experiments: BSDS



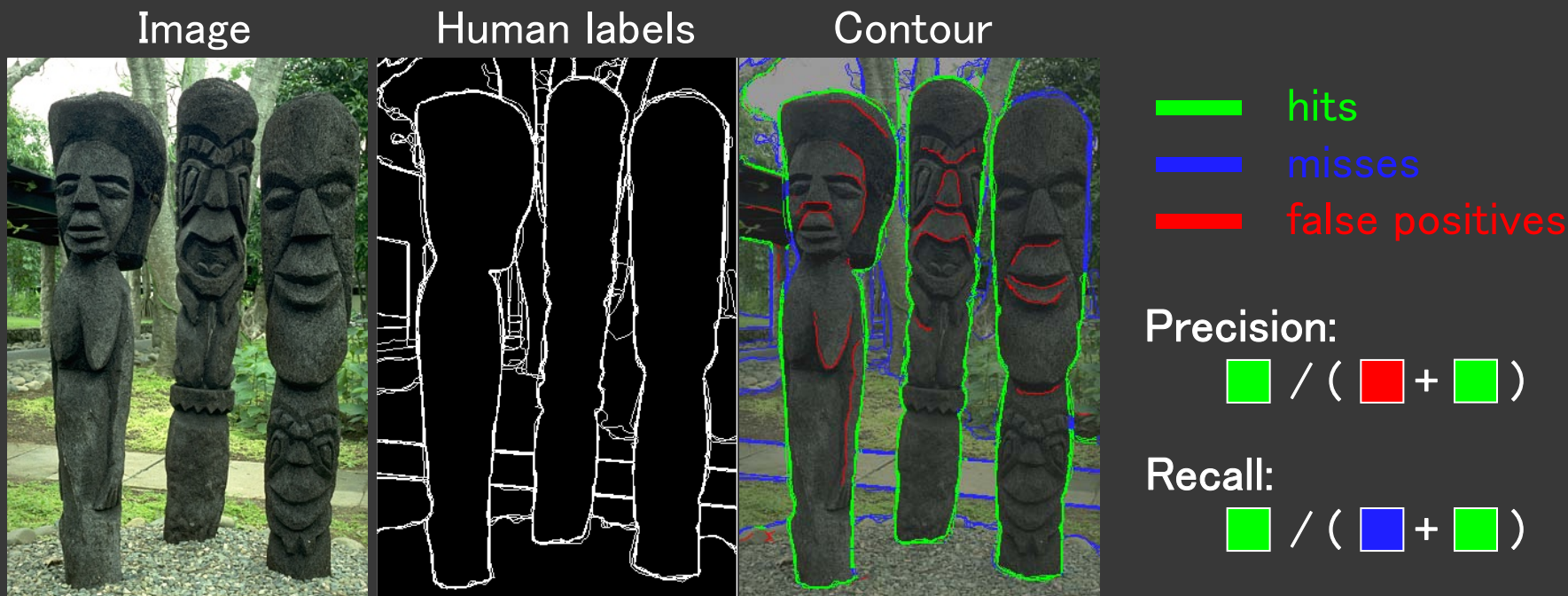
Experiments: BSDS



Experiments: Horses



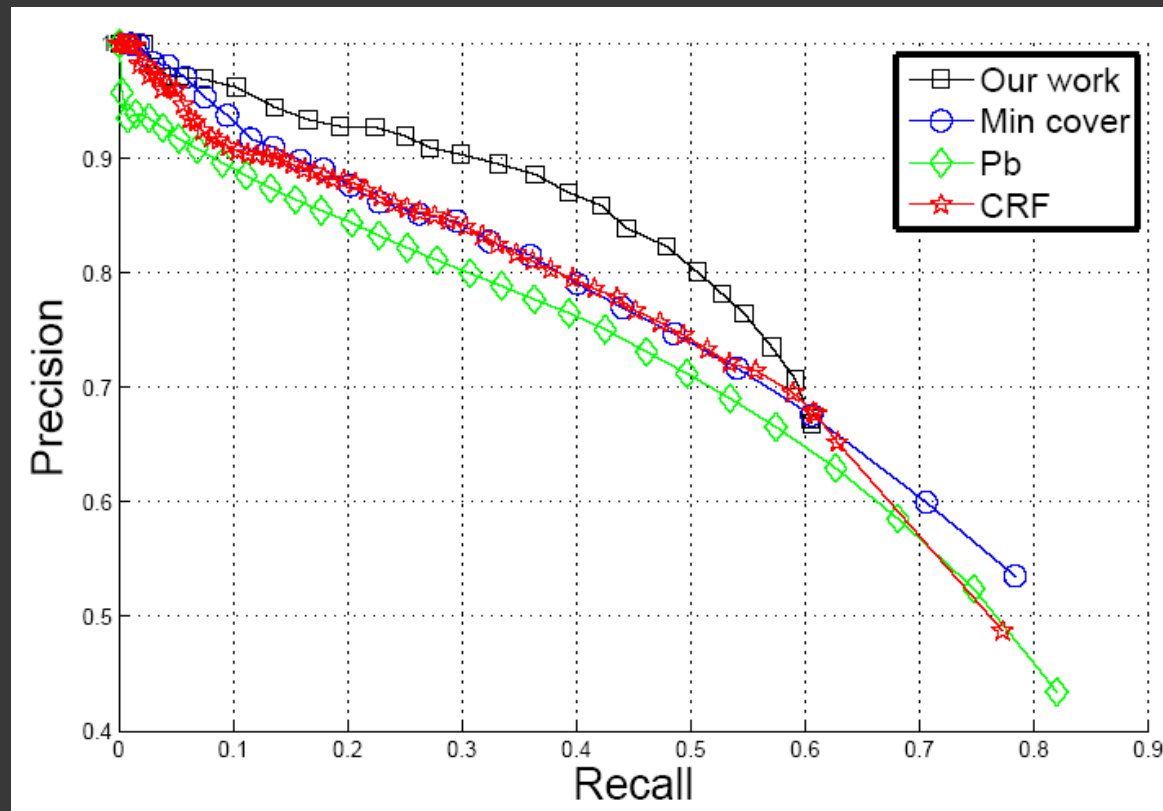
Berkeley Segmentation Benchmark



Compare our method to

- Pb D. Martin *et al*, PAMI 2004
- CRF X. Ren *et al*, ICCV 2005
- Min cover P. Felzenszwalb *et al*, WPOCV 2006

