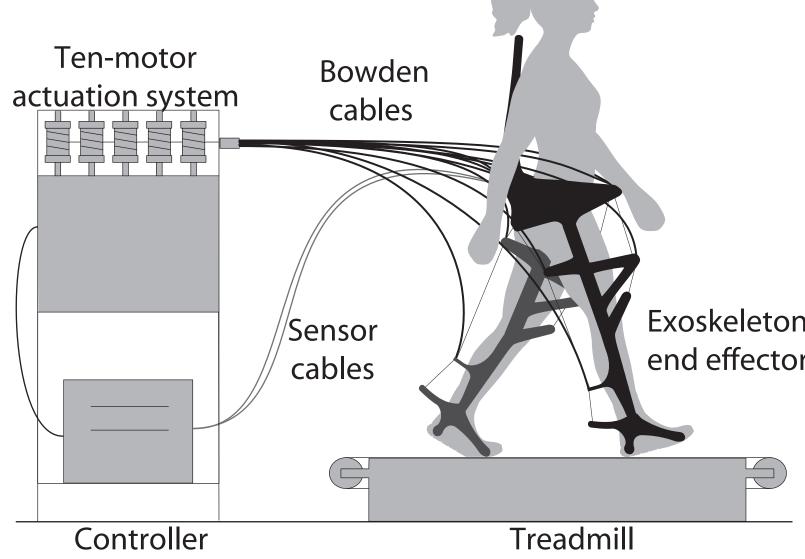
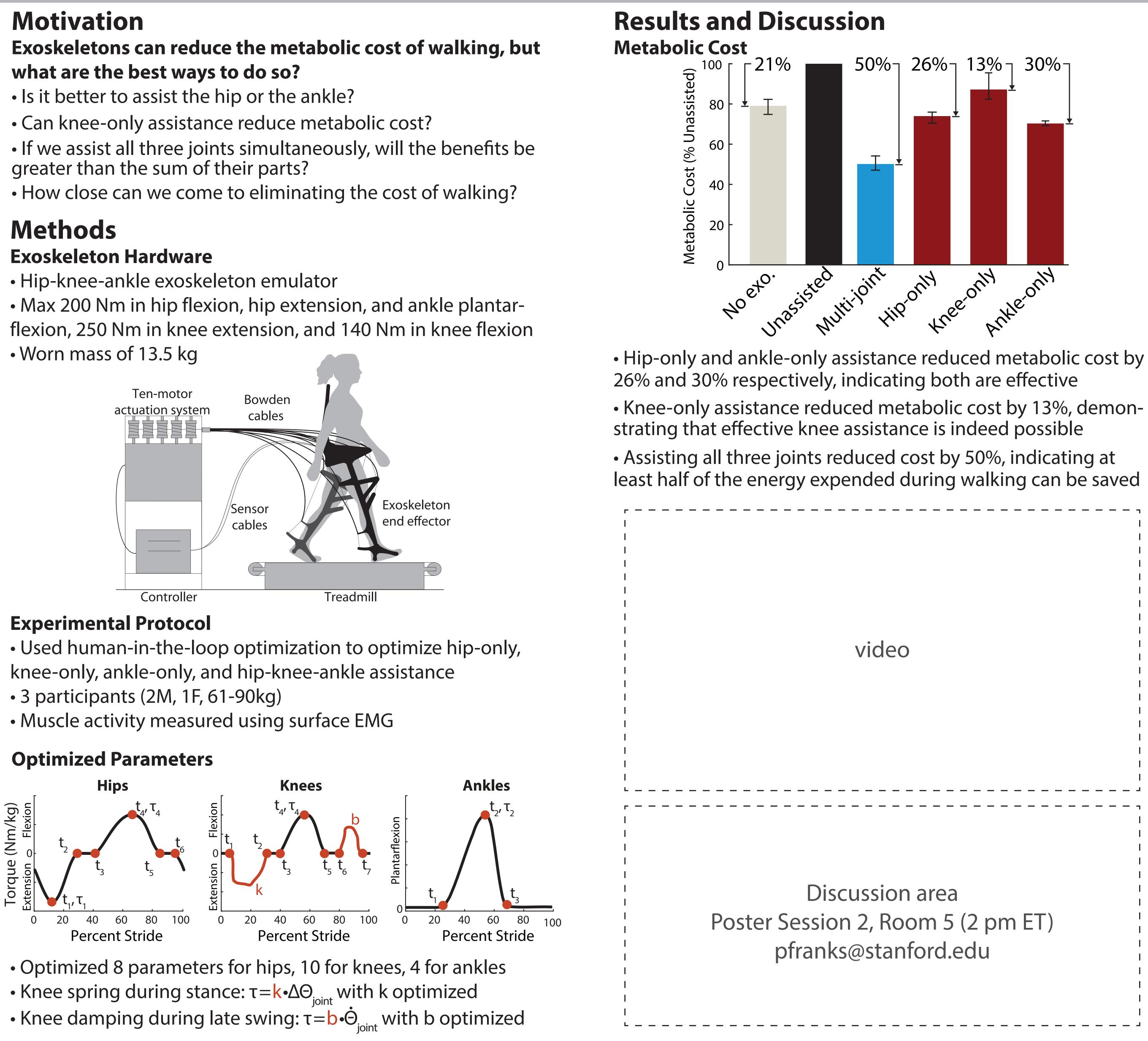
Stanford

