

# Optimizations & Bounds for Sparse Symmetric Matrix-Vector Multiply

**Berkeley Benchmarking and Optimization Group (BeBOP)**  
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# Outline

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- **Performance Tuning Challenges**
- **Performance Optimizations**
  - Register Blocking
  - Matrix Symmetry
  - Multiple Vectors
- **Performance Bounds Models**
- **Experimental Evaluation**
  - 7.3x max speedup over reference (median: 4.2x)
- **Conclusions**

# Introduction & Background

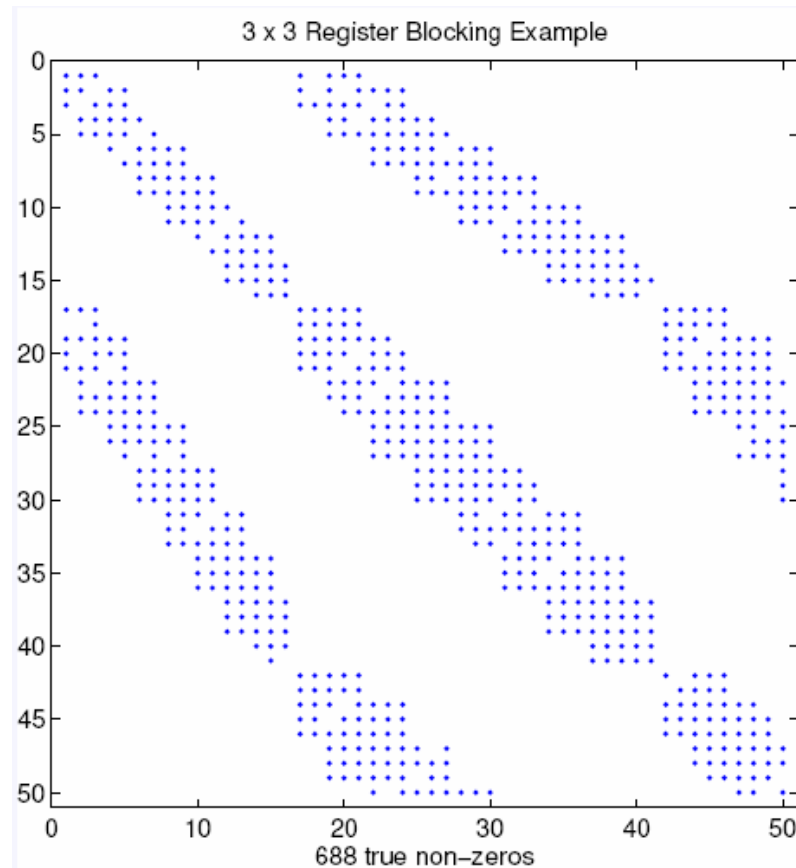
## ■ Computational Kernels

- Sparse Matrix-Vector Multiply (SpMV):  $y \leftarrow y + A \cdot x$ 
  - $A$ : Sparse matrix, symmetric (*i.e.*  $A = A^T$ )
  - $x, y$ : Dense vectors
- Sparse Matrix-Multiple Vector Multiply (SpMM):  $Y \leftarrow Y + A \cdot X$ 
  - $X, Y$ : Dense matrices

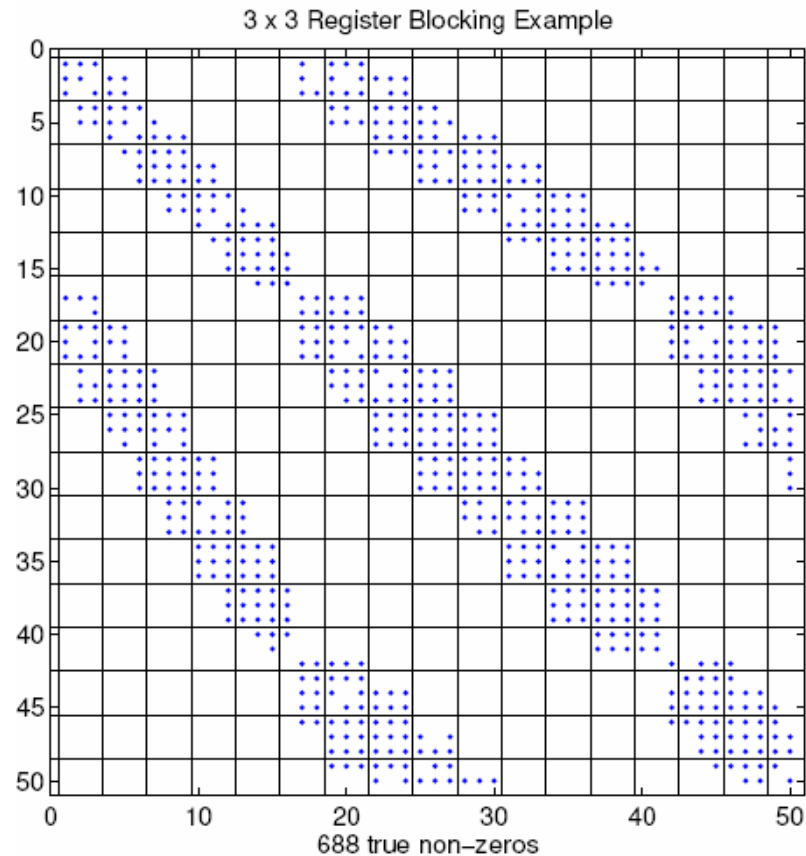
## ■ Performance Tuning Challenges

- Sparse code characteristics
  - High bandwidth requirements (matrix storage overhead)
  - Poor locality (indirect, irregular memory access)
  - Poor instruction mix (low ratio of flops to memory operations)
- SpMV performance less than 10% of machine peak
- Performance depends on kernel, matrix and architecture