Berkeley Segmentation Comparison



P. F. Felzenszwalb and D. McAllester. A min-cover approach for finding salient curves. In *WPOCV*, page 185, 2006.

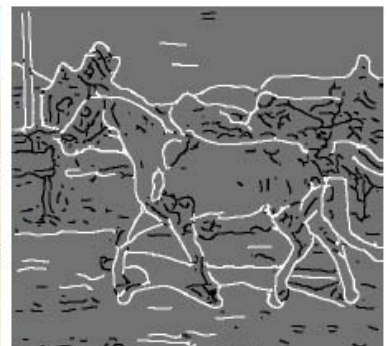
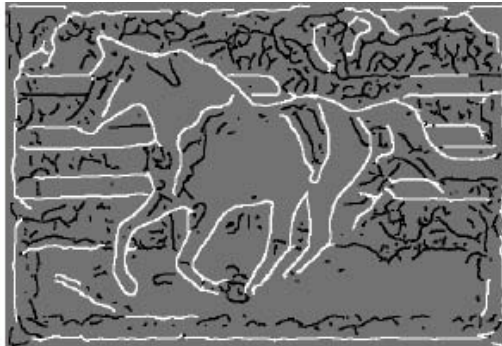
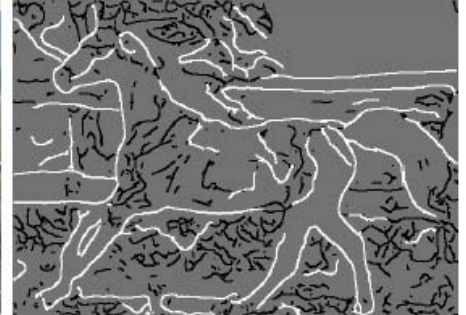
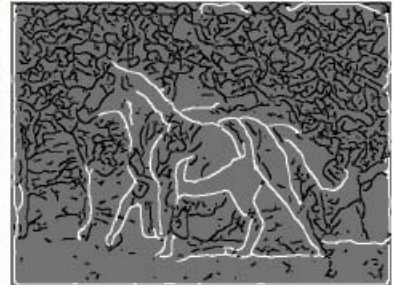
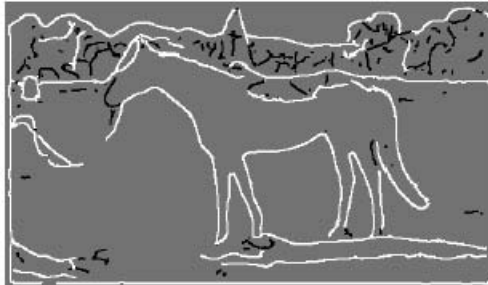
X. Ren, C. Fowlkes, and J. Malik. Scale-invariant contour completion using conditional random fields. In *ICCV*, pages 1214–1221, 2005.

