ECE552 / CPS550 Advanced Computer Architecture I

Lecture 1 Introduction

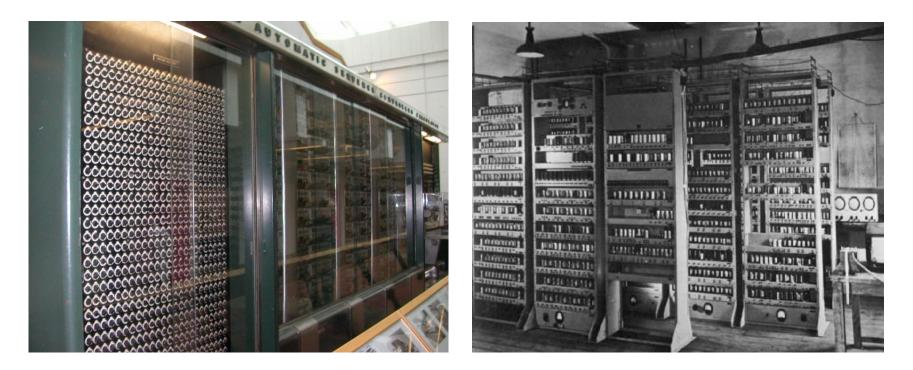
Benjamin Lee Electrical and Computer Engineering Duke University

www.duke.edu/~bcl15 www.duke.edu/~bcl15/class/class_ece552fall12.html



Mark I Harvard University, 1944

EDSAC University of Cambridge, 1949



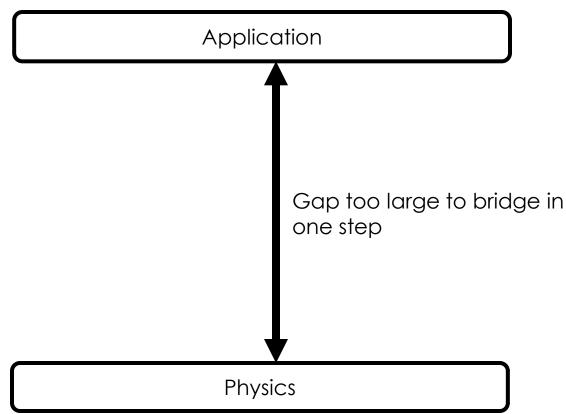


iPad Apple/ARM, 2010 Blue Gene/P IBM, 2007





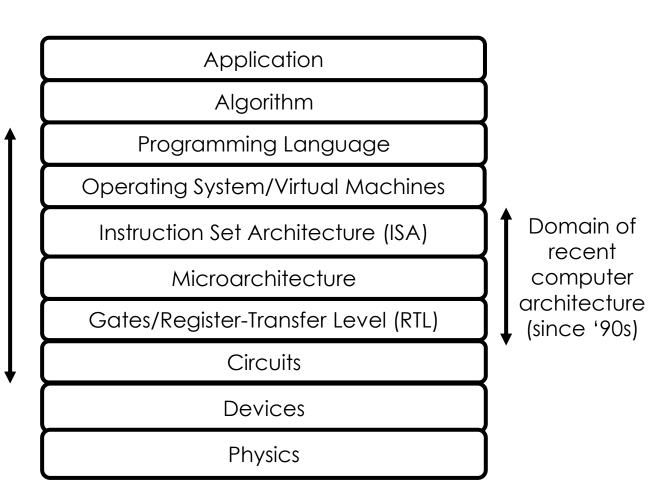




Computer architecture is the <u>design of abstraction layers</u>, which allow efficient implementations of computational applications on available technologies



Domain of early computer architecture ('50s-'80s)





Architect Systems

- Coordinate technology, hardware, run-time software, compilers, apps
- Responsible for end-to-end functionality

Design and Analyze

- Search the space of possible designs at all levels in computer system
- Evaluate designs with quantitative metrics (performance, power, cost)