# Optimizations: Register Blocking (1/3)

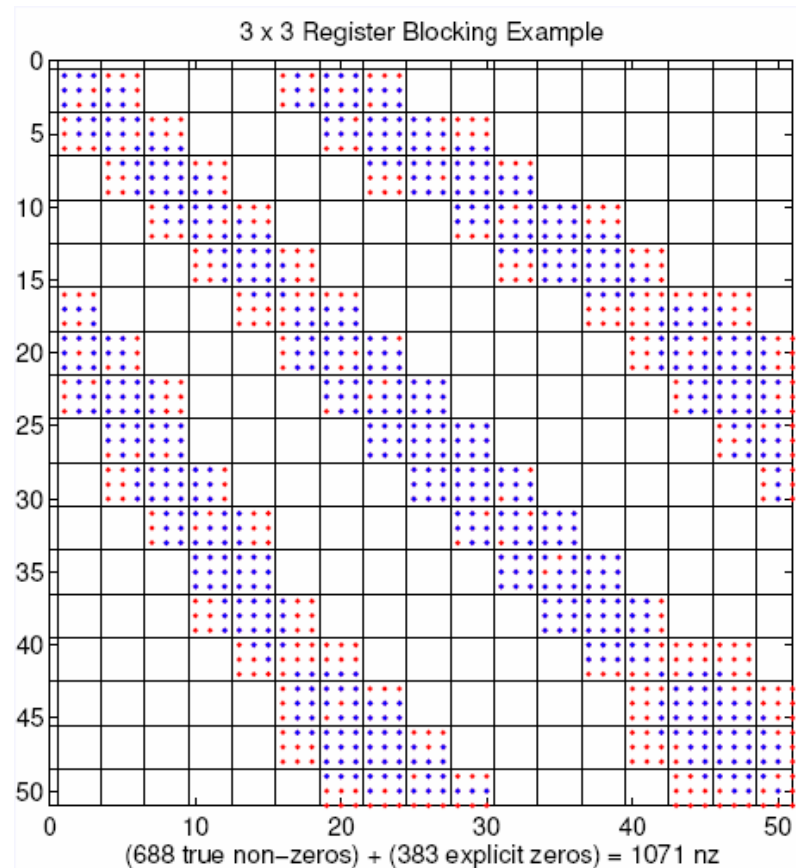


# Optimizations: Register Blocking (2/3)



- BCSR with uniform, aligned grid

# Optimizations: Register Blocking (3/3)



- Fill-in zeros: Trade extra flops for better blocked efficiency

# Optimizations: Matrix Symmetry

## ■ Symmetric Storage

- Assume compressed sparse row (CSR) storage
- Store half the matrix entries (*e.g.*, upper triangle)

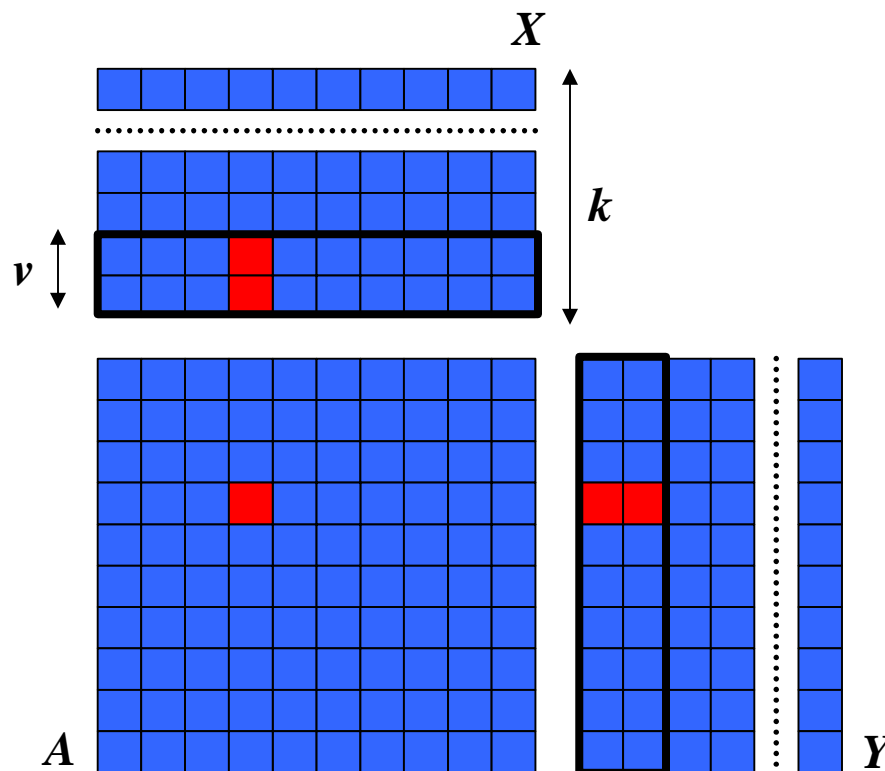
## ■ Performance Implications

- Same flops
- Halves memory accesses to the matrix
- Same irregular, **indirect** memory accesses
  - For each stored non-zero  $A(i, j)$ 
    - $y(i) += A(i, j) * x(j)$
    - $y(j) += A(i, j) * x(i)$
- Special consideration of diagonal elements