Pb D. Martin *et al*, PAMI 2004

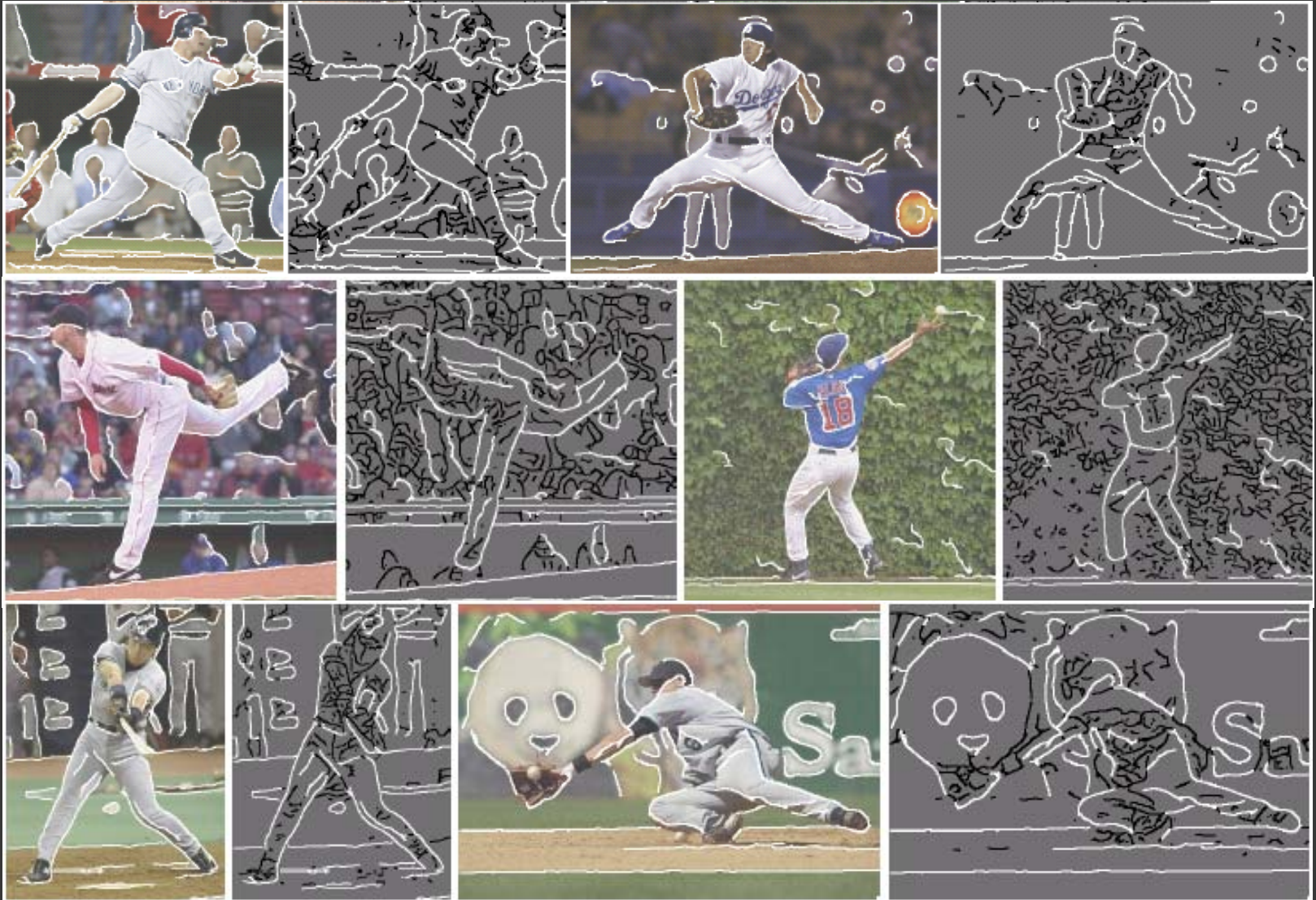
Conclusion

- Utilize topology information for contour grouping
- Persistent cycles: circular/complex embedding
- Untangling cycle cut score: grouping 1D structures