Biomechatronics Laboratory

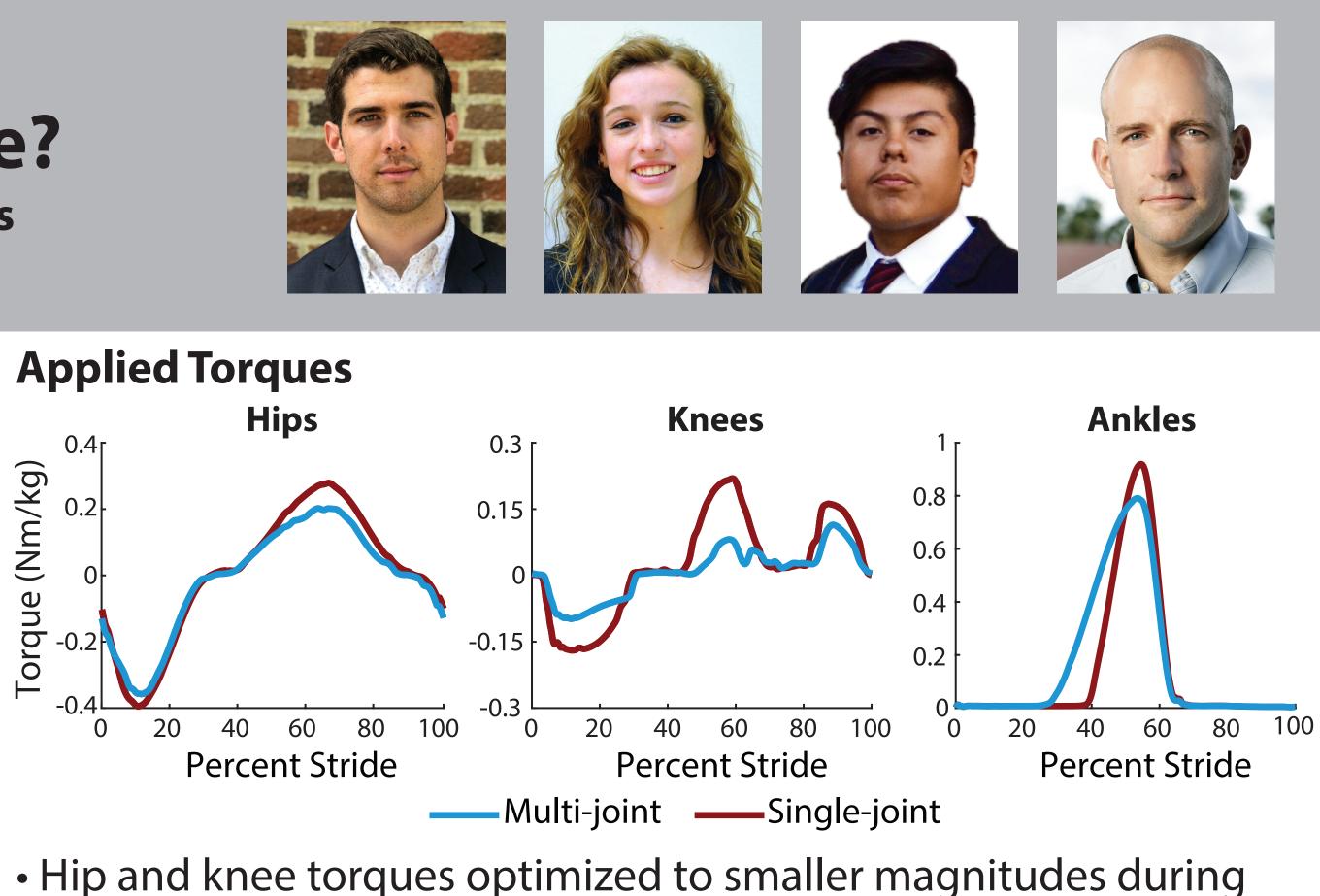




For an Exo to Be, as Good as Can Be, Help the Ankle, the Knee, the Hip or All Three?