# Optimizations: Multiple Vectors

## ■ Performance Implications

- Reduces loop overhead
- Amortizes the cost of reading  $A$  for  $v$  vectors

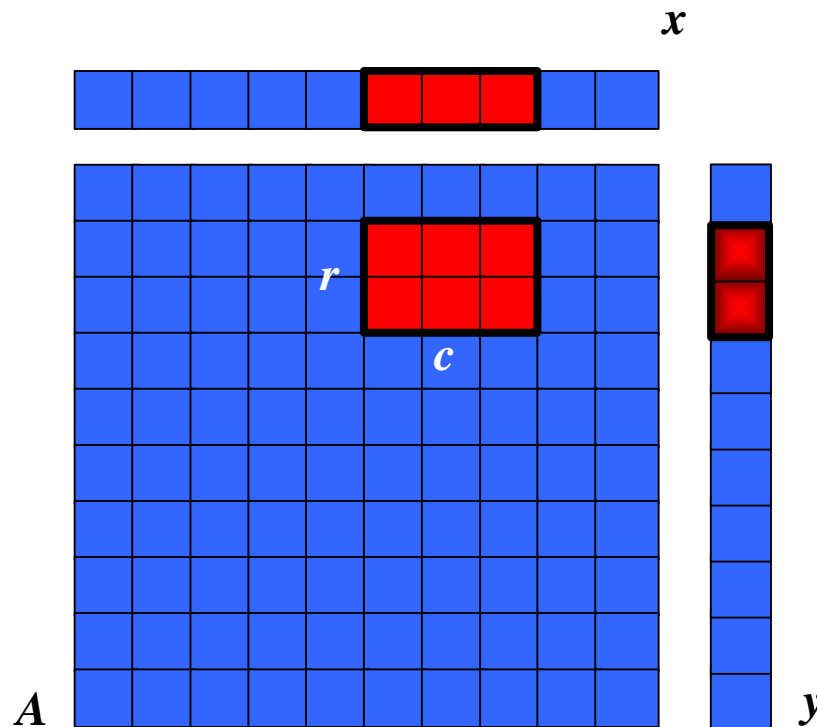




# Optimizations: Register Usage (1/3)

## ■ Register Blocking

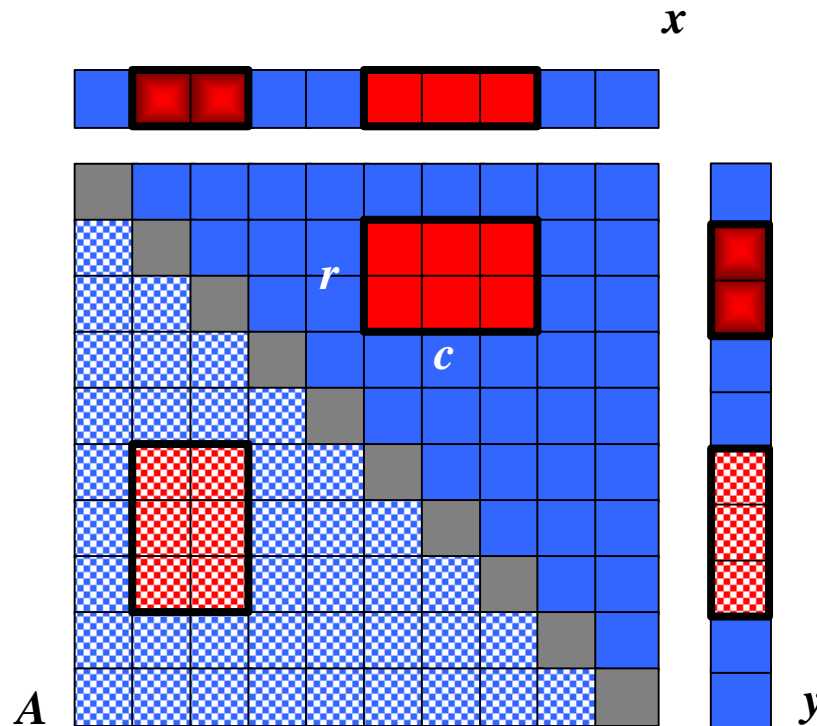
- Assume column-wise unrolled block multiply
- Destination vector elements in registers ( $r$ )



# Optimizations: Register Usage (2/3)

## ■ Symmetric Storage

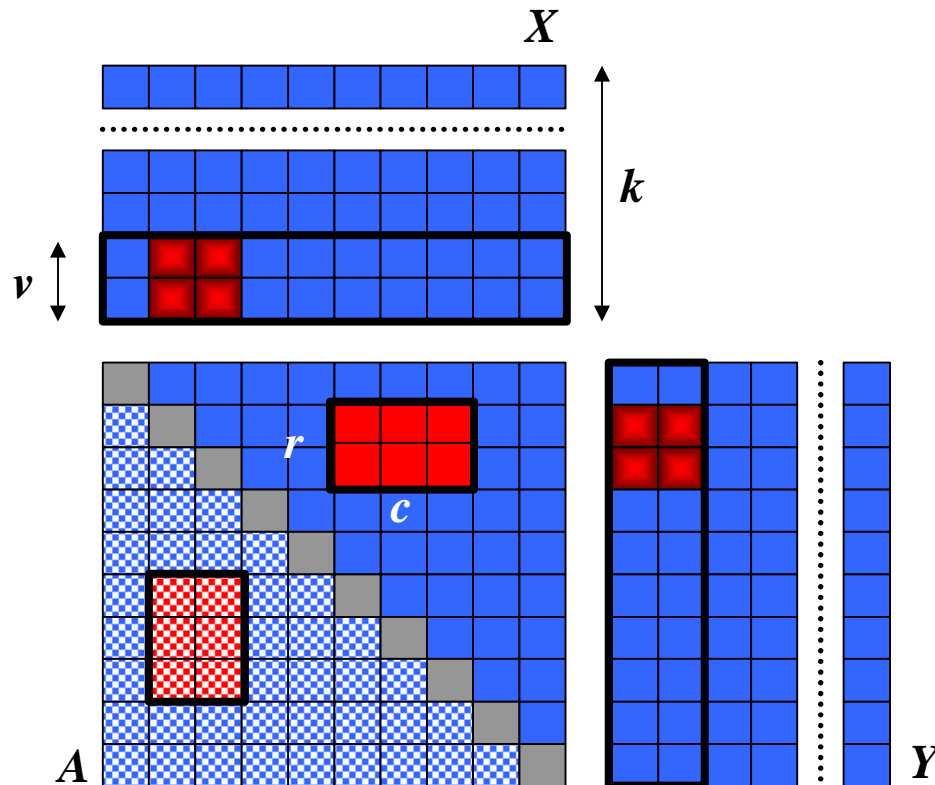
- Doubles register usage (  $2r$  )
  - Destination vector elements for stored block
  - Source vector elements for transpose block



# Optimizations: Register Usage (3/3)

- **Vector Blocking**

- Scales register usage by vector width ( $2rv$ )



# Performance Models

## ■ Upper Bound on Performance

- Evaluate quality of optimized code against bound

## ■ Model Characteristics and Assumptions

- Considers only the cost of memory operations
- Accounts for minimum effective cache and memory latencies
- Considers only compulsory misses (*i.e.* ignore conflict misses)
- Ignores TLB misses