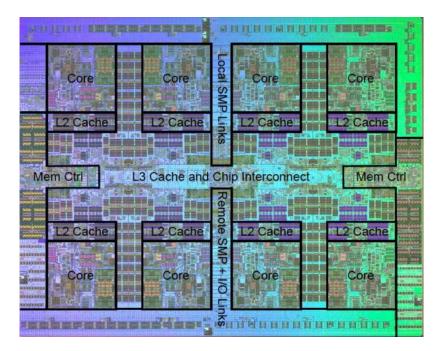
Navigate Computing Landscape

- Architects work at the hardware-software interface
- Technologies are emerging
- Applications are demanding
- Systems are scaling



In-order Datapath (built, ECE152)

Chip Multiprocessors (understand, experiment ECE552)





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TeachingMarisabel Guevara, mg@cs.duke.eduAssistantsOffice Hours: Tu 12:25-1:25pm, W 4-5pm, TBD

Weidan Wu, ww53@duke.edu Office Hours: M 4-5pm, Th 2:40-3:40pm, TBD

Lectures Tu/Th 1:25-2:40PM, 208 Hudson

TextComputer Architecture: A Quantitative Approach,
5th Edition (2012). Do not use earlier editions

Web http://www.duke.edu/~BCL15/class/class_ece552fall12.html



Participation

- Electrical and Computer Engineering, Computer Science
- PhD, MS, Undergraduates

Prerequisites

- Introduction to computer architecture (CPS 104, ECE 152, or equiv.)
- Programming (homework/projects in C, C++)

Background Knowledge

- Instruction sets, computer arithmetic, assembly programming D.A. Patterson and J.L. Hennessy. Computer Organization and Design: The Hardware/Software Interface, 5th Edition.

Dropping the Course

- if you are going to drop, please do so early



1. Design Metrics

- 1. Performance
- 2. Power
- 3. Early machines
- 2. Simple Pipelining
 - 1 Multi-cycle machines
 - 2 Branch Prediction
 - 3 In-order Superscalar
 - 4 Optimizations
- 3. Complex Pipelining
 - 1 Score-boarding, Tomasulo Algorithm
 - 2 Out-of-order Superscalar

Midterm Exam Fall Break

4. Memory Systems

- 1 Caches
- 2 DRAM
- 3 Virtual Memory
- 5. Explicitly Parallel Architectures
 - 1 VLIW
 - 2 Vector machines
 - 3 Multi-threading
- 6. Multiprocessors
 - 1 Memory Models
 - 2 Coherence Protocols
- 7. Advanced Topics
 - 1 Emerging Technologies
 - 2 Specialized Architectures
 - 3 Datacenter Architectures



30% Homework and Readings

- Homework done in teams of 3
- 5 classes dedicated to paper discussions
- 15% Midterm exam
 - 75 minutes (in class), closed book
- 25% Final exam
 - 3 hours, closed-book
 - based on lectures, problem sets, readings
- 30% Term project/paper
 - Project done in teams of 3

Academic Policy

University policy as codified by Duke Undergraduate Honor Code will be strictly enforced. Zero tolerance for cheating and/or plagiarism.



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If a student is suspect of academic dishonesty (e.g., cheating on an exam, copying a lab report, collaborating inappropriately on an assignment), faculty are required to report the matter to the Office of Student Conduct.

A student found responsible for academic dishonesty faces formal disciplinary action, which may include suspension. A student suspended twice for academic dishonesty automatically faces a minimum 5-year separation from Duke University.



Scope

- Semester-long research project
- Teams of 3
- Students propose project ideas (Oct 14)

Final Paper

- 6-12 page research paper
- Evaluate research idea quantitatively
- Survey and cite related work



11 September – Homework #1 Due

Assignment on web page. Teams of 2-3. Submit hard copy in class. Email code to TA's

11 September – Class Discussion

Roughly one reading per class. Do not wait until the day before!