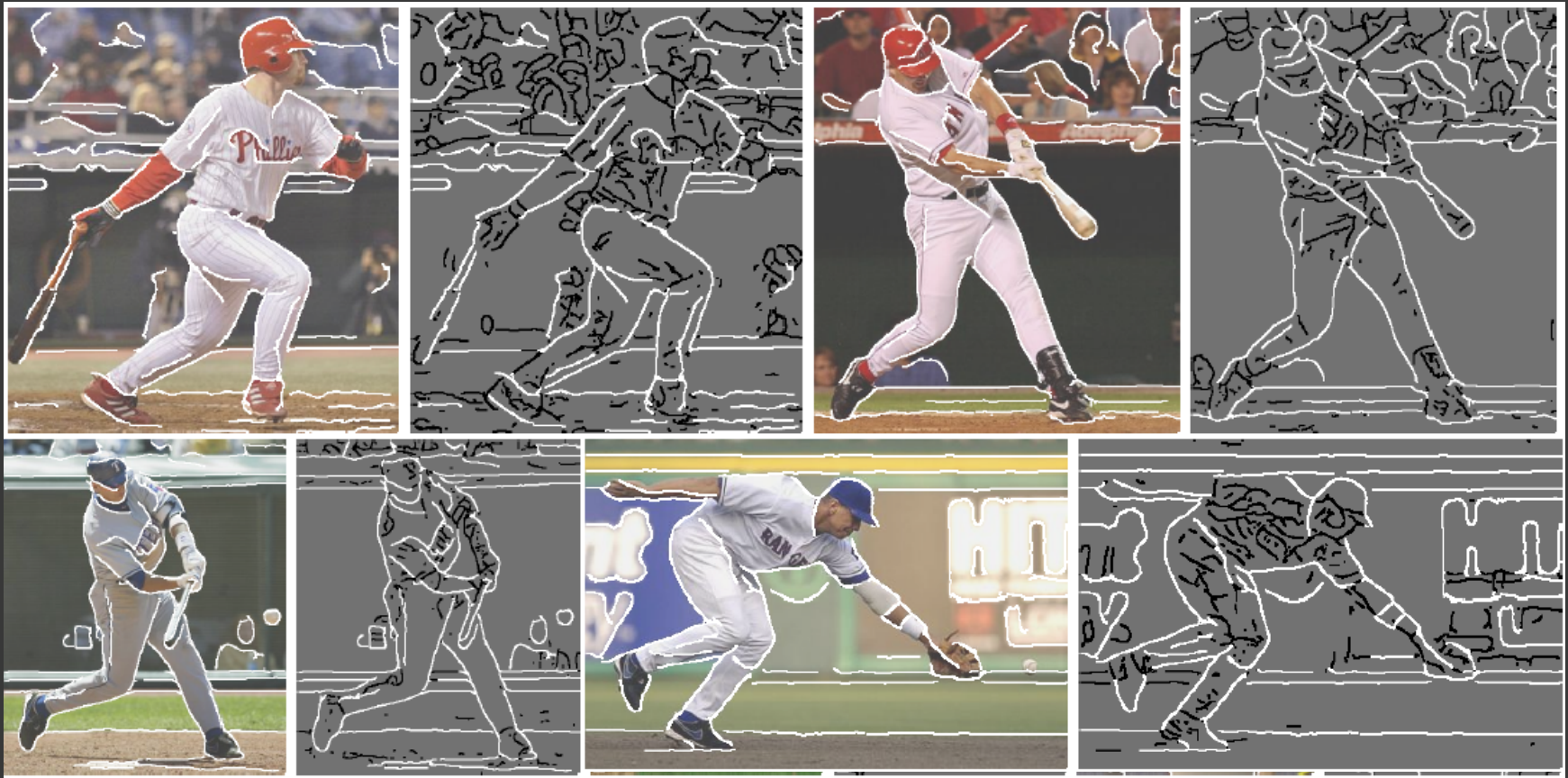
Experiments: Horses



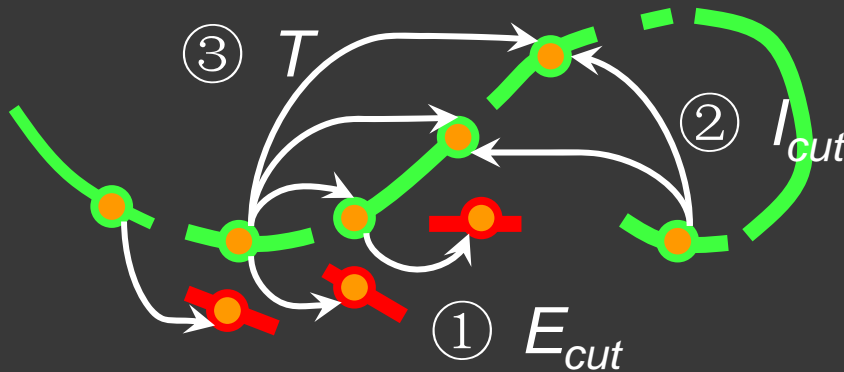
Experiments: Baseball Players



Experiments: Baseball Players



Untangling Cycle Cut Score



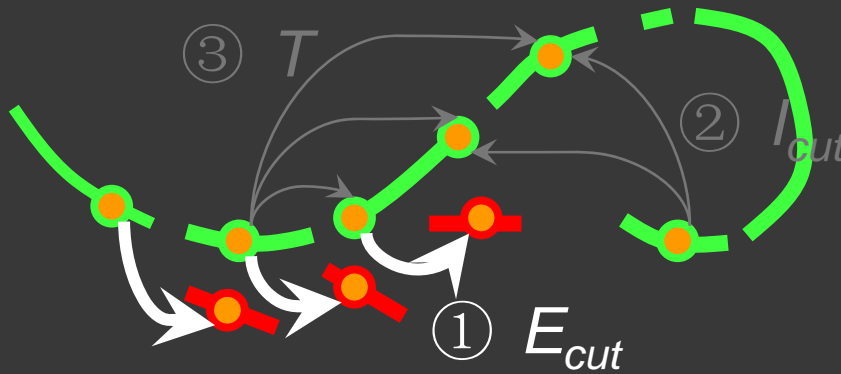
① External cut (E_{cut})

② Internal cut (I_{cut})

③ Tube size (T)

A discrete graph cut score useful for segmenting persistent cycles from continuous embedding space