## ■ Execution Time Model

- Cache misses modeled and verified with PAPI hardware counters
- Charge  $\mathbf{a}_i$  for hits at each cache level
  - $T = (L1\ hits) \mathbf{a}_1 + (L2\ hits) \mathbf{a}_2 + (Mem\ hits) \mathbf{a}_{mem}$
  - $T = (Loads) \mathbf{a}_1 + (L1\ misses)(\mathbf{a}_2 - \mathbf{a}_1) + (L2\ misses)(\mathbf{a}_{mem} - \mathbf{a}_2)$

# Evaluation: Methodology

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## ■ Four Platforms

- Sun Ultra 2i, Intel Itanium, Intel Itanium 2, IBM Power 4

## ■ Matrix Test Suite

- Twelve matrices
- Dense, Finite Element, Assorted, Linear Programming

## ■ Reference Implementation

- Non-symmetric storage
- No register blocking (CSR)
- Single vector multiplication

# Evaluation: Observations

## ■ Performance

- 2.6x max speedup (median: 1.1x) from symmetry
  - {Symmetric BCSR Multiple Vector} vs. {Non-Symmetric BCSR Multiple Vector}
- 7.3x max speedup (median: 4.2x) from combined optimizations
  - {Symmetric BCSR Multiple Vector} vs. {Non-symmetric CSR Single Vector}

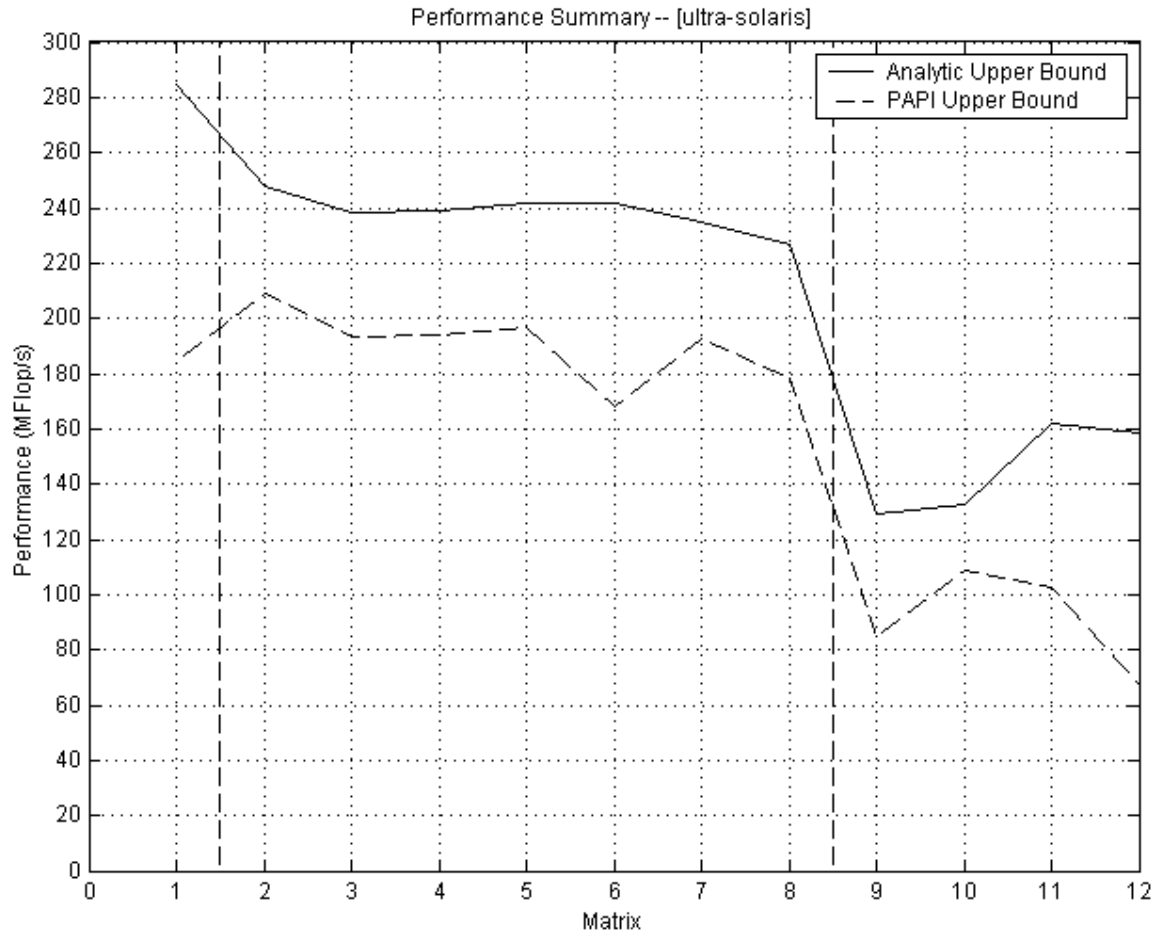
## ■ Storage

- 64.7% max savings (median: 56.5%) in storage
  - Savings > 50% possible when combined with register blocking
- 9.9% increase in storage for a few cases
  - Increases possible when register block size results in significant fill