- 1. Hill et al. "Classic machines: Technology, implementation, and economics"
- 2. Moore. "Cramming more components onto integrated circuits"
- 3. Radin. "The 801 minicomputer"
- 4. Patterson et al. "The case for the reduced instruction set computer"
- 5. Colwell et al. "Instruction sets and beyond: Computers, complexity, controversy"



Definitions

- Latency: time to finish given task (a.k.a. execution time)
- Throughput: number of tasks in given time (a.k.a. bandwidth)
- Throughput can exploit parallelism while latency cannot

Example: Move people from Duke to UNC, 10 miles

- Car: capacity = 5, speed = 60 miles/hour
- Bus: capacity = 60, speed = 20 miles/hour
- Latency(car) = (10 miles @ 60 miles/hour)= 10 minutes
- Latency(bus) = (10 miles @ 20 miles/hour) = 30 minutes
- Throughput(car) = (3 trips @ 60 miles per hour) = 15 people/hour
- Throughput(bus) = (1 trip @ 20 miles per hour) = 60 people/hour



Measuring Performance

- Target Workload: accurate but not portable
- Representative Benchmark: portable but not accurate
- Microbenchmark: small, fast code sequences but incomplete

Representative Benchmarks

- SPEC (Standard Performance Evaluation Corporation, <u>www.spec.org</u>)
- Collects, standardizes, distributes benchmark programs
- Parallel Benchmarks
- Scientific and commercial computing
- SPLASH-2, NAS, SPEC OpenMP, SPECjbb
- Transaction Processing Council (TPC)
- Online transaction processing (OLTP) with heavy I/O, memory
- TPC-C, TPC-H, TPC-W



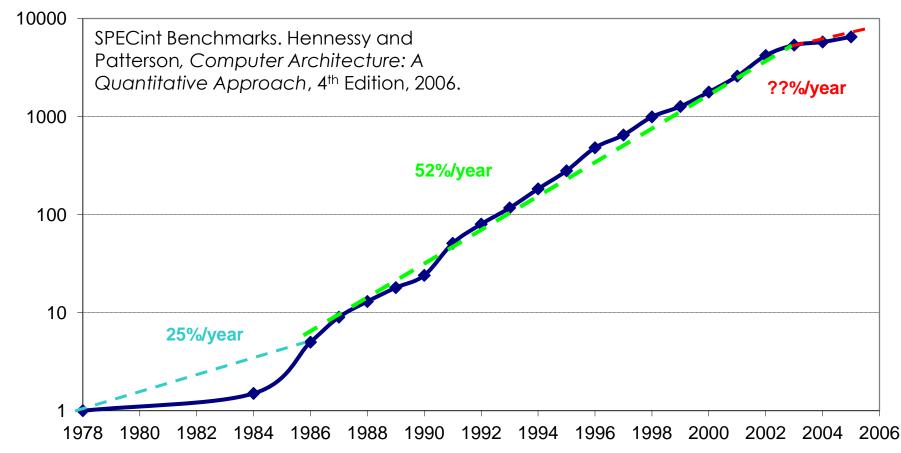
Addition

- Latency is additive but throughput is not
- Example: Consider applications A1 and A2 on processor P
- Latency(A1,A2) = Latency(A1) + Latency(A2)
- Throughput (A1,A2) = 1/[1/Throughput(A1) + 1/Throughput(A2)]

Averages

- Arithmetic Mean: (1/N) * $\sum_{P=1..N}$ Latency(P)
- For measures that are proportional to time (e.g., latency)
- Harmonic Mean: N / $\sum_{P=1..N}$ 1/Throughput(P)
- For measures that are inversely proportional to time (e.g., throughput)
- Geometric Mean: $(\prod_{P=1..N} \text{Speedup}(P)) \land (1/N)$
- For ratios (e.g., speed-ups)







Latency = (Instructions / Program) x (Cycles / Instruction) x (Seconds / Cycle)

Seconds / Cycle

- Technology and architecture
- Transistor scaling
- Processor microarchitecture

Cycles / Instruction (CPI)

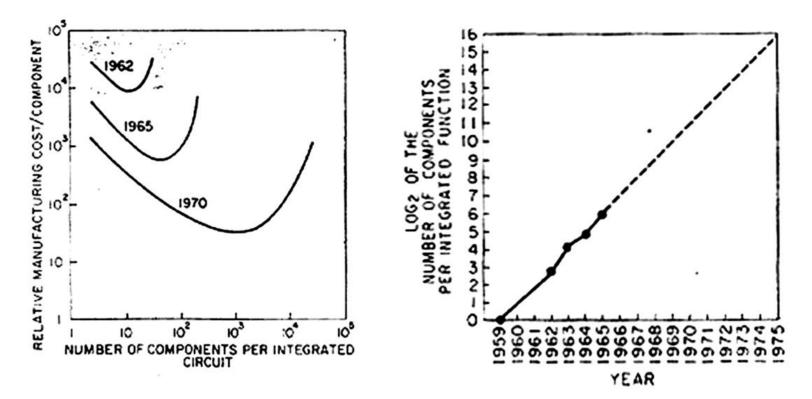
- Architecture and systems
- Processor microarchitecture
- System balance (processor, memory, network, storage)