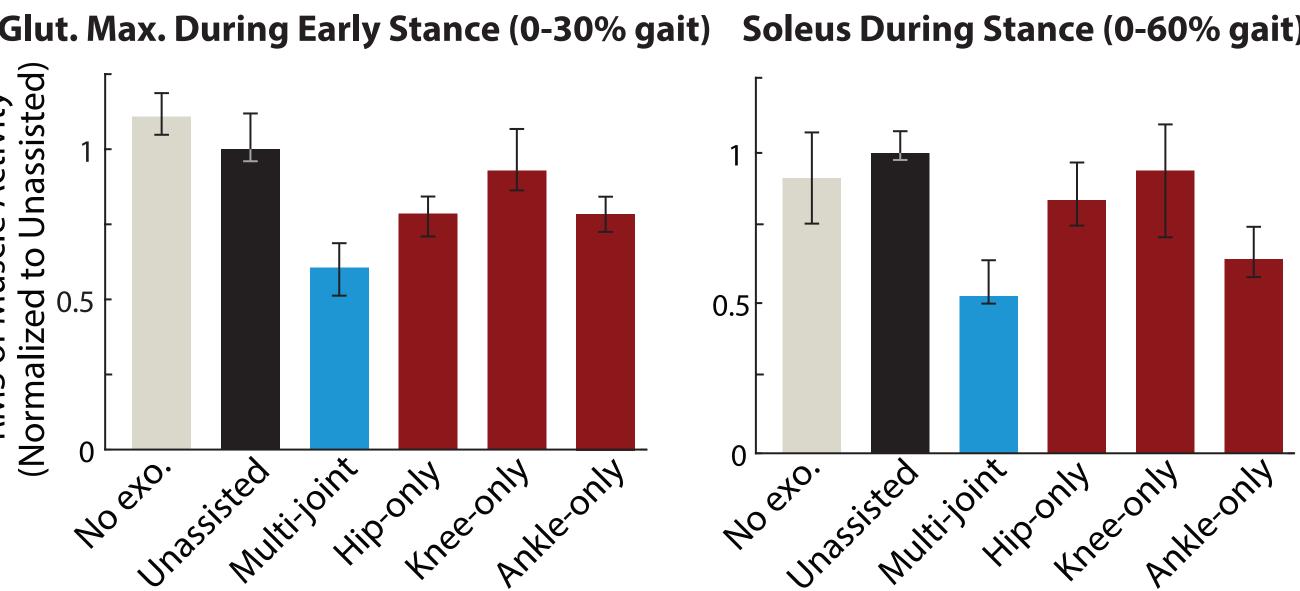
Patrick W. Franks, Gwendolyn M. Bryan, Ricardo Reyes, Steven H. Collins **Department of Mechanical Engineering, Stanford University**

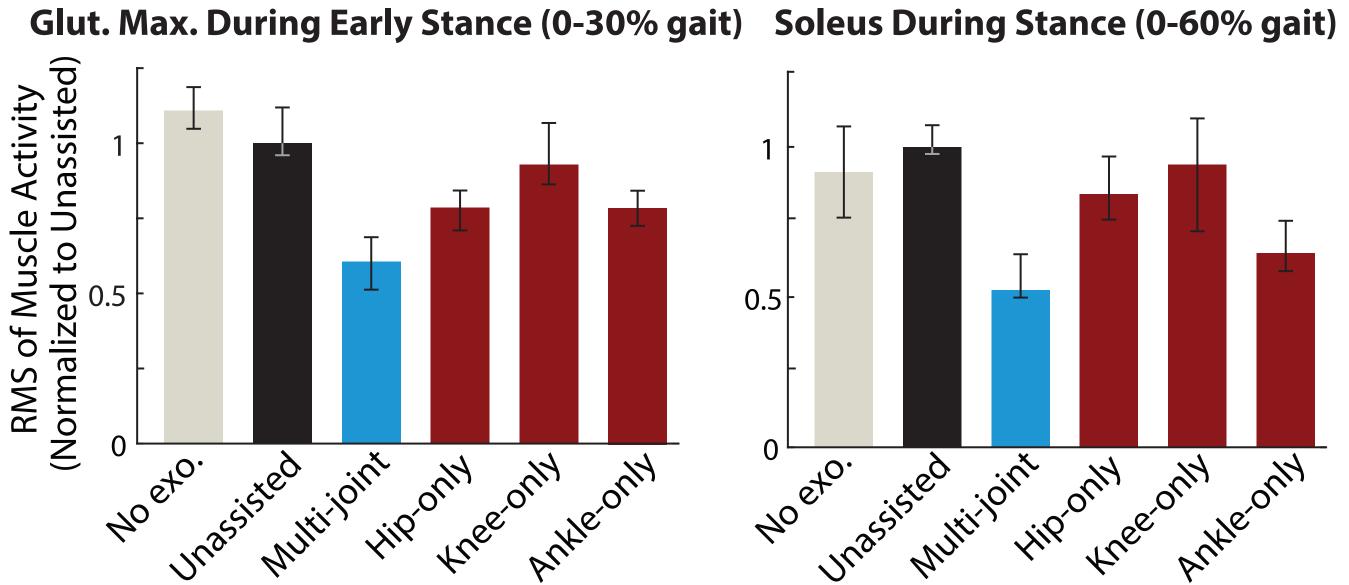




- multi-joint assistance
- Ankle torque was limited to at most 1 Nm/kg for single-joint and 0.8 Nm/kg for multi-joint for user comfort

Muscle Activity





• Gluteus maximus activity (left) decreased for hip-only and multi-joint assistance, but also for ankle assistance, indicating the gluteus was indirectly assisted by ankle exoskeleton torque

• Soleus activity (right) decreased for ankle-only, multi-joint, and hip-only assistance, but hip-only assistance only slightly reduced muscle activity, indicating a similar but less-pronounced effect of indirect assistance

Conclusion

- Assist the entire limb for maximum effect
- Assist a single well-chosen joint for maximum efficiency

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