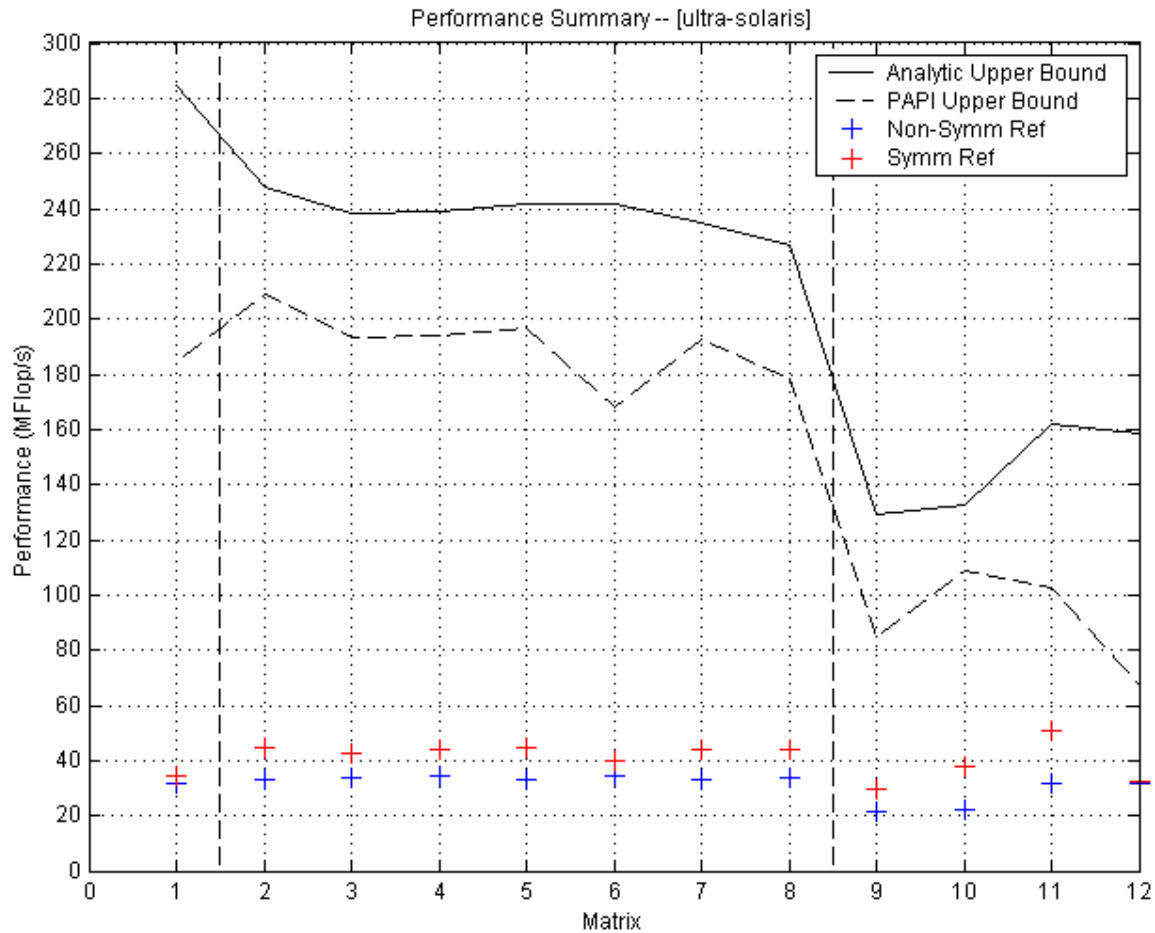
## ■ Performance Bounds

- Measured performance achieves 68% of PAPI bound, on average

# Performance Results: Sun Ultra 2i

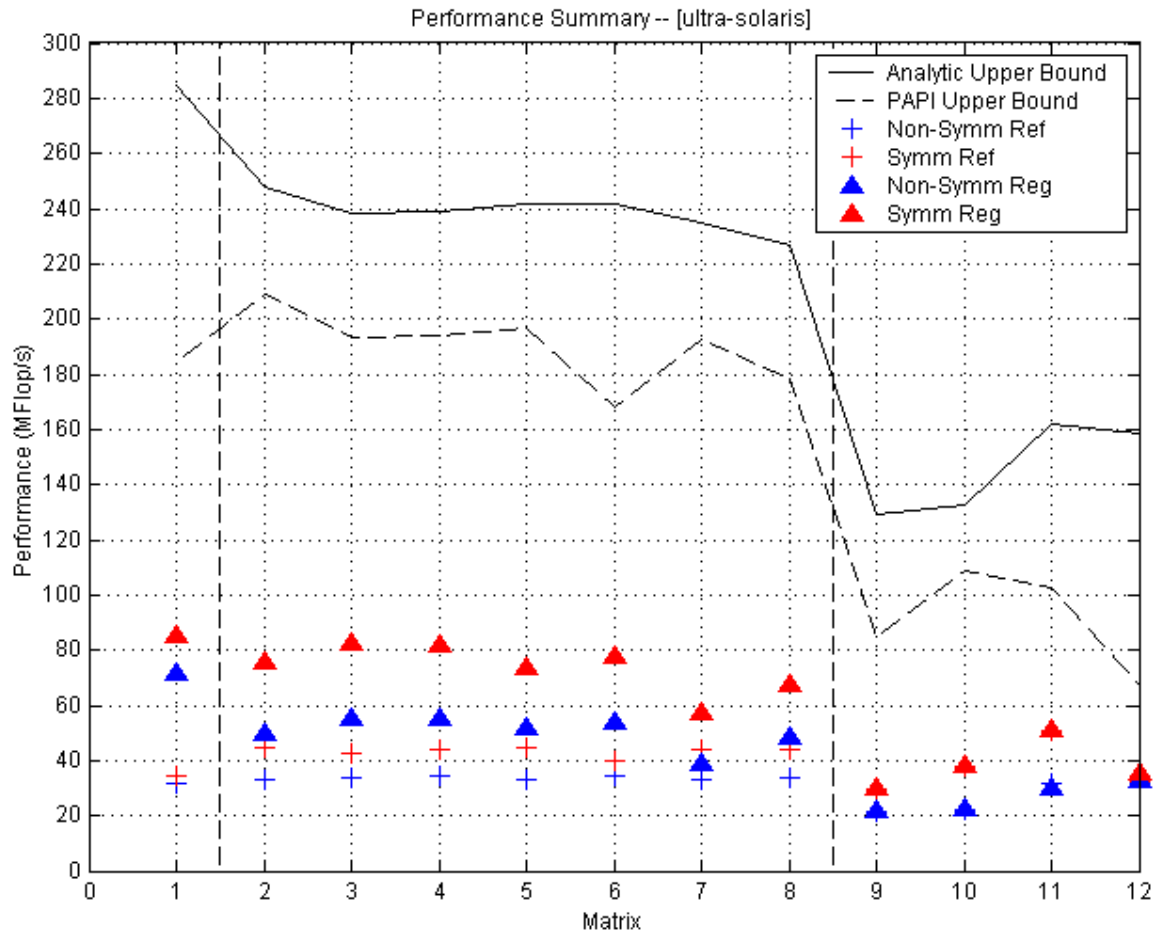


# Performance Results: Sun Ultra 2i

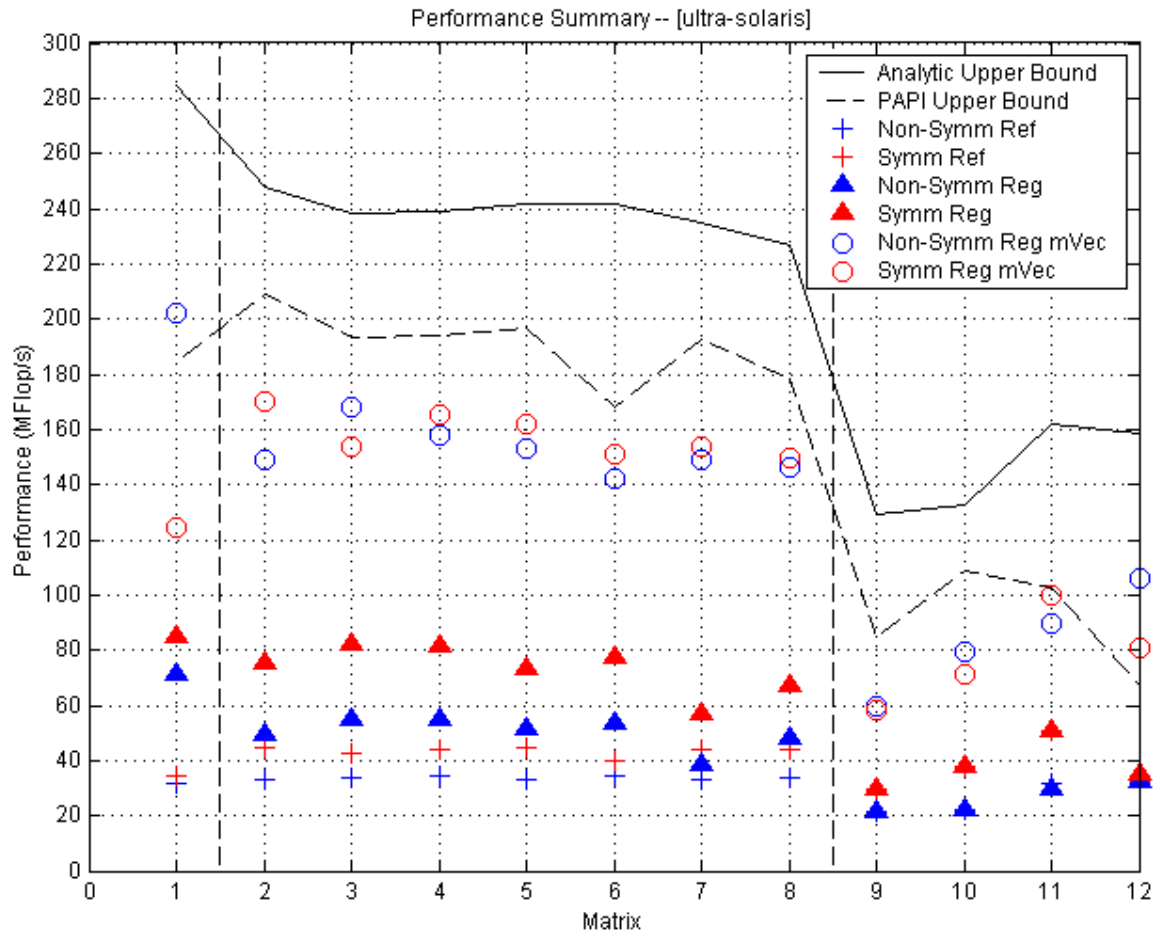




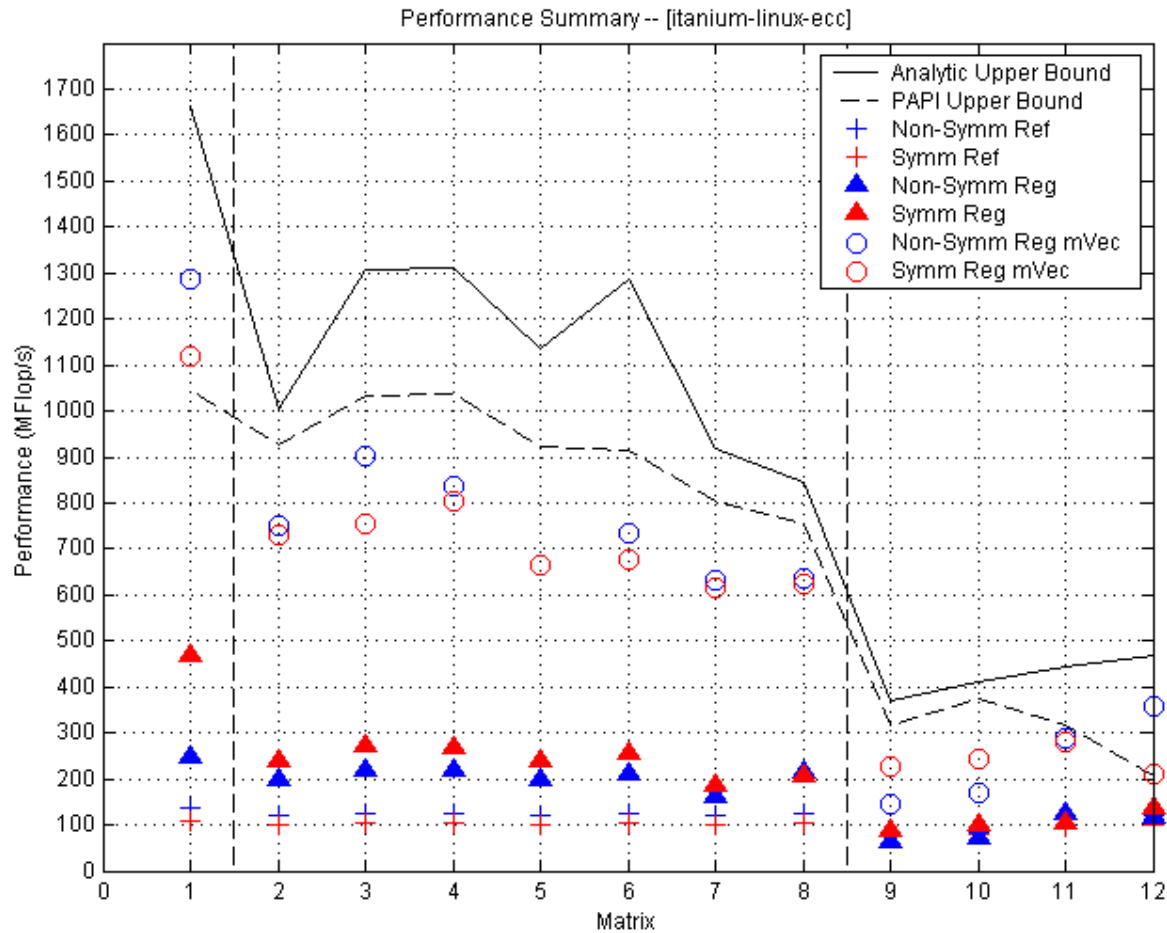
# Performance Results: Sun Ultra 2i



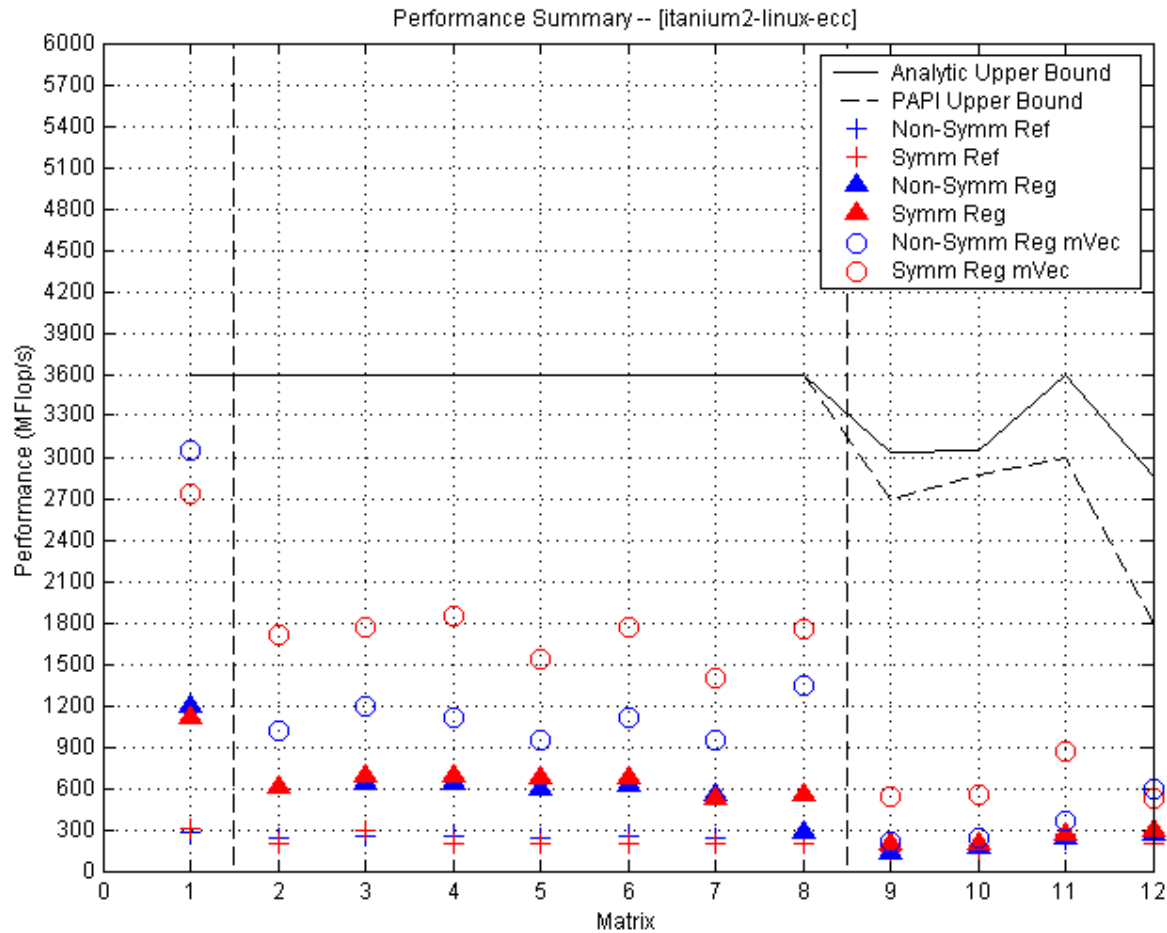
# Performance Results: Sun Ultra 2i



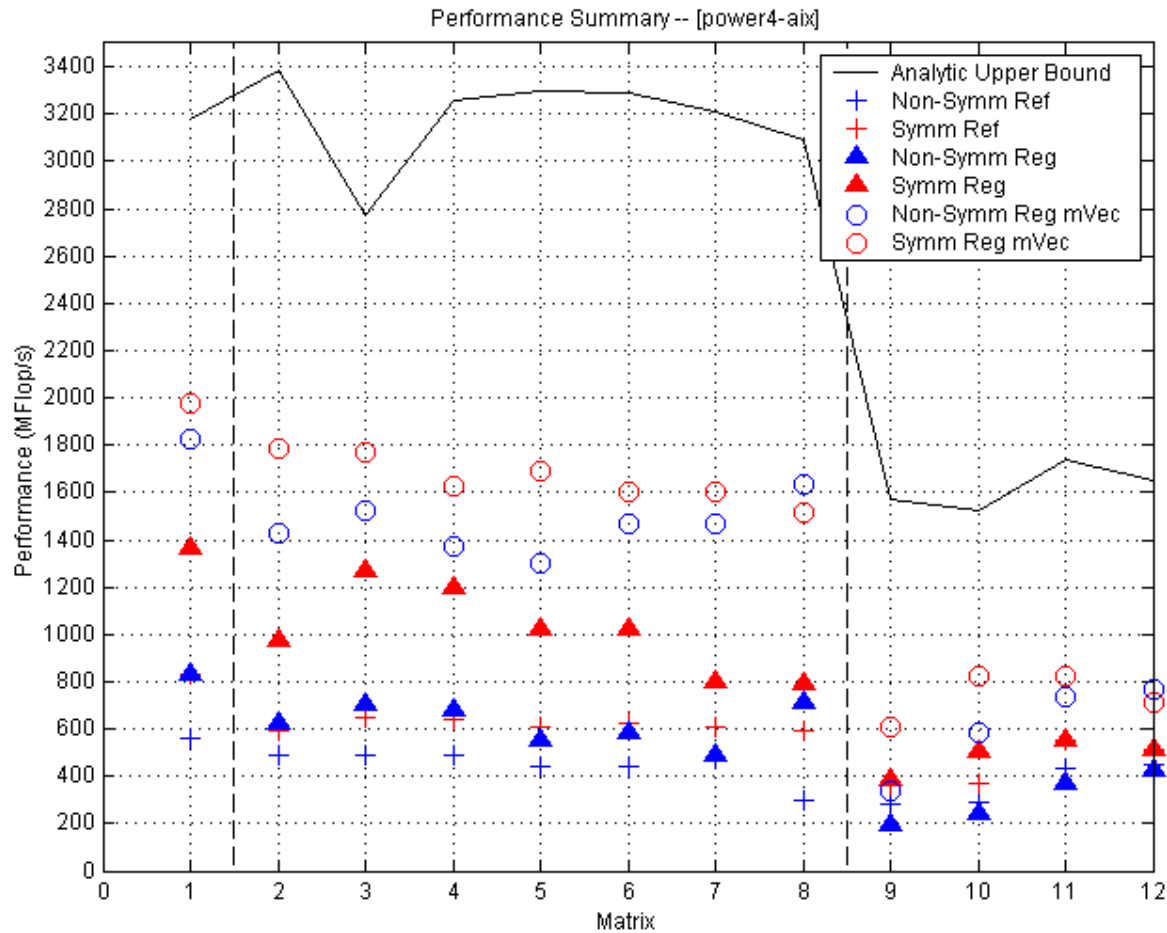
# Performance Results: Intel Itanium 1



# Performance Results: Intel Itanium 2



# Performance Results: IBM Power 4



# Conclusions

## ■ Matrix Symmetry Optimizations

- Symmetric Performance: 2.6x speedup (median: 1.1x)
  - {Symmetric BCSR Multiple Vector} vs. {Non-Symmetric BCSR Multiple Vector}
- Overall Performance: 7.3x speedup (median: 4.15x)