Instructions / Program

- Algorithm and applications
- Compiler transformations, optimizations
- Instruction set architecture



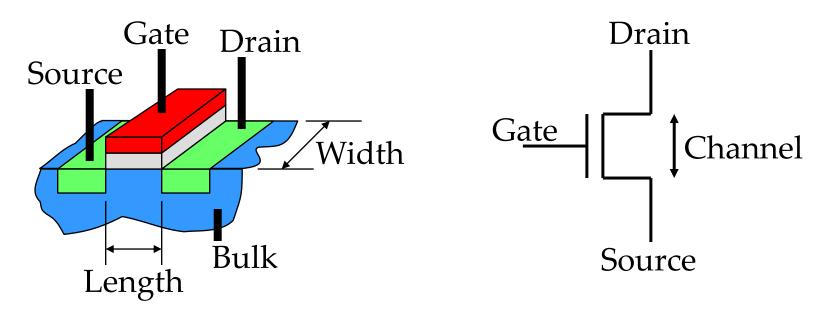
- Moore. "Cramming more components onto integrated circuits." Electronics, Vol 38, No. 8, 1965.
- As integration increases and packaging cost decrease
- How does Moore's Law impact performance?





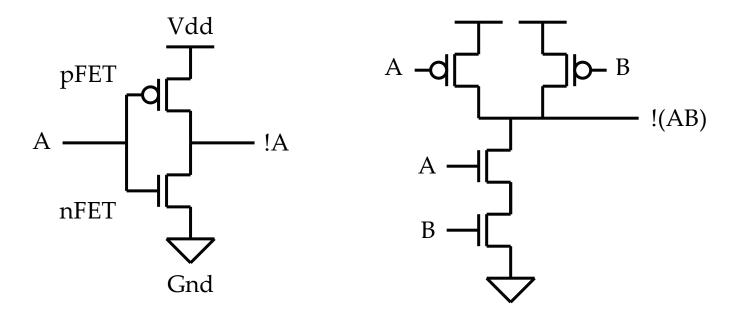
MOSFET

- MOS: metal-oxide semiconductor
- FET: field-effect transistor
- Charge carriers flow between source-drain
- Flow controlled by gate voltage
- Abstract MOSFET as electrical switch



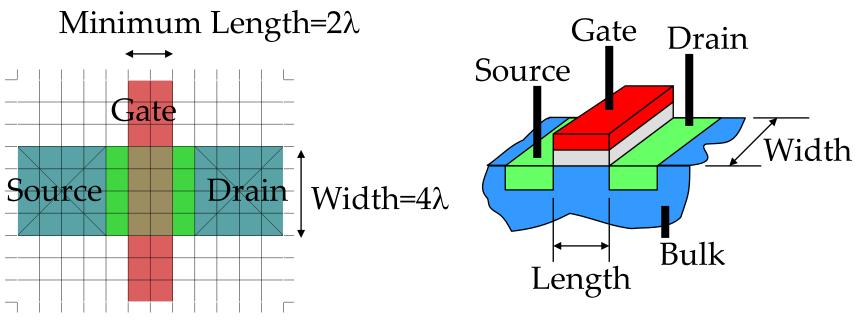


- Voltages map to logical values (Vdd=1, Gnd=0)
- Implement complementary Boolean logic
- nFET: conduct charge when Vg = Vdd, used in pull-down network
- pFET: conduct charge when Vg = Gnd, used in pull-up network
- Examples: Inverter, NAND (universal, any logic function via De Morgan's Law)





- Process defined by feature size (F), layout design ($\lambda = F/2$)
- Example: $F=2\lambda = 45nm$ process technology
- Transistor dimensions determine technology performance
- Transistor drive strength (i.e., performance) increases as channel length shrinks