External Cut

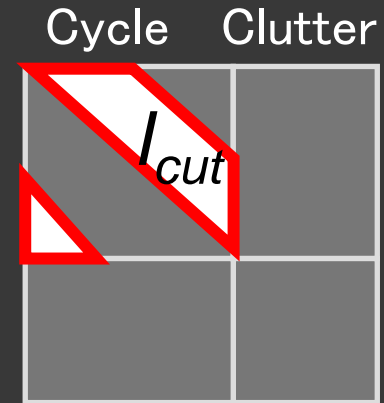
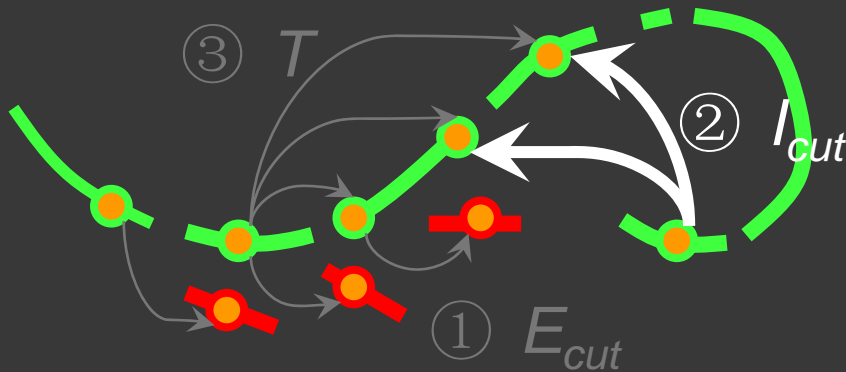


Cycle	Clutter
	E_{cut}

$$E_{cut}(S) = \frac{1}{|S|} \sum_{i \in S, j \in (V-S)} P_{ij}$$

- Cut cycle (S) from clutter ($V-S$)
- Similar to NCut (2D grouping)

Internal Cut



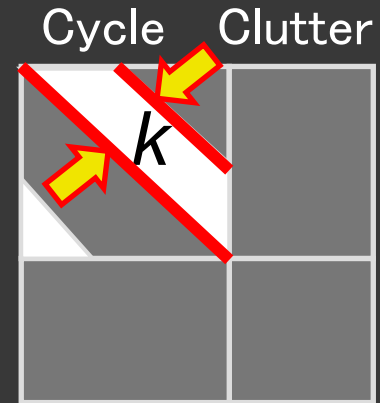
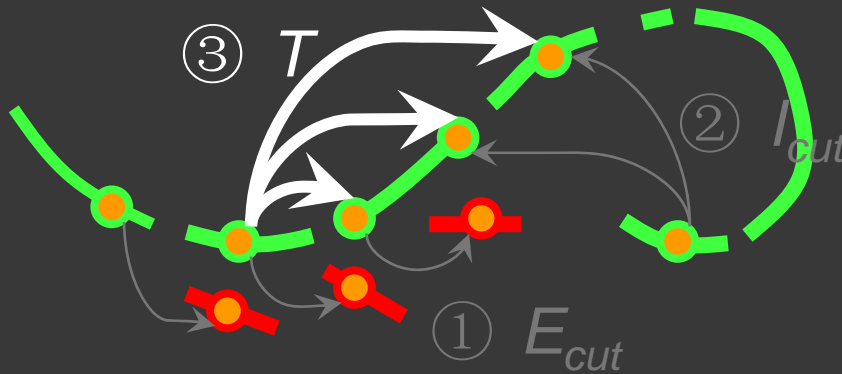
$$I_{cut}(S, O, k) = \frac{1}{|S|} \sum_{(O(i) \geq O(j)) \vee (O(j) \geq O(i) + k)} P_{ij}$$

Ordering

$O : S \mapsto S = \{1, 2, \dots, |S|\}$

Forward $0 < O(j) - O(i) \leq k$
 Backward $-|S|/2 \leq O(j) - O(i) \leq 0$
 Fast-forward otherwise