  - {Symmetric BCSR Multiple Vector} vs. {Non-symmetric CSR Single Vector}
- Symmetric Storage: 64.7% savings (median: 56.5%)
- Cumulative performance effects
- Trade-off between optimizations for register usage

## ■ Performance Modeling

- Models account for symmetry, register blocking, multiple vectors
- Gap between measured and predicted performance
  - Measured performance is 68% of predicted performance (PAPI)
  - Model refinements are future work

# Current & Future Directions

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## ■ Heuristic Tuning Parameter Selection

- Register block size and vector width chosen independently
- Heuristic to select parameters simultaneously

## ■ Automatic Code Generation

- Automatic tuning techniques to explore larger optimization spaces
- Parameterized code generators

## ■ Related Optimizations

- Symmetry (Structural, Skew, Hermitian, Skew Hermitian)
- Cache Blocking
- Field Interlacing

# Appendices

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# Related Work

## ■ Automatic Tuning Systems and Code Generation

- PHiPAC [BACD97], ATLAS [WPD01], SPARSITY[Im00]
- FFTW [FJ98], SPIRAL[PSVM01], UHFFT[MMJ00]
- MPI collective ops (Vadhiyar, *et al.* [VFD01])
- Sparse compilers (Bik [BW99], Bernoulli [Sto97])

## ■ Sparse Performance Modeling and Tuning

- Temam and Jalby [TJ92]
- Toledo [Tol97], White and Sadayappan [WS97], Pinar [PH99]
- Navarro [NGLPJ96], Heras [HPDR99], Fraguera [FDZ99]
- Gropp, *et al.* [GKKS99], Geus [GR99]

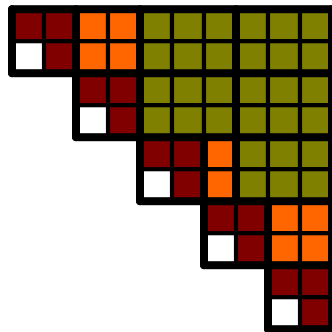
## ■ Sparse Kernel Interfaces

- Sparse BLAS Standard [BCD+01]
- NIST SparseBLAS [RP96], SPARSKIT [Saa94], PSBLAS [FC00]
- PETSc

# Symmetric Register Blocking

## ■ Square Diagonal Blocking

- Adaptation of register blocking for symmetry
- Register blocks –  $r \times c$ 
  - Aligned to the right edge of the matrix
- Diagonal blocks –  $r \times r$ 
  - Elements below the diagonal are not included in diagonal block
- Degenerate blocks –  $r \times c'$ 
  - $c' < c$  and  $c'$  depends on the block row
  - Inserted as necessary to align register blocks



**Register Blocks –  $2 \times 3$**

**Diagonal Blocks –  $2 \times 2$**

**Degenerate Blocks – Variable**

# Multiple Vectors Dispatch Algorithm

## ■ Dispatch Algorithm

- $k$  vectors are processed in groups of the vector width ( $v$ )
  - SpMM kernel contains  $v$  subroutines:  $SR_i$  for  $1 = i = v$
  - $SR_i$  unrolls the multiplication of each matrix element by  $i$
- Dispatch algorithm, assuming vector width  $v$ 
  - Invoke  $SR_v$ ,  $\text{floor}(k/v)$  times
  - Invoke  $SR_{k\%v}$  once, if  $k\%v > 0$

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