- Dennard et al. "Design of ion-implanted MOSFETs with very small physical dimensions," Journal Solid State Circuits, 1974.
- Scale not only dimensions but also doping concentration and voltage
- Transistors become faster (1.4x)
- Applied to Moore's Law: k=1.4, 1/k = 0.7 every 18-24 months

Gate Drain	TABLE I Scaling Results for Circuit Performance	
	Device or Circuit Parameter	Scaling Factor
Width Bulk Length	Device dimension t_{ox} , L, W Doping concentration N_a Voltage V Current I Capacitance $\epsilon A/t$ Delay time/circuit VC/I Power dissipation/circuit VI Power density VI/A	$1/\kappa$ κ $1/\kappa$ $1/\kappa$ $1/\kappa$ $1/\kappa^2$ 1



- Horowitz et al. "Scaling, power, and the future of CMOS." IEDM, 2005.
- Classical Dennard scaling ended at 130nm in 2000-2001.
- Oxide Thickness: How to manage increasing leakage? Use high-K dielectrics
- Channel Length: How to manage increasing leakage? Stop scaling L
- Doping Concentration: How to handle imprecise doping? Manage variability
- Voltage: How to manage increasing leakage? Stop scaling V
- Current: How to increase current with shrinking channels? Stress silicon
- Example: Intel 22nm process technology with FinFET

TABLE I

Device or Circuit Parameter	Scaling Factor
Device dimension t_{ox} , L, W	1/κ
Doping concentration N_a	κ
Voltage V	$1/\kappa$
Current I	$1/\kappa$
Capacitance $\epsilon A/t$	$1/\kappa$
Delay time/circuit VC/I	$\frac{1}{\kappa}$
ower dissipation/circuit VI	$1/\kappa^2$
Power density VI/A	1

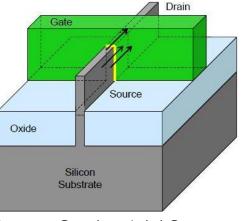
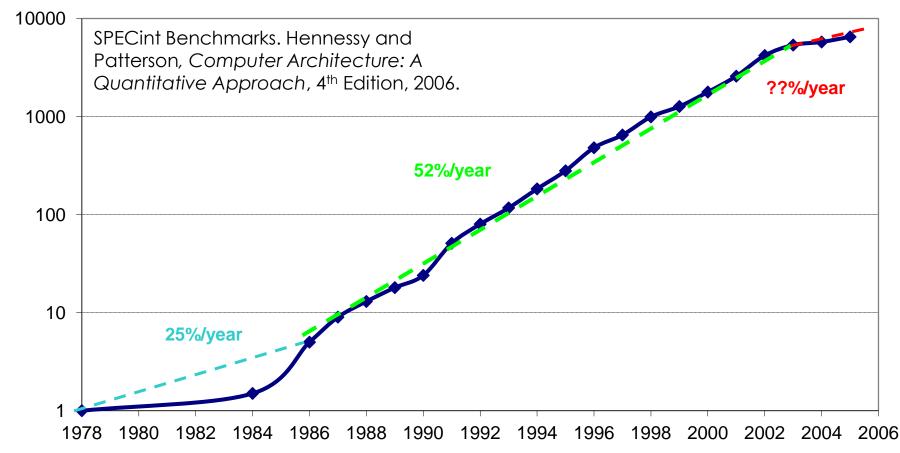


Image: Courtesy Intel Corp.

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Seconds / Cycle

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Cycles / Instruction (CPI)

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Instructions / Program

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Average Instruction Latency

- Examine instruction frequency
- Different instructions require different number of cycles
- Example: Integer instructions (1 cy), Floating-point instruction (>10 cy)
- CPI is slightly easier to calculate than IPC (time versus rate)

Example

- Instruction frequency: 1/3 INT, 1/3 FP, 1/3 MEM operations
- Instruction cycles: 1cy INT, 3cy FP, 2cy MEM
- $-CPI = (1/3 \times 1) + (1/3 \times 3) + (1/3 \times 2)$

Caveat

- CPI provides high-level, quick estimates of performance
- Does not account for details (e.g., instruction dependences)



Baseline Processor / Application

- Integer ALU: 50%, 1 cycle
- Load: 20%, 5 cycle
- Store: 10%, 1 cycle
- Branch: 20%, 2 cycle

Possible Enhancements

- Option 1: Branch prediction to reduce branch cost to 1 cycle
- Option 2: Bigger data cache to reduce load cost to 3 cycles
- Which enhancement would we prefer?