Tube Size



$$T(k) = k / |S|$$

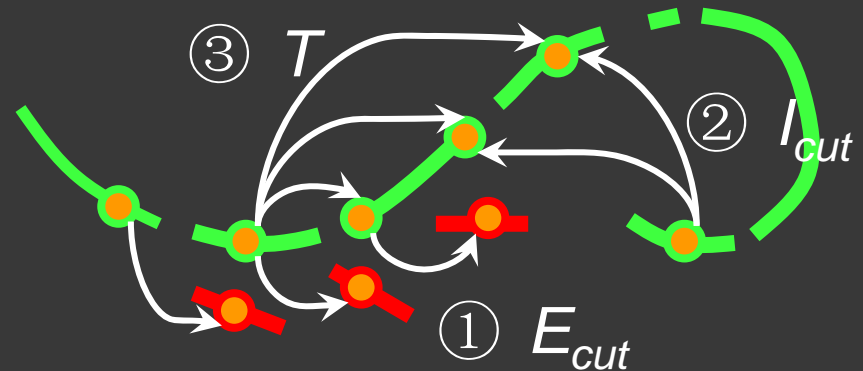
- Thickness: how fat is the cycle?
- Special cases
 - $k=1$ ideal case of a cycle
 - $k=|S|$ 2D structures

Combining Scores

Maximize Untangling Cycle Cut Score

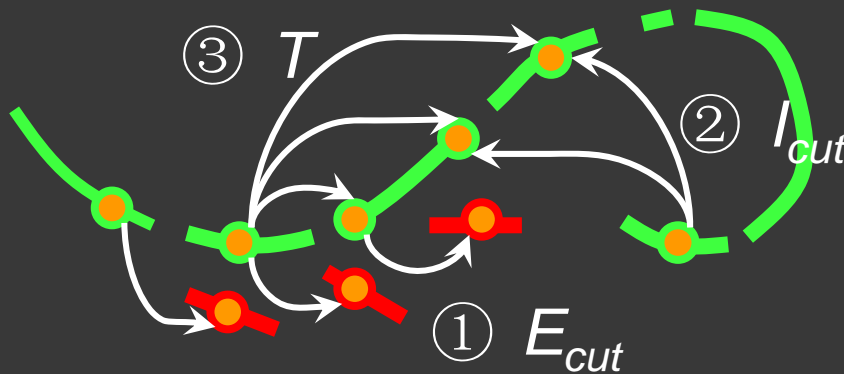
$$C_u(S, O, k) = \frac{1 - E_{cut}(S) - I_{cut}(S, O, k)}{T(k)}$$

- S Subset of graph nodes V
- O Cycle ordering on S
- k Cycle thickness

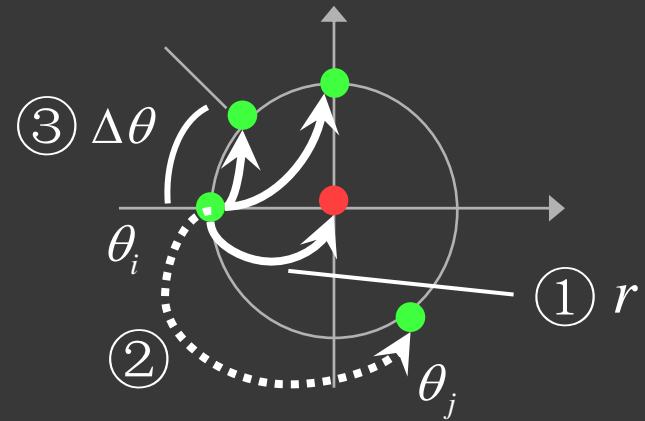


Cut Score Interpretation

Three untangling cycle criteria



Circular embedding



- ① External cut: $r \Leftrightarrow E_{cut}$
- ② Internal cut: $\theta \Leftrightarrow I_{cut}$
- ③ Tube size: $\Delta\theta \Leftrightarrow T$