Cycles Per Instruction

- $-Base = (0.5 \times 1) + (0.2 \times 5) + (0.1 \times 1) + (0.2 \times 2) = 2 \text{ cycles}$
- Option 1 = $(0.5 \times 1) + (0.2 \times 5) + (0.1 \times 1) + (0.2 \times 1) = 1.8$ cycles
- Option 1 = $(0.5 \times 1) + (0.2 \times 3) + (0.1 \times 1) + (0.2 \times 2) = 1.6$ cycles



Physical Measurements

- Measure wall clock time as application runs
- Multiply time by clock frequency to get cycles
- Profile application with hardware counters (e.g., Intel VTune)

Simulated Measurements

- Cycle-level, microarchitectural simulation (e.g., SimpleScalar)
- Run applications on simulated hardware
- Track instructions as they progress through the design



Ignoring Instructions per Program

- Neglect dynamic instruction count
- Misleading if working in algorithms, compilers, or ISA

Using Instructions per Second

- MIPS = (Instructions / Cycle) x (Cycles / Second) x 1E-6
- FLOPS: considers only floating-point instructions
- Example: CPI = 2, clock frequency = 500MHz, 250 MIPS
- Example: compiler removes instructions, latency falls, MIPS increases

Using Clock Frequency

- Cannot equate clock frequency with performance
- Proc A: CPI = 2, f = 500MHz
- Proc B: CPI = 1, f = 300MHz
- Given the same ISA and compiler, B is faster



- Amdahl. "Validity of the single-processor approach..." AFIPS, 1967.

Make Common Case Fast

Consider improving <u>fraction F</u> of system with a <u>speedup S</u>.

T(new) = T(base) x (1-F) + T(base) x F / S

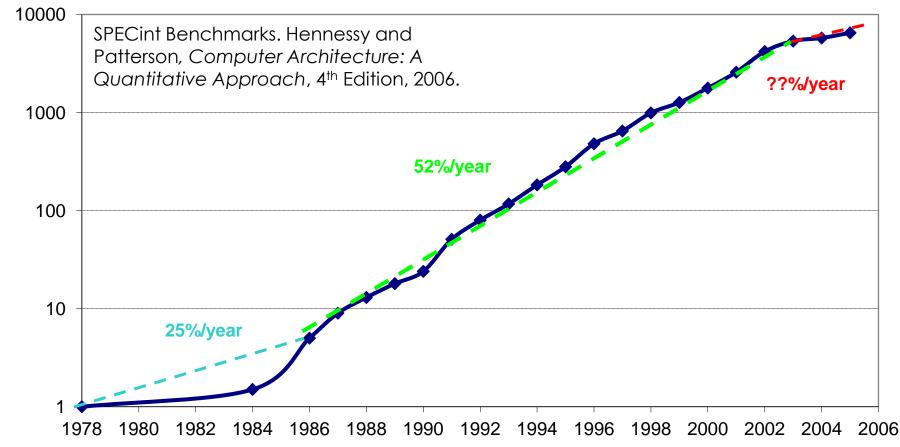
= T(base) x [(1-F) + F/S]

Speedup	= 1 / [(1-F) + F/S] = T(base)/T(new)
Max Speedup	= 1 / (1 – F)

Example

- Suppose FP computation is 1/4 of an application's execution time
- Maximum benefit from optimizing FP unit is 1.3x (=1/0.75)
- Multiprocessor systems were original application of this law
- Accounts for diminishing marginal returns







Definitions

- Energy (Joules) = $a \times C \times V^2$
- Power (Watts) = $a \times C \times V^2 \times f$

Power Factors and Trends

- activity (a): function of application resource usage
- capacitance (C): function of design; scales with area
- voltage (V): constrained by leakage, which increases as V falls
- frequency (f): varies with pipelining and transistor speeds
- Models in cycle-accurate simulators (e.g., Princeton Wattch)

Dynamic Voltage and Frequency Scaling (DVFS)

P-states: move between operational modes with different V, f
 Intel TurboBoost: increase V, f for short durations without violating thermal design point (TDP)



Temperature

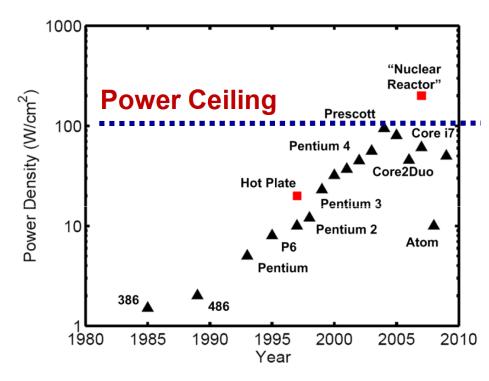
- Power density (Watts / sq-mm) is proxy for thermal effects

- Estimate thermal conductivity and resistance to understand processor hot spots (e.g., University of Virginia, HotSpot simulator)

Power Budgets

- Higher power budgets increase packaging cost

- 130W servers, 65W desktops, 10-30W laptops, 1-2W hand-held





Definitions

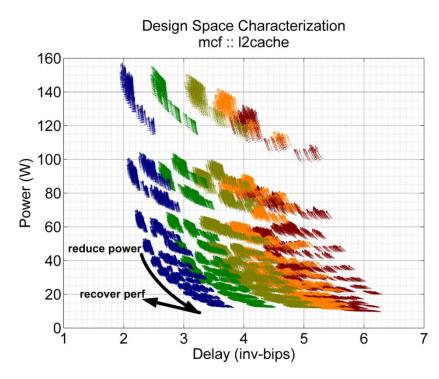
Historically, multiprocessors use multiple packages (e.g., IBM Power 3)
Chip multi-processor integrates multiple

cores on the same die

Multiprocessor Efficiency

- Reduce power with simpler cores

- Recover lost performance with many core parallelism (e.g., IBM Power 4)





Lower voltages, frequencies

- Voltage, frequency scale together (approximately)
- Power proportional to V², f (falls cubically)
- Performance proportional to f (falls linearly)

Example

- Baseline: 1-core at V, f
- Multiprocessor: 4-cores at 0.85V, 0.85f; program is 75% parallel
- 1-Core Power
 0.61x = 0.85³

 1-Core Performance
 0.85x
- Power impact
- Performance adjusted for parallelism
- Performance adjusted for freq slowdown

2.44x = 0.61x 4 2.28x = 1/[0.25 + (0.75 / 4)] 1.94x = 2.28 x 0.85

- Multiprocessor: 1.5% power per 1% performance (=144%/94%)
- Higher V, f: 3% power per 1% performance (=(1.01³-1)/(1.01-1))

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Non-recurring Engineering (NRE)

- Dominated by engineer-years (\$200K per engineer-year)
- Mask costs (>\$1M per spin)

Chip Cost

- Depends on wafer and chip size, process maturity

Packaging Cost

- Depends on number of pins (e.g., signal + power/ground)
- Depends on thermal design point (e.g., heat sink)

Total Cost of Ownership

- Capital costs (e.g., server procurement cost)
- Operating costs (e.g., electricity)



Wafers

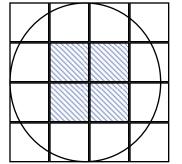
- Integrated circuits built with multi-step chemical process on wafers
- Cost per wafer depends on wafer size, number of steps

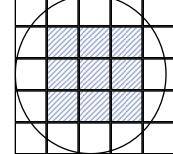
Chip (a.k.a. Die)

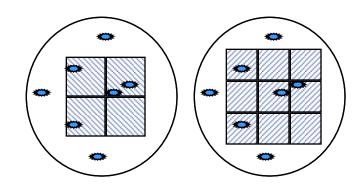
- If chips are large, fewer chips per wafer
- Larger chips have lower yield
- Uniform defect density
- Chip cost is proportional to area²⁻³

Process Variability

- Yield is non-binary
- Binning for speed grades
- Binning for core count
- Post-fabrication tuning with spares









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